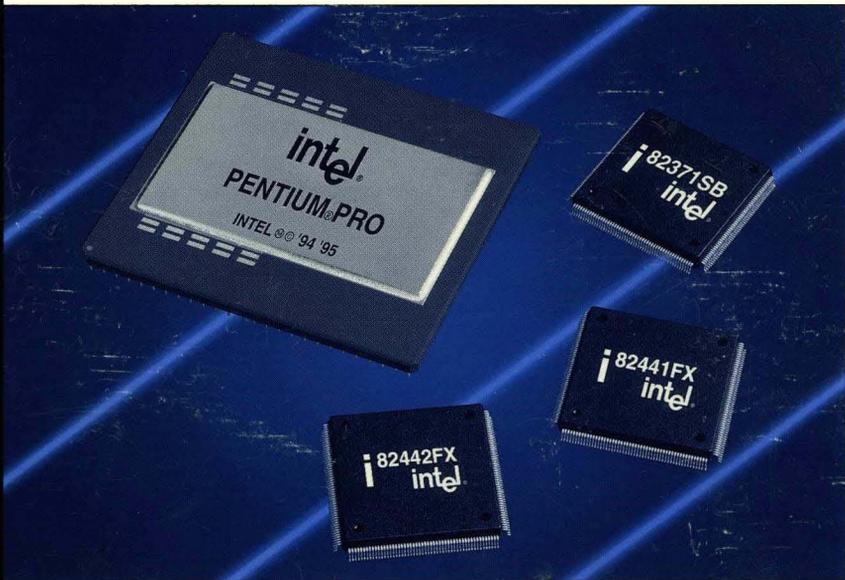


## Intel 440FX PCIset

82441FX PCI and Memory Controller (PMC)

82442FX Data Bus Accelerator (DBX)

*Building  
Blocks for the  
Best Business  
System*



**PCI**  
LOCAL BUS

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# INTEL 440FX PCISSET

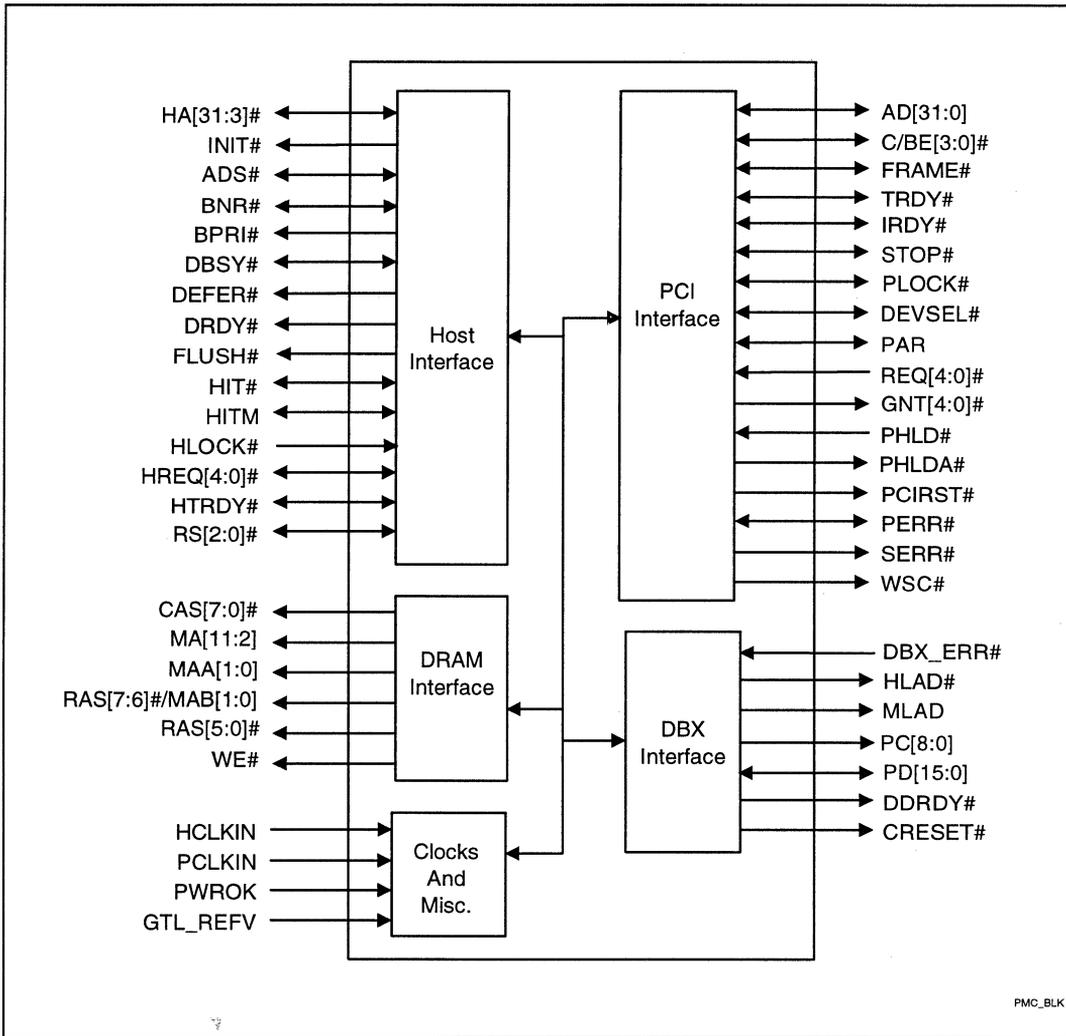
## 82441FX PCI AND MEMORY CONTROLLER (PMC) AND 82442FX DATA BUS ACCELERATOR (DBX)

- Supports the Pentium® Pro Processors at Bus Frequencies Up To 66 Mhz
  - Supports 32-Bit Addressing
  - Optimized in-Order and Request Queue
  - Full Symmetric Multi-Processor (SMP) Protocol for up to Two Processors
  - Dynamic Deferred Transaction Support
  - GTL+ Compliant Host Bus
  - Supports USWC Cycles
- Integrated DRAM Controller
  - 8 MB to 1 GB Main Memory
  - 64/72-Bit Non-Interleaved Path to Memory
  - FPM (Fast Page Mode), EDO (Extended Data Out -Page Mode), BEDO (Extended Data Out -Burst Mode) DRAMs Providing x-222 to x-4-4-4 Burst Capability
  - Support for Auto Detection of Memory Type: BEDO, EDO or FPM
  - 8 RAS Lines Available
  - Support for 4-, 16- and 64-Mb DRAM Devices
  - Support for Symmetrical and Asymmetrical DRAM Addressing
  - Configurable Support for ECC or Parity
  - ECC with Single Bit Error Correction and Multiple Bit Error Detection
  - Read-Around-Write Support for Host and PCI DRAM Read Accesses
  - Supports 3.3V or 5V DRAMs
- PCI Bus Interface
  - PCI Rev. 2.1, 5V Interface Compliant
  - Greater than 100 MBps Data Streaming for PCI to DRAM Accesses Enables Native Signal Processing (NSP) on Systems Designed With the Pentium Pro Processor
  - Integrated Arbiter With Multi-Transaction PCI Arbitration Accelerator Hooks
  - 5 PCI Bus Masters are Supported in Addition to the Host and PCI-to-ISA I/O Bridge
  - Delayed Transaction Support
  - PCI Parity Checking and Generation Support
  - Supports Concurrent Pentium Pro and PCI Transactions to Main Memory
- Data Buffering For Increased Performance
  - Extensive CPU-to-DRAM and PCI-to-DRAM Write Data Buffering
  - Write Combining Support for CPU-to-PCI Burst Writes
- System Management Mode (SMM) Compliant
- 208-Pin PQFP PCI Bridge/ Memory Controller (PMC), 208-Pin PQFP for the 440FX PCIsset Data Bus Accelerator (DBX)

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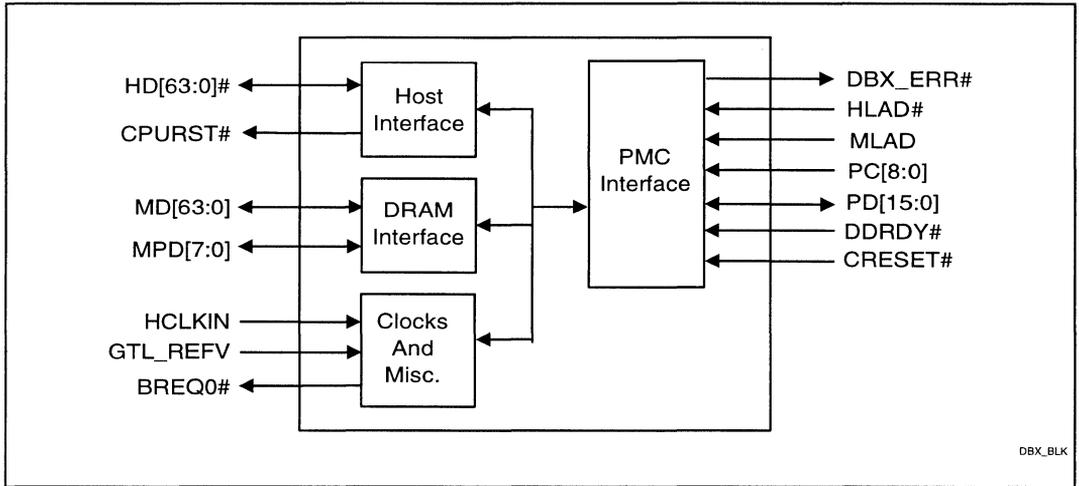
The Intel 440FX PCIsset provides a highly integrated solution for systems based on one or two Pentium® Pro processors. The 440FX PCIsset consists of the 82441FX PCI and Memory Controller (PMC), the 82442FX Data Bus Accelerator (DBX), and the 82371SB PCI I/O IDE Xcelerator (PIIX3). The PMC and DBX provide a two-chip host-to-PCI bridge including the DRAM control function, the PCI interface, and the PCI arbiter function. The 440FX PCIsset supports EDO, FPM, and BEDO DRAM technologies. The DRAM controller provides support for up to eight rows of memory and optional DRAM error detection/correction or parity. The 440FX PCIsset contains extensive buffering between all interfaces for high system data throughput and concurrent operations.

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PMC\_BLK

PMC Simplified Block Diagram



DBX Simplified Block Diagram

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### 1.0. OVERVIEW

The 440FX PCIset consists of a host-to-PCI bridge and memory controller, and an I/O subsystem core that allows an optimized price/performance path for the next generation of personal computers based on the Pentium Pro processor. The host-to-PCI bridge consists of two components; the PCI Bridge/Memory Controller (PMC) and the Data Bus Accelerator (DBX). The PMC and the DBX includes the following functions.

- Support for one/two Pentium Pro Processors at bus frequencies up to 66 MHz
- 64-bit GTL+ based host bus data interface
- 32-bit host address support
- 32-bit PCI bus interface
- 64/72-bit main memory interface
- Extensive data buffering between all interfaces for high throughput and concurrent operations

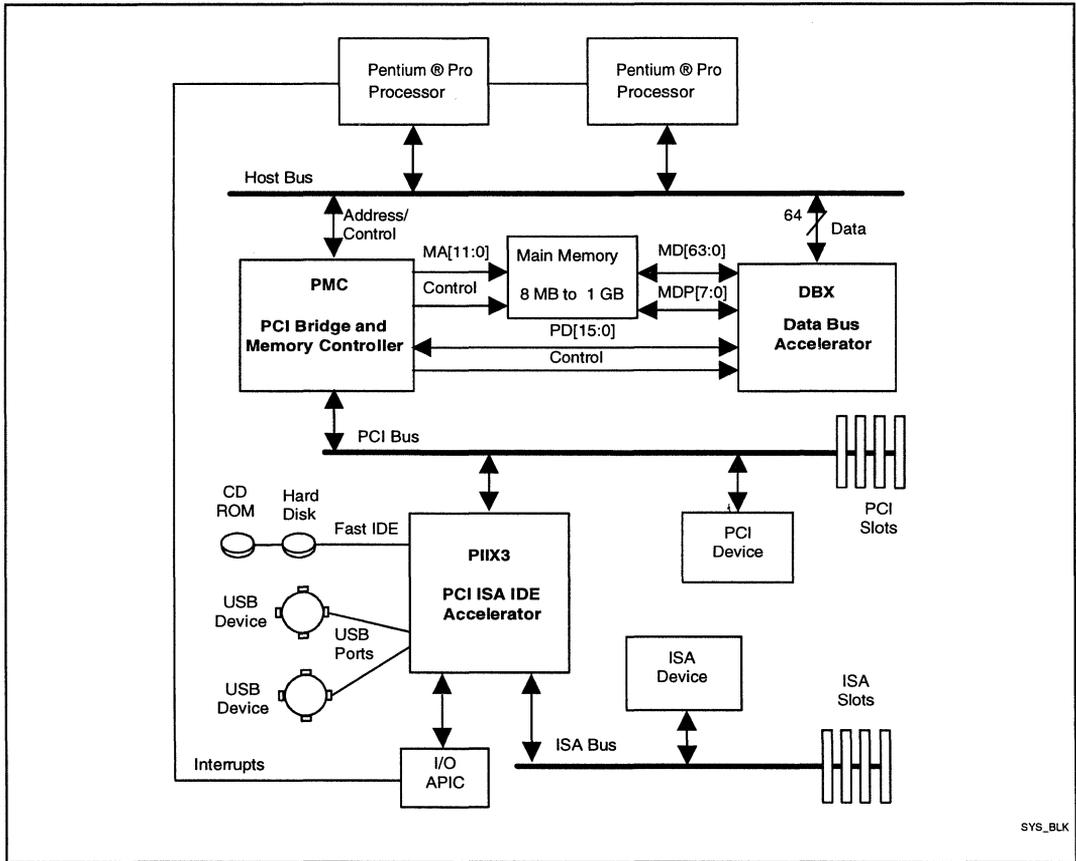


Figure 1. 440FX PCIset System Block Diagram

The PMC and the DBX interface with the Pentium Pro processor host bus. A maximum of two Pentium Pro processors are supported on the Pentium Pro host bus in a two processor symmetrical multi-processing configuration. A 16-bit private data bus (PD[15:0]) operating at host frequency between the DBX and the PMC provides a high throughput indirect interface between the DBX and PCI bus.

The PMC and the DBX host bus interfaces are designed based on the GTL+ specification. The PMC/DBX also provides a 5.0V tolerant 3.3V main memory interface that allows support of either 5V or 3V DRAMs. The PMC connects directly to the 5V PCI bus. The PMC includes an internal PCI arbiter.

The PIIX3 provides the PCI-to-ISA bridge functions along with Universal Serial Bus (USB) support. In addition, the PIIX3 contains a local bus master IDE interface and an interface for the I/O APIC component required for second Pentium Pro processor support. The PIIX3 is compliant to the PCI Rev. 2.1 specification.

### Host Interface

The PMC provides bus control signals and address paths for transfers between the host bus, PCI bus, and main memory. The PMC supports an optimized in-order queue that allows for pipelining of outstanding transaction requests on the host bus.

During Host to PCI cycles, the PMC controls the PCI protocol and data flows through the DBX and PMC via the private bus (PD[15:0]). This bus operates at the host bus clock frequency.

The PMC also receives addresses from PCI bus initiators for PCI-to-DRAM transfers. These addresses are translated to the appropriate memory addresses and are also provided on the host bus for snoop cycles. PCI master cycles are sent to main memory through the PMC with data moving over the PD bus to the DBX, which subsequently forwards the data to DRAM.

### DRAM Interface

The PMC integrates a main memory controller that supports a 64/72-bit DRAM interface. The PMC DRAM controller interface supports the following features:

- DRAM type: standard Fast Page Mode(FPM), Extended Data Out (EDO) (sometimes referred to as Hyper Page Mode) and Burst EDO (BEDO) memory.
- Memory Size: 8 Mbytes to 1 Gbytes with eight RAS lines available.
- Addressing Type: Symmetrical and Asymmetrical addressing
- Memory Modules supported: Single and double density SIMMs and DIMMs
- DRAM device technology: 4 Mbit, 16 Mbit, and 64 Mbit
- DRAM Speeds: 50, 60, and 70 ns

The memory controller provides capability for auto-detection of BEDO/EDO/FPM DRAM type installed in the system during system configuration and initialization providing a Plug and Play DRAM interface to the user. The PMC/DBX also provides data integrity features including ECC in the memory array and parity error detection. During host and PCI reads of the DRAM, the DBX provides error checking and correction of the data. The DBX supports multiple-bit error detection and single-bit error correction when ECC mode is enabled and parity error detection when parity mode is enabled. During host or PCI master writes to DRAM, the DBX generates ECC/Parity for the data.

## DBX

A single DBX provides a 64-bit CPU-to-main memory data path. The DBX also interfaces to the 16-bit private data bus for PCI transactions and PMC configuration register set access. The private bus operating at host frequency provides enough throughput to sustain PCI bandwidth. The DBX allows for a cost effective solution providing optimal CPU-to-DRAM performance while maintaining a relatively small footprint (208 pins).

## PCI Interface

The PCI interface is 5V Revision 2.1 compliant and supports up to five PCI bus masters in addition to the PIIX3 components. The PMC supports a divide-by-2 synchronous PCI coupling to the host bus frequency.

## IOAPIC

The IOAPIC component supports dual processors as well as enhanced interrupt processing in the single processor environment. No special interface is required on the PMC in this case. The PMC furnishes an external status output signal to the standalone IOAPIC component that is used for buffer flushing during synchronization events for the PIIX3.

## 2.0. SIGNAL DESCRIPTION

This section provides a detailed description of each signal. The signals are arranged in functional groups according to their associated interface.

The “#” symbol at the end of a signal name indicates that the active, or asserted state occurs when the signal is at a low voltage level. When “#” is not present after the signal name the signal is asserted when at the high voltage level.

The terms assertion and negation are used extensively. This is done to avoid confusion when working with a mixture of “active-low” and “active-high” signals. The term **assert**, or **assertion** indicates that a signal is active, independent of whether that level is represented by a high or low voltage. The term **negate**, or **negation** indicates that a signal is inactive.

The following notations are used to describe the signal and type:

<b>I</b>	Input pin
<b>O</b>	Output pin
<b>OD</b>	Open Drain Output pin. This requires a pull-up to the VCC of the processor core
<b>I/O</b>	Bi-directional Input/Output pin

The signal description also includes the type of buffer used for the particular signal:

<b>GTL+</b>	Open Drain GTL+ interface signal. Refer to the GTL+ I/O Specification for complete details
<b>PCI</b>	PCI bus interface signals. These signals are compliant with the PCI 5.0V Signaling Environment DC and AC Specifications
<b>LVTTL</b>	Low Voltage TTL compatible signals. These are also 3.3V outputs with 5V tolerant inputs.

## 2.1. PMC Signals

### 2.1.1. HOST INTERFACE (PMC)

Name	Type	Description
INIT#	O LVTTL	<b>INITIALIZATION:</b> INIT# is asserted (soft reset) by the PMC during a CPU shutdown bus cycle, or after the writing to the reset control register to initiate a soft reset.
HA[31:3]#	I/O GTL+	<b>ADDRESS BUS:</b> HA[31:3]# connects to the CPU address bus. The PMC drives HA[31:3]# during snoop cycles on behalf of PCI initiators. Note that the CPU address bus is an inverted bus.
ADS#	I/O GTL+	<b>ADDRESS STROBE:</b> The CPU bus owner asserts ADS# to indicate the first of two cycles of a request phase.
BNR#	O GTL+	<b>BLOCK NEXT REQUEST:</b> Used to block the current request bus owner from issuing new requests. This signal is used to dynamically control the CPU bus pipeline depth.
BPRI#	O GTL+	<b>PRIORITY AGENT BUS REQUEST:</b> The owner of this signal will always be the next bus owner. This signal has priority over symmetric bus requests and causes the current symmetric owner to stop issuing new transactions unless the HLOCK# signal is asserted. The PMC drives this signal to gain control of the CPU bus.
DBSY#	I/O GTL+	<b>DATA BUS BUSY:</b> Used by the data bus owner to hold the data bus for transfers requiring more than one cycle.
DEFER#	O GTL+	<b>DEFER:</b> The PMC uses a dynamic deferring policy to optimize for system performance. The PMC also uses the DEFER# signal to indicate a CPU retry response.
DRDY#	I/O GTL+	<b>DATA READY:</b> Asserted for each cycle that data is transferred.
FLUSH#	OD LVTTL	<b>FLUSH:</b> Issued to CPU(s) for L1/L2 cache for a write back of all cache lines in modified state and then invalidate all cache lines. This signal is asserted by the PMC to throttle the CPU bus in the deturbo mode of operation.
HIT#	I/O GTL+	<b>HIT:</b> Indicates that a caching agent holds an unmodified version of the requested line. Also, driven in conjunction with HITM#, by the target, to extend the snoop window.
HITM#	I/O GTL+	<b>HIT MODIFIED:</b> Indicates that a caching agent holds a modified version of the requested line and that this agent assumes responsibility for providing the line. Also, driven in conjunction with HIT# to extend the snoop window.
HLOCK#	I GTL+	<b>HOST LOCK:</b> All CPU bus cycles sampled with the assertion of HLOCK# and ADS#, until the negation of HLOCK# must be atomic (i.e., no PCI activity to DRAM is allowed and the locked cycle is translated to PCI, if targeted for the PCI bus.)
HREQ[4:0]#	I/O GTL+	<b>REQUEST COMMAND:</b> Asserted during both clocks of the request phase. In the first clock, the signals define the transaction type to a level of detail that is sufficient to begin a snoop request. In the second clock, the signals carry additional information to define the complete transaction type.

Name	Type	Description																		
HTRDY#	I/O GTL+	<b>HOST TARGET READY:</b> Indicates that the target of the CPU transaction is able to enter the data transfer phase.																		
RS[2:0]#	I/O GTL+	<p><b>RESPONSE SIGNALS:</b> Indicates the type of response:</p> <table border="1"> <thead> <tr> <th>RS[2:0]</th> <th>Response type</th> </tr> </thead> <tbody> <tr> <td>000</td> <td>Idle state</td> </tr> <tr> <td>001</td> <td>Retry response</td> </tr> <tr> <td>010</td> <td>Defer response</td> </tr> <tr> <td>011</td> <td>Reserved</td> </tr> <tr> <td>100</td> <td>Hard Failure</td> </tr> <tr> <td>101</td> <td>Normal without data</td> </tr> <tr> <td>110</td> <td>Implicit Writeback</td> </tr> <tr> <td>111</td> <td>Normal with data</td> </tr> </tbody> </table>	RS[2:0]	Response type	000	Idle state	001	Retry response	010	Defer response	011	Reserved	100	Hard Failure	101	Normal without data	110	Implicit Writeback	111	Normal with data
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Note: All of the signals in the host interface are described in the Pentium Pro datasheet. The preceding table highlights 440FX PCIset specific uses of these signals.

