

THE DIGITAL GROUP

C A S S E T T E    S T O R A G E    S Y S T E M

CSSB-0-RØ

the digital group

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## I. INTRODUCTION

The Digital Group Cassette Storage System is a total magnetic tape data storage and retrieval system capable of controlling up to four Phi-Deck cassette transports and accessing any of over one million 8-bit bytes within 20 seconds, using standard C-30 Phillips cassettes.

The system is ideal for general purpose data and program storage, file copying, editing, and sorting operations. Each deck is fully controlled to prevent tape breakage. Electronic braking precisely controls tapes for fast forward and rewind operations. A 4- to 5-bit translation scheme called Group Coded Recording, allows higher packing densities with a soft error rate of less than one bit in  $10^8$ . This system operates at 1600 flux changes per inch, yielding a data transfer rate of 800 bytes per second at a tape speed of five inches per second.

## SPECIFICATIONS

Recording Density: 1600 FCPI (Flux Changes Per Inch)

Data Density: 1280 BPI (Bits Per Inch)  
using 4- to 5-bit Group Coded Recording

Data Rate: 800 Bytes per second (6400 Baud)

Data Capacity: 250,000 bytes on each side of a C-30 audio cassette  
540,000 bytes on each side of 300 foot data cassette

Tape Speed: 5 IPS Read/Write  
100 IPS Fast Forward/Reverse

Speed Tolerance: ±20% (i.e., the system will read a tape that was recorded 20% from the nominal speed without adjustment. It will read tapes outside this range by adjusting the data rate control.)

Error Rate: Soft - less than 1 bit in  $10^8$   
Hard - virtually zero when using the software package supplied with the system and a good quality audio tape

Power: +5V DC ±5%  
1.0 Amps nominal 1 drive  
2.0 Amps maximum 4 drives  
4.0 Amps peak for .1 second during drive enable

+12V DC unregulated (limits: 11V-20V)  
0.4 Amp average with tape moving  
0.7 Amp peak during motor start

## II. SOFTWARE INTERFACE

Since the absolute method of controlling the cassette system will differ for each installation, only a basic interface will be described. The user can then modify the basic interface to meet his own requirements.

### COMMANDS

The command port (see Table 2.1) interprets the various commands into tape motion and activates the read/write electronics. The two select bits, SEL1 and SEL2, select the active deck, according to Table 2.2. The selected deck can only be changed when all decks are stopped (status bit NOT BUSY is on). Otherwise, even though a command may specify a different deck, the original deck will be used. ENABLE/DISABLE (Enable=1, Disable=Ø) controls the deck capstan motors so that they may be turned off under software control. The capstan motors should be enabled during and at least one second prior to any other commands. STOP/RUN (Stop=1, Run=Ø) controls tape motion. The STOP command also takes up slack in the tape. FWD/REV (Fwd=1, Rev=Ø) controls tape direction, and SLOW/FAST (Slow=1, Fast=Ø) controls tape speed. Note that since "slow reverse" cannot be performed, a "slow forward" is automatically substituted. RCD/READ (Record=1, Read=Ø) controls the Read/Write electronics, and ERASE (=1) will erase the tape when RCD is selected. All commands other than the RECORD or ERASE commands should have RCD/READ=Ø to prevent recording spurious glitches on the tape.

Table 2.1

### Status and Command Ports

COMMAND PORT		STATUS PORT	
Bit	Definition (1 active)	Bit	Definition (1 active)
Ø	SEL 1	Ø	OVERRUN/UNDERRUN
1	SEL 2	1	READY (data ready or ready for data)
2	l=ERASE	2	STOP (possible jam or end of tape)
3	l=RECORD	Ø=READ	3
4	l=STOP	Ø=RUN	NOT BUSY (user may change decks)
5	l=FORWARD	Ø=REVERSE	
6	l=SLOW	Ø=FAST	
7	l=ENABLE	Ø=DISABLE	

Table 2.2

### Deck Selection

SEL 2	SEL 1	DECK
Ø	Ø	Ø
Ø	1	1
1	Ø	2
1	1	3

## STATUS

The status port (see Table 2.1) provides information on the state of the controller. Four status bits are brought out, leaving four input bits for other uses. Two of the bits, STOP and NOT BUSY, supply information on the deck status. STOP is an immediate response to a stop command or a jam. NOT BUSY occurs about a second after STOP turns on, signifying the deck is totally stopped. STOP is used by the software in all cases, except to switch the selected deck, which can only occur in a not busy state. The other two bits are status bits for the read/write electronics. READY indicates that the deck can accept another data byte (in Record) or that a new data byte is in the DATA-OUT port (in Read). READY is reset about one millisecond after it is set. It is also reset by a command, data in, or data out strobe. OVERRUN/UNDERRUN indicates that the computer has not serviced a READY by supplying or looking at the new character within the required time. It will remain set until a new command is issued. It is to be treated in most cases as an error condition.

## INPUT DATA (FOR RECORD)

The data input port requests the data bytes which are to be recorded on the tape. The first byte should be loaded either prior to issuing the record command or within about five milliseconds after issuing the record command. Each subsequent byte of data to be recorded should be loaded when the READY status goes high. Loading the new byte will automatically reset the READY line. The byte should be loaded within .5 milliseconds after the READY signal. Otherwise, OVERRUN/UNDERRUN will come on, and the record electronics will go into erase mode. This may be allowed to happen at the end of a data block in order to record an inter-record gap. If a new command is to be given immediately after the last recorded byte, the OVERRUN/UNDERRUN bit must come on before the command is given. If the command is issued earlier, part of the last byte will not be recorded.

## OUTPUT DATA (FOR READ)

The data output port is loaded by the read/write electronics with the data being read from the tape: After issuing a read command, the electronics will look for a sync pattern and then load the output port with the first data byte. At this time, READY will go high. When the byte is read, the READY signal will be reset. The byte should be read within .5 milliseconds after the READY signal. Otherwise, OVERRUN/UNDERRUN will come on, and the read electronics will be halted until another read command is issued.

## MECHANICAL CONSIDERATIONS

Since the various tape and head movements require certain amounts of time to stabilize, consideration must be given by the software to insure error free read and record operations.

1. Never issue a record command (or turn on the record bit) when the tape is in any state other than slow forward, and the tape is stabilized against the head. The tape may take as much as one second to align itself with the tape guides on the head and an unaligned tape may record errors. A good practice to insure reliable recording is to read the previous block without error. This implies the tape is tracking correctly for the record operation.
2. When issuing a read command which causes the head to come up against the tape, noise and random patterns as the tape becomes aligned may cause false synchronizing and give erroneous read data. Therefore, it is a good practice in this situation to wait about a second, and then reissue the read command, using only the data from this second read command.
3. When recording the first block of data at the start of a tape, issue an erase command, and then time out about five to seven seconds to allow the tape leader to pass before recording data.
4. To allow the recording of two consecutive blocks at different points in time, always go into erase mode after recording the first block for a time longer than the space between blocks. (This is easily done by ignoring the READY after the last byte has been recorded, and timing out for the erase time. The electronics will immediately begin erasing without glitching) When the next block is to be recorded, it is begun somewhere within the erased section, thus preventing any glitching and subsequent false synchronizing on read operations.

The following bit patterns are recommended for issuing the various commands:

<u>COMMAND</u>	Bit:	<u>ENABLE</u>	<u>SLOW FST</u>	<u>FWD/ BKW</u>	<u>STOP RUN</u>	<u>RECORD HEAD</u>	<u>ERASE</u>	
38-	STOP	1	1	1	1	0	0	Selected Deck
24-	FAST FORWARD	1	0	1	0	0	0	(Note: Selected deck may
20-	FAST REVERSE	1	0	0	0	0	0	only be changed
34-	READ	1	1	1	0	0	0	when status bit
35-	RECORD	1	1	1	0	1	0	NOT BUSY is on.)
35(4+)	ERASE	1	1	1	0	1	1	
16-	STANDBY	0	1	1	1	0	0	

### III. HARDWARE INTERFACE

#### Computer Interface

The basic interface of the cassette controller to the computer occurs through four controller I/O ports. These ports may be connected in various schemes to fully utilize the hardware arrangement of the computer.

The computer's output ports connect to the command port and the data-in port. The computer's input ports interface to the data-out port and the status port. Each port has its own strobe line which is used either to strobe information into the internal latch or to activate the tri-state output in order to read the port.

All outputs from the controller will support ten TTL loads, and all data or control inputs are one TTL load. The command strobe is two TTL loads, the data-in strobe is three TTL loads, the status strobe is four TTL loads, and the data-out strobe is five TTL loads. The data-out and status ports are tri-state, activated by their respective strobes. All strobe signals are active low, and should remain high when not in use. The command data-in and data-out strobes should be low for a period greater than 500nsec, but less than one millisecond. A strobe greater than one millisecond is likely to cause false status indication from the read/write electronics.

Some typical connections are shown below. Figure 3.1 depicts a setup where all input and output ports are provided by the computer. Unless all strobes are obtainable from the computer, a third output port will have to be dedicated for software controlled strobe pulses. The scheme in Figure 3.2 uses this strobe port, but takes advantage of a bus system, since the strobes are no longer tied to specific ports but are under software control. Figure 3.3 uses a bus system found on more complex systems. Here, inputs and outputs are shared on the same line and controlled totally by the strobe signals. Care should be taken when using this method not to load the bus beyond its capacity.

#### Deck Interface

The cassette controller must also be interfaced to the decks. Refer to Figure 5.1 for the wiring of the decks. The board has four separate connections for each of four decks on all pins except ALLCAP, CAPSUPPLY, ALLENGSW, and ALLENGSWGND. The connectors supplied with the deck cables (when decks are included with the controller) will plug into connections for decks 0 and 1. When decks 2 and/or 3 are used, the above signals must be wired into the connector for deck 0 or 1. Also, HDGND is a common head ground, and all cable shields must be terminated at these two pins.

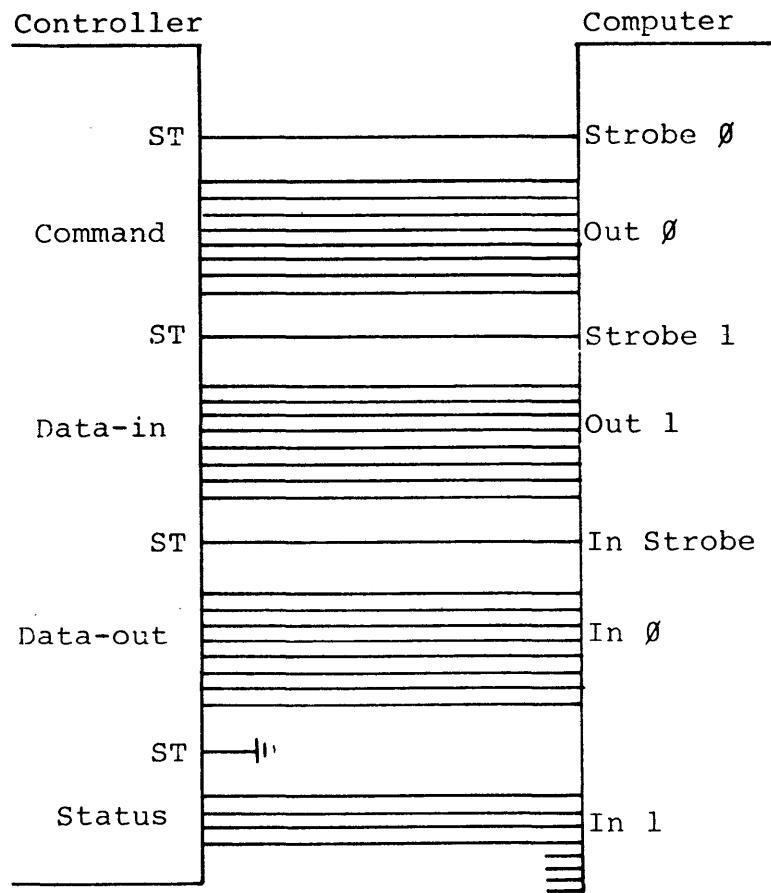


Figure 3.1 Dedicated I/O Ports

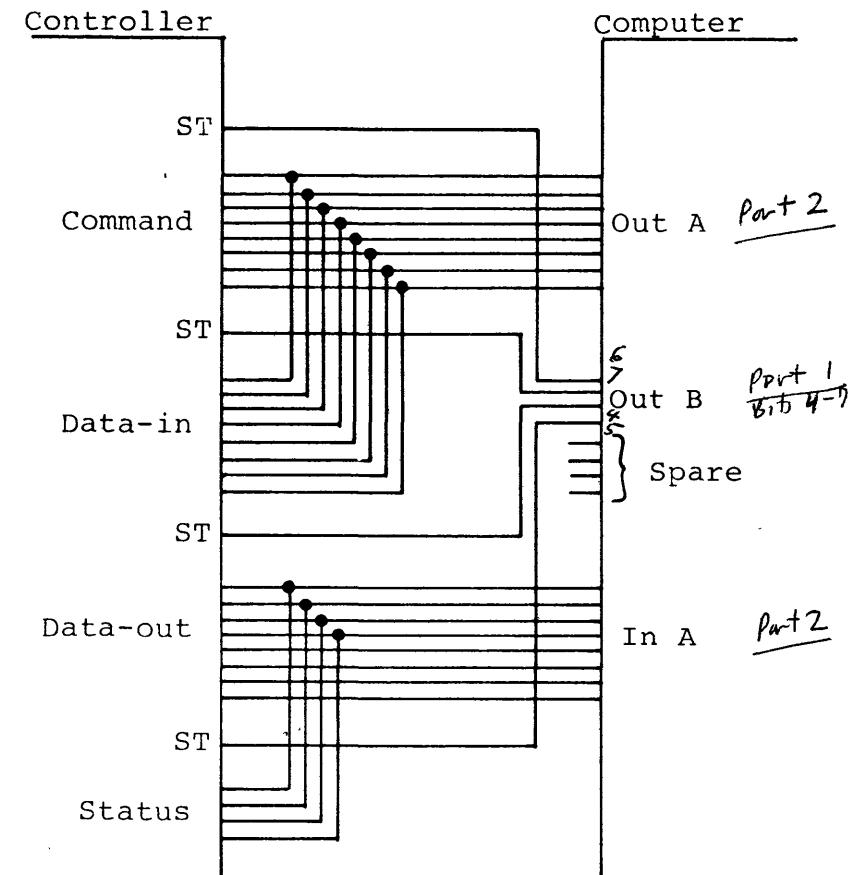


Figure 3.2 Multiplexed I/O Ports with Dedicated Strobes (Used with Digital Group Systems)

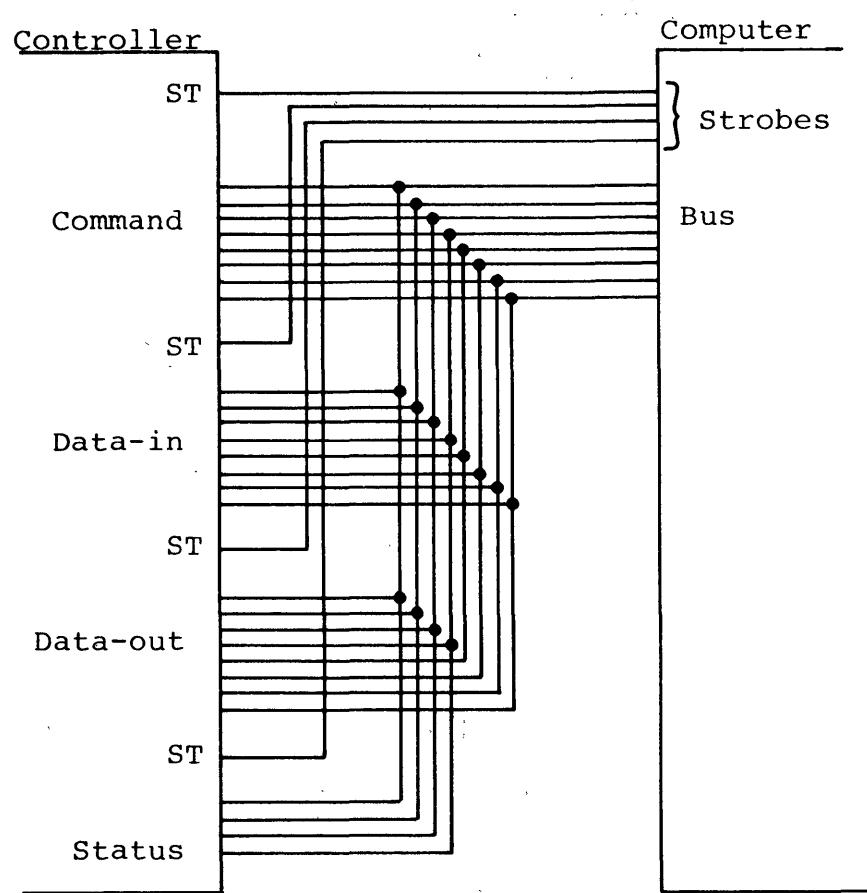


Figure 3.3 Bus Oriented Ports

#### IV. THEORY OF OPERATION

##### HEAD ELECTRONICS

The head electronics consists of IC27 and IC28 which drive the head during record and IC13 which amplifies the head signal during read. IC27 and IC28 (75125's) have tri-state outputs which normally are in the high impedance state during a read operation so that they won't influence the low level signal going from the head to the amplifier (IC13). During record, only the sections of IC27 and IC28 associated with the selected drive go into a low impedance state and drive the head in a push-pull manner. R6, R9, R20, and R23 are used to limit the current through the head and should be adjusted for a current of 1.5 times the head saturation current if the standard head is not used. Figure 4.1 shows typical waveforms for the record drivers.

During a read operation, section 1 of IC 13 is used as a pre-amp with balanced inputs and a gain of 3.9. Section 2 is an amplifier with a gain of 22. Section 3 is a low-pass filter and differentiator which produces zero crossings at its output whenever the input signal has a peak. The low-pass filter reduces the differentiator's sensitivity to noise. Section 4 is a Schmitt trigger which detects the zero crossings and produces a TTL compatible signal at its output. Figure 4.2 shows typical waveforms for the read electronics.

##### BIT SYNCHRONIZING ELECTRONICS

This section of the controller is used to generate the proper fixed frequency clocks for record and variable frequency clocks synchronized to the data during read. The data is also converted from NRZI encoding to level encoding. This section of the electronics consists of IC9, IC37, IC50, IC41, IC42, IC55, IC10, IC11, T13, and associated logic and components.

IC9 oscillates at 14 times the bit rate (it takes ten of these bits for every eight bit data byte that is recorded) and is adjusted using R28. During read, IC37 and its associated reset circuitry divides the OSC signal by 8 if the data is coming in slow, by 7 if the data is coming in on frequency, and by 6 if the data is coming in fast. The incoming data rate is checked every time there is a data bit of value "1". There is no correction for data bits of value "0". This compensates for small rapid variations in tape speed. Large speed variations generate a DC error voltage with IC10 and IC11 which is fed back to the control input of oscillator IC9. During record, IC37 divides OCS by 7 and T13 turns off the DC feedback loop.

##### GROUP CODED RECORDING

Since a flux density of 1,600 flux changes per inch was incorporated, a special effort was made to also increase bit density in a packing scheme which maintains self-synchronization. Figure 4.4 illustrates this convention, group-coded recording, in a comparison with some older methods.

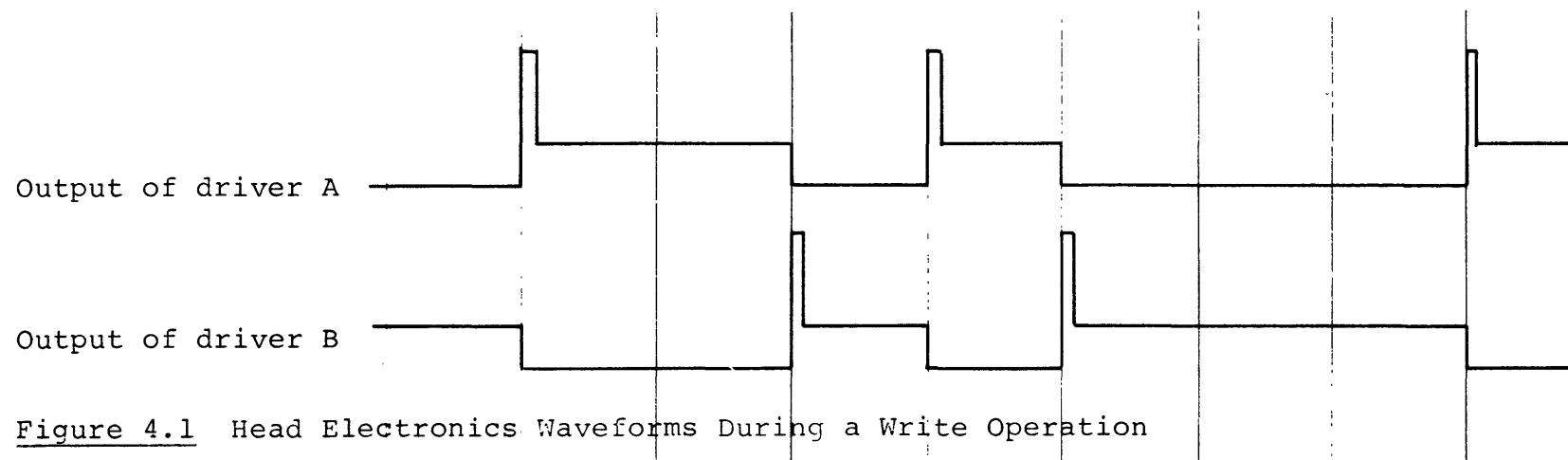


Figure 4.1 Head Electronics Waveforms During a Write Operation

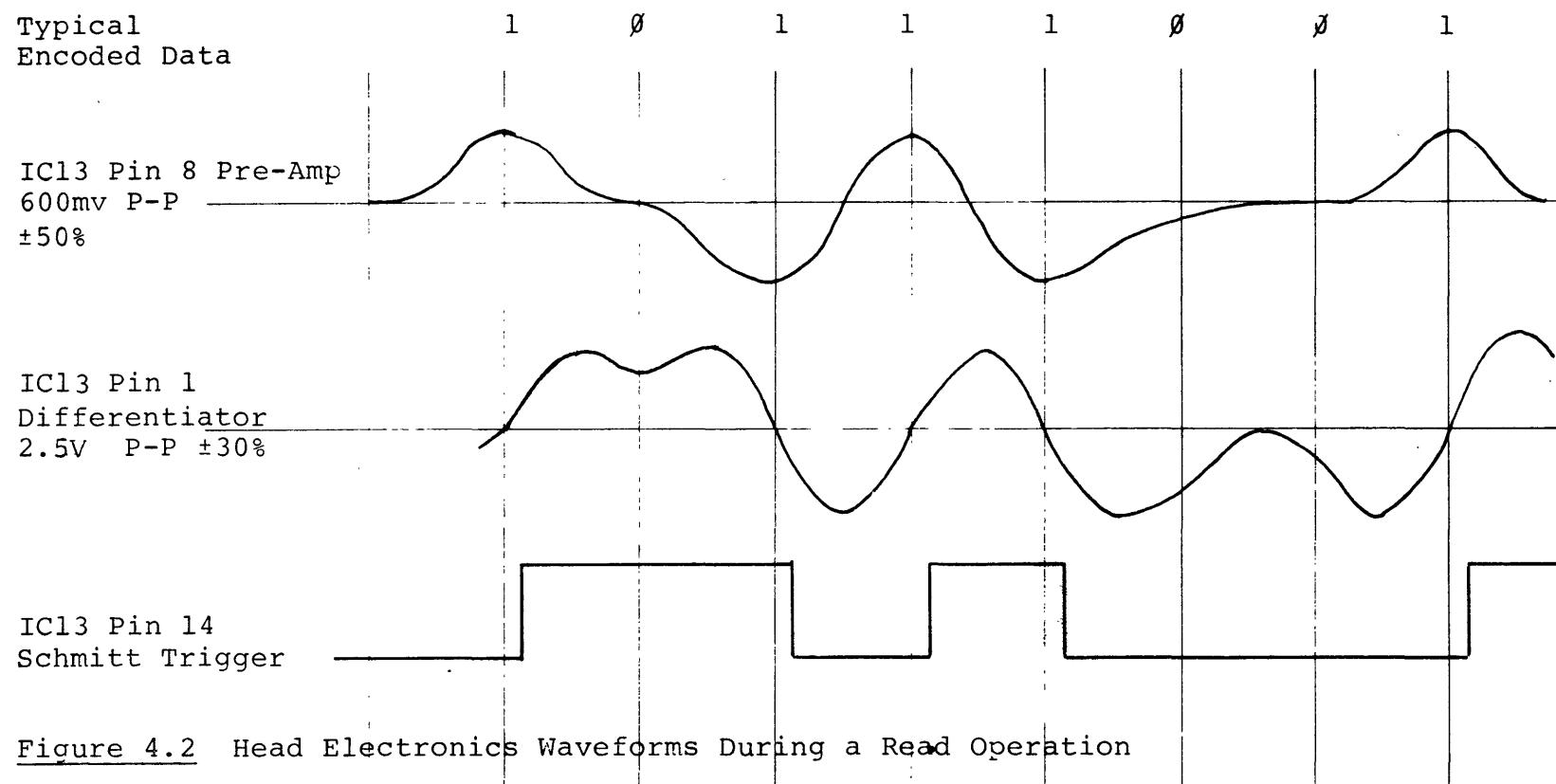
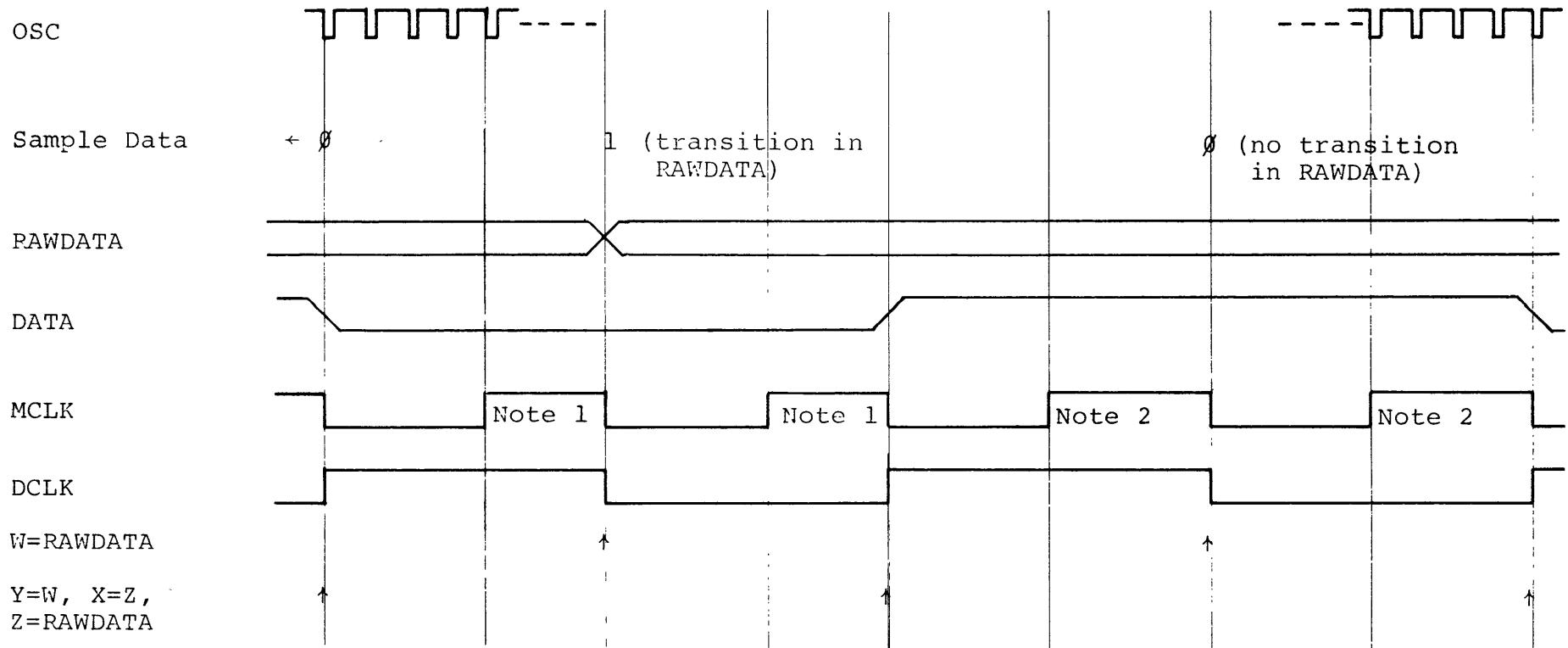


Figure 4.2 Head Electronics Waveforms During a Read Operation



Note 1: This pulse is always 3 OSC cycles if DATA is Ø or RECORDING.  
 Note 2: This pulse is either 2 or 4 OSC cycles if incoming data is fast or slow respectively and DATA is 1.

