

PART 5

DOS/BATCH DEVICE DRIVERS

PART 5

CHAPTER 1

USING DEVICE DRIVERS OUTSIDE DOS/BATCH

Subroutines to handle I/O transfers between a PDP-11 and each of its peripheral devices are developed as required for use within the Disk Operating System DOS/BATCH. These subroutines are made available within an I/O Utilities Package for the benefit of PDP-11 users who have configurations unable to support DOS/BATCH or who wish to run programs outside DOS/BATCH control.

All the subroutines associated with one peripheral device form an entity known as a device driver. This part provides a general description of a driver and shows how it can be used in a stand-alone environment. The unique properties of each driver are discussed in separate documents, which are made available as part of the Device Driver Package. The I/O utilities package for any system is determined by the peripherals of that system. Thus, the full documentation for a particular package consists of this document and applicable supplements.

PART 5

CHAPTER 2

DRIVER FORMAT

2.1 STRUCTURE

The basic principle of all drivers under the DOS/BATCH Monitor is that they must present a common interface to the routines using them in order to provide device-independent operation. The subroutines are structured to meet this end. Moreover, a driver can be loaded anywhere in memory under Monitor Control. Its code is always position-independent (PIC).¹

A detailed description of a driver is found in Chapter 5-4. This section describes driver interfaces.

2.1.1 Driver Interface Table

The first section of each driver is a table which contains, in a standard format, information on the nature and capabilities of the device it represents and entry points to each of its subroutines. The calling program can use this table as required, regardless of the device being called. See Section 5-4.1 for a detailed description of the table.

2.1.2 Setup Routines

Each driver is expected to handle its device under the PDP-11 interrupt system. When called by a program, therefore, a driver subroutine merely initiates the required action by setting the device hardware registers appropriately. It returns to the calling program by a standard subroutine exit.

The main setup routines prepares for a data transfer to or from the device, using parameters supplied by the calling program. Normally, blocks of data are moved at each transfer. The driver returns control to the program only when the whole block has been transferred or when it is unable to continue because there is no more data available.

¹See Part 6 for information on PIC.

The driver can also contain subroutines by which the calling program can request (1) start-up or shut-down action, such as leader or trailer functions for a paper tape punch, or (2) some special function provided by the device hardware (or a software simulation of that for some similar device), e.g., rewind of a magnetic tape or DECTape.

2.1.3 Interrupt Servicing

The driver routine to service device interrupts is particularly dependent upon the device hardware provisions for controlling transfers. In general, the driver determines the cause of the interrupt and checks whether the last action was performed correctly or was prevented by some error condition. If more device action is needed to satisfy the program request, the driver again initiates that action and takes a normal interrupt exit. If the program request has been fully met, control is returned to the program at an address supplied at the time of the request.

2.1.4 Error Handling

Device errors can be handled in two ways. There are some errors for which recovery can be programmed; the driver, if appropriate, attempts this itself (as in the case of parity or timing failure on a bulk-storage device) or recalls the program with the error condition flagged (as at the end of a physical paper tape). Other errors normally require external action, perhaps by an operator. The driver calls a DOS/BATCH error handler via an IOT call with supporting information on the processor stack.

2.2 INTERFACE TO THE DRIVER

2.2.1 Control Interface

The principal link between a calling program and any driver subroutine is the first word of the driver table (link word). In order to provide the control parameters for a device operation, the calling program prepares a list in a standardized form and places a pointer to the list in the link word. The called driver uses the pointer to access the parameters. The driver can place return status information (if needed) in the list area via the link word. The first word of the driver table can also act as a busy indicator; if it is \emptyset , the driver is not currently performing a task, but if it contains a listpointer, the driver can be assumed to be busy. Since most drivers support only one job at a time, the link word state is significant.

2.2.2 Interrupt Interface

Although the driver expects to use the interrupt system, it does not itself ensure that its interrupt vector in the memory area below 400_8 has been set up correctly; the Monitor takes care of this. However, the driver table contains the information required to initialize the appropriate vector.

PART 5

CHAPTER 3

STAND-ALONE USE

Because each driver is designed for operation within the device-independent framework of the Monitor, it can be similarly used in other applications. Since the easiest way to use the driver is to assemble it with the program that requires it, this method will be described first. Other possible methods will be discussed later.

3.1 DRIVER ASSEMBLED WITH PROGRAM

3.1.1 Setting Interrupt Vector

As noted in Section 5-2.2.2, the calling program must initialize the device transfer vector within memory locations 0-377. The address of the driver's interrupt entry point can be identified on the source listing by the symbolic name which appears as the contents of the Driver Table Byte, DRIVER+5. The priority level at which the driver expects to process the interrupt is at byte DRIVER+6. For a program which can reference position-dependent code, the setup sequence might be:

```
MOV          #DVRINT,VECTOR      ;SET INT. ADDRESS
MOVB        DRIVER+6,VECTOR+2    ;SET PRIORITY
CLRB        VECTOR+3            ;CLEAR UPPER STATUS BYTE
```

where the Driver Table Byte (at DRIVER+5) shows the following instruction:

```
.BYTE DVRINT-DRIVER
```

If the program must be position-independent, it can take advantage of the fact that the Interrupt Entry address is stored as an offset from the start of the driver, as illustrated above. In this case, a sample sequence might be:

```
MOV          PC,R1              ;GET DRIVER START
ADD          #DRIVER-.,R1
MOV          #VECTOR,R2        ;...& VECTOR ADDRESSED
CLRB        @R2                ;SET INT. ADDRESS
MOVB        5(R1),@R2          ;...AS START ADDRESS+OFFSET
ADD          R1,(R2)+
CLRB        @R2                SET PRIORITY
MOVB        6(R1),@R2
```

3.1.2 Parameter Table for Driver Call

For any call to the driver the program must provide a list of control arguments mentioned in Section 5-2.2.1. This list must adhere to the following format:¹

[SPECIAL FUNCTION POINTER]²
[BLOCK NO.]³
STARTING MEMORY ADDRESS FOR TRANSFER
NO. OF WORDS to be transferred (2's complement)
STATUS CONTROL showing in Bits:

 0-2 Function (octally 2=WRITE, 4=READ)⁴
 8-10 Unit (if Device can consist of several units, e.g., DECTape)
 11 Direction for DECTape travel (0=Forward)

ADDRESS for RETURN ON COMPLETION
[RESERVED FOR DRIVER USE]⁵

The list can be assembled in the required format since its content will not vary. The driver can return information in this area; this will not corrupt the program data.

On the other hand, most programs will probably use the same list area for several tasks or even for different drivers. In this case, the program must contain the necessary routine to set up the list for each task before making the driver call. The driver may refer to the list again when it is recalled by an interrupt or when returning information to the calling program. Therefore, the list must not be changed until any driver has completed a function requested; for concurrent operations, different list areas must be provided.

¹In some cases, it can be further extended as discussed in later sections.

²Required only if Driver is being called for Special Function; addresses a Special Function Block.

³Required only if the device is bulk storage (e.g., Disk or DECTape).

⁴Most devices transfer words regardless of their content, i.e., ASCII or Binary. Some devices (e.g., Card Reader) may be handled differently depending on the mode for these, Bit 0 must also be set to indicate ASCII=0, Binary =1. In these cases, the driver always produces or accepts ASCII even though the device itself uses some other code.

⁵This word may be omitted if the device is bulk storage.

3.1.3 Calling the Driver

To enable the driver to access the parameter list, the program must set the first word of the driver to an address six bytes less than that of the word containing the MEMORY START ADDRESS. It can then directly call the required driver subroutine by a normal JSR PC,xxxx call, where xxxx is the address of the driver subroutine.