### 2.1.2. DRAM INTERFACE (PMC)

Name	Type	Description
CAS[7:0]#	O LVTTTL	<b>COLUMN ADDRESS STROBE:</b> The CAS[7:0]# signals are used to latch the column address on the MA[11:0] lines into the DRAMs. These signals drive the DRAM array directly without external buffering.
MA[11:2]	O LVTTTL	<b>MEMORY ADDRESS:</b> MA[11:2] provide multiplexed row and column address to DRAM. MA[11:2] are externally buffered to drive the address lines of the DRAM.
MAA[1:0]	O LVTTTL	<b>LOWER MEMORY ADDRESS SET A:</b> MAA[1:0] are the lower two bits of the memory address used to complete the row and column address to the DRAM. These two pins are toggled during the burst phase.
RAS[7:6]#/ MAB[1:0]	O LVTTTL	<p><b>ROW ADDRESS STROBES RAS7# AND RAS6# OR LOWER MEMORY ADDRESS SET B:</b> MAB[1:0] are the lower two bits of the memory address used to complete the row and column address to the DRAM. These signals are toggled during the burst phase. RAS[7:6]# are used to latch the row address on the MA[11:0] lines into the DRAMs. These signals should be used to select the upper two rows in the memory array. These signals drive the DRAM array directly without external buffers.</p> <p>The strapping on <b>PC8</b> selects the function of these pins.</p>
RAS[5:0]#	O LVTTTL	<b>ROW ADDRESS STROBE:</b> The RAS[5:0]# signals are used to latch the row address on the MA[11:0] lines into the DRAMs. Each signal is used to select one DRAM row. These signals drive the DRAM array directly without any external buffers.
WE#	O LVTTTL	<b>WRITE ENABLE SIGNAL:</b> WE# is asserted during writes to main memory. During burst writes to main memory, WE# is externally buffered to drive the WE# inputs of the DRAM.

**2.1.3. PCI INTERFACE (PMC)**

Name	Type	Description																																		
AD[31:0]	I/O PCI	<b>PCI ADDRESS/DATA:</b> These signals are connected to the PCI address/data bus. Address is driven by the PMC with FRAME# assertion, data is driven or received in following clocks.																																		
DEVSEL#	I/O PCI	<b>DEVICE SELECT:</b> Device select, when asserted, indicates that a PCI target device has decoded its address as the target of the current access. The PMC asserts DEVSEL# based on the DRAM address range being accessed by a PCI initiator or if it decodes the current configuration cycle is targeted to the PMC.																																		
FRAME#	I/O PCI	<b>FRAME:</b> FRAME# is an output when the PMC acts as an initiator on the PCI Bus. FRAME# is asserted by the PMC to indicate the beginning and duration of an access. The PMC asserts FRAME# to indicate a bus transaction is beginning.																																		
IRDY#	I/O PCI	<b>INITIATOR READY:</b> IRDY# is an output when PMC acts as a PCI initiator and an input when the PMC acts as a PCI target. The assertion of IRDY# indicates the current PCI Bus initiator's ability to complete the current data phase of the transaction.																																		
PLOCK#	I/O PCI	<b>PLOCK:</b> PLOCK# indicates an exclusive bus operation and may require multiple transactions to complete. When PLOCK# is asserted, non-exclusive transactions may proceed. A grant to start a transaction on the PCI Bus does not guarantee control of the PLOCK# signal. Control of the PLOCK# signal is obtained under its own protocol in conjunction with the GNT# signal. The PMC supports bus lock mode of operation.																																		
TRDY#	I/O PCI	<b>TARGET READY:</b> TRDY# is an input when the PMC acts as a PCI initiator and an output when the PMC acts as a PCI target. The assertion of TRDY# indicates the target agent's ability to complete the current data phase of the transaction.																																		
C/BE[3:0]#	I/O PCI	<p><b>COMMAND/BYTE ENABLE:</b> PCI Bus Command and Byte Enable signals are multiplexed on the same pins. During the address phase of a transaction, C/BE[3:0]# define the bus command. During the data phase C/BE[3:0]# are used as byte enables. The byte enables determine which byte lanes carry meaningful data. PCI Bus command encoding and types are listed below.</p> <table border="0" data-bbox="404 1036 1207 1490"> <thead> <tr> <th data-bbox="404 1036 728 1060">C/BE[3:0]#</th> <th data-bbox="728 1036 1207 1060">Command Type</th> </tr> </thead> <tbody> <tr><td data-bbox="404 1060 728 1084">0 0 0 0</td><td data-bbox="728 1060 1207 1084">Interrupt Acknowledge</td></tr> <tr><td data-bbox="404 1084 728 1109">0 0 0 1</td><td data-bbox="728 1084 1207 1109">Special Cycle</td></tr> <tr><td data-bbox="404 1109 728 1133">0 0 1 0</td><td data-bbox="728 1109 1207 1133">I/O Read</td></tr> <tr><td data-bbox="404 1133 728 1157">0 0 1 1</td><td data-bbox="728 1133 1207 1157">I/O Write</td></tr> <tr><td data-bbox="404 1157 728 1182">0 1 0 0</td><td data-bbox="728 1157 1207 1182">Reserved</td></tr> <tr><td data-bbox="404 1182 728 1206">0 1 0 1</td><td data-bbox="728 1182 1207 1206">Reserved</td></tr> <tr><td data-bbox="404 1206 728 1230">0 1 1 0</td><td data-bbox="728 1206 1207 1230">Memory Read</td></tr> <tr><td data-bbox="404 1230 728 1255">0 1 1 1</td><td data-bbox="728 1230 1207 1255">Memory Write</td></tr> <tr><td data-bbox="404 1255 728 1279">1 0 0 0</td><td data-bbox="728 1255 1207 1279">Reserved</td></tr> <tr><td data-bbox="404 1279 728 1304">1 0 0 1</td><td data-bbox="728 1279 1207 1304">Reserved</td></tr> <tr><td data-bbox="404 1304 728 1328">1 0 1 0</td><td data-bbox="728 1304 1207 1328">Configuration Read</td></tr> <tr><td data-bbox="404 1328 728 1352">1 0 1 1</td><td data-bbox="728 1328 1207 1352">Configuration Write</td></tr> <tr><td data-bbox="404 1352 728 1377">1 1 0 0</td><td data-bbox="728 1352 1207 1377">Memory Read Multiple</td></tr> <tr><td data-bbox="404 1377 728 1401">1 1 0 1</td><td data-bbox="728 1377 1207 1401">Reserved (Dual Address Cycle)</td></tr> <tr><td data-bbox="404 1401 728 1425">1 1 1 0</td><td data-bbox="728 1401 1207 1425">Memory Read Line</td></tr> <tr><td data-bbox="404 1425 728 1450">1 1 1 1</td><td data-bbox="728 1425 1207 1450">Memory Write and Invalidate</td></tr> </tbody> </table>	C/BE[3:0]#	Command Type	0 0 0 0	Interrupt Acknowledge	0 0 0 1	Special Cycle	0 0 1 0	I/O Read	0 0 1 1	I/O Write	0 1 0 0	Reserved	0 1 0 1	Reserved	0 1 1 0	Memory Read	0 1 1 1	Memory Write	1 0 0 0	Reserved	1 0 0 1	Reserved	1 0 1 0	Configuration Read	1 0 1 1	Configuration Write	1 1 0 0	Memory Read Multiple	1 1 0 1	Reserved (Dual Address Cycle)	1 1 1 0	Memory Read Line	1 1 1 1	Memory Write and Invalidate
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0 0 1 1	I/O Write																																			
0 1 0 0	Reserved																																			
0 1 0 1	Reserved																																			
0 1 1 0	Memory Read																																			
0 1 1 1	Memory Write																																			
1 0 0 0	Reserved																																			
1 0 0 1	Reserved																																			
1 0 1 0	Configuration Read																																			
1 0 1 1	Configuration Write																																			
1 1 0 0	Memory Read Multiple																																			
1 1 0 1	Reserved (Dual Address Cycle)																																			
1 1 1 0	Memory Read Line																																			
1 1 1 1	Memory Write and Invalidate																																			

Name	Type	Description
PAR	I/O PCI	<b>PARITY:</b> PAR is driven by the PMC when it acts as a PCI initiator during address and data phases for a write cycle, and during the address phase for a read cycle. PAR is driven by the PMC when it acts as a PCI target during each data phase of a PCI memory read cycle. Even parity is generated across AD[31:0] and C/BE[3:0]#.
PERR#	I/O PCI	<b>PCI PARITY ERROR:</b> Pulsed by an agent receiving data with bad parity one clock after PAR is asserted. The PMC generates PERR# active if it detects a parity error on the PCI bus and the PERR# Enable bit is set.
SERR#	O PCI	<b>SYSTEM ERROR:</b> The PMC can be programmed to assert SERR# for 2 types of memory error conditions: <ol style="list-style-type: none"> <li>1. Main memory single bit ECC error</li> <li>2. Main memory (DRAM) parity or multiple bit ECC error</li> </ol> The PMC can be programmed to assert SERR# when it detects a target abort on a PMC initiated PCI cycle and when PERR# is sampled active.
PCIRST#	O PCI	<b>PCI RESET:</b> PCI bus reset forces the PCI interfaces of each device to a known state. The PMC generates a minimum 1 ms pulse for PCIRST#.
STOP#	I/O PCI	<b>STOP:</b> STOP# is an input when the PMC acts as a PCI initiator and an output when the PMC acts as a PCI target. STOP# indicates that the bus initiator must immediately terminate its current PCI Bus cycle at the next clock edge and release control of the PCI Bus. STOP# is used for disconnect, retry, and abort sequences on the PCI Bus.

#### 2.1.4. PCI SIDEBAND INTERFACE (PMC)

Name	Type	Description
PHOLD#	I PCI	<b>PCI HOLD:</b> The PIIX3 asserts this signal to request the PCI bus.
PHLDA#	O PCI	<b>PCI HOLD ACKNOWLEDGE:</b> The PMC asserts this signal to grant PCI bus ownership to the PIIX3.
WSC#	O PCI	<b>WRITE SNOOP COMPLETE:</b> Asserted to indicate that all that the snoop activity on the CPU bus on behalf of the last PCI-to-DRAM write transaction is complete.
REQ[4:0]#	I PCI	<b>PCI BUS REQUEST:</b> REQ[4:0]# are the PCI bus request signals used by the PMC for PCI initiator arbitration.
GNT[4:0]#	O PCI	<b>PCI GRANT:</b> GNT[4:0]# are the PCI bus grant signals used by the PMC for PCI initiator arbitration.

**2.1.5. DBX INTERFACE (PMC)**

Name	Type	Description
DBX_ERR#	I LVTTTL	<b>DBX ERROR:</b> Asserted by the DBX if an ECC or parity error occurred during a memory cycle. DBX_ERR# is asserted for 5 host clocks to indicate a Single-bit ECC error and 6 host clocks to indicate a parity or Multi-bit ECC error.
HLAD#	O LVTTTL	<b>HOST LATCH AND ADVANCE:</b> During CPU reads (both from DRAM and PCI), this signal controls the latching of the read data into the DBX CPU interface output latch.
MLAD	O LVTTTL	<b>MEMORY LATCH AND ADVANCE:</b> During DRAM reads, asserting this signal latches memory read data into the DBX. During DRAM writes, asserting this signal latches write data out of the DBX.
PC[8:0]	I/O LVTTTL	<b>PMC CONTROL SIGNALS:</b> PC[8:0] are control signals between the PMC and DBX.
PD[15:0]	I/O LVTTTL	<b>PRIVATE DATA BUS:</b> This is a 16 bit private data path between the PMC and DBX. This bus runs at the host clock rate and is used to transfer data during CPU-to-PCI cycles and PCI to DRAM cycles
DDRDY#	O LVTTTL	<b>DELAYED DATA READY:</b> This delayed version of the DRDY# signal is asserted by the PMC to the DBX.

**2.1.6. CLOCKS (PMC)**

Name	Type	Description
HCLKIN	I 2.5V LVTTTL	<b>HOST CLOCK IN:</b> This pin receives a host clock input from an external clock source. The input is configurable via the PD1 strap. If the PD1 is sampled low at reset(default), 3.3V buffer mode is enabled. This is normal operation enabled by internal pulldowns. If PD1 is sampled high, 2.5V buffer mode is enabled.
PCLKIN	I LVTTTL	<b>PCI CLOCK IN:</b> This pin receives a PCI clock reference that is synchronous with respect to the host clock. This is the PCI clock reference that can be synchronously derived by an external clock synthesizer component from the host clock (divide-by-2). This signal clocks the PMC logic that is in the PCI clock domain.

**2.1.7. MISCELLANEOUS (PMC)**

Name	Type	Description
CRESET#	O LVTTTL	<b>CHIP RESET:</b> This is a reset output signal driven by the PMC to the DBX. CRESET# is driven active for 2 msec. The DBX drives CPURST# to the CPUs, which is a 2 host clocks delayed version of the CRESET#. The PMC can also activate CRESET# under software control by writing to the internal reset configuration register to initiate a hard reset or CPU BIST.
GTL_REFV	I	<b>GTL+ REFERENCE VOLTAGE:</b> This is the reference voltage derived from the termination voltage to the pullup resistors and determines the noise margin for the signals.

Name	Type	Description
PWROK	I LVTTL	<b>POWER OK:</b> This input goes active after all the power supplies in the system have reached their specified values. PWROK forces all of the PMC internal state machines to their default values. PWROK inactive generates CPURST# and PCIRST# active. The rising edge of PWROK is asynchronous, but must meet set-up and hold specifications for recognition on any specific clock. The PMC holds CPURST# for 2 msec and PCIRST# active for 1 msec after the rising edge of PWROK.

### 2.1.8. POWER UP STRAP OPTIONS (PMC)

Below is a list of all power on options that are loaded into the PMC based on the voltage level present on the respective strappings at the rising edge of PWROK. The PMC floats all signals connected to straps during CRESET# and keeps them floated for a minimum of 4 host clocks after the negation of CRESET#. To enable the different modes, external pullups should be approximately 10 K $\Omega$  to 3.3V (does not apply to A7#). Note that all signals that are used to select powerup strap options are connected to weak internal pulldowns.

Signal	Register Name/bit	Description										
PC8	PMCCFG[14]	<p><b>Rows 7 And 8 Enable:</b> PC8 selects if RAS[7:6]#/ MAB[1:0] pins are used as row selects or extra copies of the lower two memory addresses. These are selected as follows:</p> <table border="0"> <tr> <td style="text-align: center;"><b>PC8</b></td> <td style="text-align: center;"><b>RAS[7:6]/MAB[1:0]</b></td> </tr> <tr> <td style="text-align: center;">0</td> <td style="text-align: center;">MAB[1:0]</td> </tr> <tr> <td style="text-align: center;">1</td> <td style="text-align: center;">RAS[7:6]#</td> </tr> </table>	<b>PC8</b>	<b>RAS[7:6]/MAB[1:0]</b>	0	MAB[1:0]	1	RAS[7:6]#				
<b>PC8</b>	<b>RAS[7:6]/MAB[1:0]</b>											
0	MAB[1:0]											
1	RAS[7:6]#											
PC[3:2]	PMCCFG[9:8]	<p><b>Host Frequency Select:</b> PC[3:2] selects the CPU bus frequency.</p> <table border="0"> <tr> <td style="text-align: center;"><b>PC[3:2]</b></td> <td style="text-align: center;"><b>CPU Bus Frequency</b></td> </tr> <tr> <td style="text-align: center;">0 0</td> <td style="text-align: center;">Reserved</td> </tr> <tr> <td style="text-align: center;">0 1</td> <td style="text-align: center;">60 MHz</td> </tr> <tr> <td style="text-align: center;">1 0</td> <td style="text-align: center;">66 MHz</td> </tr> <tr> <td style="text-align: center;">1 1</td> <td style="text-align: center;">Reserved</td> </tr> </table>	<b>PC[3:2]</b>	<b>CPU Bus Frequency</b>	0 0	Reserved	0 1	60 MHz	1 0	66 MHz	1 1	Reserved
<b>PC[3:2]</b>	<b>CPU Bus Frequency</b>											
0 0	Reserved											
0 1	60 MHz											
1 0	66 MHz											
1 1	Reserved											
PD[15:12]		<b>Test Mode:</b> See Testability Section										
PD1		<p><b>HCLKIN Input Buffer Select:</b> PD1 selects whether the 2.5V or 3.3V mode is enabled.</p> <table border="0"> <tr> <td style="text-align: center;"><b>PC1</b></td> <td style="text-align: center;"><b>HCLKIN Input Buffer Select</b></td> </tr> <tr> <td style="text-align: center;">0</td> <td style="text-align: center;">3.3V Input (Default)</td> </tr> <tr> <td style="text-align: center;">1</td> <td style="text-align: center;">2.5V Input</td> </tr> </table>	<b>PC1</b>	<b>HCLKIN Input Buffer Select</b>	0	3.3V Input (Default)	1	2.5V Input				
<b>PC1</b>	<b>HCLKIN Input Buffer Select</b>											
0	3.3V Input (Default)											
1	2.5V Input											
A7#	PMCCFG2	<p><b>In-order Queue Depth Select/Enable:</b> The value on A7# sampled on the rising edge of CRESET# reflects if the IOQD is set to 1 or maximum of four. Note that A7# is pulled up as a GTL+ signal and can be driven by to zero by external logic.</p>										

## 2.2. DBX Signals

### 2.2.1. DRAM INTERFACE SIGNALS (DBX)

Name	Type	Description
MD[63:0]	I/O LVTTTL	<b>MEMORY DATA:</b> These signals are connected to the DRAM data bus and have weak internal pulldowns.
MPD[7:0]	I/O LVTTTL	<b>MEMORY PARITY DATA:</b> These signals are connected to the parity or ECC bits of the DRAM data bus and have weak internal pulldowns.

### 2.2.2. PMC INTERFACE SIGNALS (DBX)

Name	Type	Description
DBX_ERR#	O LVTTTL	<b>DBX ERROR:</b> DBX_ERR# is generated for ECC or parity errors during a memory read cycle. DBX_ERR# is asserted for 5 host clocks to indicate a Single-bit ECC error and 6 host clocks to indicate a parity or Multi-bit ECC error.
HLAD#	I LVTTTL	<b>HOST LATCH AND ADVANCE SIGNAL:</b> During CPU reads, HLAD# controls the latching of read data into the DBX CPU interface output latch.
MLAD	I LVTTTL	<b>MEMORY LATCH AND ADVANCE SIGNAL:</b> During DRAM reads, the PMC asserts this signal to latch memory read data into the DBX. During DRAM writes, the PMC asserts this signal to latch write data from the DBX.
PC[8:0]	I LVTTTL	<b>PMC DBX CONTROL SIGNALS:</b> PC[8:0] are control signals between the PMC and DBX.
DDRDY#	I LVTTTL	<b>DELAYED DATA READY:</b> The PMC asserts this delayed version of DRDY# to the DBX.
PD[15:0]	I/O LVTTTL	<b>PRIVATE DATA BUS:</b> These signals are connected to the PD data bus on the PMC. This is the data path for the PCI-to-DRAM and CPU-to-PCI cycles. During PCI-to-DRAM reads and CPU-to-PCI writes, the DBX drives data on this bus. During CPU-to-PCI reads and PCI-to-DRAM writes, the DBX receives data on this bus.

### 2.2.3. HOST INTERFACE SIGNALS (DBX)

Name	Type	Description
HD[63:0]#	I/O GTL+	<b>HOST DATA:</b> These signals are connected to the CPU data bus. Note that the data signals are inverted on the CPU bus.
CPURST#	O GTL+	<b>CPU RESET:</b> The CPURST# pin is an output from the DBX that is driven directly from the CRESET#. It allows the CPUs to begin execution at a known state.

## 2.2.4. MISCELLANEOUS (DBX)

Name	Type	Description
HCLKIN	I 2.5V LVTTTL	<b>HOST CLOCK IN:</b> This pin receives a host clock input from an external source. The input is configurable via the PD1 strap. If the PD1 is sampled low at reset (default), 3.3V buffer mode is enabled. This is normal operation enabled by internal pulldowns. If PD1 is sampled high, 2.5V buffer mode is enabled.
CRESET#	I LVTTTL	<b>CHIP RESET:</b> This is a reset input signal driven by the PMC to the DBX. It forces the DBX to begin execution in a known state. This signal is also used to drive the CPURST# to the CPUs.
GTL_REFV	I	<b>GTL REFERENCE VOLTAGE:</b> This is the reference voltage derived from the termination voltage to the pullup resistors and determines the noise margin for the signals. This signal goes the reference input of the GTL+ sense amp on each GTL+ input or I/O pin.
BREQ0#	O GTL+	<b>SYMMETRIC AGENT BUS REQUEST:</b> Driven by the DBX during CPURST# to configure the symmetric bus agents.

## 2.2.5. POWER UP STRAP OPTIONS (DBX)

Below is a list of all power on options that are loaded into the DBX, based on the voltage level present on the respective strappings at the rising edge of CRESET#. To enable the different modes, external pullups should be approximately 10 K $\Omega$  to 3.3V. Note that all signals that are used to select powerup strap options are connected to weak internal pulldowns.

Signal	Register Name/bit	Description						
PD[5:2]		<b>Test Mode:</b> See Testability Section						
PD1		<p><b>HCLKIN Input Buffer Select:</b> PD1 selects whether the 2.5V or 3.3V mode is enabled.</p> <table border="1"> <thead> <tr> <th>PC1</th> <th>HCLKIN Input Buffer Select</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>3.3V Input (Default)</td> </tr> <tr> <td>1</td> <td>2.5V Input</td> </tr> </tbody> </table>	PC1	HCLKIN Input Buffer Select	0	3.3V Input (Default)	1	2.5V Input
PC1	HCLKIN Input Buffer Select							
0	3.3V Input (Default)							
1	2.5V Input							

### 3.0. REGISTER DESCRIPTION

The PMC contains two sets of software accessible registers (I/O Mapped and Configuration registers), accessed via the Host CPU I/O address space. The I/O Mapped registers control access to PCI configuration space. Configuration Registers reside in PCI configuration space and specify PCI configuration, DRAM configuration, operating parameters, and optional system features.

The PMC internal registers (both I/O Mapped and Configuration registers) are accessible by the Host CPU. The registers can be accessed as Byte, Word (16-bit), or Dword (32-bit) quantities, with the exception of CONFADD which can only be accessed as a Dword. All multi-byte numeric fields use "little-endian" ordering (i.e., lower addresses contain the least significant parts of the field). The following nomenclature is used for access attributes.

**RO**      **Read Only.** If a register is read only, writes to this register have no effect.  
**R/W**      **Read/Write.** A register with this attribute can be read and written.  
**R/WC**     **Read/Write Clear.** A register bit with this attribute can be read and written. However, a write of 1 clears (sets to 0) the corresponding bit and a write of 0 has no effect.

Some of the PMC registers described in this section contain reserved bits. Software must deal correctly with fields that are reserved. On reads, software must use appropriate masks to extract the defined bits and not rely on reserved bits being any particular value. On writes, software must ensure that the values of reserved bit positions are preserved. That is, the values of reserved bit positions must first be read, merged with the new values for other bit positions and then written back.

In addition to reserved bits within a register, the PMC contains address locations in the PCI configuration space that are marked "Reserved" (Table 3-1). The PMC responds to accesses to these address locations by completing the host cycle. When a reserved register location is read, a zero value is returned. Software should not write to reserved PMC configuration locations in the device-specific region (above address offset 3Fh).

During a hard reset, the PMC sets its internal configuration registers to predetermined **default** states. The default state represents the minimum functionality feature set required to successfully bring up the system. Hence, it does not represent the optimal system configuration. It is the responsibility of the system initialization software (usually BIOS) to properly determine the DRAM configurations, operating parameters and optional system features that are applicable, and to program the PMC registers accordingly.