Figure 4.3

Bit Synchronizer Timing

NRZI, non-return-to-zero, illustrates a recording efficiency of 1.0, where recording efficiency is defined as the highest ratio of BPI (bits per inch) to FCPI for a given format. There is, at most, only one flux change per bit. Unfortunately, this is not a self-clocking scheme, and is therefore impractical for use on a cassette system which has inherent speed fluctuations.

PE, phase encoding, was designed to overcome such limitations by providing a flux change at the center of each bit period which would synchronize a clocking circuit. The direction of this flux change indicates whether the bit is a 1 or Ø. The recording efficiency of this method, however, is only Ø.5.

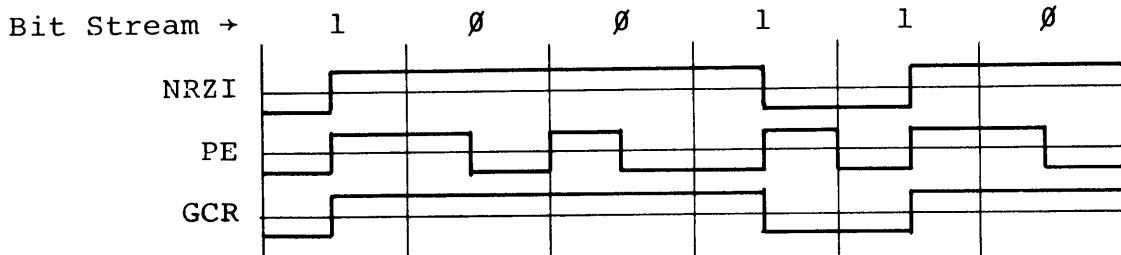


Figure 4.4 Recording Methods

GCR, group-coded recording, at first glance appears very similar to the efficient NRZI method, but with one important difference: No more than two zeros may appear in a row in the bit stream. This guarantees a clock pulse at least once every three bits which provides synchronization. Since a restriction of no more than two zeros in a row cannot be placed on data, a translation scheme is used to encode 4-bit groups into 5-bit groups, and the above restriction is then placed on the 5-bit groups. The translation table is shown in Table 4.5. Since the format is essentially NRZI, we have 4 bits per 5 flux changes, or a recording efficiency of 0.8, which is 60% better than PE.

Table 4.5

4- to 5-Bit Translation Table

<u>4-Bit Data Value</u>	<u>5-Bit Recording Value</u>
0 0 0 0	1 1 0 0 1
0 0 0 1	1 1 0 1 1
0 0 1 0	1 0 0 1 0
0 0 1 1	1 0 0 1 1
0 1 0 0	1 1 1 0 1
0 1 0 1	1 0 1 0 1
0 1 1 0	1 0 1 1 0
0 1 1 1	1 0 1 1 1
1 0 0 0	1 1 0 1 0
1 0 0 1	0 1 0 0 1
1 0 1 0	0 1 0 1 0
1 0 1 1	0 1 0 1 1
1 1 0 0	1 1 1 1 0
1 1 0 1	0 1 1 0 1
1 1 1 0	0 1 1 1 0
1 1 1 1	0 1 1 1 1

### RECORDING FORMAT

A synchronous format is automatically added by the electronics to the data being recorded. Of all the 5-bit patterns possible for use in this system, the only pattern not used is 11111. Therefore, this pattern is sent 15 times at the beginning of a data block (75 ones). The purpose of using this pattern is twofold. First, since the start of a block must be found by dropping the head anywhere on the tape, the electronics searches for about 20 ones in a row, and this pattern only occurs at the block start. Second, the ones form a steady clock frequency and allows the self-correcting clocking circuitry to achieve sync in the fastest possible time.

After the ones are recorded, the five bit sequence, 00101, is recorded as a sync character. This particular sequence uniquely defines the absolute start of the block. At that point, the 4 high bits of the first byte are translated to 5 bits and recorded, and then the 4 low bits are translated and recorded. The rest of the bytes are recorded in a similar manner. If a new block is not immediately started, an erase signal will begin after the last byte. Figure 4.6 depicts the format.

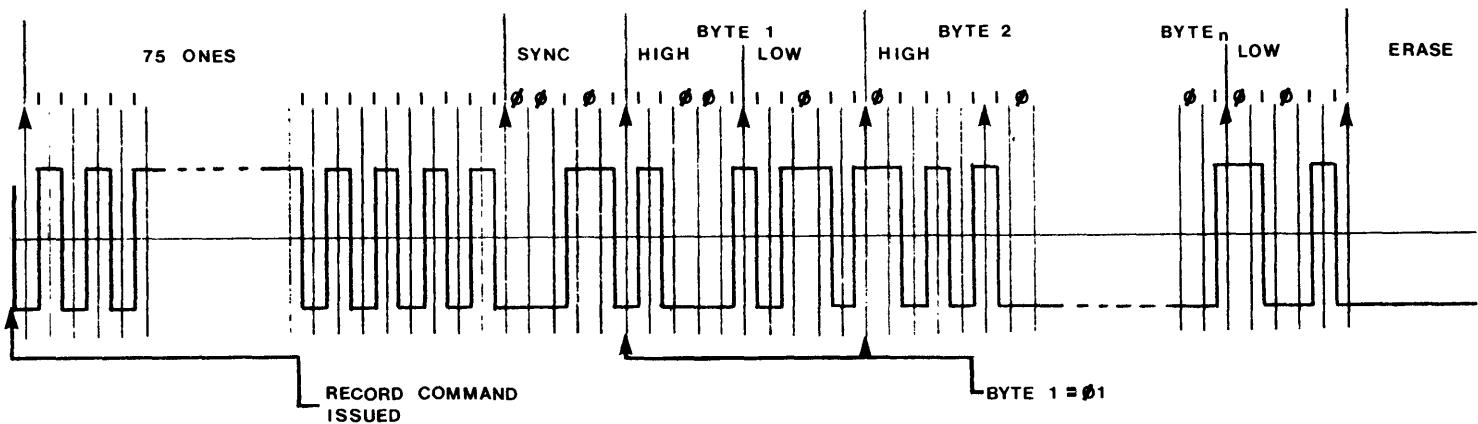


Figure 4.6

Recording Format

### DATA FLOW

Record - Data is strobed into IC46 and IC47 with the data input strobe. IC31 and IC32 select the half-byte to be recorded as well as the sync address. IC29 is a ROM which then encodes the 4-bit code into the 5-bit code and sends it to the 5-bit shift register, IC's 30, 5, and 24. The data is then shifted into IC4 which provides the record signal.

Read - Data from the read circuitry is clocked into the 5-bit shift register (IC's 30, 5, and 24). After each half-byte is loaded, data is routed through the selector (IC's 31 and 32) and into the ROM decoder (IC29). Here, the 5-bit code is decoded back into 4 bits and is loaded alternately into IC43 and IC44 to be strobed out.

#### CONTROL SEQUENCER

The flip-flops whose outputs are RECORD, RUN, B, and A control the sequence of events in the reading and recording processes. Refer to Table 4.7 for the valid sequencer states. The command strobe forces the "SEARCH FOR ONES" state immediately, and system clocks put the sequencer through the appropriate states when the strobe is removed.

For record mode, the sequencer will go to the "GENERATE ONES" state at the next CLOCK1 pulse. The system then waits for IC's 7 and 20 to count out 75 ones and produce the ONESDONE signal. During this time, the ONES signal forces IC29's chip enable to output all ones into the shift register. After the ones are recorded, "SEND SYNC" is entered which produces the SYNC-GEN signal to load a sync pattern into the shift register. Next, "RECORD A" is entered and selects the high bits of the data byte, loading them into the shift register. Finally, "RECORD B" loads and sends the low bits of the data byte. "RECORD A" and "RECORD B" are then alternately repeated until either the next command strobe, a tape stop or jam, or an underrun condition. The latter two events will force the sequencer to the "GAP" or erase state.

Table 4.7

#### Valid Sequencer States

<u>Function</u>	<u>State</u>			
	<u>RECORD</u>	<u>RUN</u>	<u>B</u>	<u>A</u>
GAP	1	Ø	Ø	1
GENERATE ONES	1	1	Ø	1
RECORD A	1	1	1	1
RECORD B	1	1	1	Ø
SEND SYNC	1	1	Ø	Ø
SEARCH FOR ONES	Ø	Ø	Ø	1
SEARCH FOR SYNC	Ø	1	Ø	1
READ A	Ø	1	1	1
READ B	Ø	1	1	Ø

For read mode, the sequencer remains in the "SEARCH FOR ONES" state until IC's 7 and 20 detect about 20 consecutive ones. If a zero occurs, IC7 is reset and the count begins again. When sufficient ones are found, ONEDET tells the sequencer to go to the "SEARCH FOR SYNC" state. Each read bit is then shifted into IC30 and all five bits in the shift register are selected and routed to the ROM. The SYNC signal occurs when the proper sync bit pattern is found. The "reset to 9" on IC20 is then released and the sequencer is synchronized to the data. Also, the "READ A" state becomes active, and the next five bits of data are shifted in, decoded, and loaded into IC43 as "READ B" is activated. The next five bits are operated on in the same way, except that IC44 is now loaded, and the sequencer goes back to state "READ A."

This sequencer repeats until either a command strobe or an overrun occurs. In the second case, the "SEARCH FOR ONES" state is again forced until the next command strobe.

#### DATA STATUS LOGIC

READY and OVERRUN/UNDERRUN are controlled by IC21 and only occur at the times the shift register or the data output latches are being loaded. READY is set at the end of state "RECORD B" as the second half-byte of data is loaded into the shift register. It must then be serviced by the time "RECORD A" is entered, since the new first half-byte of data is needed at that point. If READY is not reset at this point (by the input data strobe), OVERRUN/UNDERRUN will latch on.

In read mode, READY is set at the end of state "READ B." It is at this time that the second half-byte of data is loaded into IC44. IF the output data byte is not read before the next half-byte is loaded, the OVERRUN/UNDERRUN flag is latched on.

#### CLOCKS AND SYSTEM TIMING

There are four major clocking signals derived from a four-phase clock system. MCLK, the master clock, with DCLK, the data clock, generate ECLK, as in Figure 4.8.

IC20 is used to divide DCLK by 5 and get a signal, DIVIDE-BY-5, once every data half-byte. This is combined with other clock phases and sequencer states to obtain the clocks and signals shown in Figure 4.9.

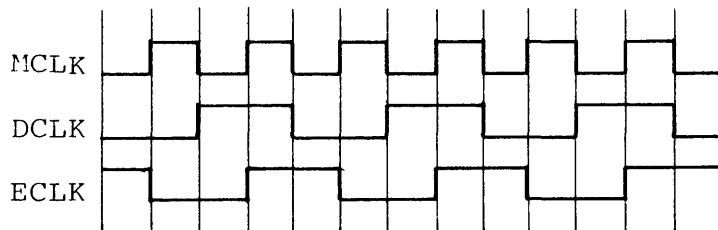


Figure 4.8

4-Phase Clocks

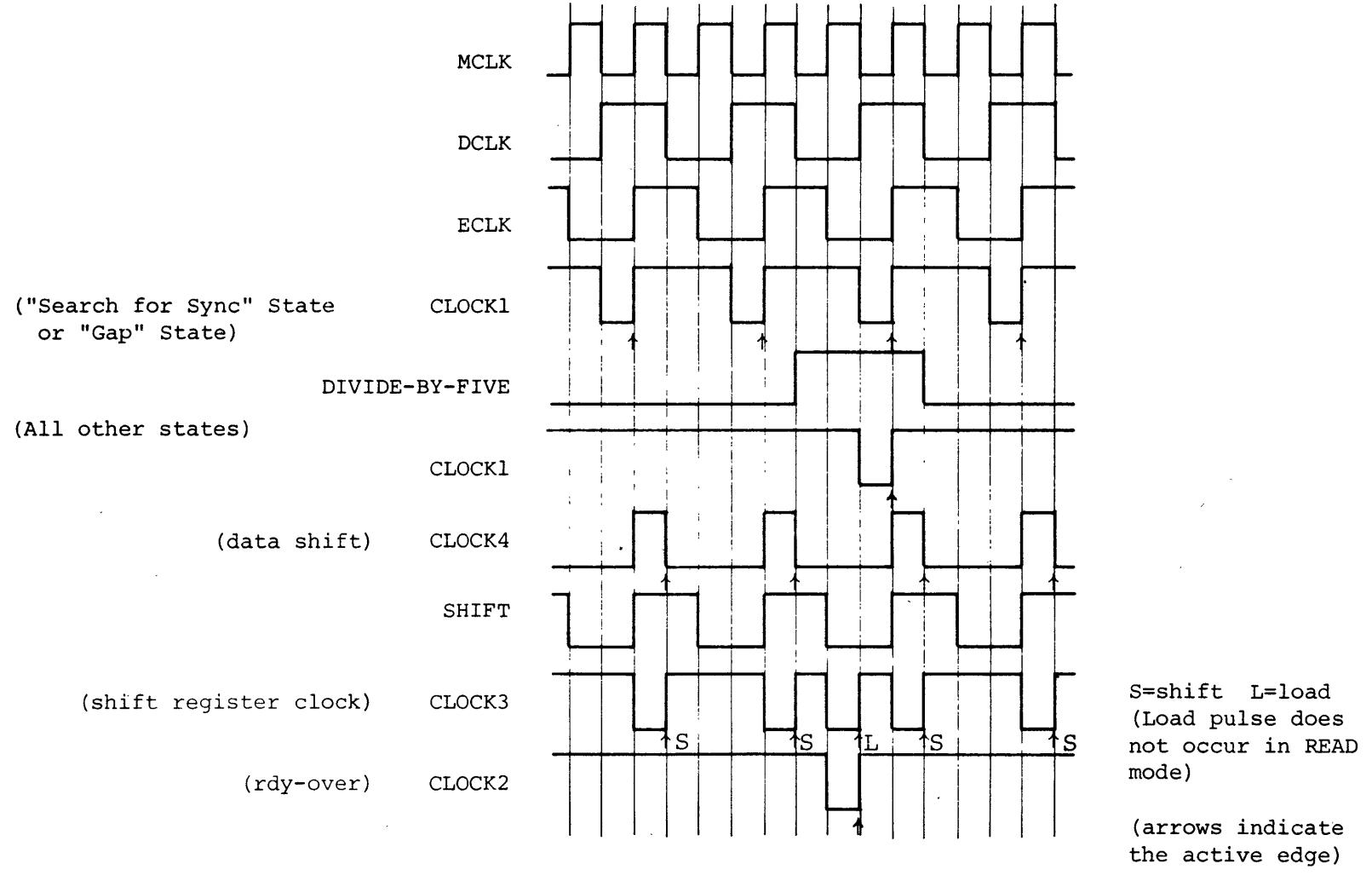


Figure 4.9

### MOTOR DRIVE AND SENSE ELECTRONICS

The purpose of this section of the controls is to provide drive to the motors, braking for the motors, deck selection, and sense tape motion for feedback to the motor control electronics.

TAKUPDRV goes to the low state whenever the takeup reel should be driven during read or record. R46 limits the motor torque during this operation. BOTHDRV goes low whenever the motor control electronics senses that the reels should have braking torque applied or that there may be slack tape in the cartridge. R45 limits the torque during this operation. ALCAP is used to turn on the capstan drive motor.

ENGAJDRV goes to the low state whenever the motor control electronics senses that the head and pinch roller should be moved toward or away from the tape. T7, T8, T9, and T10 are used to brake the engage motor whenever it is not being driven. FFDRV and FRDRV are used to drive the tape in the fast forward or fast reverse direction whenever those commands are given.

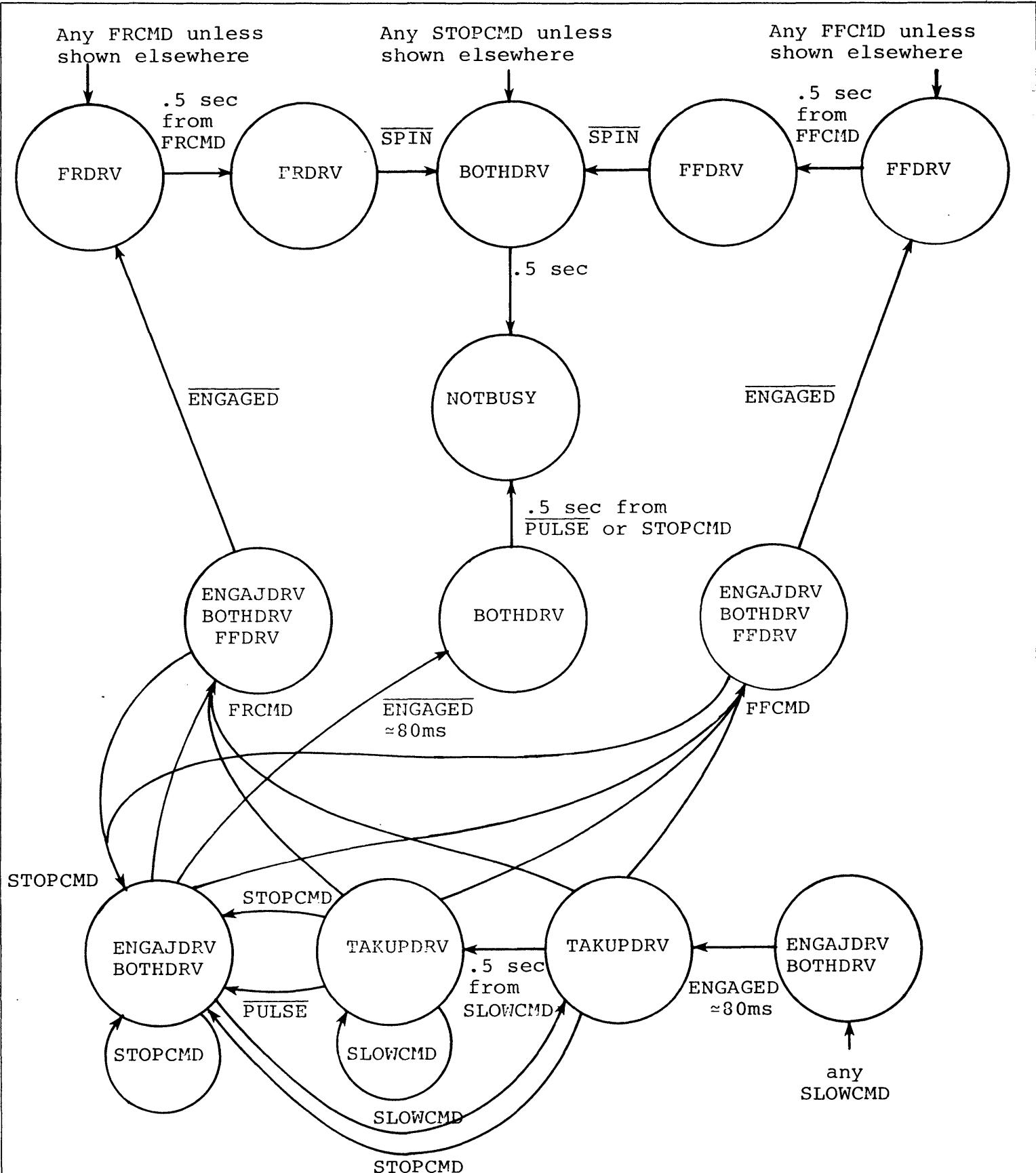
Transistors T2, T3, T4, and T5 in conjunction with steering diodes D1 - D11 and D15 are used to provide drive to the selected deck. Diodes D12, D13 and D14 apply drag to the undriven reel during the fast forward and reverse operations to prevent excessive tape speed and to slow the tape as it nears the end of the reel. Transistors T11 and T12 generate a signal called SPIN which tells the motor control electronics that the undriven reel is turning during the fast forward and reverse operations. The PULSE signal has small negative going pulses on it whenever the takeup reel is turning. This is used to detect tape jams and end of tape during the read, record, or erase operations.

### MOTOR CONTROL ELECTRONICS

The motor control electronics senses the status of the tape motion, the position of the headbar, and the commands given by the user and sends control signals to the motor drive circuits. The status bits STOP and NOT BUSY are also generated and sent to the user interface.

The following discussion provides the user with a description of the primary control signals. The user should look at the state diagram given in Figure 4.10 to determine how the deck is actually controlled.

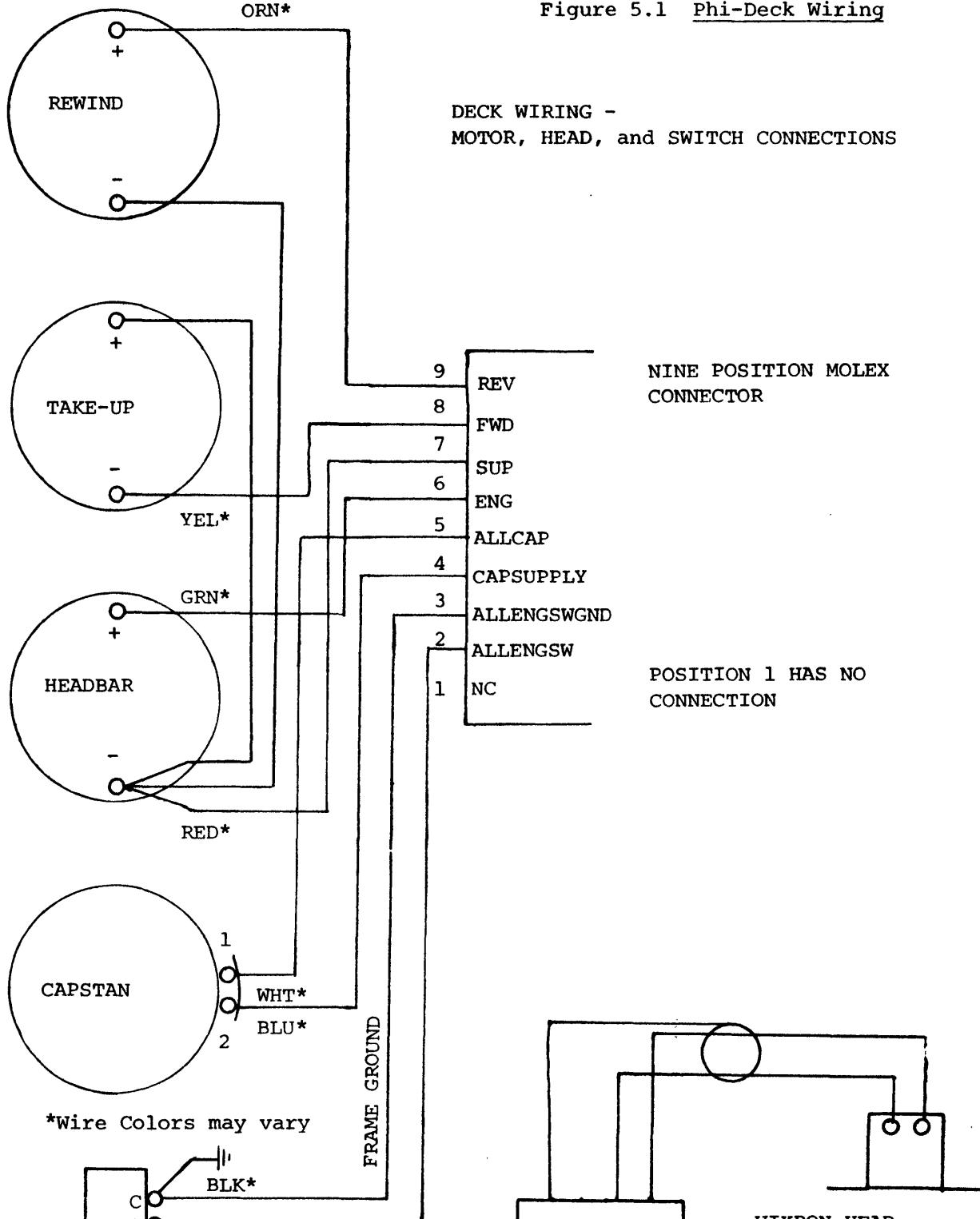
PULSES is generated by a one-shot (IC23) that goes active whenever a command is given and the deck is in the stopped state. PULSES stays active as long as a pulse is received on the PULSE line at least once every half second. If a pulse is not received within the allowed time, PULSES will go to a 1 and cause the deck to go toward the NOT BUSY state. The DELAY signal is also generated by a one-shot (IC23) and is used to inhibit tape motion sensing for 1/2 second after a command is given to allow for the tape to accelerate to the proper speed. This one-shot is also used to time the BOTH signal after a STOP command or tape jam is detected.



Note: Names within circles are motor control signals. Labels on lines indicate commands given by user or events within controller.

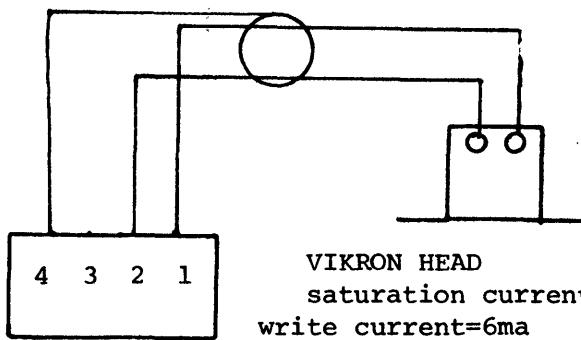
Figure 4.10 Motor Control State Diagram

Figure 5.1 Phi-Deck Wiring



NOTE: Four position molex connector may be cut between 2 & 4 to separate HDGND from HDB and HDA.

1. HDB
2. HDA
3. No Connection
4. HDGRND (Shield)



VIKRON HEAD  
saturation current=4ma  
write current=6ma  
read output=5.5mv

bandwidth 100kHz

QUIT will go to the 1 level if the manual stop button is pressed, if a STOP command is given, if no pulses are detected and there is an active SLOW command, or if SPIN goes low during any FAST command and DELAY is not active. QUIT is equivalent to STOP on the user interface.

## V. CONSTRUCTION

### Tools:

Fine tipped, low wattage soldering iron, "wire solder" (around 20 gauge resin solder), small diagonal cutters, needle-nose pliers.

### Test Equipment:

Voltmeter  
500KHz or better oscilloscope  
Frequency counter  
Microprocessor, Mini, etc.

Estimated Construction Time: 6 - 11 hours

1. Using the component placement chart given in the appendix, insert the 12 16-pin sockets into the PC board. If the sockets have an indicator for pin one, orient it away from the edge connector. Invert the board by placing a book on the sockets to hold them in and carefully solder all pins.
2. Insert and solder the 36 14-pin sockets as described above.
3. Insert and solder the 6 8-pin sockets.
4. The controller and deck need +5 Volts at 1 Amp nominal and +12 Volts at 0.7 Amps peak. Insert ICL2, using silicone grease and the heat sink. Solder R57 and R58.
5. Apply power to the board and check voltages. The 9 Volt supply should be between 8.4 and 9.6 Volts. The 5 Volts should be between 4.75 and 5.25.
6. Remove power from the board.
7. Insert and solder the three resistors rated above 1/4 watt (R44, R45, and R46).
8. Insert and solder the data-rate potentiometer (R28). Orient it so that it may be adjusted from the top of the board.
9. Insert and solder the remaining resistors.
10. Insert and solder all polarized capacitors (C2, C13 - C19, C22, C27, C30, C32). C13 and C14 are marked with a + or -. The others have a solid section of color on the positive lead. The board has + notations to aid in orientation.