As an example, the following position-independent code might appear in a program which wishes to read Blocks #100-103 backward from DECTape unit 3 into a buffer starting at address BUFFER.

```

MOV      PC,R0                ;GET TABLE ADDRESS
ADD      #TABLE+12-.,R0
MOV      PC,@R0               ;GET AND STORE...
ADD      #RETURN-.,@R0        ;...RETURN ADDRESS
MOV      #5404,-(R0)          ;SET READ REV. UNIT 3
MOV      #-1024,-(R0)         ;4 BLOCKS REQUIRED
MOV      PC,-(R0)             ;GET AND STORE
ADD      #BUFFER-.,@R0        ;...BUFFER ADDRESS
MOV      #103,-(R0)           ;START BLOCK
CMP      -(R0),-(R0)          ;SUBTRACT 4 FROM POINTER
MOV      R0,DT                ;SET DRIVER LINK
JSR      PC,DT.TFR            ;GO TO TRANSFER ROUTINE
WAIT:    .                     ;RETURNS HERE WHEN
        .                     ;...TRANSFER UNDER WAY
        .                     ;RETURNS HERE WHEN
        .                     ;...TRANSFER COMPLETE
TABLE:   .WORD 0               ;LIST AREA SET
        .WORD 0               ;...BY ABOVE SEQUENCE
        .WORD 0
        .WORD 0
        .WORD 0
        .WORD 0

```

3.1.4 User Registers

During its setup operations for the function requested, the driver assumes that Processor Registers 0-5 are available for its use. If their contents are of value, the program must save them before the driver is called.

While servicing intermediate interrupts, the driver may need to save or restore its registers. It expects to have two subroutines available for the purpose (provided by the Monitor). It accesses them via addresses in memory locations 44₈ and 46₈.

```

MOV      @#44,-(SP)           ;OR MOV @#46,-(SP)
JSR      R5,@(SP)+

```

The driver must also ensure that the start addresses are set into the correct locations (44_8 and 46_8).

At its final interrupt, the driver saves the contents of Registers \emptyset -5 before returning control to the calling program completion return.

3.1.5 Returns From Driver

As shown in the example in Section 5-3.1.3, the driver returns control to the calling program immediately after the JSR as soon as it has set the device in motion. The program can wait or carry out alternative operations until the driver signals completion by returning at the address specified (i.e., RETURN above). Prior to this, the program must not attempt to access the data being read in, nor refill a buffer being written out.

The program routine beginning at address RETURN varies according to the device being used. In general, the driver has given control to the routine for one of two reasons; either the function has been satisfactorily performed, or it cannot be carried out due to some hardware failure with which the driver is unable to cope, though the program may be able to do so. In the latter case, the driver uses the STATUS word in the program list to show the cause:

Bit 15 = 1 indicates that a device or timing failure occurred and the driver has not been able to overcome this, perhaps after several attempts.

Bit 14 = 1 shows that the end of the available data has been reached.

The driver places in $R\emptyset$ the contents of its first word as a pointer to the parameter table (see Section 5-3.1.2).

Possibly, the driver has transferred only some of the data requested. In this case, it shows in the RESERVED word of the program list a negative count of the words not transferred in addition to setting Bit 14 of the STATUS word. As mentioned in the note in Section 5-3.1.2, this applies only to non-bulk storage devices. The drivers for DECTape or disks¹ always endeavor to complete the full transfer, even beyond a parity failure, or they take more drastic action (see Section 5-3.1.6).

¹This includes RFl1 Disk; although this is basically word-oriented, it is assumed to be subdivided into 64-word blocks.

It is thus the responsibility of the program RETURN routine to check the information supplied by the driver in order to verify that the transfer was satisfactory and to handle the error situations appropriately.

In addition, the routine must contain a sequence to take care of the Processor Stack, Registers, etc. As noted earlier, the driver takes the completion return address after an interrupt and saves Registers 0-5 on the stack above the Interrupt Return Address and Status. The program routine should, therefore, contain some sequence to restore the processor to its state prior to such interrupt, e.g., using the same Restore subroutine illustrated earlier:

```

MOV      @#46,-(SP)      ;CALL REGISTER RESTORE
JSR      R5,@(SP)+
.
.
.
RTI      ;RETURN TO INTERRUPTED PROGRAM

```

3.1.6 Irrecoverable Errors

All hardware errors other than those noted in the previous section cannot normally be overcome by the program or by the driver on its behalf. Some of these could be due to an operator fault, such as not turning on a paper tape reader or not setting the correct unit number on a DECTape transport. Once the operator has rectified the problem, the program could continue. Other errors, however, require hardware repair or even software repair, e.g., if the program asks for Block 20000 on a device having a maximum of 10000. In general, all these errors result in the driver placing identifying information on the processor stack and calling IOT to produce a trap through location 34_g.

Under DOS/BATCH, the Monitor provides a routine to print a teleprinter message when this occurs. In a stand-alone environment, the program using the driver must itself contain the routine to handle the trap (unless the user wishes to modify the driver error exits before assembly). The handler format depends upon the program. The following format takes advantage of the information supplied by the driver:

	(SP):	Return Address	
2	(SP):	Return Status	Stored by IOT call
4	(SP):	Error No. Code	Generally unique to driver
5	(SP):	Error Type Code:	1 = Recoverable after Operator Action
			3 = No recovery
6	(SP):	Additional Information	Such as content of Driver, Control Register, Driver Identity, etc.

As a rule, the driver expects a return following the IOT call in the case of recoverable errors but contains no provision for an IOT call following a return from irrecoverable errors.

3.1.7 General Comment

The source language of each driver has been written for use with DOS/BATCH and contains some code which is not accepted by the Paper Tape Software PAL-11R, in particular, .TITLE, .GLOBL, and Conditional Assembly directives. Such statements should be deleted before the source is used. Similarly, an entry in the driver table gives the device name as .RAD5Ø 'DT' to obtain a specifically packed format used internally by DOS/BATCH. If the user wishes to keep the name, for instance, for identification purposes as discussed in Section 5-3.3, .RAD5Ø might easily be changed to .ASCII without detrimental effect, or it might be replaced with .WORD Ø.

3.2 DRIVERS ASSEMBLED SEPARATELY

Rather than assemble the driver with every program requiring its availability, the user may wish to hold it in binary form and attach it to the program only when loaded. The only requirement is that the start address of the driver should be known or be determinable by the program.

The example in Section 5-3.1.2 showed that the Interrupt Servicing routine can be accessed through an offset stored in the Driver Table. The same technique can be used to call the setup routines, as these also have corresponding offsets in the Table, as follows:

DRIVER+7	Open ¹
+10	Transfer
+11	Close ¹
+12	Special Functions ¹

The problem is the start address. There is the obvious solution of assembling the driver at a fixed location so that each program using it can immediately reference the location chosen. This ceases to be convenient when the program has to avoid the area occupied by the driver. A more general method is to relocate the driver as dictated by the program using it, thus taking advantage of the position-independent nature of the driver. The Absolute Loader, described in the Paper Tape Software Handbook (DEC-11-XPTSA-A-D), provides the capability to continue a load from the point at which it ended. Using this facility to enter the driver immediately following the program, the program might contain the following code to call the subroutine to perform the transfer illustrated in Section 5-3.1.3.

¹If the routine is not provided, these are Ø.

```

MOV      PC,R1          ;GET DRIVER START ADDRESS
ADD      #PRGEND-. ,R1
MOV      PC,R0          ;GET TABLE ADDRESS
ADD      #TABLE+12-. ,R0 ;AND SET UP AS SHOWN
          .              ;...IN SECTION 5-3.1.3
          .
          .
CMP      -(R0) ,-(R0)   ;FINAL POINTER ADJUSTMENT
MOV      R0,@R1         ;STORE IN DRIVER LINK
CLR      -(SP)          ;GET BYTE SHOWING...
MOVB    10(R1) ,@SP    ;...TRANSFER OFFSET
ADD      (SP)+,R1       ;COMPUTE ADDRESS
JSR     PC,@R1         ;GO TO DRIVER
          .
          .
          .
PGREND:  .END

```

This technique can be extended to cover situations in which several drivers are used by the same program, provided that it takes account of the size of each driver (known because of prior assembly) and that the drivers themselves are always loaded in the same order.

For example, to access the second driver, the above sequence would be modified to:

```

MOV      PC,R1          ;GET DRIVER 1 ADDRESS
ADD      #PRGEND-. ,R1
ADD      #DVR1SZ,R1     ;SET TO DRIVER 2
          .
          .
          .
DVR1SZ=n
PGREND:  .END

```

An alternative method may be to use the MACRO Assembler in association with the Linker program LINK, both of which are available through the DECUS Library. The start address of each driver is identified as a global. Any calling programs need merely include a corresponding .GLOBAL statement, e.g., .GLOBL DT.

3.3 DEVICE-INDEPENDENT USAGE

The drivers are assigned for use in a device-independent environment, i.e., one in which a calling program need not know in advance which driver has been associated with a table for a particular run. One application of this type might be to allow line printer output to be diverted to some other output medium because the line printer is not currently available. Another might be to provide a general program to analyze data samples although these on one occasion might come directly

from an Analog-to-Digital converter and on another be stored on a DECTape because the sampling rate was too high to allow immediate evaluation.