**Note:** The 440FX PCIset depends on the atomicity of configuration cycles in a 2-way SMP system. Thus, software (BIOS or OS) must guarantee that in a system with two processors only one processor can access the configuration space at any time. During system initialization, only the "Boot Processor" must be allowed access to configuration space. Additionally, PnP BIOS and EISA configuration utilities must guarantee that addresses 0CF8h to 0CFh are allocated as motherboard addresses and not available as I/O locations.

#### 3.1. I/O Mapped Registers

The PMC contains two registers that reside in the CPU I/O address space—the Configuration Address (CONFADD) Register and the Configuration Data (CONFDATA) Register. The Configuration Address Register enables/disables the configuration space and determines what portion of configuration space is visible through the Configuration Data window.

### 3.1.1. CONFADD—CONFIGURATION ADDRESS REGISTER

I/O Address: 0CF8h (Accessed as a Dword)  
 Default Value: 00000000h  
 Access: Read/Write

CONFADD is a 32-bit register accessed only when referenced as a Dword. A Byte or Word reference will "pass through" the Configuration Address Register to the PCI Bus. The CONFADD Register contains the Bus Number, Device Number, Function Number, and Register Number for which a subsequent configuration access is intended.

Bit	Descriptions
31	<b>Configuration Enable (CONE).</b> 1=Enable. 0=Disable.
30:24	<b>Reserved.</b>
23:16	<b>Bus Number (BUSNUM).</b> When BUSNUM is programmed to 00h, the target of the configuration cycle is either the PMC or the PCI Bus that is directly connected to the PMC, depending on the Device Number field. If the Bus Number is programmed to 00h and the PMC is not the target, a type 0 configuration cycle is generated on PCI. If the Bus Number is non-zero, a type 1 configuration cycle is generated on PCI with the Bus Number mapped to AD[23:16] during the address phase.
15:11	<b>Device Number (DEVNUM).</b> This field selects one agent on the PCI Bus selected by the Bus Number. During a Type 1 Configuration cycle, this field is mapped to AD[15:11]. During a Type 0 configuration cycle, this field is decoded and one of AD[31:11] is driven to 1. The PMC is always Device Number 0.
10:8	<b>Function Number (FUNCNUM).</b> This field is mapped to AD[10:8] during PCI configuration cycles. This allows the configuration registers of a particular function in a multi-function device to be accessed. The PMC responds to configuration cycles with a function number of 000b; all other function number values attempting access to the PMC (Device Number = 0, Bus Number = 0) generate a type 0 configuration cycle on the PCI Bus with no IDSEL asserted, which results in a master abort.
7:2	<b>Register Number (REGNUM).</b> This field selects one register within a particular bus, device, and function as specified by the other fields in the Configuration Address Register. This field is mapped to AD[7:2] during PCI configuration cycles.
1:0	<b>Reserved.</b>

### 3.1.2. CONFDATA—CONFIGURATION DATA REGISTER

I/O Address: 0CFCh  
 Default Value: 00000000h  
 Access: Read/Write

CONFDATA is a 32-bit read/write window into configuration space. The portion of configuration space that is referenced by CONFDATA is determined by the contents of CONFADD.

Bit	Descriptions
31:0	<b>Configuration Data Window (CDW).</b> If bit 31 of CONFADD is 1, any I/O reference in the CONFDATA I/O space is mapped to configuration space using the contents of CONFADD.

## 3.2. PCI Configuration Space Mapped Registers

The PCI Bus defines a slot based "configuration space" that allows each device to contain up to 256 8-bit configuration registers. The PCI specification defines two bus cycles to access the PCI configuration space—**Configuration Read** and **Configuration Write**. While memory and I/O spaces are supported by the Pentium microprocessor, configuration space is not supported. The PCI specification defines two mechanisms to access configuration space, Mechanism #1 and Mechanism #2. The PMC only supports Mechanism #1 (both type 0 and 1 accesses). Table 1 shows the PMC configuration space.

The configuration access mechanism makes use of the CONFADD Register and CONFDATA Register. To reference a configuration register, a Dword I/O write cycle is used to place a value into CONFADD that specifies the PCI Bus, the device on that bus, the function within the device, and a specific configuration register of the device function being accessed. CONFADD[31] must be 1 to enable a configuration cycle. Then, CONFDATA becomes a window onto four bytes of configuration space specified by the contents of CONFADD. Read/write accesses to CONFDATA generates a PCI configuration cycle to the address specified by CONFADD.

### 3.2.1. PCI CONFIGURATION ACCESS

**Type 0 Access:** If the Bus Number field of CONFADD is 0, a type 0 configuration cycle is generated on PCI. CONFADD[10:2] is mapped directly to AD[10:2]. The Device Number field of CONFADD is decoded onto AD[31:11]. The PMC is Device #0 and does not pass its configuration cycles to PCI. Thus, AD11 is never asserted. (For accesses to device #1, AD12 is asserted, etc., to Device #20 which asserts AD31.) Only one AD line is asserted at a time. All device numbers higher than 20 cause a type 0 configuration access with no IDSEL asserted, which results in a master abort.

**Type 1 Access:** If the Bus Number field of CONFADD is non-zero, a type 1 configuration cycle is generated on PCI. CONFADD[23:2] are mapped directly to AD[23:2]. AD[1:0] are driven to 01 to indicate a Type 1 Configuration cycle. All other lines are driven to 0.

Table 1. PMC Configuration Space

Address Offset	Register Symbol	Register Name	Access
00–01h	VID	Vendor Identification	RO
02–03h	DID	Device Identification	RO
04–05h	PCICMD	PCI Command Register	R/W
06–07h	PCISTS	PCI Status Register	RO, R/WC
08	RID	Revision Identification	RO
09–0Bh	CLASSC	Class Code	RO
0Ch	—	Reserved	—
0Dh	MLT	Master Latency Timer	R/W
0Eh	HEADT	Header Type	R/W
0Fh	BIST	BIST Register	R/W
10–4Fh	—	Reserved	—
50–51h	PMCCFG	PMC Configuration	R/W
52h	DETURBO	Deturbo Counter Control	R/W
53h	DBC	DBX Buffer Control	R/W
54h	AXC	Auxiliary Control	R/W
55–56h	DRAMR	DRAM Row Type	R/W
57h	DRAMC	DRAM Control	R/W
58h	DRAMT	DRAM Timing	R/W
59–5Fh	PAM[6:0]	Programmable Attribute Map (7 registers)	R/W
60–67h	DRB[7:0]	DRAM Row Boundary (8 registers)	R/W
68h	FDHC	Fixed DRAM Hole Control	R/W
69–6Fh	—	Reserved	—
70h	MTT	Multi-Transaction Timer	R/W
71h	CLT	CPU Latency Timer	R/W
72h	SMRAM	System Management RAM Control	R/W
73–8Fh	—	Reserved	—
90h	ERRCMD	Error Command Register	R/W
91h	ERRSTS	Error Status Register	R/WC
92h	—	Reserved	—
93h	TRC	Turbo Reset Control Register	R/WC
94–FFh	—	Reserved	—

**3.2.2. VID—VENDOR IDENTIFICATION REGISTER**

Address Offset: 00–01h  
 Default Value: 8086h  
 Attribute: Read Only

The VID register contains the vendor identification number. This 16-bit register combined with the Device Identification register uniquely identify any PCI device. Writes to this register have no effect.

Bit	Description
15:0	<b>Vendor Identification Number.</b> This is a 16-bit value assigned to Intel. Intel VID = 8086h.

**3.2.3. DID—DEVICE IDENTIFICATION REGISTER**

Address Offset: 02–03h  
 Default Value: 1237h  
 Attribute: Read Only

This 16-bit register combined with the Vendor Identification register uniquely identifies any PCI device. Writes to this register have no effect.

Bit	Description
15:0	<b>Device Identification Number.</b> This is a 16 bit value assigned to the PMC.

**3.2.4. PCICMD—PCI COMMAND REGISTER**

Address Offset: 04–05h  
 Default Value: 0006h  
 Attribute: Read/Write

This 16-bit register provides basic control over the PMC's ability to respond to PCI cycles. The PCICMD register enables and disables the SERR# signal, the parity error signal (PERR#), PMC response to PCI special cycles, and enables and disables PCI master accesses to main memory.

Bit	Descriptions
15:10	<b>Reserved.</b>
9	<b>Fast Back-to-Back.</b> Not Implemented. This bit is hardwired to 0.
8	<b>SERR# Enable (SERRE).</b> If this bit is set to a 1, the PMC generates SERR# signal for all relevant bits set in the ERRSTS and PCISTS registers as controlled with the corresponding bits of the ERRCMD register. If SERRE is reset to 0, then SERR# is never driven by the PMC. Address Parity error reporting as a target is enabled by the PERRE bit located in this register.
7	<b>Address/Data Stepping.</b> Not Implemented. This bit is hardwired to 0.

Bit	Descriptions
6	<b>Parity Error Enable (PERRE).</b> PERRE controls the PMC's response to PCI parity errors during data phase when PMC receives the data. If PERRE=1, these errors are reported on the PERR# signal. Note that, when PERRE=1, address parity errors are reported via the SERR# mechanism (if enabled via SERRE bit). If PERRE=0, parity errors are not signaled (i.e., PMC's parity checking is disabled).
5	<b>Reserved.</b>
4	<b>Memory Write and Invalidate Enable.</b> Not Implemented. This bit is hardwired to 0.
3	<b>Special Cycle Enable.</b> Not Implemented. This bit is hardwired to 0.
2	<b>Bus Master Enable (BME).</b> Not Implemented. This bit is hardwired to 1 (PMC bus master capability always enabled).
1	<b>Memory Access Enable (MAE).</b> Not Implemented. This bit is hardwired to 1 (PMC allows PCI master access to main memory).
0	<b>I/O Access Enable (IOAE).</b> Not Implemented. This bit is hardwired to 0 (PMC does not respond to PCI I/O cycles).

### 3.2.5. PCISTS—PCI STATUS REGISTER

Address Offset: 06–07h  
 Default Value: 0280h  
 Attribute: Read Only, Read/Write Clear

PCISTS is a 16-bit status register that reports the occurrence of a PCI master abort and PCI target abort. PCISTS also indicates the DEVSEL# timing that has been set by the PMC hardware. Bits [15:12,8] are read/write clear and bits [10:9] are read only.

Bit	Descriptions
15	<b>Detected Parity Error (DPE)—RW/C.</b> This bit is set to a 1 to indicate PMC's detection of a parity error in either the data or address phase when it is the target of the PCI cycle. Software sets this bit to 0 by writing a 1 to it. Note that the function of this bit is not affected by the PERRE bit.
14	<b>Signaled System Error (SSE)—RW/C.</b> When the PMC asserts the SERR# signal, this bit is also set to 1. Software sets this bit to 0 by writing a 1 to it.
13	<b>Received Master Abort Status (RMAS)—RW/C.</b> When the PMC terminates a Host-to-PCI transaction (PMC is a PCI master) with an unexpected master abort, this bit is set to 1. Note that master abort is the normal and expected termination of PCI special cycles. Software sets this bit to 0 by writing a 1 to it.
12	<b>Received Target Abort Status (RTAS)—RW/C.</b> When a PMC-initiated PCI transaction is terminated with a target abort, RTAS is set to 1. The PMC also asserts SERR# if enabled in the ERRCMD register. Software sets this bit to 0 by writing a 1 to it.
11	<b>Signaled Target Abort Status (STAS)—RW/C.</b> When, as a PCI target, the PMC initiates a target abort to terminate a PCI transaction, STAS is set to a 1. Software sets this bit to 0 by writing a 1 to it.
10:9	<b>DEVSEL# Timing (DEVT)—RO.</b> This 2-bit field indicates the timing of the DEVSEL# signal when the PMC responds as a target, and is hard-wired to the value 01b (medium) to indicate the time when a valid DEVSEL# can be sampled by the initiator of the PCI cycle.

Bit	Descriptions
8	<b>Data Parity Detected (DPD)—RW/C.</b> This bit is set to a 1, when conditions 1-3 below are met. Software sets this bit to 0 by writing a 1 to it. <ol style="list-style-type: none"> <li>1. The PMC asserted PERR# or sampled PERR# asserted.</li> <li>2. The PMC was the initiator for the operation in which the error occurred.</li> <li>3. The PERRE bit in the PCI command register is set to 1.</li> </ol>
7	<b>Fast Back-to-Back (FB2B)—RO.</b> This bit is hardwired to 1, since the PMC as a target supports fast back-to-back transactions when transactions are to a different agent.
6:0	<b>Reserved.</b>

### 3.2.6. RID—REVISION IDENTIFICATION REGISTER

Address Offset: 08h  
 Default Value: xxh  
 Attribute: Read Only

This register contains the revision number of the PMC. These bits are read only and writes to this register have no effect.

Bit	Description
7:0	<b>Revision Identification Number.</b> This is an 8-bit value that indicates the revision identification number for the PMC. Please refer to Specification Update or Stepping Information for RID.

### 3.2.7. CLASSC—CLASS CODE REGISTER

Address Offset: 09–0Bh  
 Default Value: 060000h  
 Attribute: Read Only

This register contains the device programming interface information related to the Sub-Class Code and Base Class Code definition for the PMC. This register also contains the Base Class Code and the function sub-class in relation to the Base Class Code.

Bit	Description
23:16	<b>Base Class Code (BASEC):</b> 06=Bridge device.
15:8	<b>Sub-Class Code (SCC):</b> 00h=Host Bridge.
7:0	<b>Programming Interface (PI):</b> 00h=Hardwired as a Host-to-PCI Bridge.

**3.2.8. MLT—MASTER LATENCY TIMER REGISTER**

Address Offset: 0Dh  
 Default Value: 00h  
 Attribute: Read/Write

MLT is an 8-bit register that controls the amount of time the PMC, as a bus master, can burst data on the PCI Bus. The Count Value is an 8 bit quantity. However, MLT[2:0] are hardwired to 0. The PMC's MLT is used to guarantee to the PCI agents (other than PMC) a minimum amount of the system resources.

Bit	Description
7:3	<b>Master Latency Timer Count Value.</b> The number of clocks programmed in this field represents the guaranteed time slice (measured in PCI clocks) allotted to the PMC, after which it must complete the current data transfer phase and then surrender the bus as soon as its bus grant is removed. For example, if the MLT Register is programmed to 18h, then the value is 24 PCI clocks. The default value of MLT is 00h and disables this function.
2:0	<b>Reserved.</b>

**3.2.9. HEADT—HEADER TYPE REGISTER**

Address Offset: 0Eh  
 Default: 00h  
 Attribute: Read Only

This register contains the Header Type of the PMC. This code is 00h indicating that the PMC's configuration space map follows the basic format. This register is read only.

Bit	Description
7:0	<b>Header Type (HTYPE):</b> 00h=Basic configuration space format.

**3.2.10. BIST—BIST REGISTER**

Address Offset: 0Fh  
 Default: 00h  
 Attribute: Read/Write

The Built In Self Test (BIST) function is not supported by the PMC. Writes to this register have no affect.

Bit	Descriptions
7:0	<b>Reserved.</b>

**3.2.11. PMCCFG—PMC CONFIGURATION REGISTER**

Address Offset: 50–51h  
 Default Value: xxh (some bits reflect hardware strapping options)  
 Attribute: Read/Write, Read Only

PMCCFG is a 16-bit register that is controls and logs the system level configuration.

Bit	Description												
15	<b>WSC Protocol Enable (WPE)—R/W.</b> 1=Disable. 0=Enable(default). This bit enables WSC protocol which is required for a two processor system using the IOAPIC. In a uniprocessor system, this bit should be disabled.												
14	<b>Row Select or Extra Copy of Lower Memory Address Enable (ELME)—RO.</b> This bit reflects the value on PC8 sampled on the rising edge of PWROK. If this bit is set to 1, the two pins on the PMC are configured as two additional row selects (RAS[7:6]#). If this bit is set to a 0 (default), an extra copy of MAB[1:0] is enabled.												
13:10	<b>Reserved.</b>												
9:8	<b>Host Frequency Select (HFS)—RO.</b> These bits reflect the polarity of the PC[3:2] sampled during the rising edge of PWROK. These bits are status bits only and writes to these bits have no affect. The values reflect the host bus frequency used: <table border="1" style="margin-left: 20px;"> <thead> <tr> <th>HFS</th> <th>Host bus frequency</th> </tr> </thead> <tbody> <tr> <td>00</td> <td>Reserved</td> </tr> <tr> <td>01</td> <td>60 MHz</td> </tr> <tr> <td>10</td> <td>66 MHz</td> </tr> <tr> <td>11</td> <td>Reserved</td> </tr> </tbody> </table>	HFS	Host bus frequency	00	Reserved	01	60 MHz	10	66 MHz	11	Reserved		
HFS	Host bus frequency												
00	Reserved												
01	60 MHz												
10	66 MHz												
11	Reserved												
7	<b>Reserved.</b>												
6	<b>ECC/Parity TEST Enable (EPTE)—R/W.</b> 1=ECC Test Mode. 0=Normal mode (default). When set, The PMC/DBX handles subsequent cycles to DRAM as described in the Functional Description section until this bit is written to 0.												
5:4	<b>DRAM Data Integrity Mode (DDIM)—R/W.</b> These bits provide software configurability of selecting ECC mode/parity or non-parity mode. Note that after reset, non-parity mode is enabled. BIOS should setup this field appropriately for the kind of SIMM installed in the system. <table border="1" style="margin-left: 20px;"> <thead> <tr> <th>DDIM</th> <th>DRAM Data Integrity Mode</th> </tr> </thead> <tbody> <tr> <td>00</td> <td>No Parity or ECC Checking (default)</td> </tr> <tr> <td>01</td> <td>Parity Generation and Checking</td> </tr> <tr> <td>10</td> <td>ECC Checking/Generation Enabled and Correction Disabled(SED/DED)</td> </tr> <tr> <td>11</td> <td>ECC Checking/Generation Enabled and Correction Enabled(SEC/DED)</td> </tr> </tbody> </table>	DDIM	DRAM Data Integrity Mode	00	No Parity or ECC Checking (default)	01	Parity Generation and Checking	10	ECC Checking/Generation Enabled and Correction Disabled(SED/DED)	11	ECC Checking/Generation Enabled and Correction Enabled(SEC/DED)		
DDIM	DRAM Data Integrity Mode												
00	No Parity or ECC Checking (default)												
01	Parity Generation and Checking												
10	ECC Checking/Generation Enabled and Correction Disabled(SED/DED)												
11	ECC Checking/Generation Enabled and Correction Enabled(SEC/DED)												
3	<b>Reserved.</b>												
2	<b>In-Order Queue Depth (IOQD)—RO.</b> 1=In-order Queue depth of 4. 0=In-order queue depth of 1. This bit reflects value sampled on the A7# signal. <table border="1" style="margin-left: 20px;"> <thead> <tr> <th>A7# Electrical Value</th> <th>A7# Logical Value</th> <th>IOQD Value</th> <th>Depth</th> </tr> </thead> <tbody> <tr> <td>1.5 V</td> <td>0</td> <td>1</td> <td>4</td> </tr> <tr> <td>0.0 V</td> <td>1</td> <td>0</td> <td>1</td> </tr> </tbody> </table>	A7# Electrical Value	A7# Logical Value	IOQD Value	Depth	1.5 V	0	1	4	0.0 V	1	0	1
A7# Electrical Value	A7# Logical Value	IOQD Value	Depth										
1.5 V	0	1	4										
0.0 V	1	0	1										
1:0	<b>Reserved.</b>												

**3.2.12. DETURBO—DETURBO COUNTER REGISTER**

Address Offset: 52h  
 Default Value: 00h  
 Access: Read/Write

Some software packages rely on the operating speed of the processor to time certain system events. To maintain backward compatibility with these software packages, the PMC provides a mechanism to emulate a slower operating speed. DETURBO register supports a deturbo mode by providing a mechanism to stall the CPU bus pipeline using the BPRI# signal, at a rate programmed in this register. The deturbo mode must be first enabled in the TRC Register.

Bit	Description
7:0	<b>DETURBO Count (DC).</b> In the deturbo mode FLUSH# is held asserted to disable caching and the CPU bus pipeline is stalled at a rate determined by this field. Deturbo counter value is compared to an 8-bit counter running at the CPU system bus clock divided by 8. When the counter value is equal to the value specified in this register, BPRI# is asserted. BPRI# is negated when the counter rolls over to 00h and when it is less than this register value. The deturbo emulation speed is directly proportional to the value in this register. Smaller values in this register allows for slower emulation speed.

**3.2.13. DBC—DBX BUFFER CONTROL**

Address Offset: 53h  
 Default Value: 80h  
 Access: Read/Write

This 8-bit register allows for DBX buffer control as well as control for the advanced features included in the PMC.

**NOTE**

All PMC testing assumes the features in this register are enabled. This register has been included only as a means to ensure functionality. No assumptions should be made about the existence of this register in the future versions of the PMC.

Bit	Description
7	<b>Delayed Transaction Enable (DTE).</b> 1=Enable (default). 0=Disable. When this bit is enabled, a read cycle from PCI to DRAM is immediately retried due to any pending CPU-to-PCI cycle.
6	<b>CPU-to-PCI IDE Posting Enable (CPIE).</b> 1=Enable (01F0h and 0170h). 0=Disable (default). When disabled, the cycles are treated as normal I/O write transactions.
5	<b>USWC Write Post During I/O Bridge Access Enable (UWPIO).</b> 1=Enable. 0=Disable (default). When enabled, the PMC allows posting of CPU-to-PCI cycles destined for a USWC region, even during a passive release cycle.
4	<b>PCI Delayed Transaction Timer Disable (DTD).</b> 1=Disable. 1=Enable (default). When this bit is enabled, the PMC retries any PCI access that takes longer than 32 PCI clocks.
3	<b>CPU-to-PCI Write Post Enable (CPWE).</b> 1=Enable. 0=Disable (default). This enables the CPU-to-PCI posting.

Bit	Description
2	<b>PCI-to-DRAM Pipeline Enable (PDPE).</b> 1=Enable. 0=Disable (default). When this bit is disabled, it restricts pipelining of PCI-to-DRAM write cycles.
1	<b>PCI Burst Write Combining Enable (BWCE).</b> 1=Enable. 0=Disable (default). When this bit is enabled, DBX is allowed to combine back-to-back sequential CPU-to-PCI writes (Dword or larger) into a single PCI write burst.
0	<b>Read-Around-Write Enable (RAWWE).</b> 1=Enable. 0=Disable (default). When disabled, all posted writes in the DBX are retired before a CPU or PCI read access is serviced.

**3.2.14. AXC—AUXILIARY CONTROL REGISTER**

Address Offset: 54h  
 Default Value: 00h  
 Access: Read/Write

This 8-bit register controls auxiliary functions such as additional DRAM timings and memory I/O buffer strength.