11. Insert and solder the various remaining capacitors.
12. Insert and solder the four 1N4148 diodes and the 15 1N4001 diodes. All diodes should be oriented so that the bands on the diode are toward the right side of the board. There is also a diode symbol on the board to aid in orientation.
13. Insert and solder T6 - T12 into place. The emitter lead for these transistors is marked with a dot on one of the transistor pads. The appendix contains a pictorial to aid in orienting the various transistors supplied in your kit.
14. Insert and solder the FET (T13). Orient it so that the drain is toward the top of the board (opposite from the connector).
15. Insert and solder T1 - T5. These transistors are placed vertically with the leads inserted fully through the circuit board. Note that the emitter lead is marked with an E on the circuit board.
16. Insert all IC's into their respective sockets, observing correct orientation (pin 1 away from edge connectors).
17. Wire the board into the microprocessor's I/O structure, as described below. Connect the Phi-Deck by slipping the Molex connector supplied with the deck onto pins H - R of the controller's 36-pin socket. Orient the Molex connectors such that the orange wire is on pin R. This puts the deck into position Ø. Remove the protective plastic shield from the digital head on the transport if one has been supplied.
18. If deck 1 will also be used. connect its Molex connector similarly to the connector for deck Ø. Bend the pins out on the 36-pin socket and slip on the connector. Decks 2 and 3 must be rewired at the connector, since several of the necessary signal pins are common to all of the decks.
19. Connect the shielded pair from deck Ø to pins 1 and A. Connect the ground to pin 5 or E. If deck 1 is to be used, connect the shielded pair to pins 2 and B (reverse the connector's orientation) and rewire the ground pin into deck Ø's ground connector. For decks 2 and 3, a different method of connection must be employed, as no more Molex connectors will fit.
20. Proceed with the initial checkout of the board by following the steps under section VII, DEBUG.
21. When the board seems to be working properly, perform the oscillator calibration and read amplifier gain calibration procedures under section VI, CALIBRATION. Calibrate the motor speed only if it is absolutely necessary. The Cassette Storage System is now ready for use.

## USING THE CONTROLLER IN A DIGITAL GROUP SYSTEM

The connection diagram in Figure 3.2 of the controller manual is used with the Digital Group Software packages. Most systems will use the wiring chart (Table 6.1).

An optional stop switch may be wired to the controller. A normally open momentary push button which brings the manual stop pin ( $\bar{B}$ ) to ground will stop all deck movement.

## VI. CALIBRATION

### Oscillator Calibration

- To insure compatibility between decks and tapes among all users of this system, the data rate should be adjusted to meet the standard specifications. Before you proceed with the adjustment of R28, the controller must be placed in the record mode by issuing a record command from the computer. This disables the DC feedback path to pin 5 of IC9. Adjust R28 for a 112 KHz signal at pin 3 of IC9. In record mode, this will produce an 8 KHz signal on DCLK. This bit rate (8,000 bits/sec) will record 1,600 flux changes per inch at a tape speed of five inches per second. The data rate is then 6,400 baud when referenced to the data transfer rate between the computer and the controller.

### Motor Speed Calibration

- The capstan motor on the Phi-Deck is preadjusted to 5 ips at the factory. The following adjustment may be made periodically to keep the deck speed within tolerance. (Note: Side B of your tape has approximately one minute of a 4 KHz test signal recorded on it. This is equivalent to 1,600 FCPI.) Using the 4 KHz test signal recorded on the reverse side of the cassette supplied with your controller, monitor the tape signal in the read mode on IC13, pin 14. With a non-metallic screwdriver or alignment tool, adjust the tape speed through the hole on top of the capstan motor so that the frequency of the tape signal is 4 KHz.

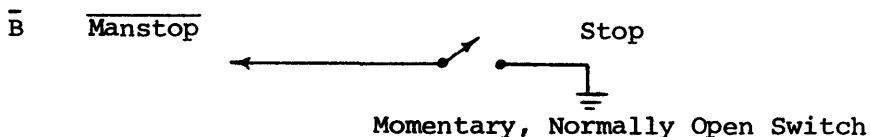
Table 6.1

Wiring ChartPhi-Deck Board

PIN #	DESCRIPTION	CONNECT TO
6	DO7	
7	DO6	
8	DO5 Data	
9	DO4 Output	
10	DO3 Lines	
11	DO2	
12	DO1	
13	DOØ	
14	Data Output Strobe	
15	DI7	
16	DI6	
17	DI5	
18	DI4 Data	
19	DI3 Input	
20	DI2 Lines	
21	DI1	
22	DIØ	
23	Data Input Strobe	
L	* Not Busy	Status
M	* Stop	Port
N	* Ready	
P	* Overrun/Underrun	
R	Status Strobe	
S	* Enable/Disable	
T	* Slow/Fast	
U	* FWD/BKWD	Command
V	* Stop/Run	Port
W	* RCD/READ	
X	* ERASE	
Y	* SEL2	
Z	* SEL1	
Ā	Command Strobe	

I/O Board (Ports Ø-3)

PIN #	DESCRIPTION
26	MSB
25	MSB-1
24	MSB-2 Input
23	MSB-3 Port 2
22	LSB+3
21	LSB+2
20	LSB+1
19	LSB
R	MSB-3, Output Port 1
D	MSB
C	MSB-1 Output
B	MSB-2 Port 2
A	MSB-3
Z	LSB+3
Y	LSB+2
X	LSB+1
W	LSB
U	MSB, Output Port 1
22	LSB+3
21	LSB+2 Input
20	LSB+1 Port 2
19	LSB
S	MSB-2, Output Port 1
D	MSB
C	MSB-1
B	MSB-2 Output
A	MSB-3 Port 2
Z	LSB+3
Y	LSB+2
X	LSB+1
W	LSB
T	MSB-1, Output Port 1



\* These pins may actually be wired to the opposite pin on the Phi-Deck Board connector (i.e., pin L to pin 10 on the Phi-Deck Board).

Read Amplifier Gain Calibration - First, record several minutes of test data onto a tape that you will be using. (Once you have decided on a type of tape that gives you good results and that is readily available, you should not change tapes.) Now place the controller in read mode and read your tape. Monitor the signal at IC13, pin 1. If the amplitude is not within the limit shown in Figure 4.2, try different values of R18 until the amplitude is within limits. This adjustment is not critical and your controller will give good results even if your amplitude is not within the limits specified.

## VII. DEBUG

Reread the software section to be certain the correct procedures are being executed. Insert controller card (do not connect Phi-Deck yet) and turn power on.

Issue input and output commands to the I/O ports and verify that the strobe signals are present when the command is issued. Also, verify that the data is being latched in the command and data latches correctly (IC33, 46, 47, and 28).

CONNECT THE PHI-DECK AND PROCEED THROUGH THE FOLLOWING SECTIONS.

### MOTOR CONTROL ELECTRONICS

Place an old cassette into the deck (if the motor control electronics is not working properly this test may destroy the tape). Issue a fast forward command and check tape movement (these commands are given in the Mechanical Considerations portion of this manual.) Issue a fast reverse command and check tape movement. Remove cassette and issue a stop command. Both reel motors should turn in opposite directions. Reinsert the cassette and issue a record command. The head should engage the tape and the takeup reel should turn. Place your finger on the takeup reel motor pulley. The head should disengage within 1.5 seconds after stopping the motor. If any of the above tests fail, refer to the Theory of Operation for the motor drive and sense electronics and the motor control electronics and proceed to trace the problem.

### HEAD SENSE AND BIT SYNCHRONIZING ELECTRONICS

Place controller in record mode and output data bytes to the controller every time READY comes true. You should see waveforms similar to those shown in Figure 4.1 at the outputs of the selected head driver (IC27 or IC28). Waveforms similar to these should also appear on the head of the selected drive.

The read amplifiers may be tested by using the tape you made in the previous paragraph, placing the deck in read mode after rewinding the tape, and looking for the waveforms given in Figure 4.2. If the voltage at IC13, pin 1 is clipping or not within the range shown, refer to Calibration for Adjustment. This adjustment is not critical and is probably not the cause of the controller malfunction.

The bit synchronizing electronics may be checked by verifying the timing diagram shown in Figure 4.3.

#### READ/WRITE ELECTRONICS

Test all of the clocking signals depicted in Figure 4.9. If a signal is not present or correct, trace back through the logic generating that signal. Make sure about 0.2 Volts of the tape head signal is present on record, and not on read. Check that RECORD reflects the selected state and RDY had a pulsing signal when recording or reading.

The basic clock, IC9, may be removed, and a bounceless switch (Figure 7.1) used to single step the system (14 clocks per data bit). If an oscilloscope is not available, an audio amplifier with the circuit in Figure 7.2 can be used to probe for clocks and data flow. For example, recording or reading in hex "5A" will sound like a 4 KHz square wave on pin 6 of IC5, and (on record) a 2 KHz square wave on pin 3 of IC4. (This signal is not present on erase and read.)

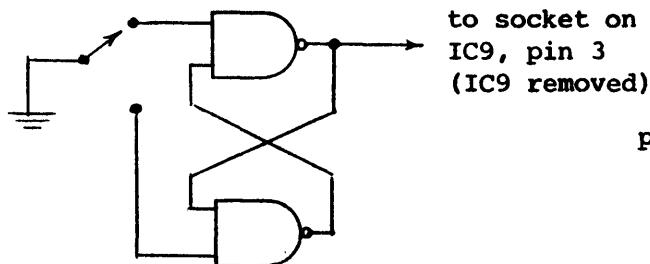


Figure 7.1 Single-step Clock

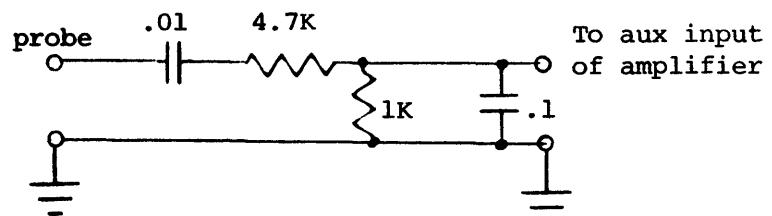


Figure 7.2 Digital to Audio Sensor

VIII. APPENDIX

- A. Parts List
- B. PROM Pattern
- C. Connector Pinout
- D. Component Placement
- E. Schematic
- F. Transistor Orientation
- G. Driver Software Description
- H. Recording Format
- I. Flowcharts
- J. Program Tape and Listings
- K. Phi-Deck Maintenance

A. PARTS LIST

<u>DESCRIPTION</u>	<u>QUANTITY</u>	<u>CIRCUIT REFERENCE</u>
74S00	1	IC49
7400	8	IC1,8,10,14,16,17,25,38,
7402	1	IC15
7404	2	IC34,40
7408	1	IC36
7410	2	IC19,39
7411	1	IC18
7420	2	IC6,22
7451	2	IC2,24
7473	1	IC41
7474	6	IC3,5,21,42,50,55
7475	4	IC33,46,47,48
7486	1	IC26
7490	1	IC20
7493	2	IC7,37
74107	1	IC4
74123	1	IC23
74125	3	IC27,28,45
74153	2	IC31,32
74155	1	IC35
74173,8551	2	IC43,44
74195	1	IC30
74S188,8223,6330-1J	1	IC29
75451	4	IC51,52,53,54
LM324	1	IC13
LM340T-8.0,uA7808	1	IC12
LM358	1	IC11
LM555	1	IC9
2N4403	4	T7,8,9,10
2N5129	1	T12
2N5139	2	T6,11
2N6109	4	T2,3,4,5
2N6410,MJE2050	1	T1
MPF971	1	T13
1.5Ω,1/2W	1	R44
7.5Ω,1W	1	R46
18Ω,2W	1	R45
47Ω	2	R53,57
82Ω	1	R27
220Ω	1	R12
470Ω	1	R48
510Ω	1	R58
680Ω	8	R32,33,34,35,36,37,38,39
1KΩ	7	R6,9,20,23,26,31,55
1.2KΩ	5	R15,16,19,30,42
2.2KΩ	2	R1,29
4.7KΩ	2	R2,49
5KΩPOT	1	R28

<u>DESCRIPTION</u>	<u>QUANTITY</u>	<u>CIRCUIT REFERENCE</u>
10KΩ	13	R7,8,10,11,14,17,21,22, 24,25,43,47,54
15KΩ	1	R50
22KΩ	2	R40,41
39KΩ	2	R4,5
47KΩ	1	R3
100KΩ	1	R13
150KΩ	2	R51,52
220KΩ	1	R18
1 Meg Ω	1	R56
220pf d mylar	1	C4
.0015mfd mylar	1	C12
.0033mfd mylar	1	C25
.005mfd mylar	1	C3
.01mfd disc	14	C5,6,7,8,9,10,11,20,21, 23,26,28,29,31
.1mfd disc	2	C1,24
1mfd tantalum	10	C2,15,16,17,18,19,22,27, 30,32
100mfd electrolytic	2	C13,14
1N4001	15	D1,2,3,4,5,6,7,8,9,10,11, 12,13,14,15
1N4148	4	D16,17,18,19
TO-220 Heatsink, THM6072B	1	
4-40 Screws	2	
4-40 Nuts	2	
#4 Lockwashers	2	
8-Pin DIP Sockets	6	
14-Pin DIP Sockets	36	
16-Pin DIP Sockets	12	
Dual 22-Pin Edge Connectors	1	
Dual 36-Pin Edge Connectors	1	
PC Board	1	

## B. PROM PATTERN

A4	A3	A2	A1	A0	B0	B1	B2	B3	B4	B5	B6	B7
0	0	0	0	0	1	1	0	1	1	1	0	0
0	0	0	0	1	1	1	1	1	0	0	0	0
0	0	0	1	0	1	0	1	0	1	0	0	0
0	0	0	1	1	1	0	1	1	0	0	1	0
0	0	1	0	0	1	1	0	1	1	1	0	0
0	0	1	0	1	1	0	0	1	0	0	0	1
0	0	1	1	0	1	0	1	0	1	0	1	0
0	0	1	1	1	1	0	1	1	1	0	1	0
0	1	0	0	0	1	1	1	0	1	1	1	0
0	1	0	0	1	0	1	0	1	1	0	1	0
0	1	0	1	0	0	1	1	0	1	1	0	0
0	1	0	1	1	0	1	1	1	1	1	1	0
0	1	1	0	0	1	1	1	0	1	1	1	0
0	1	1	0	1	0	1	0	1	1	1	0	0
0	1	1	1	0	0	1	1	1	1	1	1	0
0	1	1	1	1	0	1	1	1	1	1	1	0
1	0	0	0	0	0	0	0	0	0	1	1	0
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1	0	1	0	0	0	0	0	0	0	0	1	0
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1	0	1	1	0	0	0	0	0	0	0	1	0
1	1	0	0	0	0	0	0	0	0	0	0	1
1	1	0	0	1	0	0	0	0	0	0	0	0
1	1	1	0	1	0	0	0	0	0	1	0	0
1	1	1	1	1	0	0	0	0	0	0	0	1
1	1	1	1	0	1	0	0	0	0	0	0	0
1	1	1	1	1	0	0	0	0	0	1	0	0
1	1	1	1	1	1	0	0	0	0	0	0	1
1	1	1	1	1	1	1	0	0	0	0	0	0

C. CONNECTOR PINOUT

Top of Card - Component Side

<u>Pin No.</u>	<u>Description</u>
1	HDAØ
2	HDA1
3	HDA2
4	HDA3
5	HDGND
6	DO7
7	DO6
8	DO5 Data
9	DO4 Output
10	DO3 Lines
11	DO2
12	DO1
13	DOØ
14	Data Output Strobe
15	DI7
16	DI6
17	DI5
18	DI4 Data
19	DI3 Input
20	DI2 Lines
21	DI1
22	DIØ
23	Data Input Strobe
24	+9V Out
25	ENG3
26	SUP3
27	FWD3
28	REV3
29	ALLENGSW
30	ALLENGSWGND
31	CAPSUPPLY
32	ALCAP
33	ENG1
34	SUP1
35	FWD1
36	REV1

Bottom of Card - Circuit Side

<u>Pin No.</u>	<u>Description</u>
A	HDBØ
B	HDB1
C	HDB2
D	HDB3
E	HDGND
F	DATA READY IRQ
H	n/c
J	n/c
K	n/c
L	Not Busy
M	Stop Status
N	Ready Port
P	Overrun/underrun
R	Status Strobe
S	Enable/Disable
T	Slow/Fast
U	FWD/BKWD Command
V	Stop/Run Port
W	RCD/READ
X	ERASE
Y	SEL 2
Z	SEL 1
Ā	Command Strobe
ĀB	Manstop
ĀC	ENG2
ĀD	SUP2
ĀE	FWD2
ĀF	REV2
ĀH	ALLENGSW
ĀJ	ALLENGSWGND
ĀK	CAPSUPPLY
ĀL	ALCAP
ĀM	ENGØ
ĀN	SUPØ
ĀP	FWDØ
ĀR	REVØ