Programs of this type should be written to use all the facilities that any one device might offer, but not necessarily for each device. For instance, the program should ask for start-up procedures because it may sometime use a paper tape punch which provides them, even though it may normally use DECTape which does not. As noted in paragraph 5-2.2.1, the driver table contains an indication of its capabilities to handle this situation. The program can thus examine the appropriate item before calling the driver to perform some action. As an example, the code to request start-up procedures might be (assuming R0 already set to List Address):

```
MOV          #DVRADD,R1          ;GET DRIVER ADDRESS
TSTB        2(R1)              ;BIT 7 SHOWS
BPL         NOOPEN             ;...OPEN ROUTINE PRESENT
MOV         R0,@R1             ;STORE TABLE ADDRESS
CLRB        -(SP)              ;BUILD ADDRESS
MOVB        7(R1),@SP          ;...OF THIS ROUTINE
ADD         (SP)+,R1
JSR         PC,@R1             ;...AND GO TO IT
                                   ;FOLLOWED POSSIBLY BY
                                   ;WAIT AND COMPLETION
                                   ;PROCESSING
                                   ;RETURN TO COMMON OPERATION
```

NOOPEN:

Similarly, the indicators show whether the device is capable of performing input or output, or both; whether it can handle ASCII or binary data; whether it is a bulk storage device capable of supporting a directory structure or is a terminal-type device requiring special treatment. Other table entries show the device name as identification and the number of words the device might normally expect to transfer at a time (in 16-word units). All of the information can be readily examined by the calling program, thus enabling the use of a common call sequence for any I/O operation, as illustrated in the example on the following page.

```

MOV          #DVRADR,R5          ;SET DRIVER START
JSR          R5,IOSUB           ;CALL SET UP SUB
BR           WAIT               ;SKIP TABLE FOLLOWING ON RETURN
.WORD       1Ø                 ;TRANSFER REQUIRED
.WORD       1Ø3                ;BLOCK NO.
.WORD       BUFFER             ;BUFFER ADDRESS
.WORD       -256.              ;WORD COUNT
.WORD       4Ø4                ;READ FROM UNIT 1
.WORD       RETURN             ;EXIT ON COMPLETION
.WORD       Ø                  ;RESERVED
WAIT:
.
.
.
IOSUB: MOV     @SP,RØ           ;PICK UP DRIVER ADDR
MOV     R5,R1                 ;SET UP POINTER TO LIST
TST     (R1)+                  ;BUMP TO COLLECT CONTENT
.                               ;ROUTINE CHECKS ON DEVICE
.                               ;...CAPABILITY USING R1
.                               ;...TO ACCESS LIST AND
.                               ;...RØ THE DRIVER TABLE
.                               ;IF O.K...
MOV     @R1,R1                ;GET ROUTINE OFFSET
ADD     RØ,R1
CLR     -(SP)                  ;USE IT TO BUILD
MOVB   @R1,@SP                ;...ENTRY POINT
ADD     RØ,@SP
JSR     PC,@(SP)+             ;CALL DRIVER
RTS     R5                     ;EXIT TO CALLER

```

The calling program, or a subroutine of the type just illustrated, may take advantage of a feature mentioned earlier; the fact that when a driver is in use, its first word is non-zero. The driver itself does not clear this word except in special cases shown in the description for the driver concerned. If the program itself always ensures that the first word of the driver is set to zero between driver tasks, then this word forms a suitable driver-busy flag. Under DOS, the program parameter list is extended to allow additional words to provide linkage between lists as a queue in which the list indicated in the driver's first word is the first link.

The preceding paragraphs indicate possible ways of incorporating the available drivers into the type of environment for which they were designed. The user should carefully read the more detailed description of the driver structure in Chapter 5-4, and the individual driver specifications before determining the final form of his program.

A word of warning is appropriate here. Although most drivers set up an operation and then wait for an interrupt to produce a completion state, there are some cases in which the driver can finish its required task without an interrupt, e.g., "opening" a paper tape reader involves only a check on its status. Moreover, where "Special Functions" are concerned, the driver routine may determine from the code specified that the function is not applicable to its device, and therefore, have nothing to do. In such cases, the driver clears the intermediate return address from the processor stack and immediately takes the completion return. Special problems can arise, however, if the driver concerned is servicing several tasks, any of which can cause a queue for the driver's services under DOS/BATCH. To overcome these problems, the driver expects to be able to refer to flags outside the scope of the list so far described. This can mean that a program using such a driver may also need to extend the list range to cover such possibilities. Particular care should be exercised in such cases.

PART 5

CHAPTER 4

I/O DRIVERS WITHIN THE DOS/BATCH OPERATING SYSTEM

The principal function of an I/O driver is to satisfy a Monitor processing routine's requirement for the transfer of a block of data in a standard format to or from the device it services. This involves setting up the device hardware registers to cause the transfer and gaining control under the interrupt scheme of PDP-11, making allowance for peculiar device characters (e.g., conversion to or from ASCII if some special code is used).

The I/O driver must also include routines for handling device start-up or shut-down such as punching leader or trailer, and for making available to the user certain special features of the device, such as rewind of magtape.

4.1 DRIVER STRUCTURE

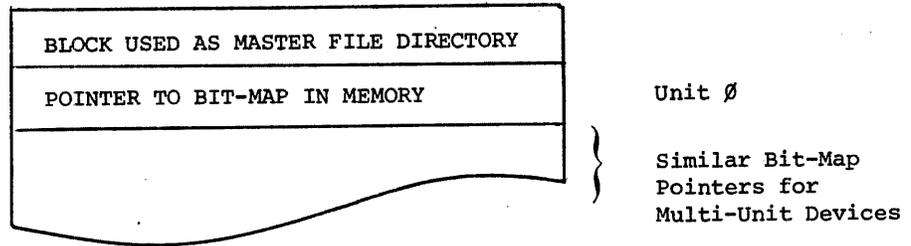
In order to provide a common interface to the Monitor, all drivers must begin with a table of identifying information as follows:

DVR:

BUSY FLAG (initially 0)	
FACILITY INDICATOR (expanded below)	
Offset to Interrupt Routine*	Standard Buffer Size in 16-word Units.
Offset to OPEN Routine*	Priority for Interrupt Service*
Offset to CLOSE Routine*	Offset to Transfer Routine*
Space	Offset to Special Functions*
DEVICE NAME (Packed Radix-50)	

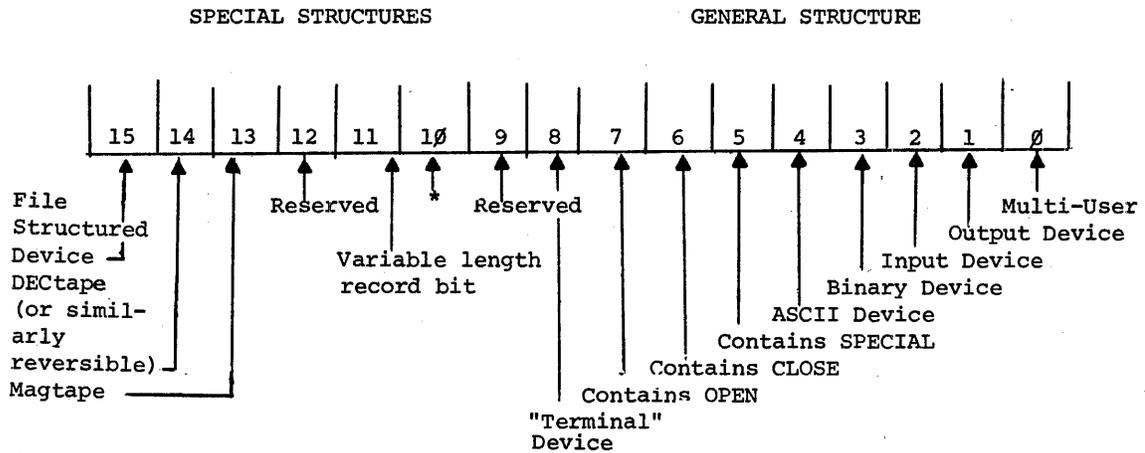
Offsets marked * enable the calling routine to indicate the routine required. The offsets are considered to be an unsigned value to be added to the start address of the driver. This may mean that with a 256-word maximum, the instruction referenced by the offset is a JMP or BR (routine).

