IDENTIFICATION

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PREFACE

Scope and Purpose

The material in this manual is arranged to initially provide the reader with an introduction to the new DEC/X11 System Exerciser. This is followed by an overview of the system and procedural information pertaining to both the loading and control of the software, in relation to the generation of user-designed Run-Time Exerciser (RTE) programs. The manual concludes with separate detailed procedures for both loading and controlling the user-designed programs.

The information is formally arranged as follows:

- Chapter 1 provides an introduction to the new DEC/X11 monitor in regard to general improvements in both design and functionality.
- Chapter 2 provides an overview of the entire DEC/X11 system, defining the various software elements.
- Chapter 3 provides the user with all of the procedural information required to load, start, and operate the DEC/X11 RTE build programs and the resultant user-designed RTE modules.
- APPENDIX A provides the user with a sample build from pre-build planning through the actual build under the Configurator/Linker program.

CHAPTER 1

INTRODUCTION

1.1 DEC/X11 SYSTEM EXERCISER MONITOR

1.1.1 System Exerciser Programs

1.1.2 New DEC/X11 Monitor

1.1.3 New DEC/X11 RTE Programs

1.2 REFERENCE DOCUMENTS

1.1 DEC/X11 SYSTEM EXERCISER MONITOR

Run-Time Exerciser (RTE) programs provide confidence and reliability testing for PDP-11 hardware by generally providing for the detection, as opposed to the isolation, of a wide range of hardware problems.

There are three classes of exerciser program: subsystem exercisers, unit exercisers, and system interaction exercisers. System interaction exercisers are the most complex, and the main concern of this manual, since they are both designed and generated using DEC/X11 software.

1.1.1 System Exerciser Programs

System interaction exerciser programs drive associated systems at maximum activity rates in order to provoke noise, timing, and logical interaction failures. The programs exercise systems hardware at the limits of design in order to ensure reliability. Such programs require a high degree of parameterization and operator interaction and are generally large in both size and scope although problem isolation and fault resolution only occur at a subsystem level.

The system activity stress provided by this class of exerciser program, as opposed to normal customer usage, makes these programs ideally suited for (1) prototype acceptance testing, (2) customer installation testing, and (3) preventive and corrective field maintenance usage.

1.1.2 New DEC/X11 Monitor

The new DEC/X11 Monitor is a modularized program which incorporates both structured design and programming techniques. The nature of this design enhances maintainability by providing extensive documentation, at a modular level, as an inherent by-product of structured programming and simplification of flow as a by-product of top-down implementation. As a result, the new DEC/X11 software lends itself more readily to the support of future hardware options and/or enhancements.

1.1.3 New DEC/X11 RTE Programs

Run-time system exerciser programs, created via the new DEC/X11 software, are a combination of user selected DEC/X11 monitor modules and exerciser option modules. Enhancements to the monitor portions of the final programs improve both the operation and control of the RTEs in the following areas.

- Operator/user interface

- System interactions
- Management of memory
- Error reporting and recovery

Operator/User Interface

The operator/user interface has been improved to provide:

1. Increased Console Interaction:

   Many of the keyboard commands and control characters may now be entered dynamically as well as statically, i.e., in Busy Mode (BSY>) as well as Command Mode (CMD>).

2. Increased Operator Control:

   An expanded set of keyboard commands and control characters now provides increased report generation capabilities (e.g., summaries of module header information), access to user specified locations, and expanded editing abilities.

System Interactions

Improved system interaction and, as a by-product, increased throughput has been achieved as follows:

1. By asynchronous parallel processing of:

   - Keyboard input and command decoding: where interrupt servicing, and decoding, will occur as fast as the operator can enter the input.
   - Message dequeuing and terminal output: where processing and printout will occur as fast as the terminal device can accept the data.
   - Job scheduling and multiprogramming: where option and monitor module processes are serviced on a First-In First-Out (FIFO) basis.

2. By an increased degree of multiprogramming:

   Made possible by minimizing the amount of overhead required to service the option modules (Control Queue) and console device (Type Queue), thus increasing the amount of CPU time available to run option modules.

Management of Memory

Memory management has been improved in the following areas:

1. Advanced Memory Utilization:

   - Through the use of optional keyboard commands, the operator may initiate a systematic relocation of the exerciser program through all of memory.

   - Through the use of optional bit settings in the Software Switch Register, the operator may inititate sequential movement of the exerciser program through memory.

2. Write Buffer Control:

   - Rotation of the write buffer, through the 124K bank of memory in which the exerciser currently resides, is both continous and contiguous.

   - Periodically, worst-case UNIBUS data patterns are written into all of the memory space not currently occupied by the exerciser program.

Error Reporting and Recovery

Error reporting and recovery have been improved in the following ways:

- A run summary now lists both hard and soft errors occurring within a module.

- If a system error is caused by an option module, the name of the module is now listed along with the offset value of the Program Counter.

1.2 REFERENCE DOCUMENTS

The following reference documents are currently available:

DEC/X11 USER'S MANUAL (MD-ZZ-CXQUA)
DEC/X11 CROSS REFERENCE MANUAL (MD-ZZ-CXQUB)
XXDP+ USER'S MANUAL (MD-ZZ-CHQUS)
DEC/X11 REFERENCE CARD

CHAPTER 2

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2.0 DEC/X11 SYSTEM OVERVIEW

DEC/X11 system software is used to create independent Run-Time Exerciser (RTE) programs from monitor and device/option modules that are selected by the user from the DEC/X11 CROSS REFERENCE MANUAL.

In Figure 2-1, an overview of the basic DEC/X11 system is depicted, along with a general representation of the layout of a typical RTE program. The DEC/X11 system consists of three fundamental parts:

- DEC/X11 Monitor Library
- DEC/X11 Device/Option Test Modules
- DEC/X11 Configurator/Linker Programs

From these the user selects a particular monitor, required test modules, and an applicable configurator/linker program in order to generate an RTE program for a particular hardware system. Once the RTE program is linked, it may be independently loaded via a standard ABS loader or an XXDP+ Monitor, depending on whether the load module is contained on paper tape or on a non-paper tape medium, respectively.

Whenever an RTE program is loaded into memory, an unrelocatable portion of the monitor always resides in the lowest 4K of memory. The area directly above may then contain a maximum of 39 test modules plus the remaining portion of the monitor (if the standard linker is used) or 19 test modules plus the remaining portion of the monitor (if the short linker is used). In either case, the remaining free memory area satisfies the need for write buffer space and monitor/test module relocation.

```
            ----------
           /!DEC/X11 !
          / !MONITORS!\
MONITOR  /  !--    --!  \
LIBRARY--   !--    --!   !
        !   !--    --!  -----                        ---------------
        !   !--    --!   !   !                        !  DEC/X11     !
         \  !--    --!  /    !   ------------------   ! RUN-TIME     !
          \ !--    --!/      !   !    DEC/X11     !   ! EXERCISER    !
           \!--    --!       !-->! CONFIG/LINKER !-->!  (LOAD        !
            !--    --!       !   !   PROGRAM      !   !   MODULE)    !
            ----------       !   ------------------   !              !
                             !                       --------------
                             !
                             !
                             !
         ----------------    !
         !   DEC/X11     !   !
         !OPTION/DEVICE  !   !
         ! TEST MODULES !\   !
         !---------------! ! !
         !--          --! !  !
         !--          --! ---
         !--          --! !
         !--          --!/
         ----------------

                                 SYSTEM OVERVIEW
                                 ---------------


                               ---------------------
                               !       WRITE       !
                               !      BUFFER       !
                               !       AREA        !
                               !-------------------!
                        --    /!--               --!
                             / !   OPTION/DEVICE   !
                             ! !--     TEST      --!
                  *39/19-----! !     MODULES       !
                   MAX.      ! !--               --!
                             ! !                   !
                             ! !-------------------!
    *39 for Standard Linker  ! !      MONITOR      !
     19 for Short Linker     ! !-------------------!\
                             ! !      MONITOR      ! !
                             \ ! (NON-RELOCATABLE) ! -----Lowest 4K
                              \---------------------/

                             RTE PROGRAM
                             -----------
```

FIG. 2-1 DEC/X11 SYSTEM OVERVIEW

2.1 Option/Device Modules

Each option/device module is a program, that is dedicated to the testing of a single option or device-controller within the confines of a system configuration. Thus, unlike a stand-alone diagnostic program that is used to isolate a static problem within an individual device, a system exerciser module is used to isolate an individual device only as it relates to a system problem. In fact, prior to running a collective group of exerciser modules for a given system, it is presumed that stand-alone diagnostics have been individually, and successfully, run for each device.

Each option/device module communicates with its resident monitor via software hooks that are contained in both the body of each module and a module's header-statement. In addition, there are seven basic types into which all modules are grouped. With this arrangement (interfacing with the monitor by type) a module may gain access to those support and/or utility routines that the monitor provides and the module requires.

The following subsections describe the seven basic module types currently available and the purpose of each.

2.1.1 Background Module (BKMOD)

The BKMOD-type only runs in a background mode (i.e., via non-interrupt driven devices) and at the lowest module run-time priority. A module of this type is used to exercise non-interrupt hardware options or functions.

Examples of BKMOD usage are:

- Exercising a floating point hardware option. (Module FPA)
- Testing the basic PDP-11 Instruction Set.

In addition, all modules of this type are run separately and consecutively. When relocation occurs, a pointer to the next module to be run ensures that although all the modules may not be run in each bank, they will be run consecutively.

NOTE

> When the "RUN" command is entered or after relocation BKMODS will do a 1 iteration pass by taking on the identity of a TMPIO (Temporary IOMOD). This is done to insure BKMODs are run in a high I/O activity system.

2.1.2 Special Background Module (SBKMOD)

The SBKMOD-type-module only runs in a background mode and is the first type of module to be run (i.e., before any resident NBKMOD). Once this module is initially run, it will, following every relocation, be run once again. The latter allows the special function of this module type (i.e., to set-up a special system condition) to be initially executed when the exerciser is relocated to another memory bank. Examples of SBKMOD usage are:

- To set-up the run-time sequencing of other resident modules or peripheral devices.
- To switch the DT03 Buss Switch before the other modules are run.

2.1.3 Non-Restartable Background Module (NBKMOD)

The NBKMOD-type-module only runs in a background mode, is the second type of module to be run, and is non-restartable. Once this type of module has been initially run successfully, it is never run again; unless, of course, an exercise is both aborted and restarted.

Examples of NBKMOD usage are:

- Checking system timing before other modules are run.
- Checking system parity before other modules are run.

2.1.4 I/O Module (IOMOD)

The IOMOD-type-module only runs in Input/Output mode (i.e., via interrupt-driven devices), depending on expected interrupts in order to run continuously. These modules generally service buffer-driven devices (i.e., devices that do not generate NPRs or contain word-count registers). This type of module can be relocated without restriction.

Examples of IOMOD usage are:

- For exercising TA-11 Cassettes, and floppy disks.
- For exercising a paper tape reader/punch or a line printer.
- Exercising a floating point hardware option (module FPB)

2.1.5 I/O Module Restricted (IOMODR)

The IOMODR-type-module is an IOMOD that cannot be relocated, due to hardware restrictions, and is only run in the lowest bank of memory.

An example of IOMODR usage is: the exercising of a UNIBUS Tester.

2.1.6 I/O Module Extended (IOMODX)

The IOMODX-type-module is an IOMOD with extended capabilities that services NPR devices. The capabilities of this module type include: use of a monitor supplied write buffer, the ability to change the size of read and write buffers, the ability to access a monitor's check data utility routine, and the ability to convert 16-bit addresses to 18-bit addresses or 18-bit addresses to 22-bit addresses.

Examples of IOMODX usage are:

- Exercising the RK11 Controller and up to 8 drives (types RK02-RK05).
- Exercising the RP11 high and low density disk drives.

2.1.7 I/O Module Partially Restricted (IOMODP)

The IOMODP-type-module is an IOMODX that is partially relocatable. This means that due to hardware restrictions the module is only relocated to certain fixed boundaries (e.g., 32K).

2.2 DEC/X11 Monitors

Since there are several DEC/X11 monitor programs that are available to the user, the selection of an appropriate monitor depends on the configuration of the hardware system to be tested. However, the monitor programs are not separate entities. A desired monitor must be constructed, via the configurator/linker process, from pre-assembled monitor modules that are contained in a DEC/X11 Monitor Library. Therefore, to provide for both convenient selection and adaptation to the configurator/linker process, DEC/X11 monitor programs are classified by type and named (i.e., A,B,C, etc.) as described in the DEC/X11 CROSS REFERENCE MANUAL.

Such monitor classification in the reference manual not only allows the user to apply an appropriate monitor program to a given hardware configuration, but to select a monitor that most nearly meets the needs of the hardware system in relation to (1) the functional requirements of the resultant RTE and (2) the more efficient use of assigned monitor space.

Moreover, in the same manner that the linking of the basic software components of an RTE program (monitor and option modules) depends on the total configuration of the hardware system, the linking of the basic software components of the monitor portion of the RTE (pre-assembled monitor modules) depends on the type of processor to be serviced and its available options.

Finally, since in all probability additional monitors will be designed, the following material is not intended to describe monitor concepts in terms of specific monitor differences but rather in terms of common functionality.

Monitor Operations

Basically, the monitor portion of an RTE program is responsible for starting the RTE (via Initialization); establishing operator communications (via Command Decoding); establishing communications with its resident option modules (via Trap Interpretation); providing for option module control (via Queue Priority Servicing); and providing for memory usage control (via RTE Relocation and Write Buffer Rotation).

2.2.1 System Initialization

When an RTE program is loaded, the monitor portion of the program provides for the initialization of certain software and hardware components of the system via the execution of two routines: the Start-Up and Initialization routines.

Start-up Routine

This routine sets-up required software components of the monitor and determines the operating environment by performing the following functions:

- Set-up the Power Failure Vector.
- Set-up the software and hardware trap handlers.
- Set-up the Software Switch Register (SWR) and certain Status Indicator Words (for option status).
- Size and Poll the system to determine:
  - (a) Processor type (11/70, 11/60, etc.)
  - (b) Processor Options (KT, CACHE, etc.).
  - (c) Memory size (size of RTE is in Loc. Zero).
  - (d) If good parity must be written in memory

(only if PARITY or ECC option).

(e) Software environment (APT, ACT/SLIDE/XXDP+)

- Output RTE identity message.
- Output System Size message.
- Output Keyboard Prompt (CMD>).

Initialization Routine

This routine Initializes certain software and hardware components (and starts the monitor running) as follows:

- Initialize both the Control and Type Queues.
- Initialize error logging function (if available).
- Initialize the option module servicing mechanisms (i.e., set-up the various pointers and flags).
- Enable the keyboard for operator input.

2.2.2 Operator Interfacing

Once an RTE program is Initialized, the fact that the monitor portion of the program is running (and the keyboard enabled for command input) is indicated by the printing of the Command Mode (CMD>) prompt. Thus, at this point the monitor is available to provide service to the more than twenty keyboard commands available to the user. Some of the commands (such as module start, option disable/re-enable commands, and the module parameter modification command) are restricted to entry in Command Mode only. The remaining commands, that are generally related to the deselection/reselection of modules and the disposition of printout data, may be entered in either the Command Mode or (following a module start command) the Run Mode (BSY>).

In any case, as the operator enters a command format, each character is stored in the Keyboard Input Buffer until a Carriage Return (CR) is both entered and recognized by the Monitor. When this occurs, the Monitor (via its Task Scheduler) dispatches control to its Keyboard Input Processing Routine to execute the following 5 monitor modules:

- The Process Command Routine (CMDPRC)
- The Copy Command Routine (CMDCPY)
- The Decode Command Routine (CMDDEC)

- The Service Command Routine (CMDSRV)

- The Reset Command Routine (CMDRST)

Process Command Routine (CMDPRC)

CMDPRC is the control module for the entire Keyboard Input Processing Routine. As such, the module is responsible for initially clearing all local storage locations required by the process and ultimately calling for the execution of each of the subordinate routines as follows:

1. CMDPRC initially calls the Copy-Command-Routine (CMDCPY) to allow the contents of the Keyboard Input Buffer to be transferred to the Decode Buffer. Following the transfer, CMDCPY then returns control to CMDPRC. However, there are two possible results of the transfer:

   (a) If CMDCPY does not detect an abnormal condition in the Decode Buffer, CMDPRC is directed to call the Decode-Command-Routine (CMDDEC) to check for the validity of the command.

   (b) If CMDCPY detects an abnormal condition in the Decode Buffer, an Abort Flag is set and CMDPRC is directed to call the Reset-Command-Routine (CMDRST), to allow a correction to be made following the issuance of an appropriate prompt (CMD> or BSY>).

2. Whenever a command is checked for validity by CMDDEC, control is always returned to CMDPRC to continue process control. However, there are two possible results of the check:

   (a) If the command in the Decode Buffer is valid, CMDPRC is directed to call the Service-Command-Routine (CMDSRV) in order to execute the function prescribed by the command.

   (b) If an Invalid Command is detected in the Decode Buffer, CMDDEC loads an error message into the Type Queues and CMDPRC is directed to call the Reset-Command Routine (CMDRST) in order for a correction to be made. The message is then output, followed by the issuance of an appropriate prompt (CMD> or BSY>).

3. When the prescribed function is executed, CMDSRV always returns control to CMDPRC which, in turn, always calls CMDRST to enable the issuance of the appropriate prompt (CMD> or BSY>). Thus, keyboard interrupts and the possible entry of another command are both re-enabled.

4. Finally, whenever the appropriate prompt has been output via CMDRST, a return is always made to CMDPRC in order to effect

a return to the Task Scheduler.

Copy Command Routine (CMDCPY)

The CMDCPY routine allows the command string that is originally contained in the Input Buffer to be copied into the Decode Buffer, one character at a time, up to (and including) the Carriage Return (CR) or Line Feed (LF). Moreover, since the Input Buffer may contain both Rubout (\) and replacement characters, the routine will delete the unwanted characters.

Following the receipt of a command string, the routine always returns control to the Process-Command-Routine (CMDPRC). However, prior to the return, an Abort Flag will be set (allowing for re-direction in Process Control) if any one of the following abnormal conditions occurs:

- A Control U(^U) character is detected (See CMDPRC Step 1b)
- The first character detected is a Rubout, Carriage Return, or Line Feed (See CMDPRC Step 1b).

Decode Command Routine (CMDDEC)

The CMDDEC routine scans the Decode Buffer and compares the command entry with entries contained in a Valid Command Table. There are two possible results:

- If a match is found, the command is validated and its code is obtained from the table as a return is made to Process Control (See CMDPRC Step 2a).
- If a match cannot be made, an Invalid Command indicator is set, an appropriate error message is loaded into the Type Queue, and control is returned to Process Control (See CMDPRC Step 2b).

It may be noted that following a comparison a return to CMDPRC is always made. However, if a match cannot be made, the setting of the Invalid Command indicator provides for a redirection in Process Control.

Service Command Routine (CMDSRV)

The CMDSRV Routine provides for the execution of all valid commands. Once its function is performed, a return is made to Process Control (See CMDPRC Step 2a and Step 3).

Reset Command Routine (CMDRST)

The CMDRST Routine ouptuts an appropriate prompt and re-enables keyboard interrupts in order to accomodate additional or corrective operator input. To output the proper prompt message, the routine determines if the system is currently in a Command (CMD>) or a Run (BSY>) Mode by examining a status indicator. However, if an error message is in the Type Queue, it will be output prior to loading and outputting a prompt message. Once the routine's function is completed, a return is always made to Process Control (See CMDPRC Steps: 1b, 2b, 3 and 4).

2.2.3 Option Module Control

Monitor control of an RTE program's resident modules is basically concerned with the implementation of two tasks: (1) Priority scheduling for module execution and (2) establishing effective communications with each module.

2.2.3.1 Priority Scheduling

As part of an RTE, each option/device module performs a unique test, which must be properly sequenced during run-time. However, in regard to module functionality and processing modes of operation (i.e., Background Mode and Input/Output Mode), many of the modules are similar. For these reasons all modules are divided, by common functionality and processing mode, into the following seven types: Background Modules (SBKMOD, NBKMOD, BKMOD) which do not service interrupt-driven devices; and Input/Output Modules (IOMOD, IOMODX, IOMODP, IOMODR) which do service interrupt-driven devices. In addition, each module--is defined by type via status word bits contained in the module's header.

With this arrangement, the monitor during Initialization uses the status word bits to construct a Priority Schedule by listing each resident module in a pre-determined manner, thus defining the order of execution by type.

With the system in Command Mode (CMD>), the typing-in of a Module Start Command, with or without relocation specified (i.e., RUN or RUNL), initiates the execution of the option modules (as prescribed in the Priority Schedule) and outputs a Run Mode (BSY>) prompt. Each module is then conditionally sequenced as follows:

1. <u>SBKMODs</u>

   The SBKMODs are the first type to be run. Each module is separately run once prior to relocation and once again following each relocation (i.e., if relocation is enabled.)

2. NBKMODs

The NBKMODs are the next type to be run. Each module is separately run once, and never again.

3. IOMOD,X,P,R

All the I/O Modules are the next types to be run. They run simultaneously and continuously (i.e., as long as there are interrupts to drive them).

4. BKMODs

The BKMODs are started last and each module is run separately. However, since these modules have the lowest priority, they can only be run when none of the other types are running.