Note: n/c = no connection

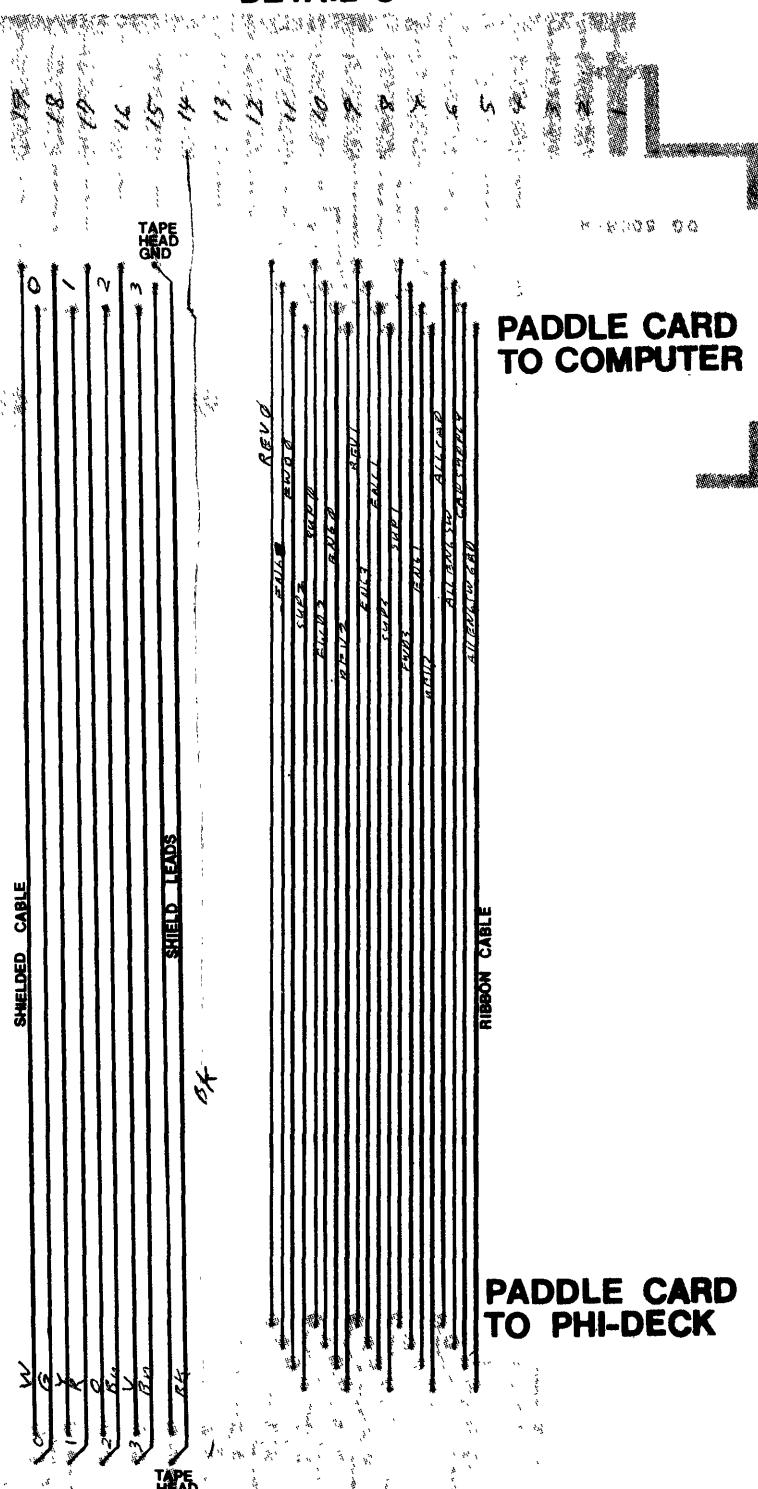
Pin 1 on 22-pin connector = +5V

Pin 2 on 22-pin connector = GND

Pin 22 on 22-pin connector = +12V

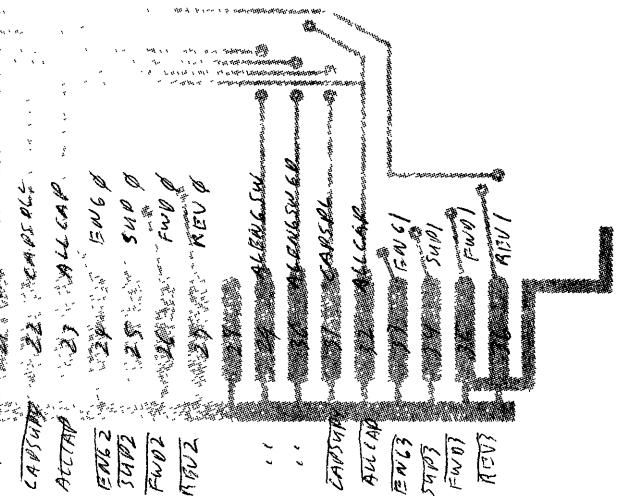
### **DETAIL 3**

TOP OF  
PADDLE  
CANOE

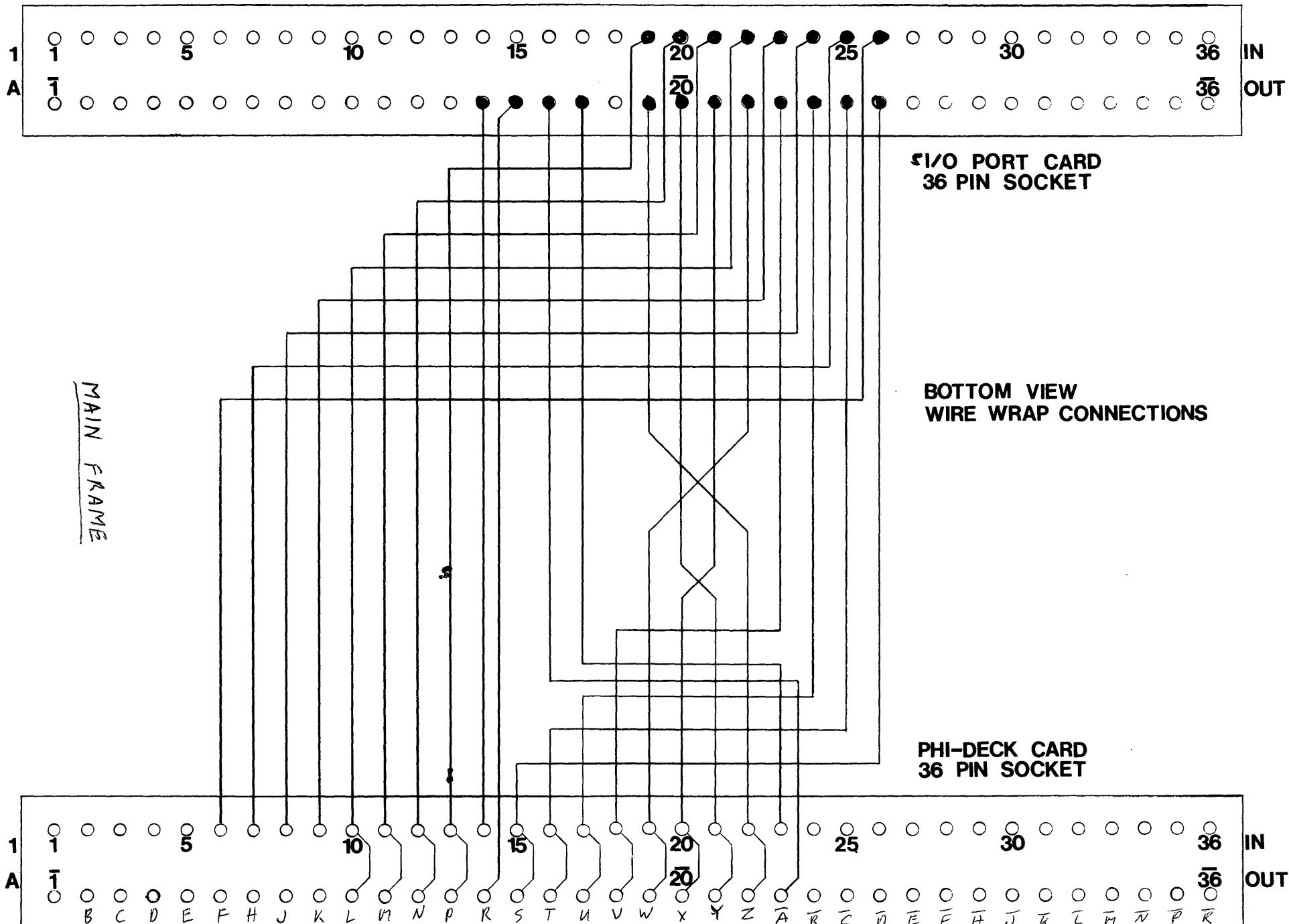


## PADDLE CARD TO COMPUTER

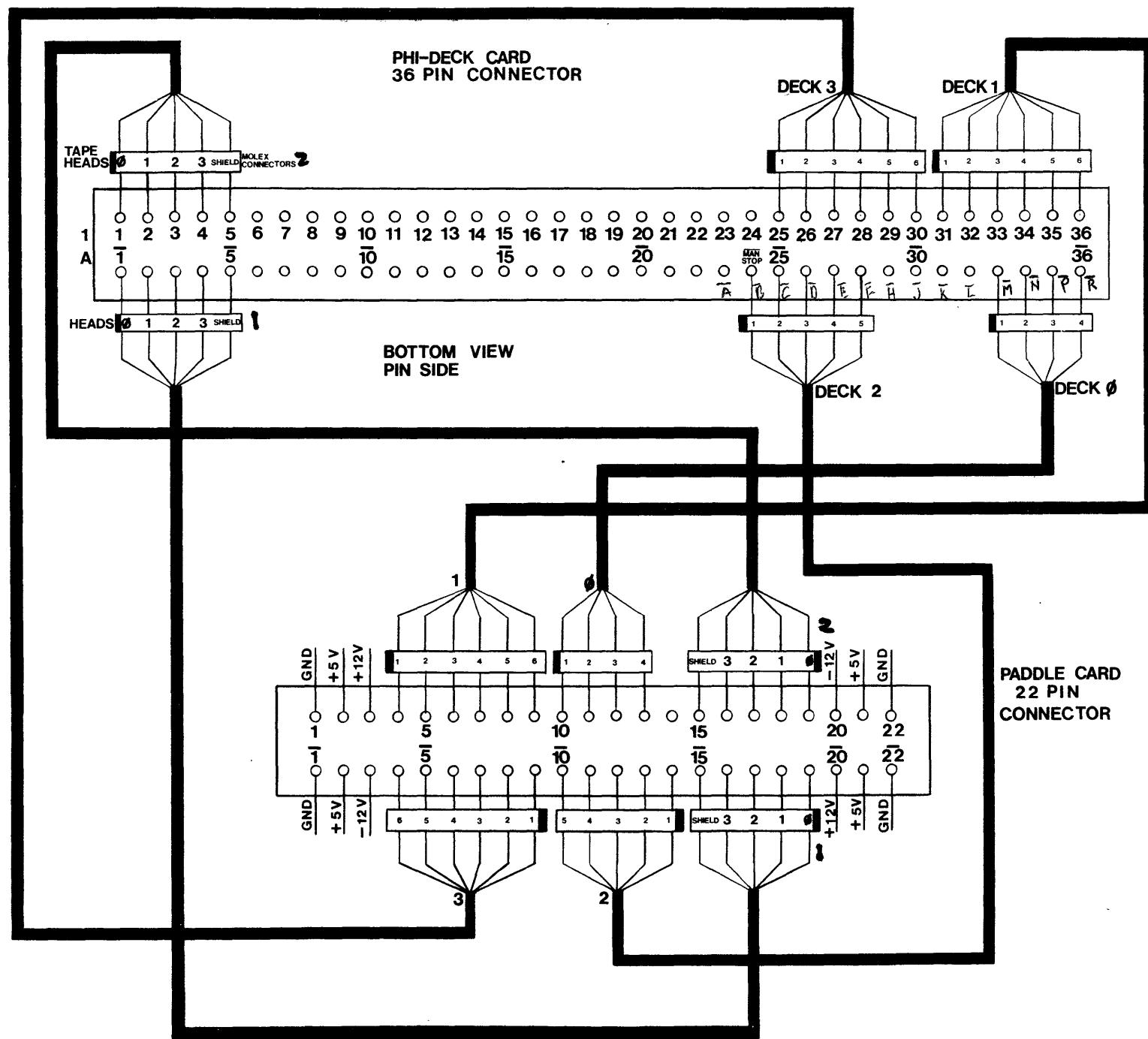
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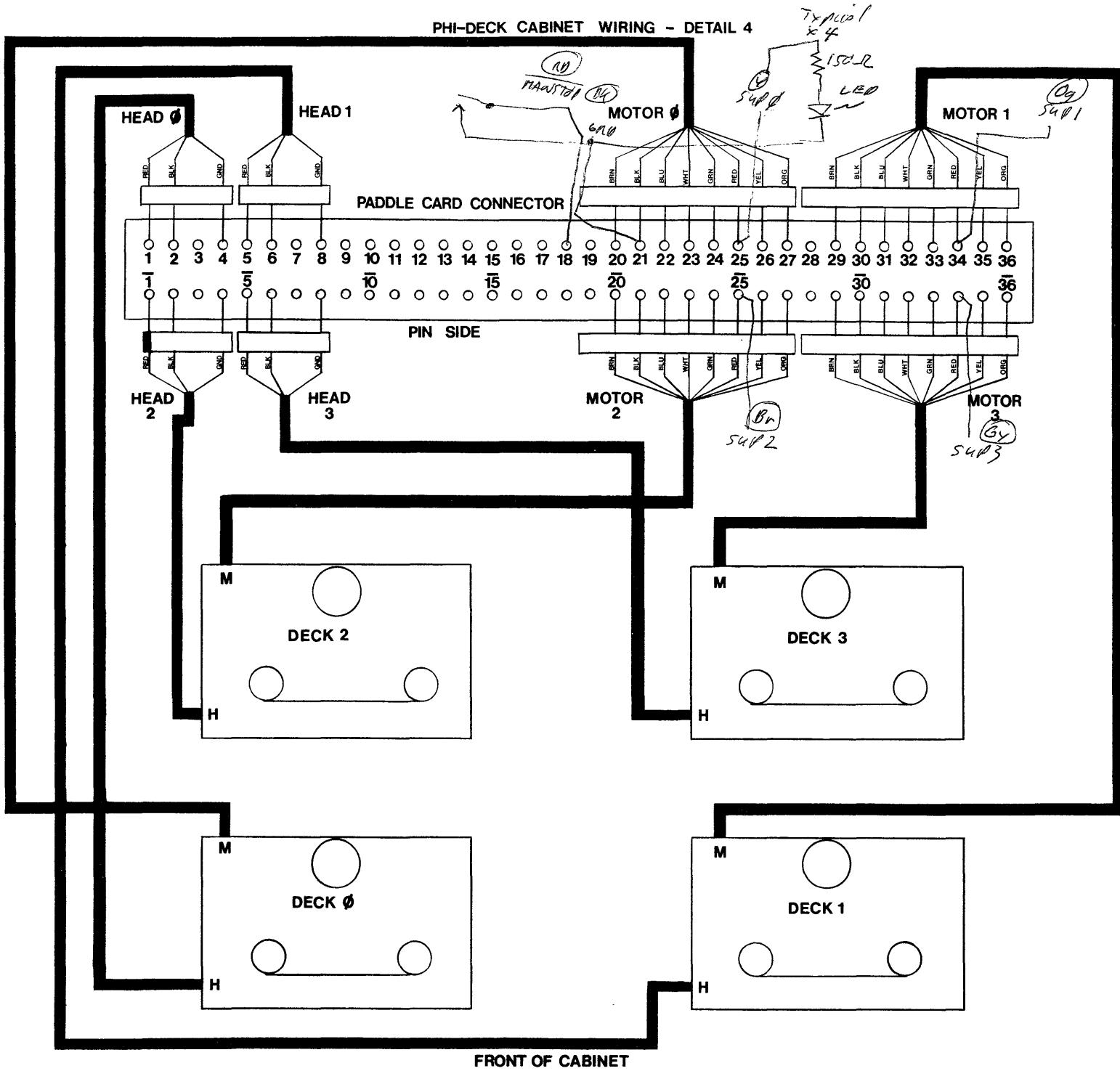
CONNECTIONS BETWEEN CARDS - DETAIL 1



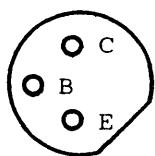
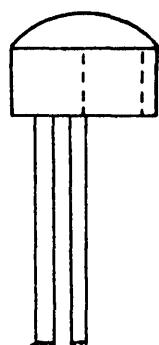
PHI-DECK CARD CONNECTIONS TO  
PADDLE CARD BACKPLANE - DETAIL 2



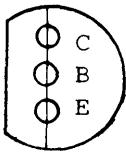
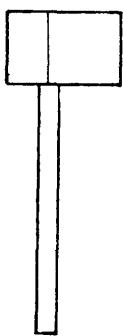
**PHI-DECK CABINET WIRING - DETAIL 4**



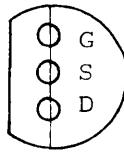
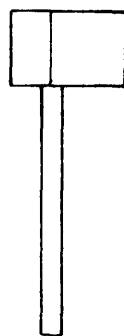
F. TRANSISTOR ORIENTATION



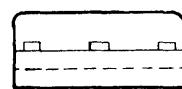
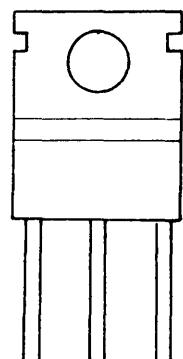
CASE  
A



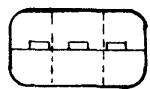
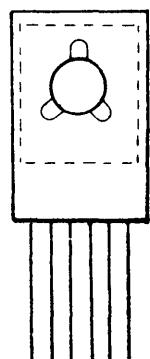
CASE  
B



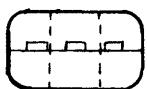
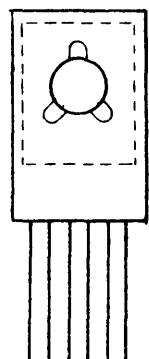
CASE  
C



CASE  
D



CASE  
E



CASE  
F

Transistor

2N6109  
2N5139  
2N5129  
2N4403  
2N6410  
MJE2050  
MPF971

Case

D  
A or B  
A or B  
B  
F  
E  
C

## G. DRIVER SOFTWARE DESCRIPTION

The software supplied with the Digital Group Cassette Storage System contains deck control subroutines to allow the user to concentrate on applications. The READ and RECORD routines provide all error recovery during read, and data verification during record.

The software package consists of several major routines to aid the user in controlling the decks. These are the RECORD, CMDOUT, READ, and REWIND routines. There are numerous minor subroutines the user may invoke if he feels the need to control the deck on a more basic level.

The sample 8080 program given below is a simple example of how to use the major routines. The sample program will read the tape on deck 0 and write the data on deck 1, one block at a time. This program will halt if an unrecoverable error occurs. The major routines are described in more detail following the example. (Note: The sample Z80 program may be found under Program Listings.)

```
* SAMPLE PROGRAM TO COPY A TAPE
* ON DECK 0 TO A TAPE ON DECK 1
* ONE BLOCK AT A TIME
```

<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
REDBLK	MVI	A,0	SET DECK 0
	STA	DECK	
	CALL	REWIND	REWIND DECK 0
	MVI	A,1	SET DECK 1
	STA	DECK	
	CALL	REWIND	REWIND DECK 1
	SUB	A	CLEAR REGISTER A
	STA	TEMPID	INITIALIZE ID
	IN	TAPEIN	WAIT FOR NOT BUSY
	ANI	08H	BECAUSE THE DECK
	JZ	REDBLK	NUMBER IS CHANGING
	MVI	A,0	SET DECK 0
	STA	DECK	
	LXI	H, BUFFER	SET UP POINTER
	SHLD	POINTR	
	LDA	TEMPID	SET UP ID
	STA	IDR	
	MVI	E,0	SET READ MODE
	CALL	READ	READ BLOCK
	PUSH	PSW	SAVE REGISTER A
	MVI	C,F0H	STOP DECK
	CALL	CMDOUT	
	POP	PSW	RESTORE REGISTER A
	CPI.	0	ERROR?
	JZ	WRTBLK	NO
	CPI	2	BLOCK FOUND?

<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
WRTBLK	RZ		NO, FINISHED
	HLT		HALT BECAUSE ERROR
	IN	TAPEIN	WAIT FOR NOT BUSY
	ANI	Ø8H	BECAUSE THE DECK
	JZ	WRTBLK	NUMBER IS CHANGING
	MVI	A,1	SET DECK 1
	STA	DECK	
	LXI	H,BUFFER	SET UP POINTER
	SHLD	POINTW	
	LDA	TEMPID	SET UP ID
	STA	IDW	
	INR	A	INCREMENT ID
	STA	TEMPID	
	MOV	A,B	SET UP COUNT
X256	CPI	Ø	256?
	JZ	X256	YES
	MOV	L,B	
	MVI	H,Ø	
	JMP	CALRCD	
	MVI	H,1	
	MVI	L,Ø	
	CALL	RECORD	RECORD BLOCK
	CPI	Ø	ERROR?
CALRCD	JZ	REDBLK	NO, COPY NEXT BLOCK
	HLT		HALT BECAUSE ERROR
	TEMPID	DS 1	
	BUFFER	DS 256	
		END	

The REWIND routine will stop the operating deck, select the specified deck, and rewind it. This routine returns to the calling routine after the selected deck has been rewound and readied for another command. Memory location "DECK" must contain the selected deck number (in binary) before the routine is called.

The RECORD routine will record data in the standard block format and then check the recorded data to verify that it was recorded without error. If an error is detected, that portion of the tape is erased and all the remaining data is re-recorded. This process is repeated until all data has been recorded successfully, or an unrecoverable error is detected.

As the user records data he must record blocks in sequence starting with IDW = Ø,1,2, etc. Numbers may not be skipped! After a series of blocks have been recorded, the user may re-record a block, but all old blocks following the new blocks may be lost. Although not absolutely necessary, it is recommended that tapes be erased with a bulk eraser or using the Phi-Deck in erase mode to obtain maximum performance and prevent the controller software from becoming confused with the old data.

In order to use this routine properly, the input variables must be set up properly:

1. The deck number must be placed in memory location DECK.
2. The low order byte of the block ID must be placed in memory location IDW, and the high order byte must be placed in IDW+1.
3. The low order byte of the address of the first byte to be recorded is placed in memory location POINTW, and the high order byte is placed in POINTW+1.
4. The number of bytes to be recorded is placed in register pair H and L. A count of zero will cause the record routine to simply return without recording any data.

When the record routine returns control to the calling routine, the registers and memory are modified as follows:

1. All Registers are altered.
2. IDW returns the ID of the last block recorded plus one.
3. POINTW points one location greater than the last byte recorded.
4. The error code is returned in the A register and should be checked after every call to the RECORD routine. The error codes are:

Ø - Record completed with no errors  
1 - CRC error in block ID-1  
2 - Block ID-1 not found  
3 - End of tape or jam

The READ routine will read one block and return to the calling routine. The deck is left running so the user must either read another block or issue a stop command to the deck directly (see the CMDOUT routine).

To use this routine the following variables must be set up properly:

1. The deck number is placed in memory location DECK.
2. Memory location IDR contains the low order byte of the ID of the block to be read. IDR+1 contains the high order byte.
3. ~~Memory location POINTR containing the low order byte of the address of the data that is to be deposited. POINTR+1 contains the high order byte.~~
4. Register E contains the mode. Ø indicates that the data block is to be read into memory starting at the location specified by POINTR. 1 indicates that the data block is to be checked for errors only (in this mode POINTR is not used).
5. RETRYS (Register D) should be initialized only if the ALTRD or ALTRD2 entry points are used. It is automatically initialized to 10 if the READ entry point is used. The user should normally use the READ entry point.

When the read routine returns control to the calling routine, the registers and memory are modified as follows:

1. Registers A,B,C,D,H, and L are modified.

2. COUNT (Register B) contains the number of bytes contained in the block:

Ø = 256 bytes  
1 = 1 byte  
2 = 2 bytes  
255 = 255 bytes

3. ERROR (Register A) contains the error code after a read operation has been completed. The error codes are:

Ø - No errors  
1 - Unrecoverable data error  
2 - Unable to find block specified by ID  
3 - End of tape or jam

The CMDOUT routine is used to issue commands to the transport. Memory location DECK must contain the number of the deck that is referenced by the command. Register C must contain the command to be issued to the deck. The valid commands are:

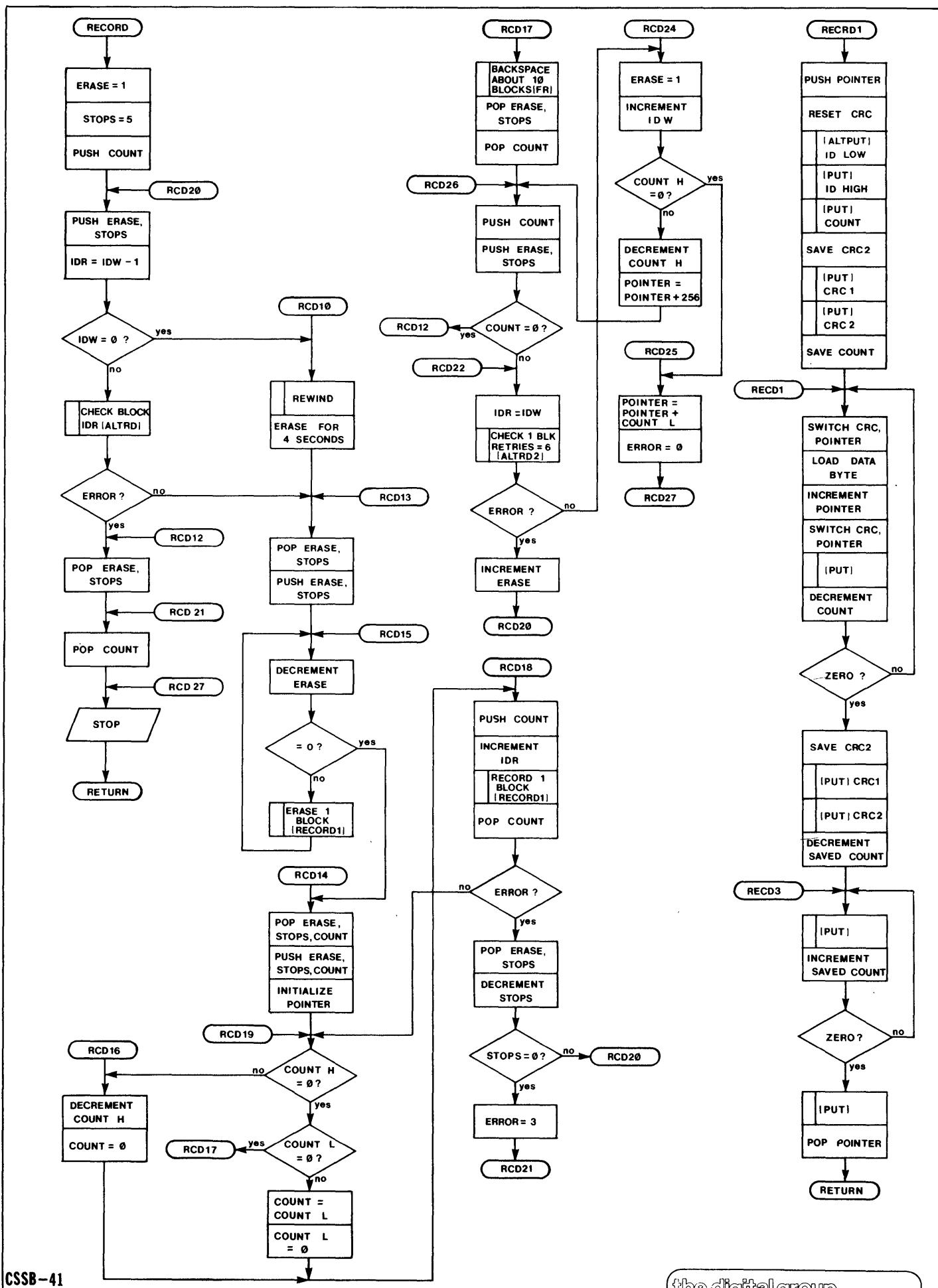
<u>COMMAND</u>	<u>VALUE IN REGISTER C</u>			
STOP	1	1	1	1
FAST FORWARD	1	0	1	0
FAST REVERSE	1	0	0	0
READ	1	1	1	0
RECORD	1	1	1	0
ERASE	1	1	1	0
STANDBY	0	1	1	1

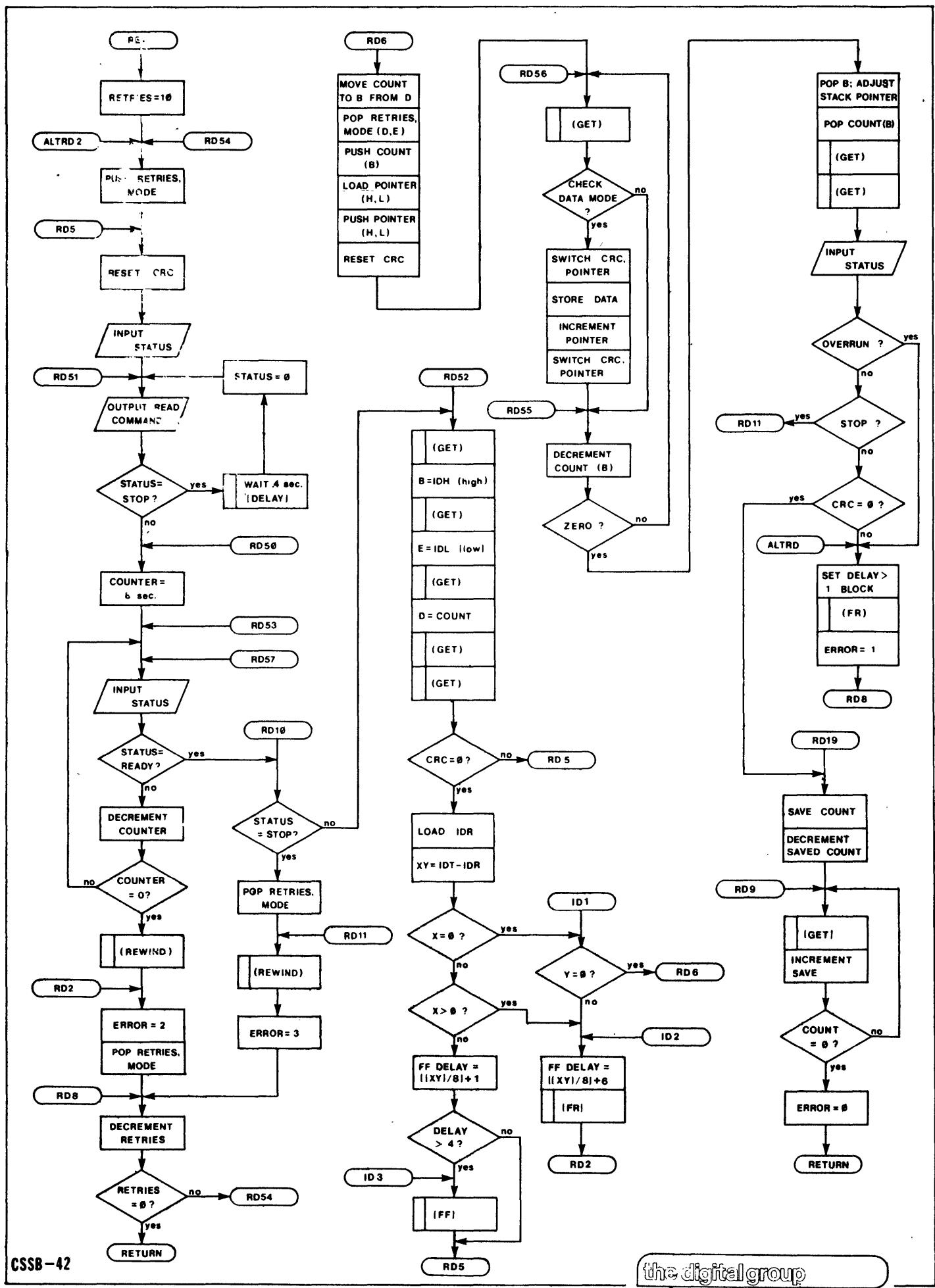
#### H. RECORDING FORMAT

This appendix shows the block format as it is recorded on the tape by the driver software and controller. Each byte recorded on the tape consists of 10 bits or flux changes (see hardware description).

<u>DESCRIPTION</u>	<u>BYTES RECORDED</u>
75 one bits	7.5
SYNC character	.5
ID high	1.
ID low	1.
COUNT	1.
CRC 1	1.
CRC 2	1.
DATA	1. to 256
CRC 1	1.
CRC 2	1.
TOTALS*	16 to 271

\*The record routine will erase to an equivalent of 271 bytes for short blocks so that all blocks will be the same size.





J. PROGRAM TAPE AND LISTINGS

```
*****
* The tape supplied with the program listing is an *
* AUDIO CASSETTE recorded at 1100 Baud in Suding *
* format. This WILL NOT load from the PHI-DECK. *
*****
```

The program tape contains four programs in the following order:

1. Phi-Deck Demo for Z-80
2. Z-80 Ops System
3. Phi-Deck Demo for 8080
4. 8080 Ops System

Each program includes the PHI-DECK driver routines in the program listing in locations \$900H thru \$B9DH (\$1100\$ thru \$13235).

Z-8Ø PHI-DECK DEMO SOFTWARE

1. Programs are loaded via audio cassette.
2. At completion of a successful load a listing of Phi-Deck commands will be displayed.
3. In addition to the displayed options, there are three possible options - "R", "S", and "P".
4. "R" will return control to the Z-8Ø Ops System which includes:
  - 1 Read - Read an audio cassette
  - 2 Write - Write an audio cassette
  - 3 Octal Dump - Storage Dump in octal
  - 4 Octal Program - User programming in octal
  - 5 Hex Dump - Storage Dump in hex
  - 6 Hex Program - User programming in hex
  - 7 Phi-Deck Ops
5. "S" will display memory in either hex or octal depending upon last option (hex or octal) chosen by the user.
6. "P" will allow user to program as in Z-8Ø Ops System in either hex or octal depending upon last method chosen in Z-8Ø options 3 thru 6.
7. Reset will return control to Phi-Deck ops.
8. "P", "R", and "S" will operate when in Storage Dump, Program, or Phi-Deck Ops.
9. Phi-Deck option "#" allows the user to select any of 4 decks (Ø-3) by pressing shift # then desired deck number. To return to Phi-Deck Ops press Y. The selected deck number will be displayed in the options listing upon return.
10. Phi-Deck option "Ø" will copy a tape from deck Ø to deck 1. This is not intended as an efficient method of duplicating tapes, only as a demonstration of Phi-Deck routines.
11. Page Ø15 is being used as a 256 byte buffer in the Copy Tape option.
12. Phi-Deck option "1" will erase a tape on the selected deck.
13. Phi-Deck option "2" will fast reverse the selected deck.
14. Phi-Deck option "3" will fast forward the selected deck.
15. Phi-Deck option "4" will place all decks in standby. The capstan motors will be turned off.
16. Phi-Deck option "5" will stop the selected deck.
17. Phi-Deck option "6" will issue a read command to the selected deck. This will not read data from a tape.
18. Phi-Deck option "7" will issue a record command to the selected deck. This will not record data on a tape.
19. Phi-Deck option "8" will record 256 byte blocks of data in a fixed pattern.
20. Phi-Deck option "9" will read 256 byte blocks of data from a tape in a fixed pattern. An "e" will be displayed on the monitor for blocks in error and a "g" for good blocks.

CHANGES TO Z-80 OPERATING SYSTEM  
FOR PHI-DECK DEMO

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
Ø54E	ØØ				Address for key 7
Ø54F	Ø7				
Ø5FØ	13				Spaces
Ø5F1	B7				7
Ø5F2	AØ				
Ø5F3	DØ				P
Ø5F4	C8				H
Ø5F5	C9				I
Ø5F6	AØ				
Ø5F7	C4				D
Ø5F8	C5				E
Ø5F9	C3				C
Ø5FA	CB				K
Ø5FB	AØ				
Ø5FC	CF				O
Ø5FD	DØ				P
Ø5FE	D3				S
Ø5FF	ØØ				Return
Ø1Ø3	ØØ		RST	8	
Ø1Ø4	Ø7				
Ø4Ø1	Ø3				
Ø4Ø2	Ø5				
Ø4D6	Ø3				
Ø4D7	Ø5				
Ø5ØØ	C3				
Ø5Ø1	ØØ				
Ø5Ø2	Ø7				

Z-80 PHI-DECK DEMO SOFTWARE

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
0700	31 02 02	0190	LD	SP,2200H LOAD STACK POINTER	
0703	ED 46	0220	IM	0 SET INTERRUPT MODE 0	
0705		0210 *		(8080 IDENTICAL)	
0705	FB	0220	EI		ENABLE INTERRUPTS
0706	3A B0 0A	0230	LD	A,(DECK)	
0709	F6 B0	0240	OR	0B0H CONVERT TO ASCII	
070B	32 83 07	0250	LF	(DKNFR),A LOAD DECK # IN MESSAGE	
070E	21 6E 07	0260	LD	HL,MSG1	
0711	CD 02 02	0270	CALL	TVEDIT CALL TV EDITOR	
0714	CD A8 01	0280 KYFD	CALI	01A8H CALL KEYBOARD	
0717	FE BA	0290	CP	0BAH NUMBER?	
0719	D2 38 07	0300	JP	NC,LETTER NO	
071C	FE B0	0310	CP	2B0H NUMBER?	
071E	DA 4A 07	0320	JP	C,CHAR NC	
0721	F5	0330	PUSH AF	SAVE A&F	
0722	CD E6 00	0340	CALL ERASE	ERASE SCREEN	
0725	F1	0350	POP AF	RESTORE A&F	
0726	07	0360	RLCA		PRODUCE L INDEX
0727	D6 09	0370	SUB	09H	
0729	EF	0380	LD	L,A	
072A	26 07	0390 HINDEX	LD	H,07H F INDEX	
072C	7E	0400	LD	A,(HL) SELECT ADDRESS	
072D	32 36 07	0410	LD	(0736H),A	
0730	23	0420	INC	HL	
0731	7E	0430	LD	A,(HL)	
0732	32 37 07	0440	LD	(0737H),A	
0735	C3 00 00	0450	JP	SELADR	
0738	F6 20	0460 LETTER	OR	20H	
073A	FE F3	0470	CP	0F3H "S" ?	
073C	CA 00 03	0480	JP	Z,TVDDUMP YES, JUMP TO TV	
073F		0490 *			STORAGE DUMP
073F	FE F2	0500	CP	0F2H "R" ?	
0741	CA 03 05	0510	JP	Z,0503H YES, JUMP TO Z80 OPS SYSTEM	
0744	FE F0	0520	CP	0F0H "P" ?	
0746	CA 91 24	0530	JP	Z,0491H YES, JUMP TO KEYBOARD	
0749		0540 *			PROGRAMMER ROUTINE
0749	CF	0550	RST	8D	
074A	FE A3	0560 CHAR	CP	2A3H	
074C	C2 14 07	0570	JP	NZ,KYBD	
074F	2E 60	0580	LD	L,6CH	
0751	C3 2A 07	0590	JP	HINDEX	
0754	00	0600	NOP		
0755	00	0610	NOP		
0756	00	0620	NOP		