The table should be extended as follows if the device is file-structured:



The driver routines that set up the transfer and control under the interrupt follow the table.

Bits in the Facility Indicator Word define the device for Monitor reference:



* Multi-unit System type devices (i.e., RK disk).

4.2 MONITOR CALLING

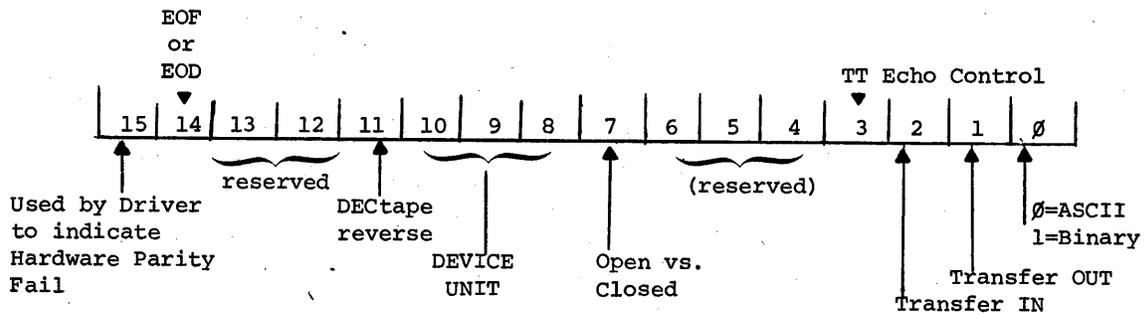
When a Monitor I/O processing routine needs to call the driver, it first sets up the parameters for the driver operation in relevant words of the appropriate DDB¹, as illustrated in the following table.

¹Dataset Data Block - a 16-word table which provides the main source of communication between the Monitor drivers and a particular set of data being processed on behalf of a using program.

DDB:

—	(User Call Address)
SPECIAL FUNCTION CODE	(User Line Address)
DEVICE BLOCK NUMBER	
MEMORY BLOCK ADDRESS	
WORD COUNT (2'S COMPLEMENT)	
TRANSFER FUNCTIONS (expanded below)	
COMPLETION RETURN ADDRESS	
(DRIVER WORD-COUNT RETURN) Set to Zero	

The relevant content of the Transfer Function word is as follows:



Provided that the Facility Indicator in the Driver Table described above shows that the driver is able to satisfy the request, according to the direction and mode and the service required, the Monitor routine places in Register 1 the relative Byte address of the entry in the Driver Table containing the offset to the routine to be used (e.g., for the Transfer routine, this would be 10). The Monitor routine then calls the Driver Queue Manager, using a JSR PC, S.CDB instruction.

The Driver Queue Manager refers to the Busy Flag (Word 0 of the driver table) to assure that the driver is free to accept the request. If the Busy Flag contains 0, the Queue Manager inserts the address of the DDB from Register 0 and jumps to the start of the routine in the driver using Register 1 content to evaluate the address required. If the driver is already occupied, the new request is placed in a queue linking the appropriate DDB's for datasets waiting for the driver's services. It is taken from the queue when the driver completes its current task. (This is done by a recall to the Queue Manager from the routine just serviced, using JSR PC,S.CDQ).

On entry to the Driver Routine, therefore, the address following the Monitor routine call remains as the "top" element of the processor stack. It can be used by the driver in order to make an immediate return to the Monitor (having initiated the function requested), using RTS PC. It should also be noted that the Monitor routine saves register contents if it needs them after the device action. The driver may thus freely use the registers for its own operations.

When the driver has completely satisfied the Monitor request, it should return control to the Monitor using the address set into the DDB. On such return, Register 0 must be set to contain the address of the DDB just serviced and since the return will normally follow an interrupt, Registers 0-5 at the interrupt must be stored on top of the stack.

4.3 DRIVER ROUTINES

4.3.1 TRANSFER

The sole purpose of the TRANSFER routine is to set the device in motion. The information needed to load the hardware registers is available in the DDB, whose address is contained in the first word of the driver. Conversion of the stored values is the function of the routine. It must also enable the interrupt; however, it need not set the interrupt vectors as these are preset by the Monitor when the driver is brought into core. After the TRANSFER routine has activated the device, the routine returns to the calling processor by an RTS PC instruction.

4.3.2 Interrupt Servicing

The form of this routine depends upon the nature of the device. In most drivers it falls into two parts, one for handling the termination of a normal transfer and the other to deal with reported error conditions.

For devices which are word or byte-oriented, the routine must provide for individual word or byte transfers, with appropriate treatment of certain characters (e.g., TAB or Null) and for their conversion between ASCII or binary and any special device coding scheme, until either the word count in the DDB is satisfied or an error prevents this. On these devices, the most likely case for such error is the detection of the end of the physical medium; the treatment for the error varies according to whether the device is providing input or accepting output. The calling program usually needs to take action in the former case and the driver should merely indicate the error by returning the unexpired portion of the word count in DDB Word 7 on exit to the Monitor. Output End of Data requires operator

action. To obtain this, the driver should call the Error Diagnostic Print routine within the Monitor by:

```
MOV          DEVNAM,-(SP)      ;SHOW DEVICE NAME
MOV          #402,-(SP)      ;SHOW DEVICE NOT READY
IOT                                     ;CALL ERROR DIAGNOSTIC PRINT ROUTINE
```

On the assumption that the operator will reset the device for further output and request continuation, the driver must follow the above sequence with a Branch or Jump to resume the transfer.

Normal transfer handling on blocked devices (or those like RFl1 Disk which are treated as such) is simpler since the hardware takes care of individual words or bytes and the interrupt only occurs on completion.

Errors that indicate definite hardware malfunctions must generate diagnostic messages to the Operator, The only recourse is to start the program over, after the malfunction has been corrected.

There are some errors which the driver can attempt to overcome by restarting the transfer. Device parity failure on input is a common example. If one or more retries are unsuccessful, the driver should normally allow programmed recovery and indicate the error by Bit 15 of DDB word 5. Nevertheless, because the program may try to process the data despite the error, the driver should attempt to transfer the whole block requested if this has not already been effected. The remaining forms of errors must be processed according to the type of recovery deemed desirable.

Whether the routine uses processor registers for its operation depends on considerations of the core space saved against the time taken to save the user's contents. However, on completion (or error return to the Monitor), the calling routine expects the top of the stack to contain the contents of Registers 0-5 and Register 0 to be set to the address of the DDB just serviced. The driver must, therefore, provide for this.

4.3.3 OPEN

This routine need be provided only for those devices that require some hardware initialization. It should not normally appear in drivers for devices used in a file oriented manner. The presence of the routine must be indicated by Bit 7 in the driver table Facility Indicator.

The OPEN routine may vary according to the transfer direction of the device. For output devices, the probable action required is the transmission of appropriate data, e.g., CR/LF at a keyboard terminal, form-feed at a printer, or null characters as punched leader code, and for this a return interrupt is expected. The OPEN routine should then be somewhat similar to the TRANSFER routine in that it sets the device going and makes an interim return via RTS PC, waiting until completion of the whole transmission before taking the final return address in the DDB.

An input OPEN may consist of just a check on the readiness of the device to provide data when requested. In this case, the desired function can be effected without any interrupt wait. The routine should, therefore, take the completion return immediately. Nevertheless, it must ensure that the saved PC value on top of the stack from the call to S.CDB is appropriately removed before exit. In the case of drivers which can service only one dataset at a time (i.e., Bit 0 of their Facility Pattern word is set to 0) and can never be queued, a TST (SP)+ instruction can effect this. However, a multi-user driver must allow for the possibility that it may be recalled to perform some new task waiting in a queue. This condition exists if the byte at DDB-3 is non-zero. In this case, the driver must simulate the interrupt expected by the completion process. This is accomplished by inserting a PS word on the stack above the return address supplied by the JSR of the Open request. A possible sequence for the interrupt simulation is illustrated below.

```

MOV          DRIVER,R0          ;PICK UP DDB ADDRESS
MOV          (SP)+,R5          ;SAVE INTERIM RETURN
TSTB        -3(R0)            ;COME FROM QUEUE?
BEQ         EXIT
MOV         @#177776,-(SP)      ;IF SO, STORE STATUS
MOV         R5,-(SP)           ;...& RETURN
SUB         #14,SP             ;DUMMY SAVE REGS
EXIT:       JMP         @10(R0)

```

4.3.4 CLOSE

The CLOSE routine is like the OPEN routine, in that it should provide for the possibility of some form of hardware shut-down, such as the punching of trailer code and that it is not necessary for file-structured devices. Moreover, it is likely to be a requirement for output devices only. If it is provided, Driver Table Facility Indicator (Bit 6) must be set.