Bit	Description
7	<b>RAS Precharge Enable (RPE).</b> 1=4 host clocks. 0=3 host clocks (default).
6:2	<b>Reserved.</b>
1	<b>Lower Memory Address Buffer Set A (LMAA).</b> 1=8 mA for MAA[1:0]. 0= 12 mA for MAA[1:0]. This bit selects the I/O buffer strength of MAA[1:0] signals.
0	<b>Reserved.</b>

### 3.2.15. DRT—DRAM ROW TYPE REGISTER

Address Offset: 55–56h  
 Default Value: 0000h  
 Access: Read/Write

This 16-bit register identifies the type of DRAM (BEDO, EDO or FPM) used in each row, or if the row is empty. BIOS should program this register for optimum performance if BEDO or EDO DRAMs are used. The register also identifies if a particular row is left unpopulated and the total number of rows populated in the system. The hardware uses these bits to determine the correct cycle timing to use before a DRAM cycle is run. This register must be accessed as bytes.

Bit	Description			
15:0	<b>DRAM Row Type (DRT).</b> Each pair of bits in this register corresponds to the DRAM row identified by the corresponding DRB Register.			
	<b>DRT</b>	<b>Corresponding DRB Register</b>	<b>DRT</b>	<b>Corresponding DRB Register</b>
	DRT[1:0]	DRB0, row 0	DRT[9:8]	DRB4, row 4
	DRT[3:2]	DRB1, row 1	DRT[11:10]	DRB5, row 5
	DRT[5:4]	DRB2, row 2	DRT[13:12]	DRB6, row 6
	DRT[7:6]	DRB3, row 3	DRT[15:14]	DRB7, row 7
	The value programmed in each DRT bit pair uniquely identifies the DRAM timings used for the corresponding row.			
	<b>DRT Pair</b>	<b>Corresponding DRB Register</b>		
	00	FPM mode		
	01	EDO mode		
	10	BEDO mode		
	11	Empty Row		

### 3.2.16. DRAMC—DRAM CONTROL REGISTER

Address Offset: 57h  
 Default Value: 01h  
 Access: Read/Write

This 8-bit register controls main memory DRAM operating modes and features.

Bit	Description
7	<b>Reserved.</b>
6	<b>DRAM Refresh Queue Enable (DRQE).</b> 1=Enable (The internal 4-deep refresh queue is enabled with the 4th request being the priority request. All refresh requests are queued.). 0=Disable (default). All refreshes are priority requests.  Note that all PMC testing will be done assuming this bit is always enabled. This bit has been included only as a means to ensure functionality. No assumptions should be made about the existence of this bit in the future versions of the PMC.
5	<b>DRAM EDO Auto-Detect Mode Enable (DEDM).</b> When DEDM=1, a special timing mode for BIOS to detect EDO DRAM type on a row-by-row basis is enabled. 0=Disable (default).
4	<b>DRAM Refresh Type Select (DRFT).</b> 1= RAS only. 0= CAS-before-RAS.

Bit	Description												
3	<b>Reserved.</b>												
2:0	<p><b>DRAM Refresh Rate (DRR).</b> The DRAM refresh rate is adjusted according to value in this field. When normal is selected, the refresh rate is determined by the HFS field in the PMCCFG register. Note that refresh is also disabled via this field, and that disabling refresh results in the eventual loss of DRAM data. Note that changing DRR value resets the refresh request timer. The fast refresh mode implements a refresh cycle every 32 host clocks.</p> <table border="1"> <thead> <tr> <th>Bits[2:0]</th> <th>Host Bus Frequency</th> </tr> </thead> <tbody> <tr> <td>000</td> <td>Refresh Disabled</td> </tr> <tr> <td>001</td> <td>Normal</td> </tr> <tr> <td>01x</td> <td>Reserved</td> </tr> <tr> <td>1xx</td> <td>Reserved</td> </tr> <tr> <td>111</td> <td>Fast Refresh</td> </tr> </tbody> </table>	Bits[2:0]	Host Bus Frequency	000	Refresh Disabled	001	Normal	01x	Reserved	1xx	Reserved	111	Fast Refresh
Bits[2:0]	Host Bus Frequency												
000	Refresh Disabled												
001	Normal												
01x	Reserved												
1xx	Reserved												
111	Fast Refresh												

### 3.2.17. DRAMT —DRAM TIMING REGISTER

Address Offset: 58h  
 Default Value: 10h  
 Access: Read/Write

This 8-bit register controls main memory DRAM timings.

Bit	Description																				
7	<b>Reserved.</b>																				
6	<p><b>WCBR Mode Enable (WME).</b> 1=Enable. 0=Disable. The WCBR programming mode for BEDO DRAMs is controlled by this bit and allows setting the BEDO DRAMs data mode in x86 toggle burst mode or linear burst mode. This bit should only be enabled by the BIOS during the BEDO DRAM auto-detect sequence as described in section 4.3.</p>																				
5:4	<p><b>DRAM Read Burst Timing (DRBT).</b> The DRAM read burst timings are controlled by the DRBT field. Slower rates may be required in certain system designs to support loose layouts or slower memories. Most system designs will be able to use one of the faster burst mode timings. The timing used depends on the type of DRAM on a per-row basis, as indicated by the DRT register.</p> <table border="1"> <thead> <tr> <th>DRBT</th> <th>BEDO Rate</th> <th>EDO Rate</th> <th>FPM Rate</th> </tr> </thead> <tbody> <tr> <td>00</td> <td>x333</td> <td>x444</td> <td>x444</td> </tr> <tr> <td>01</td> <td>x222</td> <td>x333</td> <td>x444</td> </tr> <tr> <td>10</td> <td>x222</td> <td>x222</td> <td>x333</td> </tr> <tr> <td>11</td> <td>Reserved</td> <td>Reserved</td> <td>Reserved</td> </tr> </tbody> </table>	DRBT	BEDO Rate	EDO Rate	FPM Rate	00	x333	x444	x444	01	x222	x333	x444	10	x222	x222	x333	11	Reserved	Reserved	Reserved
DRBT	BEDO Rate	EDO Rate	FPM Rate																		
00	x333	x444	x444																		
01	x222	x333	x444																		
10	x222	x222	x333																		
11	Reserved	Reserved	Reserved																		
3:2	<p><b>DRAM Write Burst Timing (DWBT).</b> The DRAM write burst timings are controlled by the DWBT field. Slower rates may be required in certain system designs to support loose layouts or slower memories. Most system designs will be able to use one of the faster burst mode timings. The timing used depends on the type of DRAM on a per-row basis, as indicated by the DRT register.</p> <table border="1"> <thead> <tr> <th>DWBT</th> <th>BEDO/EDO Rate</th> <th>FPM Rate</th> </tr> </thead> <tbody> <tr> <td>00</td> <td>x444</td> <td>x444</td> </tr> <tr> <td>01</td> <td>x333</td> <td>x444</td> </tr> <tr> <td>10</td> <td>x333</td> <td>x333</td> </tr> <tr> <td>11</td> <td>x222</td> <td>x333</td> </tr> </tbody> </table>	DWBT	BEDO/EDO Rate	FPM Rate	00	x444	x444	01	x333	x444	10	x333	x333	11	x222	x333					
DWBT	BEDO/EDO Rate	FPM Rate																			
00	x444	x444																			
01	x333	x444																			
10	x333	x333																			
11	x222	x333																			

Bit	Description
1	<b>RASx# to CASx# Delay (RCD).</b> 1=One clock between the assertion of RASx# and CASx#. 0=Zero clocks. This has no impact on page hit cases and affects only Row and Page misses.
0	<b>MA Wait State (MAWS).</b> When MAWS = 1, one additional wait state is inserted before the assertion of the first MAxx and CASx#/RASx# assertion during DRAM read or write leadoff cycles. This affects page hit and row miss cases. When both MAWS and RCD bits are set, the MAWS functionality overrides.

### 3.2.18. PAM—PROGRAMMABLE ATTRIBUTE MAP REGISTERS (PAM[6:0])

Address Offset: PAM0 (59h) — PAM6 (5Fh)

Default Value: 00h

Attribute: Read/Write

The PMC allows programmable memory attributes on 13 memory segments of various sizes in the 640-Kbyte to 1-Mbyte address range. Seven Programmable Attribute Map (PAM) Registers are used to support these features. Cacheability of these areas is controlled via the MTRR registers in the CPU processor. Two bits are used to specify memory attributes for each memory segment. These bits apply to both CPU accesses and PCI initiator accesses to the PAM areas. These attributes are:

**RE Read Enable.** When RE=1, CPU read accesses to the corresponding memory segment are claimed by the PMC and directed to main memory. Conversely, when RE=0, the CPU read accesses are directed to PCI.

**WE Write Enable.** When WE=1, CPU write accesses to the corresponding memory segment are claimed by the PMC and directed to main memory. Conversely, when WE=0, the CPU write accesses are directed to PCI.

The RE and WE attributes permit a memory segment to be read only, write only, read/write, or disabled. For example, if a memory segment has RE=1 and WE=0, the segment is read only. Each PAM Register controls two regions, typically 16-Kbyte in size. Each of these regions has a 4-bit field. The four bits that control each region have the same encoding and are defined Table 2.

Table 2. Attribute Bit Assignment

Bits [7,6,3,2] Reserved	Bits [5, 1] WE	Bits [4, 0] RE	Description
x	0	0	<b>Disabled.</b> DRAM is disabled and all accesses are directed to PCI. PMC does not respond as a PCI target for any read or write access to this area.
x	0	1	<b>Read Only.</b> Reads are forwarded to DRAM and writes are forwarded to PCI for termination. This write protects the corresponding memory segment. PMC responds as a PCI target for read accesses but not for any write accesses.
x	1	0	<b>Write Only.</b> Writes are forwarded to DRAM and reads are forwarded to the PCI for termination. PMC responds as a PCI target for write accesses but not for any read accesses.
x	1	1	<b>Read/Write.</b> This is the normal operating mode of main memory. Both read and write cycles from the CPU are claimed by the PMC and forwarded to DRAM. PMC responds as a PCI target for both read and write accesses.

As an example, consider a BIOS that is implemented on the expansion bus. During the initialization process the BIOS can be shadowed in main memory to increase the system performance. When a BIOS is shadowed in main memory, it should be copied to the same address location. To shadow the BIOS, the attributes for that address range should be set to write only. The BIOS is shadowed by first doing a read of that address. This read is forwarded to the expansion bus. The CPU then does a write of the same address, which is directed to main memory. After the BIOS is shadowed, the attributes for that memory area are set to read only so that all writes are forwarded to the expansion bus. Table 3 shows the PAM registers and the associated attribute bits:

**Table 3. PAM Registers and Associated Memory Segments**

PAM Reg	Attribute Bits	Memory Segment	Comments	Offset
PAM0[3:0]	Reserved	Reserved	Reserved	59h
PAM0[7:4]	R R WE RE	0F0000–0FFFFFFh	BIOS Area	59h
PAM1[3:0]	R R WE RE	0C0000–0C3FFFh	ISA Add-on BIOS	5Ah
PAM1[7:4]	R R WE RE	0C4000–0C7FFFh	ISA Add-on BIOS	5Ah
PAM2[3:0]	R R WE RE	0C8000–0CBFFFh	ISA Add-on BIOS	5Bh
PAM2[7:4]	R R WE RE	0CC000–0CFFFFh	ISA Add-on BIOS	5Bh
PAM3[3:0]	R R WE RE	0D0000–0D3FFFh	ISA Add-on BIOS	5Ch
PAM3[7:4]	R R WE RE	0D4000–0D7FFFh	ISA Add-on BIOS	5Ch
PAM4[3:0]	R R WE RE	0D8000–0DBFFFh	ISA Add-on BIOS	5Dh
PAM4[7:4]	R R WE RE	0DC000–0DFFFFh	ISA Add-on BIOS	5Dh
PAM5[3:0]	R R WE RE	0E0000–0E3FFFh	BIOS Extension	5Eh
PAM5[7:4]	R R WE RE	0E4000–0E7FFFh	BIOS Extension	5Eh
PAM6[3:0]	R R WE RE	0E8000–0EBFFFh	BIOS Extension	5Fh
PAM6[7:4]	R R WE RE	0EC000–0EFFFFh	BIOS Extension	5Fh

**DOS Application Area (00000–9FFFh).** The DOS area is 640 Kbytes in size and it is further divided into two parts. The 512-Kbyte area at 0 to 7FFFFh is always mapped to the main memory controlled by the PMC, while the 128-Kbyte address range from 080000 to 09FFFFh can be mapped to PCI or to main DRAM. By default this range is mapped to main memory and can be declared as a main memory hole (accesses forwarded to PCI) via the FDHC Register

**Video Buffer Area (A0000–BFFFFh).** This 128-Kbyte area is not controlled by attribute bits. The CPU - initiated cycles in this region are always forwarded to PCI for termination. This area can be programmed as SMM area via the SMRAM register.

**Expansion Area (C0000–DFFFFh).** This 128-Kbyte area is divided into eight 16-Kbyte segments which can be assigned with different attributes via PAM Control Register.

**Extended System BIOS Area (E0000–EFFFFh).** This 64-Kbyte area is divided into four 16-Kbyte segments which can be assigned with different attributes via PAM Control Register.

**System BIOS Area (F0000–FFFFFFh).** This area is a single 64-Kbyte segment which can be assigned with different attributes via PAM Control Register.

**3.2.19. DRB[0:7]—DRAM ROW BOUNDARY REGISTERS**

Address Offset:	DRB0 (60h) — DRB7 (67h)
Default Value:	01h
Access:	Read/Write

The PMC supports 8 rows of DRAM. The memory data interface is 64 bits wide. The DRAM Row Boundary registers define upper and lower addresses for each DRAM row. Contents of these 8-bit registers represent the boundary addresses in 8-Mbyte granularity. For example, a value of 01h indicates 8 Mbyte.

- 60h DRB0 = Total memory in row0 (in 8 Mbytes)
- 61h DRB1 = Total memory in row0 + row1 (in 8 Mbytes)
- 62h DRB2 = Total memory in row0 + row1 + row2 (in 8 Mbytes)
- 63h DRB3 = Total memory in row0 + row1 + row2 + row3 (in 8 Mbytes)
- 64h DRB4 = Total memory in row0 + row1 + row2 + row3 + row4 (in 8 Mbytes)
- 65h DRB5 = Total memory in row0 + row1 + row2 + row3 + row4 + row5 (in 8 Mbytes)
- 66h DRB6 = Total memory in row0 + row1 + row2 + row3 + row4 + row5 + row6 (in 8 Mbytes)
- 67h DRB7 = Total memory in row0 + row1 + row2 + row3 + row4 + row5 + row6 + row7 (in 8 Mbytes)

The DRAM array can be configured with 1 M x 36, 2M x 36, 4 M x 36, 8M x 36 and 16 M x 36 SIMMs. Each register defines an address range that causes a particular RAS# line to be asserted (e.g. if the first DRAM row is 8 Mbytes in size then accesses within the 0 to 8 Mbytes minus 1 range causes RAS0# to be asserted). The DRAM Row Boundary (DRB) registers are programmed with an 8-bit upper address limit value.

Bit	Description
7:0	<b>Row Boundary Address.</b> This 8-bit value is compared against address lines HA[30:23] to determine the upper address limit of a particular row (i.e., DRB minus previous DRB = row size).

**Row Boundary Address**

These 8 bit values represent the upper address limits of the eight rows (i.e., this row - previous row = row size). npolluted rows have a value equal to the previous row (row size = 0). DRB7 reflects the maximum amount of DRAM in the system. The top of memory is determined by the value written into DRB7. Note that the PMC supports a maximum of 1 Gbytes of DRAM.

As an example of a general purpose configuration where eight physical rows are configured for either single-sided or double-sided SIMMs, the memory array would be configured like the one shown in Figure 2. In this configuration, the PMC drives two RAS# signals directly to each SIMM row. If single-sided SIMMs are populated, the even RAS# signal is used and the odd RAS# is not connected. If double-sided SIMMs are used, both RAS# signals are used.

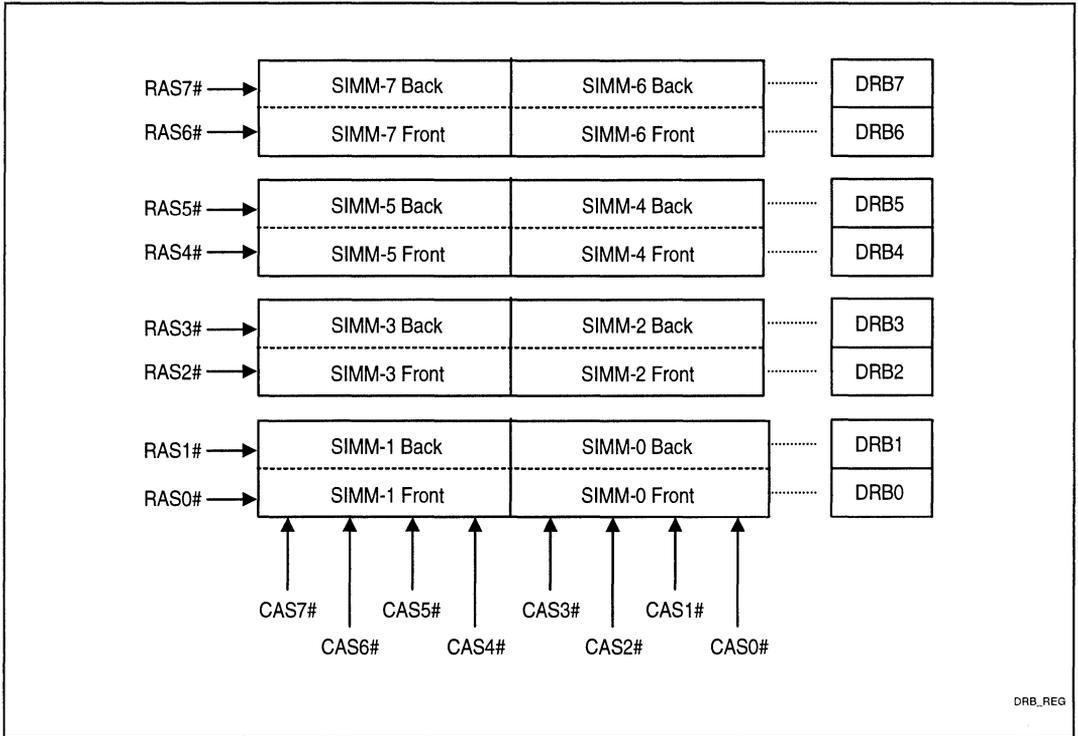


Figure 2. SIMMs and Corresponding DRB Registers

3.2.20. FDHC—FIXED DRAM HOLE CONTROL REGISTER

Address Offset: 68h  
 Default Value: 00h  
 Access: Read/Write

This 8-bit register controls 2 fixed DRAM holes: 512–640 Kbytes and 15–16 Mbytes.

Bit	Description										
7:6	<p><b>Hole Enable (HEN).</b> This field enables a memory hole in DRAM space. CPU cycles matching an enabled hole are passed on to PCI. PCI cycles matching an enabled hole are ignored by the PMC (no DEVSEL#). Note that a selected hole is not remapped.</p> <table border="1"> <thead> <tr> <th>Bits[7:6]</th> <th>Hole Enabled</th> </tr> </thead> <tbody> <tr> <td>0 0</td> <td>None</td> </tr> <tr> <td>0 1</td> <td>512 KB–640 KB (128 Kbytes)</td> </tr> <tr> <td>1 0</td> <td>15 MB–16 MB (1 Mbytes)</td> </tr> <tr> <td>1 1</td> <td>Reserved</td> </tr> </tbody> </table>	Bits[7:6]	Hole Enabled	0 0	None	0 1	512 KB–640 KB (128 Kbytes)	1 0	15 MB–16 MB (1 Mbytes)	1 1	Reserved
Bits[7:6]	Hole Enabled										
0 0	None										
0 1	512 KB–640 KB (128 Kbytes)										
1 0	15 MB–16 MB (1 Mbytes)										
1 1	Reserved										
5:0	Reserved.										

**3.2.21. MTT—MULTI-TRANSACTION TIMER REGISTER**

Address Offset: 70h  
 Default Value: 00h  
 Access: Read/Write

MTT is an 8-bit register that controls the amount of time that the PMC's arbiter allows a PCI initiator to perform multiple back-to-back transactions on the PCI bus within a guaranteed time slice (measured in terms of PCI clocks). The default value of MTT is 0 and disables this function.

**NOTE**

No assumptions should be made about the existence of this register in the future versions of the PMC.

Bit	Description
7:3	<b>Multi-Transaction Timer Count Value (MTTC):</b> The MTT value can be programmed with 8 clock granularity in the same manner as the MLT. For example, if the MTT is programmed to 20h, the selected value corresponds to the time period of 32 PCI clocks.
2:0	<b>Reserved.</b>

**3.2.22. CLT—CPU LATENCY TIMER REGISTER**

Address Offset: 71h  
 Default Value: 10h  
 Access: Read/Write

CLT is an 8-bit register that controls the amount of time the CPU is stalled in its snoop phase for a CPU cycle destined to PCI, before the cycle is deferred. When the counter value expires, the pending CPU-to-PCI cycle is deferred, if there is another transaction pending in the in-order queue. The maximum value of this counter is 32 host clocks.

Bit	Description
7:5	<b>Reserved.</b>
4:0	<b>Snoop Stall Count Value.</b> The count value indicates the number of host clocks during which the CPU transaction at the top of the in-order queue is stalled in its snoop phase. Once the 16th host clock has expired and the current snoop phase has been completed, the cycle will be deferred, if another CPU bus cycle is pending. This allows a one wait state medium decode PCI cycle to run (4 PCI clocks) without being deferred.

**3.2.23. SMRAM—SYSTEM MANAGEMENT RAM CONTROL REGISTER**

Address Offset: 72h  
 Default Value: 02h  
 Access: Read/Write

The SMRAM register controls how accesses to this space are treated. The Open, Close, and Lock SMRAM Space bits function only when the SMRAM enable bit is set to a 1. Also, the OPEN bit should be reset before the LOCK bit is set.

Bit	Description
7	<b>Reserved.</b>
6	<b>SMM Space Open (DOPEN).</b> When DOPEN=1 and DLCK=0, SMM space DRAM is made visible even when CPU cycle does not indicate SMM mode access via EXF4#/Ab7# signal. This is intended to help BIOS initialize SMM space. Software should ensure that DOPEN=1 is mutually exclusive with DCLS=1. When DLCK is set to a 1, DOPEN is set to 0 and becomes read only.
5	<b>SMM Space Closed (DCLS).</b> When DCLS=1, SMM space DRAM is not accessible to data references, even if CPU cycle indicates SMM mode access via EXF4#/Ab7# signal. Code references may still access SMM space DRAM. This allows SMM software to reference "through" SMM space to update the display even when SMM space is mapped over the VGA range. Software should ensure that DOPEN=1 is mutually exclusive with DCLS=1.
4	<b>SMM Space Locked (DLCK).</b> When DLCK=1, DOPEN is set to 0 and both DLCK and DOPEN become read only. DLCK can be set to 1 via a normal configuration space write but can only be cleared by a power-on reset. The combination of DLCK and DOPEN provide convenience with security. The BIOS can use the DOPEN function to initialize SMM space and use DLCK to "lock down" SMM space in the future so that no application software (or BIOS itself) can violate the integrity of SMM space, even if the program has knowledge of the DOPEN function.
3	<b>SMRAM Enable (SMRAME).</b> When SMRAME=1, the SMRAM function is enabled, providing 128 Kbytes of DRAM accessible at the A0000h address during CPU SMM space accesses (as indicated in the second clock of request phase on EXF4#/Ab7# signal).
2:0	<b>SMM Space Base Segment (DBASESEG).</b> This field programs the location of SMM space. SMM DRAM is not remapped. It is simply "made visible", if the conditions are right to access SMM space. Otherwise, the access is forwarded to PCI. DBASESEG=010 selects the SMM space as A0000-BFFFFh. All other values are reserved. PCI initiators are not allowed access to SMM space.