0757 02	0630	NOP	
0758 AD 08	0640	DW	08ADH 0 SELECT ADDRESS
075A D8 08	0650	DW	08D8H 1 SELECT ADDRESS
075C D2 08	0660	DW	08D2H 2 SELECT ADDRESS
075E CC 08	0670	DW	08CCH 3 SELECT ADDRESS
0760 DE 08	0680	DW	08DEF 4 SELECT ADDRESS
0762 E4 08	0690	DW	08E4H 5 SELECT ADDRESS
0764 EA 08	0700	DW	08EAH 6 SELECT ADDRESS
0766 F0 08	0710	DW	08F0H 7 SELECT ADDRESS
0768 F6 08	0720	DW	08B6H 8 SELECT ADDRESS
076A BF 08	0730	DW	08BFH 9 SELECT ADDRESS
076C 80 08	0740	DW	0880H # SELECT ADDRESS
076E FF	0750 MSG1	DE	0FFH ERASE
076F	0760	DW	'# SEI DECK'
A3 A0 D3 C5 CC			
A0 C4 C5 C3 CE			
0779 04	0770	DB	4D SPACES
077A	0780	DW	'IN USE - '
C9 CE A0 D5 D3			
C5 A0 AD A0			
0783	0790 DKNBR	DW	'0'
B2			
0784 08	0800	DF	8D SPACES
0785	0810	DW	'0 COPY TAPE'
B0 A0 C3 CF D0			
D9 A0 D4 C1 D0			
C5			
790 15	0820	DB	21D SPACES
0791	0830	DW	'1 ERASE'
B1 A0 C5 D2 C1			
D3 C5			
0798 19	0840	DB	25D SPACES
0799	0850	DW	'2 FAST REVERSE'
B2 A0 C6 C1 D3			
I4 A0 D2 C5 L6			
C5 D2 D3 C5			
07A7 12	0860	DB	18D SPACES
07A8	0870	DW	'3 FAST FORWARD'
B3 A0 C6 C1 D3			
D4 A0 C6 CF D2			
D7 C1 L2 C4			
07B6 12	0880	DB	18D SPACES
07B7	0890	DW	'4 STANDBY'
B4 A0 D3 D4 C1			
CE C4 C2 D9			
07C0 17	0900	DB	23D SPACES
07C1	0910	DW	'5 STOP'
B5 A0 D3 D4 CF			
D0			
07C7 1A	0920	DB	26D SPACES
07C8	0930	DW	'6 READ'
B6 A0 D2 C5 C1			
C4			
07CE 1A	0940	DB	26D SPACES
07CF	0950	DW	'7 RECORD'

B7 A0 D2 C5 C3				
CF D2 C4				
07D7 18	0960	DB	24D SPACES	
07D8	0970	DW	'8 RECORD TEST DATA'	
B8 A0 D2 C5 C3				
CF D2 C4 A0 D4				
C5 D3 D4 A0 C4				
C1 D4 C1				
07EA 0E	0980	DB	14D SPACES	
07EB	0990	DW	'9 READ TEST DATA'	
E9 A0 D2 C5 C1				
C4 A0 D4 C5 D3				
D4 A0 C4 C1 D4				
C1				
07FB 57	1000	DB	87D SPACES	
07FC	1010	DW	'PHI DECK COMMANDS'	
D0 C8 C9 A0 C4				
C5 C3 CB A0 C3				
CF CD CD C1 CE				
C4 D3				
080D 00	1020	DB	0D RETURN	
080E FF	1030 MSG2	LB	0FFH ERASE	
080F 07	1040	DB	7D SPACES	
0810	1050	DW	'TAPE BEING COPIED'	
D4 C1 D0 C5 A0				
C2 C5 C9 CE C7				
A0 C3 CF D0 C9				
C5 C4				
0821 00	1260	DB	0D RETURN	
0822 FF	1070 MSG3	LB	0FFH ERASE	
0823 06	1080	DB	6D SPACES	
0824	1090	DW	'RECORDING TEST DATA'	
D2 C5 C3 CF D2				
C4 C9 CE C7 A0				
D4 C5 D3 D4 A0				
C4 C1 D4 C1				
0837 00	1100	LB	0D RETURN	
0838 FF	1110 MSG4	DB	0FFH ERASE	
0839 06	1120	LP	6D SPACES	
083A	1130	DW	'TEST DATA BEING READ'	
D4 C5 D3 D4 A0				
C4 C1 D4 C1 A0				
C2 C5 C9 CE C7				
A0 D2 C5 C1 C4				
084E 06	1140	DB	6D SPACES	
084F 00	1150	DB	0D RETURN	
0850 FF	1160 MSG5	DB	0FFH ERASE	
0851	1170	DW	'SELECT DECK NUMBER (0-3)'	
D3 C5 CC C5 C3				
D4 A0 C4 C5 C3				
CB A0 CE D5 CD				
C2 C5 D2 A0 A8				
B0 AD B3 A9				
0869 28	1180	DB	40D SPACES	
086A	1190	DW	'DECK # '	

C4 C5 C3 CE A0

A3 A0

2871

B0

0872 38

1200 DNR DW '0'

2873

1210 DE 56D SPACES  
1220 DW 'DONE? (Y?)'

C4 CF CE C5 BF

A0 A8 D9 BF A9

087D 02

1230 DE 0D RETURN

087E 00

1240 NOP

087F 00

1250 NOP

0882 21 50 08

1260 TV LD HL,MSG5 LOAD H&L WITH DECK

0883

1270 \* SELECT MESSAGE

0883 3A B6 0A

1280 LD A,(DECK) LOAD A WITH DECK #

2886 F6 B0

1290 OR 0B0H CONVERT TO ASCII

0888 32 71 08

1300 LD (DNR),A LOAD DECK NUMBER IN

088B

1310 \* MESSAGE AREA

088P CD 00 02

1320 CALL TVEDIT CALL TV EDITOR

288E DB 00

1330 IN 0 INPUT FROM KEYBOARD

0890 FE B4

1340 CP 0B4H >"3" ?

0892 D2 A5 08

1350 JP NC,DONE YES, CHECK FOR "Y"

0895 FE B2

1360 CP 0B2E <"0" ?

0897 DA 8E 08

1370 JP C,IN YES, JUMP TO KEYBOARD

089A

1380 \* (LOOK FOR A NUMBER)

089A 32 83 07

1390 LD (DNR),A IF BETWEEN 0 & 3, LOAD

089D

1400 \* DECK NUMBER IN MESSAGE

089D E6 03

1410 ANE 3D MASK ALL BUT 3 LSF'S

089F 32 B0 0A

1420 LD (DECK),A LOAD DECK NUMBER AT "DECK"

08A2 C3 80 08

1430 JP TV DISPLAY MESSAGE WITH NEW DECK #

08A5 F6 20

1440 DONE OR 20H CONVERT TO LOWER CASE

08A7 FE F9

1450 CP 0F9H "Y" ?

08A9 C2 80 08

1460 JP NZ,TV NO, JUMP TO MESSAGE

08AC CF

1470 RST 8D RESTART AT PHI DECK

08AD

1480 \* COMMANDS IF "Y"

08AD 21 0E 08

1490 CPYTP LD HL,MSG2 LOAD H&L WITH MESSAGE AREA

08B0 CD 00 02

1500 CALL TVEDIT CALL TV EDITOR

08B3 C3 C8 08

1510 JP CPY JUMP TO COPY TAPE ROUTINE

08B6 21 22 08

1520 RCTD LD HL,MSG3 LOAD H&L WITH MESSAGE AREA

08B9 CD 00 02

1530 CALL TVEDIT CALL TV EDITOR

08BC C3 A0 0B

1540 JP RCDTD JUMP TO RECCRD TEST DATA

08BF

1550 \* ROUTINE

08BF 21 38 08

1560 RDTD LD HL,MSG4 LOAD H&L WITH MESSAGE AREA

08C2 CD 00 02

1570 CALL TVEDIT CALL TV EDITOR

08C5 C3 CC 0B

1580 JP RTD JUMP TO READ TEST DATA

08C8

1590 \* ROUTINE

08C8 CD 00 0C

1600 CPY CALL COPY CALL COPY TAPE ROUTINE

08CB CF

1610 RST 8D RESTART

08CC 0E A0

1620 FFWD LD C,0A0H LOAD C WITH FAST FORWARD

08CE

1630 \* COMMAND

08CE CD 9B 0A

1640 CALL CMDOUT OUTPUT COMMAND

08D1 CF

1650 RST 8D RESTART

08D2 0E 80

1660 REV LD C,80H LOAD C WITH FAST REVERSE

08D4

1670 \* COMMAND

08D4 CD 9B 0A

1680 CALL CMDOUT OUTPUT COMMAND

08D7 CF

1690 RST 8D RESTART

08D8 0E EC	1700 ERASET LD C,0ECH LOAD C WITH ERASE COMMAND
08DA CD 9F 0A	1710 CALL CMDOUT OUTPUT COMMAND
68DD CF	1722 RST 8D RESTART
08DE 0E 70	1730 STNDEI LD C,70H LOAD C WITH STANDBY COMMAND
08E0 CD 9F 0A	1740 CALL CMDOUT OUTPUT COMMAND
08E3 CF	1752 RST 8D RESTART
08E4 0E F0	1760 STOP LD C,0F0H LOAD C WITH STOP COMMAND
08E6 CD 9B 0A	1770 CALL CMDOUT OUTPUT COMMAND
08E9 CF	1780 RST 8D RESTART
08EA 0E E0	1790 READ LD C,0E0H LOAD C WITH READ COMMAND
08EC CD 9B 0A	1800 CALL CMDOUT OUTPUT COMMAND
08EF CF	1810 RST 8D RESTART
08F0 0E E8	1820 RECORD LD C,0E8H LOAD C WITH RECORD COMMAND
08F2 CD 9B 0A	1830 CALL CMDOUT OUTPUT COMMAND
08F5 CF	1840 RST 8D RESTART

0BA0 06 00	0100 RCDTD	LD	B,0D	INITIALIZE COUNT
0EA2 0E E8	0110	LD	C,0EE2H	LOAD C WITH RECORD COMMAND
0BA4 CD 9B 0A	0120	CALL	CMDOUT	OUTPUT COMMAND
0BA7 48	0130 RCD	LD	C,B	LOAD C WITH COUNT
0BA8 CD A8 0A	0140	CALL	DOUT	OUTPUT DATA
0BAP DE 02	0150 STATUS	IN	2D	INPUT STATUS
0BAD EE 03	0160	AND	3D	READY?
0FAF CA AB 0B	0170	JP	Z,STATUS NO.	CHECK STATUS
0EB2 05	0180	DEC	P	DECREMENT COUNT
0EB3 C2 A7 0B	0190	JP	NZ,RCD	256?
0EF6 16 02	0200	LD	D,2D	YES, OUTPUT DUMMY CHARACTERS
0EB8 4E	0210 LOOP	LD	C,B	
0EB9 CD A8 0A	0220	CALL	DOUT	
0EFC DE 02	0230 STAT	IN	2D	INPUT STATUS
0BEE E6 03	0240	AND	3D	READY?
0EC0 CA BC 0B	0250	JP	Z,STAT	NO, CHECK STATUS
0EC3 15	0260	DEC	D	DECREMENT LCOF
0EC4 C2 B8 0B	0270	JP	NZ,LOOP	
0EC7 C3 A0 0E	0280	JP	RCDTD	RECORD NEXT BLOCK
0ECA 00	0290	NOP		
0BCB 02	0300	NOP		
0BCC 06 02	0310 RTD	LD	B,0	INITIALIZE COUNT
0ECE 0E E0	0320	LD	C,0EE2H	LOAD C WITH READ COMMAND
0BD0 CD 9B 0A	0330	CALL	CMDOUT	OUTPUT COMMAND
0BD3 DB 02	0340 STATR	IN	2D	INPUT STATUS
0BD5 E6 03	0350	AND	3I	READY?
0BI7 CA 13 0B	0360	JP	Z,STATR NO.	CHECK STATUS
0EDA CD 8F 0A	0370	CALL	DIN	YES INPUT DATA
0EDD 79	0380	LD	A,C	LOAD A WITH DATA
0BIE 18	0390	CP	F	COMPARE TO COUNT
0EDF C2 FF 0B	0400	JP	NZ,ERROR	
0FE2 05	0410	DEC	B	DECREMENT COUNT
0BE3 C2 D3 0B	0420	JP	NZ,STATR	
0BEE 21 FA 0B	0430	LD	FL,GOOD	OUTPUT "G" IF BLOCK IS GOOD
0BES CD 00 02	0440	CALL	TVEDII	CALL TV EDITOR
0BEC C3 CC 0B	0450	JP	RTD	READ NEXT BLOCK
0BEF 21 F8 0B	0460 ERROR	LD	HI,ERR	OUTPUT "E" IF BLOCK IS IN ERROR
0E12	0470 *			
0BF2 CL 02 02	0480	CALL	TVEEDIT	CALL TV EDITOR
0BF5 C3 CC 0B	0490	JP	RTD	READ NEXT BLOCK
0EF8 E5	0500 FRR	DP	0F5H	
0E99 E2	0510	DP	3	RETURN
05FA E7	0520 GOOD	DP	0F7H	
0FFE 22	0530	DP	1	RETURN
0EFC 02	0540	LDP		
03FD 02	0550	NOP		
0FFC 02	0560	NOP		
0BFF 00	0570	NOP		
0C02 3E 02	0580 COPY	LD	A,C	SET DECF2 2
0C02 32 F4 0A	0590	LD	(DECK),A	STORE DECF2 2
0C05 0F 4F 0A	0600	CALL	REWIND	REWIND DECK 2
0C06 3E 01	0610	LD	A,1P	SET DECF1 1
0C0A 32 B2 0A	0620	LD	(DECK),A	STORE DECK 1

0C0D CD 4F 0A	0630	CALL REWIND REWIND DECK 1
0C10 97	0640	SUF A CLEAR A
0C11 32 76 0C	0650	LD (TEMPID),A INITIALIZE ID
0C14 DB 02	0660	REDBLK IN TAPEIN
0C16 E6 08	0670	AND 8D WAIT FOR NOT BUSY
0C18 CA 14 0C	0680	JP Z,REDBLK
0C1B 3E 00	0690	LD A,0 SET DECK 0
0C1D 32 B0 0A	0700	LD (DECK),A STORE DECK 0
0C20 21 00 0D	0710	LD HL,BUFFER SET UP POINTER
0C23 22 B3 0A	0720	LD (POINTR),HL POINTER ADDRESS
0C26 3A 76 0C	0730	LD A,(TEMPID) SET UP ID
0C29 32 B1 2A	0740	LD (IDR),A
0C2C 1E 00	0750	LD E,0 SET UP READ MODE
0C2E CD E9 2A	0760	CALL READ
0C31 F5	0770	PUSH AF SAVE A & FLAGS
0C32 0E F0	0780	LD C,0F0H STOP DECK
0C34 CD 9E 0A	0790	CALL CMDOUT
0C37 F1	0800	POP AF RESTORE A & FLAGS
0C38 FE 00	0810	CP 0 ERROR?
0C3A CA 41 0C	0820	JP Z,WRTBLK NO
0C3D FE 02	0830	CP 2D BLOCK FOUND?
0C3F C8	0840	RET Z NO, FINISHED
0C40 76	0850	HALT HALT BECAUSE OF ERROR
0C41 DB 02	0860	WRTBLK IN TAPEIN
0C43 E6 08	0870	AND 8D WAIT FOR NOT BUSY
0C45 CA 41 0C	0880	JP Z,WRTBLK
0C48 3E 01	0890	LD A,1D SET DECK 1
0C4A 32 B0 2A	0900	LD (DECK),A STORE DECK 1
0C4D 21 00 0D	0910	LD HL,BUFFER SET UP POINTER
0C50 22 B7 0A	0920	LD (POINTW),HL
0C53 3A 76 0C	0930	LD A,(TEMPID) SET UP ID
0C56 32 B5 0A	0940	LD (IDW),A
0C59 3C	0950	INC A
0C5A 32 76 0C	0960	LD (TEMPID),A
0C5D 78	0970	LD A,B SET UP COUNT
0C5E FE 00	0980	CP 0 256?
0C60 CA 69 0C	0990	JP Z,X256
0C63 68	1000	LD L,B
0C64 26 00	1010	LD H,0
0C66 C3 6D 0C	1020	JP CALRCD
0C69 26 01	1030 X256	LD H,1D
0C6B 2E 02	1040	LD L,0
0C6D CD 00 09	1050 CALRCD	CALL RECORD
0C70 FE 00	1060	CP 0
0C72 CA 14 0C	1070	JP Z,REDBLK
0C75 76	1080	HALT

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LOC	OBJ	LABEL	OP	OPERAND	COMMENTS
2902		2120	*	RECORD (UNTIL COUNT EXHAUSTED)	
2942		2110	*	DECK IS STOPPED AFTER RETURN	
2922		2126	*	INPUT:	
2922		2132	*	LECK - DECK NUMBER LOCATED IN MEMORY	
2922		2140	*	POINTW - LOCATED IN MEMORY	
2922		2150	*	(FIRST DATA BYTE)	
2922		2162	*	IDW - LOCATED IN MEMORY (FIRST BLOCK)	
2922		2170	*	COUNT - REGISTER H,L	
2922		2182	*	OUTPUT:	
2922		2190	*	POINTW - LOCATED IN MEMORY	
2922		2202	*	(LAST DATA BYTE + 1)	
2922		2212	*	ERHCF - REGISTER A	
2922		2220	*	2 - NO ERRORS	
2922		2232	*	1 - CRC ERROR IN BLOCK	
2922		2242	*	IDW - 1	
2922		2250	*	2 - BLOCK IDW-1 NOT FOUND	
2922		2262	*	3 - TAPE END OR JAM	
2922		2270	*	IPW - LOCATED IN MEMORY	
2922		2282	*	(LAST BLOCK + 1)	
2922		2292	*	ALTERED	
2922		2340	*	REGISTERS - A,F,C,P,E,H,L,DR,POINTW	
2922 16 21		2310	RCD01	LI I,1I	ERASF=1
2922 1F 05		2320		LD E,5D	STOPS=5
2922 E5		2330		PUSH HL	COUNT
2922 F5		2340	RCD12	PUSH PE	ERASF, STOPS
2922 2A B5 2A		2350		LD PL,(IDW)	
2922 2F		2360		DEC PL	IDR=IDW -1
2922 22 B1 2A		2370		LL (IDR),PL	
2922 23		2380		INC HL	
2922 71		2390		ID A,L	IDW=0 ?
2922 B4		2400		CR H	
2912 CA 29 29		2410		JP Z,RCD10	YES
2912 16 2F		2420		LL D,11D	RETRIFS = 12
2912 1E 01		2430		LD E,1D	CHECK MODE
2912 CD 7P 2E		2440		CALL ALTRD	
2912 3C		2450		INC A	ERRCR?
2912 3I		2460		DEC A	
2912 CA 36 29		2470		JP Z,RCD13	NO
2912 I1		2480	RCD12	POP DE	ERASE, STOPS
2920 E1		2490	RCD21	POP HL	COUNT
2921 2F 92		2500	RCD27	LD C,90H	STOP
2922 47		2510		LD F,A	SAVE ERROR
2922 CT 9F 2A		2520		CALL CMDOUT	
2922 7E		2530		LD A,B	RESTORE ERROR
2922 C9		2540		RET	
2922 CT 4F 0A		2550	RCD10	CALL REWIND	
2922 4E EC		2560		LD C,0ECE	ERASE
2922 CT 9F 2A		2570		CALL CMDOUT	

0931 3E 28	0580	LD A,40D 4 SECONDS
0933 CD 81 0A	0590	CALL DELAY
0936 D1	0600 RCD13	POP DE ERASE, STOPS
0937 D5	0610	PUSH DE
0938 15	0620 RCD15	DEC D ERASE (ERASE - 1) BLOCKS
0939 CA 40 09	0630	JP Z,RCD14
093C 0E EC	0640	LD C,0ECH ERASE
093E CD 9B 0A	0650	CALL CMDOUT
0941 D5	0660	PUSH DE
0942 CD DA 09	0670	CALL RECRD1
0945 I1	0680	POP DE
0946 C3 38 09	0690	JP RCD15
0949 E1	0700 RCD14	POP HL ERASE, STOPS
094A D1	0710	POP DE COUNT
094B D5	0720	PUSH DE
094C E5	0730	PUSH HL
094D 2A B7 0A	0740	LD HL,(POINTW) POINTER
0950 15	0750 RCD19	DEC D COUNT HIGH = 0?
0951 14	0760	INC D
0952 C2 D4 09	0770	JP NZ,RCD16 NO
0955 1D	0780	DEC E
0956 1C	0790	INC E
0957 CA 81 09	0800	JP Z,RCD17 YES
095A 43	0810	LD B,E COUNT = COUNTL
095B 1E 00	0820	LD E,0D COUNTL = 0
095D D5	0830 RCD18	PUSH DE SAVE COUNT
095E FB	0840	EX DE,HL
095F 2A B1 0A	0850	LD HL,(IDR)
0962 23	0860	INC HL
0963 22 B1 0A	0870	LD (IDR),HL
0966 EB	0880	EX DE,HL
0967 0E E8	0890	LD C,0E8H RECORD
0969 CD 9B 0A	0900	CALL CMDOUT
09EC CD DA 09	0910	CALL RECRD1
09EF DF 02	0920	IN TAPEIN ERROR?
0971 E6 0D	0930	AND 0DH
0973 D1	0940	POP DE GET COUNT
0974 CA 50 09	0950	JP Z,RCD19 NO
0977 I1	0960	POP DE DECREMENT STOPS
0978 1D	0970	DEC E 0?
0979 C2 05 09	0980	JP NZ,RCD20 NO
097C 3E 03	0990	LD A,3D ERROR=3
097E C3 20 09	1000	JP RCD21
0981 3E 05	1010 RCD17	LD A,5D APPROXIMATELY 10 BLOCKS
0983 CD 68 0A	1020	CALL FR
0986 E1	1030	POP HL ERASE, STOPS
0987 D1	1040	POP DE COUNT
0988 D5	1050 RCD26	PUSH DE
0989 E5	1060	PUSH HL
098A 97	1070	SUB A COUNT=0?
098B E2	1080	ADD D
098C C2 93 09	1090	JP NZ,RCD22 NO
098F 63	1100	ADD E
0990 CA 1F 09	1110	JP Z,RCD12 YES
0993 2A B5 0A	1120 RCD22	LD HL,(IDW)
0996 22 B1 0A	1130	LD (IDR),HL

2999	16 06	1140	ID L,ED	RETRIES = 6
299P	1E 01	1150	LD E,1D	CHECK MODE
299D	CD BB 0A	1160	CALL ALTRD2	
29A0	3C	1170	INC A	ERROR?
29A1	3D	1180	DEC A	
29A2	D1	1190	POP DE	
29A3	CA AA 08	1200	JP Z,RCD24	NO
29A5	14	1210	INC D	INCREMENT ERASE
29A7	C3 25 29	1220	JP RCD20	
29AA	16 41	1230	LD D,1D	ERASE=1
29AC	2A FC 0A	1240	LD HL,(IDW)	INCREMENT IDW
29AF	23	1250	INC HL	
29B2	22 F3 2A	1260	LD (IPW),HL	
29B3	FF	1270	EX DE,HI	
29B4	11	1280	POP DE	
29B5	14	1290	INC D	COUNTH = 2?
29B6	15	1300	DEC D	
29B7	CA 07 29	1310	JP Z,RCD21	YES
29BA	15	1320	DEC D	DECREMENT COUNTH
29EE	E5	1330	PUSH HL	
29BC	2A B7 2A	1340	LD HL,(POINTW)	
29BF	24	1350	INC F	
29C0	22 B7 2A	1360	LD (POINTW),HI	
29C3	E1	1370	POP HL	
29C4	C3 82 09	1380	JP RCD26	
29C7	2A P7 2A	1390	LD HL,(POINTW) ALL COUNTL TO POINTER	
29CA	16 02	1400	LD I,2P	
29CC	19	1410	SUB HL,HI	
29CD	22 B7 2A	1420	LD (POINTW),HI	
29D0	97	1430	SUB A	ERROR = 2
29D1	C3 21 09	1440	JP RCD27	
29D4	15	1450	PCP16 DEC D	DECREMENT COUNTH
29F5	26 00	1460	LD E,CP	COUNT=0
29D7	C3 50 29	1470	JP RCD19	
29DA	*	1480	* RECALL (RECORD ONE BLOCK)	
29DA	*	1490	RECALL OR ERASE COMMAND MUST BE ISSUED	
29DA	*	1500	BEFORE CALLING.	
29DA	*	1510	UNDERRUN AND STOP SHOULD BE CHECKED	
29DA	*	1520	AFTER RETURN.	
29DA	*	1530	INPUTS:	
29IA	*	1540	DECK - DECK NUMBER LOCATED	
29IA	*	1550	IN MEMORY	
29DA	*	1560	ID - REGISTER I,F	
29IA	*	1570	COUNT - REGISTER F	
29IA	*	1580	(01=1 BYTE, 25=256 BYTES)	
29DA	*	1590	POINTER - REGISTER E,I	
29DA	*	1600	(FIRST DATA BYTE)	
29IA	*	1610	OUTPUT:	
29DA	*	1620	POINTER - REGISTER E,I	
29DA	*	1630	(LAST DATA BYTE + 1)	
29IA	*	1640	ALIENEL	
29DA	*	1650	REGISTERS - A,B,C,D,E,F,I	
29IA	E5	1660	RECDP1 PUSH HL	PUSH POINTW
29DB	21 02 00	1670	LD HL,Z1	REGISTER C=0
29DE	4A	1680	LD C,D	I0 TRUE
29DF	CD 45 0A	1690	CALL ALIPUT	
		1700		
		1710		

09E2	4B	1720	LD C,E	ID LOW
09E3	CD 42 2A	1730	CALL PUT	
09E6	48	1740	LD C,B	COUNT
09E7	CD 42 0A	1750	CALL PUT	
09EA	54	1760	LD D,H	SAVE CRC2
09EB	4L	1770	LD C,L	CRC1
09EC	CD 42 0A	1780	CALL PUT	
09EF	4A	1790	LD C,D	CRC2
09F0	CD 42 0A	1800	CALL PUT	
09F3	58	1810	LD E,B	SAVE COUNT
09F4	E3	1820	RECD1	EX (SP),HL SWITCH CRC, POINTER
09F5	4E	1830	LD C,(HL)	LOAD DATA
09F6	23	1840	INC HL	INCREMENT POINTER
09F7	E3	1850	EX (SP),HL	SWITCH CRC, POINTER
09F8	CD 42 2A	1860	CALL PUT	
09FF	25	1870	DEC B	DECREMENT COUNT
09FC	C2 F4 09	1880	JP NZ,RECD1	NOT ZERO
09FF	54	1890	LD D,H	SAVE CRC2
0A00	4D	1900	LD C,L	CRC1
0A01	CD 42 0A	1910	CALL PUT	
0A04	4A	1920	LD C,D	CRC2
0A05	CD 42 0A	1930	CALL PUT	
0A08	1D	1940	DEC E	DECREMENT SAVED COUNT
0A09	CD 42 2A	1950	RECD3	CALL PUT
0A0C	1C	1960	INC E	INCREMENT SAVED COUNT
0A0D	C2 29 0A	1970	JP NZ,RECD3	NCT ZERO
0A10	CD 42 0A	1980	CALL PUT	
0A13	E1	1990	POP HL	POP POINTER
0A14	C9	2000	RET	
0A15		2010	*	GET
0A15		2020	*	CRC IN H,L
0A15		2030	*	DATA RETURNED IN C
0A15		2040	*	A,C,H,L ALTERED
0A15	DB 02	2050	GET	IN TAPEIN STATUS
0A17	E6 0F	2060	AND 0FH	
0A19	CA 15 2A	2070	JP Z,GET	
0A1C	CD 8F 0A	2080	CALL DIN	
0A1F	D5	2090	CRC	PUSH DE
0A20	79	2100	LD A,C	
0A21	AD	2110	XOR L	
0A22	6F	2120	LD L,A	
0A23	1E 07	2130	LD E,7D	7 TIMES
0A25	17	2140	CRCA	RLA A
0A26	AD	2150	XCR L	
0A27	1D	2160	DEC E	
0A28	C2 25 0A	2170	JP NZ,CRCA	DONE?
0A2B	6F	2180	LD L,A	YES
0A2C	0F	2190	RRCA A	
0A2D	0F	2200	RRCA A	
0A2E	5F	2210	LD E,A	SAVE 1
0A2F	E6 C0	2220	AND 0C0H	
0A31	AC	2230	XOR H	
0A32	57	2240	LD D,A	SAVE 2
0A33	7B	2250	LD A,E	RESTORE 1
0A34	E6 3F	2260	AND 3FH	
0A36	AD	2270	XOR L	