Again, the probable form is initialization of the hardware action required, with immediate return via RTS PC and eventual completion return via the DDB-stored address.

4.3.5 SPECIAL

This routine may be included if either the device itself contains the hardware to perform some special function or there is a need for software simulation of each hardware on other devices, e.g., tape rewind; it should not be provided otherwise. Its presence must be indicated by Bit 5 of the Facility Indicator.

The function itself is stored by the Monitor as a code in the DDB. When called, the driver routine must determine whether such function is appropriate in its case. If not, the completion return should be taken immediately with prior stack clearance, as discussed under OPEN. For a recognized function, the necessary routine must be provided. Its exit method depends upon the necessity for an interrupt wait.

4.4 DRIVERS FOR TERMINALS

The rate of input from terminal devices normally reflects the typing skill of the operator. For both input and output, the amount of data to be transferred on each occasion may be a varying length, i.e., a line rather than a block of standard size. Furthermore, echoing input may conflict with interrupting output. As a result, drivers for such devices demand special treatment.

Normal output operation, i.e., .WRITE by the program, is handled by the Monitor Processor. On recognizing that the device being used is a terminal, as shown by Bit 8 of the facility indicator, this routine always causes a driver transfer at the end of the user line, even though the internal buffer has not been filled. The driver, however, is given the whole of a standard buffer, padded as necessary with nulls. Provided the driver can ignore these, the effect is the suppression of trailing nulls.

Input control remains the driver's responsibility since overcoming the rate problem requires circular buffering within the driver. This circular buffering feature allows the user type-ahead facilities. A subsequent input request may then be satisfied by data already in core. If the data is sufficient to fill the Monitor buffer, the driver awaits the next request before further transfer. If this is insufficient, the driver should operate as any other device and use subsequent interrupts to satisfy the Monitor's requests. Since the driver must stop any transfer at the end of a line in normal operation, in order to allow the Monitor to continue, the driver must simulate the filling of the buffer by null padding. If the user requests .TRAN's which are not line oriented, the buffer size varies from the standard and the driver assumes the program requires a complete buffer before return.

PART 5
CHAPTER 5
SAMPLE LINE PRINTER DRIVER LISTING

The following is a sample listing of a DOS/BATCH Device Driver. The actual driver is the LP11 Line Printer Driver (for device name LP:).

```

1      ;      DIGITAL EQUIPMENT CORPORATION, MAYNARD, MASSACHUSETTS 01
2      ;      COPYRIGHT, 1973
3      ;
4      ;      DIGITAL EQUIPMENT CORPORATION ASSUMES NO RESPONSIBILITY
5      ;      FOR THE USE OR RELIABILITY OF ITS SOFTWARE ON EQUIPMENT
6      ;      WHICH IS NOT SUPPLIED BY DIGITAL EQUIPMENT CORPORATION.
7      ;
8      ;      VERSION NUMBER: V13.01
9      ;
10     ;      DATED:           MARCH 5, 1973
11     ;
12     ;      DEVICE DRIVER FOR THE LP11/LS11 LINE PRINTER(S)
13     ;
14     ;      DRIVER PARAMETERIZATION SYMBOLS
15     ;      LP11, LS11, WIDTH, SPACES, SPREAD
16     ;
17
18     ;      .IF      NDF,LPTYP           ;LPTYP=0 if LP11
19     LPTYP      ■      0                 ;LPTYP=1 if LS11
20     ;      .ENDC           ;DEFAULT IS 0
21     ;      .IF      EQ,LPTYP
22     ;      .TITLE     DV.LP0
23     000001 LP11      ■      1
24     000012 SKIP2    ■      12
25     ;      .IFF
26     ;      .IF      EQ,<LPTYP-1>
27     ;      .TITLE     DV.LP:
28     LS11          ■      1
29     SPREAD        ■      1
30     SKIP2         ■      13
31     ;      .IFF
32     ;      .MERROR  ;UNSUPPORTED LINE PRINTER
33     ;      .ENDC
34     ;      .ENDC
35
36     ;      .IFNDF  WIDTH
37     WIDTH        ■      80.           ; 80. COLUMN PRINTER DEFAULT
38     ;      .ENDC
39
40     000000 R0      ■      X0
41     000001 R1      ■      X1
42     000002 R2      ■      X2
43     000003 R3      ■      X3
44     000004 R4      ■      X4
45     000005 R5      ■      X5
46     000006 SP      ■      X6
47     000007 PC      ■      X7
48
49     000402 A002    ■      402         ; DIAGNOSTIC MESSAGE CODE
50
51     000044 S.RSAV  ■      44         ; REGISTER SAVE (MONITOR SUPPORT

```

```

1
2
3      .GLOBL LP
4      .IDENT /13,01/
5
6      /      DOS-11 DEVICE DRIVER'S STANDARDIZED INTERFACE
7 000000 000000 LP:  .WORD      0      ; USER'S DOB POINTER
8                    .IFDF      LS11&SPREAD
9                    .BYTE      362      ; FACILITIES INDICATOR
10                   .ENOC
11                   .IFNDF      LS11&SPREAD
12 000002      322    .BYTE      322      ; FACILITIES INDICATOR
13                   .ENOC
14 000003      000    .BYTE      0      ; SPECIAL STRUCTURES, NONE
15 000004      003    .BYTE      <<WIDTH+37>/40> ; STANDARD BUFFER SIZE
16 000005      110    .BYTE      LP.INT-LP   ; INTERRUPT ENTRY OFFSET
17 000006      200    .BYTE      200      ; INTERRUPT PRIORITY 4
18 000007      036    .BYTE      LP.OPN-LP   ; OPEN ENTRY OFFSET
19 000010      060    .BYTE      LP.TRN-LP   ; TRAN ENTRY OFFSET
20 000011      036    .BYTE      LP.CLS-LP   ; CLOSE ENTRY OFFSET
21                   .IF      EQ,LPTYP
22 000012      000    .BYTE      0
23                   .IFF
24                   .BYTE      LP.SPC-LP   ; SPECIAL ENTRY OFFSET
25                   .ENOC
26 000013      000    .BYTE      0      ; SPARE
27 000014 046600 LP.NAM: .RAD50 /LP/ ; DEVICE DRIVER'S NAME
28
29      000200 LP.TRP  =      200      ; INTERRUPT VECTOR'S ADDRESS
30      177514 LP.CSR  =      177514   ; COMMAND/STATUS REGISTER
31      177516 LP.DBR  =      177516   ; DATA BUFFER REGISTER
32
33 00016 000120 LP.SIZ: .WORD      WIDTH   ; THIS WORD IS SET BY THE INITIA
34 00020 000133 UPPCAS: .WORD      133    ; SET TO THE HIGHER PRINT LIMIT
35 00022 000000 OVPRNT: .WORD      0      ; SET TO TRUE WHEN OVER PRINTING
36 00024 000000 LP.LIN: .WORD      0      ; ALREADY SENT (CHARACTERS)
37 00026 000000 LP.BKS: .WORD      0      ; BLANK POSITIONS COUNTER
38 00030 000000 LP.TCT: .WORD      0      ; TRANSFER CHARACTER COUNT
39 00032 000000 LP.BAD: .WORD      0      ; BUFFER ADDRESS POINTER
40
41 00034      LP.TOP:  ; COMMAND DEVICE TO TOP-OF-FORM
42                   .IFDF      LS11
43                   .BYTE      21      ; COMMAND DEVICE TO ON-LINE
44                   .ENOC
45 00034      015    .BYTE      15,14    ; CR, FF
46      00035      014
47                   .EVEN
48                   .IFDF      LS11&SPREAD
49 LP.FLG:  .WORD      0      ; CHARACTER ELONGATION FLAG
50                   .ENOC
51      000040 LP.LOW  =      40      ; PRINTABILITY, LOWER LIMIT

