NISHA INTERFACE

GENERAL DESCRIPTION:

PIN	SIGNAL NAME	1/0	FUNCTION
1	INDEX	0	THIS SIGNAL INDICATES THE BEGINNING OF SERVO SECTOR AND END OF DATA SECTOR 31. ONE PER REVOLUTION (2749RPM + - 1.5%).
3	SECTOR	0	THIS SIGNAL INDICATES THE BEGINNING OF DATA SECTORS. TOTAL DATA SECTORS IS 32 STARTING FROM SECTOR 0 TO 31. EACH SECTOR HAS 620+-16 BYTES OR 661+-17 US.
5	RWCLK	0	READ/WRITE CLOCK IS THE SIGNAL TO SYNCHRONIZE THE DRIVE READ/WRITE DATA. CLOCK FREQUENCY IS 7.5 MHZ + - 40%. WITH 50+-10 % DUTY CYCLE.
7	/RDATA	0	NRZ READ DATA FROM DRIVE IS SYNCHRONIZED TO THE RISING EDGE OF THE READ/WRITE CLOCK (RWCLK). READ DATA CAN CHANGE AT A MIN. OF 40NS AND AT A MAX. OF 90NS FROM THE RISING EDGE OF THE RWCLK.
9	WDATA	1	NRZ WRITE DATA FROM CONTROLLER IS SYNCHRONIZED TO THE RISING EDGE OF THE RWCLK. WRITE DATA CAN CHANGE AT A MIN. OF 40NS AND AT A MAX. OF 90NS FROM THE RISING EDGE OF THE RWCLK.
11	/WTGT	ł	WRITE GATE FROM CONTROLLER, WHICH INDICATES THAT WRITE DATA IS SHIFTING FROM CONTROLLER TO DRIVE.
12	HS0	l	HEAD SELECT O INDICATES THE SELECTION OF HEAD O. HEAD SWITCHING RECOVERY TIME IS 1 US.
13	RDGT	i	READ GATE FROM CONTROLLER, WHICH MUST BE TURNED ON AT GLITCH FREE DATA SYNCHRONIZATION AREA. READ DATA WILL BE AYAILABLE AFTER YCO IS LOCKED ON THE DATA SYNCHRONIZATION BYTES (00). YCO LOCK ON TIME IS 12 BYTES MAXIMUM.
14	HS1	I	HEAD SELECT 1, A RESERVED PIN FOR FUTURE ADDITION OF READ WRITE HEADS.
15	SERYOUT	0	SERVO SERIAL DATA OUT IS AN OUTPUT SIGNAL THAT SHIFTS SERVO STATUS FROM DRIVE TO CONTROLLER AT A MAX. RATE OF 58.6 K BITS/SEC.
16	/RWI		REDUCED WRITE CURRENT IS A SIGNAL THAT INDICATES TO DRIVE THAT LESS WRITE CURRENT IS REQUIRED AT THE INSIDE TRACKS WHICH HAVE MUCH HIGHER FLUX CHANGE PER INCH (FCI).
17	SERYOIN	1	SERYO SERIAL DATA IN IS AN INPUT SIGNAL THAT SHIFTS SERYO COMMANDS FROM CONTROLLER TO DRIVE AT A MAX. RATE OF 58.6 K BITS/SEC.
18	/SERYORST	ı	SERYO RESET IS AN INPUT SIGNAL THAT RESET THE SERYO CONTROL FUNCTIONS.

NISHA INTERFACE

19	SIORDY	0	SERVO INPUT/OUTPUT READY IS AN INDICATION FROM DRIVE TO CONTROLLER THAT SERVO COMMUNICATION IS READY.
21	SERYORDY	0	SERYO READY IS AN OUTPUT SIGNAL THAT DRIVE INDICATES TO CONTROLLER THAT READ/WRITE HEAD IS ON TRACK AND IS READY FOR READ/WRITE DATA TRANSFER.
23 .4	SERYOERR _wite_scy	0 'L.	SERVO ERROR IS AN OUTPUT SIGNAL THAT DRIVE INDICATES TO CONTROLLER THAT SERVO COMMUNICATION HAS AN ERROR OR SERVO TRACK FOLLOWING HAS AN ERROR.
8	+5Y	1	POWER SUPPLY INPUT
10	+5Y	1	POWER SUPPLY INPUT
2	GND	i	GROUND
4	GND	1	GROUND
6	GND	1	GROUND
20	+ 1 2¥	ſ	POWER SUPPLY INPUT
	+ 12Y	ı	POWER SUPPLY INPUT
24	-12Y	1	NEGATIYE POWER SUPPLY INPUT
25	MOTOR 12Y	1	POWER SUPPLY TO MOTOR (ISOLATED FROM + 12Y IN NISHA)
26	MOTOR GND	1	MOTOR GROUND (ISOLATED FROM GND IN NISHA)

NISHA INTERFACE

DC ELECTRICAL CHARACTERISTICS (TEMPERATURE=10 TO 60 C)

PARAM	IETER	MIN -0.3	TYP	MAX	UNIT Y	COMMENTS IOL MAX=- 400UA
YIL	INPUT LOW YOLTAGE			0.8		
YIH	INPUT HIGH YOLTAGE	2.0		YCC	Y	IOH MAX=+40 UA
YOL	OUTPUT LOW YOLTAGE			0.4	Y	3 LSTTL=+1.2 MA
HOY	OUTPUT HIGH YOLTAGE	2.4			Y	3 LSTTL=-120UA
57	POWER SUPPLY YOLTAGE	4.75	5.00	5.25	Y	1A MAX
+12Y	POWER SUPPLY YOLTAGE	12.0		13.2	¥	
-12Y	NEG POWER SUPPLY YOLTAGE	-12.0		-13.2	2 Y	
MOTOR	+ 12Y MOTOR SUPPLY YOLTAGE	12.0		13.2	¥	