2A37	E7	2282	LD	E,A	CRC HIGH DONE	
2A38	17	2292	RLA	A	TEST FIT 7	
2A39	7A	2302	LD	A,D	RESTORE 2	
2A3A	D2	2312	JP	NC,CRCFIN	BIT 7 WAS 1?	
2A3D	EE	2322	XCR	1D	YES	
2A3F	6F	2332	CRCFIN	LD	L,A	CRC LOW DONE
2A40	D1	2342	POP	DE		
2A41	C9	2352	RFT			
2A42		2362	*	PUT		
2A42		2370	*	DATA IN REGISTER C		
2A42		2380	*	CRC IN H,L		
2A42		2390	*	A,H,L ALTERED		
2A42	DE	2400	PUT	IN	TAPEIN STATUS	
2A44	EE	2410	AND	0FH		
2A46	CA	2420	JP	Z,PUT		
2A49	CD	2430	ALIPUT	CALL	DOUT	
2A4C	C3	2440	JP	CRC		
2A4F		2450	*	REWIND		
2A4F		2460	*	REGISTER A,C ALTERED		
2A4F		2470	*	THIS ROUTINE WILL GUARANTEE		
2A4F		2480	*	LECK SELECTION		
2A4F	0E	2490	REWIND	LD	C,90H STOP	
2A51	CD	2502	CALL	CMDOUT		
2A54	FB	2510	REWB	IN	TAPEIN	
2A56	EE	2520	AND	08H		
2A58	CA	2530	JP	Z,REW		
2A5F	2E	2540	LD	C,80H FR		
2A5D	CD	2550	CALL	CMDOUT		
2A62	DE	2560	REWA	IN	TAPEIN	
2A62	E6	2570	AND	8D		
2A64	CA	2580	JP	Z,REWA		
2A67	C9	2590	RET			
2A68		2600	*	FAST REVERSE, FAST FORWARD		
2A68		2610	*	REGISTER A CONTAINS MULTIPLE		
2A68		2620	*	OF 100 MILLI-SECONDS DELAY		
2A68		2630	*	REGISTER A ALTERED		
2A68	C5	2640	FR	PUSH BC		
2A69	F5	2650		PUSH AF		
2A6A	2E	2660	LD	C,80H		
2A6C	CD	2670	FRA	CALL CMDOUT		
2A6F	F1	2680		POP AF		
2A70	CD	2690		CALL DELAY		
2A73	2E	2700	LD	C,90H		
2A75	CD	2710		CALL CMDOUT		
2A78	C1	2720		POP BC		
2A79	C9	2730		RET		
2A7A	C5	2740	FF	PUSH BC		
2A7B	F5	2750		PUSH AF		
2A7C	2E	2760	LD	C,0A0H		
2A7E	C3	2770		JP FRA		
2A81		2780	*	DELAY MULTIPLE OF 100 MS IN REGISTER A		
2A81		2790	*	REGISTERS A,B,C ALTERED		
2A81	01	2800	DELAY	LD	BC,29B4H	
2A84	0B	2810	D1	DEC	BC	
A85	04	2820		INC	B	
2A86	05	2830		DEC	B	

0A87 C2 84 0A	2840	JP NZ,D1
0A8A 3D	2850	DEC A
0A8B C2 81 0A	2860	JP NZ,DELAY
0A8E C9	2870	RET
0A8F	2880 *	INPUT DATA. BYTE (DATA RETURNED IN C)
0A8F	2890 *	REGISTER A IS ALTERED
0A8F 3E EF	2900 DIN	LD A,2EFF
0A91 D3 21	2910	OUT STROBE
0A93 1B 02	2922	IN TAPEIN
0A95 4F	2930	LD C,A
0A96 3F DF	2940 DINA	LD A,0DFH
0A98 13 01	2950	OUT STROBE
0A9A C9	2960	RET
0A9E	2970 *	OUTPUT COMMAND (DATA IN REGISTER C)
0A9B	2980 *	DECK IS OR'D WITH DATA
0A9B	2990 *	REGISTER A IS ALTERED
0A9E 3A B2 0A	3000 CMDOUT	LD A,(DECK)
0A9E E1	3010	OR C
0A9F D3 02	3020	OUT TAPOUT
0AA1 3E 9F	3030	LD A,9FH
0AA3 D3 01	3040 CMDA	CUT STROBE
0AA5 C3 96 0A	3050	JP DINA
0AA8	3060 *	OUTPUT DATA (DATA IN REGISTER C)
0AA8	3070 *	REGISTER A IS ALTERED
0AA8 79	3080 DOUT	LD A,C
0AA9 D3 02	3090	CUT TAPOUT
0AAE 3E 5F	3100	LD A,5FH
0AAD C3 A3 0A	3110	JP CMDA
0AEC	3120 *	VARIAPLE DATA AREA
0AEC	3130 DECK	DS 1D DECK NUMBER TO BE USED
0AB1	3140 IDR	DS 2D READ ID
0AB3	3150 POINTR	DS 2D READ POINTER
0AB5	3160 IDW	DS 2D WRITE ID
0AB7	3170 POINTW	DS 2D WRITE POINTER
0AB9	3180 *	READ ONE FLOCK
0AB9	3190 *	DECK REMAINS RUNNING AFTER RETURN
0AB9	3200 *	INPUT:
0AB9	3210 *	DECK - DECK NUMBER LOCATED IN MEMORY
0AB9	3220 *	POINTR - LOCATED IN MEMORY
0AB9	3230 *	(FIRST BYTE)
0AB9	3240 *	IDR - LOCATED IN MEMORY
0AB9	3250 *	RETRY'S - REGISTER D (ALTRD ONLY)
0AB9	3260 *	MODE - REGISTER E 0=READ
0AB9	3270 *	1=CHECK
0AB9	3280 *	OUTPUT:
0AB9	3290 *	DECK, POINTER, IDR UNCHANGED
0AB9	3300 *	REGISTER - A,B,C,D,E,L ALTERED
0AB9	3310 *	COUNT - REGISTER E 01=1 BYTE
0AB9	3320 *	00=256 BYTES
0AB9	3330 *	ERROR - REGISTER A 0=NO ERRORS
0AB9	3340 *	1=CRC ERROR
0AB9	3350 *	2=BLOCK NOT FOUND
0AB9	3360 *	
0AB9	3370 *	
0AB9	3380 *	
0AB9	3390 *	

0A9 3400 \* 3=END OF TAPE OR JAM  
 0A9 3410 \* ENTRY POINTS:  
 AB9 3420 \* READ - NORMAL ENTRY  
 0AB9 3430 \* ALTRD - DECK WILL BACKSPACE  
 0AP9 3440 \* FIRST, USER MUST SUPPLY RETRIES  
 0AB9 3450 \* ALTRD2 - NORMAL, EXCEPT USER MUST  
 0AP9 3460 \* SUPPLY RETRIES.  
 0AP9 16 0A 3470 READ LD D,10D RETRIES  
 0AEB D5 3480 RD54 PUSH DE RETRIES, MODE  
 0AFC 3490 ALTRD2 EQU RD54  
 0ABC 21 00 02 3500 RD5 LD HL,0D RESET CRC  
 0ABF DB 02 3510 IN TAPFIN STATUS  
 0AC1 57 3520 LD D,A  
 0AC2 0E E0 3530 RD51 LD C,0E0H READ  
 0AC4 CD 9B 0A 3540 CALL CMDOUT  
 0AC7 7A 3550 LD A,D STOP?  
 0ACE E6 04 3560 AND 04H  
 0ACA CA D7 0A 3570 JP Z,RD50 NO  
 0ACD 3E 04 3580 LD A,4D .4 SECONDS  
 0ACF CD 81 0A 3590 CALL DELAY  
 0AD2 16 02 3600 LD D,0D STATUS=0  
 0AD4 C3 C2 0A 3610 JP RD51  
 0AD7 06 3A 3620 RD50 LD B,3AH 8 SECOND TIMEOUT  
 0AD9 50 3630 RD57 LD D,B  
 0ADA DB 02 3640 RD53 IN TAPEIN STATUS  
 0ADC E6 0F 3650 AND 0FH READY?  
 0ADE C2 90 0B 3660 JP NZ,RD10 YES  
 0AF1 1F 3670 DEC DE  
 0AE2 14 3680 INC D  
 0AE3 15 3690 DEC D  
 0AE4 C2 DA 0A 3700 JP NZ,RD53  
 0AE7 05 3710 DEC B  
 0AE8 C2 D9 0A 3720 JP NZ,RD57  
 0AEP CD 4F 0A 3730 CALL REWIND  
 0AEE 3E 02 3740 RD2 LD A,2D ERROR=2  
 0AF0 D1 3750 POP DE RETRIES, MODE  
 0AF1 15 3760 RD8 DEC D  
 0AF2 C2 BB 0A 3770 JP NZ,RD54  
 0AF5 C9 3780 RET  
 0AF6 CD 15 0A 3790 RD52 CALL GET IDH  
 0AF9 41 3800 LD B,C  
 0AFA CD 15 0A 3810 CALL GET IDL  
 0AFD 59 3820 LD E,C  
 0AFE CD 15 0A 3830 CALL GET COUNT  
 0B01 51 3840 LD D,C  
 0B02 CD 15 0A 3850 CALL GET CRC1  
 0B05 CD 15 2A 3860 CALL GET CRC2  
 0B08 97 3870 SUB A CRC=0?  
 0B09 84 3880 ADD H  
 0B0A C2 BC 0A 3890 JP NZ,RD5 NO  
 0B0D 85 3900 ADD L  
 0B0E C2 BC 0A 3910 JP NZ,RD5 NO  
 0B11 3920 \* COMPUTE BE TAPEID  
 0B11 3930 \* -HL IDR  
 0B11 3940 \* =XY  
 0B11 7B 3950 LD A,E

2E12	2A	51	2A	3960	LI	E1.(ITP)
2B15	9E			3972	SUB	I
0E16	5F			3980	LD	E,A REGISTER A CONTAINS Y
2E17	6F			3992	LP	L,A
2E18	78			4200	LI	A,F
2E19	90			4212	SEC	V REGISTER A CONTAINS ?
2E1A	67			4224	ID	E,A F=XY/Z
0E1B	29			4232	ADD	HL,HL
0E1C	29			4242	ADD	HL,FI
0E1D	29			4252	ADD	FL,FI
2E1F	29			4262	ADD	FI,FL
2E1F	29			4270	ADD	FL,FL
2F22	70			4282	LI	A,H
2P21	CA	38	2F	4090	JP	Z,IP1
0E24	F2	3D	0B	4100	JP	P,ID2
2E27	2F			4110	CPL	COMPUTE FF DELAY
2E28	C6	02		4120	AID	2D ALD1+1 FOR Z'S COMP
0E2A	FA	32	0F	4130	JP	M, ID3
0E2D	FE	04		4140	CF	4D GREATER THAN THRESHOLD?
0E2F	FA	BC	0A	4150	JP	M,RL5 NO
0E32	CD	7A	0A	4160	ID3	CALL FF
0E35	C3	EC	0A	4170	JP	RD5
0E38	1C			4180	ID1	INC E Y=0?
0E39	1D			4190	DFC	E
0F3A	CA	45	2F	4200	JP	Z,RDS YES
0E3D	C6	26		4210	ID2	ALD ED
0E3F	CD	62	0A	4220	CALL	FR
2E42	C3	EE	0A	4230	JP	RD2
2E45	42			4240	RD6	LL B,D COUNT
2E46	D1			4250	POP	DE RETRIES, MODE
0E47	C5			4260	PUSH	PC CCUNT
0E48	2A	B3	2A	4270	LL	HL,(POINTR)
0E49	F5			4280	PUSH	FL
2E4C	21	02	00	4290	ID	HL,ED RESET CRC
0E4F	CD	15	0A	4300	R156	CALL GET
0E52	1C			4310	INC	E
2E53	1D			4320	DEC	E
2E54	C2	5F	0B	4330	JA	NZ,E,E
0E57	E3			4340	YY	(SP),HL SWITCH CRC,POINTER
2E58	71			4350	LP	(HL),C STORE DATA
0E59	23			4360	INC	HL BUMP POINTER
0E5A	E3			4370	EX	(SP),HL SWITCH CRC, POINTER
0E5F	05			4380	RD55	DEC E DECREMENT COUNT
2E5C	C2	4F	0B	4390	JP	NZ, RD56
2B5F	C1			4400	POP	PC ADJUST STACK POINTER
2E60	C1			4410	PCP	PC CCUNT
0E61	CD	15	0A	4420	CALL	GET
0E64	CD	15	0A	4430	CALL	GET
2E67	DF	02		4440	IN	TAPEIN STATUS
2E69	1F			4450	RRA	OVERRUN?
0E6A	DA	7B	0B	4460	JP	C,ALTRD YES
0E6D	1F			4470	RRA	A
0E6E	1F			4480	RRA	A STOP?
0E6F	DA	96	0B	4490	JP	C, RD11 YES
0F72	97			4500	SUB	A
0E73	E4			4510	ADD	H

0B74 C2 7F 0B	4520	JP NZ,ALTRD NO
0E77 E5	4530	ADD L
078 CA 85 0B	4540	JP Z, RD19
0E7B 3E 05	4550 ALTRD	LD A,5D GREATER THAN 1 FLOCK
057D CD 6E 0A	4560	CALL FR
2B80 3E 01	4570	LD A,1D ERROR=1
2B82 C3 F1 0A	4580	JP RD8
0B85 50	4590 RD19	LL I,B SAVE COUNT
0B86 15	4600	DFC D DECREMENT SAVED COUNT
0B87 CD 15 0A	4610 RD9	CALL GET
0B8A 14	4620	INC D INCREMENT SAVED COUNT
0B8B C2 87 0B	4630	JP NZ, RD9
0B8E 97	4640	SUB A ERROR=0
0B8F C9	4650	RET
0B90 E6 04	4660 RD10	AND 04H STOP?
0B92 CA F6 2A	4670	JP Z, RD52 NO
0B95 I1	4680	POP DE RETRIES, MODE
0B96 CD 4F 0A	4690 RD11	CALL REWIND
0B99 3E 03	4700	LT A,3D ERROR=3
2B9B C3 F1 0A	4710	JP RD8

8080 PHI-DECK DEMO SOFTWARE

1. Programs are loaded via AUDIO CASSETTE.
2. At completion of a successful load, a listing of Phi-Deck Command options will be displayed.
3. In addition to the options displayed on the screen, there are also three options possible - "R", "S", and "P".
4. "R" will return control to 8080 OPS System options which include:
  - 1 READ Cassette - Read an Audio Cassette
  - 2 WRITE Cassette - Write an Audio Cassette
  - 3 TV Storage Dump - TV Display of Memory in Octal
  - 4 Keyboard Program - User may program in Octal
  - 5 PHI-DECK OPS
5. "S" will display memory as option 3 in 8080 OPS System.
6. "P" will allow user to program same as option 4 in 8080 OPS System.
7. Reset will return control to Phi-Deck Commands.
8. "P", "R", and "S" will operate also when in Program, Storage Dump, or Phi-Deck OPS.
9. Phi-Deck Option "#" allows user to select any of four decks (0-3) by first pressing shift and # then the desired deck number. To return to Phi-Deck OPS press Y. The deck number selected will be displayed in Options listing upon return.
10. Phi-Deck Option "1" will erase a tape on the selected deck.
11. Phi-Deck Option "2" will fast reverse the selected deck.
12. Phi-Deck Option "3" will fast forward the selected deck.
13. Phi-Deck Option "4" will place all decks in standby. The capstan motors will be turned off.
14. Phi-Deck Option "5" will stop the selected deck.
15. Phi-Deck Option "6" will issue a read command to the selected deck. This will not read data from the tape.
16. Phi-Deck Option "7" will issue a record command to the selected deck. This will not record data on the tape.
17. Phi-Deck Option "8" will record 256 byte blocks of data in a fixed pattern.
18. Phi-Deck Option "9" will read 256 byte blocks of data in the same pattern as recorded in Option "8". An "e" will be displayed on the monitor for blocks in error and a "g" for good blocks.
19. Page 015 is being used as a 256 byte buffer in the copy tape routine.
20. Option "0" will copy a tape from deck #0 to deck #1. This is not intended as an efficient method of duplicating Phi-Deck Tapes, only as a demonstration of Phi-Deck routines.

CHANGES TO 8080 OPERATING SYSTEM  
FOR PHI-DECK DEMO

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<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
005 112		170			ADDRESS JUMP
005 113		007			FOR KEY 5
005 271		016			SPACES
005 272		265			5
005 273		240			
005 274		320			P
005 275		310			H
005 276		311			I
005 277		240			
005 300		304			D
005 301		305			E
005 302		303			C
005 303		313			K
005 304		240			
005 305		317			O
005 306		320			P
005 307		323			S
005 310		000			RETURN
001 003		170			
001 004		007			
003 257		003			
003 260		005			
004 176		003			
004 177		005			
005 000		303			
005 001		170			
005 002		007			

8080 PHI-DECK DEMO SOFTWARE

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
007 000	076 000		COPY	MVI	A, Ø
007 002	062 26Ø Ø12		STA	DECK	STORE DECK #
007 005	315 117 Ø12		CALL	REWIND	REWIND DECK Ø
007 010	076 001		MVI	A,1	SET DECK 1
007 012	062 26Ø Ø12		STA	DECK	STORE DECK #
007 015	315 117 Ø12		CALL	REWIND	REWIND DECK 1
007 020	227		SUB	A	CLEAR A
007 021	062 166 007		STA	TEMPID	INITIALIZE ID
007 024	333 002	REDBLK	IN	TAPEIN	WAIT FOR NOT BUSY
007 026	346 Ø10		ANI	Ø1Ø	
007 030	312 024 007		JZ	REDBLK	
007 033	076 000		MVI	A,Ø	SET DECK Ø
007 035	062 26Ø Ø12		STA	DECK	STORE DECK #
007 040	041 000 015		LXI	H,BUFFER	SET UP POINTER
007 043	042 263 Ø12		SHLD	POINTR	STORE POINTER ADDRESS
007 046	072 166 007		LDA	TEMPID	SET UP ID
007 051	062 261 Ø12		STA	IDR	
007 054	036 000		MVI	E,Ø	SET UP READ MODE
007 056	315 271 Ø12		CALL	READ	READ A BLOCK
007 061	365		PUSH	PSW	SAVE A
007 062	Ø16 36Ø		MVI	C, 36Ø	STOP DECK
007 064	315 233 Ø12		CALL	CMDOUT	
007 067	361		POP	PSW	RESTORE A
007 070	376 000		CPI	Ø	ERROR
007 072	312 101 007		JZ	WRTBLK	NO
007 075	376 002		CPI	ØØ2	BLOCK FOUND?
007 077	31Ø		RZ		NO, FINISHED
007 100	166		HLT		HALT BECAUSE OF ERROR
007 101	333 002	WRTBLK	IN	TAPEIN	WAIT FOR NOT BUSY DECK NUMBER CHANGING
007 103	346 Ø1Ø		ANI	Ø1Ø	
007 105	312 101 007		JZ	WRTBLK	
007 110	076 001		MVI	A,1	SET DECK 1
007 112	062 26Ø Ø12		STA	DECK	
007 115	041 000 015		LXI	H,BUFFER	SET UP POINTER
007 120	042 267 Ø12		SHLD	POINTW	
007 123	072 166 007		LDA	TEMPID	SET UP ID
007 126	062 265 Ø12		STA	IDW	
007 131	074		INR	A	INCREMENT ID
007 132	062 166 007		STA	TEMPID	
007 135	17Ø		MOV	A,B	SET UP COUNT
007 136	376 000		CPI	Ø	256?
007 140	312 151 007		JZ	X256	
007 143	15Ø		MOV	L,B	

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
007 144	046 000		MVI	H,Ø	
007 146	303 155 007		JMP	CALRCD	
007 151	046 001	X256	MVI	H,1	
007 153	056 000		MVI	L,Ø	
007 155	315 000 Ø11	CALRCD	CALL	RECORD	RECORD BLOCK
007 160	376 000		CPI	Ø	
007 162	312 Ø24 007		JZ	REDBLK	
007 165	166		HLT		
007 166	Ø00 Ø00	TEMPID			
007 170	Ø61 Ø00 Ø02		LXI	SP	LOAD STACK POINTER
007 173	373		EI		
007 174	Ø41 316 007		LXI	H	
007 177	Ø72 26Ø Ø12		LDA	(Ø12 26Ø)	LOAD A W DECK #
007 202	366 26Ø		ORI	26Ø	CONVERT TO ASCII
007 204	Ø62 342 007		STA	ØØ7 342	PLACE DECK # IN MESSAGE
007 207	315 Ø45 Ø02		CALL	TVEDIT	CALL TV EDITOR
007 212	315 Ø00 Ø02	KYBD	CALL		CALL KEYBOARD
007 215	376 272		CPI	272	NUMBER?
007 217	322 155 Ø1Ø		JNC	LETTER	NO, JUMP TO LETTERS
007 222	376 26Ø		CPI	26Ø	< Ø ?
007 224	332 256 007		JC	CHARS	YES, JUMP TO CHARS
007 227	365		PUSH	A	SAVE A
007 23Ø	315 Ø21 Ø02		CALL	ERASE	ERASE
007 233	361		POP	A	RESTORE A
007 234	ØØ7		RLC		ROTATE LEFT
007 235	3Ø6 127		ADI	127	PRODUCE L INDEX
007 237	157		MOV	L,A	
007 24Ø	Ø46 007		MVI	H, ØØ7	H INDEX
007 242	176		MOV	A,M	
007 243	Ø62 254 007		STA		STORE A
007 246	Ø43		INX	H	INCREMENT H & L
007 247	176		MOV	A,M	
007 25Ø	Ø62 255 007		STA		
007 253	3Ø3 * *		JMP		
007 256	376 243	CHARS	CPI	243	# ?
007 26Ø	3Ø2 212 007		JNZ	KYBD	
007 263	Ø56 314		MVI	L, 314	
007 265	3Ø3 24Ø 007		JMP		
007 27Ø	3ØØ Ø13				Ø SELECT ADDRESS
007 272	217 Ø1Ø				1 SELECT ADDRESS
007 274	211 Ø1Ø				2 SELECT ADDRESS
007 276	2Ø3 Ø1Ø				3 SELECT ADDRESS

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
007 300	225 010				4 SELECT ADDRESS
007 302	233 010				5 SELECT ADDRESS
007 304	241 010				6 SELECT ADDRESS
007 306	247 010				7 SELECT ADDRESS
007 310	311 013				8 SELECT ADDRESS
007 312	322 013				9 SELECT ADDRESS
007 314	115 014				# SELECT ADDRESS
007 316	377				ERASE
007 317	243				#
007 320	240				
007 321	323				S
007 322	345				e
007 323	354				l
007 324	240				
007 325	304				D
007 326	345				e
007 327	343				c
007 330	353				k
007 331	004				SPACES
007 332	311				I
007 333	356				n
007 334	240				
007 335	325				U
007 336	363				s
007 337	345				e
007 340	240				
007 341	240				
007 342	260				Ø
007 343	Ø11				SPACES
007 344	260				Ø
007 345	240				
007 346	303				C
007 347	357				O
007 350	360				F
007 351	371				Y
007 352	240				
007 353	324				T
007 354	341				a
007 355	360				p
007 356	345				e
007 357	Ø25				SPACES
007 360	261				l
007 361	240				

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
007 362	305				E
007 363	362				r
007 364	341				a
007 365	363				s
007 366	345				e
007 367	031				SPACES
007 370	262				2
007 371	240				
007 372	306				F
007 373	341				a
007 374	363				s
007 375	364				t
007 376	240				
007 377	322				R
010 000	345				e
010 001	366				v
010 002	345				e
010 003	362				r
010 004	363				s
010 005	345				e
010 006	022				SPACES
010 007	263				3
010 010	240				
010 011	306				F
010 012	341				a
010 013	363				s
010 014	364				t
010 015	240				
010 016	306				F
010 017	357				o
010 020	362				r
010 021	367				w
010 022	341				a
010 023	362				r
010 024	344				d
010 025	022				SPACES
010 026	264				4
010 027	240				
010 030	323				S
010 031	364				t
010 032	341				a
010 033	356				n
010 034	344				d
010 035	342				b
010 036	371				y
010 037	027				SPACES

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
010 040	265				5
010 041	240				S
010 042	323				t
010 043	364				t
010 044	357				o
010 045	360				p
010 046	032				SPACES
010 047	266				6
010 050	240				R
010 051	322				e
010 052	345				a
010 053	341				d
010 054	344				SPACES
010 055	032				7
010 056	267				R
010 057	240				e
010 060	322				c
010 061	345				o
010 062	343				r
010 063	357				c
010 064	362				o
010 065	344				r
010 066	030				SPACES
010 067	270				8
010 070	240				R
010 071	322				e
010 072	345				c
010 073	343				o
010 074	357				r
010 075	362				c
010 076	344				o
010 077	240				r
010 100	324				T
010 101	345				e
010 102	363				s
010 103	364				t
010 104	240				D
010 105	304				a
010 106	341				t
010 107	364				a
010 110	341				SPACES
010 111	016				9
010 112	271				R
010 113	240				
010 114	322				

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
Ø1Ø 115	345				e
Ø1Ø 116	341				a
Ø1Ø 117	344				d
Ø1Ø 12Ø	24Ø				
Ø1Ø 121	324				T
Ø1Ø 122	345				e
Ø1Ø 123	363				s
Ø1Ø 124	364				t
Ø1Ø 125	24Ø				
Ø1Ø 126	3Ø4				D
Ø1Ø 127	341				a
Ø1Ø 13Ø	364				a
Ø1Ø 131	341				
Ø1Ø 132	127				SPACES
Ø1Ø 133	32Ø				P
Ø1Ø 134	31Ø				H
Ø1Ø 135	311				I
Ø1Ø 136	24Ø				
Ø1Ø 137	3Ø4				D
Ø1Ø 14Ø	3Ø5				E
Ø1Ø 141	3Ø3				C
Ø1Ø 142	313				K
Ø1Ø 143	24Ø				
Ø1Ø 144	3Ø3				C
Ø1Ø 145	317				O
Ø1Ø 146	315				M
Ø1Ø 147	315				M
Ø1Ø 15Ø	3Ø1				A
Ø1Ø 151	316				N
Ø1Ø 152	3Ø4				D
Ø1Ø 153	323				S
Ø1Ø 154	ØØØ				RETURN
Ø1Ø 155	366 Ø4Ø	LETTER	ORI	Ø4Ø	PRODUCE LOWER CASE
Ø1Ø 157	376 363		CPI	363	'S' ?
Ø1Ø 161	312 ØØØ ØØ3		JZ	ØØ3 ØØØ	JUMP IF 'S' TO STORAGE DUMP
Ø1Ø 164	376 362		CPI	362	'R' ?
Ø1Ø 166	312 ØØ3 ØØ5		JZ	ØØ5 ØØ3	JUMP IF EQUAL TO 8Ø8Ø OPS SYSTEM
Ø1Ø 171	376 36Ø		CPI	36Ø	'P' ?
Ø1Ø 173	312 Ø65 ØØ4		JZ	ØØ4 Ø65	JUMP IF EQUAL TO KEYBOARD PROGRAMMING
Ø1Ø 176	317		RST	Ø1Ø	
Ø1Ø 177	315 ØØØ ØØ7	CPY	CALL	COPY	COPY TAPE ROUTINE