```

```

1
2          ) OPEN PROCESSOR
3 000036   LP.OPNI
4          ) CLOSE PROCESSOR
5 000036   LP.CLS:
6 000036 004767 JSR    PC,LP.STS      ; SIMULATE INTERRUPT
          000454
7 000042 062701 ADD    #LP.TOF-.,R1      ; R1 = PC (BY LP.STS)
          177772
8 000046 010167 MOV    R1,LP.BAD        ; INTERNAL BUFFER'S ADDRESS
          177760
9          .IFDF    LS11
10         MOV     #-3,LP.TCT      ; INITIALIZE TRANSFER COUNT
11         .ENDC
12         .IFNDF   LS11
13 000052 010267 MOV    R2,LP.TCT        ; R2 = -2 (BY LP.STS)
          177752
14         .ENDC
15         .IFDF    LS11&SPREAD
16         CLR     LP.FLG          ; INITIALIZE ELONGATION FLAG
17         .ENDC
18 000056 000414 BR     LP.INT           ; DISPATCH INTERNAL BUFFER
19
20         .IFDF    LS11&SPREAD
21
22         ) SPECIAL PROCESSOR
23         LP.SPC:
24         MOV     2(R0),R1        ; R1 = FUNCTION BLOCK'S ADDRESS
25         CMPB   #1,(R1)         ; LINE ELONGATION FUNCTION ?
26         BNE    LP.S00         ; NO, IGNORE
27         MOV     2(R1),LP.FLG    ; ENABLE/DISABLE ELONGATION
28         LP.S00: JMP     @14(R0)  ; EXIT VIA COMPLETION RETURN
29         .ENDC
30
31         ) TRAN PROCESSOR
32         LP.TRN:
33 000060 004767 JSR    PC,LP.STS      ; SIMULATE AN INTERRUPT
          000432
34 000064 016700 MOV    LP,R0           ; R0 = USER'S DDB ADDRESS
          177710
35 000070 016067 MOV    6(R0),LP.BAD    ; RETAIN BUFFER'S ADDRESS
          000006
          177734
36 000076 016067 MOV    10(R0),LP.TCT   ; RETAIN DDB'S BYTE COUNT
          000010
          177724
37 00104 006367 ASL    LP.TCT
          177720

```

```

1
2
3
4 000110 LP.INT: BIC #100,LP.CSR ; DISABLE INTERRUPT
   000110 042737
   000110 000100
   000110 177514
5 000116 BGE LP.I0 ; SEGREGATE ERRORS
6 000120 JMP LP.ERR ; ENTER ERROR PROCESSOR
   000120 000167
   000120 000354
7 000124 LP.I01: TST LP.TCT ; ANY CHARACTERS REMAINING ?
   000124 005767
   000124 177700
8 000130 BEQ LP.DONE ; NO, LINE COMPLETED
9 000132 MOV R4,-(SP) ; SAVE REGISTERS
10 00134 MOV R3,-(SP) ;
11 00136 MOV R2,-(SP) ;
12 00140 MOV R1,-(SP) ;
13 00142 MOV LP.BKS,R4 ; R4 = BLANK COUNTER
   00142 016704
   00142 177660
14 00146 MOV LP.LIN,R3 ; R3 = PRINT POSITION
   00146 016703
   00146 177652
15 00152 MOV LP.BAD,R2 ; R2 = BUFFER POINTER (ADDRESS)
   00152 016702
   00152 177654
16 00156 LP.I00: MOVB (R2)+,R1 ; *** ACCESS CHARACTER ***
17 00160 BEQ LP.DNP ; NULL (0) IGNORED
18 00162 LP.I01: CMPB R1,LP.LOW ; PRINTABILITY CHECK
   00162 120127
   00162 000040
19 00166 BLT LP.I10 ; EXCEEDS LOWER LIMIT
20 .IFDF SPACES
21 BGT LP.I02 ; VALID CHARACTER, SO FAR
22 INC R4 ; BLANK (40) ISOLATED, COUNT
23 BR LP.TNT ; ACCESS NEXT CHARACTER
24 .ENDC
25 00170 LP.I02: CMPB R1,UPPCAS ; PRINTABILITY CHECK
   00170 120167
   00170 177624
26 00174 BGE LP.I18 ; EXCEEDS UPPER LIMIT
27 00176 LP.I03: INC R3 ; PRINTER'S WIDTH EXCEEDED ?
28 00200 BGT LP.DNP ; YES, DO NOT PRINT
29 00202 LP.I04: BIT #100200,LP.CSR ; ACCESS ERROR/READY STATUS
   00202 032737
   00202 100200
   00202 177514
30 00210 BMI LP.I22 ; ERROR INDICATION
31 00212 BEQ LP.I20 ; NOT READY INDICATION
32 00214 DEC R4 ; DECREMENT BLANK COUNTER
33 00216 BMI LP.I05 ; NOT PROCESSING BLANKS
34 00220 MOVB #40,LP.DBR ; BLANK/HTAB EXPANSION PERFORMED
   00220 112737
   00220 000040
   00220 177516
35 00226 BR LP.I03 ; CONTINUE PENDING COMPLETION
36 00230 LP.I05: MOVB R1,LP.DBR ; *** PRINT CHARACTER ***
   00230 110137
   00230 177516
37 00234 LP.I06: CLW R4 ; INSURE NO BLANKS PENDING
38 00236 LP.DNP:
39 00236 LP.TRT: INC LP.TCT ; INCREMENT BUFFER'S CHARACTER
   00236 005267
   00236 177566
40
41 00242 BNE LP.I00 ; COUNTER, ANY MORE ?
   00242 001345

```

```

1
2
3
4 000244 105737          TSTB      #LP.CSR      ; DEVICE BUSY ?
      177514
5 000250 100103          BPL        LP.I21      ; YES
6 000252 004567 LP.ONE: JSR      R5,LP.SET    ; RESTORE TEMPORARIES
      000250
7 000256 013746 LP.DUN: MOV      #S,RSV,-(SP) ; SAVE REGISTERS
      000044
8 000262 004536          JSR        R5,#(SP)+  ;
9 000264 016700          MOV        LP,R0      ; R0 = USER'S ODB ADDRESS
      177510
10 00270 000170          JMP        #14(R0)    ; EXIT VIA COMPLETION RETURN
      000014

11
12 00274 120127 LP.I10: CMPB     R1,#11      ; HORIZONTAL TAB (11) ?
      000011
13 00300 001010          BNE        LP.I13     ; NO
14
15
16
17 00302 016746          MOV        LP.SIZ,-(SP) ; PRINTER'S MAX WIDTH
      177510

18
19          .IFDF      LS11&SPREAD
20          TST        LP.PLG      ; ELONGATION ?
21          BEQ        LP.I11     ; NO
22          ASR        (SP)       ; (PRINTER'S WIDTH)/2
23          .ENDC
24 00306 060316 LP.I11: ADD      R3,(SP)      ; - PRINT POSITION
25          .IFDF      LS11&SPREAD
26          BGE        LP.I12     ; NOT EXCEEDED PRINTER'S WIDTH
27          CLR        LP.TCT     ; ELONGATION LINE TERMINATION
28          BR         LP.ONE     ; EXIT
29          .ENDC
30 00310 060416 LP.I12: ADD      R4,(SP)      ; + BLANK COUNTER
31 00312 052716          BIS        #177770,(SP) ; (MODULO 8) - 8
      177770
32 00316 102604          SUB        (SP)+,R4    ; + BLANK COUNTER
33 00320 000746          BR         LP.TRT     ; = BLANK COUNTER
      ; ACCESS NEXT CHARACTER
34