Table 4 summarizes the operation of SMRAM space cycles targeting SMI space addresses:

**Table 4. SMRAM Space Cycles**

SMRAME	DLCK	DCLS	DOPEN	CPU SMM Mode Request (0=active)	Code Fetch	Data Reference
0	X	X	X	X	PCI	PCI
1	0	0	0	0	DRAM	DRAM
1	0	X	0	1	PCI	PCI
1	0	0	1	X	DRAM	DRAM
1	0	1	0	0	DRAM	PCI
1	0	1	1	X	INVALID	INVALID
1	1	0	X	0	DRAM	DRAM
1	1	X	X	1	PCI	PCI
1	1	1	X	0	DRAM	PCI

### 3.2.24. ERRCMD—ERROR COMMAND REGISTER

Address Offset: 90h  
 Default Value: 00h  
 Access: Read/Write

This 8-bit register controls the PMC responses to various system errors. The actual assertion of SERR# or PERR# is enabled via the PCI command register.

Bit	Description
7:5	<b>Reserved.</b>
4	<b>SERR# on Receiving Target Abort Enable.</b> 1=Enable. 0=Disable.
3	<b>SERR# on PCI Parity Error (PERR# asserted) Enable.</b> 1=Enable. 0=Disable.
2	<b>Reserved.</b>
1	<b>SERR# on Receiving Multiple-Bit ECC/Parity (DBX_ERR# asserted) Error Enable.</b> 1=Enable. 0=Disable. For systems not supporting ECC or parity this bit must be disabled.
0	<b>SERR# on Receiving Single-bit ECC Error Enable.</b> When this bit is set to 1, the PMC asserts SERR# when it detects a single-bit ECC error reported via the DBX_ERR# signal to the PMC.

**3.2.25. ERRSTS—ERROR STATUS REGISTER**

Address Offset: 91h  
 Default Value: 00h  
 Access: Read Only, Read/Write Clear

This 8-bit register is used to report error conditions received from the DBX via the DBX\_ERR# signal.

Bit	Description
7:5	<p><b>Multi-bit First Error (MBFRE)—RO.</b> This field contains the encoded value of the DRAM row in which the first multi-bit error occurred. When an error is detected, this field is updated and the MEF bit is set. This field is then locked (no further updates) until the MEF flag is set to 0. If MEF is 0, the value in this field is undefined.</p>
4	<p><b>Multiple-bit ECC/Parity (uncorrectable) Error Flag (MEF)—R/WC.</b> If this bit is set to 1, the memory data transfer had an uncorrectable error (i.e., multiple-bit error). When enabled, a multiple bit error is reported on the DBX_ERR# signal by the DBX and propagated to the SERR# pin of PMC, if enabled by bit 1 in the ERRCMD register. BIOS has to write a 1 to clear this bit.</p> <p>Note: If the MEF bit is set to a 1, when MEF bit is 0 and SERR# reporting is enabled, then an error will be reported on the SERR# pin.</p>
3:1	<p><b>Single-bit First Row Error (SBFRE)—RO.</b> This field contains the encoded value of the DRAM row in which the first single-bit error occurred. When an error is detected, this field is updated and SEF is set. This field is then locked (no further updates) until the SEF flag is set to 0. If SEF is 0, the value in this field is undefined.</p>
0	<p><b>Single-bit (correctable) ECC Error Flag (SELF)—R/WC.</b> If this bit is set to 1, the memory data transfer had a single-bit correctable error and the corrected data was sent for the access. When ECC is enabled, a single bit error is reported on the DBX_ERR# signal by the DBX and propagated to the SERR# pin of the PMC, if enabled by bit 0 in the ERRCMD register. BIOS has to write a 1 to clear this bit and unlock the SBFRE field.</p>

**3.2.26. TRC—TURBO RESET CONTROL REGISTER**

Address Offset: 93h  
 Default Value: 00h  
 Access: Read/Write

TRC is an 8-bit register that selects turbo/deturbo mode of the CPU, initiates CPU reset cycles, and initiates CPU Built-in Self Test (BIST). A 440FX PCIset design with PIIX3 should not use this register to initiate a hard reset. Instead, an I/O access to 0x0CF9h (TRC within the PIIX3) should be used to initiate a hard reset.

Bit	Descriptions
7:4	<b>Reserved.</b>
3	<b>BIST Enable (BISTE).</b> BISTE enables/disables CPU Built-In Self Test. This bit is used in conjunction with RCPU and SHRE of this register. When BISTE=1, a subsequent initiation of CPU hard reset via the RCPU causes the BIST feature of the CPU to be executed. The PMC only invokes the CPU BIST during a hard reset (SHRE=1). In addition to the assertion of the CRESET# for hard reset, the PMC asserts INIT#. The DBX then drives CPURST# subsequently to the CPUs. If the CPU samples INIT# asserted during the active-to-inactive transition of the CPURST#, the CPU enters the BIST mode.
2	<b>Reset CPU (RCPU).</b> RCPU is used to initiate a hard or soft reset to the CPU. During hard reset, the PMC asserts CRESET# for 2 msec and PCIRST# for 1 msec. During soft reset, the PMC asserts INIT#. <p>BISTE and SHRE must be set up prior to writing a 1 to this bit. Two operations are required to initiate a reset using this register. The first write operation programs BISTE and SHRE to the appropriate state while setting RCPU to 0. The second write operation keeps the BISTE and SHRE at their programmed state while setting RCPU to 1. When RCPU transitions from a 0 to 1</p> <ul style="list-style-type: none"> <li>- and [BISTE,SHRE] = 0 0, a soft reset is initiated</li> <li>- and [BISTE,SHRE] = 0,1, a hard reset is initiated</li> <li>- and [BISTE,SHRE] = 1,1, CPU BIST mode is enabled</li> </ul>
1	<b>System Hard Reset Enable (SHRE).</b> This bit is used in conjunction with RCPU bit to initiate either a hard or soft reset. When SHRE=1, the PMC initiates a hard reset to the CPU when RCPU bit transitions from 0 to 1. When SHRE=0, the PMC initiates a soft reset when RCPU bit transitions from 0 to 1.
0	<b>Deturbo Mode (DM).</b> This bit enables and disables deturbo mode. When DM=1, the PMC is in the deturbo mode. In this mode, the PMC disables CPU caching by asserting FLUSH# and stalls the CPU pipeline at a rate programmed in the Deturbo Counter Register (DC). When this bit is 0, deturbo mode is disabled and Deturbo counter has no effect.

## 4.0. FUNCTIONAL DESCRIPTION

### 4.1. System Address Map

A Pentium Pro system based on the 440FX PCIsset supports 4 Gbytes of addressable memory space and 64 Kbytes of addressable I/O space. The lower 1 Mbyte of this addressable memory is divided into regions which can be individually controlled with programmable attributes such as disable, read/write, write only, or read only (see Register Description section for details on attribute programming).

#### NOTE

The Pentium Pro processor family can have up to 64 Gbytes of addressable memory. The PMC claims any access over 4 Gbytes by terminating the transaction (without forwarding it to the PCI bus). Writes are terminated by dropping the data and the PMC returns all zeros for reads

#### 4.1.1. MEMORY ADDRESS RANGES

Figure 3 represents system memory address map. It shows the main memory regions defined and supported by the 440FX PCIsset. At the highest level, the address space is divided into four conceptual regions (Figure 3). These are the 0–1-Mbyte DOS Compatibility Area, the 1-Mbyte to 16-Mbyte Extended Memory region used by ISA, the 16-Mbyte to 4-Gbyte Extended Memory region, and the 4-Gbyte to 64-Gbyte Extended Memory introduced by 36 bit addressing.

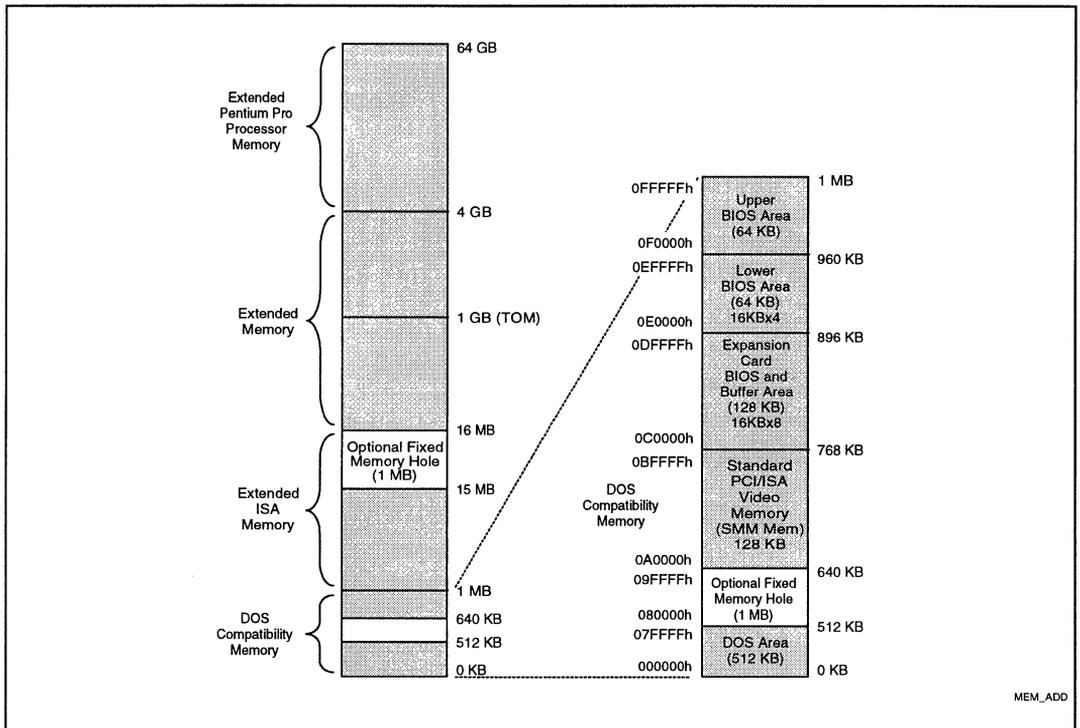


Figure 3. Memory Address Map

#### 4.1.1.1. Compatibility Area

The first region of memory is called the Compatibility Area because it was defined for early PCs. This area is divided into the following address regions:

- 0–512-Kbyte DOS Area
- 512–640-Kbyte DOS Area - Optional ISA/PCI Memory
- 640–768-Kbyte Video Buffer Area
- 768–896-Kbyte in 16-Kbyte sections (total of 8 sections) - Expansion Area
- 896–960-Kbyte in 16-Kbyte sections (total of 4 sections) - Extended System BIOS Area
- 960-Kbyte–1-Mbyte Memory (BIOS Area) - System BIOS Area

There are thirteen ranges which can be enabled or disabled independently for both read and write cycles and one (512 Kbyte–640 Kbyte) which can be mapped to either main DRAM or PCI.

#### DOS Area (00000–9FFFh)

The DOS area is 640 Kbytes in size and it is further divided into two parts. The 512-Kbyte area at 0 to 7FFFFh is always mapped to the main memory controlled by the PMC, while the 128-Kbyte address range from 080000 to 09FFFFh can be mapped to PCI or to main DRAM. By default this range is mapped to main memory and can be declared as a main memory hole (accesses forwarded to PCI) via the FDHC register.

#### Video Buffer Area (A0000–BFFFFh)

The 128-Kbyte graphics adapter memory region is normally mapped to a video device on the PCI bus (typically VGA controller). This area is not controlled by attribute bits and CPU-initiated cycles in this region are always forwarded to PCI for termination. This region is also the default region for SMM space.

#### ISA Expansion Area (C0000–DFFFFh)

This 128-Kbyte ISA Expansion region is divided into eight 16-Kbyte segments. Each segment can be assigned one of four Read/Write states: read-only, write-only, read/write, or disabled. Typically, these blocks are mapped through the PCI bridge to ISA space. Memory that is disabled is not remapped.

#### Extended System BIOS Area (E0000–EFFFFh)

This 64-Kbyte area is divided into four 16-Kbyte segments. Each segment can be assigned independent read and write attributes so it can be mapped either to main DRAM or to PCI. Typically, this area is used for RAM or ROM. Memory that is disabled is not remapped.

#### System BIOS Area (F0000–FFFFh)

This area is a single 64-Kbyte segment that can be assigned read and write attributes. It is by default (after reset) read/write disabled and cycles are forwarded to PCI. By manipulating the read/write attributes, the PMC can “shadow” BIOS into main memory. Memory that is disabled is not remapped.

#### 4.1.1.2. Extended Memory Area

This memory area covers 10\_0000h (1 Mbyte) to FFFF\_FFFFh (4 Gbytes minus 1) address range and it is divided into the following regions:

- DRAM memory from 1 Mbyte to a Top Of Memory (TOM) (maximum of 256 Mbytes using 16Mb DRAM technology or 1 Gbyte using 64Mb technology)
- PCI Memory space from the Top of Memory to 4 Gbytes with two specific ranges
- APIC Configuration Space from FEC00000h (4 Gbytes minus 20 Mbyte) to FEC0\_FFFFh
- High BIOS area from 4 Gbytes to 4 Gbytes minus 2 Mbytes

#### Main DRAM Address Range (0010\_0000h to Top of Main Memory)

The address range from 1 Mbyte to the top of main memory is mapped to the main memory address range controlled by the PMC. All accesses to addresses within this range are forwarded by the PMC to the main memory, unless a hole in this range is created by programming the FDHC register.

#### PCI Memory Address Range (Top of Main Memory to 4 Gbytes)

The address range from the top of main DRAM to 4 Gbytes (top of physical memory space supported by the 440FX PCIset) is normally mapped to PCI. The PMC forwards all accesses within this address range to PCI. There are two sub-ranges within this address range defined as APIC Configuration Space and High BIOS Address Range.

##### 1. APIC Configuration Space (FEC0\_0000h–FEC0\_FFFFh)

This range is reserved for APIC configuration space which includes the default I/O APIC configuration space. The default Local APIC configuration space is FEE0\_0000h to FEE0\_0FFFh.

The Pentium Pro processor accesses to the Local APIC configuration space do not result in external bus activity since the Local APIC configuration space is internal to the processor. However, a MTRR must be programmed to make the Local APIC range uncacheable (UC). The Local APIC base address in each CPU should be relocated to the FEC0\_0000h (4 Gbytes minus 20 Mbytes) to FEC0\_FFFFh range so that one MTRR can be programmed to 64 Kbytes for the Local and I/O APICs. The I/O APIC(s) usually reside in the I/O Bridge portion of the chip-set or as a stand-alone component(s).

I/O APIC units are located beginning at the default address FEC0\_0000h. The first I/O APIC is located at FEC0\_0000h. Each I/O APIC unit is located at FEC0\_x000h where x is I/O APIC unit number 0 through F(hex). This address range is normally mapped to PCI (like all other memory ranges above the Top of Main Memory).

The address range between the APIC configuration space and the High BIOS (FEC0\_FFFFh to FFE0\_0000h) is always mapped to the PCI.

## 2. High BIOS Area (FFE0\_0000h–FFFF\_FFFFh)

The top 2 Mbytes of the Extended Memory Region is reserved for System BIOS (High BIOS), extended BIOS for PCI devices, and the A20 alias of the system BIOS. The CPU begins execution from the High BIOS after reset. This region is mapped to the PCI so that the upper subset of this region is aliased to 16 Mbytes minus 256-Kbyte range. The actual address space required for the BIOS is less than 2 Mbytes. However, the minimum CPU MTRR range for this region is 2 Mbytes. Thus, the full 2 Mbytes must be considered.

### 4.1.2. SYSTEM MANAGEMENT MODE (SMM) MEMORY RANGE

The PMC supports the use of main memory as SMM memory when the System Management Mode is enabled. When this function is disabled the memory address range A0000–BFFFFh is normally defined as a sub-range of the Video Buffer range where accesses are directed to PCI and physical DRAM memory is not accessed. When SMM is enabled via SMRAM register, the A0000–BFFFFh range is used as a SMM RAM. The CPU bus cycles executed in SMM mode access the A0000–BFFFFh range by being mapped to the corresponding physical DRAM address range instead of being forwarded to PCI. Before this space is accessed in SMM mode, the corresponding DRAM range must be first initialized via the SMRAM register. A PCI initiator can not access the SMM space.

#### NOTE

A SMM handler accessing the configuration space must save the context of 0CF8h when entering the SMM space and restore it before leaving SMM space. This is due to the fact that a configuration access can be interrupted by a SMI after 0CF8h access and before the subsequent 0CFCh access. For other interrupts, this is handled by disabling the interrupts before a configuration access and enabling them after the access is completed. However, this approach does not work for SMI since SMI will be recognized even if the interrupts are masked at the CPU level.

### 4.1.3. MEMORY SHADOWING

Any block of memory that can be designated as read only or write only can be “shadowed” into PMC DRAM memory. Typically, this is done to allow ROM code to execute more rapidly out of main DRAM. ROM is used as read only during the copy process while DRAM at the same time is designated write only. After copying, the DRAM is designated read only so that ROM is shadowed. CPU bus transactions are routed accordingly. The PMC does not respond to transactions originating from PCI or ISA masters and targeted at shadowed memory blocks.

### 4.1.4. I/O ADDRESS SPACE

The PMC does not support the existence of any other I/O devices besides itself on the CPU bus. The PMC generates PCI bus cycles for all CPU I/O accesses, except to PMC’s internal registers. PMC contains two registers in the CPU I/O space, Configuration Address Register (CONFADD) and the Configuration Data Register (CONFDATA). These locations are used to implement PCI configuration space access mechanism. See the Register Description section for details.

## 4.2. Host Interface

The Host Interface of the 440FX PCISET is designed to support the Pentium Pro family of processors. The host interface of the PMC supports up to 66 MHz bus speeds. The PMC also supports a two processor SMP mode of operation.

### 4.3. DRAM Interface

The PMC provides the control signals and address lines to support from 8 Mbytes to 1Gbytes of main memory. The data path is through the DBX under the PMC's control. This section describes the structure and implementation of the main memory structure.

#### 4.3.1. DRAM POPULATION RULES

The following set of rules allows for optimum configurations.

- SIMM sockets must be populated in pairs; the memory array is 64- or 72-bits wide
- SIMM sockets can be populated in any order (i.e., SIMM 0/1 does not have to be populated before SIMM sockets 2/3 or 4/5 or 6/7 are used)
- SIMM socket pairs need to be populated with the same densities (single or double). For example, SIMM sockets 2/3 must be populated with identical densities. However, SIMM sockets 4/5 can be populated with different densities than SIMM socket pairs 2/3 or 0/1. Additionally, asymmetrical DRAMs of the same type should be used in the whole row.
- BEDO, EDO, and standard page mode can be mixed within the memory array. However, only one type should be used per SIMM socket pair. For example, SIMM sockets 2/3 can be populated with EDO while SIMM socket 0/1 can be populated with standard page mode. If different type of memory is used for different rows, each row will be optimized for that type of memory.
- The DRAM Timing register, which provides the DRAM speed grade control for the entire memory array, must be programmed to use the timings of the slowest DRAMs installed.

Table 5 lists a sample of the possible SIMM socket configurations. The following configuration assumes a memory array of six double-sided SIMMs. SIMM sockets 0/1, 2/3, and 4/5 each have 2 RAS lines connected allowing double-sided SIMMs to be used in these socket pairs.

Table 5. Sample Of Possible Mix And Match Options For 6 Row SIMM Configurations

SIMM0/ SIMM1 (RAS[ 0,1]#)	SIMM2/ SIMM3 (RAS[ 2,3]#)	SIMM4/ SIMM5 (RAS[4,5]#)	D R B 0	D R B 1	D R B 2	D R B 3	D R B 4	D R B 5	D R B 6	D R B 7	Total Mem.
0	0	1MBx36/S	00h	00h	00h	00h	01h	01h	01h	01h	8 MB
1MBx36/S	0	0	01h	8 MB							
2MBx36/S	0	0	02h	16 MB							
1Mx36/S	1Mx36/S	0	01h	01h	02h	02h	02h	02h	02h	02h	16 MB
0	4Mx36/S	0	00h	00h	04h	04h	04h	04h	04h	04h	32 MB
2Mx36/D	2Mx36/D	2Mx36/D	01h	02h	03h	04h	05h	06h	06h	06h	48 MB
4Mx36/S	0	2Mx36/D	04h	04h	04h	04h	05h	06h	06h	06h	48 MB
4Mx36/S	0	4Mx36/S	04h	04h	04h	04h	08h	08h	08h	08h	64 MB
4Mx36/S	4Mx36/S	2Mx36/D	04h	04h	08h	08h	07h	10h	10h	10h	80 MB
8Mx36/D	0	4Mx36/S	04h	08h	08h	08h	0Ch	0Ch	0Ch	0Ch	96 MB
8Mx36/D	8Mx36/D	8Mx36/D	04h	08h	0Ch	10h	14h	18h	18h	18h	192 MB
16Mx36/S	16Mx36/S	0	10h	10h	20h	20h	20h	20h	20h	20h	256 MB
8Mx36/D	16Mx36/S	8Mx36/D	04h	08h	18h	18h	1Ch	20h	20h	20h	256 MB
0	32Mx36/D	16Mx36/S	00h	00h	10h	20h	30h	30h	30h	30h	384 MB
32Mx36/D	32Mx36/D	16Mx36/S	10h	20h	30h	40h	50h	50h	50h	50h	640 MB

Note: "S" denotes single-sided SIMM's; "D" denotes double-sided SIMM's.

4.3.2. AUTO-DETECTION

BEDO and EDO DRAM can use the same standard 72-pin SIMM as the module built using FPM DRAM. This allows the end user to mix different types of DRAM in the system by providing common 72-pin SIMM sockets. The PMC has a special timing mode that may be used by the BIOS to detect the type of DRAM installed on a bank-by-bank basis. For EDO detection, the EDO detect bit must be set in the DRAM Control register. These algorithms must be implemented by the BIOS during the POST routines.