2.2.3.2 Module Communications

When the option modules are running, communication is established with the monitor via software hooks that are contained in the body of each module (i.e., Trap Calls) and also, in some cases, in the header (i.e., parameter locations). These elements, therefore, comprise a module's interface with the monitor.

Currently there are 19 calls collectively available to the option modules. Some calls are used by all of the modules, others are only used with certain module-types, while others are function-related and are, therefore, only used by specific modules, regardless of type.

Basically, when a module call is trapped to the monitor, the monitor responds with a service and/or parameters such as: buffer services including parameters, an error reporting routine, or a message output service.

I/O Module Buffer Service Calls:

GWBUF$	;Get Write Buffer information call.
GETPA$	;Get 18-bit Physical Address call.
MAP22$	;Map 22-bit Physical Address call.
CDATA$	;Check Data call.
DATCK$	;Provide Check Data error count call

Output Message Calls:

- Monitor-Defined Error Messages:

DATER$	;Data Error message call.

```
        HRDER$                  ;Hard Error message call.
        SOFER$                  ;Soft Error message call.
```

- Module-Defined Messages:

```
        MSG$                    ;Output single ASCII message call.
        MSGS$                   ;Output all ASCII messages in table
                                 call.
        MSGN$                   ;Output all ASCII messages in table
                                 with header call.
```

Return Control To Monitor Calls:

```
        EXIT$                   ;Module awaiting interrupt call.
        PIRQ$                   ;Put Interrupt Request in Queue
                                 call.
        BREAK$                  ;Temporarily return to monitor
                                 call.
```

Ending Calls:

```
        ENDIT$                  ;End of iteration call.
        END$                    ;Drop module from exercise call.
```

Utility Calls:

```
        OTOA$                   ;Octal to ASCII conversion call.
        BTOD$                   ;Binary to Decimal conversion call.
        RAND$                   ;Random Number request call.
```

I/O Module Buffer Service Calls

To process data transfers for certain I/O modules (IOMODX and IOMODP), the monitor, on request (GWBUF$), provides a write buffer area in free core from which data is sent to the device. In addition, the monitor provides the module interface (i.e., header locations) with both the size of the write buffer (WBUFSZ) and its starting physical address (WBUFPA).

Since the read buffer area is contained within the module, both the size (RBUFSZ) and starting virtual address (RBUFVA) of the read buffer are known, but its starting physical address (RBUFPA) is not. Therefore, the physical address of the read buffer is also requested (GETPA$ or MAP22$) from the monitor. With the size and location of the buffers established for both the monitor and the module, the generation of a Write and Read Command to the device will be followed by a module request (CDATA$ or DATCK$) to the monitor to initiate a data comparison and, if an error is detected, the monitor will output an error message. If CDATA$ is used, the monitor will also output a summary message containing an error count. If DATCK$ is used, a summary will not be output and the error count will be returned to the module for storage.

1. The GWBUF$ Call:

The GWBUF$ call traps to the monitor for write buffer information. In response, the monitor examines the value in the Write Buffer Request (WBUFRQ) location to determine if there is enough free core to satisfy the request. If the requested value is smaller than the amount of available free core, the monitor satisfies the request by merely returning the same value to the Write Buffer Size (WBUFSZ) location. However, if the requested value is larger, the monitor can only send a lesser value to the buffer size location indicating what is available.

In addition, the monitor sends the starting address of the buffer to the Write Buffer Physical Address (WBUFPA) location including, if necessary, any extended address bits (WBUFEA).

2(a) The GETPA$ Call:

The GETPA$ call is used to convert a 16-bit virtual address to an 18-bit physical address and, as such, the call is used by many types of modules. Normally, however, the call is used by IOMODX and IOMODP modules to effect the conversion of the starting virtual address of the read buffer (RBUFVA) to a starting physical address (RBUFPA), including any extended address bits (RBUFEA). The module then loads the 16 low-order physical address bits into the Bus Address Register and any extended bits into the Command Register, prior to issuing a Read Command.

2(b) The MAP22$ Call:

The MAP22$ call is used to convert an 18-bit virtual address to a 22-bit physical address. As such, the call is used with any type of module, as long as the hardware and associated monitor are capable of handling 22-bit addressing. Normally, however, the call is used by IOMODX and IOMODP modules as described for the GETPA$ call.

3(a) The CDATA$ Call:

The CDATA$ call traps to the monitor, with the starting physical address of the read buffer (RBUFPA), to request a comparison between the module's read and write buffer data.

If the monitor detects a data error, it will output an error message followed by a summary. The summary will include a print-out of both the total number of errors detected and the total number of words transfered. Following the summary print-out, the monitor will increment an error counter within the module by one, indicating that a single summary error message has occurred.

3(b) The DATCK$ Call:

The DATCK$ call performs the same function as the CDATA$ call with the following exceptions:

If the monitor detects a data error, only an error message will be output. However, the total number of errors and words transfered will be delivered to the body of the module and the error counter will be incremented, as previously described.

Output Message Calls

There are six output message calls: Three (DATER$, HRDER$, SOFER$) are used to request predefined error reports from the monitor while the remaining three (MSG$, MSGS$, MSGN$) are used to request user-defined messages from the module defining certain normal operating conditions and/or error statistics (e.g., TOO MANY WRITE ERRORS).

The monitor-defined error messages are:

1. The DATER$ Call:

   The DATER$ call traps to the monitor to request an error report when a data buffer comparison error has been internally detected within a module (e.g., IOMOD, IOMODR). This is in contrast to the data comparison that is externally performed by the monitor for IOMODX and IOMODP modules (refer to the CDATA$ and DATCK$ calls under I/O Module Buffer Service). In any case when the error message is output, the monitor will increment the module's soft error counters by one to indicate that the error message has occurred.

2. The HRDER$ Call:

   The HRDER$ call traps to the monitor to request the output of a standard error message when an unrecoverable Hard Error (e.g., non-existent memory) is detected by a module. As such, the call can be used by any module type. In addition, certain modules will pass a comment (i.e., a cause of error statement) to the monitor for outputting with the message. Moreover, an extended form of the call can also pass the address of a table containing statistical error information (e.g., contents of all of a device's registers) for outputting. The monitor will increment the module's Hard Error Counts.

3. The SOFER$ call traps to the monitor, to request the output of a standard error message, when a recoverable Soft Error (e.g., data late) is detected by a module. As such, the call can be used by any type module. With the exception of the appearance of the word "SOFT" as a replacement for the word "HARD", basic and extended message formatting for the call is

identical to the formatting outputted for an HRDER$ call. The monitor will increment the module's Soft Error Counts.

The module-defined messages are:

1. The MSG$ Call

   The MSG$ call traps to the monitor to request the output of a single ASCII message. An address is also passed to the monitor to define the location of the message.

2. The MSGS$ Call

   The MSGS$ call traps to the monitor to request the output of a table of ASCII messages. An address is included to define the location of the table.

3. The MSGN$ Call:

   The MSGN$ call traps to the monitor to request the output of a table of ASCII messages. An address is included to define the location of the table. In addition, however, this call elicits the output of a complete header message (i.e., modulename, PC contents, etc.).

Return Control To Monitor Calls

The three return-control-to-monitor calls are used to provide for a more efficient use of exerciser run-time in regard to module scheduling, the execution of interrupt service routines, and the processing of module requests.

1. The EXIT$ Call:

   The EXIT$ call is used to return control to the monitor when a module is awaiting an interrupt. As such, the call is only used with a module that is dedicated to servicing an interrupt-driven device (normally, but not necessarily, an I/O Module). In any case, by relinquishing control to the monitor during the wait period, the monitor allows module scheduling to continue.

2. The PIRQ$ Call:

   The PIRQ call is trapped to the monitor to request that the execution of an interrupt service routine, contained within an I/O Module, be deferred to a lower priority. This is done to defer the execution of a non-critical routine, such as a routine which error-checks registers that are not subject to immediate change. This is in direct opposition to the priority required for the execution of a critical routine, such as a routine that must service the contents of a communications buffer.

When PIRQ$ is executed, the monitor stores the Interrupt Request in a FIFO queue at the lowest priority (i.e., PRO) and does an RTI to return to the processing operation that was being performed prior to the generation of the interrupt request. However, the latter statement should not be misconstrued. It does not imply a direct return to the scheduling of the Background Modules (i.e., BKMODs) since all I/O interrupt requests in the queue, regardless of their relative module priority, must be serviced before a BKMOD can be run.

3. The BREAK$ Call:

The BREAK$ call is used to transfer temporary control to the monitor while a module awaits the occurrence of an asynchronous event (e.g., the setting of a DONE or READY bit) before proceeding. As such, the call is normally but not necessarily used with I/O Modules.

When the BREAK$ call is executed, the monitor checks the queues for pending I/O interrupt requests. When all previous requests have been serviced, the monitor returns control to the module; specifically, to the instruction directly following the BREAK$ call.

Ending Calls

There are two ending calls: one is used to indicate the successful completion of a module's test procedure(s) prior to a restart while the other is used by all modules.

1. The ENDIT$ Call:

The ENDIT$ call is trapped to inform the monitor that an iteration point has been reached. The monitor responds by incrementing an Iteration Counter in the module's header by one and comparing the resultant count with an Iteration Constant that is also contained in the module's header. If the values are equal, the monitor will output an END OF PASS message and restart the module. However, if the values are not equal, the monitor will resume module operation by executing the instruction that directly follows the ENDIT$ call.

2. The END$ Call:

The END$ call is used to inform the monitor that a fatal error has been detected (e.g., device is off-line). The monitor responds by stopping the module, via the setting of Bit 13 in the module's status word, and outputting a module-dropped message. Thus, the setting of Bit 13 prevents the module from running for the duration of the exercise. However, if the error is detected in an I/O Module, interrupt lines are also disabled prior to the generation of the call.

Utility Calls

There are three utility calls currently available: one will convert an octal number to ASCII characters, another will convert a binary number to its decimal ASCII equivalent, while the third generates a random number. The calls may be used by any type of module.

1. The OTOA$ Call:

   The OTOA$ call traps to the monitor to request the conversion of an octal number (max. 16 bits) to equivalent ASCII characters (max. 6 characters). When the call is issued, the module provides the monitor with both the module location of the number to be converted and the module location of the starting address to which the result will be directed.

   As an example of usage: the call may be issued prior to the issuance of an MSG$ call to define the ASCII message.

2. The BTOD$ Call:

   The BTOD$ call traps to the monitor to request the conversion of a binary number (max. 16 bits) to decimally equivalent ASCII characters (max. 5 characters). When the call is issued, the module provides the monitor with both the module location of the number to be converted and the module location of the starting address to which the result will be directed.

   As an example of usage: the call may be issued prior to the issuance of an MSG$ call to define the ASCII message.

3. The RAND$ Call:

   The RAND$ call traps to the monitor to request the generation of a new random number (max. 16 bits). Once the number is generated, it is directed to a random number location in the module's header.

   As an example of usage: a new random number may be used to alter the sector address for a disk, thus allowing random instead of contiguous SEEKs to occur.

2.2.4 Memory Usage Control

When the RTE is running, one of the monitor's major responsibilities is to exercise an efficient control of memory resources. This includes:

- Control of the available memory hardware options (i.e., KT, CACHE, PARITY, ECC, etc.)

- The sizing and designation of write buffer space for requesting modules within a pre-defined write buffer area.
- Control over the relocation of the moveable portion of both the RTE and the monitor (i.e., if the option is enabled).
- The generation of memory-worst-case patterns in free core for a more comprehensive exercise of available memory resources.

2.2.4.1 Memory Options Control

The monitor is responsible for establishing control over all memory hardware options that may be available to the system. This includes: (1) Memory Management (KT); (2) Parity Memory, ECC, and Cache Memory; and (3) the 22-Bit Addressing option.

Memory Management (KT) Control

Initially, the monitor determines if a KT unit is available. If it is, the following control functions will be performed:

- The KT may be turned On or Off via keyboard command.
- All Page Address Registers (PARs) and Page Descriptor Registers (PDRs) will be set up.
- If a CDATA$ or DATCK$ call is trapped to the monitor, the processor will be switched from KERNEL to USER Mode.

Parity, ECC, and Cache Memory Control

Monitor control of Parity, ECC, and Cache Memory consists of turning these options On or Off via keyboard commands and accommodating associated error traps. However, in regard to Parity Memory and the ECC option, common On/Off commands are currently in use. Thus, turning Parity Memory On will also turn the ECC option On, if it is available.

22-Bit Addressing Control

Monitor control of 22-Bit Addressing consists of turning the option On or Off via keyboard command and loading the Mapping Registers. Initiation of the latter provides pointers to the write buffer area.

2.2.4.2 Write Buffer Control

Certain DEC/X11 test modules (i.e., IOMODX, IOMODP) have the ability to request that the monitor provide write buffer space for the transfer of output data to an associated device. In this regard, monitor control of the write buffer area concerns (1) the designation of such space on request and (2) the "rotation" of write buffer spaces (via the RTON Command) during successive requests, to provide a device with more comprehensive testing in relation to its ability to access all of free core. Write Buffer Area
----

For systems having only 128K of memory or less, all of the memory space not currently occupied by the RTE is defined as the write buffer area from which write buffer space is assigned.

However, for systems greater than 128K which require 22-bit addressing, memory is divided into contiguous segments consisting of the 124K locations. The write buffer area is then limited to that 124K segment of memory in which the moveable portion of the RTE currently resides. Segmentation is necessary due to hardware addressing restrictions in which the UNIBUS Mapping Registers, fully loaded, can only accommodate a maximum addressing range of 124K locations.

In Figure 2-2, three examples of segmentation depict the relationships existent between the current location of the RTE and the location and limits of the write buffer area:

In example 2a, the limits of the write buffer area are shown when the moveable portion of the RTE is in the lowest 124K segment. Note that the RTE is not relocated within the segment and, if it were, the limits of the write buffer would remain the same.

In example 2b, the limits of the write buffer area are shown when the moveable portion of the RTE is relocated to another 124K segment. Note that if the RTE is again relocated but remains within the segment, the limits of the write buffer will remain the same.

In example 2c, the limits of the write buffer area are shown when the moveable portion of the RTE has been relocated to straddle the boundary of a 124K segment. Note, in this instance, that the lower limit of the write buffer area starts at the base of the moveable portion of the RTE and ends 124K locations above the base.

Write Buffer Rotation

Briefly, write buffer rotation (if enabled) allows an initial write buffer assignment to be made from a pre-defined starting position; that is, the first free location above the top of the moveable portion of the RTE. Subsequently, assignments are advanced through the write buffer area until the top of the area is reached, whereupon the monitor returns to the bottom of the area to continue the process. However, if rotation is not enabled, all assignments are made from the pre-defined starting point (i.e., top of the RTE).

SOME EXAMPLES OF WRITE BUFFER LIMITS

```
------------           ------------            ------------
|          |           |          |            |          |
|          |-248K      |          |-248K       |          |-248K
|          |           |          |\           |          |
|          |           |          | \          |          |
|          |           |          |  |         |          |\
|          |           |----------|  |WRITE    |          | \
|          |           |   RTE    |  |BUFFER   |          |  |
|          |           |----------| /          |          |  |WRITE
|          |           |          |/           |----------|  |BUFFER
|          |-124K      |          |-124K       |   RTE    |-/--124K
|          |\          |          |            |----------|/
|          | \         |          |            |          |
|----------|  |        |          |            |          |
|   RTE    |  |WRITE   |          |            |          |
|----------|  |BUFFER  |----------|            |----------|
| RTE LOW  |  |        | RTE LOW  |            | RTE LOW  |
|   4K     | /         |   4K     |            |   4K     |
------------/          ------------            ------------

    2a                     2b                      2c
```

FIGURE 2-2

Write Buffer Segmentation

(For Systems Greater Than 128K)

Before describing the rotation process, recall that whenever an Extended I/O Module requests write buffer space, the monitor will initially determine if the area contains sufficient space to satisfy the request. Once this determination is made, the monitor either grants the requesting module the desired buffer size or provides the module with whatever space is available. The monitor then delivers the start address of the assigned buffer space to the module.

To accommodate such requests, and also the requirements of both the Exerciser Relocation option and the Write Buffer Rotation option, the monitor uses a write buffer area as the first free location above the moveable portion of the RTE, thus defining a start address which equates with the base address of the write buffer area (i.e., the top of the RTE). This is accomplished via pointer initialization which occurs under two conditions: (1) prior to the issuance of an initial request and (2) following any relocation of the RTE. Moreover, since the pointer can only be advanced when Write Buffer Rotation is enabled, all subsequent requests, made with rotation disabled, will effectively use the base address of the area as a start address.

In any case, with the initial start address appropriately defined and rotation enabled, the pointer will be advanced to define the first free location above the top of the first requested buffer space. At this point, if sufficient core is available, the pointer will assume an address-value which equates with the requested buffer size plus one. Otherwise, the pointer will assume an address which equates with available space. In this manner, every subsequent request will advance the pointer through the buffer area until the top of the area is reached, whereupon the pointer will be returned to the bottom of the write buffer area, where the advancement process will continue.

However, as shown in Figure 2-2, depending on relocation, the bottom of the buffer area may again be at the top of the RTE (Examples 2a and 2c) or below the RTE (Example 2b). If the latter is true, advancement will continue until the last free location, at the bottom of the moveable portion of the RTE, is eventually reached. At this point, since the RTE itself cannot be used as write buffer space, the address pointer will skip to the top of the RTE and the rotation process will continue.

2.2.4.3 Exerciser Relocation

Before describing the Relocation Process, recall that when an RTE program is loaded into memory the program is effectively divided into two sections: (1) a fixed monitor portion which must reside in the lowest 4K of memory and is not relocatable and (2) a moveable portion, consisting of the remainder of the monitor and all of the test modules, which initially resides above the fixed portion and can be continuously relocated through the remainder of memory (See Figure 1-1).

In addition, continuous relocation is only possible if: (1) the system contains a Memory Management (KT) unit, (2) the KT unit is enabled via the KTON Command, and (3) the Relocation Process is not locked out (i.e., the RTE is started by a RUN Command as opposed to a RUNL.

Relocation Process

The Relocation Process is a monitor controlled option which allows the moveable portion of the RTE to be continuously relocated through main memory via a series of relocation operations to provide for a complete test of all available core (the lowest 4K excepted).

During the process, each new relocation operation is initiated by the monitor when all of the I/O type modules have completed a single pass or when any BKMOD (if no I/O modules exist) has completed a pass. However, since the modules have varying run-times, some of the modules will have completed a pass and restarted. Therefore, all of the modules will be stopped at their next iteration point, at which point they will be restarted when relocation is completed.

When a relocation operation is completed, a RELOCATED TO XXXXXX message is output, indicating the new physical start address (XXXXXX) of the RTE.

However, there are two separate types of relocation operations that may sequence during a Relocation Process: Constant Relocation operations or Random Relocation operations. Moreover, by setting a bit (SW08 = 1) in the RTE's Software Switch Register, the execution of the series of random relocation operations may be disabled. If both types of relocation are permitted (SW08 = 0), constant relocation operations will first cycle the RTE completely through memory, but only once. The Relocation Process will then be continuously effected by random relocation operations until the program is stopped and restarted. However, if Random Relocation is disabled (SW08 = 1), constant relocation operations will run continuously.

Constant Relocation Operations

Starting at a base address defined by the user, or the original base address defined by default, the moveable portion of the RTE is advanced to a new base address via an incremental constant (normally 4K). In this manner, constant relocations occur until an upper limit of memory is eventually reached that can accomodate the program. The monitor then returns the RTE to its original base address and the cycle is completed. At this point, if Random Relocation is enabled, the process will never be re-cycled until the program is stopped. Otherwise, it will recycle continuously.

Random Relocation Operations

Following the completion of a series of constant relocation operations which return the RTE to its original base address, the Relocation Process may be re-initiated by a series of random relocation operations.

During Random Relocation, the moveable portion of the RTE is relocated to randomly selected areas of memory, via random number generation, until a pre-defined number of relocations (determined by total memory size) has occurred. At this point, the next relocation will return the RTE to the lowest possible address (the original base address). The next relocation will then direct the RTE to the highest possible address that can accommodate the program, which completes the cycle. The entire process is then continuously repeated until the program is stopped.

2.2.4.4 Memory-Worst-Case-Pattern Generation

As previously stated, all of the memory space not currently occupied by the RTE is defined as free core and as such serves as the write buffer area. With this consideration, when a Module Start Command (i.e., RUN or RUNL) is entered, a memory worst-case pattern is automatically written into the free core area in order to intensify UNIBUS activity during I/O data transfers.

However, if relocation of the RTE is enabled, during each successive relocation increasing portions of the worst-case pattern are overlaid. Therefore, whenever the RTE is eventually relocated to lowest memory, the worst-case pattern is completely re-written.

2.2.5 Trap Processing

Trap processing by the monitor is concerned with the handling of both software and hardware traps. Software traps are used to provide access to special handling routines via a Trap Instruction when an option/device module requires external services that the monitor provides such as buffer services or error reporting services (refer to Module Communications 2.2.3.2). Hardware traps are used to provide access to special handling routines following the execution of an instruction when an internal error condition is detected by the CPU. Thus, hardware traps are caused by internal failures as opposed to external failures occuring within a device.