```

```

1 000322 120127 LP.I13: CMPB R1,#15 ; CARRIAGE-RETURN (15) ?
   000015
2 000326 003010 BGT LP.I14 ; NO, ABOVE
3 000330 001014 BNE LP.I15 ; NO, BELOW
4 000332 005767 TST OVPRNT ; PRINT THE CARRIAGE-RETURN ?
   177464
5 000336 001021 BNE LP.I16 ; YES
6 000340 016703 MOV LP.SIZ,R3 ; R3 = -( PRINTER'S WIDTH )
   177452
7 000344 005403 NEG R3 ;
8 .IFDF LS11&SPREAD
9 TST LP.FLG ; ELONGATION ENABLED ?
10 BEQ LP.IXX ; NO
11 ASR R3 ; HALVE PRINTER'S WIDTH
12 MOV R3,LP.FLG ; RE-INITIALIZE THE FLAG
13 .ENDC
14 00346 LP.IXX: BR LP.I06 ; SUPPRESS CARRIAGE-RETURN
15 00346 000732 LP.I14: .IFDF LS11&SPREAD
16 00350 TST LP.FLG
17 BEQ LP.IYY
18 CMPB R1,#16
19 BEQ LP.I04
20 LP.IYY:
21 .ENDC
22 CMPB R1,#22
23 00350 120127 BNE LP.I17 ; NO
   000022 MOV #SKIP2,R1 ; SUBSTITUTE APPROPRIATE CHAR
24 00354 001016 BNE LP.I17
25 00356 012701 MOV #SKIP2,R1
   000012
26 00362 120127 LP.I15: CMPB R1,#12 ; LINEFEED (12) ?
   000012
27 00366 002411 BLT LP.I17 ; NO, BELOW
28 00370 001404 BEQ LP.I16 ; YES
29 00372 120127 CMPB R1,#13 ; VERTICAL TAB (13) ?
   000013
30 00376 001717 BEQ LP.DNP ; YES, IGNORE IT !
31 00400 000400 BR LP.I16 ; NO, FURMFEEED (14) ISOLATED
32 00402 LP.I16: MOV LP.SIZ,R3 ; R3 = -( PRINTER'S WIDTH )
33 00402 016703
   177410
34 00406 005403 NEG R3 ;
35 .IFDF LS11&SPREAD
36 TST LP.FLG ; ELONGATION ENABLED ?
37 BEQ LP.I04 ; NO, PRINT CHARACTER
38 ASR R3 ; HALVE PRINTER'S WIDTH
39 MOV R3,LP.FLG ; RE-INITIALIZE THE FLAG
40 .ENDC
41 00410 000674 BR LP.I04 ; PRINT THE CHARACTER

```

```

1 000412 012701 LP.I17: MOV      #40,R1      ; UNPRINTABLE, BLANK SUBSTITUTIO
      000040
2 000416 000667          BR      LP.I03      ; PRINT A BLANK
3 000420 120127 LP.I18: CMPB    R1,#172      ; LOWER CASE ALPHABET ?
      000172
4 000424 003003          BGT      LP.I19      ; EXCEEDS
5
6          ;
7          ;
8 000426 042701          BIC      #40,R1      ; CONVERSION PERFORMED
      000040
9 000432 000661          BR      LP.I03      ; PRINT CHARACTER
10 00434 120127 LP.I19: CMPB    R1,#177      ; RUBOUT (177) ?
      000177
11 00440 001676          BEQ      LP.ONP      ; YES, IGNORED
12 00442 126727          CMPB    UPPCAS,#137 ; UPPER CASE PERMITTED ?
      177352
      000137
13 00450 101252          BHI      LP.I03      ; YES, PRINT CHARACTER
14 00452 000757          BR      LP.I17      ; UNPRINTABLE, BLANK SUBSTITUTIO
15
16 00454 005303 LP.I20: DEC      R3          ; BACKUP PRINT POSITION
17 00456 005302          DEC      R2          ; BACKUP BUFFER POSITION
18 00460 004567 LP.I21: JSR      R5,LP.SET    ; RESTORE TEMPORARIES
      000052
19 00464 052737          BIS      #100,#LP.CSR ; ENABLE INTERRUPT
      000100
      177514
20 00472 000002          RTI          ; EXIT FROM INTERRUPT
21
22 00474 005303 LP.I22: DEC      R3          ; BACKUP PRINT POSITION
23 00476 005302          DEC      R2          ; BACKUP BUFFER POSITION
24 00500 016746 LP.ERR: MOV      LP.NAM,-(SP) ; DEVICE DRIVER'S MNEMONIC
      177310
25 00504 012746          MOV      #A002,-(SP) ; MESSAGE CODE
      000402
26 00510 000004          IOT          ;
27 00512 000167          JMP      LP.INT      ; TRY AGAIN
      177372

```

```

1
2
3
4 000516 012601 LP.STS: MOV (SP)+,R1 ; RETURN PC
5 000520 011646 MOV (SP),-(SP) ; OLD PC
6 000522 005002 CLR R2 ; ADDRESS PS (-2)
7 000524 014266 MOV =(R2),2(SP) ; OLD STATUS
000002
8 000530 013712 MOV @#LP.TRP+2,(R2) ; NEW STATUS
000202
9 000534 010107 MOV R1,PC ; RETURN
10
11 00536 010467 LP.SET: MOV R4,LP.BKS ; RESTORE TEMPORARIES
177264
12 00542 010367 MOV R3,LP.LIN ;
177256
13 00546 010267 MOV R2,LP.BAD ;
177260
14 00552 016604 MOV 10(SP),R4 ; RESTORE REGISTER 4
000010
15 00556 012666 MOV (SP)+,6(SP) ; RETAIN RETURN ADDRESS
000006
16 00562 012601 MOV (SP)+,R1 ; RESTORE REGISTERS
17 00564 012602 MOV (SP)+,R2 ;
18 00566 012603 MOV (SP)+,R3 ;
19 00570 000205 RTS R5 ; EXIT SUBROUTINE
20 000001 .END

```

A002	=	000402	BFSHFT	=	010000	BLANK	=	000040
BSLSH	=	000134	CR	=	000015	DDBADR	=	000006
DDBLCK	=	000004	DDBCNT	=	000010	DDBCRT	=	000014
DDBDVA	=	177776	DDBSTS	=	000012	DDBULA	=	000002
DDBUNT	=	000013	DITBFS	=	000004	DITBMP	=	000016
DITBSY	=	000000	DITFAC	=	000002	DITINT	=	000005
DITMFD	=	000014	DITNAM	=	000012	DITOPN	=	000007
DITPRI	=	000006	DITSPF	=	000011	DITXFR	=	000010
EMTINT	=	000006	EMTRET	=	000014	EMTVAL	=	104000
EMTVEC	=	000030	FTCOM	=	000001	FTDOS	=	000001
FTMUO	=	000001	FTRPG	=	000001	FTRP03	=	000001
F001	=	001401	F002	=	001402	F003	=	001403
F005	=	001405	F007	=	001407	F011	=	001411
F012	=	001412	F017	=	001417	F024	=	001424
F042	=	001442	F050	=	001450	F052	=	001452
KSBSIZ	=	000400	LF	=	000012	LP	=	000000KG
LPTYP	=	000000	LP.BAD	=	000032R	LP.BKS	=	000026R
LP.CLS	=	000036R	LP.CSR	=	177514	LP.DBR	=	177516
LP.DNE	=	000252R	LP.ONP	=	000236R	LP.DON	=	000256R
LP.ERR	=	000500R	LP.INT	=	000110R	LP.IXX	=	000346R
LP.I0	=	000124R	LP.I00	=	000156R	LP.I01	=	000162R
LP.I02	=	000170R	LP.I03	=	000176R	LP.I04	=	000202R
LP.I05	=	000230R	LP.I06	=	000234R	LP.I10	=	000274R
LP.I11	=	000306R	LP.I12	=	000310R	LP.I13	=	000322R
LP.I14	=	000350R	LP.I15	=	000362R	LP.I16	=	000402R
LP.I17	=	000412R	LP.I18	=	000420R	LP.I19	=	000434R
LP.I20	=	000454R	LP.I21	=	000460R	LP.I22	=	000474R
LP.LIN	=	000024R	LP.LOW	=	000040	LP.NAM	=	000014R
LP.OPN	=	000036R	LP.SET	=	000536R	LP.SIZ	=	000016R
LP.STS	=	000516R	LP.TCT	=	000030R	LP.TOF	=	000034R
LP.TRN	=	000000R	LP.TRP	=	000200	LP.TRT	=	000236R
LP11	=	000001	MSBSIZ	=	001000	OVL006	=	000002
OVL016	=	000006	OVRPT	=	000022R	OVL061	=	000012
OV2061	=	000012	PATSIZ	=	000030	PRI4	=	000200
PRI7	=	000340	PS	=	177776	PSPRIO	=	177437
RPBIT	=	004000	RPU2SZ	=	000020	RUBOUT	=	000177
SKIP2	=	000012	SMBSIZ	=	000040	STMASK	=	107070
S.RSAV	=	000044	TABCH	=	000011	UPPCAS	=	000020R
V.CDB	=	000050	V.CDQ	=	000052	V.GTB	=	000054
V.RLB	=	000056	V.RRES	=	000046	V.RSAV	=	000044
V.SVT	=	000040	V.XIT	=	000042	WIDTH	=	000120
XFTCOM	=	000000	XFTDOS	=	000000	XFTMUO	=	000000
XFTRPG	=	000000	SSPASS	=	000000			
.ABS.	=	000000						
		000572						
		001						