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
Ø1Ø 2Ø2	317		RST	Ø1Ø	RESTART
Ø1Ø 2Ø3	Ø16 24Ø	FFWD	MVI	C, 24Ø	LOAD C w FAST FORWARD
Ø1Ø 2Ø5	315 233 Ø12		CALL	CMDOUT	OUTPUT COMMAND
Ø1Ø 21Ø	317		RST	Ø1Ø	RESTART
Ø1Ø 211	Ø16 2ØØ	FREV	MVI	C, 2ØØ	LOAD C w FAST REVERSE
Ø1Ø 213	315 233 Ø12		CALL	CMDOUT	OUTPUT COMMAND
Ø1Ø 216	317		RST	Ø1Ø	RESTART
Ø1Ø 217	Ø16 354	ERASE	MVI	C, 354	LOAD C w ERASE
Ø1Ø 221	315 233 Ø12		CALL	CMDOUT	OUTPUT COMMAND
Ø1Ø 224	317		RST	Ø1Ø	RESTART
Ø1Ø 225	Ø16 16Ø	STNDBY	MVI	C, 16Ø	LOAD C w STANDBY
Ø1Ø 227	315 233 Ø12		CALL	CMDOUT	OUTPUT COMMAND
Ø1Ø 232	317		RST	Ø1Ø	RESTART
Ø1Ø 233	Ø16 36Ø	STOP	MVI	C, 36Ø	LOAD C w STOP
Ø1Ø 235	315 233 Ø12		CALL	CMDOUT	OUTPUT COMMAND
Ø1Ø 24Ø	317		RST	Ø1Ø	RESTART
Ø1Ø 241	Ø16 34Ø	READ	MVI	C, 34Ø	LOAD C w READ
Ø1Ø 243	315 233 Ø12		CALL	CMDOUT	OUTPUT COMMAND
Ø1Ø 246	317		RST	Ø1Ø	RESTART
Ø1Ø 247	Ø16 35Ø	RECORD	MVI	C, 35Ø	LOAD C w RECORD
Ø1Ø 251	315 233 Ø12		CALL	CMDOUT	OUTPUT COMMAND
Ø1Ø 254	317		RST	Ø1Ø	RESTART
Ø1Ø 26Ø	ØØ6 ØØØ	RCDTD	MVI	B, Ø	INITIALIZE COUNT
Ø1Ø 262	Ø16 35Ø		MVI	C, 35Ø	LOAD C w RECORD
Ø1Ø 264	315 233 Ø12		CALL	CMDOUT	OUTPUT COMMAND
Ø1Ø 267	11Ø	RCD	MOV	C, B	LOAD C w COUNT
Ø1Ø 27Ø	315 25Ø Ø12		CALL	DOUT	OUTPUT DATA
Ø1Ø 273	333 ØØ2	STATUS	IN	2	INPUT STATUS
Ø1Ø 275	346 ØØ3		ANI	3	READY
Ø1Ø 277	312 273 Ø1Ø		JZ	STATUS	NO, INPUT STATUS
Ø1Ø 3Ø2	ØØ5		DEC	B	YES, DECREMENT COUNT
Ø1Ø 3Ø3	3Ø2 267 Ø1Ø		JNZ	RCD	256?
Ø1Ø 3Ø6	Ø26 ØØ2		MVI	D, 2	YES, OUTPUT ADDED CHARACTERS TO ALLOW TIME FOR DELAY
Ø1Ø 31Ø	11Ø	LOOP	MOV	C, B	LOAD C w COUNT
Ø1Ø 311	315 25Ø Ø12		CALL	DOUT	OUTPUT DATA
Ø1Ø 314	333 ØØ2	STAT	IN	2	INPUT STATUS
Ø1Ø 316	346 ØØ3		ANI	3	READY?
Ø1Ø 32Ø	312 314 Ø1Ø		JZ	STAT	NO, INPUT STATUS

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
Ø1Ø 323	Ø25		DEC	D	YES, DECREMENT LOOP COUNT
Ø1Ø 324	3Ø2 31Ø Ø1Ø		JNZ	LOOP	
Ø1Ø 327	3Ø3 26Ø Ø1Ø		JMP	RCDTD	RECORD NEXT BLOCK
Ø1Ø 334	ØØ6 ØØØ	RTD	MVI	B, Ø	INITIALIZE COUNT
Ø1Ø 336	Ø16 34Ø		MVI	C, 340	LOAD C W READ
Ø1Ø 34Ø	315 233 Ø12		CALL	CMDOUT	OUTPUT COMMAND
Ø1Ø 343	333 ØØ2	STATR	IN	2	INPUT STATUS
Ø1Ø 345	346 ØØ3		ANI	3	READY?
Ø1Ø 347	312 343 Ø1Ø		JZ	STATR	NO
Ø1Ø 352	315 217 Ø12		CALL	DIN	YES, INPUT DATA
Ø1Ø 355	171		MOV	A,C	MOVE DATA TO A
Ø1Ø 356	27Ø		CMP	B	COMPARE TO COUNT
Ø1Ø 357	3Ø2 262 Ø13		JNZ	ERROR	JUMP IF NOT EQUAL TO ERROR
Ø1Ø 362	ØØ5		DEC	B	DECREMENT COUNT
Ø1Ø 363	3Ø2 343 Ø1Ø		JNZ	STATR	256? NO, READ NEXT BYTE
Ø1Ø 366	Ø41 275 Ø13		LXI	H	OUTPUT '9' IF END OF BLOCK
Ø1Ø 371	315 Ø45 ØØ2		CALL	TVEDIT	CALL TV EDITOR
Ø1Ø 374	3Ø3 334 Ø1Ø		JMP	RTD	READ NEXT BLOCK

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
Ø13 262	Ø41 273 Ø13	ERROR	LXI	H	OUTPUT 'e' IF ERROR
Ø13 265	315 Ø45 ØØ2		CALL	TVEDIT	CALL TV EDITOR
Ø13 27Ø	3Ø3 334 Ø1Ø		JMP RTD		READ NEXT BLOCK
Ø13 273	345		DB	345	'e'
Ø13 274	ØØØ		DB	Ø	RETURN
Ø13 275	347		DB	347	'g'
Ø13 276	ØØØ		DB	Ø	RETURN
Ø13 3ØØ	Ø41 335 Ø13		LXI	H	LOAD COPY TAPE MESSAGE AREA
Ø13 3Ø3	315 Ø45 ØØ2		CALL	TVEDIT	CALL TV EDITOR
Ø13 3Ø6	3Ø3 177 Ø1Ø		JMP	CPY	JUMP TO COPY TAPE ROUTINE
Ø13 311	Ø41 361 Ø13		LXI	H	LOAD RECORDING TEST DATA MESSAGE AREA
Ø13 314	315 Ø45 ØØ2		CALL	TVEDIT	CALL TV EDITOR
Ø13 317	3Ø3 26Ø Ø1Ø		JMP	RCDTD	JUMP TO RECORD TEST DATA ROUTINE
Ø13 322	Ø41 ØØ7 Ø14		LXI	H	LOAD READ TEST DATA MESSAGE AREA
Ø13 325	315 Ø45 ØØ2		CALL	TVEDIT	CALL TV EDITOR
Ø13 33Ø	3Ø3 334 Ø1Ø		JMP	RTD	JUMP TO READ TEST DATA ROUTINE
Ø13 335	377				ERASE
Ø13 336	ØØ7				SPACES
Ø13 337	324				T
Ø13 34Ø	341				a
Ø13 341	36Ø				p
Ø13 342	345				e
Ø13 343	24Ø				
Ø13 344	3Ø2				B
Ø13 345	345				e
Ø13 346	351				i
Ø13 347	356				n
Ø13 35Ø	347				g
Ø13 351	24Ø				
Ø13 352	3Ø3				C
Ø13 353	357				o
Ø13 354	36Ø				p
Ø13 355	351				i
Ø13 356	345				e
Ø13 357	344				d
Ø13 36Ø	ØØØ				RETURN
Ø13 361	377				ERASE
Ø13 362	ØØ6				SPACES

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
013 363	322				R
013 364	345				e
013 365	343				c
013 366	357				o
013 367	362				r
013 370	344				d
013 371	351				i
013 372	356				n
013 373	347				g
013 374	240				
013 375	324				T
013 376	345				e
013 377	363				s
014 000	364				t
014 001	240				
014 002	304				D
014 003	341				a
014 004	364				t
014 005	341				a
014 006	000				RETURN
014 007	377				ERASE
014 010	006				SPACES
014 011	324				T
014 012	345				e
014 013	363				s
014 014	364				t
014 015	240				
014 016	304				D
014 017	341				a
014 020	364				t
014 021	341				a
014 022	240				
014 023	302				B
014 024	345				e
014 025	351				i
014 026	356				n
014 027	347				g
014 030	240				
014 031	322				R
014 032	345				e
014 033	341				a
014 034	344				d
014 035	006				SPACES

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
014 036	000				RETURN
014 037	377				ERASE
014 040	323				S
014 041	345				e
014 042	354				l
014 043	345				e
014 044	343				c
014 045	364				t
014 046	240				
014 047	304				D
014 050	345				e
014 051	343				c
014 052	353				k
014 053	240				
014 054	316				N
014 055	365				u
014 056	355				m
014 057	342				b
014 060	345				e
014 061	362				r
014 062	240				(
014 063	250				0
014 064	260				-
014 065	255				3
014 066	263				)
014 067	251				SPACES
014 070	050				D
014 071	304				e
014 072	345				c
014 073	343				k
014 074	353				
014 075	240				#
014 076	243				
014 077	240				0
014 100	260				SPACES
014 101	070				D
014 102	304				o
014 103	357				n
014 104	356				e
014 105	345				?
014 106	277				
014 107	240				(
014 110	250				Y
014 111	331				?
014 112	277				

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
Ø14 113	251				)
Ø14 114	ØØØ				RETURN
Ø14 115	Ø41 Ø37 Ø14	TV	LXI	H,Ø14 Ø37	LOAD H & L W MESSAGE AREA
Ø14 12Ø	Ø72 26Ø Ø12		LDA	DECK	LOAD A w DECK #
Ø14 123	366 26Ø		ORI	26Ø	CONVERT TO ASCII
Ø14 125	Ø62 1ØØ Ø14		STA	Ø14 1ØØ	STORE IN MESSAGE
Ø14 13Ø	315 Ø45 ØØ2		CALL	TVEDIT	CALL TV EDITOR
Ø14 133	333 ØØØ	IN	IN	Ø	INPUT FROM KEYBOARD
Ø14 135	376 264		CPI	264	> '3' ?
Ø14 137	322 162 Ø14		JPC	DONE	YES
Ø14 142	376 26Ø		CPI	26Ø	< 'Ø' ?
Ø14 144	332 133 Ø14		JPC	IN	YES
Ø14 147	Ø62 342 ØØ7		STA	ØØ7 342	PLACE NUMBER IN MESSAGE
Ø14 152	346 ØØ3		ANI	3	
Ø14 154	Ø62 26Ø Ø12		STA	DECK	STORE DECK #
Ø14 157	3Ø3 115 Ø14		JMP	TV	JUMP TO MESSAGE
Ø14 162	366 Ø4Ø	DONE	ORI	Ø4Ø	CONVERT TO LOWER CASE
Ø14 164	376 371		CPI	371	'v' ?
Ø14 16Ø	3Ø2 115 Ø14		JNZ	TV	NO
Ø14 171	317		RST	Ø1Ø	YES

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<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
*				RECORD (UNTIL COUNT EXHAUSTED)	
*				DECK IS STOPPED AFTER RETURN	
*				INPUT:	
*				DECK - DECK NUMBER LOCATED IN MEMORY	
*				POINTW - LOCATED IN MEMORY	
*				(FIRST DATA BYTE)	
*				IDW - LOCATED IN MEMORY (FIRST BLOCK)	
*				COUNT - REGISTER H,L	
*				OUTPUT:	
*				POINTW - LOCATED IN MEMORY	
*				(LAST DATA BYTE + 1)	
*				ERROR - REGISTER A	
*				Ø - NO ERRORS	
*				1 - CRC ERROR IN BLOCK	
*				IDW - 1	
*				2 - BLOCK IDW-1 NOT FOUND	
*				3 - TAPE END OR JAM	
*				IDW - LOCATED IN MEMORY	
*				(LAST BLOCK + 1)	
*				ALTERED	
*				REGISTERS - A,B,C,D,E,H,L, IDR, PTRINR	
0909	1601	RECORD	MVI	D,1	ERASE = 1
0902	1E05		MVI	E,5	STOPS = 5
0904	E5		PUSH	H	COUNT
0905	D5	RCD20	PUSH	D	ERASE, STOPS
0906	2AB50A		LHLD	IDW	
0909	2B		DCX	H	IDR = IDW - 1
090A	22B10A		SHLD	IDR	
090D	23		INX	H	
090E	7D		MOV	A,L	IDW = Ø ?
090F	B4		ORA	H	
0910	CA2909		JZ	RCD10	YES
0913	160B		MVI	D,11	RETRIES = 10
0915	1E01		MVI	E,1	CHECK MODE
0917	CD7B0B		CALL	ALTRD	
091A	3C		INR	A	ERROR?
091B	3D		DCR	A	
091C	CA3609		JZ	RCD13	NO
091F	D1	RCD12	POP	D	ERASE, STOPS
0920	E1	RCD21	POP	H	COUNT
0921	0E90	RCD27	MVI	C,90H	STOP
0923	47		MOV	B,A	SAVE ERROR
0924	CD9B0A		CALL	CMDOUT	
0927	78		MOV	A,B	RESTORE ERROR
0928	C9		RET		
0929	CD4F0A	RCD10	CALL	REWIND	
092C	0EEC		MVI	C,ECH	ERASE

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
092E	CD9B0A		CALL	CMDOUT	
0931	3E28		MVI	A,40	4 SECONDS
0933	CD810A		CALL	DELAY	
0936	D1	RCD13	POP	D	ERASE, STOPS
0937	D5		PUSH	D	
0938	15	RCD15	DCR	D	ERASE (ERASE - 1) BLOCKS
0939	CA4909		JZ	RCD14	
093C	0EEC		MVI	C,ECH	ERASE
093E	CD9B0A		CALL	CMDOUT	
0941	D5		PUSH	D	
0942	CDDA09		CALL	RECRD1	
0945	D1		POP	D	
0946	C33809		JMP	RCD15	
0949	E1	RCD14	POP	H	ERASE, STOPS
094A	D1		POP	D	COUNT
094B	D5		PUSH	D	
094C	E5		PUSH	H	
094D	2AB70A		LHLD	POINTW	POINTER
0950	15	RCD19	DCR	D	COUNT HIGH = Ø?
0951	14		INR	D	
0952	C2D409		JNZ	RCD16	NO
0955	1D		DCR	E	
0956	1C		INR	E	
0957	CA8109		JZ	RCD17	YES
095A	43		MOV	B,E	COUNT = COUNTL
095B	1EØØ		MVI	E,Ø	COUNTL = Ø
095D	D5	RCD18	PUSH	D	SAVE COUNT
095E	EB		XCHG		
095F	2AB10A		LHLD	IDR	
0962	23		INX	H	
0963	22B10A		SHLD	IDR	
0966	EB		XCHG		
0967	0EE8		MVI	C,E8H	RECORD
0969	CD9B0A		CALL	CMDOUT	
096C	CDDA09		CALL	RECRD1	
096F	DBØ2		IN	TAPEIN	ERROR?
0971	E6ØD		ANI	ØDH	
0973	D1		POP	D	GET COUNT
0974	CA5ØØ9		JZ	RCD19	NO
0977	D1		POP	D	DCR STOPS
0978	1D		DCR	E	Ø?
0979	C2Ø5Ø9		JNZ	RCD20	NO
097C	3EØ3		MVI	A,3	ERROR = 3
097E	C32ØØ9		JMP	RCD21	
0981	3EØ5	RCD17	MVI	A,5	APPROXIMATELY 10 BLOCKS
0983	CD680A		CALL	FR	
0986	E1		POP	H	ERASE, STOPS
0987	D1		POP	D	COUNT
0988	D5	RCD26	PUSH	D	
0989	E5		PUSH	H	
098A	97		SUB	A	COUNT = Ø?

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
098B	82		ADD	D	
098C	C29309		JNZ	RCD22	NO
098F	83		ADD	E	
0990	CA1F09		JZ	RCD12	YES
0993	2AB50A	RCD22	LHLD	IDW	
0996	22B10A		SHLD	IDR	
0999	1606		MVI	D,6	RETRIES = 6
099B	1E01		MVI	E,1	CHECK MODE
099D	CDBB0A		CALL	ALTRD2	
09A0	3C		INR	A	ERROR?
09A1	3D		DCR	A	
09A2	D1		POP	D	
09A3	CAAA09		JZ	RCD24	NO
09A6	14		INR	D	INCREMENT ERASE
09A7	C30509		JMP	RCD20	
09AA	1601	RCD24	MVI	D,1	ERASE = 1
09AC	2AB50A		LHLD	IDW	INCREMENT IDW
09AF	23		INX	H	
09B0	22B50A		SHLD	IDW	
09B3	EB		XCHG		
09B4	D1		POP	D	
09B5	14		INR	D	COUNTH = \$?
09B6	15		DCR	D	
09B7	CAC709		JZ	RCD25	YES
09BA	15		DCR	D	DECREMENT COUNTH
09BB	E5		PUSH	H	
09BC	2AB70A		LHLD	POINTW	
09BF	24		INR	H	
09C0	22B70A		SHLD	POINTW	
09C3	E1		POP	H	
09C4	C38809		JMP	RCD26	
09C7	2AB70A	RCD25	LHLD	POINTW	ADD COUNTL TO POINTER
09CA	1600		MVI	D,\$	
09CC	19		DAD	D	
09CD	22B70A		SHLD	POINTW	
09D0	97		SUB	A	ERROR = \$
09D1	C32109		JMP	RCD27	
09D4	15	RCD16	DCR	D	DECREMENT COUNTH
09D5	0600		MVI	B,\$	COUNT = \$
09D7	C35D09		JMP	RCD18	
	*		RECRD1	(RECORD ONE BLOCK)	
	*			RECORD OR ERASE COMMAND MUST BE ISSUED	
	*			BEFORE CALLING.	
	*			UNDERUN AND STOP SHOULD BE CHECKED	
	*			AFTER RETURN.	
	*			INPUTS:	
	*			DECK - DECK NUMBER LOCATED	
	*			IN MEMORY	
	*			ID - REGISTER D,E	
	*			COUNT - REGISTER B	
	*			(01=1 BYTE, \$0=256 BYTES)	

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
		*			POINTER - REGISTER H,L (FIRST DATA BYTE)
		*			OUTPUT:
		*			POINTER - REGISTER H,L (LAST DATA BYTE + 1)
		*			ALTERED
		*			REGISTERS - A,B,C,D,E,H,L
Ø9DA	E5	RECDL	PUSH	H	PUSH POINTER
Ø9DB	21 ØØØØ		LXI	H,Ø	RESET CRC
Ø9DE	4A		MOV	C,D	ID HIGH
Ø9DF	CD 49ØA		CALL	ALTPUT	
Ø9E2	4B		MOV	C,E	ID LOW
Ø9E3	CD42ØA		CALL	PUT	
Ø9E6	48		MOV	C,B	COUNT
Ø9E7	CD42ØA		CALL	PUT	
Ø9EA	54		MOV	D,H	SAVE CRC2
Ø9EB	4D		MOV	C,L	CRC1
Ø9EC	CD42ØA		CALL	PUT	
Ø9EF	4A		MOV	C,D	CRC2
Ø9FØ	CD42ØA		CALL	PUT	
Ø9F3	58		MOV	E,B	SAVE COUNT
Ø9F4	E3	RECDL	XTHL		SWITCH CRC, POINTER
Ø9F5	4E		MOV	C,M	LOAD DATA
Ø9F6	23		INX	H	INCREMENT POINTER
Ø9F7	E3		XTHL		SWITCH CRC, POINTER
Ø9F8	CD42ØA		CALL	PUT	
Ø9FB	05		DCR	B	DECREMENT COUNT
Ø9FC	C2F4Ø9		JNZ	RECDL	NOT ZERO
Ø9FF	54		MOV	D,H	SAVE CRC2
ØAØØ	4D		MOV	C,L	CRC1
ØAØ1	CD42ØA		CALL	PUT	
ØAØ4	4A		MOV	C,D	CRC2
ØAØ5	CD42ØA		CALL	PUT	
ØAØ8	1D		DCR	E	DECREMENT SAVED COUNT
ØAØ9	CD42ØA	RECD3	CALL	PUT	
ØAØC	1C		INR	E	INCREMENT SAVED COUNT
ØAØD	C2Ø9ØA		JNZ	RECD3	NOT ZERO
ØAØØ	CD42ØA		CALL	PUT	
ØA13	E1		POP	H	POP POINTER
ØA14	C9		RET		
		*	GET		
		*	CRC IN H,L		
		*	DATA RETURNED INC		
		*	A,C,H,L, ALTERED		
ØA15	DBØ2	GET	IN	TAPEIN	STATUS
ØA17	E6ØF		ANI	ØFH	
ØA19	CA15ØA		JZ	GET	
ØA1C	CD8FØA		CALL	DIN	
ØA1F	D5	CRC	PUSH	D	
ØA2Ø	79		MOV	A,C	
ØA21	AD		XRA	L	

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
ØA22	6F		MOV	L,A	
ØA23	LEØ7		MVI	E,7	Ø07 TIMES
ØA25	17	CRCA	RAL		
ØA26	AD		XRA	L	
ØA27	1D		DCR	E	
ØA28	C225ØA		JNZ	CRCA	DONE?
ØA2B	6F		MOV	L,A	YES
ØA2C	ØF		RRC		
ØA2D	ØF		RRC		
ØA2E	5F		MOV	E,A	SAVE 1
ØA2F	E6CØ		ANI	CØH	
ØA31	AC		XRA	H	
ØA32	57		MOV	D,A	SAVE 2
ØA33	7B		MOV	A,E	RESTORE 1
ØA34	E63F		ANI	3FH	
ØA36	AD		XRA	L	
ØA37	67		MOV	H,A	CRC HIGH DONE
ØA38	17		RAL		TEST BIT 7
ØA39	7A		MOV	A,D	RESTORE 2
ØA3A	D23FØA		JNC	CRCFIN	BIT 7 WAS 1?
ØA3D	EEØ1		XRI	1	YES .
ØA3F	6F	CRCFIN	MOV	L,A	CRC LOW DONE
ØA40	D1		POP	D	
ØA41	C9		RET		
	*		PUT		
	*		DATA IN REGISTER C		
	*		CRC IN H,L		
	*		A,H,L ALTERED		
ØA42	DBØ2	PUT	IN	TAPEIN	STATUS
ØA44	E6ØF		ANI	ØFH	
ØA46	CA42ØA		JZ	PUT	
ØA49	CDA8ØA	ALTPUT	CALL	DOUT	
ØA4C	C31FØA		JMP	CRC	
	*		REWIND		
	*		REGISTER A, C ALTERED		
	*		THIS ROUTINE WILL GUARANTEE		
	*		DECK SELECTION		
ØA4F	OE9Ø	REWIND	MVI	C,9ØH	STOP
ØA51	CD9BØA		CALL	CMDOUT	
ØA54	DBØ2	REWB	IN	TAPEIN	
ØA56	E6Ø8		ANI	08H	
ØA58	CA54ØA		JZ	REWB	
ØA5B	OE8Ø		MVI	C,8ØH	FR
ØA5D	CD9BØA		CALL	CMDOUT	
ØA60	DBØ2	REWA	IN	TAPEIN	
ØA62	E6Ø8		ANI	8	
ØA64	CA6ØØA		JZ	REWA	
ØA67	C9		RET		
	*		FAST REVERSE, FAST FORWARD		
	*		REGISTER A CONTAINS MULTIPLE		
	*		OF 100 MILLI-SECONDS DELAY		
	*		REGISTER A ALTERED		

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
0A68	C5	FR	PUSH	B	
0A69	F5		PUSH	PSW	
0A6A	0E80		MVI	C,80H	
0A6C	CD9B0A	FRA	CALL	CMDOUT	
0A6F	F1		POP	PSW	
0A70	CD810A		CALL	DELAY	
0A73	0E90		MVI	C,90H	
0A75	CD9B0A		CALL	CMDOUT	
0A78	C1		POP	B	
0A79	C9		RET		
0A7A	C5	FF	PUSH	B	
0A7B	F5		PUSH	PSW	
0A7C	0EA0		MVI	C,A0H	
0A7E	C36C0A		JMP	FRA	
		*			DELAY MULTIPLE OF 100 MS IN REGISTER A.
		*			REGISTERS A,B,C ALTERED
0A81	010020	DELAY	LXI	B,2000H	
0A84	0B	D1	DCX	B	
0A85	04		INR	B	
0A86	05		DCR	B	
0A87	C2840A		JNZ	D1	
0A8A	3D		DCR	A	
0A8B	C2810A		JNZ	DELAY	
0A8E	C9		RET		
		*			INPUT DATA BYTE (DATA RETURNED IN C)
		*			REGISTER A IS ALTERED
0A8F	3EEF	DIN	MVI	A,EFH	
0A91	D301		OUT	STROBE	
0A93	DB02		IN	TAPEIN	
0A95	4F		MOV	C,A	
0A96	3EDF	DINA	MVI	A,DFH	
0A98	D301		OUT	STROBE	
0A9A	C9		RET		
		*			OUTPUT COMMAND (DATA IN REGISTER C)
		*			DECK IS OR'D WITH DATA
		*			REGISTER A IS ALTERED
0A9B	3AB00A	CMDOUT	LDA	DECK	
0A9E	B1		ORA	C	
0A9F	D302		OUT	TAPOUT	
0AA1	3E9F		MVI	A,9FH	
0AA3	D301	CMDA	OUT	STROBE	
0AA5	C3960A		JMP	DINA	
		*			OUTPUT DATA (DATA IN REGISTER C)
		*			REGISTER A IS ALTERED
0AA8	79	DOUT	MOV	A,C	
0AA9	D302		OUT	TAPOUT	
0AAB	3E5F		MVI	A,5FH	
0AAD	C3A30A		JMP	CMDA	
		*			VARIABLE DATA AREA
0AB0	00	DECK	DS	1	DECK NUMBER TO BE USED
0AB1	00 00	IDR	DS	2	READ ID

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
ØAB3	00 00	POINTR	DS	2	READ POINTER
ØAB5	00 00	IDW	DS	2	WRITE ID
ØAB7	00 00	POINTW	DS	2	WRITE POINTER
	*				READ ONE BLOCK
	*				DECK REMAINS RUNNING AFTER RETURN
	*				INPUT:
	*				DECK - DECK NUMBER LOCATED IN MEMORY
	*				POINTR - LOCATED IN MEMORY
	*				(FIRST BYTE)
	*				IDR - LOCATED IN MEMORY
	*				RETRYs - REGISTER D
	*				(ALTRD ONLY)
	*				MODE - REGISTER E
	*				Ø=READ
	*				1=CHECK
	*				OUTPUT:
	*				DECK, POINTER, IDR UNCHANGED
	*				REGISTER - A,B,C,D,H,L ALTERED
	*				COUNT - REGISTER B
	*				Ø1=1 BYTE
	*				ØØ=256 BYTES
	*				ERROR - REGISTER A
	*				Ø - NO ERRORS
	*				1 - CRC ERROR
	*				2 - BLOCK NOT FOUND
	*				3 - END OF TAPE OR JAM
	*				ENTRY POINTS:
	*				READ - NORMAL ENTRY
	*				ALTRD - DECK WILL BACKSPACE
	*				FIRST, USER MUST SUPPLY RETRIES.
	*				ALTRD2 - NORMAL, EXCEPT USER MUST
	*				SUPPLY RETRIES.
ØABC9	16ØA	READ	MVI	D, RETRYs	
ØABCB	D5	RD54	PUSH	D	RETRIES, MODE
		ALTRD2	EQU	RD54	
ØABC	21ØØØØ	RD5	LXI	H, Ø	RESET CRC
ØABF	DBØ2		IN	TAPEIN	STATUS
ØAC1	57		MOV	D, A	
ØAC2	ØEEØ	RD51	MVI	C, EØH	READ
ØAC4	CD9BØA		CALL	CMDOUT	
ØAC7	7A		MOV	A, D	STOP?
ØAC8	E6Ø4		ANI	Ø4H	
ØACA	CAD7ØA		JZ	RD5Ø	NO
ØACD	3EØ4		MVI	A, 4	.4 SECONDS
ØACF	CD81ØA		CALL	DELAY	
ØAD2	16ØØ		MVI	D, Ø	STATUS = Ø
ØAD4	C3C2ØA		JMP	RD51	
ØAD7	0630	RD50	MVI	B, 3OH	8 SECOND TIMEOUT
ØAD9	5Ø	RD57	MOV	D, B	
ØADA	DBØ2	RD53	IN	TAPEIN	STATUS

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
ØADC	E6ØF		ANI	ØFH	READY?
ØADE	C29ØØB		JNZ	RD1Ø	YES
ØAE1	1B		DCX	D	
ØAE2	14		INR	D	
ØAE3	15		DCR	D	
ØAE4	C2DAØA		JNZ	RD53	
ØAE7	Ø5		DCR	B	
ØAE8	C2D9ØA		JNZ	RD57	
ØAEB	CD4FØA		CALL	REWIND	
ØAEE	3EØ2	RD2	MVI	A,2	ERROR = 2
ØAFØ	D1		POP	D	RETRIES, MODE
ØAF1	15	RD8	DCR	D	
ØAF2	C2BBØA		JNZ	RD54	
ØAF5	C9		RET		
ØAF6	CD15ØA	RD52	CALL	GET	IDH
ØAF9	-41		MOV	B,C	
ØAF9A	CD15ØA		CALL	GET	IDL
ØAFD	59		MOV	E,C	
ØAFE	CD15ØA		CALL	GET	COUNT
ØBØ1	51		MOV	D,C	
ØBØ2	CD15ØA		CALL	GET	CRC1
ØBØ5	CD15ØA		CALL	GET	CRC2
ØBØ8	97		SUB	A	CRC = Ø?
ØBØ9	84		ADD	H	
ØBØA	C2BCØA		JNZ	RD5	NO
ØBØD	85		ADD	L	
ØBØE	C2BCØA		JNZ	RD5	NO
	*		COMPUTE		BE TAPEID
	*				-HL IDR
	*				XY
ØB11	7B		MOV	A,E	
ØB12	2AB1ØA		LHLD	IDR	
ØB15	95		SUB	L	
ØB16	5F		MOV	E,A	REGISTER E CONTAINS Y
ØB17	6F		MOV	L,A	
ØB18	78		MOV	A,B	
ØB19	9C		SBB	H	
ØB1A	67		MOV	H,A	REGISTER A CONTAINS X H = XY/8
ØB1B	29		DAD	H	
ØB1C	29		DAD	H	
ØB1D	29		DAD	H	
ØB1E	29		DAD	H	
ØB1F	29		DAD	H	
ØB2Ø	7C		MOV	A,H	
ØB21	CA38ØB		JZ	ID1	
ØB24	F23DØB		JP	ID2	
ØB27	2F		CMA		COMPUTE FF DELAY
ØB28	C602		ADI	2	ADD 1+1 FOR 2'S COMP
ØB2A	FA32ØB		JM	ID3	
ØB2D	FEØ4		CPI	4	GREATER THAN THRESHOLD?