Software Traps

When a module issues a trap call (e.g., GWBUF$, GETPA$, etc.), the trap instruction is vectored via Location 34(TRAP instruction) to the monitor's Trap Service routine. The trap code is identified and the module's register contents and offset PC address are saved. The monitor then dispatches to the appropriate routine(s) where, depending on both the type of call and the complexity of the requested service, one or more of the following operations will occur:

- The request is executed and control is returned to the requesting module (e.g., OTOA$, RAND$, etc).
- The request is executed and/or an entry is provided

to the Type Queue (e.g., CDATA$, DATER$, MSG$, etc.).

. An entry is provided to the Control Queue for subsequent service (e.g., PIRQ$, BREAKS, etc.).

. The request is executed and control is returned to the monitor's Priority Scheduler routine (e.g., END$, EXIT$).

Hardware Traps

Hardware trap handling concerns the processing of internally produced errors associated with the CPU and memory options that are classified as follows: (1) System Errors; (2) Parity Errors (main or cache memory) and ECC Errors; (3) Memory Management (KT) Errors.

1. System Errors:

   When a Bus Error (e.g., non-existent memory, odd address, etc.) is trapped through location 04 or a Reserved Instruction Error (i.e., an illegal instruction) is trapped through location 10, the monitor saves the contents of the updated PC, PSW, and SP. The monitor then initializes the system and outputs a System Error message. However, at this point any or all of the following may occur:

   . If error logging is available to the CPU, it is performed.

   . If an option module is responsible for four system errors, it is dropped.

   . If the entire RTE program has accumulated excessive system errors, the run is terminated and the system is returned to Command Mode (CMD>). With the exception of the latter possibility (i.e., return to CMD>), following the processing of a system error the RTE is restarted as follows: All modules that have completed an End-Of-Pass will be re-initiated from the beginning (i.e., RESTART address) while the remaining modules will be re-initiated from a pre-defined location (i.e., START address).

2. Parity Errors and ECC Double-Bit Errors:

   If a Memory Parity Error, a Cache Parity Error, or an ECC Memory Double-Bit Error is trapped through location 114, the system is initialized and the contents of the appropriate registers are output, along with an appropriate error message. However, if ten of these errors occur, the run is terminated and the system is returned to CMD> mode. Otherwise, the RTE is restarted as previously described.

3. Memory Management (KT) Errors:

   If a KT Error is trapped through location 250, the system is initialized and the contents of the available general registers (SR0 and SR2, SR1 and SR3) are output, along with an appropriate error message. However, if a KT error occurs, the run is terminated and the system is returned to CMD> mode.

2.3 Configurator/Linker Program

The DEC/X11 configurator/linker program is used to create Run-Time Exerciser (RTE) programs. The initial implementation of a configuration process (via construction of a Configuration Table) is followed by the implementation of a linking process (via execution of a LINK Command), which results in the creation of an individualized RTE module. A user specified monitor and user specified test modules are selected, entered in the Configuration Table (C-Table), and linked by command to derive an RTE module. 2.3.1 The Configuration Process

The configuration process facilitates the execution of the linking process, by providing an accessible area for required monitor and test module information.

Following the loading of a configurator/linker program, the user implements the configuration process by initiating a Configure Mode of operation and constructing a Configuration Table (C-Table). During construction, the name of the desired monitor is entered in the table. The name of each desired test module is then separately entered along with certain associated parameters, such as device and vector addresses and priority levels. The C-Table will accommodate a maximum of 40, 11-word entries (i.e., 1 monitor entry and 39 test module entries).

When the construction of the C-Table is completed, the information required for the linking process is available and the user provides for an exit to the Non-Configure Mode of operation to initiate the link.

2.3.2 The Linking Process

With the construction of the C-Table completed, the user initiates the linking process via the formatting and execution of a Link Command.

Basically, the linking process effects the building of an RTE by examining the C-Table and selecting, or informing the user to select (i.e., if the input medium is paper tape), the appropriate monitor modules (from the monitor library) and the appropriate test module input. However as each module is selected, it is individually processed and output, a block at a time, as a portion of the RTE. In this manner, the RTE is created as a single executable binary file.

2.4 DEC/X11 Distribution

DEC/X11 software is packaged for usage over a wide media range. Therefore, the elements of a software package are associated with a particular medium via a MAINDEC designator (alphanumeric code) that is both listed and described in the DEC/X11 CROSS REFERENCE MANUAL.

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CHAPTER 3

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3.1 GENERAL INFORMATION

This chapter provides all of the reference and procedural information the user needs to (1) load, start, and run a DEC/X11 Configurator/Linker program and (2) effectively create a run-time exerciser (RTE) module for a specified device.

To accomplish the above, the user must have an adequate knowledge of the PDP-11 system for which the RTE module is intended (i.e., processor type, core size, device and vector addresses, priority levels, etc.). Such information is necessary prior to initiating the configuration process in order to both determine and specify which device/option modules and monitor program are needed to satisfy device test requirements.

3.2 EXERCISER BUILD PROCEDURES

The following material initially provides a procedural guide (with a pre-build check list) to the use of the build information contained in this section. The build information first defines the hardware, software, and reference documentation required to successfully construct a run-time exerciser program to user specifications. This is followed by descriptions of load, start, and run procedures as they relate to the DEC/X11 Configurator/Linker program and those PDP-11 devices currently available. The section concludes with a description of the keyboard commands and their procedural application to the configuration process.

3.2.1 Procedural Guide

In order to successfully construct an RTE program, a carefully evaluated pre-build planning phase must be initiated that is followed by a systematic application of the exerciser build procedures that are described in this section.

In this regard and as an aid to the inexperienced user of DEC/X11 software, the following material provides both a step-by-step guide to the planning and building of an RTE program and a subsection-by-subsection guide to the systematic use of the build procedures as they are contained in this section.

Step One: Initiate a Pre-Build Plan

In the pre-build planning phase, major elements of the hardware configuration to be tested are cross-referenced with appropriate DEC/X11 software elements (i.e., monitor and test modules) in order to prepare a formal listing of build requirements. This is done prior to selecting, loading, starting, and running the configurator/linker

program.
For details: refer to PRE-BUILD PLANNING and BUILD REQUIREMENTS, subsections 3.2.2 and 3.2.3.

Step Two: Build a Configuration Table (C-Table)

This step is entered with the configurator/linker program running and its repetoire of run-time commands available to the user. Under these conditions and to facilitate the next step in the build (i.e., the RTE linking process), the name of the monitor, each test module, and certain parameters that have all been derived from pre-build notations are entered in the Configuration Table (C-Table).

For details: refer to OPERATING PROCEDURES, CONFIGURE MODE COMMANDS, and THE CONFIGURATION TABLE (C-TABLE); subsections 3.2.4.2, 3.2.4.2.1 and 3.2.5.1.

Step Three: Initiate The Linking Process

In this, the last step of the build, the Link Command is formatted and executed to create an RTE file named by the user.

For details: refer to OPERATING PROCEDURES, LINKING PROCESS COMMAND, and THE LINKING PROCESS (LINK COMMAND), subsections 3.2.4.2, 3.2.4.2.2 and 3.2.5.2.

3.2.2 Pre-Build Planning

Pre-build planning consists of a careful determination of the elements required to properly test a given hardware system. This involves noting all of the major hardware components, options, and required parameters and cross-referencing these elements (via the DEC/X11 CROSS REFERENCE MANUAL) to derive a list that will associate the appropriate software with the hardware configuration. An example of such a list is shown in Figure 3-1.
Notice in figure 3-1 that a particular monitor (C) has been derived for a given processor (PDP-11/34) and its options while specific test modules have been derived (CPA, FBB, etc.) for both the processor and its associated devices. In addition, both default and specified parameters (DVA, VCT, etc.) are listed. With these considerations, the planning phase may be implemented as follows:

Step 1: Determine and note the major hardware components and options of the system, such as:

- The processor type and available options (e.g., KT, CACHE, etc.).

. The associated device(s) and available options (e.g., DUAL PORTS, etc.).

In addition, note the device addresses (DVA), vectors (VCT), priority levels (BR1, BR2), and the counts required to define the numbers of devices (DVC).

Step 2: Cross-referencing the DEC/X11 CROSS REFERENCE MANUAL with the information gathered in the previous step, implement the following:

. Determine the types of software (monitor and test modules) required to accommodate the hardware configuration and formally list the monitor type and modulenames.

. Next, formally list the parameters (default or specified) for and associated with each modulename, as follows:

(a) DVA (Device Address)
(b) VCT (Vector Address)
(c) BR1 (Buss Request Level 1)
(d) BR2 (Buss Request Level 2)
(e) DVC (Device Count)
(f) SR1-SR4 (Software Switch Register 1-4)

Step 3: Implement the configurator/linker phase.

SHEET 1 of 1

DEC/X11 System Configuration Worksheet

Selected DEC/X11 Monitor For Listed
CPU and CPU options: C

FILE: EXERR1.BIN DATE: 20 SEPT 78

DEVICE	MOD	R	DVA	VCT	BR1	BR2	DVC	SR1	SR2	SR3	SR4
KW11-A	KWA	A	177546*	100*	6*	0*	1*	4			
LS11/LV01	LPA	A	177514*	200*	4*	0*	1*	10000			
RX11/RX01	RXA	A	177170*	264*	5*	0*	2*				
TMB11/TS03	TMA	A	172520*	224*	5*	0*	1*				
RP11E/RP02	RPA	A	176710*	254*	5*	0*	2				
RK11-D/RK05	RKA	A	177400*	220*	5*	0*	1*				
RK611/RK06	RKB	A	177400*	210*	5*	0*	1*				
EIS	CPB	A									
11/34 Instr.	CPA	A									
FP11-A	FPB	A									

*SOFTWARE DEFAULTS

FIGURE 3 - 1
HARDWARE CONFIGURATION LISTING

3.2.3 Build Requirements

DEC/X11 programs are not self-loading. Therefore, loading depends on the medium employed (i.e., paper tape or non-paper tape). A DEC/X11 program is loaded from a paper tape device via a Paper Tape Loader (ABS) program, and from a non-paper tape device via an associated XXDP+ Monitor program, both of which are previously loaded by the manual insertion of a bootstrap program or the availability of a ROM bootstrap option. It must be noted, however, that the configurator/linker program is available only on XXDP+ media, and not on paper tape.

With these considerations, the following hardware, software, and documentation are required to construct a run-time exerciser load module.

3.2.3.1 Required Hardware

The following information lists hardware requirements for the DEC/X11 Configuration Program. These requirements are related to the basic differences encountered in the use of PDP-11 systems.

Common Hardware Requirements

- PDP-11 Processor
- Minimum memory capacity of 16K
- Console device (e.g., ASR33,35; VT05; etc.)
- ROM bootstrap Loader (e.g., BM792, MR11, M9301, etc.)

A ROM bootstrap loader is not required. However, the availability of this option facilitates the loading of an XXDP+ Monitor Program.

XXDP+ Requirements*

Dectape System:

A TC11 Dectape Controller and a TU56 Dual Dectape Transport.

Disk System:

An RK11 Controller and an RK05 Disk Drive.

----

*Note: These examples offer only a partial listing of supported media. For a complete listing refer to current XXDP+ documentation.

Floppy Disk System:

An RX11 Controller and RX01 Disk Drives.

Magtape Systems:

A TM11 Magtape Controller and two (2) TU10 Magtape Drives. If 2 drives are not available, the run-time exerciser must be directed to another medium.

3.2.3.2 Required Software

The version of the DEC/X11 software package to be used will depend on the hardware system employed. For example: if the run-time exerciser is to be built from paper tape, there will be separate tapes for each of the desired test modules and the monitor library. However, if an XXDP+ medium is used, the DEC/X11 software will reside on the media employed (i.e., Dectape, Disk, etc.), with each option module and the monitor library having a unique filename (i.e., .OBJ and .LIB extensions, respectively). But, since the configurator/linker program is available only on XXDP+ media, and not paper tape, the DEC/X11 software requirements for building an RTE file will be as follows:

- A device-associated XXDP+ monitor program
- DEC/X111 Configurator/Linker Program on XXDP+ medium
- DEC/X11 Monitor Library and option modules on paper tape or XXDP+ medium

3.2.3.3 Required Documentation

Documentation requirements are related to the reference material required to (1) select the desired device/option and monitor modules and (2) acquire the boot, load, and start procedures for the applicable paper tape or non-paper tape device. These requirements are as follows:

- The DEC/X11 Cross Reference Manual (MD-ZZ-CXQUB)
- The PDP-11 Paper Tape Software User's Manual
- The XXDP+ User's Manual

3.2.4 Configurator/Linker Program

The object of the configurator program is to link a user specified monitor with user specified option modules, thereby creating a run-time exerciser (RTE) module having a user defined .BIN or .BIC extension.

User selected device/option modules are relocatable-object-modules with a .OBJ extension that cannot be run independently. Therefore, they must be linked to a monitor that is extracted from a library having a .LIB Extension under the direction of the Configurator/Linker program to derive an RTE program for the testing of a specified system.

Table 3-1
Configurator/Linker Commands
and
Switch Symbols

NON-CONFIGURE MODE COMMANDS	PURPOSE
BOOT devl:	;Load XXDP+ Monitor from device ;specified.
CHECK devl:filnam.ext	;Check file for correct object ;format and Checksum.
CNF	;Initiate Configure Mode.
EXIT	;Return to XXDP+ monitor
GETC devl:filnam.ext	;Get Configuration Table from ;device specified.
LINK dev0:filnam.ext<devl:filnam.ext	;Link exerciser from device ;specified and output load ;module on directory device ;specified.
PRINTC	;Output Configuration Table on ;line printer.
PRINTM devl:filnam.ext	;Output the Load Map file ;on line printer.
SAVC dev0:filnam.ext	;Store Configuration Table on ;device specified.
SAVM dev0:filnam.ext	;Store the Load Map on ;device specified (following ;LINK DONE message).
TYPEC	;Output Configuration Table ;on console.
TYPEM devl:filnam.ext	;Output the Load Map file ;on console.

CONFIGURE MODE COMMANDS	PURPOSE
BR1 number	;Enter high-order byte priority ;level.
BR2 number	;Enter low-order byte priority

```
                                   ;level.

CL                                 ;Clear Configuration Table.

DVA addr                           ;Enter Device-Address (base
                                   ;address for device).

DVC number                         ;Enter Device Count (number
                                   ;of drives to select).

EX                                 ;Exit Configure Mode.

KI                                 ;Delete current Configuration
                                   ;Table entry.

MON                                ;Monitor change command.

MON name                           ;enter the specified monitor name
                                   ;in the configuration table.

MDL                                ;Output the header (module
                                   ;interface) contents of the
                                   ;current module entry.

MDL modulename                     ;Enter the specified modulename
                                   ;in the Configuration Table.

NXT                                ;Output the header (module
                                   ;interface) contents of the next
                                   ;(not current) module entry.

POINT modulename                   ;Output the header (module
                                   ;interface) contents of the
                                   ;specified module entry in the
                                   ;Configuration Table.

SR1 number                         ;Enter value in Software
                                   ;Switch Register 1.

SR2 number                         ;Enter value in Software
                                   ;Swtich Register 2.

SR3 number                         ;Enter value in Software
                                   ;Switch Register 3.

SR4 number                         ;Enter value in Software
                                   ;Switch Register 4.

VCT addr                           ;Enter Device-Vector-Address.

SWITCHES                                    PURPOSE
--------                                    -------

/MLP                               ;During LINK Command: print
```

	;map on line printer.
/MP	;During LINK Command: print ;map on console.
/NP	;During Configure Mode: inhibit ;operator prompts.

3.2.4.1 Load and Start Procedures

Depending on the input medium employed (i.e., paper tape or a non-paper tape medium currently supported by XXDP+) a configurator program will be loaded by either an absolute loader program (ABS) or an XXDP+ monitor.

3.2.4.1.1 Loading Via Absolute Loader

When a configurator program is contained on paper tape, the program is loaded into main memory via an absolute loader program (ABS). Once loaded, the configurator program is self-starting (refer to PDP-11 Paper Tape Software Handbook for ABS loading procedures).

3.2.4.1.2 Loading Via XXDP+ Monitor

When the configurator program resides on an input medium that is supported by XXDP+, it does so as a named file (see DECX11 cross-reference manual for file name). As such, the file may be loaded under control of the associated XXDP+ monitor.

When the XXDP+ monitor program is successfully loaded, the program identifies itself to the user, requests the date, generates a restart address, outputs a prompt character (.), and awaits an operator response. At this point the operator types the configurator file name (.R <filename>no extension), allowing the selected program to load and self-start (refer to XXDP+ User's Manual for monitor loading procedures).

3.2.4.1.3 Starting Procedures

When the selected configurator/linker program is successfully loaded, the program identifies itself to the user and then outputs a restart address and a Help query. In this regard, the following provides an example in which program requests are underlined and operator responses are not:

```
.R DXCL                 ;load/start program DXCL
-

CHUXC-? XXDP+ DECX11 CNF/LNK
----------------------------

                        ;program identity
RESTART: 006620         ;restart address
---------------

DO YOU WANT HELP? (Y<CR> OR JUST <CR>)
--------------------------------------
```

;Help query(std. only)

<CR> ;do not print Help list.

* ;prompt character for command.

In the example, the operator has chosen to ignore the Help query (by typing a <CR>). However, if a help-list is requested (by typing a Y<CR>), all available commands and switches (See Table 3-1) will be listed prior to the issuance of the command prompt(*).

When the asterisk is output, the configurator/linker program is ready to receive the keyboard commands that are required to build an exerciser program. However, if for some reason the user desires to restart the program (e.g., keyboard is inoperative), the operator may accomplish this by manually loading the Restart Address (in this case 006620) and depressing the START switch.

3.2.4.2 Operating Procedures

In Table 3-1, the Configurator/linker commands are listed alphabetically and divided into Non-Configure Mode and Configure Mode Commands. This emphasizes the fact that one group may only be used in Configure Mode while the use of the remaining commands is unrestricted.

In order to successfully create an RTE program, run-procedures must involve a systematic application of the keyboard commands. To better understand these applications, the commands are subdivided into four operational types: The first three types initiate and satisfy fundamental build requirements while the last consists of a single command that may be used, with discretion, to modify a selected location within the configurator linker program.

Under these conditions, the following material lists and generally describes the commands by operational type, concluding with a description of the switch options (i.e., /MLP, etc.) that may be used to modify and/or expand the operation of certain commands (i.e., the CNF and LINK Commands).

Type 1: Configure Mode Commands

The initiation of a Configure Mode of operation, via a CNF Command, allows the remaining commands in the group to effect the construction of a Configuration Table (C-Table), the contents of which is specified by the user for use in the configuration process (See Figure 3-1). The commands are as follows:

CNF ;Initiate Configure Mode

```
MON modnam            ;Enter monitor name
MDL                   ;Output current module entry
MDL modnam            ;Enter module name
DVA addr              ;Enter Device Address
VCT addr              ;Enter Vector Address
BR1, BR2 number       ;Enter priority levels
DVC number            ;Enter Device Count
SR1-SR4 number        ;Enter values in Software
                       Switch Registers
KI                    ;Delete current entry
POINT modnam          ;Output specified module entry
NXT                   ;Output next module entry
CL                    ;Clear C-Table
EX                    ;Exit Configure Mode
```

On entering Configure Mode, the CNF Command will automatically initiate a command prompt sequence to guide the user through the C-Table build procedure. However, the prompting sequence can be disabled by issuing a No Prompt (/NP) switch with the CNF Command.

For complete details on the functions of these commands refer to Subsection 3.2.4.2.1.

Type 2: Linking Process Command

The initiation of the linking process via a LINK Command causes the block by block assembly of the device/option modules with the selected monitor, as specified by the C-Table. The single command is as follows:

```
LINK devo:filnam.ext<devi:filnam.ext
         ;link and output RTE  module to device specified
```

Modules from the input device (devi) will be linked and delivered to the output device (devo) block by block.

For complete details on the function of the LINK Command refer to Subsection 3.2.4.2.2.

Type 3: Required I/O Control Commands

The initiation of these commands may occur in or out of the Configure Mode. The commands are used to control and direct the listing, storage, and retrieval of various files, in relation to both the construction and linking of an RTE program and the use of the I/O devices and storage media employed.

```
TYPEC                     ;Output C-Table on console
PRINTC                    ;Output C-Table on line printer
SAVC devo:filnam.ext      ;Store C-Table on device
GETC devi:filnam.ext      ;Get C-Table from device
```

```
SAVM devo:filnam.ext       ;Store Load Map on device
TYPEM devi:filnam.ext      ;Retrieve Load Map and output
                            on console
PRINTM devi:filnam.ex      ;Retrieve Load Map and output
                            on line printer
CHECK devi:filnam.ex       ;Check object module format
                            and Checksum
EXIT                       ;Return to XXDP+ monitor
BOOT dev:                  ;Reload XXDP+ Monitor
```

For complete details on the function of each of these commands refer to Subsection 3.2.4.2.2.

Type 4: General Utility Command (and Control C)

The initiation of the single utility command (MOD addr) may occur in or out of Configure Mode. The command may be used at the user's discretion to modify a specified configurator/linker location. It must be used in the format shown:

```
MOD addr          ;Open location for modification
```

For complete details of the function of this command, refer to Subsection 3.2.4.2.4.

Control C(^C) is a keyboard-feature rather than a command. Execution of this feature will abort any current operation.