ERRORS DETECTED: 0
 FREE CORE: 15039. WORDS
 ,LP:LP0/CRF<SY:PRAMTR/NL,SYSMAC,FEATSW,DK1:LP0(200,200)/LI/LI:ME

CROSS REFERENCE TABLE S-1

A002	1- 83#	4- 49#	10- 25				
BFSHFT	1-102#						
BLANK	1-123#						
BSLSH	1-124#						
CR	1-120#						
DOBADR	1- 54#						
DDBBLK	1- 53#						
DDBCNT	1- 55#						
DDBCRT	1- 58#						
DDBDVA	1- 51#	1-106#					
DDBSTS	1- 56#						
DDBULA	1- 52#	1-105#					
DDBUNT	1- 57#						
DITBFS	1- 36#						
DITBMP	1- 45#						
DITBSY	1- 34#						
DITFAC	1- 35#						
DITINT	1- 38#						
DITMFD	1- 44#						
DITNAM	1- 43#						
DITOPN	1- 40#						
DITPRI	1- 39#						
DITSPF	1- 42#						
DITXFR	1- 41#						
EMTINT	1- 63#						
EMTRET	1- 62#						
EMTVAL	1- 61#						
EMTVEC	1- 64#						
FTCOM	3- 6#						
FTUOS	3- 12#						
FTMUO	3- 8#						
FTRPG	3- 10#						
FTRP03	3- 16#						
F001	1- 81#						
F002	1- 80#						
F003	1- 85#						
F005	1- 82#						
F007	1- 88#						
F011	1- 86#						
F012	1- 87#						
F017	1- 89#						
F024	1- 91#						
F042	1- 92#						
F050	1- 84#						
F052	1- 90#						
KSBSIZ	2-160#						
LF	1-121#						
LP	5- 2#	5- 7#	5- 16	5- 18	5- 19	5- 20	6- 34
	8- 9						
LPTYP	4- 18	4- 21	5- 21				
LP.BAD	5- 39#	6- 8#	6- 35#	7- 15	11- 13#		
LP.BKS	5- 37#	7- 13	11- 11#				
LP.CLS	5- 20	6- 5#					
LP.CSR	5- 30#	7- 4#	7- 29	8- 4	10- 19#		
LP.DBR	5- 31#	7- 34#	7- 36#				
LP.DNE	8- 6#						
LP.DNP	7- 17	7- 28	7- 38#	9- 30	10- 11		
LP.DON	7- 8	8- 7#					

CROSS REFERENCE TABLE S-2

LP.ERR	7- 6	10- 24#						
LP.INT	5- 16	6- 18	7- 3#	10- 27				
LP.IXX	9- 14#							
LP.I0	7- 5	7- 7#						
LP.I00	7- 16#	7- 41						
LP.I01	7- 18#							
LP.I02	7- 25#							
LP.I03	7- 27#	7- 35	10- 2	10- 9	10- 13			
LP.I04	7- 29#	9- 41						
LP.I05	7- 33	7- 36#						
LP.I06	7- 37#	9- 15						
LP.I10	7- 19	8- 12#						
LP.I11	8- 23#							
LP.I12	8- 29#							
LP.I13	8- 13	9- 1#						
LP.I14	9- 2	9- 16#						
LP.I15	9- 3	9- 26#						
LP.I16	9- 5	9- 28	9- 31	9- 32#				
LP.I17	9- 24	9- 27	10- 1#	10- 14				
LP.I18	7- 26	10- 3#						
LP.I19	10- 4	10- 10#						
LP.I20	7- 31	10- 16#						
LP.I21	8- 5	10- 18#						
LP.I22	7- 30	10- 22#						
LP.LIN	5- 36#	7- 14	11- 12#					
LP.LOW	5- 51#	7- 18						
LP.NAM	5- 27#	10- 24						
LP.OPN	5- 18	6- 3#						
LP.SET	8- 6	10- 18	11- 11#					
LP.SIZ	5- 33#	8- 17	9- 6	9- 33				
LP.STS	6- 6	6- 33	11- 4#					
LP.TCT	5- 38#	6- 13#	6- 36#	6- 37#	7- 7	7- 39#		
LP.TUF	5- 41#	6- 7						
LP.TRN	5- 19	6- 32#						
LP.TRP	5- 29#	11- 8						
LP.TRT	7- 39#	8- 33						
LP11	4- 23#							
LS11	5- 8	5- 11	5- 42	5- 47	6- 9	6- 12	6- 15	
	6- 20	8- 18	8- 24	9- 8	9- 16	9- 35		
MSBSIZ	2-159#							
OVL006	1-108#							
OVL016	1-107#							
OVRPNT	5- 35#	9- 4						
OV1061	1-109#							
OV2061	1-110#							
PATSIZ	1-116#							
PC	1- 14#	4- 47#	6- 6#	6- 33#	11- 9#			
PRI4	1- 74#							
PRI7	1- 75#							
PS	1- 72#							
PSPRIO	1- 73#							
RPBIT	1-103#							
RPO2SZ	1-104#							
RUBOUT	1-125#							
R0	1- 7#	4- 40#	6- 34#	6- 35	6- 36	8- 9#	8- 10	
R1	1- 8#	4- 41#	6- 7#	6- 8	7- 12	7- 16#	7- 18	
	7- 25	7- 36	8- 12	9- 1	9- 23	9- 25#	9- 26	
	9- 29	10- 1#	10- 3	10- 8#	10- 10	11- 4#	11- 9	

CROSS REFERENCE TABLE S-3

	11- 16#						
R2	1- 9#	4- 42#	6- 13	7- 11	7- 15#	7- 16	10- 17#
	10- 23#	11- 6#	11- 7	11- 8#	11- 13	11- 17#	
R3	1- 10#	4- 43#	7- 10	7- 14#	7- 27#	8- 23	9- 6#
	9- 7#	9- 33#	9- 34#	10- 16#	10- 22#	11- 12	11- 18#
R4	1- 11#	4- 44#	7- 9	7- 13#	7- 32#	7- 37#	8- 29
	8- 31#	11- 11	11- 14#				
R5	1- 12#	4- 45#	8- 6#	8- 8#	10- 18#	11- 19#	
SKIP2	4- 24#	9- 25					
SMBSIZ	2-158#	2-159	2-160				
SP	1- 13#	4- 46#	7- 9#	7- 10#	7- 11#	7- 12#	8- 7#
	8- 8	8- 17#	8- 23#	8- 29#	8- 30#	8- 31	10- 24#
	10- 25#	11- 4	11- 5#	11- 7#	11- 14	11- 15#	11- 16
	11- 17	11- 18					
SPACES	7- 20						
SPREAD	5- 8	5- 11	5- 47	6- 15	6- 20	8- 18	8- 24
	9- 8	9- 16	9- 35				
STMASK	1- 93#						
S.RSAV	4- 51#	8- 7					
TABCH	1-122#						
UPPCAS	5- 34#	7- 25	10- 12				
V.CDB	1- 25#						
V.CDQ	1- 26#						
V.GTB	1- 27#						
V.RLB	1- 28#						
V.RRES	1- 24#						
V.RSAV	1- 23#						
V.SVT	1- 21#						
V.XIT	1- 22#						
WIDTH	4- 36	5- 15	5- 33				
XFTCOM	3- 7#						
XFTDOS	3- 13#						
XFTMUO	3- 9#						
XFTRPG	3- 11#						
SSPASS	2-177#						
	5- 7						

CROSS REFERENCE TABLE M-1

AERROR	2- 31#
CALL	2- 73#
CALLS	2- 69#
CHKPNT	2- 96#
DIAL	2-324#
ERROR	2- 18#
FERROR	2- 28#
FREMSB	2-251#
GETBUF	2-124#
IERROR	2- 39#
IOTERR	2- 24#
MODEND	2-232#
MOOSTA	2-179#
MOVMSB	2-273#
MOVSEG	2-297#
OUTMSB	2-259#
OVLNAM	2-222#
POP	2- 63#
PUSH	2- 57#
QURVR	2-146#
RELBUF	2-138#
RESREG	2-107#
RETEM	2-280#
RETURN	2- 77#
SAVREG	2-102#
SERROR	2- 35#
SETABS	2-165#
STDEV	2-333#
SWPCAL	2- 84#
WERROR	2- 43#

CROSS REFERENCE TABLE C-1

	55520
. ABS.	55520