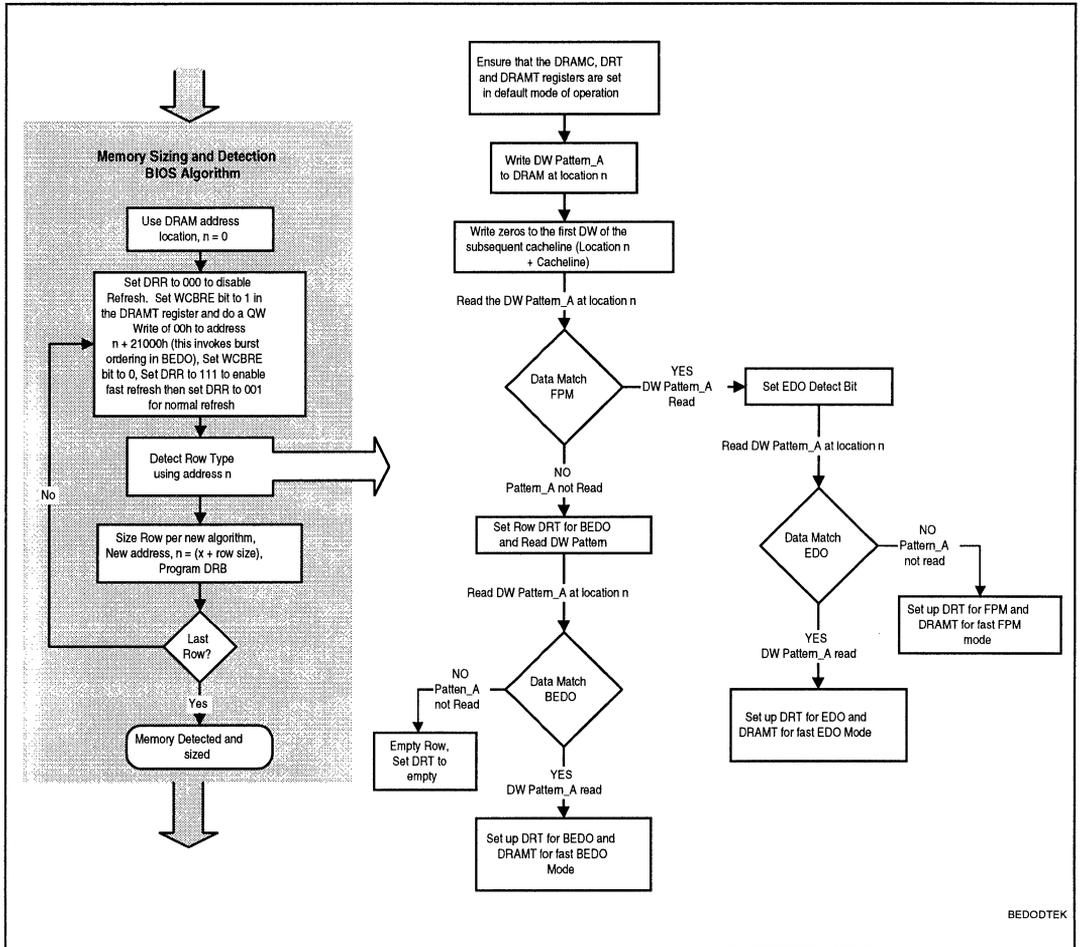


Figure 4. DRAM Auto-Detection Algorithm

Detection of BEDO type can be entirely accomplished in software. The memory row can be tested for DRAM type using the sequence outlined in the flow chart in Figure 4. The memory sizing and detection scheme used in 440FX PCIset detects and sizes one row at a time until all rows have been detected and sized. Starting with base address 000h, the steps followed are:

- Part of the BEDO DRAM requirement is the burst mode that the DRAM will burst the data out once the access has been initiated. The BEDO specification uses a WCBR program cycle to allow for the burst sequence to be set to linear or x86 mode. Once set, this mode remains active until another WCBR cycle is introduced or power to DRAMs is interrupted. Run a WCBR cycle using the base address + 21000h (this enables the BEDO programming mode) to enable the current row into x86 burst mode. Exit the programming mode by running a fast refresh cycle using the DRR register. If the current row is BEDO, then it allows the DRAM to be set for x86 burst order.
- Use the detection algorithm outlined in Figure 4 to detect the type of DRAM.
- Use the memory sizing algorithm to detect the memory size. Ensure that the considerations as suggested in Section 4.3.4 are used in the implementation of the memory sizing algorithm. Program the DRB register appropriately. Add this memory size to the current base address to get the new base address. Repeat the process until all of memory is detected and sized.
- After all the rows have been set to the x86 mode, the DRAM array has been primed to enter the detection and sizing mode. The BEDO DRAM architecture requires that detection and sizing be done on a per row basis as shown in the algorithm above. The actual detection scheme is shown in Fig.5.1. Once the type of DRAM has been detected, this information must then be programmed into the DRAM Row Type Register for optimal performance. The PMC uses the DRAM Row Type information in conjunction with the DRAM timings set in the DRAM Timing Register to configure DRAM accesses optimally.

#### 4.3.3. DRAM ADDRESS TRANSLATION AND DECODING

The PMC contains address decoders that translate the address received on the host bus to an effective memory or PCI address. This translation takes into account memory gaps and the normal host to memory or PCI address.

The PMC supports a maximum of 64 Mbit DRAM device. The PMC supports the DRAM page size of the smallest density DRAM that can be installed in the system. For 36-bit SIMM using 1M x 4 DRAMs, the overall DRAM SIMM page size is 4096 bytes (4 KB). Since each row supports 2 SIMMs for a 64-bit wide memory, the effective page size supported by the PMC is 8 Kbytes. The page offset address is driven over MA[8:0] when driving the column address. MA[11:0] are translated from the address lines HA[26:3] for all memory accesses. The multiplexed row/column address to the DRAM memory array is provided by MA[11:0]. MA[11:0] are derived from the host address bus as defined by Table 6 for symmetrical and asymmetrical DRAM devices. The DRAM addressing and the size supported by these options is shown in Table 7.

**Table 6. DRAM Address Translation**

Memory Addr., MA[11:0]	11	10	9	8	7	6	5	4	3	2	1	0
Row Address	A24	A23	A21	A20	A19	A18	A17	A16	A15	A14	A13	A12
Column Address	A26	A24 <sup>1</sup>	A22	A11	A10	A9	A8	A7	A6	A5	A4	A3

<sup>1</sup> For supporting 12 x 11 and 12 x 12 addressing this bit is driven as A25. This accomplished dynamically by the PMC.

**Table 7. Memory Mapping Options**

Memory Org.	Addressing	Address Size
<b>4 Mb</b>		
1M x 4	Symmetric	10 x 10
<b>16 Mb</b>		
1M x 16	Symmetric	10 x 10
2M x 8	Asymmetric	11 x 10
4M x 4	Symmetric	11 x 11
	Asymmetric	12 x 10
<b>64 Mb</b>		
4M x 16	Symmetric	11 x 11
	Asymmetric	12 x 10
8M x 8	Asymmetric	12 x 11
16M x 4	Symmetric	12 x 12

#### 4.3.4. PSEUDO-ALGORITHM FOR DYNAMIC MEMORY SIZING

PMC implements asymmetrical addressing as described in Section 5.3 including support for 12 x 10 DRAM addressing. This section describes a pseudo-algorithm for calculating the memory sizing dynamically, including identification of memory addressing type. This pseudo-algorithm should be appropriately added to the algorithm used currently in the BIOS or the OS. A generic algorithm is described as follows:

1. Configure row size for 128 MBytes (12 x 12 addressing) with base address = Baddr
2. Write a pattern 0Ch to location Baddr + 0000\_0000h (encoding for 8 MB)
3. Write a pattern 04h to location Baddr + 0400\_0000h (encoding for 16 MB)
4. Write a pattern 03h to location Baddr + 0200\_0000h (encoding for 32 MB)
5. Write a pattern 01h to location Baddr + 0100\_0000h (encoding for 64 MB)
6. Write a pattern 00h to location Baddr + 0080\_0000h (encoding for 128 MB)
7. Read from locations Baddr + 0200\_0000h into Register X
8. OR the value in register X with data from location Baddr + 0000\_0000h into register X
9. Increment register X

The result of this register X contains the correct value to add to the previous DRB register to get the correct value for the current DRB register. It is important to note that all the DRBs must be programmed to 128 MB until all the rows have been sized. The correct value of the row sizes should be programmed in all the DRBs after all the rows have been sized.

Table 8. Algorithm Results

Baddr + 0000_0000h	Baddr + 0200_0000h	Split	Register "X" at each Step			Row Size
			Step 7	Step 8	Step 9	
00h	00h	10 x 10	00h	00h	01h	8 MB
01h	01h	11 x 10	01h	01h	02h	16 MB
01h	01h	11 x 11	03h	03h	04h	32 MB
03h	03h	12 x 10	03h	03h	04h	32 MB
04h	03h	12 x 11	03h	07h	08h	64 MB
0Ch	0Ch	12 x 12	03h	0Fh	10h	128 MB

4.3.5. DATA INTEGRITY SUPPORT

ECC or parity can be checked on the DRAM interface. As a default no parity is selected. The DRAM must be populated with 72-bit wide memory to implement ECC or parity.

4.3.5.1. Software Requirements

BIOS must be aware of the implication of the optional parity support. All physically present DRAM must be first written before SERR#-based NMI generation in the PIIX3 is enabled.

**Detection of 64- versus 72-bit Wide SIMMS.** The PMC only supports parity or ECC properly if all DRAMs are 72-bit wide. A system with a mixture of 64- and 72-bit wide memory should disable parity and ECC. BIOS can detect the 64-bit wide DRAMs (so that it can disable SERR# on parity error) by writing data that forces the parity bits to be all 1s for address A, and then writing data that forces the parity bits to be all 0's in another location (address B). Now, if address A is read, no parity error will result only if there's a 72-bit wide DRAM present, whereas parity errors would get flagged in the ERRSTS register for a 64-bit wide DRAM.

4.3.5.2. Parity Detection

When parity is enabled, the DRAM parity protection is 8-bit based even parity. If the DRAM array is populated with 64-bit memory (vs 72-bit) the parity logic, such parity errors are registered in bit 4 in the ERRSTS register. For such DRAM configurations, bit 1 of the ERRCMD register must be 0 (default) to prevent these errors from being signaled via the SERR# mechanism.

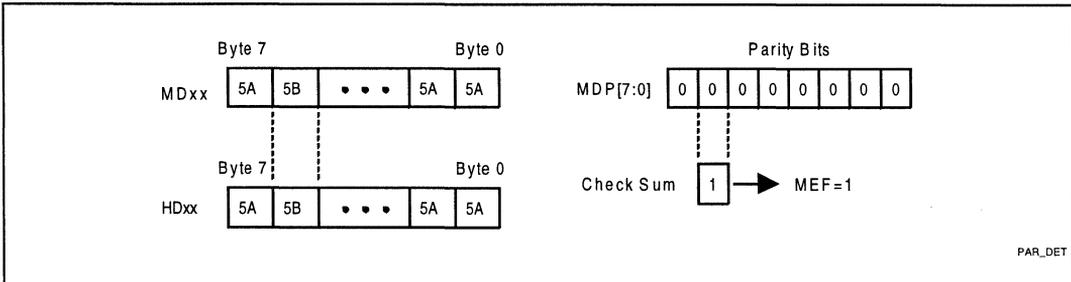


Figure 5. Parity Detection

4.3.5.3. Error Detection and correction

ECC is an optional data integrity feature provided by the PMC. The feature provides single-error correction, double-error detection, and detection of all errors confined to a single nibble (SEC-DED-S4ED) for the DRAM memory subsystem. Additional features are provided that enable software-based system management capabilities.

**ECC Generation.** When enabled, the PMC generates an 8-bit protection code for 64-bit data during DRAM write operations. If the original write is less than 64-bits, a read-merge-write operation is performed.

**ECC Checking and Correction.** When enabled, the PMC detects all single and dual-bit errors, and corrects all single-bit errors during DRAM reads. The corrected data is transferred to the requester (CPU or PCI). Note that the corrected data is *not* written back to DRAM.

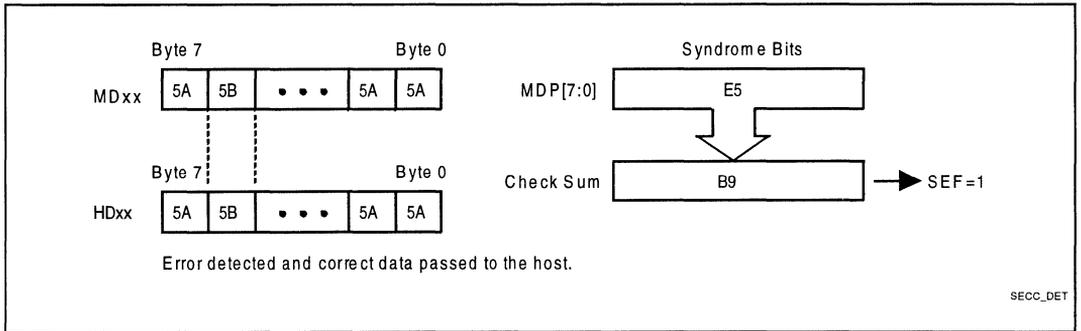


Figure 6. Single Bit Error Detection and Correction (SEC)

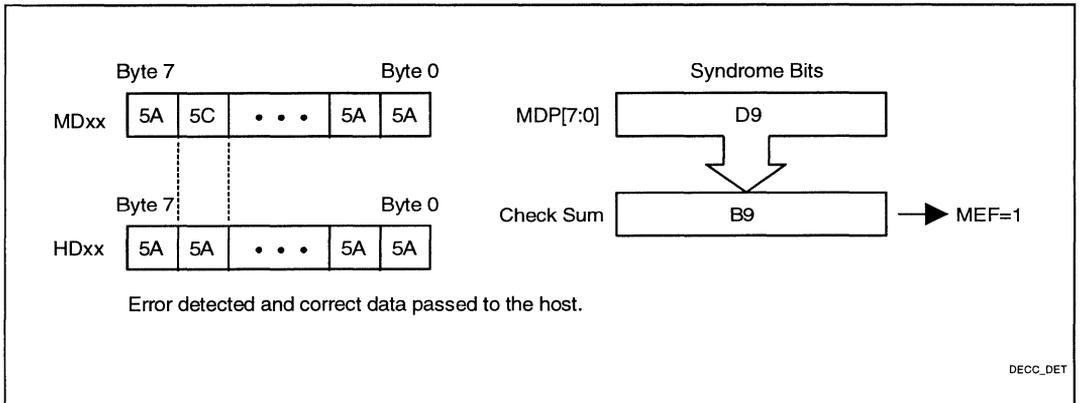
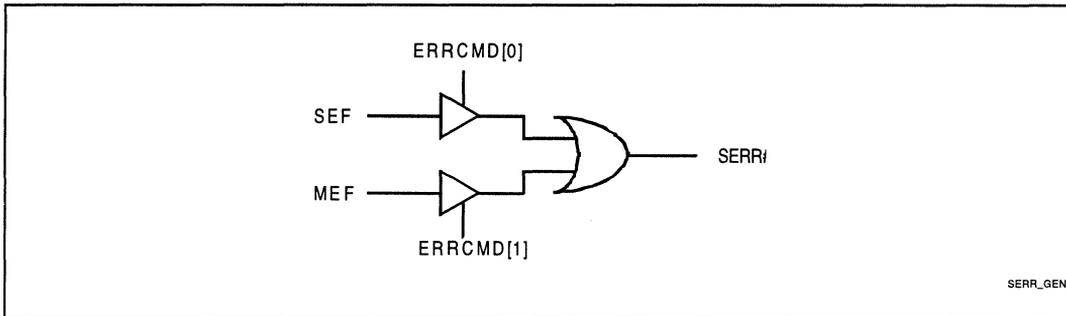


Figure 7. Multiple Bit Error Detection (DED)

**Error Reporting.** When ECC is enabled and ERRCMD is used to set SERR# functionality, ECC errors are signaled to the system via the SERR# pin. The PMC can be programmed to signal SERR# on uncorrectable errors, correctable errors, or both. The type of error condition is latched until cleared by software (regardless of SERR# signaling).



**Figure 8. SERR# Generation for Single- or Double-bit Error**

When a single or multi-bit error is detected, the offending DRAM row ID is latched in the ERRSTS register in the PMC. The latched value is held until software explicitly clears the error status flag.

**Software Requirements**

**Initialization.** If the ECC feature or parity is enabled, BIOS must take care to properly initialize the memory before enabling the checking. Software should first ensure PCICMD[SERRE] =0, then enable ECC or parity via ERRCMD. Next, the entire DRAM array should be written to ensure valid syndrome/parity bits. Finally, the desired ECC/parity error reporting should be enabled via the ERRCMD and PCICMD registers.

**Parity Error Handling.** Parity error handling should be via the system’s normal NMI routines.

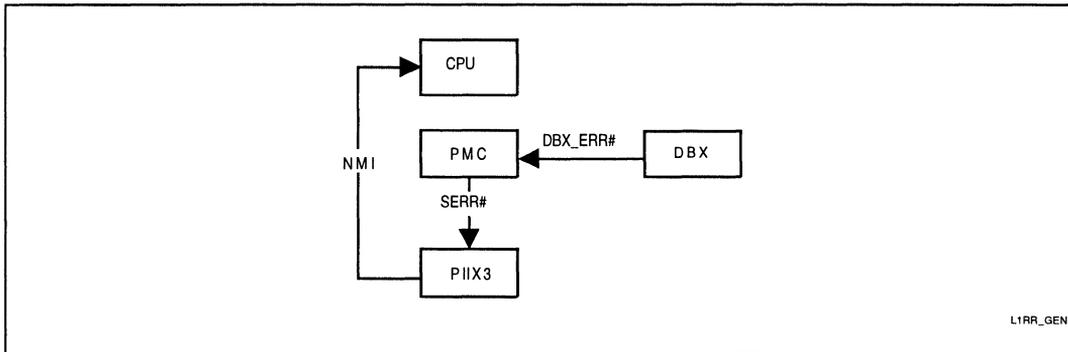
**ECC Support Levels.** The PMC allows for various levels of ECC support, depending on the specific platform requirements. The software architecture requirements vary based on the level of support implemented. The levels and basic software implications are summarized in the table below.

**Table 9. ECC Software Levels**

Level	Features	Software Requirements
1	- Error Checking/Correction	- Configuration BIOS
2	- Error Checking/Correction. - Error Scrubbing	- Configuration BIOS. - SMI Scrubbing Routine
3	- Error Checking/Correction. - Error Scrubbing. - System Management (e.g. error logging, error isolation, memory remapping, etc.)	- Configuration BIOS. - SMI Scrubbing Routine. - OS-dependent System management handler/applet

**Level 1**

Level 1 defines a minimal support level for ECC handling that would use the system’s standard NMI routine. The configuration BIOS enables SERR# generation only for uncorrectable errors, and disables SERR# generation for correctable errors. The NMI routine will interpret the uncorrectable error event as a parity error, and typically reboot the system.



**Figure 9. Level 1 SERR# Generation for ECC and Parity**

## Level 2

Level 2 adds support for error scrubbing of correctable errors using operating system independent mechanisms. SMI is the preferred mechanism to implement OS independence. In this case, the SMI handler would be invoked for both correctable and uncorrectable errors. The DBX\_ERR# signal from the DBX is connected to the PMC as well as the EXT\_SMI# input of the PIIX3. Any error signalled via the DBX\_ERR# will trigger a SMI and consequently the SMI handler will be invoked. Note that both ERRCMD[1:0] bits should be disabled to prevent the generation of SERR# upon receipt of the DBX\_ERR#.

For correctable errors, the handler first clears the error flags and then starts a scrub process. The time spent in an SMI routine should be minimized, since interrupts are disabled and OS services (e.g. real time clocks) could be adversely affected. To minimize time spent during the SMI handler, the scrub process should be distributed into small time slices. The handler can setup future SMI events to re-occur based on a hardware timer (e.g. the "Fast Off" green timer in Intel PCIset standard expansion bridges [PIIX3]) until the memory scrub has completed.

The following example estimates the worst-case scrub duration for a single correctable error.

Example Assumptions:

- 128 Mbytes/Row (64Mbit technology) = 4M lines at 32 bytes/line
- Scrub operation memory bound by linefill + writeback (with medium DRAM timings) = 30 clks/line
- SMI scrub time slice budget = 1 msec/SMI
- Fast-off SMI interrupt interval = 100 msec/interrupt

With the above assumptions The scrub time is:

- the time to scrub one row is 4M lines/row X 30 clks/line X 15ns/clk = 1.8 sec/row.
- Thus, spreading the scrub time requires: (1.8 sec/row)/(1msec /SMI) = 1800 SMI events.
- The total duration for the scrub SMI events will be 1800 SMI events \* 100msec/interrupt = 180 sec.

For uncorrectable errors, the SMI handler should first log the error and then pass the error to the system's normal NMI handler, making it appear as a standard parity error to the software. To pass the NMI event, the SMI handler will:

- Log the MBFRE field and clear the MEF bit
- Set ERRCMD[1] to enable SERR# assertion
- Write a 1 to MEF bit to cause SERR# assertion
- Clear ERRCMD[1] bit to 0 to allow logging of subsequent errors

This will result in a NMI which will be handled after exiting the SMI handler.

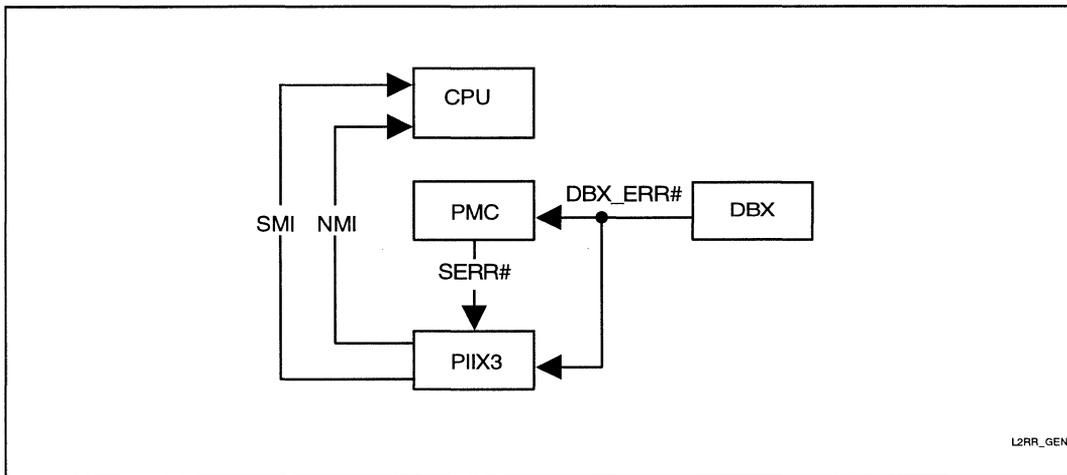


Figure 10. Level 2 SERR# Generation for ECC and Parity

### Level 3

Level 3 adds more sophisticated system management functions beyond simple error scrubbing. Typical functions could include error event logging, error isolation, memory remapping, system diagnostics and user interface applications. Software to implement Level 3 functions are OS dependent, and beyond the scope of this document. However, the features used to implement Level 2 functions can also be leveraged in Level 3 systems.

#### 4.3.5.4. ECC/Parity Test Mode

PMC and DBX provide a software mechanism to test the parity and ECC checking logic. After CRESSET# the DBX ECC/Parity control logic is set in the default mode of operation. To enter the ECC/Parity Test Mode PMCCFG[EPT] must be set to 1. This causes the PMC to send a command to the DBX to configure the latter's ECC/Parity logic for test mode. In the test mode, the DBX signals MDP[7:0] are forced to "0" during writes to DRAM. During reads, MPD[7:0] are compared against internally generated ECC/Parity Checksum. Errors generated due to mismatches are reported normally via the DBX\_ERR# signal. This mechanism can be used to test both single-bit and multiple-bit ECC and parity errors. In case of single-bit errors, a zero pattern can be written to memory followed by a walking "1" pattern. This should result in the corrected data being returned to the CPU, (i.e., all 0s). The SEF bit can also be polled to test for single-bit error logging. In case of multiple bit and parity errors, writing different patterns and reading them back should result in a multi-bit or parity error which would be logged in the MEF bit.