Command Switches

There are three command switch options: two (/MLP, /MP) are used to expand and/or modify the operation of a Link Command (LINK), while one (/NP) is used to modify the operation of a Configure Mode Command (CNF).

Map-To-Line-Printer Switch (/MLP):

If the standard linker program is used, the /MLP switch may be added to the LINK command format to direct the output of a map to the line printer.

Example: *LINK DK0:TEST1.BIN<DK0:XMON??.LIB/MLP<CR>

Map-To-Console Switch (/MP):

For any version of the linker program, the /MP switch may be added to the LINK Command format to direct the output of a map to the console device.

Example: *LINK PT:<KB:/MP<CR>

No-Prompt Switch (/NP):

If the standard configurator program is used, the /NP switch may be added to the CNF Command to disable the output of operator prompts during the building of the C-Table.

Example: *CNF/NP<CR>

```
     !                              !
     !                              !
     !<------------WORD----------->!
     !                              !
     !                              !
     !              !               !
     !<--HI BYTE--->!<--LO BYTE--->!
     !              !               !
     !              !               !
     !------------------------------!
 0   !          MODULENAME          !
     !------------------------------!
 2   !              "               !
     !------------------------------!
 4   !              "               !
     !------------------------------!
 6   !        DEVICE ADDRESS        !
     !------------------------------!
10   !        VECTOR ADDRESS        !
     !------------------------------!
12   !     BR1      !      BR2      !
     !------------------------------!
14   !         DEVICE COUNT         !
     !------------------------------!
16   !   SPECIAL OPTIONS REG. 1     !
     !------------------------------!
20   !      "       "       "  2    !
     !------------------------------!
22   !      "       "       "  3    !
     !------------------------------!
24   !      "       "       "  4    !
     !------------------------------!
```

CONFIGURATOR TABLE
ENTRY

FIGURE 3-1

3.2.4.2.1 Configure Mode Commands

Using typical examples of program requests and operator responses, the following material describes both the formatting and usage of the CNF and Configure Mode Commands.

Notice that the command descriptions are arranged in the same order (i.e., CNF, MON, MDL, etc.) presented in the Operating Procedures (3.2.4.2). Also, to clarify usage, all program requests including the prompt character (*) are underlined while user responses are not.

Finally, following operator input, if an invalid command or inappropriate response is detected an error message will be output (Refer to Command Error Messages. 3.2.4.2.5).

Enter Configure Mode (CNF)

The CNF Command is used to initiate a Configure Mode of operation. If the C-Table is empty when CNF is entered the program will request a monitor name and if the name is accepted the program will issue a next-command prompt (*). At this point subsequent program requests will depend on whether the CNF Command was entered with or without a No-Prompt Switch (/NP).

If CNF is entered without the switch, a subsequent Enter Modulename Command (MDL name) will evoke nine successive requests for header parameters for the named module. When the prompting sequence is ended, the program will then output a summary. An example follows:

```
CNF without /NP:     *CNF<CR>
                     -
                     *MONITOR:  A<CR>
                     ---------
                     *MDL  WXYZ<CR>
                     -
                     DVA-  177540<CR>
                     ----
                     VCT-  203<CR>
                     ----
                     BR1-  5<CR>
                     ----
                     BR2-  5<CR>
                     ----
                     DVC-  2<CR>
                     ----
                     SR1-   <CR>
                     ----
                     SR2-  4000<CR>
                     ----
                     SR3-    <CR>
                     ----
                     SR4-    <CR>
```

```
WXYZ DVA-177540 VCT-000230 BR1-000240 BR2-000240 DVC-000003

SR1-000000 SR2-004000 SR3-000000 SR4-000000
```

Finally, if at any point the operator desires to discontinue the prompt, a Control C(^C) may be typed and prompting for the current module will end. However, any values already entered will be stored. Following this, a next-command prompt (*) will be printed and the operator may enter the next module name.

However, if CNF is entered with a No-Prompt Switch (/NP) added, the subsequent entry of a module name (MDL name) will not invoke a prompting sequence. An example follows:

```
CNF with /NP:      *CNF/NP<CR>

                   *MONITOR:  B<CR>

                   *MDL  QRST<CR>

                   *DVA  177530<CR>

                   *VCT  230<CR>

                         (etc.)
```

However, if at any time the operator desires to re-initiate a prompting sequence, the operator can simply type a CNF without leaving Configure Mode and prompting will begin when the next MDL Command is entered.

Monitor Change Command (MON)

The MON Command may be used to change the monitor entry as follows:

```
*MON name <CR>
```

Output Current Module Entry (MDL)

The MDL Command (no name argument) allows a summary of the current module entry to be output as follows:

```
*MDL  CR

WXYZ  DVA-000000 VCT-000000 BR1-000000 BR2-000000 DVC-000000
```

SR1-000000 SR2-oooooo SR3-000000 SR4-000000

The above indicates that Module WXYZ has been entered and its parameters are zeros.

Enter Module Name (MDL name)

The MDL Command (with name argument) is used to enter a specified module name in the first available slot in the C-Table, as follows:

```
*MDL WXYZ<CR>
-
```

The name entered must be a valid four-character modulename which defines the following:

- WX: A two-character device/option name
- Y: A specific module (since others may exist for the same device/option).
- Z: The version level of the module specified.

NOTE: If the version level is unknown, a "?" may be used as the fourth character of the module name when entering a module into the C-table. During the execution of the "LINK" command all ?'s in the C-table will be replaced by the proper version letters.

Since, under certain conditions, the MDL name Command can invoke a prompting sequence (for the entry of module-header paramters), refer to the information contained in the Enter Configure Mode (CNF) description.

Enter Device Address (DVA)

The DVA Command is used to enter a device address parameter into the current module entry. Only an even address may be entered:

```
*MDL WXYZ<CR>                 ;WXYZ is current module entry
-

*DVA 177600<CR>               ;Enter DVA parameter (177600)
-

*MDL<CR>                      ;Output current module entry
-
WXYZ  DVA-177600 VCT-000200 BR1-000000 BR2-000000 DVC-000000
------------------------------------------------------------
```

In the example, the summary is incomplete (SR1-SR4 is omitted). However, it shows that the DVA parameter has been filled.

In general, a DVA Command must be used whenever the DEC/X11 CROSS REFERENCE MANUAL indicates that a desired module does not provide a device address (by default) or that the address provided is non-standard in relation to the actual device employed (e.g., a second RP11 Disk or TM11 Magtape Controller).

Enter Vector Address (VCT)

The VCT Command is used to enter a device vector address parameter into the current module entry. Only an even octal address (774 max.) may be entered.

```
*VCT 200<CR>                    ;Enter VCT address of 200
-

*MDL<CR>                        ;Output current module entry
-
WXYZ  DVA-177600 VCT-000200 BR1-000000 BR2-000000 DVC-000000
------------------------------------------------------------
```

In the example, the summary is incomplete. However, it shows that a vector address has been added to the current module entry.

In general, a VCT Command must be used whenever the DEC/X11 CROSS REFERENCE MANUAL indicates that a desired module does not provide a vector address (by default) or that the vector provided is at a non-standard address.

Enter Priority Levels (BR1, BR2)

The BR1 and BR2 Commands are used to enter high-order byte (BR1) and low-order byte (BR2) priority level parameters into the current module entry. Only an octal value (7 max.) may be entered.

```
              *BR1 6<CR>              ;Enter PRTY6 parameter
              -

              *BR2 4<CR>              ;Enter PRTY4 parameter
              -

              *MDL <CR>               ;Output current module entry
              -

WXYZ  DVA-177600 VCT-000200 BR1-000300 BR2-000200 DVC-000000
------------------------------------------------------------
```

In the example, the summary is incomplete. However, it shows that the

BR1 and BR2 levels have been converted by the program into Processor Status Word (PSW) equivalents.

In general, BR1 and BR2 Commands must be used whenever the DEC/X11 CROSS REFERENCE MANUAL indicates that a desired module does not provide priority levels (by default) or that the levels provided are non-standard in relation to the device employed.

Enter Device Count (DVC)

The DVC Command is used to enter a decimal number (16 max.) to define the number of sub-devices (e.g., drives) or multiple devices (e.g., 8DL11s) to be tested by the module. It should be noted that the number entered must equal the actual number of devices to be consecutively tested:

```
    *DVC 5<CR>                    ;Enter device count of five
    -

    *MDL<CR>                      ;Output current module entry
    -

WXYZ  DVA-177600 VCT-000200 BR1-000300 BR2-000200 DVC-000037
------------------------------------------------------------
```

In the example, the summary is not complete. However, it shows that the decimal device count (5) has been converted to an octal number (37) which, in turn, represents a binary-bit-map. The weight of each consecutive One-bit contained in the map (011 111 binary) then effectively represents the logical number of each device (i.e., 0-4) consecutively arranged for testing:

```
0 0   0   0   3   7
0 000 000 000 011 111  Binary Bit Map
               !! !!!    \
               !! !!!---0 !
               !! !!      !
               !! !!----1 !
               !! !       \ 5-Devices
               !! !-----2 /
               !!         !
               !!-------3 !
               !          !
               !--------4 !
                          /
```

Moreover, consecutive testing of multiple devices is mandatory. Thus the bit-map must have consecutive One-bits which equate with the number of devices on a one-for-one basis. In the same vein, multiples must be accessed by consecutive device addresses (whether ascending or descending) following the first device-address. Thus, no addressing holes are permitted.

Software Switch Registers (SR1-SR4)

The SR1 through SR4 Commands are used separately to enter individual octal values into the Software Switch Registers for the current module entry. Values must be entered as directed by the DEC/X11 CROSS REFERENCE MANUAL to modify the execution of a module, thus accommodating any standard, optional, and/or special features that may be available to a device.

```
*SR2 4000<CR>                  ;Set Bit 11 in Sft. Sw. Reg. 2.
-

*MDL<CR>                       ;Output current module entry.
-

WXYZ  DVA-177600 VCT-000200 BR1-000300 BR2-000200 DVC-000037
------------------------------------------------------------

      SR1-000000 SR2-004000 SR3-000000 SR4-000000
      --------------------------------------------
```

In the example, Bit 11 in Software Switch Register 2 has been set to provide a flag for a device feature: the line printer to be used has 132 columns (instead of 80) and Bit 11 (set) is the indicator.

Delete Current Entry (KI)

The KI Command is used to delete the current module entry (including all its associated parameter values) from the C-Table:

```
*KI<CR>            ;Kill the last entry referenced
-
```

When a module entry is deleted in this manner, subsequent requests for a summary of the C-Table (via a TYPEC or PRINTC Command) will cause the output of an Empty Indicator (<EMPTY>) message for the deleted entry.

Search and Output Specified Entry (POINT)

The POINT Command is used to initiate a search through the C-Table from the current module entry position for a specified module.

```
*POINT WXYZ<CR>                ;Search, from last referenced entry,
-                              ;for Module WXYZ. If found, output
                               ;content.
```

If the desired module name is found, the contents of the entry is output. Conversely, if the desired entry is not found, a message (? INVALID NAME) is output.

Output Next Module Entry (NXT)

The NEXT Command is used to output the contents of the module entry that directly follows the last referenced entry (i.e., the current entry). If a next-entry does not exist, an asterisk (*) will be output.

```
*NXT<CR>                      ;Output contents of next module entry
-                             ;(if existent).
```

Clear C-Table (CL)

The CL Command is used to initiate a clear of the entire Configuration Table. When the C-Table is cleared, a monitor prompt request is issued by the program (as in the CNF Command).

```
*CL<CR>                       ;Clear entire C-Table
-
*MONITOR:  name               ;Enter monitor name
---------
```

Exit Configure Mode (EX)

The EX Command is used to exit from the Configure Mode of operation when the construction of a C-Table is completed. Re-entry is via a CNF Command. If re-entry is made, the availability of a valid monitor entry negates the need for a monitor request. Thus, the program merely points to the first module entry in the C-Table and outputs a command prompt (*).

```
*EX<CR>                       ;Exit Configure Mode
-
*CNF<CR>                      ;Re-enter Configure Mode
-
*                             ;Enter Command prompt
-
```

3.2.4.2.2 Linking Process Command

Following an exit from the Configure Mode, the linking process (as briefly described in the Operating Procedures subsection, 3.2.4.2) may be initiated via the formatting of the LINK Command. From a general format, the command may be applied in one of two ways: (1) for non-directory devices (e.g., paper tape, magtape, etc.) or (2) for directory devices (e.g., disk, dectape, etc.) as follows:

General Format: LINK devo:[filnam.ext]<devi:[filnam.ext]

(If devo or devi is omitted, the default is the system device.)

1. LINK devo:<devi:

   The non-directory device format requires that only the I/O devices (i.e., devi/devo) be specified. During execution, the required paper tapes for the monitor and option modules will be requested via a prompt sequence.

2. LINK devo:filnam.ext<devi:LIBNAM.LIB

   The directory device format requires that, along with the I/O devices, the file name of the monitor library input (LIBNAM.LIB) must be specified while the RTE output must be specified by a file name devised by the user (FILNAM.BIN or FILNAM.BIC). For .BIC extensions refer to XXDP+ chain mode operations. During execution, the monitor and option modules are automatically selected.

In either case, the LINK Command allows the monitor and option modules to be extracted from the input device (devi) for linking as defined by the current C-Table, thus producing an executable RTE program for delivery to the output device (devo). Once the RTE module is output, a completion message follows (LINK DONE) and the program returns to command mode (*). However, prior to termination, a Load Map may be invoked by including in the command a Load Map To Line Printer (/MLP) or Load Map To Console (/MP) switch. Two typical examples of LINK Command usage (non-directory and directory) follow, in which all program requests for user response are underlined. However, prior to analyzing the examples, the reader should note the following possibility: If, during the processing of the LINK Command (also SAVM and SAVC Commands), the output file specified in the format already exists on the specified medium, the program will query the operator as to whether or not the old file should be deleted with the following message:

DELETE OLD?(Y <CR> OR JUST <CR>)

If an affirmative answer is entered (Y <CR>), the old file will be deleted, the LINK command will be processed, and the new file will be output. If the operator enters a negative response (<CR>), the old file will not be deleted and the LINK Command will not be processed. Instead, a message (? USE NEW FILE NAME) will be output, and a new prompt will be typed.

Non-Directory Device Format

In the following example, the object module tapes are input from a TTY-reader (KB), while the completed RTE module is output on paper tape via the TTY-punch (PT).

```
*LINK PT:<KB: <CR>                ;Link Command format
-
SYS SIZE:  160000 <CR>            ;RTE memory requirement
---------
MAKE OUTPUT READY. WRITE ENABLE  ;enable output device
-------------------------------
TYPE(CR) WHEN READY <CR>          ;acknowledge enable
-------------------
PASS 1                            ;scan all modules
------
ANYMORE MONITOR PAPER TAPES, CASSETTES, ETC.? (YES,NO)
------------------------------------------------------
                                  ;monitor tape request
YES <CR>                          ;acknowledge tape
RELOAD INPUT WITH NEXT PAPER TAPE, CASSETTE, ETC.
-------------------------------------------------
                                  ;next monitor tape request
TYPE(CR) WHEN READY <CR           ;acknowledge tape
-------------------
ANYMORE MONITOR PAPER TAPES, CASSETTES, ETC.? (YES,NO)
------------------------------------------------------
                                  ;acknowledge tape
NO <CR>                           ;acknowledge tape
WXYZ SHOULD BE NEXT!              ;Mod. WXYZ tape request
--------------------
TYPE(CR) WHEN READY <CR>          ;ack. test module tape
-------------------
TRANSFER ADDRESS:  002200         ;start address for RTE
-------------------------
LOW LIMIT:  000000                ;RTE base address
------------------
HIGH LIMIT  045302                ;RTE end address
------------------
PASS 2                            ;link and output RTE module
------
INPUT TAPES, CASSETTES, ETC. IN SAME SEQUENCE AS IN PASS 1
----------------------------------------------------------
                                  ;tape requests
TYPE(CR) WHEN READY <CR>          ;acknowlege tape
-------------------
ANYMORE MONITOR PAPER TAPES, CASSETTES, ETC.? (YES,NO)
------------------------------------------------------
                                  ;monitor tape request
YES <CR>                          ;acknowlege tape
RELOAD INPUT WITH NEXT PAPER TAPE, CASSETTE, ETC.
-------------------------------------------------
                                  ;next monitor tape request
TYPE(CR) WHEN READY <CR>          ;acknowlege tape
-------------------
```

```
     WXYZ SHOULD BE NEXT!            ;Mod. WXYZ tape request
     --------------------
     TYPE(CR) WHEN READY <CR>        ;ack. test module tape
     -------------------
     LINK DONE                       ;link process completed
     ---------
```

Once the LINK Command is entered, the program initially requests the memory size of the target system (i.e., the size of the actual system on which the resultant RTE will be run). In response, the operator must enter one of the following octal numbers:

If size is:	Enter:
4K	20000
8K	40000
12K	60000
16K	100000
20K	120000
24K	140000
28K and greater	160000

The program then enters the first phase (PASS 1) of the linking process in which the monitor and test module tapes are requested in the same order defined in the C-Table. In pass 1 the program performs a partial read of the requested tapes, to ascertain the final structure of the RTE module. In the second phase (PASS 2) the same tapes are again requested and read in their entirety to cause the actual linking and output of the RTE module.

Finally, if either the Load Map To console (/MP) or Load Map To Line Printer (/MLP) switch is used with the LINK Command, the address limits of the RTE (i.e., TRANSFER ADDRESS, LOW LIMIT, HIGH LIMIT) will not be printed during the first phase (PASS 1).

Directory Device Format

In the following example, the object modules are automatically selected as input from an RK11 (Disk Drive Zero), linked as defined by the C-Table, and output as an RTE module to the same drive.

```
*LINK DKO.TEST1.BIN<DK0:XMON??.LIB  <CR>  ;Link Command entry
-
SYS SIZE:  160000  <CR>                   ;RTE memory requirement
---------
MAKE OUTPUT READY. WRITE ENABLE           ;enable output device
-------------------------------
TYPE(CR) WHEN READY  <CR>                 ;acknowlege enable
-------------------
PASS 1                                    ;scan for all modules
------
TRANSFER ADDRESS:  002200                 ;start address for RTE
-------------------------
```

```
LOW LIMIT:  000000                       ;RTE base address
------------------
HIGH LIMIT:  063514                      ;RTE end address
-------------------
PASS 2                                   ;output RTE module
------
LINK DONE                                ;link process completed
---------
```

As previously stated, if a Load Map To Console Switch (/MP) or Load Map To Line Printer Switch (/MLP) is included with the LINK Command, the address limits of the RTE will not be printed during the first phase (PASS 1).

3.2.4.2.3 I/O Control Commands

As stated in the Operating Procedures (subsection 3.2.4.2), the I/O Control Commands may be used in or out of Configure Mode to allow: (1) certain information to be listed, stored, and retrieved (e.g., C-Table and Load Map data); (2) control to be returned to the XXDP+ monitor (the monitor is not reloaded); or (3) the XXDP+ Monitor to be reloaded. Examples of the formatting and usage of these commands follow, with program response being underlined for clarity.

Output C-Table On Console (TYPEC)

The TYPEC Command is used to list the entire contents of the C-Table on the console.

```
        *TYPEC<CR>                       ;Output C-Table on console
        -
```

Output C-Table On Line Printer (PRINTC)

The PRINTC Command is used to list the entire contents of the C-Table on the line printer.

```
        *PRINTC<CR>                      ;Output   C-Table   on   line
printer.
        - Save The C-Table (SAVC)
----------------------
```

The SAVC Command is used to store a copy of the current C-Table on either a non-directory (e.g., paper tape) or directory (e.g., disk) medium for subsequent modification or reuse. To serve these ends, the command utilizes a general format in which the filename argument is only required for directory devices.

General Format: SAVC dev0:[filnam.ext]

(If devo is omitted, the default is the system device.)

Non-directory device example: In the following example, the C-Table will be output on paper tape via a High-Speed Punch (PP).

```
*SAVC PP:<CR>                    ;Store current C-Table on paper tape.
```

Directory device example: In the following example, the C-Table will be output on Disk Drive Zero (DK0) under a file name specified by the user (CNF1.CNF).

```
*SAVC DK0:CNF1.CNF<CR>           ;Store current C-Table on Disk
                                 ;Zero as file CNF1.CNF.
```

If, during the processing of a SAVC Command, the output file already exists on the specified medium, the program will query the operator as to whether or not the old file should be deleted, with the following message:

DELETE OLD?(Y <CR> OR JUST <CR>)

If an affirmative answer is entered(Y <CR>), the old file will be deleted, the command processed, and the new file output. If the operator enters a negative response (<CR>), the old file will not be deleted and the command will not be processed. Instead, a message (? USE NEW FILE NAME) will be output and a new prompt will be typed.

Get the C-Table (GETC)

The GETC Command is used to retrieve a previously stored copy of the C-Table, from either a non-directory (e.g., paper tape) or directory (e.g., disk) medium, for modification via the Configure Mode Commands (refer to subsection 3.2.4.2.1) for reuse. The command utilizes a general format in which the filename argument is only used for directory devices. Moreover the command restores the table to the proper memory space regardless of format.

General Format: GETC devi:[filnam.ext]

(If devi is omitted, the default is the system device.) Non-directory device example: In the following example, the C-Table is returned to memory from paper tape via the High-Speed Reader (PR).

```
*GETC PR:<CR>                    ;Return C-Table via High-Speed Reader
```

Directory device example: In the following example, the C-Table is located on Disk Drive Zero (DK0) under the specified file name

(CNF1.CNF) and returned to memory.

```
        *GETC DK0:CNF1.CNF<CR>        ;Return C-Table file  CNF1.CNF
to
                                      ;memory from Disk Zero.
```

Save The Load Map (SAVM)

The SAVM Command is used to store a copy of the Load Map, generated during a LINK Command, on either a non-directory (e.g., paper tape) or directory (e.g., disk) medium. If used, this command must be entered directly following the LINK DONE message. The command utilizes a general format in which the filename argument is only required for directory devices.

General Format: SAVM devo:[filnam.ext]

(If devo is omitted, the default is the system device.)

Non-directory device example: In the following example, the Load Map will be output on paper tape via a TTY-punch (PT).

```
        SAVM PT:<CR>                  ;Store Load Map on paper tape
```

Directory device example: In the following example, the Load Map will be output on Disk Drive One (DK1) under a file name specified by the user (LMP1.MAP).

```
        *SAVM DK1:LMP1.MAP<CR>        ;Store Load Map on Disk One
                                      ;as file LMP1.MAP.
```

If, during the processing of a SAVM Command, the output file already exists on the specified medium, the program will query the operator as to whether or not the old file should be deleted, with the following message:

DELETE OLD?(Y <CR> OR JUST <CR>)

If an affirmative answer is entered(Y <CR>), the old file will be deleted, the command processed, and the new file output. If the operator enters a negative response (<CR>), the old file will not be deleted and the command will not be processed. Instead, a message (? USE NEW FILE NAME) will be output, and a new prompt will be typed.

Retrieve Map and Output On Console (TYPEM)

The TYPEM Command is used to retrieve a previously stored copy of the Load Map, from either a non-directory (e.g., paper tape) or directory (e.g., disk) medium, for output on the console. The command utilizes a general format in which the filename argument is only required for directory devices.

General Format: TYPEM devi:[filnam.ext]

(If devi is omitted, the default is the system device.)

Non-directory device example: In the following example, the Load Map is returned to memory from paper tape, via a TTY-reader (KB), and output on the console.

```
*TYPEM KB:<CR>                  ;Return Load Map and output on
-
                                ;console
```

Directory device example: In the following example, the Load Map file (LMP1.MAP) is returned to memory from RK11 Disk Drive One (DK1) and output on the line printer.

```
*TYPEM DK1:LMP1.MAP<CR>         ;Return Load Map from Disk
-
                                ;One and output on console.
```

Retrieve Map and Output On Line Printer (PRINTM)

The PRINTM Command is used to retrieve a previously stored copy of the Load Map, from either a non-directory (e.g., paper tape) or directory (e.g., disk) medium, for output on the line printer. The command utilizes a general format in which the filename argument is only required for directory devices.

General Format: PRINTM devi:[filnam.ext]

(If devi is omitted, the default is the system device.)

Non-directory device example: In the following example, the Load Map is returned to memory from paper tape via a High-Speed Reader (PR) and output on the line printer.

```
*PRINTM PR:<CR>                 ;Return Load Map and output on
-
                                ;line printer.
```

Directory device example: In the following example, the Load Map file (LMP1.MAP) is returned to memory from Floppy Disk Drive Zero (DX0) and output on the line printer.

```
*PRINTM DX0:LMP1.MAP<CR>        ;Return Load Map from Disk
Zero
-
                                ;and output on line printer.
```

Check Object Module (CHECK)

The CHECK Command is used to examine an object module, from either a non-directory (e.g., paper tape) or directory (e.g., disk) device, for proper formatting and/or a Checksum error. The command utilizes a general format in which the filename argument is only required for directory devices.

General Format: CHECK devi:[filnam.ext]

(if devi is omitted, the default is the system device.)

Non-directory device example: Input module for check from paper tape High-Speed Reader (PR).

```
        *CHECK PR:<CR>                ;Check object module format
and
        -
                                      ;Checksum
```

Directory device example: Input module file (XRKAG0.OBJ) for check from RK11 Disk Drive Zero (DK0).

```
        *CHECK DK0:XRKAG0.OBJ<CR>     ;Check object module file for
        -
                                      ;proper format and checksum.
```

Return to XXDP+ Monitor (EXIT)

The EXIT command is used to leave the configurator/linker program and return to the XXDP+ monitor. This command does not clear the configurator/linker program from memory and does not reload the XXDP+ monitor.

```
        *EXIT                         ;Return to the
        -;                            ;currently-loaded
                                      ;XXDP+ monitor
```

Reload XXDP+ Monitor (BOOT)

The BOOT Command is used to reload the XXDP+ Monitor associated with the system.

```
        *BOOT MT0:<CR>                ;Load the TMDP Monitor from
        -
                                      ;Magtape Drive Zero.
```

3.2.4.2.4 General Utility Command

The Modify Command (MOD addr) may be used in or out of the Configure Mode for the examination and/or modification of a specified location within the configurator/linker program. The format is as follows:

```
MOD addr              ;Output the contents of the location
                      ;specified by the absolute address
                      ;argument (addr).
```

The following provides an example of the use of the Modify Command:

```
*MOD 4000<CR>         ;open location 4000
- Program response:

004000/123456         ;location 4000 contains value
                      ;123456
```

Operator response:

1. Close location 4000 by typing <CR>.

2. Insert new value and close location 4000 by typing <CR>.

3. Insert new value and open next word by typing <LF>.

4. Close location 4000 and open next word by typing <LF>.

3.2.4.2.5 Command Error Messages

The Configurator/Linker program will generate error messages to indicate that an error has occurred during the RTE build procedure. Some examples of these errors are: (1) the improper formatting and/or use of a command; (2) improper C-Table construction; (3) possible file errors; (4) possible device errors (5) memory range and allocation errors; (6) programming and/or program errors. The following provides a listing of each error message and its purpose:

? INVALID COMMAND

An invalid command has been entered; correct and re-enter.

? INVALID NAME

An invalid name has been used in a command format or as a response to a program request (e.g., special characters are not allowed); correct and re-enter.

? NUMBER TOO BIG

The number typed in response to a program request is larger than is allowed for the requested parameter. For example, the device count in the C-Table must not exceed decimal 16; vector addresses must not exceed octal 774, etc.; correct and re-enter.

? INVALID SWITCH

An invalid switch has been used with a command (if command will accomodate a valid switch) or a switch has been included with a command that does not accomodate switches.

? CHECKSUM ERROR

A Checksum error has occurred during the reading of a binary formatted block.

FILNAMEXT? NON-EXISTANT FILE

THE file named FILNAM.EXT, which has been specified in the command format which does not in fact exist on the employed medium; correct and re-enter.

? END-OF-MEDIUM

This message indicates that the end of an input medium has been reached (e.g., EOT), and can occur as the result of an unsuccessful block search within a file (e.g., EOF).

? PROGRAM OVERFLOW

This message indicates that the block size of the input file is greater than the size of the input buffer.

? NOT IN CNF MODE

This message indicates that a Configure Mode Command (e.g., DVA, VCT, BR1, etc.) has been illegally entered in non-configure mode; re-enter

Configure Mode (i.e., CNF<CR>) and re-enter command.

? MUST BE OCTAL

The number typed in response to a program request was not octal and should have been.

? NO ROOM FOR A DRIVER

The device driver specified in the command cannot be placed in the driver buffer.

? CNF TABLE FULL

This message indicates that the maximum number of entries (i.e., 20 or 40) have been made in the Configuration Table.

? COR EXCD

This message indicates that during the linking process (refer to subsection 3.2.4.2.2) the range of the RTE program exceeds the core size of the system for which it is being generated.

? SYMBOL TABLE OVERFLOW

During pass 1 of the linking process, the symbol table has used up all available memory space; use a system with a larger memory.

? USE NEW FILE NAME

A file name specified in the command already exists; use another name or delete the old file.

? DEVICE FULL

There is no more room available on the specified output device.

? READ ERROR

An error was encountered while attempting to read from the specified input medium.

? WRITE ERROR

An error was encountered while attempting to write onto the specified output medium.

(ERR01) Symbol Table Error

The program has detected an error in the Symbol Table during the linking process.

(ERR02) Global Search Error

A global search in the Relocation Directory (RLD) has failed during the linking process.

(ERR03) No PC Mod Command

The Relocation Directory (RLD) does not contain a Program Counter (PC) modification command. Program error has been detected during linking process.

(ERR04) GSD Block Missing

A Global Symbol Directory (GSD) block has not been found at the start of the object module. This could be a program error detected during the linking process. However, if paper tape is the input medium, the tape could have been loaded backwards.

(ERR05) Module Name Missing From GSD

The first entry in the Global Symbol Directory (GSD) is not an object module name. This could be a program error detected during the linking process. However, if paper tape is the input medium, the wrong tape could have been loaded.

(ERR06) Section Name Missing

A Section Name, specified by the Relocation Directory (RLD), cannot be found; program error.

(ERR07) Can't Find Module Name In Symbol Table

A module name is missing from the symbol table. Possible reason is an option module's filename does not match the name in the header.

(ERR09) Jump Table Index Error

The Jump Table index value exceeds the required range (i.e., the GSD code byte is too large); program error.

(ERR12) Load Module Error

The program detected an error during the writing of the RTE load module on the output medium.

3.2.5 Generating A Run-Time Exerciser Module

The following provides a brief summary of the configuration and linking process in regard to: (1) construction and/or modification of the C-Table, (2) execution of the Link Command, and (3) generation of the RTE module. The text includes references to certain configurator/linker commands but does not provide detailed descriptions related to formatting and usage. For such information the reader may refer to the material available under Operating Procedures (3.2.4.2) for the configurator/linker program.

3.2.5.1 The Configuration Table (C-Table)

The use of the C-Table facilitates the linking process, and simplifies the formatting of the LINK Command, by providing an easily accessible area for option module and monitor data.

The C-Table accommodates a maximum of 40 entries (i.e., 39 option modules and one monitor entry) with each entry accommodating eleven words (See Figure 3-1).

The construction of a C-Table may begin when the configurator/linker program is loaded and a Configure Mode of operation is initiated via the entry of a CNF Command.

Clearing the C-Table

If the C-Table is empty when CNF is entered, the program will request a monitor name and the user may initiate a new build. However, if the table is not empty, the program assumes that the user intends to modify existent entries and a request for a monitor name will not be made. Therefore, if the C-Table is not empty and a new build is desired, the table must be initially cleared by entering a CL Command.

Current Entry Pointer

As a build proceeds, the configurator program adjusts a pointer to specify the current module entry (i.e., the entry effected by the last MDL name Command). Thus, as each parameter entry command (e.g., DVA, DVC, etc.) is used, it only affects the content of the module so specified. Under these conditions, a current entry may be deleted by entering a KI Command without affecting the location of the pointer.

Finally, two additional Configure Mode commands (i.e., NXT and POINT name Command) can be used to affect the location of the pointer if the modification of a filled C-Table is in progress. Respectively, the commands will adjust the pointer to the next entry (if it exists) or to a specified entry and output the contents of the entry.

Listing and Saving the C-Table

To obtain a console listing of the completed C-Table, the TYPEC Command is used. A line printer listing is obtained by entering a PRINTC Command. These commands may be entered in or out of Configure Mode.

The completed C-Table can be saved under a file name by entering a SAVC Command. The file may then be retrieved by entering a GETC Command. These commands may also be issued in or out of Configure Mode.

3.2.5.2 The Linking Process (LINK Command)

The LINK Command pieces together a Run-Time Exerciser (RTE) program by linking all of the required monitor modules and all of the requested option modules to produce a single executable binary file.

Processing Phases

The linking process consists of two phases which the linker defines for the user as PASS 1 and PASS 2. During Phase One, only a portion of each monitor module and each option module is read to memory for an initial evaluation (e.g., global references are identified and evaluated). During Phase Two, the remaining portions of each module are also read to memory, absolute addresses are assigned, and the RTE module is produced as a single output file.

Processing Phase One (PASS 1)

When a LINK command is entered, the eventual execution of Phase One is indicated to the user by the typing of PASS 1. During this phase, the linker examines the C-Table to determine which monitor has been requested by the user. The program then searches the monitor library to determine which monitor modules are required to satisfy the request. As the appropriate modules are read, Phase One processing is separately performed for each one.

If the monitor library resides on a directory device (non-paper tape) the linker can automatically reference the library's modules. If the library resides on paper tapes, the user must mount the first library tape on the reader to start the process. When the linker has completed processing the first tape the user will be prompted to load the next tape and all subsequent tapes that may be required.

When Phase One processing of the monitor modules is completed, the linker will again examine the C-Table to determine which option modules have been requested by the user for processing.

If the option modules reside on a directory device, the linker processes each module automatically. If the modules are contained on paper tapes, the user will be specifically prompted to load each tape.

At this point it is important to note that since only a small portion of any paper tape will be read during Phase One, the user should not misconstrue this to be a malfunction, unless of course the program fails to request a tape.

When Phase One is completed, the address range of the RTE module is printed. However, if either a map-to-console (/MP) or map-to-line-printer (/MLP) switch is included with the LINK Command, a load map will be printed instead followed by a PASS 2, the latter indicating that Phase Two of the linking process has been initiated.

Processing Phase Two (PASS 2)

Using the information stored in the C-Table and that derived during the Phase One module scan, the general structure of the final RTE module has been determined when Phase Two is entered. Thus, in Phase Two, the actual linking process will be initiated.

Phase Two begins with the block-by-block transfer to memory from the monitor library of each of the monitor modules. As each individual block of the monitor modules is read, it is subjected to Phase Two Processing, and separately output as a portion of the RTE module, continuing until the monitor modules are processed in their entirety. Again, if the monitor library is contained on paper tapes, the user must load each tape on request. Similarly, each entire test module is read, and if contained on paper tapes, similarly requested. In this manner the linker outputs the test module portions of the RTE to the specified medium until the build is complete, at which time the program generates a completion message (LINK DONE).

3.2.3.3 The Run-Time Exerciser (RTE)

The completed exerciser load module is a binary file configured in Absolute Loader (ABS) format. As such, the configured module may be output on paper tape or on another type of load medium as a named file. Considering the medium employed, an RTE module will either be loaded via a paper tape ABS Loader or under the control of an associated XXDP+ monitor.

3.3 RUN-TIME EXERCISER PROCEDURES

Run-Time Exerciser (RTE) programs are not self-loading. Therefore, loading depends on the input medium employed (i.e., paper tape or non-paper tape): An RTE program is loaded from a paper tape device via a Paper Tape Loader (ABS) program, and from a non-paper tape device via an associated XXDP+ monitor program. The loader programs are themselves loaded by the manual insertion of a bootstrap program or the availability of a ROM bootstrap option.

With these considerations, the following information initially provides a listing of the hardware and software required to successfully load, start, and operate an RTE program. This is followed by procedural information which includes an extensive analysis of the available keyboard commands and message print-outs.

3.3.1 Hardware And Software Requirements

Depending on the load medium employed, the following hardware and software are required to load, start, and run an RTE program. Common Hardware Requirements
----

- PDP-11 Processor
- Minimum memory capacity of 12K
- Console device (e.g., ASR33,35; VT05; etc.)
- ROM bootstrap loader (e.g., M9301, etc.)

A ROM bootstrap loader is not required. However, the availability of this option facilitates the loading of an ABS loader program for paper tape or the loading of an XXDP+ monitor program.

Paper Tape Hardware

Either: A PC11 High Speed Reader/Punch

or: A Teletype (ASR33 or ASR35)

XXDP+ Hardware

Any type of device that is currently supported by XXDP+ (refer to XXDP+ User's Manual).

Software Requirements

For paper tape systems:

- The ABS Loader Program
- The DEC/X11 RTE Paper Tape

For non-paper tape systems:

- The device associated XXDP+ monitor program
- The DEC/X11_RTE file on an associated XXDP+ medium.

3.3.2 Load And Start Procedures

Depending on the input medium employed, a configured exerciser program (RTE) is loaded and started as follows: 3.3.2.1 Load/Start Via Absolute Loader

When an RTE program is contained on paper tape, the module is loaded into main memory via an Absolute Loader (ABS) program. Once loaded, the user starts the program at address 0200 and may restart the program at address 1000. When the program starts it identifies itself to the user, specifies the memory capacity of the system, and indicates the availability of certain optional features (i.e., memory management, parity memory, etc.). Available features are turned on (default condition) as follows:

```
DEC/X11 EXERCISER
-----------------
     (MONITOR V00.00) MD-XX-XXXXX-X  ;Identity of RTE program
```

```
    ----------------

MONITOR:  C                           ;Monitor Identity
-----------

SYSTEM SIZE:  00016 K                 ;Memory capacity of system
---------------------

WRITE BUFFER ROTATION ON              ;Write Buffer Rotation is On
------------------------

KT ON                                 ;Memory Management is On
-----

LD MEDIA TSTING CLR LOC.  40          ;Clear loc.  40 if load
----------------------------
                                      ;device is to be tested.
CMD>                                  ;RTE keyboard command prompt
----
```

3.3.2.2 Loading Via XXDP+ Monitor

When an RTE program resides on an XXDP+ supported medium, it resides as a named file with a .BIN or a .BIC extension. As such, the RTE file is loaded from the device by the associated XXDP+ monitor that is itself booted from the device (refer to XXDP+ User's Manual).

However, if the configurator/linker program used to configure the RTE load module is still active, a BOOT Command (refer to 3.2.2.2.3, I/O Control Commands) may be used to return the XXDP+ monitor to memory, effectively overlaying the configurator program. An example follows:

```
*BOOT DK0: <CR>      ;reload and start RKDP Monitor.
-
```

In any case, when the XXDP+ monitor is successfully loaded, it will identify itself and type a Help message, which can be terminated by entering a Control C (^C), followed by a Filler Count option and a monitor command prompt (.), as shown in the following example:

```
CHMDKB0 XXDP+ DK MONITOR
------------------------
BOOTED VIA UNIT#:   0
----------------------
28K UNIBUS SYSTEM
-----------------

ENTER DATE (DD-MMM-YY):

RESTART ADDR:152010
-------------------
THIS IS XXDP+.  TYPE "H" OR "H/L" FOR HELP.
-------------------------------------------
```

The RTE program may now be loaded by typing a LOAD Command (.L YYYYYY) along with the appropriate file name which simply loads the program or a RUN Command (.R YYYYYY) which both loads and starts the program. For example:

```
.L DECX1 <CR>        ;load program;  to start type S <CR>.
-

.R DECX1 <CR>        ;load program and start at 0200.
-
```

At this point, before describing start conditions and procedures, it should be understood that it is always best to load the RTE via the XXDP+ monitor as opposed to loading via an XXDP+ update program. This is due to the fact that unlike the monitor the update program does not reveal (to the exerciser) the type of load device employed. With the device unidentified it would be possible for data on the load medium to be destroyed if the exerciser tested the load device.

3.3.2.3 Starting Via XXDP+ Monitor

Following the output of the XXDP+ monitor command prompt (.), the self-starting RUN Command (.R) may be used to load and automatically start the RTE program at the appropriate address. However, if the LOAD Command (.L) is used, the starting address (0200) must be manually inserted prior to either typing a START Command (S) or manually depressing the START switch. In either case a restart will necessitate both the manual insertion of the restart address (1000) and depression of the START switch. An example of a RUN Command load/start follows:

```
.R DECX70                               ;Load and start RTE program.
-

DEC/X11 EXERCISER
------------------
     (MONITOR V00.0) MD-XX-XXXXX-X      ;Identity of RTE program.
     -----------------------------

MONITOR:  E                             ;Monitor Identity
-----------

SYSTEM SIZE:  00384 K                   ;Memory capacity of system
---------------------

WRITE BUFFER ROTATION ON                ;Write Buffer Rotation is
------------------------
                                        ;On.
KT ON                                   ;Memory Management Unit is
-----
                                        ;On.
PARITY MEMORY ON                        ;Parity Memory Check is On.
----------------

CACHE ON                                ;Cache Memory is On.
--------
```

MAP BOX ON	;UNIBUS Map Box is On.
LD MEDIA TSTING CLR LOC. 40	;Clear loc. 40 if load ;device is to be tested.
CMD>	;RTE keyboard command prompt

3.3.3 Operating Procedures

The execution of DEC/X11 Exerciser Programs is externally controlled by the use of 22 types of keyboard commands (refer to Table 3-2), while certain run-time features, including accompanying print-outs, may be either enabled or disabled by the optional configuration of a Switch Register (SR).
All commands may be initiated in Command Mode (CMD>). Most may also be initiated while in Run Mode (BSY>). However, some commands (e.g., RUN, MOD, etc.) can only be initiated in Command Mode.

3.3.3.1 Switch Register Options

The DEC/X11 Monitor provides a Software Switch Register for system usage. Therefore the use of Hardware Switch Registers (if it occurs) will be ignored.

The Software Switch Register bits may be conditioned to provide the following run-time features:

BIT	OPERATION
SR00 = 0	;Disable printing of the one-character "Null" ;message.
SR00 = 1	;Enable printing of the one-character "Null" ;message.
SR08 = 0	;Cycle the exerciser once, through all of memory, ;then allow random relocation.
SR08 = 1	;Cycle the exerciser through memory by the ;constant offset value, while inhibiting ;random relocation.
SR09 = 0	;Enable the "RELOCATED TO" printout.
SR09 = 1	;Inhibit the "RELOCATED TO" printout.
SR10 = 0	;Report only the first three data errors occurring ;within a transferred block.