#### 4.4. PCI Bus Arbitration

The PMC's PCI Bus arbiter allows concurrent host and PCI transactions to main memory. The arbiter supports five PCI masters in addition to the PIIX3 component (Figure 11). REQ[4:0]#/GNT[4:0]# are used by PCI masters. PHLD#/PHLDA# are the arbitration request/grant signals for the PIIX3 and provide guaranteed access time capability for ISA masters. The arbiter dynamically allocates to PIIX3 to optimize system latencies for better Universal Serial Bus (USB) performance.

##### Multi-Transaction Timer (MTT)

The arbitration mechanism is enhanced with a Multi-Transaction Timer mechanism. The effect of the MTT is to guarantee a minimum time slice on PCI to an agent that keeps its request asserted. (Note that this mechanism differs from the MLT operation, that enforces a maximum time slice for an agent.) The MTT algorithm ensures a fairer bandwidth allocation for PCI devices that generate short burst traffic, or for multi-function devices with several bus master agents behind one physical PCI interface. This feature improves the PCI bandwidth allocation to short bursts, an important consideration for example, with typical video capture devices.

##### Passive Release and Bus Lock

To comply with PCI Specification, revision 2.1 latency requirements, the PMC supports passive release. The PMC disables CPU-to-PCI posting during the passive release, except for transactions to the USWC region. The PMC only supports bus lock mode. The bus lock mode precludes 3rd party locks.

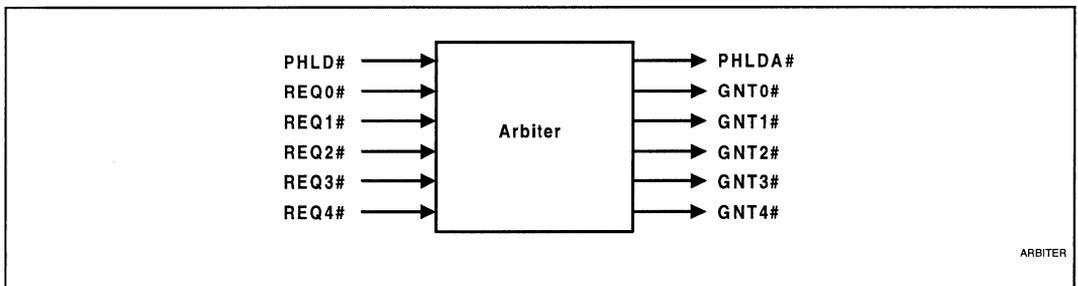


Figure 11. PCI Bus Arbiter

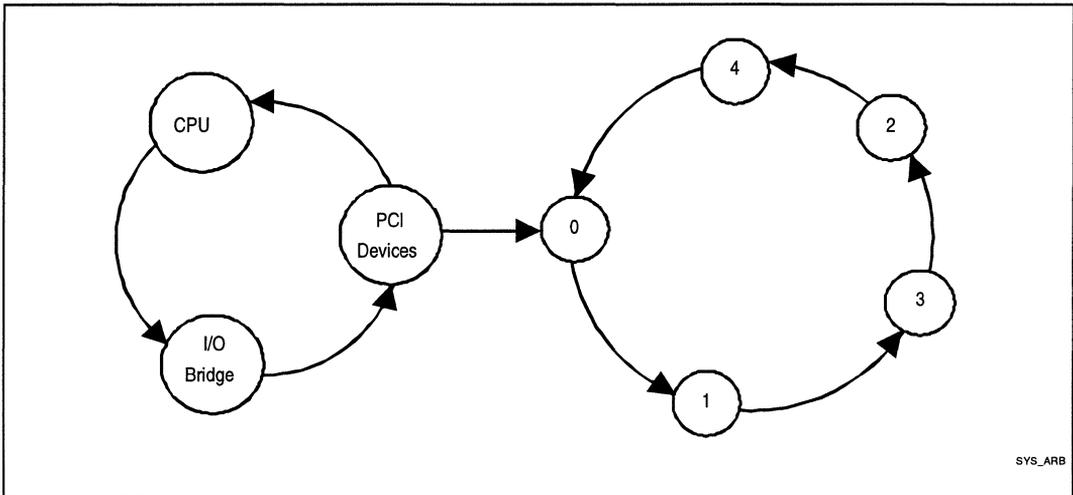


Figure 12. System Arbiter

## 4.5. System Clocking and Reset

### 4.5.1. HOST FREQUENCY SUPPORT

The Pentium Pro processor uses a clock ratio scheme where the host bus clock frequency is multiplied by a ratio to produce the processor's core frequency. The PMC supports a host bus frequency ranging up to 66 MHz. The external synthesizer is responsible for generating the host clock. The Pentium Pro processor samples four signals LINT[1:0], IGNNE# and A20M# on the active-to-inactive edge of CPURST# to set the ratio.

### 4.5.2. CLOCK GENERATION AND DISTRIBUTION

The PMC receives two outputs of a clock synthesizer on the HCLKIN and PCLKIN pins. The DBX also receives a clock on its HCLKIN pin. The PMC uses the HCLKIN signal to drive the host, memory and private bus and the PCLKIN bus to drive the PCI interface.

The clock signal requirements for the CPU clock are outlined in the Pentium Pro Bus Input Clock Specification. The clock skew between two host clock outputs of the synthesizer must be less than 250 ps (at 1.5V). The clock skew between two PCI clock outputs of the synthesizer must be less than 500 ps (at 1.5V). In addition, the host clocks should always lead the PCI clocks by a minimum of 1 ns and a maximum of 6 ns. The PMC requires a 45%/55% maximum output duty cycle. A maximum of 200 ps jitter must be maintained on the host clocks going from cycle to cycle.

### 4.5.3. SYSTEM RESET

The PMC contains reset logic for both soft and hard reset. The PMC generates a hard reset at power on. The PMC can be programmed to generate a hard or a soft reset after power on. The PMC generates a soft reset in response to a shutdown bus cycle on the CPU bus. External logic is required to combine the PMC soft reset with the keyboard controller and I/O port 92 soft reset generation. The PMC can also be used to invoke BIST on the CPU. Figure 13 shows the reset structure for the 440FX PCIsset.

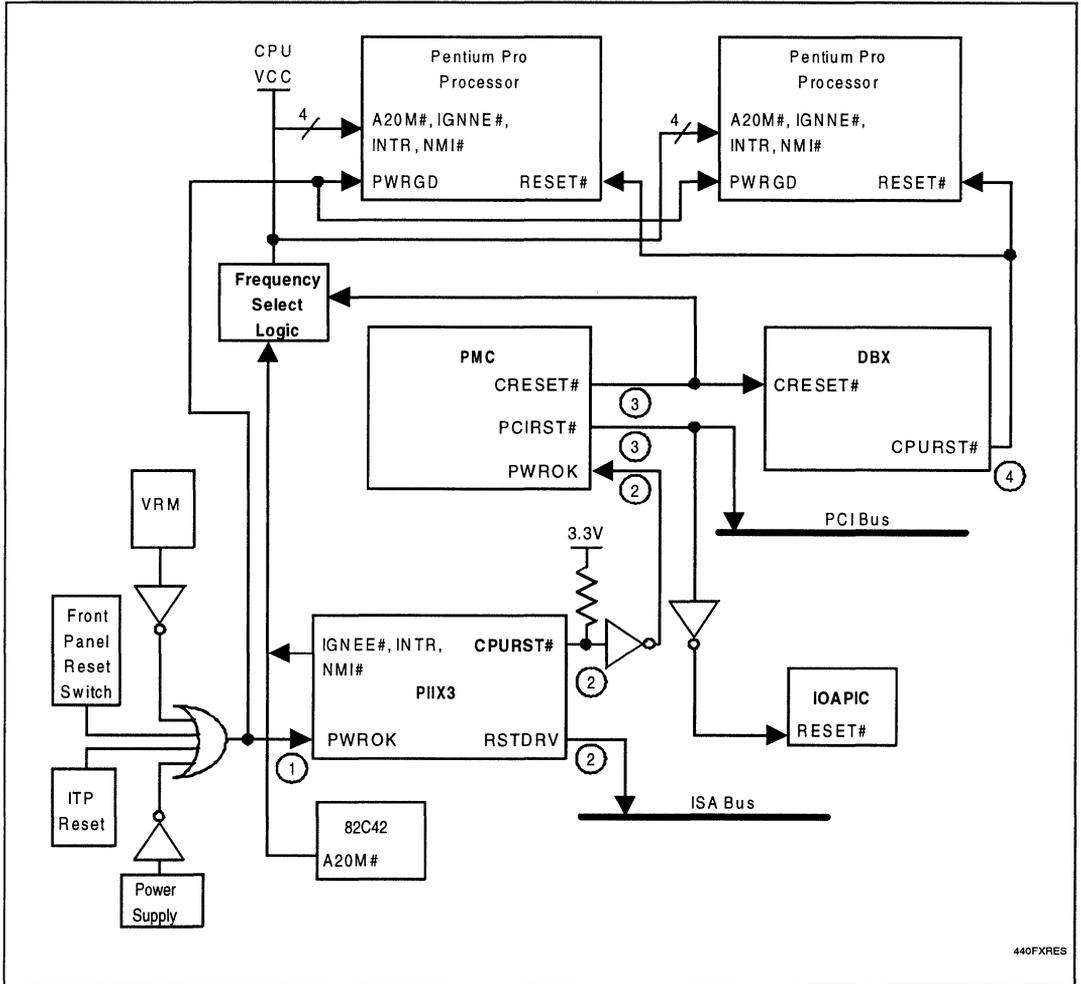


Figure 13. Reset Structure for 440FX PCiset with PIIX3

4.5.3.1. Hard Reset

There are two sources of hard reset in the system:

- During Power-up, PWROK asserted 1 ms after the system power has stabilized
- I/O write to the PMC Turbo/Reset Control Register (configuration offset 93h)

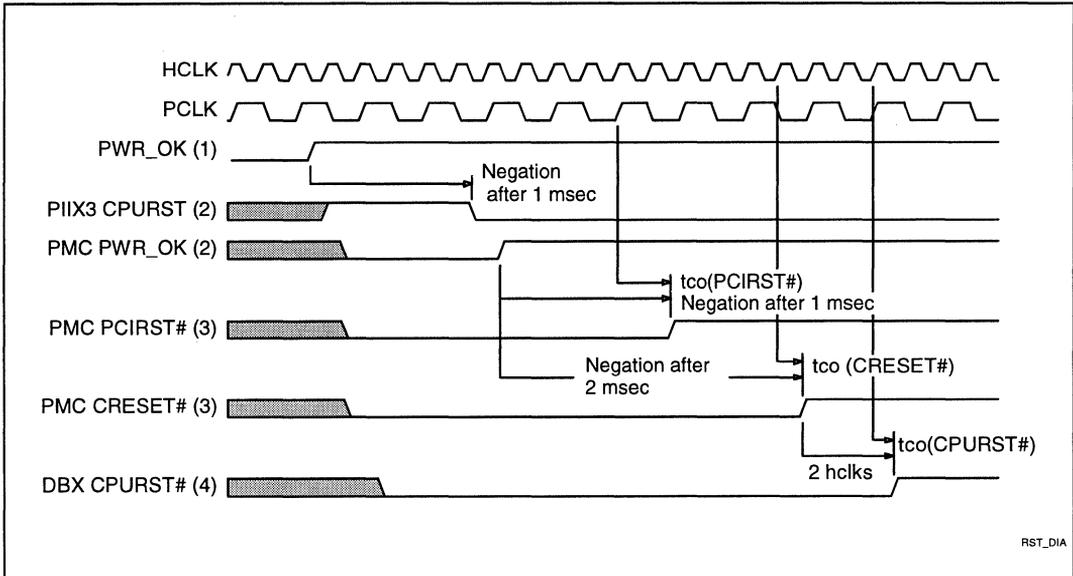


Figure 14. Hard Reset

The PMC generates a hard reset for the system when the PWROK signal is sampled inactive (low). The PMC generates PCIRST# and CRESET# while the PWROK input is sampled inactive (low). The PMC continues to assert PCIRST# for 1 msec and CRESET# for 2 msec after sampling PWROK asserted. CRESET# is an input to the DBX. The DBX drives CPURST# to the CPUs as long as the CRESET# input is sampled active. The DBX releases CPURST# (external GTL+ pullup will drive it high) 2 host clocks after CRESET# is sampled high by the DBX. PCIRST# is negated 1 msec after PWROK is asserted and CRESET# is negated 2 msec after PWROK is negated. CPURST# and CRESET# are released synchronously to the HCLKIN input. PCIRST# is driven synchronously to the PCLKIN input.

Note that the CPURST# output signal from the PIIX3 should be connected to the PMC's PWROK input signal through an inverter. This insures that PIIX3 is reset before the first PCI cycle occurs on the PCI bus. Otherwise, the PWROK signal should be connected to a schmitt trigger buffered version of the power supply POWER\_GOOD signal.

The PMC is the only agent in the system that is allowed to drive PCIRST#. Note that the PCIRST# signal from the PIIX3 should be left as a no connect.

The PMC can be programmed to generate a hard reset through the Turbo/Reset Control Register (configuration offset 93h). The PMC asserts CRESET# for a minimum of 2 msec and PCIRST# for 1 msec. The DBX correspondingly generates the CPURST# to the CPUs. Note that the internal registers of the PMC are also reset.

#### NOTE

The PMC should not be used to generate a hard reset in a system designed with PIIX3. Instead use the PIIX3 to generate the hard reset.

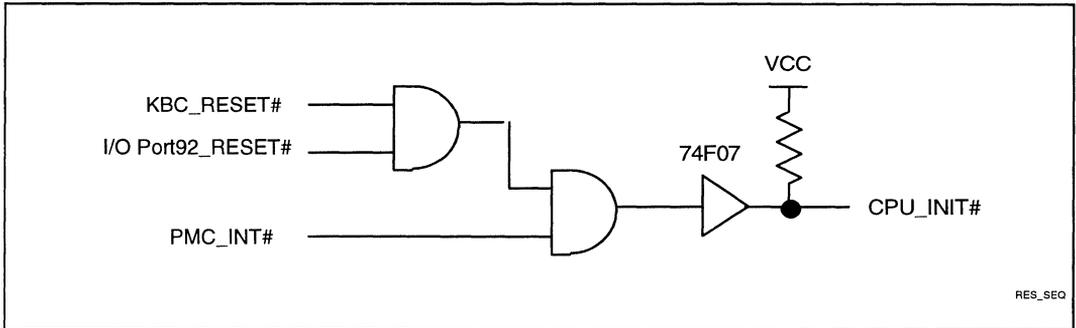
The PMC straps are sampled on the rising edge of PWROK. The DBX receive CRESET# as an input, and reset the internal DBX state machines. The DBX straps are sampled on the rising edge of CRESET#.

**4.5.3.2. Soft Reset**

There are 4 sources of soft reset in the system:

- CPU shutdown bus cycle
- I/O write to the keyboard controller
- I/O write to port 92h
- I/O write to the PMC Turbo/Reset Control Register

When the PMC detects a CPU shutdown bus cycle, it terminates the CPU bus cycle with no data response type as defined in the Pentium Pro processor EBS and then asserts INIT# for a minimum of 4 host clocks. The PMC can be programmed to generate a soft reset through the Turbo/Reset Control Register (offset 93h). The PMC asserts INIT# for a minimum of 4 host clocks. The INIT# output of the PMC must be externally gated with the I/O port 92 (not supported on PII/X3) and keyboard controller soft reset sources as shown in Figure 15.



**Figure 15. Reset Sequencing**

**4.5.3.3. CPU BIST**

The PMC can be programmed to activate BIST mode of the CPU through the Turbo Reset Control register (offset 93h). The PMC asserts both CRESET# and INIT#. The PMC asserts PCIRST# for 1 msec, CRESET# for 2 msec and asserts INIT# for 2 msec plus 16 host clocks. The DBX correspondingly asserts CPURST# to the CPUs. This invokes BIST mode on the CPU.

## 5.0. PINOUT AND PACKAGE SPECIFICATIONS

### 5.1. PMC Pinout Information

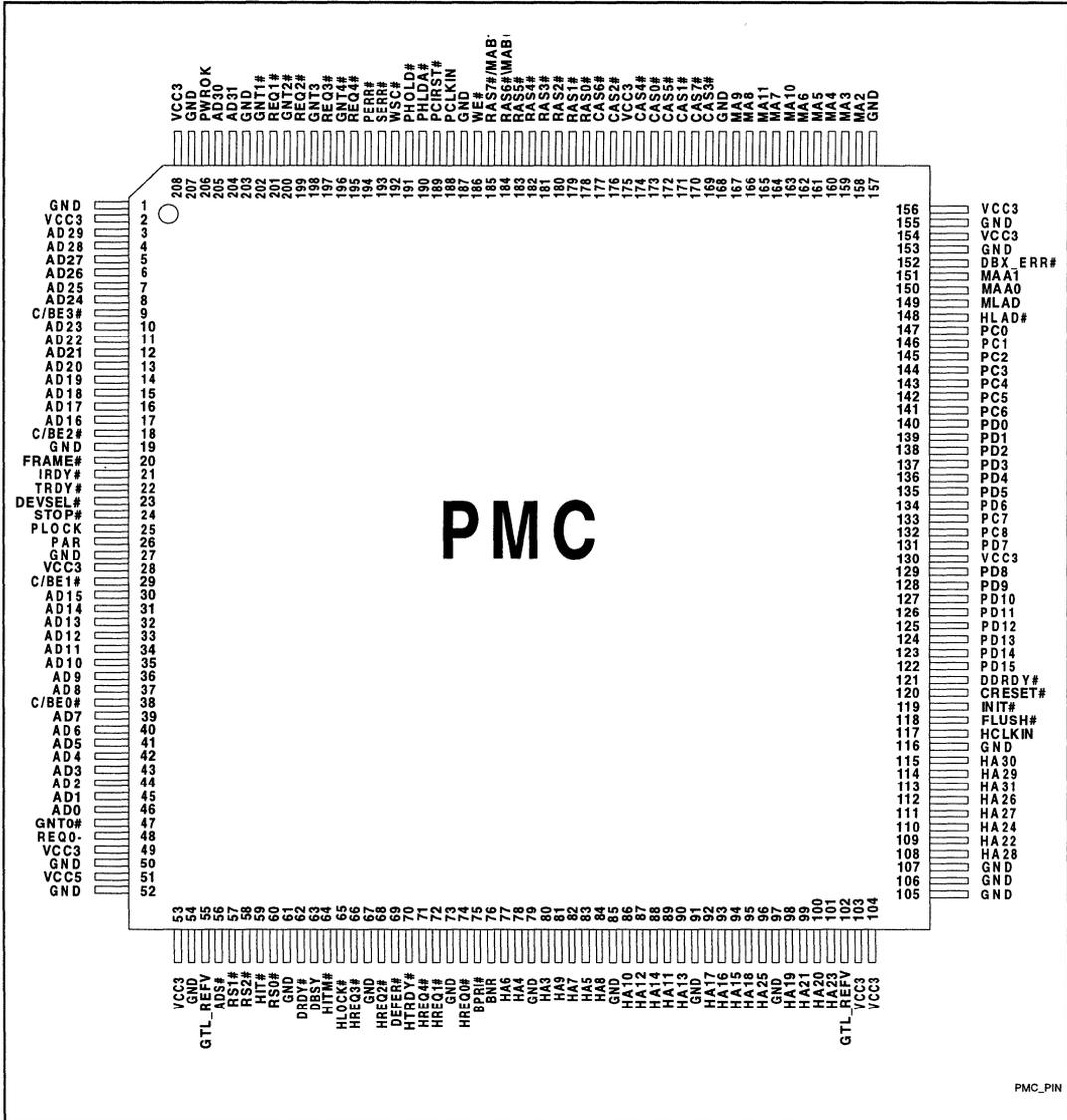


Figure 16. PMC Pinout Diagram

**Table 10. PMC Alphabetical Pin Assignment**

Name	Pin#	Type
AD0	46	I/O
AD1	45	I/O
AD2	44	I/O
AD3	43	I/O
AD4	42	I/O
AD5	41	I/O
AD6	40	I/O
AD7	39	I/O
AD8	37	I/O
AD9	36	I/O
AD10	35	I/O
AD11	34	I/O
AD12	33	I/O
AD13	32	I/O
AD14	31	I/O
AD15	30	I/O
AD16	17	I/O
AD17	16	I/O
AD18	15	I/O
AD19	14	I/O
AD20	13	I/O
AD21	12	I/O
AD22	11	I/O
AD23	10	I/O
AD24	8	I/O
AD25	7	I/O
AD26	6	I/O
AD27	5	I/O
AD28	4	I/O

**Table 10. PMC Alphabetical Pin Assignment**

Name	Pin#	Type
AD29	3	I/O
AD30	205	I/O
AD31	204	I/O
ADS#	56	I/O
BNR	76	O
BPRI#	75	O
C/BE0#	38	I/O
C/BE1#	29	I/O
C/BE2#	18	I/O
C/BE3#	9	I/O
CAS0#	173	O
CAS1#	171	O
CAS2#	176	O
CAS3#	169	O
CAS4#	174	O
CAS5#	172	O
CAS6#	177	O
CAS7#	170	O
CRESET#	120	O
DBSY	63	I/O
DBX_ERR#	152	I/O
DDRDY#	121	
DEFER#	69	O
DEVSEL#	23	I/O
DRDY#	62	I/O
FLUSH#	118	I
FRAME#	20	I/O
GND	1	V
GND	19	V

**Table 10. PMC Alphabetical Pin Assignment**

Name	Pin#	Type
GND	27	V
GND	50	V
GND	52	V
GND	54	V
GND	61	V
GND	67	V
GND	73	V
GND	79	V
GND	85	V
GND	91	V
GND	97	V
GND	105	V
GND	106	V
GND	107	V
GND	116	V
GND	153	V
GND	155	V
GND	157	V
GND	168	V
GND	187	V
GND	203	V
GND	207	V
GNT0#	47	O
GNT1#	202	I
GNT2#	200	I
GNT3#	198	I
GNT4#	196	I
GTL_REFV	55	V
GTL_REFV	102	V

Table 10. PMC Alphabetical Pin Assignment

Name	Pin#	Type
HA3	80	I/O
HA4	78	I/O
HA5	83	I/O
HA6	77	I/O
HA7	82	I/O
HA8	84	I/O
HA9	81	I/O
HA10	86	I/O
HA11	89	I/O
HA12	87	I/O
HA13	90	I/O
HA14	88	I/O
HA15	94	I/O
HA16	93	I/O
HA17	92	I/O
HA18	95	I/O
HA19	98	I/O
HA20	100	I/O
HA21	99	I/O
HA22	109	I/O
HA23	101	I/O
HA24	110	I/O
HA25	96	I/O
HA26	112	I/O
HA27	111	I/O
HA28	108	I/O
HA29	114	I/O
HA30	115	I/O
HA31	113	I/O
HCLKIN	117	I