SR10 = 1	;Report all data errors.
SR12 = 1	;Permit the "END OF PASS" printouts.
SR13 = 1	;Inhibit the error and module printouts.
SR14 = 0	;After the 20th error, and following a "MODULE ;DROPPED" printout, drop the module.
SR14 = 1	;After the 20th error, inhibit the dropping of the ;module.
SR15 = 1	;After one error (hard or soft), and following a ;"MODULE DROPPED" printout, drop the module.

TABLE 3-2

LIST OF KEYBOARD COMMANDS

*Command Mode (CMD) Only

COMMAND	OPERATION
*RUN	Execute exerciser
*RUN addr	Execute exerciser at specified address
*RUNL	Lock and execute exerciser
*RUNL addr	Relocate to specified address, lock and execute exerciser
*MOD	Output contents of last modified location
*MOD addr	Output contents of address specified
*MOD modulename addr	Output contents of address specified in named module
*KTON	Enable Memory Management
*KTOFF	Disable Memory Management
*MON	Enable Map Box
*MOFF	Disable Map Box
MAP	Output maps for all modules
MAP modulename	Output map for named module
SEL	Select all modules
SEL modulename	Select named module

DES	Deselect all modules
DES modulename	Deselect named module
FILL	Output contents of FILL CHAR/FILL CNT location
FILL number number	Replace contents of FC/FC location and output same
PON	Enable Parity Memory
POFF	Disable Parity Memory
ROTON	Enable Write Buffer Rotation
ROTOFF	Disable Write Buffer Rotation
LPON	Enable console output to Line Printer
LPOFF	Disable console output to Line Printer
CON	Enable Cache Memory
COFF	Disable Cache Memory
EXAM	Output last examined location
EXAM addr	Output specified location for examination
EXAM modulename addr	Output specified location in named module for examination
SUM	Output summary message for all module
SUM modulename	Output summary message for the named module
SWR	Output contents of Software Switch Register
SWR number	Replace contents of SWR and output same

3.3.3.2 Keyboard Commands

Basically, there are only 22 different types of keyboard commands. However, a variety of entry formats expands the listing of Table 3-2 to 34.

A command is composed, entered, and edited by the use of certain keyboard characters. However, if characters other than those described in this subsection are entered they will be considered invalid by the DEC/X11 Monitor and will be ignored by the command interpreter.

The following material initially describes those keyboard characters recognized by the DEC/X11 Monitor. This is followed by descriptions of the keyboard error messages. The subsection concludes with a detailed analysis of each of the commands, arranged alphabetically by command name.

3.3.3.2.1 Keyboard Character Usage

Where it applies to a given command format, any standard alphabetic (A through Z) or numeric (0 through 9) keyboard character may be used.

However, only the following special characters (i.e., SP; LF; CR; DEL; CTRL C, U or O) may be used to format, control, and/or edit command entries.

SPACE Key (SP):
Depression of the Space Key generates a space code and moves the pointer one character position to the right.

LINE FEED Key (LF):
Depression of the Line Feed Key advances the pointer to the next print line.

CARRIAGE RETURN Key (CR):
Depression of the Carriage Return Key terminates command entry, returns the pointer to the left margin, and advances to the next print line.

RUBOUT or DELETE Key (DEL):
Depression of the Rubout Key deletes the last typed character. Depressing the key n times deletes the last n characters. All deleted characters are echoed at the terminal and bordered by backslashes (\).

CONTROL Key (CTRL):
Holding the Control Key down in conjunction with a momentary depression of either the C, U or O Key allows one of the following three functions to be performed.

- Initiation of Control C (^C) aborts the exerciser and returns to Command Mode (CMD>).
- Initiation of Control U (^U) deletes the current line of input back to the last CR/LF, while the current mode of operation (i.e., CMD> or BSY>) is not interrupted.
- Initiation of Control O (^O) suppresses current message output to the terminal.
- Initiation of Control S (^S) sends XOFF to the host, suspending data transmission to the terminal. Some terminals however, may continue printing data until their internal character buffers or silos are empty.

. Initiation of Control Q (^Q) sends XON to the host, resuming data transmission from the host to the terminal.

3.3.3.2.2 Keyboard Error Messages

There are eight general keyboard error messages related to inappropriate entry procedures and three additional messages which pertain to the use of the RUN RUNL Commands only.

The general error messages are as follows:

1. Invalid Address Message

   The INVALID ADDRESS message is printed if a non-existent address is entered, that is non-existent, greater than 16 bits, or otherwise not allowed by the monitor.

2. Invalid Command Message

   The INVALID COMMAND message is printed if a command, other than those listed in Table 3-2, is used. In addition, the message includes the invalid command entry (e.g., INVALID COMMAND--MAPP).

3. Invalid Command In Run Mode Message

   The INVALID COMMAND IN RUN MODE message is printed if a command (e.g., RUN, RUNL, MOD, etc.) is entered while in Run Mode (BSY) which is restricted to being entered in Command Mode (CMD) only.

4. Invalid Module Name Message

   The INVALID MODULE NAME message is printed if the name is not five characters in length or is otherwise unrecognizable to the monitor.

5. Invalid Or Missing Argument Message

   The INVALID OR MISSING ARGUMENT message is printed if an argument is either improperly included in a command format or is missing (e.g., MOD modulename with addr missing).

6. Must Be Even Address Message

   The MUST BE EVEN ADDRESS message is printed if an odd-numbered address is entered for the address argument (addr).

7. Not An Octal Number Message

   The NOT AN OCTAL NUMBER message is printed if the number argument entered is other than an octal number (i.e., 0-7) or contains an alphabetic.

8. Number Too Large Message

   The NUMBER TOO LARGE message is printed if the number argument entered exceeds the allowable maximum of 16 bits (i.e., 177777 octal).

The RUN and RUNL error messages are as follows:

1. Address-OK-But-Exerciser-Won't-Fit Message

   The ADDRESS OK BUT EXERCISER WON'T FIT message is printed if there is not enough room to contain the exerciser between the address specified, by either command, and the top of memory.

2. Must-Have-KT-On Message

   The MUST HAVE KT ON message is printed if an address argument is specified with either command and the Memory Management Unit (KT11) is Off.

3. No-Modules-Selected Message

   The NO MODULES SELECTED message is printed if the user enters either command with all modules deselected.

4. Map Box Must Be On Message

   The MAP BOX MUST BE ON message is printed if the user specifies an address argument greater than 96K(600000) and 22-bit mapping is disabled(MOFF Command).

3.3.3.2.3 Keyboard Command Analysis

The following material provides a detailed analysis of each of the keyboard commands. The commands are alphabetically arranged and a detailed description of the command is provided.

```
COFF Command          ;Cache-Off Command
CON Command           ;Cache-On Command
DES Command           ;Deselect Command
EXAM Command          ;Examine Command
FILL Command          ;Filler Word Command
KTOFF Command         ;KT-Off Command
KTON Command          ;KT-On Command
LPOFF Command         ;Line Printer off Command
LPON Command          ;Line Printer on Command
MAP Command           ;Mapping Command
MOD Command           ;Modify Command
MOFF Command          ;UNIBUS Map-Off Command
MON Command           ;UNIBUS Map-On Command
POFF Command          ;Parity-Off Command
PON Command           ;Parity-On Command
ROTOFF Command        ;Rotation-Off Command
```

! COFF Command !

Function

The Cache Off Command (COFF) is used to disable a system's Cache Memory.

Format

```
COFF       ;turn off cache memory.
```

Characteristics

A system's Cache Memory is automatically enabled when an exerciser program is started. However, the memory may be disabled via the COFF Command and re-enabled by executing a Cache On Command (CON).

Associated Messages

Refer to subsection

Example

```
.COFF<CR> ;disable cache memory.
```

! CON Command !

Function

The Cache On Command (CON) is used to re-enable a system's Cache Memory.

Format

```
          CON        ;turn on cache memory.
```

Characteristics

A system's Cache Memory is automatically enabled when an exerciser program is started. However, the memory may be disabled by executing a Cache Off Command (COFF) and re-enabled via the CON Command.

Associated Messages

Refer to subsection

Example

```
          .CON<CR>  ;re-enable cache memory.
```

! DES Command !

Function

The Deselect Command (DES) allows all modules or a single specified module to be deselected.

Format

General: DES [modulename]

1. DES
   Deselect all modules.

2. DES modulename
   Deselect the specified (modulename) module.

Characteristics

When the exerciser is initially loaded, all modules are automatically selected for execution; this is the default condition. However, if the user desires to run a single module, the remaining modules must be deselected; and if the user desires to run all modules except one, the exception must be deselected. Thus, the Deselect Command (DES) is generally used in conjunction with a Select Command (SEL). The latter allows all modules, or a specified module, to be selected.

Example: To deselect one module:

```
SEL                          ;select all modules
DES modulename               ;deselect named module
```

Example: To deselect all but one module

```
DES                          ;deselect all modules
SEL modulename               ;select named module
```

Restrictions

The modulename argument must be five characters in length.

Associated Messages

Refer to subsection

Examples

Format 1:

```
.DES<CR>                        ;deselect all modules
```

Format 2:

```
.DES DCAA0<CR>                  ;deselect Module DCAA0
```

! EXAM Command !

Function

The examine Command (EXAM) is used to output the contents of the location specified by either the last EXAM Command or the current command.

Format

General: EXAM[[modulename]addr]

1. EXAM
   Output the contents of the last examined location.

2. EXAM addr
   Output the contents of the location specified by the address argument (addr).

3. EXAM modulename addr
   Output the contents of the location, specified by a relative address (addr) within the named module (modulename).

Characteristics

The EXAM Command makes it possible to examine the contents of a location while the system is operating in the Run Mode (BSY>).
When Format 1 is used, the contents of the last location accessed by an EXAM Command will be output.
When Format 2 is used, the address argument specifies a virtual address.
When Format 3 is used, the address argument specifies the offset value for a word, within a named module, relative to the virtual base address of the module. However, the Monitor response defines the word address relative to the virtual base address of the exerciser.

Restrictions

- The address argument has a maximum length of 16 bits.
- The modulename argument must be five characters in length.

Associated Messages

Refer to subsection

Examples

Format 1:

```
     .EXAM<CR>              ;output contents of last EXAM location.
  Monitor response:
     053772/002345          ;002345 is the contents of location
                            ;053772
```

Format 2:

```
     .EXAM 053776<CR>       ;output contents of location 053776.

  Monitor response:
     053776/000005          ;000005 is the contents of location
                            ;053776.
```

Format 3:

```
     .EXAM LPAE0 36<CR>     ;output word 36 from Module LPAE0.
  Monitor response:
     053774/000004          ;000004 is word 36 (in Module LPAE0)
                            ;from location 053774.
```

```
----------------
! FILL Command !
----------------
```

Function

The Fill Command (FILL) is used to output a combination Fill Character and Filler Count word for examination and/or complete alteration.

Format

General: FILL[number number]

1. FILL
   Output the FILL CHAR/FILL CNT word.

2. FILL number number
   Replace the FILL CHAR (number)/FILL CNT (number) word and output same.

Characteristics

In relation to a particular console device (e.g., LA30S, VT05B, etc.), the detection of an associated Fill character (e.g., Carriage Return, Line Feed, etc.) allows an optional number of Filler Characters (i.e., non-printable null characters) to be recognized in order to delay message output while mechanical adjustments are made to the pointer. For example: following detection of a Carriage Return Code (158), a number of Filler Characters, defined by the Filler Count, provide an appropriate delay while the pointer is being returned to the left margin, thus eliminating garbled output.
The Fill argument (number number) consists of a maximum of 16 bits (2 bytes): The low-order byte contains the Filler Count (FILL CNT), while the high-order byte contains the Fill Character (FILL CHAR) required by the console (i.e., CR, LF, etc.).

```
0 1 2  0 1 4
-----  -----
  !      !
  !      !----------FILLER COUNT BYTE
  !-----------------FILL CHARACTER BYTE
```

Restriction

- The Fill argument (number number) must consist of octal digits.
- If the entire argument is replaced, a space must be inserted between the numbers (i.e., character and count).

Associated Messages

Refer to subsection

Examples

```
Format 1:
       .FILL<CR>              ;output current Fill Word.
   Monitor response:

       FILL/006401            ;FILL CHAR is CR with FILL COUNT of One,
                              ;right justified (0 000 110 100 000
                              ;001).

Format 2:
       .FILL 15 14<CR>        ;replace character with CR and
                              ;count with 14, output same.

   Monitor response:
       FILL/006414            ;replacement right justified.
```

! KTOFF Command !

Function

The Memory-Management-Off Command (KTOFF) is used to disable the Memory Management Unit (KT) and clear its status indicator (KTSTAT).

Format

```
        KTOFF                   ;Disable the Memory Management Unit
```

Characteristics

If a Memory Management Unit (KT) is available to a system, the unit is automatically enabled when a DEC/X11 Exerciser Program is loaded and started. The KT Status (KTSTAT) indicator is then set and mapping occurs as required. The user now has the option in Command Mode (CMD>) of disabling (KTOFF) the unit or re-enabling (KTON) the unit, as the case may be.

Restrictions

The KTOFF command must be entered in Command Mode (CMD>) only.

Associated Messages

Refer to subsection

Example

```
        .KTOFF<CR>              ;Disable KT Unit and clear KTSTAT flag.
```

! KTON Command !

Function

The Memory-Management-On Command (KTON) is used to re-enable the Memory Management Unit (KT).

Format

```
        KTON                    ;Re-enable the Memory Management Unit
```

Characteristics

If a Memory Management Unit (KT) is available to a system, the unit is automatically enabled when the DEC/X11 Exerciser Program is loaded and started. The KT Status (KTSTAT) indicator is then set and mapping occurs as required. The user now has the option in Command Mode (CMD>) of disabling (KTOFF) the unit or re-enabling (KTON) the unit, as the case may be.

Restriction

The KTON Command must be entered in Command Mode (CMD>) only.

Associated Messages

Refer to subsection --

Example

```
        .KTON<CR>               ;Re-enable KT Unit and set KTSTAT flag.
```

```
-----------------
!     LPOFF     !
-----------------
```

Function

The Line Printer Off Command(LPOFF) is used to redirect all output for the line printer back to the console.

Format

```
        LPOFF                ;turn off line printer
```

Characteristics

When the LPOFF Command is entered, all subsequent output(i.e., prompts, messages, summaries etc.) and operator input(i.e., program queries and request responses) are re-directed from the line printer back to the console.

Associated Messages

Refer to subsection

Example

```
        .LPOFF <CR>          ;disable line printer
```

```
-----------------
!  LPON Command !
-----------------
```

Function

The Line Printer On command(LPON) is used to redirect all output for the console to the line printer.

Format

```
          LPON             ;turn on line printer
```

Characteristics

When the LPON Command is entered, all subsequent output (i.e., prompts, messages, summaries, etc.) and operator input (i.e., program query and request response) are re-directed from the console(default condition) to the line printer. Thus console echoing is effectively disabled.

Associated Messages

Refer to subsection

Example

```
          .LPON <CR>       ;enable line printer
```

! MAP Command !

Function

The Mapping Command (MAP) is used to output a message from the monitor concerning the identity and current status of all of the resident modules, or single specified module.

Format

General: MAP [modulename]

1. MAP
   Output Map message information for all modules.

2. MAP modulename
   Output Map message information for the named module.

Characteristics

Each line of a Map message is formatted as follows:

(modulename) AT VA: (address) STAT: (status word)

Modulename:

The five-character modulename indicates the following:

```
R K A D 0
----- - -
 !    ! !
 !    ! !
 !    ! !------Copy Number (0-7)
 !    !--------Version Letter
 !
 !-------------Identifier Letters
```

Address:

The virtual address defines the first word of the module (i.e., word zero of the header).

Status Word:

With the exception of bits 11, 13 and 14, the remaining bits of the 16-bit status word (00-15) are used to define the module type (i.,e., Input/Output, Background, etc.); while bits 11, 13, and 14 are used to define the current status of the module (i.e., Active, Dropped, or Selected), as follows:

- Excepting bits 11, 13 and 14: all bits cleared (000000) indicates a Special Background Module (SBKMOD).

- Excepting bits 11, 13 and 14: bit 04 set (000020) indicates a Background Module (BKMOD).
- Bit 11 set indicates the module is Active.
- Excepting bits 11, 13 and 14: bit 09 set (001000) indicates a Non-Background Module (NBKMOD).
- Excepting bits 11, 13 and 14: bit 15 set (100000) indicates an I/O Module (IOMOD).
- Excepting bits 11, 13 and 14: bits 10 and 15 set (102000) indicates a Partially Restricted I/O Module (IOMODP).
- Excepting bits 11, 13 and 14: bits 10, 12 and 15 set (112000) indicates a Restricted I/O Module (IOMODR).
- Excepting bits 11, 13 and 14: bits 12 and 15 set (110000) indicates an Extended I/O Module (IOMODX).
- Bit 13 set indicates that the module has been Dropped.
- Bit 14 set indicates that the module has been Selected.

Restrictions

- The modulename argument must be five characters in length.

Associated Messages

Refer to subsection

Examples

Format 1:

```
.MAP<CR>                     ;Map all modules.
```

Monitor response:

```
RKAD0 AT VA: 021544 STAT: 150000   ;IOMODX Module RKAD0 is
                                    selected.
TCAD0 AT VA: 034700 STAT: 130000   ;IOMODX Module TCAD0 is
                                    dropped.
CPAD0 AT VA: 042346 STAT: 40020    ;BKMOD Module CPAD0 is
                                    selected.
```

Format 2:

```
.MAP TAAC0 <CR>                    ;Map Module TAAC0
```

Monitor response:

```
TAACO AT VA: 037460 STAT: 140000    ;IOMOD Module TAACO
                                     is selected.
```

! MOD Command !

Function

The Modify Command (MOD) is used to examine and/or modify the contents of selected storage locations.

Format

General: MOD [[modulename] addr]

1. MOD

   Output the contents of the last modified location.

2. MOD addr

   Output the contents of the location specified by the absolute address argument (addr).

3. MOD modulename addr

   Output the contents of the location specified by both the module name and its associated relative address argument (modulename addr).

Characteristics

The MOD Command makes it possible to open and/or modify absolute as well as relative addresses (i.e., relative to the starting address of the specified module). In addition, when a relative address is specified, the monitor will respond by printing the equivalent absolute address.

Restrictions

. The MOD Command must be entered in Command Mode (CMD>) only.

. All specified addresses must be less than 32k words or the largest available address, whichever is smaller.

. All specified addresses must be even.

Associated Messages

Refer to subsection

Examples

Format 1:

```
.MOD<CR>                ;open last modified location.
```

Format 2:

```
.MOD 4000<CR>           ;open location 4000.
```

Monitor response:

```
004000/123456           ;location 4000 contains value 123456.
```

Operator response:

1. Close location 4000 by typing <CR>.
2. Insert new value and close location 4000 by typing <CR>.
3. Insert new value and open next word by typing <LF>.
4. Close location 4000 and open next word by typing <LF>.

Format 3:

```
.MOD DCAA0 20<CR>       ;open relative location 20 in Module
                        ;DCAA0 (10TH OCTAL word).
```

Monitor response:

```
012020/140000           ;absolute address of 10th octal word is
                        ;012020 and contents of location are
                        140000.
```

Operator response:

Operator has the same four options described for Format 2.

! MOFF Command !

Function

The UNIBUS-Map-Off Command (MOFF) is used to disable a system's UNIBUS mapping logic.

Format

```
        MOFF                    ;turn off the UNIBUS Map Logic.
```

Characteristics

The UNIBUS mapping hardware is automatically enabled when the exerciser is started. The logic may be disabled via the MOFF Command and re-enabled by executing, in Command Mode (CMD>) only, a UNIBUS-Map-On Command (MON).

Restrictions

The MOFF Command may be entered in Command Mode (CMD>) only.

Associated Messages

Refer to subsection

Example

```
        .MOFF<CR>               ;disable the UNIBUS Map Logic.
```

! MON Command !

Function

The UNIBUS-Map-On Command (MON) is used to re-enable the system's UNIBUS mapping logic.

Format

```
MON                    ;turn on UNIBUS Map Logic
```

Characteristics

The UNIBUS mapping hardware is automatically enabled when the exerciser is initialized. The logic may be disabled by executing, in Command Mode (CMD>) only, a UNIBUS-Map-Off Command (MOFF). The logic may then be re-enabled via the MON Command.

Restrictions

The MON Command may be entered in Command Mode (CMD>) only.

Associated Messages

Refer to subsection

Example

```
.MON <CR>              ;re-enable the UNIBUS Map Logic.
```

! POFF Command !

Function

The Parity-Off Command (POFF) is used to disable the system's Parity Check Logic.

Format

```
        POFF                    ;disable parity checking logic.
```

Characteristics

The parity checking hardware is automatically enabled when the execiser program is initialized. The logic may be disabled via the POFF Command and re-enabled by executing a Parity-On command (PON).

Associated Messages

Refer to subsection

Example

```
        .POFF <CR>              ;disable parity checking logic.
```

```
---------------
! PON Command !
---------------
```

Function

The Parity-On Command (PON) is used to re-enable a system's Parity Check Logic. The logic is used to verify the integrity of data transfered from Main Memory or Cache Memory.