Table 10. PMC Alphabetical Pin Assignment

Name	Pin#	Type
HIT#	59	I/O
HITM#	64	I/O
HLAD#	148	O
HLOCK#	65	I
HREQ0#	74	I/O
HREQ1#	72	I/O
HREQ2#	68	I/O
HREQ3#	66	I/O
HREQ4#	71	I/O
HTRDY#	70	I/O
INIT#	119	I
IRDY#	21	I/O
MA2	158	O
MA3	159	O
MA4	160	O
MA5	161	O
MA6	162	O
MA7	164	O
MA8	166	O
MA9	167	O
MA10	163	O
MA11	165	O
MAA0	150	O
MAA1	151	O
MLAD	149	O
PAR	26	I/O
PC0	147	O
PC1	146	O
PC2	145	O
PC3	144	O

Table 10. PMC Alphabetical Pin Assignment

Name	Pin#	Type
PC4	143	O
PC5	142	O
PC6	141	O
PC7	133	O
PC8	132	O
PCIRST#	189	I
PCLKIN	188	I
PD0	140	O
PD1	139	O
PD2	138	O
PD3	137	O
PD4	136	O
PD5	135	O
PD6	134	O
PD7	131	O
PD8	129	O
PD9	128	O
PD10	127	O
PD11	126	O
PD12	125	O
PD13	124	O
PD14	123	O
PD15	122	O
PERR#	194	I/O
PHLD#	191	I
PHLDA#	190	O
PLOCK	25	I/O
PWROK	206	I
RAS0#	178	O
RAS1#	179	O

**Table 10. PMC Alphabetical Pin Assignment**

Name	Pin#	Type
RAS2#	180	O
RAS3#	181	O
RAS4#	182	O
RAS5#	183	O
RAS6#/ MAB0	184	O
RAS7#/ MAB1	185	O
REQ0#	48	I
REQ1#	201	O
REQ2#	199	O
REQ3#	197	O
REQ4#	195	O

**Table 10. PMC Alphabetical Pin Assignment**

Name	Pin#	Type
RS0#	60	I/O
RS1#	57	I/O
RS2#	58	I/O
SERR#	193	O
STOP#	24	I/O
TRDY#	22	I/O
VCC3	2	V
VCC3	28	V
VCC3	49	V
VCC3	53	V
VCC3	103	V
VCC3	104	V

**Table 10. PMC Alphabetical Pin Assignment**

Name	Pin#	Type
VCC3	130	V
VCC3	154	V
VCC3	156	V
VCC3	175	V
VCC3	208	V
VCC5	51	V
WE#	186	O
WSC#	192	O

5.2. DBX Pinout Information

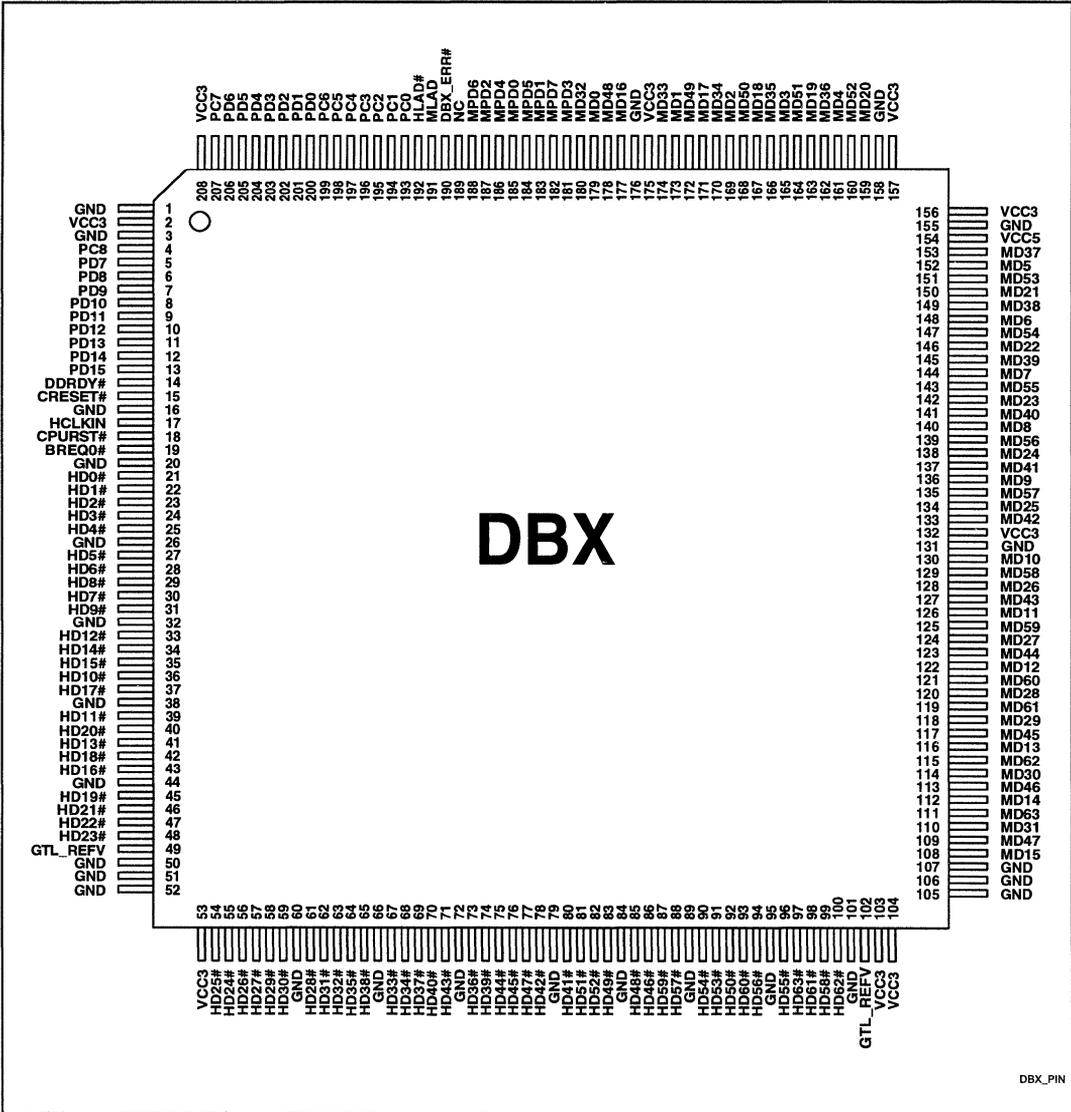


Figure 17. DBX Pinout Diagram

**Table 11. DBX Alphabetical Pin Assignment**

Name	Pin#	Type
BREQ0#	19	O
CPURST#	18	O
CRESET#	15	I
DBX_ERR#	190	I/O
DDRDY#	14	I
GLT_REFV	102	V
GND	1	V
GND	3	V
GND	16	V
GND	20	V
GND	26	V
GND	32	V
GND	38	V
GND	44	V
GND	50	V
GND	51	V
GND	52	V
GND	60	V
GND	66	V
GND	72	V
GND	79	V
GND	84	V
GND	89	V
GND	95	V
GND	101	V
GND	105	V
GND	106	V
GND	107	V
GND	131	V

**Table 11. DBX Alphabetical Pin Assignment**

Name	Pin#	Type
GND	155	V
GND	158	V
GND	176	V
GTL_REFV	49	V
HCLKIN	17	I
HD0#	21	I/O
HD1#	22	I/O
HD2#	23	I/O
HD3#	24	I/O
HD4#	25	I/O
HD5#	27	I/O
HD6#	28	I/O
HD7#	30	I/O
HD8#	29	I/O
HD9#	31	I/O
HD10#	36	I/O
HD11#	39	I/O
HD12#	33	I/O
HD13#	41	I/O
HD14#	34	I/O
HD15#	35	I/O
HD16#	43	I/O
HD17#	37	I/O
HD18#	42	I/O
HD19#	45	I/O
HD20#	40	I/O
HD21#	46	I/O
HD22#	47	I/O
HD23#	48	I/O

**Table 11. DBX Alphabetical Pin Assignment**

Name	Pin#	Type
HD24#	55	I/O
HD25#	54	I/O
HD26#	56	I/O
HD27#	57	I/O
HD28#	61	I/O
HD29#	58	I/O
HD30#	59	I/O
HD31#	62	I/O
HD32#	63	I/O
HD33#	67	I/O
HD34#	68	I/O
HD35#	64	I/O
HD36#	73	I/O
HD37#	69	I/O
HD38#	65	I/O
HD39#	74	I/O
HD40#	70	I/O
HD41#	80	I/O
HD42#	78	I/O
HD43#	71	I/O
HD44#	75	I/O
HD45#	76	I/O
HD46#	86	I/O
HD47#	77	I/O
HD48#	85	I/O
HD49#	83	I/O
HD50#	92	I/O
HD51#	81	I/O
HD52#	82	I/O

**Table 11. DBX Alphabetical  
Pin Assignment**

Name	Pin#	Type
HD53#	91	I/O
HD54#	90	I/O
HD55#	96	I/O
HD56#	94	I/O
HD57#	88	I/O
HD58#	99	I/O
HD59#	87	I/O
HD60#	93	I/O
HD61#	98	I/O
HD62#	100	I/O
HD63#	97	I/O
HLAD#	192	I
MD0	179	I/O
MD1	173	I/O
MD2	169	I/O
MD3	165	I/O
MD4	161	I/O
MD5	152	I/O
MD6	148	I/O
MD7	144	I/O
MD8	140	I/O
MD9	136	I/O
MD10	130	I/O
MD11	126	I/O
MD12	122	I/O
MD13	116	I/O
MD14	112	I/O
MD15	108	I/O
MD16	177	I/O
MD17	171	I/O

**Table 11. DBX Alphabetical  
Pin Assignment**

Name	Pin#	Type
MD18	167	I/O
MD19	163	I/O
MD20	159	I/O
MD21	150	I/O
MD22	146	I/O
MD23	142	I/O
MD24	138	I/O
MD25	134	I/O
MD26	128	I/O
MD27	124	I/O
MD28	120	I/O
MD29	118	I/O
MD30	114	I/O
MD31	110	I/O
MD32	180	I/O
MD33	174	I/O
MD34	170	I/O
MD35	166	I/O
MD36	162	I/O
MD37	153	I/O
MD38	149	I/O
MD39	145	I/O
MD40	141	I/O
MD41	137	I/O
MD42	133	I/O
MD43	127	I/O
MD44	123	I/O
MD45	117	I/O
MD46	113	I/O
MD47	109	I/O

**Table 11. DBX Alphabetical  
Pin Assignment**

Name	Pin#	Type
MD48	178	I/O
MD49	172	I/O
MD50	168	I/O
MD51	164	I/O
MD52	160	I/O
MD53	151	I/O
MD54	147	I/O
MD55	143	I/O
MD56	139	I/O
MD57	135	I/O
MD58	129	I/O
MD59	125	I/O
MD60	121	I/O
MD61	119	I/O
MD62	115	I/O
MD63	111	I/O
MLAD	191	I
MPD0	185	I/O
MPD1	183	I/O
MPD2	187	I/O
MPD3	181	I/O
MPD4	186	I/O
MPD5	184	I/O
MPD6	188	I/O
MPD7	182	I/O
NC	189	
PC0	193	I
PC1	194	I
PC2	195	I
PC3	196	I

**Table 11. DBX Alphabetical Pin Assignment**

Name	Pin#	Type
PC4	197	I
PC5	198	I
PC6	199	I
PC7	207	I
PC8	4	I
PD0	200	I
PD1	201	I
PD2	202	I
PD3	203	I
PD4	204	I
PD5	205	I

**Table 11. DBX Alphabetical Pin Assignment**

Name	Pin#	Type
PD6	206	I
PD7	5	I
PD8	6	I
PD9	7	I
PD10	8	I
PD11	9	I
PD12	10	I
PD13	11	I
PD14	12	I
PD15	13	I
VCC3	2	V

**Table 11. DBX Alphabetical Pin Assignment**

Name	Pin#	Type
VCC3	53	V
VCC3	103	V
VCC3	104	V
VCC3	132	V
VCC3	156	V
VCC3	157	V
VCC3	175	V
VCC3	208	V
VCC5	154	V

### 5.3. PMC & DBX Package Specifications

Both PMC and DBX use a 208 pin PQFP package (Figure 18).

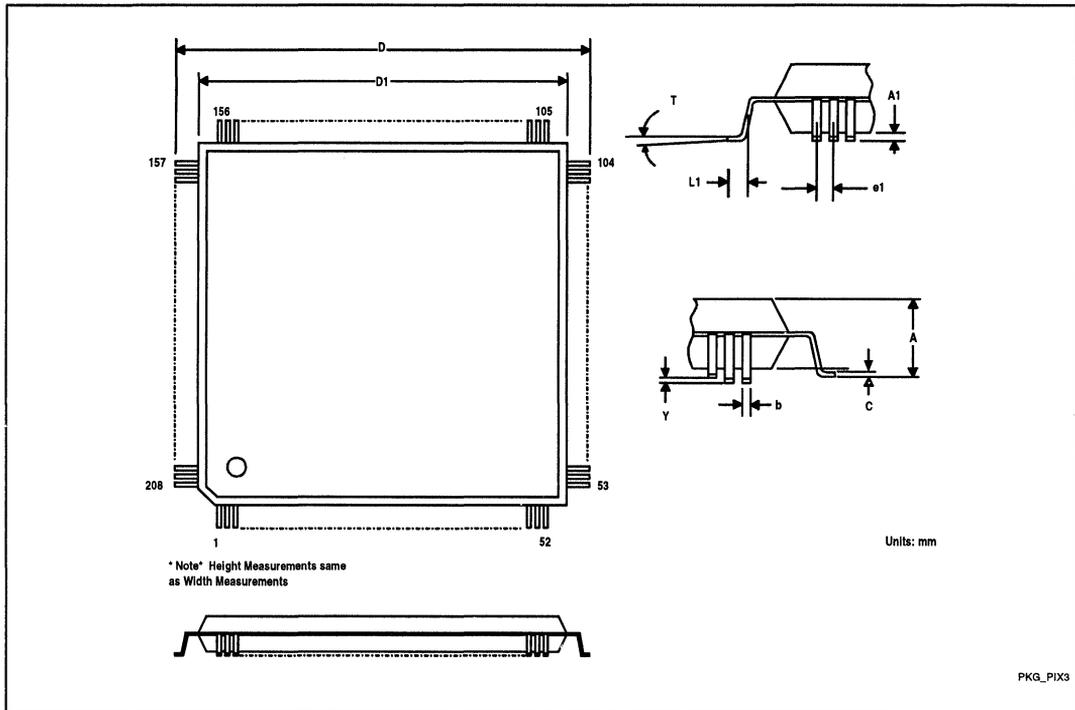


Figure 18. 208 Pin Quad Flat Pack (QFP) Dimensions

Table 12. 208 Pin Quad Flat Pack (QFP) Dimensions

Symbol	Description	Value (mm)
A	Seating Height	4.25 (max)
A1	Stand-off	0.05 (min); 0.40 (max)
b	Lead Width	$0.2 \pm 0.10$
C	Lead Thickness	$0.15 +0.1/-0.05$
D	Package Length and Width, including pins	$30.6 \pm 0.4$
D1	Package Length and Width, excluding pins	$28 \pm 0.2$
e1	Linear Lead Pitch	$0.5 \pm 0.1$
Y	Lead Coplanarity	0.08 (max)
L1	Foot Length	$0.5 \pm 0.2$
T	Lead Angle	$0^\circ - 10^\circ$

## 6.0. TESTABILITY

The test modes described below are provided in the 82441FX and 82442FX for Automated Test Equipment (ATE) board level testing.

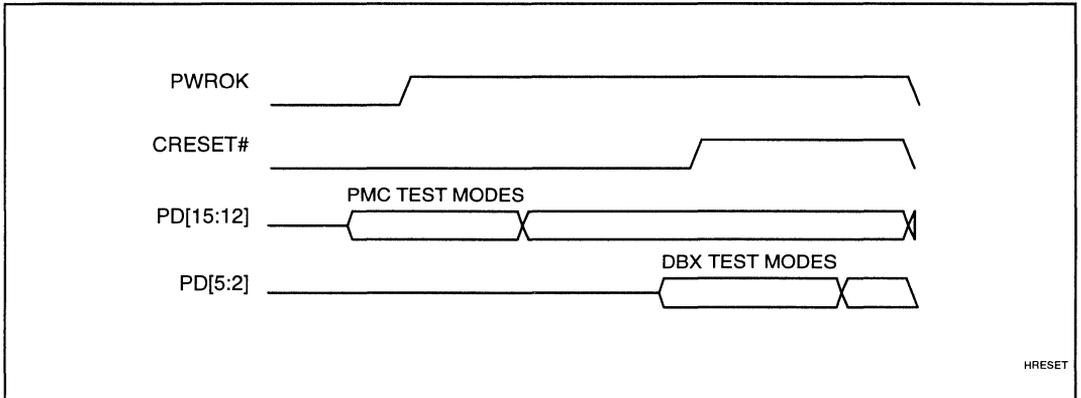


Figure 19. Hard Reset

## 6.1. 82441FX (PMC) Test Modes

The test mode of the 82441FX is latched at the rising edge of PWROK. The PMC uses PD[15:12] as test mode inputs. The PMC test modes are selected as shown in Table 13.

Table 13. PMC Test Mode Select

PD15	PD14	PD13	PD12	Mode Selected
0	0	0	0	Normal (Default)
0	0	1	0	NAND Tree
0	0	1	1	All 1s
0	1	0	0	All 0s
1	0	0	1	Tristate

**Normal Mode** - This is the functional mode of PMC. It is enabled as default via weak 50 KΩ pull-down devices.

**NAND Tree Mode** - This allows ATE to test the connectivity of the PMC signal pins. PD[9:8] are outputs of the NAND tree, PD9 is the end of the NAND tree and PD8 is the midpoint. The procedure for enabling this mode is as follows:

- Initiate HCLK and PCLK. Set PD[15:12]=0011 which is latched on the low to high edge of PWROK. Stop all clocks.
- Put DBX, PIIX3, and IOAPIC in tristate mode.

## 82441FX (PMC) AND 82442FX (DBX)

- All inputs are forced high, starting from PD7 (input furthest from PD9), and following the pinout until it ends with PD10.
- Inputs are pulsed low, one at a time starting with PD7. This toggles PD9 each time an input is changed. The last input in the chain is PD10. NAND Tree order follows the pinout. PWROK, CRESET#, PD9 and PD8 are not a part of the NAND tree.

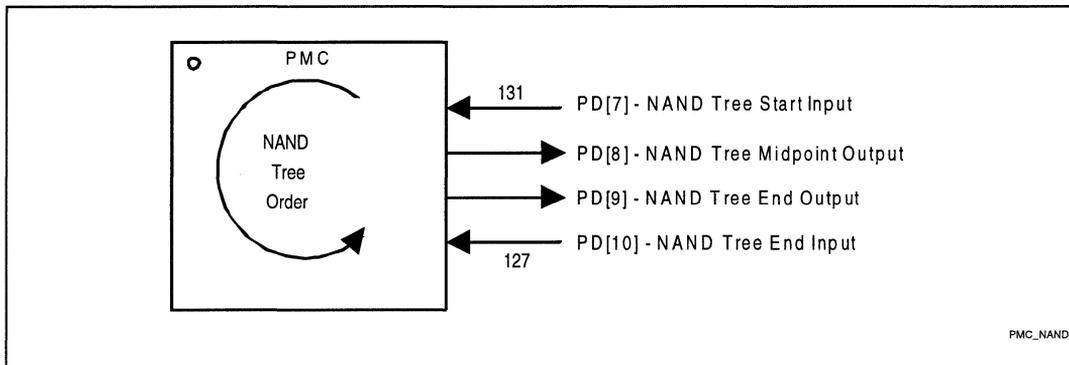


Figure 20. PMC NAND Tree

**All 1s Mode** - This mode allows all the outputs to be set high (set to 1). Setting PD[15:12]=0011 enables this mode on the low to high transition of PWROK.

**All 0s Mode** - This mode allows all the outputs to be set low (set to 0). Setting PD[15:12]=0100 enables this mode on the low to high transition of PWROK.

**Tristate Mode** - This mode allows all the outputs to be tristated “High-Z”. Setting PD[15:12]=1001 enables this mode on the low to high transition of PWROK. All GTL+ inputs are turned off.

## 6.2. DBX Test Mode

The test mode of the 82442FX is latched at the rising edge of CRESET#. The DBX uses PD[5:2] as test mode inputs. The DBX test modes are selected as shown in Table 14.

Table 14. DBX Test Mode Select

PD5	PD4	PD3	PD2	Mode Selected
0	0	0	0	Normal (Default)
0	0	1	0	NAND Tree
0	0	1	1	All 1s
0	1	0	0	All 0s
1	0	0	1	Tristate

**Normal Mode** - This is the functional mode of DBX. It is enabled as default via weak 50 KΩ pull-down devices.

**NAND Tree Mode** - This allows ATE to test the connectivity of the DBX signal pins. PD[9:8] are outputs of the NAND tree; PD9 is the end of the NAND tree and PD8 is the midpoint. The procedure for enabling this mode is as follows:

- Initiate HCLK and PCLK. Set PD[5:2]=0011 which is latched on the low to high edge of CRESET#. Stop all clocks.
- Put PMC, PIIX3, and IOAPIC in tristate mode.
- All inputs are forced high, starting from PD7 (input furthest from PD9), and following the pinout until it ends with PD10.
- Inputs are pulsed low, one at a time starting with PD7. This toggles PD9 each time an input is changed. The last input in the chain is PD10. NAND Tree order follows the pinout. CRESET#, PD9, and PD8 are not a part of the NAND tree.

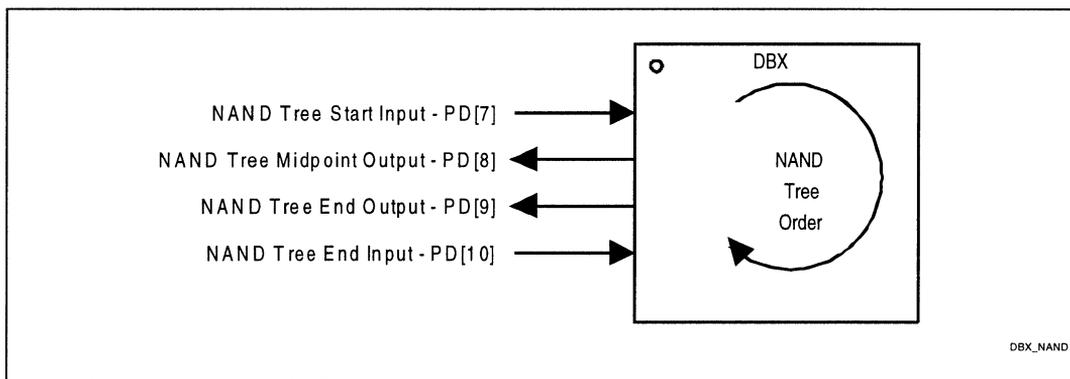


Figure 21. DBX NAND Tree

**All 1s Mode** - This mode allows all the outputs to be set high (set to 1). Setting PD[5:2]=0011 enables this mode on the low to high transition of CRESET#.

**All 0s Mode** - This mode allows all the outputs to be set low (set to 0). Setting PD[5:2]=0100 enables this mode on the low to high transition of CRESET#.

**Tristate Mode** - This mode allows all the outputs to be tristated "High-Z". Setting PD[5:2]=1001 enables this mode on the low to high transition of CRESET#. All GTL+ inputs are turned off.



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