Format

```
        PON                 ;turn on parity checking logic
```

Characteristics

The parity checking hardware is automatically enabled when the exerciser program is initialized. The logic may be disabled by executing a Parity-Off Command (POFF) and re-enabled via the PON Command.

Associated Messages

Refer to subsection

Example

```
        .PON <CR>           ;re-enable parity checking logic
```

```
------------------
! ROTOFF Command !
------------------
```

Function

The Rotation-Off Command (ROTOFF) is used to disable Write Buffer Rotation.

Format

```
        ROTOFF                    ;turn off Write Buffer Rotation.
```

Characteristics

Write Buffer Rotation is automatically enabled when an exerciser program is initialized. The feature may be disabled via a ROTOFF Command and re-enabled by executing a Rotation-On Command (ROTON).

Associated Messages

Refer to subsection

Example

```
        .ROTOFF <CR>              ;disable Write Buffer Rotation.
```

--

! ROTON Command !

Function

The Rotation-On Command (ROTON) is used to re-enable Write Buffer Rotation.

Format

```
        ROTON                ;turn on Write Buffer Rotation.
```

Characteristics

Write Buffer Rotation is automatically enabled when an exerciser program is initialized. The feature may be disabled by executing a Rotation Off Command (ROTOFF) and re-enabled via a ROTON Command.

Associated Messages

Refer to subsection

Example

```
        .ROTON <CR>          ;re-enable Write Buffer Rotation.
```

! RUN Command !

Function

The Run Command (Run) is used to initiate the Run Mode (BSY>) and start the option modules. Only those modules selected for execution will be run.

The Run Command is identical to the RUNL Command with one exception: The RUN Command allows the periodic relocation of the exerciser program* if an adequate amount of core is available for relocation and a Memory Management Unit (KT) is available and enabled.

Format

General: RUN [addr]

1. RUN

   Initiate Run Mode (BSY>) and execute option modules.

2. RUN addr

   Initiate Run Mode (BSY>) and, following an initial relocation to the address specified, execute the option modules.

Characteristics

Module Execution Sequence:

When a RUN Command is entered, Run Mode (BSY>) is initiated and the Selected modules are executed as follows: First, single passes are separately made through the Special Background Modules (SBKMOD). Second, passes are separately made through the Non-Back-ground Modules (NBKMOD). Third, the Background Modules (BKMOD) will execute a 1 iteration pass. Fourth, the interrupt-driven I/O Modules (IOMOD,X,P, AND R) are enabled. Finally, single passes are separately made through the Background Modules (BKMOD).

Write Buffer Rotation:

Write Buffer Rotation will occur if the operation is enabled: rotation is initially enabled by default, disabled via a ROTOFF Command, and re-enabled by a ROTON Command.

Initial Program Relocation:

As stated, if both adequate core and a KT Unit are avilable and the KT is enabled (i.e., by default or a KTON Command), the movable* portion of the exerciser program will be periodically relocated; however, an initial relocation address may be specified by the user (Format 2).

If an initial relocation address is specified by the user, care must be taken to ensure that the address chosen satisfies the memory requirements of the movable portion of the execiser in relation to the availability of usable core. With this assurance, initial relocation to the nearest 32-word boundary of the address will occur prior to the execution of the modules.

Aborting The Exerciser:

Once started, the option modules will continue to run until aborted by one or more of the following occurrences (at which a SUM Command may be used to provide a run-time summary of module activity):

- A Control C (^C) is entered: causing the Monitor to cease execution of the option modules, return the program to its original memory space (if necessary) and return the system to Command Mode (CMD>).

- All modules are dropped due to module errors: causing the Monitor to return the program to its original memory space (if necessary) and return the system to Command Mode (CMD>).

- The occurrence of a fatal error (e.g., too many system errors occur): causing the Monitor to cease execution of the option modules, return the program to its original memory space (if necessary), and return the system to Command Mode (CMD>).

Restrictions

- The RUN Command must be entered in Command Mode (CMD>).

- The address argument (addr) has a minimum restriction of octal 20,000*

- the address argument (addr) must satisfy both the core requirements of the exerciser and the core availability of the system.

Associated Messages

Refer to subsection

Examples

---

*A portion of the execiser program always resides in the lowest 4K words of memory, within a range of 0-17776(8), and is never relocated.

Format 1:

```
.RUN <CR>                  ;start with a relocation offset of zero
```

Format 2:

```
.RUN 360000 <CR>           ;relocate to 360000 and start
```

Monitor response:

```
RELOCATED TO 360000        ;response to valid address.
```

! RUNL Command !

Function

The Run-Locked Command (RUNL) is used to initiate the Run Mode (BSY>) and start the option modules. Only those modules selected for execution will be run.

The RUNL Command is identical to the RUN Command with one exception: The RUNL Command inhibits periodic relocation of the movable* portion of the execiser program by locking in the load address or the initial relocation address that may be defined by the user.

Format

General: RUNL [addr]

1. RUNL

   Initiate Run Mode (BSY>), lock, and start option modules.

2. RUNL addr

   Initiate Run Mode (BSY>), relocate to user specified address (addr), lock and start option modules.

Characteristics

Module Execution Sequence:

When a RUNL Command is entered, Run Mode (BSY>) is initiated, and the Selected modules are executed as follows: First, single passes are separately made through the Special Background Modules (SBKMOD); second, single passes are separately made through the Non-Background Modules (NBKMOD); third, the Background modules (BKMOD) will execute a 1 iteration pass; fourth, the interrupt-driven I/O Modules (IOMOD,X,P and R) are enabled; finally, single passes are separately made through the Background Modules (BKMOD).

Write Buffer Rotation:

Write Buffer Rotation will occur, for initial relocation, if the operation is enabled. Rotation is initially enabled by default, disabled via a ROTOFF Command, and re-enabled by a ROTON Command.

Initial Program Relocation:

If both adequate core and a KT Unit are available, and the KT is enabled (i.e., by default or a KTON Command), the movable portion of

the exerciser program can be initially relocated to an address specified by the user (Format 2); whereupon the address will be locked and no further relocation will occur.
If an initial relocation address is specified by the user, care must be taken to ensure that the address chosen satisfies the memory requirements of the movable portion of the execiser in relation to the availability of usable core; with this assurance, initial relocation to the nearest 32-word boundary of the address will be made, the address will be locked, and execution of the modules will occur.

Aborting the Exerciser:

Once started, the option modules will continue to run until aborted by one or more of the following occurrences (at which time a SUM Command may be used to provide a run-time summary of module activity):

- A Control C (^C) is entered: causing the Monitor to cease execution of the option modules, return the program to its original memory space (if necessary), and return the system to Command Mode (CMD>).

- All modules are dropped due to module errors: causing the Monitor to return the program to its original memory space (if necessary), and return the system to Command Mode(CMD>).

- The occurrence of a fatal error (e.g., too many system errors): causing the Monitor to cease execution of the option modules, return the program to its original memory space (if necessary), and return the system to Command Mode (CMD>).

Restrictions

- The RUNL Command must be entered in Command Mode (CMD>).

- The address argument (addr) has a minimum restriction of octal 20,000*.

- The address argument (addr) must satisfy both the core requirements of the exerciser and the core availability of the system.

Associated Messages

Refer to subsection

Examples

----

*A portion of the exerciser program always resides in the lowest 4K words of memory, within a range of 0-17776(8), and is never relocated.

Format 1:

```
.RUNL <CR>             ;start with a relocation offset of
                        ;Zero locked.
```

Format 2:

```
.RUNL 360000<CR>       ;relocate to 360000, lock and start.

RELOCATED TO 360000    ;response to valid address.
```

! SEL Command !

Function

The Select Command (SEL) allows all modules, or a single specified module, to be selected for execution.

Format

General: SEL [modulename]

1. SEL

   Select all modules for execution.

2. SEL modulename

   Select the specified (modulename) module for execution.

Characteristics

When the exerciser is initially loaded, all modules are automatically selected for execution; this is the default condition. However, if the user desires to run a single module, the remaining modules must be deselected and, if the user desires to run all modules except one, the exception must be deselected. Thus, the Select Command (SEL) is generally used in conjunction with a Deselect Command (DES). The latter allows all modules, or a specified module, to be deselected.

Example: To select one module:

```
DES            ;deselect all modules

SEL modulename ;select named module
```

Example: To select all but one module.

```
SEL            ;select all modules

DES modulename ;deselect named module
```

Restrictions

The modulename argument must be five characters in length.

Associated Messages

Refer to subsection

Examples

Format 1:

```
.SEL<CR>                ;select all modules
```

Format 2:

```
.SEL DCAA0<CR>          ;select Module DCAA0
```

```
---------------
! SUM Command !
---------------
```

Function

The Summary Command (SUM) is used to output a summary message for each resident module, or a specified module, concerning: module identity; current status; the decimal number of passes, hard errors, soft errors, system errors and power failures. The last two items will not be output if only a single module is specified.

Format

General: SUM [modulename]

1. SUM

   Output summary message for each resident module.

2. SUM modulename

   Output summary message line for the specified (modulename) module.

Characteristics

A SUM Command may be entered in the Run Mode (BSY>) providing a summary message that is formatted as follows:

(mod name) AT VA: (addr) STAT (stat wd) PASS (#num) HRDERRS (num) SFTERRS (num)

SYSTEM ERRORS: (num) POWER FAILS: (num)

Modulename:
The five-character modulename inidcates the following:

```
R K A D 0
----- - -
  !   ! !
  !   ! !-------Copy Number (0-7)
  !   !
  !   !
  !   !---------Version Letter
  !-------------Identifier Letters
```

Address:

The virtual address defines the first word of the module (i.e., word zero of the header).

Status Word:

With the exception of bits 11, 13 and 14, the remaining bits of the 16-bit status word (00-15) are used to define the module type (i.e., Input/Output, Background, etc.). Bits 11, 13 and 14 are used to define the current status of the module (i.e., Active, Dropped, or Selected), as follows:

- Excepting bits 11, 13 and 14: all bits cleared (000000) indicates a Special Background Module (SBKMOD).
- Excepting bits 11, 13 and 14: bit 04 set (000020) indicates a Background Module (BKMOD).
- Bit 11 set indicates the module is active.
- Excepting bits 11, 13 and 14: bit 09 set (001000) indicates a Non-Background Module (NBKMOD).
- Excepting bits 11, 13 and 14: bits 10 and 15 set (102000) indicates a Partially Restricted I/O Module (IOMODP).
- Excepting bits 11, 13 and 14: bits 10, 12 and 15 set (104000) indicates a Restricted I/O Module (IOMODR).
- Excepting bits 11, 13 and 14: bits 12 and 15 set (110000) indicates an Extended I/O Module (IOMODX).
- Bit 13 set indicates that the module has been Dropped.
- Bit 14 set indicates that the module has been Selected.

Number:

All number items that are output have a maximum range of five decimal digits.

Restrictions

The modulename argument must be five characters in length.

Associated Messages

Refer to subsection Examples

Examples

Format 1:

```
.SUM <CR>            ;summarize all modules
```

Monitor response:

```
SUMMARY AT RUNTIME:  000:02:52*

        LPAE0  AT VA: 053734 STAT 150000 PASS #00000 HRDERRS 00000
        SFTERRS 00000
                                  .
                                  .

        TCAF0 AT VA: 055310 STAT 150000 PASS #00000 HRDERRS 00000
        SFTERRS 00000

SYSTEM ERRORS:  00000     POWER FAILS:  00000
```

Format 2:

```
        .SUM RKAF0 <CR>    ;summarize Module RKAF0.
```

Monitor response:

```
        RKAF0 AT VA:  054524 STAT 150000 PASS #00000 HRDERRS 00000
        SFTERRS 00000
```

----

*Time entry will only occur if a Real-Time Clock is available to the system.

! SWR Command !

Function

The Switch-Register Command (SWR) is used to output the contents of the Software Switch Register (SR), for analysis and/or replacement.

Format

General: SWR [number]

1. SWR

   Output the current contents of the Software Switch Register.

2. SWR number

   Replace (number) the contents of the Software Switch Register and output the same.

Characteristics

The SWR Command conditions the 16-bit Software Switch Register to provide a combination of the run-time features described in subsection 3.3.3.1.

Associated Messages

Refer to subsection

Examples

Format 1:

```
.SWR<CR>                ;output contents of SWR.
```

Monitor response:

```
SWR/ 112000             ;refer to subsection 3.3.3.1 for decode.
```

Format 2:

```
.SWR 053401<CR>         ;place 053401 in SWR and output same
```

Monitor response:

```
SWR/ 053401             ;replacement verfication.
```

3.3.3.3 Operator Modifications

Necessary modifications to Monitor and/or Option Module locations are initiated in Command Mode (CMD>) and accomplished via the use of the Modify Command (MOD).

3.3.3.3.1 Monitor Modifications

3.3.3.3.2 Option Module Modifications

Although a user may modify any location within an option module via the MOD Command, the most common modifications are related to changes desired in test criteria (i.e., device and vector address changes, bus priority level changes, etc.). Such changes are accomplished by the alteration of selected and specifically labelled words that are contained in the Module Interfaces (headers). The following information pertains to the formatting and use of these selected words.

Word 6 (ADDR): Device/Option UNIBUS Address

Module Header Word 6 (ADDR) must specify the UNIBUS address for the first device or option to be tested. If more than one address is required, ADDR will specify the first of a contiguous grouping.

Header Word 6 (ADDR) Example:

```
            CMD> MOD WXYZ0 6<CR>
            ----
            52346/000000  172460<CR>          ;1st device address.
            ------------
            CMD>
            ----
```

Word 10 (VECTOR): Device/Option Vector Address

Module Header Word 10 (VECTOR) must specify the vector address for the first device or option to be tested. If more than one address is required, VECTOR will specify the first of a contiguous grouping.

Header Word 10 (VECTOR) Example:

```
            CMD> MOD WXYZ0 10<CR>
            ----
            52350/000000  230<CR>             ;1st device vector.
            ------------
            CMD>
            ----
```

Word 12 (BR1,BR2): Bus Priority Levels

Module Header Word 12 (BR1,BR2) specifies, via the high order (BR1) and low order (BR2) byte respectively, the priority levels required by interrupt-driven devices. Normally, only BR1 will be required. However, BR2 must be specified if the device is capable of separate levels of interrupt.

Header Word 12 (BR1,BR2) Example:

```
CMD> MOD WXYZ0 12<CR>
----
52352/000000 300<CR>          ;1st BR level is PRTY6.
------------
CMD>                          ;2nd BR level is unused.
----
```

Word 14 (DVID1): Device Indicator Count

Module Header Word 14 (DVID1) indicates the total number of active devices to be tested (up to 16) via the number of bits that are set (1) in the word. The word also specifies the device(s) selected (0-15) via the corresponding weight of the bit positions.

Header Word 14 (DVID1) Example:

```
CMD> MOD WXYZ0 14<CR>
-----
52354/000000  3<CR       ;Device Indicator One specifies that
------------             ;Device 0 and Device 1 (0 000 000 000
CMD                      ;000 011) are to be tested.
----
```

Words 16-24 (SR1-SR4): Module Switch Registers

Module Header Words 16 through 24 (SR1, SR2, SR3, SR4) locate the four 16-bit Software Switch Registers available to each module. These registers are provided for general-purpose program switching and are used to define unique device options and/or to point to specific module routines.

Header Word 16 (SR1) Example:

```
CMD> MOD WXYZ0 16<CR>
----
52356/000000  100000<CR>    ;Software Switch Register One is open.
------------
CMD>
----
```

Word 36 (ICONT): Iteration Constant

Module Header Word 36 (ICONT) indicates the number of times that a module will be run prior to an End-Of-Pass and may be configured at the user's discretion.

Header Word 36 (ICONT) Example:

```
CMD> MOD WXYZ0 36<CR>
----
52376/004000 100<CR>        ;count provides 64 decimal passes.
------------
CMD>
----
```

3.3.3.4 Message Print-Outs

Message print-outs may be divided into the following three categories:

- Keyboard Error Messages: which indicate an inappropriate use of the Keyboard Commands (refer to subsection 3.3.3.2.2).
- Normal Run-Time Messages: which indicate the occurrence and/or completion of normal functions of the program.
- Run-Time Error Messages: which indicate abnormal occurrences within the program and/or its associated devices.

3.3.3.4.1 Normal Run-Time Messages

There are five normal run-time messages that can be generated by any RTE program:

- End Of Pass Printout
- Module Dropped Printout
- ASCII Message Printout
- Relocated To Printout
- Power Failure Printout

End Of Pass Printout

End Of Pass is an optional message, the generation of which when enabled by the setting of bit twelve in the Software Switch Register (SR12 = 1) indicates that a complete pass through a specific module has been completed. However, due to the possibility that the generation of the printout may significantly decrease throughput, the message is normally inhibited (SR12 = 0). In any case, following the generation of an End Of Pass printout, a reexecution of the specified module will occur except when the pass is completed for a background module, in which case the monitor will start executing the next background module.

The End Of Pass Printout is as follows:

CPAF0 END PASS #00034. RUNTIME: 000:11:37 PSTIME: 000:00:37

Where:

CPAF0 identifies the module and END PASS #NNNNN defines the decimal number of completed passes. RUNTIME/PSTIME HRS:MINS:SECS respectively define the total run and pass times (zeroed if a system clock is not available).

Module Dropped Printout

A Module Dropped printout may be initiated by a module for itself via an END Call or may be generated by the monitor as a conditioned response (e.g., via switch register settings) to errors occuring within a module. In either case, following the printout, a module that has been dropped cannot be reexecuted until Command Mode(CMD>) is re-entered via ^C and Run Mode(BSY>) is reinitiated via RUN or RUNL command. available to the program.

The Module Dropped message is conditionally generated as follows:

. Via an END Call, following the occurrence of a condition that the module defines as abnormal (e.g., no drives available).

. Via the monitor, if the total number of allowable systems errors (i.e., four) for the modules is exceeded.

. Via the monitor, in conjunction with the setting of Software Switch Register bit 15 (SR15 = 1), following the occurrence of an error (whether acknowledged by printout or not).

. Via the monitor, if Software Switch Register bit 14 is reset (SR14 = 0) and the 20th hard or 40th soft error has occurred (whether acknowledged by printout or not). If bit 14 is set (SR14 = 1), the message will not be printed and the module will not be dropped.

The Module Dropped Printout is as follows:

CPAF0 DROPPED AT APC XXXXXX

Where:

CPAFO identifies the dropped module and APC XXXXXX defines the Assembled Program Counter address (as opposed to the physical address) where the drop occurred.

ASCII Message Printout

In addition to standard message generation, the monitor provides each module with an ASCII message capability which may be used to report conditions and/or statistics. Typical ASCII message printouts are as follows:

LPAA0 PA XXXXXXXX APC YYYYYY PASS# NNNNN	;defining: 22-bit Physical Address (PA of ;module LPAA0, 18-bit Assembled Program ;Counter (APC) address, and decimal number ;of completed passes.
RKAA0 PA XXXXXXXX APC YYYYYY PASS# NNNNN	;same data as above with test information:
DATA TRANSFERS: XXXXXX	;decimal number of I/O transfers
SOFT ERRORS: YYYYYY	;decimal number of recoverable errors
HARD ERRORS: ZZZZZZ	;decimal number of unrecoverable errors
LP IS OFF LINE	;line printer status

Relocated To Printout

When the entire exerciser program is relocated in memory, as described in the RUN and RUNL Command analysis, a Relocated To message is generated which includes the physical address to which relocation has occurred:

RELOCATED TO XXXXXX00

Where: XXXXXX00 implies a 22-bit octal physical address to which relocation has occured.

Power Failure Printout

Following a power failure, when a restart is initiated, the original mode of operation is reactivated (i.e., BSY> or CMD> mode) and the Power Failure message is output, as follows:

POWER FAILURE OCCURRED

Although this printout provides an awareness of a malfunction, it is a normal message as opposed to an RTE error message which would indicate an error by RTE software.

3.3.3.4.2 RTE Run-Time Error Messages

There are ten RTE run-time error messages that can be generated by an RTE program:

- System Error Printout
- Soft Error Printout
- Hard Error Printout
- Extended Soft Error Printout
- Extended Hard Error Printout
- Data Error Printout
- Monitor Data Error Printout
- Memory Management Error Printout
- Memory Parity Error Printout
- BAD Vector Printout

System Error Printout

A System Error message is output whenever a Bus Error Trap, to location four, or a Reserved Instruction Trap, to location ten, occurs. The message printout is as follows:

```
**** SYSTEM ERROR ****
VECTOR   PC+_   ADDR    PSW    SP     ERCT
AAAAAA BBBBBB CCCCCC DDDDDD EEEEEE FFFFFF

AT GGGGG HHHHHH
```

Where:

AAAAAA	- is 000004 if Bus Error Trap and 000010 if Reserved Instruction Trap.
BBBBBB	- is Program Counter address pushed on stack at time of failure.
CCCCCC	- is actual physical address of error. If no relocation, CCCCCC = BBBBBB.
DDDDDD	- is Processor Status Word at time of failure.
EEEEEE	- is contents (virtual addr.) of Stack Pointer Register at time of failure.
FFFFFF	- is the System Error count in decimal.
GGGGGG	- is module name, if error occurred within an option module.
HHHHHH	- is Assembled Program Counter (APC) address, if error occurred in option module.

Once the system error message has been output, the monitor will cause the following:

- If, when the error occurred, the system was in Command Mode (CMD>), it will remain in Command Mode.

- If, when the error occured, the system was in Run Mode (BSY>), or in Chain Mode, Run Mode will be reinitiated. Moreover, pass count and error count data will not be cleared.

For additional message possibilities refer to section entitled: Special System Error Printouts.

Soft and Hard Error Printouts

In regard to an operating system, Soft Errors are recoverable and Hard Errors are not. In regard to an exerciser program, soft and hard error message information is identical, with an exception only to type (i.e., SOFT or HARD).

The following is an example of a Hard Error printout:

```
ABCD0  PA XXXXXXXX  APC YYYYYY PASS# NNNNN HARD ERR# NNNNN
CSRA AAAAAA  CSRC CCCCCC  STATC SSSSSS  ERRTYP NNNNN
```

Where:

ABCD0	- is name of failing module
PA XXXXXXXX	- is actual 22-bit physical address of error calls
APC YYYYYY	- is Assembled PC of error call
PASS#NNNNN	- is decimal pass number during which error occurred.
HARD ERR#NNNNN	- is total decimal number of hard errors encountered.
CSRA AAAAAA	- is address of Control Status Register for failing device (if any).
CSRA CCCCCC	- is contents of device CSR (if any).
STATC SSSSSS	- is contents of Device Status Register (if any).
ERRTYP NNNNN	- is octal code which defines the type of error (for meaning of code refer to DEC/X11 Cross Reference Manual).

Locating the error call that evoked the message:

Referring to the listing the user may locate the call which evoked the error message, by referencing the address defined by the Assembled Program Counter (APC YYYYYY) printout. To facilitate this task, all error calls are clearly emphasized within the listing by a boundary of asterisks(*).

Extended Soft and Hard Error Printouts

xtended Soft and Hard Error messages contain the same information described for Soft and Hard Error Printouts. With an extended printout, one or more additional lines of error information are provided which may consist of up to eight octal values per line. The meaning of this additional data, for the module specified, may be found in the DEC/X11 Cross Reference Manual.

The following is an example of an Extended Hard Error printout:

```
ABCD0  PA XXXXXXXX  APC YYYYYY  PASS# NNNNNHARD ERR# NNNNN
CSRA AAAAAA  CSRC CCCCCC  STATC SSSSSS  ERRTYP NNNNN
XXXXXX  XXXXXX  XXXXXX  XXXXXX  XXXXXX  XXXXXX  XXXXXX  XXXXXX
```

Locating the error call that evoked the message is accomplished in the manner described in Soft and Hard Error Printouts.

Data Error Printout

With the exception of Extended I/O Modules (IOMODX), all test modules report data transfer errors via a Data Error printout, that is invoked by a DATER$ Call. The message is as follows:

```
DCAA0  PA XXXXXXXX  APC YYYYYY  PASS# MMMMM  ERR# NNNNN  DATA ERROR
CSRA AAAAAA  S/B BBBBBB  WAS WWWWWW  WRADR DDDDDD  RDADR EEEEEE
```

/here:

DCAAO	- is name of failing module.
PA XXXXXXXX	- is 22-bit physical address of Dater$ Call
APC YYYYYY	- is Assembled PC address of DATER$ Call.
PASS NNNNN	- is decimal pass number during which error occurred.
ERR NNNNN	- is total decimal error count for current test run.
CSRA AAAAAA	- is address of Control Status Register for failing device.
S/B BBBBBB	- is good expected data.
WAS WWWWWW	- is bad obtained data.
WRADR DDDDDD	- is write address of good and expected data.
RDADR EEEEEE	- is read address of bad and obtained data.

Locating the DATER$ Call that evoked the error message:

Referring to the listing, the user may locate the call that evoked the error message by referencing the address defined by the Assembled Program Counter (APC YYYYYY) printout. To facilitate this task, all DATER$ Calls are clearly emphasized within the listing by a boundary ɔf asterisks(*).

Monitor Data Error Printout

Data transfer errors associated with Extended I/O Modules (IOMODX) are detected by the monitor via a Check Data Call (CDATA$) request. This is necessary because the modules are not mapped contiguously with their write buffers. Thus, the data cannot be checked directly. In any case, a Monitor Data Error message is similar to a Data Error printout except for the following interpretations and additions:

- All errors detected within a given transfer (e.g., a 256 word block) will be counted as a single error (i.e., ERR# 00001).
- The count will not be indicated until each error has been reported by a separate printout. The reporting of all errors depends on the setting of SR10 (SR10 = 1). If the switch is cleared (SR10 = 0), only three such errors will be reported.
- An additional summary message is provided which defines the total decimal number of errors that have occurred during the transfer.

The Monitor Check Data Error Printout is as follows:

```
RKAF0 PA XXXXXXXX APC YYYYYY PASS# NNNNN ERR# NNNNN DATA ERROR
CSRA AAAAAA S/B BBBBBB WAS WWWWWW WRADR DDDDDD RDADR EEEEEE
RKAA0 HAD NNNNN ERRORS OUT OF 256 WORDS READ
```

Memory Management Error Printout

Aborts and traps generated by the Memory Management Unit (KT11) are vectored through virtual location 250. The Memory Management Status Registers (SR0 through SR3) are used to differentiate an abort from a trap, determine why one or the other ocurred, and allow for a program restart.

The following printout accompanies a Memory Management abort or trap:

```
*** KT TRAP ***
 SR0     SR2             ;identifies SR0 and SR2
CCCCCC  CCCCCC           ;contents Of SR0 and SR2
 SR1     SR3             ;if SR1 and SR3 are available,
CCCCCC  CCCCCC           ;contents of SR1 and SR3
```

Memory Parity Error Printout

Aborts and traps generated by Main or Cache Memory parity errors or Main Memory ECC errors are vectored through virtual location 114. The Control Status Register (CSR) will contain the failure information.

The following printout accompanies a memory parity or ECC error:

```
**** TRAP THROUGH VECTOR 114 ****
 CSR     CONTENTS ;AAAAAA = address of CSR(parity or ECC)
AAAAAA   BBBBBB   ;BBBBBB = contents of CSR
```

ad Vector Printout

The Bad Vector message indicates that the address pointer is invalid since an Interrupt Service Routine cannot be located. This error will not interfere with the operation of the RTE However, the module containing the faulty pointer will not output on End-Of-Pass and will therefore eventually be dropped if a system clock is available. The message is as follows:

```
BAD VECTOR:  200             ;vector 200 is invalid for device
```

When the faulty module is found, Word 10 of the module header may be corrected via hardware documentation or module abstract analysis.

Special System Error Printouts

If a system error occurs in a PDP-11/60 or 11/70 Processor (with an associated DEC/X11 Monitor), related Error Log messages are output in addition to the standard System Error printout previously described.

For a PDP-11/60, the following is included with the System Error printout:

```
11/60 ERROR LOG

JAM/XXXXXX SRV/XXXXXX PBA/XXXXXX CUA/XXXXXX
   FLG-INT/XXXXXX WHAMI/XXXXXX CDATA/XXXXXX CTAG-CPU/XXXXXX
```

Where:

JAM	-	is JAM Register status
SRV	-	is Service Register of status
PBA	-	is Physical Bus Address Register (bits 16,17)
CUA	-	is Microprogram Address
FLG/INT	-	is Flag Request Register of status/last interrupt vector serviced
WHAMI	-	is various Processor Option Status bits
CDATA	-	is Cache Memory data word
CTAG/CPU	-	is Cache memory Tag Data/Hit Register

For a PDP-11/70, the following is included with the System Errror printout:

```
11/70 ERROR LOG

MEMERREG/XXXXXX CPUERREG/XXXXXX
ADDR/XXXXXXXX          ;only output if parity error
```

Where:

MEMERREG	-	is Memory System Error Register

CPUERREG - is CPU Error Register
ADDR - is 22-bit address of parity error location

3.3.3.4.3 Debug Recommendations

The following material is intended to initially provide a general, common-sense check list for analyzing and isolating faults that may occur during the debugging of a newly created RTE program. This is followed by several examples of both problems that can occur and debugging procedures that may be applied.

If errors occur during the testing of a newly created RTE program, one of the following may prove helpful in isolating the problem:

- Check Software parameter such as VCT, BR1, SR1, etc...
- Eliminate the possibility of a peripheral error by changing tapes, cleaning heads, changing disk packs, etc.
- If a device failure is indicated, try running a stand-alone diagnostic.
- If hardware system failures are persistent and/or varied, try running the program on another system (if practical).
- If multiple module failures occur, try running the program locked in different banks, via a Run Lock Command (RUNL).
- If a specific module fails, try running it alone or with others in varied combinations.

Two examples of possible failures and suggested trouble-shooting procedures follow:

Problem 1

A total of five modules are running when a specific module fails.
;Trouble-shoot as follows:
The goal of this procedure is to cause the failure to reoccur with the least number of modules running, being aware that certain combinations of hardware running at the same time can cause such failure.

With this in mind, run the failing module first by itself. This can be done by deselecting all of the modules while the RTE is running (BSY>) and then selecting the failing module, as follows:

```
.DES <CR>                    ;deselect all modules
.SEL MODX0 <CR>              ;select failing module first
```

If the failure reoccurs, isolate the problem within the module or run a device/option diagnostic. If the fault does not reoccur, selectively add each of the remaining modules one at a time until the failure is repeated.

Problem 2

Although Software Switch Register Bit 12 is set (SR12 = 1) to cause an END OF PASS printout, a module (other than a Background Module) has not output such a message, or any message, since the run began.

Trouble-shoot as follows:

The goal of this procedure is to determine if the module in question is indeed running; and if it is not (and should be), to determine the reason by tracing the execution of the module's code.

As stated, it is assumed that the module in question is not a Background Module (BKMOD). Therefore it may be any one of the following:

. Non-Restartable Background Module (NBKMOD)

. Special Background Module (SBKMOD)

. I/O Module (IOMOD)

. I/O Module Extended (IOMODX)

. I/O Module Restricted (IOMODR)

. I/O Module Partially Restricted (IOMODP)

The first step is to determine if the module has been selected. This may be accomplished, while the RTE is running (BSY>), by invoking a summary printout for the specified module (SUM modulename) and examining the Status Word to see if the Select Bit (14) is set. If the Select Bit is set, the Active Bit (11) must also be set for the module to run while the Dropped Bit (13) must be clear. However, although a cleared Active Bit (bit 11 = 0) in the summary indicates that the associated module is not running, it does not necessarily indicate an error condition. Whether an error exists or not depends on which of the six module types is being analyzed. For example, under certain relocation conditions where boundary restrictions exist, four of the module types (NBKMOD, SBKMOD, IOMODR, IOMODP) are not permitted to run (i.e., the Active Bit will not be set until a favorable relocation occurs). However, if the Active Bit is clear and the module in question is a type unaffected by such restrictions (IOMOD and IOMODX), and should be running, a software problem exists.

If the Select Bit is set (bit 14 = 1), the Active Bit is set (bit 11 = 1), and the Dropped Bit is clear (bit 13 = 0), the defined module types should be running. To make such a determination under these conditions, the user may dynamically examine the Iteration Count (Location 40) for periodic increases (via an EXAM mdoulename addr

Command). If no increase is detected, the user may then stop the program and selectively insert (via a MOD modulename addr Command) a Halt Instruction in the module code in order to isolate the error. For example, in the case of the I/O module types (IOMOD, X,R,P,), a Halt is placed in the module's Interrupt Routine and, if the device interrupt is working, a halt will occur when the program is restarted. If a halt does not occur, it may be assumed that the device is defective.

APPENDIX A

Following is a sample build of a RTE from pre-build planning thru the linking process.

System configuration consists of the following:
- 11/70
- 256K of Memory
- Extended Instruction Set
- Cache
- Floating Point Hardware
- 1-RM03 Single Port Disk
- M9312
- 2-TM03/TE16
- 1-LP11
- 1-RS04
- 1-DH11

SHEET 1 of 1

DEC/X11 System Configuration Worksheet

Selected DEC/X11 Monitor For Listed CPU and CPU options: E

FILE: ESAMCO.BIN DATE: 20 SEPT 78

DEVICE	MOD	R	DVA	VCT	BR1	BR2	DVC	SR1	SR2	SR3	SR4
RM03	RMD	A	176700*	254*	5*	0*	1*				
LP11	LPA	A	177514*	200*	4*	0*	1*	77000			
TM03/TE16	TMB	A	172440*	224*	5*	0*	2				
RS04	RSA	A	172040*	204*	5*	0*	1*				
DH11	DHA	A	160200	300	5*	5*	1*				
EIS	CPB	A									
11/34 Instr.	CPA	A									
FP11-C	FPB	A									
M9312	BMH	A									

*   DENOTES SOFTWARE DEFAULTS PARAMETERS

At this time we are ready to start building the Configuration Table. This is done by running the Configurator/Linker.

```
$DK0<CR>                                  ;Boot the Load Medium
-

CHMDKB0 XXDP+ DK MONITOR
-----------------------
BOOTED VIA UNIT#:  0
----------------
28K UNIBUS MEMORY
-----------------
ENTER DATE (DD-MMM-YY):
-----------------------
RESTART ADDR:152010
-------------------
THIS IS XXDP+.  TYPE "H" OR "H/L" FOR HELP.
-------------------------------------------
TYPE:  <^C>                               ;Abort XXDP+ Header Message
-----
.R DXCL                                   ;Run the Configurator/Linker
-
                                         ;Program

CHUXCC0 XXDP+ DEC/X11 CNF/LNK
-----------------------------
RESTART:  006472
--------
DO YOU WANT HELP?(Y <CR> OR JUST <CR>) <CR> ;Inhibit help message
--------------------------------------

*CNF<CR>                                  ;Enter CNF mode
-

MONITOR:  E<CR>                           ;Enter Monitor name
--------

MDL RMDA<CR>                              ;Enter Module RMDA
DVA-<CR>
----
VCT-<CR>
----
BR1-<CR>
----
BR2-<CR>
----
DVC-<CR>
----
SR1-<CR>
----
SR2-<CR>
```

```
----
SR3-<CR>
----
SR4-<CR>
----
RMAA  DVA-000000 VCT-000000 BR1-000000 BR2-000000 DVC-000000
        SR1-000000 SR2-000000 SR3-000000 SR4-000000

MDL LPAA<CR>                                  ;Enter Module LPAA
DVA-<CR>
----
VCT-<CR>
----
BR1-<CR>
----
BR2-<CR>
----
DVC-<CR>
----
SR1-77000<CR>                                 ;Change LPAA SR1 value
----
SR2-<CR>
----
SR3-<CR>
----
SR4-<CR>
----
LPAA  DVA-000000 VCT-000000 BR1-000000 BR2-000000 DVC-000000
        SR1-077000 SR2-000000 SR3-000000 SR4-000000

MDL TMBA<CR>                                  ;Enter Module TMBA
DVA-<CR>
----
VCT-<CR>
----
BR1-<CR>
----
BR2-<CR>
----
DVC-2<CR>                                     ;Change TMBA DVC value
----
SR1-40<CR>                                    ;Change TMBA SR1 value
----
SR2-<CR>
----
SR3-<CR>
----
SR4-<CR>
----
TMBA  DVA-000000 VCT-000000 BR1-000000 BR2-000000 DVC-000003
        SR1-000040 SR2-000000 SR3-000000 SR4-000000

MDL RSAA<CR>                                  ;Enter Module RSAA
DVA-<CR>
----
```

```
VCT-<CR>
----
BR1-<CR>
----
BR2-<CR>
----
DVC-<CR>
----
SR1-<CR>
----
SR2-<CR>
----
SR3-<CR>
----
SR4-<CR>
----
RSAA  DVA-000000 VCT-000000 BR1-000000 BR2-000000 DVC-000000
        SR1-000000 SR2-000000 SR3-000000 SR4-000000

MDL DHAA<CR>                           ;Enter Module DHAA
DVA-160200<CR>                         ;Change DHAA DVA value
----
VCT-300<CR>                            ;Change DHAA VCT value
----
BR1-<CR>
----
BR2-<CR>
----
DVC-<CR>
----
SR1-<CR>
----
SR2-<CR>
----
SR3-<CR>
----
SR4-<CR>
----
DHAA  DVA-160200 VCT-000300 BR1-000000 BR2-000000 DVC-000000
        SR1-000000 SR2-000000 SR3-000000 SR4-000000

MDL CPBA<CR>                           ;Enter Module CPBA
DVA-<CR>
----
VCT-<CR>
----
BR1-<CR>
----
BR2-<CR>
----
DVC-<CR>
----
SR1-<CR>
----
SR2-<CR>
```

```
----
SR3-<CR>
----
SR4-<CR>
----
CPBA  DVA-000000 VCT-000000 BR1-000000 BR2-000000 DVC-000000
        SR1-000000 SR2-000000 SR3-000000 SR4-000000

MDL CPAA<CR>                                ;Enter Module CPAA
 DVA-<CR>
 ----
 VCT-<CR>
 ----
 BR1-<CR>
 ----
 BR2-<CR>
 ----
 DVC-<CR>
 ----
 SR1-77000<CR>
 ----
 SR2-<CR>
 ----
 SR3-<CR>
 ----
 SR4-<CR>
 ----
CPAA  DVA-000000 VCT-000000 BR1-000000 BR2-000000 DVC-000000
        SR1-077000 SR2-000000 SR3-000000 SR4-000000

*MDL FPBD<CR>                               ;Enter Module FPBD
-
 DVA-<CR>
 ----
 VCT-<CR>
 ----
 BR1-<CR>
 ----
 BR2-<CR>
 ----
 DVC-2<CR>
 ----
 SR1-40<CR>
 ----
 SR2-<CR>
 ----
 SR3-<CR>
 ----
 SR4-<CR>
 ----
FPBA  DVA-000000 VCT-000000 BR1-000000 BR2-000000 DVC-000003
        SR1-000040 SR2-000000 SR3-000000 SR4-000000

*MDL BMHA<CR>                               ;Enter Module BMHA
-
```

```
 DVA-<CR>
 ----
 VCT-<CR>
 ----
 BR1-<CR>
 ----
 BR2-<CR>
 ----
 DVC-<CR>
 ----
 SR1-<CR>
 ----
 SR2-<CR>
 ----
 SR3-<CR>
 ----
 SR4-<CR>
 ----
BMHA  DVA-000000 VCT-000000 BR1-000000 BR2-000000 DVC-000000
        SR1-000000 SR2-000000 SR3-000000 SR4-000000

*EX<CR>                                  ;Leave CNF mode
-

*LINK DK0:ESAMC0.BIN<DK0:XMOND0.LIB<CR> ;Enter the LINK Command
-     ----                 -------

Device not on system

SYS SIZE:160000                          ;Enter System Size
---------

MAKE OUTPUT READY.  WRITE ENABLE
--------------------------------
TYPE <CR> WHEN READY.  <CR>

PASS 1
------

TRANSFER ADDRESS: 02200
-----------------------
LOW LIMIT: 000000
-----------------
HIGH LIMIT: 122660
------------------

PASS 2
------

LINK DONE
---------

*SAVC DK0:CSAMC0.CNF                     ;Save the Configuration table
-
DONE
```

```
----
*SAVM DK0:MSAMC0.MAP                ;Save the exerciser load map
-
DONE
----

*EXIT
```

FOLLOWING IS AN EXAMPLE USING CNF/NP:

```
*CNF/NP                             ;Enter CNF mode with prompting
-
                                    ;inhibited

MONITOR: E                          ;Enter Monitor name
--------

*MDL RMAA<CR>                       ;Enter module RMAA
-

*MDL LPAA<CR>                       ;Enter module LPAA
-

*SR1 77000                          ;Change LPAA SR1 value
-

*MDL TMBA<CR>                       ;Enter module TMBA
-

*DVC 2                              ;Change TMBA DVC value
-

*SR1 40                             ;Change TMBA SR1 value
-

*MDL RSAA<CR>                       ;Enter module RSAA
-

*MDL DHAA<CR>                       ;Enter module DHAA
-

*DVA 160200<CR>                     ;Change DHAA DVA value
-

*VCT 300<CR>                        ;Change DHAA VCT value
-

*MDL CPBA<CR>                       ;Enter module CPBA
-

*MDL CPAA<CR>                       ;Enter module CPAA
-

*MDL FPBA<CR>                       ;Enter module FPBA
```

```
-

*MDL BMHA<CR>                              ;Enter module BMHA
-

*EX                                        ;Leave CNF mode
-

*LINK DK0:ESAMC0.BIN<DK0:XMONA0.LIB<CR> ;Enter the LINK Command
-

SYS SIZE:  160000
---------

MAKE OUTPUT READY.  WRITE ENABLE
-------------------------------
TYPE <CR> WHEN READY.<CR>
---------------------
DELETE OLD?  (Y<CR> OR JUST <CR>)Y<CR> ;Delete old file named
--------------------------------
                                           ;ESAMC0.BIN

PASS 1
------

TRANSFER ADDRESS: 002200
------------------------
LOW LIMIT: 000000
-----------------
HIGH LIMIT: 122660
------------------

PASS 2
------

LINK DONE
---------
*SAVC DK0:CSAMC0.CNF                       ;Save the Configuration table
-
DONE
----

*SAVM DK0:MSAMC0.MAP                       ;Save the exerciser load map
-
DONE
----

*EXIT                                      ;type EXIT not EX to exit link.
```