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
ØB2F	FABCØA		JM	RD5	NO
ØB32	CD7AØA	ID3	CALL	FF	
ØB35	C3BCØA		JMP	RD5	
ØB38	1C	ID1	INR	E	Y = Ø?
ØB39	1D		DCR	E	
ØB3A	CA45ØB		JZ	RD6	YES
ØB3D	C6Ø6	ID2	ADI	6	
ØB3F	CD68ØA		CALL	FR	
ØB42	C3EEØA		JMP	RD2	
ØB45	42	RD6	MOV	B,D	COUNT
ØB46	D1		POP	D	RETRIES, MODE
ØB47	C5		PUSH	B	COUNT
ØB48	2AB3ØA		LHLD	POINTR	
ØB4B	E5		PUSH	H	
ØB4C	21ØØØØ		LXI	H,Ø	RESET CRC
ØB4F	CD15ØA	RD56	CALL	GET	
ØB52	1C		INR	E	
ØB53	1D		DCR	E	
ØB54	C25BØB		JNZ	RD55	
ØB57	E3		XTHL		SWITCH CRC, POINTER
ØB58	71		MOV	M,C	STORE DATA
ØB59	23		INX	H	BUMP POINTER
ØB5A	E3		XTHL		SWITCH CRC, POINTER
ØB5B	Ø5	RD55	DCR	B	DECREMENT COUNT
ØB5C	C24FØB		JNZ	RD56	
ØB5F	C1		POP	B	ADJUST STACK POINTER
ØB6Ø	C1		POP	B	COUNT
ØB61	CD15ØA		CALL	GET	
ØB64	CD15ØA		CALL	GET	
ØB67	DBØ2		IN	TAPEIN	STATUS
ØB69	1F		RAR		OVERRUN?
ØB6A	DA7BØB		JC	ALTRD	YES
ØB6D	1F		RAR		
ØB6E	1F		RAR		STOP?
ØB6F	DA96ØB		JC	RD11	YES
ØB72	97		SUB	A	
ØB73	84		ADD	H	
ØB74	C27BØB		JNZ	ALTRD	NO
ØB77	85		ADD	L	
ØB78	CA85ØB		JZ	RD19	
ØB7B	3EØ5	ALTRD	MVI	A,5	GREATER THAN 1 BLOCK
ØB7D	CD68ØA		CALL	FR	
ØB8Ø	3EØ1		MVI	A,1	ERRGR = 1
ØB82	C3F1ØA		JMP	RD8	
ØB85	5Ø	RD19	MOV	D,B	SAVE COUNT
ØB86	15		DCR	D	DECREMENT SAVED COUNT
ØB87	CD15ØA	RD9	CALL	GET	
ØB8A	14		INR	D	INCREMENT SAVED COUNT
ØB8B	C287ØB		JNZ	RD9	
ØB8E	97		SUB	A	ERROR = Ø

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
ØB8F	C9		RET		
ØB9Ø	E6Ø4	RD10	ANI	Ø4H	STOP?
ØB92	CAF6ØA		JZ	RD52	NO
ØB95	D1		POP	D	RETRIES, MODE
ØB96	CD4FØA	RD11	CALL	REWIND	
ØB99	3EØ3		MVI	A,3	ERROR = 3
ØB9B	C3F1ØA		JMP	RD8	
			END		

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<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
		x		RECORD (UNTIL COUNT EXHAUSTED)	
		x		DECK IS STOPPED AFTER RETURN	
		x		INPUT:	
		x		DECK - DECK NUMBER LOCATED IN MEMORY	
		x		POINTW - LOCATED IN MEMORY	
		x		(FIRST DATA BYTE)	
		x		IDW - LOCATED IN MEMORY (FIRST BLOCK)	
		x		COUNT - REGISTER H,L	
		x		OUTPUT:	
		x		POINTW - LOCATED IN MEMORY	
		x		(LAST DATA BYTE + 1)	
		x		ERROR - REGISTER A	
		x		Ø - NO ERRORS	
		x		1 - CRC ERROR IN BLOCK	
		x		IDW - 1	
		x		2 - BLOCK IDW-1 NOT FOUND	
		x		3 - TAPE END OR JAM	
		x		IDW - LOCATED IN MEMORY	
		x		(LAST BLOCK + 1)	
		x		ALTERED	
		x		REGISTERS - A,B,C,D,E,H,L, IDR, POINTR	
011 000	026 001	RECORD	MVI	D,1	ERASE = 1
011 002	036 005		MVI	E,5	STOPS = 5
011 004	345		PUSH	H	COUNT
011 005	325	RCD2Ø	PUSH	D	ERASE, STOPS
011 006	052 265 Ø12		LHLD	IDW	
011 011	Ø53		DCX	H	IDR = IDW - 1
011 012	Ø42 261 Ø12		SHLD	IDR	
011 015	Ø43		INX	H	
011 016	175		MOV	A,L	IDW = Ø ?
011 017	264		ORA	H	
011 02Ø	312 Ø51 Ø11		JZ	RCD1Ø	YES
011 023	Ø26 Ø13		MVI	D,11	RETRIES = 1Ø
011 025	Ø36 ØØ1		MVI	E,1	CHECK MODE
011 027	315 173 Ø13		CALL	ALTRD	
011 032	Ø74		INR	A	ERROR?
011 033	Ø75		DCR	A	
011 034	312 Ø66 Ø11		JZ	RCD13	NO
011 037	321	RCD12	POP	D	ERASE, STOPS
011 04Ø	341	RCD21	POP	H	COUNT
011 041	Ø16 22Ø	RCD27	MVI	C,9ØH	STOP
011 043	1Ø7		MOV	B,A	SAVE ERROR
011 044	315 233 Ø12		CALL	CMDOUT	
011 047	17Ø		MOV	A,B	RESTORE ERROR
011 05Ø	311		RET		
011 051	315 117 Ø12	RCD1Ø	CALL	REWIND	
011 054	Ø16 354		MVI	C,ECH	ERASE

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
011 056	315 233 012		CALL	CMDOUT	
011 061	076 050		MVI	A, 40	4 SECONDS
011 063	315 201 012		CALL	DELAY	
011 066	321	RCD13	POP	D	ERASE, STOPS
011 067	325		PUSH	D	
011 070	025	RCD15	DCR	D	ERASE (ERASE-1) BLOCKS
011 071	312 111 011		JZ	RCD14	
011 074	016 354		MVI	C, ECH	ERASE
011 076	315 233 012		CALL	CMDOUT	
011 101	325		PUSH	D	
011 102	315 332 011		CALL	RECRD1	
011 105	321		POP	D	
011 106	303 070 011		JMP	RCD15	
011 111	341	RCD14	POP	H	ERASE, STOPS
011 112	321		POP	D	COUNT
011 113	325		PUSH	D	
011 114	345		PUSH	H	
011 115	052 267 012		LHLD	POINTW	POINTER
011 120	025	RCD19	DCR	D	COUNT HIGH = 0?
011 121	024		INR	D	
011 122	302 324 011		JNZ	RCD16	NO
011 125	035		DCR	E	
011 126	034		INR	E	
011 127	312 201 011		JZ	RCD17	YES
011 132	103		MOV	B, E	COUNT = COUNTL
011 133	036 000		MVI	E, 0	COUNTL = 0
011 135	325	RCD18	PUSH	D	SAVE COUNT
011 136	353		XCHG		
011 137	052 261 012		LHLD	IDR	
011 142	043		INX	H	
011 143	042 261 012		SHLD	IDR	
011 146	353		XCHG		
011 147	016 350		MVI	C, E8H	RECORD
011 151	315 233 012		CALL	CMDOUT	
011 154	315 332 011		CALL	RECRD1	
011 157	333 002		IN	TAPEIN	ERROR?
011 161	346 015		ANI	0DH	
011 163	321		POP	D	GET COUNT
011 164	312 120 011		JZ	RCD19	NO
011 167	321		POP	D	DCR STOPS
011 170	035		DCR	E	0?
011 171	302 005 011		JNZ	RCD20	NO
011 174	076 003		MVI	A, 3	ERROR = 3
011 176	303 040 011		JMP	RCD21	
011 201	076 005	RCD17	MVI	A, 5	APPROXIMATELY 10 BLOCKS
011 203	315 150 012		CALL	FR	
011 206	341		POP	H	ERASE, STOPS
011 207	321		POP	D	COUNT
011 210	325	RCD26	PUSH	D	
011 211	345		PUSH	H	
011 212	227		SUB	A	COUNT = 0?

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
Ø11 213	2Ø2		ADD	D	
Ø11 214	3Ø2	223 Ø11	JNZ	RCD22	NO
Ø11 217	2Ø3		ADD	E	
Ø11 22Ø	312 Ø37 Ø11		JZ	RCD12	YES
Ø11 223	Ø52 265 Ø12	RCD22	LHLD	IDW	
Ø11 226	Ø42 261 Ø12		SHLD	IDR	
Ø11 231	Ø26 ØØ6		MVI	D, 6	RETRIES = 6
Ø11 233	Ø36 ØØ1		MVI	E, 1	CHECK MODE
Ø11 235	315 273 Ø12		CALL	ALTRD2	
Ø11 24Ø	Ø74		INR	A	ERROR?
Ø11 241	Ø75		DCR	A	
Ø11 242	321		POP	D	
Ø11 243	312 252 Ø11		JZ	RCD24	NO
Ø11 246	Ø24		INR	D	INCREMENT ERASE
Ø11 247	3Ø3 ØØ5 Ø11		JMP	RCD2Ø	
Ø11 252	Ø26 ØØ1	RCD24	MVI	D, 1	ERASE = 1
Ø11 254	Ø52 265 Ø12		LHLD	IDW	INCREMENT IDW
Ø11 257	Ø43		INX	H	
Ø11 26Ø	Ø42 265 Ø12		SHLD	IDW	
Ø11 263	353		XCHG		
Ø11 264	321		POP	D	
Ø11 265	Ø24		INR	D	COUNTH = Ø?
Ø11 266	Ø25		DCR	D	
Ø11 267	312 3Ø7 Ø11		JZ	RCD25	YES
Ø11 272	Ø25		DCR	D	DECREMENT COUNTH
Ø11 273	345		PUSH	H	
Ø11 274	Ø52 267 Ø12		LHLD	POINTW	
Ø11 277	Ø44		INR	H	
Ø11 3ØØ	Ø42 267 Ø12		SHLD	PQINTW	
Ø11 3Ø3	341		POP	H	
Ø11 3Ø4	3Ø3 21Ø Ø11		JMP	RCD26	
Ø11 3Ø7	Ø52 267 Ø12	RCD25	LHLD	POINTW	ADD COUNTL TO POINTER
Ø11 312	Ø26 ØØØ		MVI	D, Ø	
Ø11 314	Ø31		DAD	D	
Ø11 315	Ø42 267 Ø12		SHLD	POINTW	
Ø11 32Ø	227		SUB	A	ERROR = Ø
Ø11 321	3Ø3 Ø41 Ø11		JMP	RCD27	
Ø11 324	Ø25		DCR	D	DECREMENT COUNTH
Ø11 325	ØØ6 ØØØ		MVI	B, Ø	COUNT = Ø
Ø11 327	3Ø3 135 Ø11		JMP	RCD18	
	x		RECRD1	(RECORD ONE BLOCK)	
	x			RECORD OR ERASE COMMAND MUST BE ISSUED	
	x			BEFORE CALLING.	
	x			UNDERRUN AND STOP SHOULD BE CHECKED	
	x			AFTER RETURN.	
	x			INPUTS:	
	x			DECK - DECK NUMBER LOCATED	
	x			IN MEMORY	
	x			ID - REGISTER D, E	
	x			COUNT - REGISTER B	
	x			(Ø1=1 BYTE, ØØ=256 BYTES)	

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
			x	POINTER - REGISTER H,L	
			x	(FIRST DATA BYTE)	
			x	OUTPUT:	
			x	POINTER - REGISTER H,L	
			x	(LAST DATA BYTE + 1)	
			x	ALTERED	
			x	REGISTERS - A,B,C,D,E,H,L	
Ø11 332	345	RECRD1	PUSH	H	PUSH POINTER
Ø11 333	Ø41 ØØØ ØØØ		LXI	H,Ø	RESET CRC
Ø11 336	112		MOV	C,D	ID HIGH
Ø11 337	315 111 Ø12		CALL	ALTPUT	
Ø11 342	113		MOV	C,E	ID LOW
Ø11 343	315 1Ø2 Ø12		CALL	PUT	
Ø11 346	11Ø		MOV	C,B	COUNT
Ø11 347	315 1Ø2 Ø12		CALL	PUT	
Ø11 352	124		MOV	D,H	SAVE CRC2
Ø11 353	115		MOV	C,L	CRC1
Ø11 354	315 1Ø2 Ø12		CALL	PUT	
Ø11 357	112		MOV	C,D	CRC2
Ø11 36Ø	315 1Ø2 Ø12		CALL	PUT	
Ø11 363	13Ø		MOV	E,B	SAVE COUNT
Ø11 364	343	RECD1	XTHL		SWITCH CRC, POINTER
Ø11 365	116		MOV	C,M	LOAD DATA
Ø11 366	Ø43		INX	H	INCREMENT POINTER
Ø11 367	343		XTHL		SWITCH CRC, POINTER
Ø11 37Ø	315 1Ø2 Ø12		CALL	PUT	
Ø11 373	ØØ5		DCR	B	DECREMENT COUNT
Ø11 374	3Ø2 364 Ø11		JNZ	RECD1	NOT ZERO
Ø11 377	124		MOV	D,H	SAVE CRC2
Ø12 ØØØ	115		MOV	C,L	CRC1
Ø12 ØØ1	315 1Ø2 Ø12		CALL	PUT	
Ø12 ØØ4	112		MOV	C,D	CRC2
Ø12 ØØ5	315 1Ø2 Ø12		CALL	PUT	
Ø12 Ø1Ø	Ø35		DCR	E	DECREMENT SAVED COUNT
Ø12 Ø11	315 1Ø2 Ø12	RECD3	CALL	PUT	
Ø12 Ø14	Ø34		INR	E	INCREMENT SAVED COUNT
Ø12 Ø15	3Ø2 Ø11 Ø12		JNZ	RECD3	NOT ZERO
Ø12 Ø2Ø	315 1Ø2 Ø12		CALL	PUT	
Ø12 Ø23	341		POP	H	POP POINTER
Ø12 Ø24	311		RET		
			x	GET	
			x	CRC IN H,L	
			x	DATA RETURNED IN C	
			x	A,C,H,L, ALTERED	
Ø12 Ø25	333 ØØ2	GET	IN	TAPEIN	STATUS
Ø12 Ø27	346 Ø17		ANI	ØFH	
Ø12 Ø31	312 Ø25 Ø12		JZ	GET	
Ø12 Ø34	315 217 Ø12		CALL	DIN	
Ø12 Ø37	325	CRC	PUSH	D	
Ø12 Ø4Ø	171		MOV	A,C	
Ø12 Ø41	255		XRA	L	

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
Ø12 Ø42	157		MOV	L,A	
Ø12 Ø43	Ø36 ØØ7		MVI	E,7	ØØ7 TIMES
Ø12 Ø45	Ø27	CRCA	RAL		
Ø12 Ø46	255		XRA	L	
Ø12 Ø47	Ø35		DCR	E	
Ø12 Ø5Ø	3Ø2 Ø45 Ø12		JNZ	CRCA	DONE?
Ø12 Ø53	157		MOV	L,A	YES
Ø12 Ø54	Ø17		RRC		
Ø12 Ø55	Ø17		RRC		
Ø12 Ø56	137		MOV	E,A	SAVE 1
Ø12 Ø57	346 3ØØ		ANI	CØH	
Ø12 Ø61	254		XRA	H	
Ø12 Ø62	127		MOV	D,A	SAVE 2
Ø12 Ø63	173		MOV	A,E	RESTORE 1
Ø12 Ø64	346 Ø77		ANI	3FH	
Ø12 Ø66	255		XRA	L	
Ø12 Ø67	147		MOV	H,A	CRC HIGH DONE
Ø12 Ø7Ø	Ø27		RAL		TEST BIT 7
Ø12 Ø71	172		MOV	A,D	RESTORE 2
Ø12 Ø72	322 Ø77 Ø12		JNC	CRCFIN	BIT 7 WAS 1?
Ø12 Ø75	356 ØØ1		XRI	1	YES
Ø12 Ø77	157	CRCFIN	MOV	L,A	CRC LOW DONE
Ø12 1ØØ	321		POP	D	
Ø12 1Ø1	311		RET		
			PUT		
			DATA IN REGISTER C		
			CRC IN H,L		
			A,H,L ALTERED		
Ø12 1Ø2	333 ØØ2	PUT	IN	TAPEIN	STATUS
Ø12 1Ø4	346 Ø17		ANI	ØFH	
Ø12 1Ø6	312 1Ø2 Ø12		JZ	PUT	
Ø12 111	315 25Ø Ø12	ALTPUT	CALL	DOUT	
Ø12 114	3Ø3 Ø37 Ø12		JMP	CRC	
			REWIND		
			REGISTER A, C ALTERED		
			THIS ROUTINE WILL GUARANTEE		
			DECK SELECTION		
Ø12 117	Ø16 22Ø	REWIND	MVI	C,9ØH	STOP
Ø12 121	315 233 Ø12		CALL	CMDOUT	
Ø12 124	333 ØØ2	REWB	IN	TAPEIN	
Ø12 126	346 Ø1Ø		ANI	Ø8H	
Ø12 13Ø	312 124 Ø12		JZ	REWB	
Ø12 133	Ø16 2ØØ		MVI	C,8ØH	FR
Ø12 135	315 233 Ø12		CALL	CMDOUT	
Ø12 14Ø	333 ØØ2	REWA	IN	TAPEIN	
Ø12 142	346 Ø1Ø		ANI	8	
Ø12 144	312 14Ø Ø12		JZ	REWA	
Ø12 147	311		RET		
			FAST REVERSE, FAST FORWARD		
			REGISTER A CONTAINS MULTIPLE		
			OF 1ØØ MILLI-SECONDS DELAY		
			REGISTER A ALTERED		

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
Ø12 15Ø	3Ø5		PUSH	B	
Ø12 151	365		PUSH	PSW	
Ø12 152	Ø16 2ØØ		MVI	C,8ØH	
Ø12 154	315 233 Ø12	FRA	CALL	CMDOUT	
Ø12 157	361		POP	PSW	
Ø12 16Ø	315 2Ø1 Ø12		CALL	DELAY	
Ø12 163	Ø16 22Ø		MVI	C,9ØH	
Ø12 165	315 233 Ø12		CALL	CMDOUT	
Ø12 17Ø	3Ø1		POP	B	
Ø12 171	311		RET		
Ø12 172	3Ø5	FF	PUSH	B	
Ø12 173	365		PUSH	PSW	
Ø12 174	Ø16 24Ø		MVI	C,AØH	
Ø12 176	3Ø3 154 Ø12		JMP	FRA	
			*	DELAY MULTIPLE OF 1ØØ MS IN REGISTER A.	
			*	REGISTERS A,B,C ALTERED	
Ø12 2Ø1	ØØ1 ØØØ Ø4Ø	DELAY	LXI	B,2ØØØH	
Ø12 2Ø4	Ø13	D1	DCX	B	
Ø12 2Ø5	ØØ4		INR	B	
Ø12 2Ø6	ØØ5		DCR	B	
Ø12 2Ø7	3Ø2 2Ø4 Ø12		JNZ	D1	
Ø12 212	Ø75		DCR	A	
Ø12 213	3Ø2 2Ø1 Ø12		JNZ	DELAY	
Ø12 216	311		RET		
			*	INPUT DATA BYTE (DATA RETURNED IN C)	
			*	REGISTER A IS ALTERED	
Ø12 217	Ø76 357	DIN	MVI	A,EFH	
Ø12 221	323 ØØ1		OUT	STROBE	
Ø12 223	333 ØØ2		IN	TAPEIN	
Ø12 225	117		MOV	C,A	
Ø12 226	Ø76 337	DINA	MVI	A,DFH	
Ø12 23Ø	323 ØØ1		OUT	STROBE	
Ø12 232	311		RET		
			*	OUTPUT COMMAND (DATA IN REGISTER C)	
			*	DECK IS OR'D WITH DATA	
			*	REGISTER A IS ALTERED	
Ø12 233	Ø72 26Ø Ø12	CMDOUT	LDA	DECK	
Ø12 236	261		ORA	C	
Ø12 237	323 ØØ2		OUT	TAPOUT	
Ø12 241	Ø76 237		MVI	A,9FH	
Ø12 243	323 ØØ1	CMDA	OUT	STROBE	
Ø12 245	3Ø3 226 Ø12		JMP	DINA	
			*	OUTPUT DATA (DATA IN REGISTER C)	
			*	REGISTER A IS ALTERED	
Ø12 25Ø	171	DOUT	MOV	A,C	
Ø12 251	323 ØØ2		OUT	TAPOUT	
Ø12 253	Ø76 137		MVI	A,5FH	
Ø12 255	3Ø3 243 Ø12		JMP	CMDA	
			*	VARIABLE DATA AREA	
Ø12 26Ø	ØØØ	DECK	DS	1	DECK NUMBER TO BE USED
Ø12 261	ØØØ ØØØ	IDR	DS	2	READ ID

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
ø12 263	øøø øøø	POINTR	DS	2	READ POINTER
ø12 265	øøø øøø	IDW	DS	2	WRITE ID
ø12 267	øøø øøø	POINTW	DS	2	WRITE POINTER
	x				READ ONE BLOCK
	x				DECK REMAINS RUNNING AFTER RETURN
	x				INPUT:
	x				DECK - DECK NUMBER LOCATED IN MEMORY
	x				POINTR - LOCATED IN MEMORY
	x				(FIRST BYTE)
	x				IDR - LOCATED IN MEMORY
	x				RETRYs - REGISTER D
	x				(ALTRD ONLY)
	x				MODE - REGISTER E
	x				ø=READ
	x				1=CHECK
	x				OUTPUT:
	x				DECK, POINTER, IDR UNCHANGED
	x				REGISTER - A,B,C,D,H,L ALTERED
	x				COUNT - REGISTER B
	x				ø1=1 BYTE
	x				øø=256 BYTES
	x				ERROR - REGISTER A
	x				ø - NO ERRORS
	x				1 - CRC ERROR
	x				2 - BLOCK NOT FOUND
	x				3 - END OF TAPE OR JAM
	x				ENTRY POINTS:
	x				READ - NORMAL ENTRY
	x				ALTRD - DECK WILL BACKSPACE
	x				FIRST, USER MUST SUPPLY RETRIES.
	x				ALTRD2 - NORMAL, EXCEPT USER MUST
	x				SUPPLY RETRIES
ø12 271	ø26 ø12	READ	MVI	D, RETRYs	
ø12 273	325	RD54	PUSH	D	RETRIES, MODE
ø12 274	ø41 øøø øøø	ALTRD2	EQU	RD54	
ø12 277	333 øø2	RD5	LXI	H, ø	RESET CRC
ø12 3ø1	127		IN	TAPEIN	STATUS
ø12 3ø2	ø16 34ø	RD51	MOV	D,A	
ø12 3ø4	315 233 ø12		MVI	C,EøH	READ
ø12 3ø7	172		CALL	CMDOUT	
ø12 31ø	346 øø4		MOV	A,D	STOP?
ø12 312	312 327 ø12		ANI	ø4H	
ø12 315	ø76 øø4		JZ	RD5ø	NO
ø12 317	315 2ø1 ø12		MVI	A,4	.4 SECONDS
ø12 322	ø26 øøø		CALL	DELAY	,
ø12 324	3ø3 3ø2 ø12		MVI	D, ø	STATUS = ø
ø12 327	øø6 ø6ø	RD5ø	JMP	RD51	
ø12 331	12ø		MVI	B,3øH	8 SECOND TIMEOUT
ø12 332	333 øø2	RD53	MOV	D,B	
			IN	TAPEIN	STATUS

<u>-OC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENTS</u>
Ø12 334	346 Ø17		ANI	ØFH	READY?
Ø12 336	3Ø2 22Ø Ø13		JNZ	RD1Ø	YES
Ø12 341	Ø33		DCX	D	
Ø12 342	Ø24		INR	D	
Ø12 343	Ø25		DCR	D	
Ø12 344	3Ø2 332 Ø12		JNZ	RD53	
Ø12 347	ØØ5		DCR	B	
Ø12 35Ø	3Ø2 331 Ø12		JNZ	RD57	
Ø12 353	315 117 Ø12		CALL	REWIND	
Ø12 356	Ø76 ØØ2	RD2	MVI	A,2	ERROR = 2
Ø12 36Ø	321		POP	D	RETRIES, MODE
Ø12 361	Ø25	RD8	DCR	D	
Ø12 362	3Ø2 273 Ø12		JNZ	RD54	
Ø12 365	311		RET		
Ø12 366	315 Ø25 Ø12	RD52	CALL	GET	IDH
Ø12 371	1Ø1		MOV	B,C	
Ø12 372	315 Ø25 Ø12		CALL	GET	IDL
Ø12 375	131		MOV	E,C	
Ø12 376	315 Ø25 Ø12		CALL	GET	COUNT
Ø13 ØØ1	121		MOV	D,C	
Ø13 ØØ2	315 Ø25 Ø12		CALL	GET	CRC1
Ø13 ØØ5	315 Ø25 Ø12		CALL	GET	CRC2
Ø13 Ø1Ø	227		SUB	A	CRC = Ø?
Ø13 Ø11	2Ø4		ADD	H	
Ø13 Ø12	3Ø2 274 Ø12		JNZ	RD5	NO
Ø13 Ø15	2Ø5		ADD	L	
Ø13 Ø16	3Ø2 274 Ø12		JNZ	RD5	NO
	x		COMPUTE		BE TAPEID
	x				-HL IDR
	x				XY
Ø13 Ø21	173		MOV	A,E	
Ø13 Ø22	Ø52 261 Ø12		LHLD	IDR	
Ø13 Ø25	225		SUB	L	
Ø13 Ø26	137		MOV	E,A	REGISTER E CONTAINS Y
Ø13 Ø27	157		MOV	L,A	
Ø13 Ø3Ø	17Ø		MOV	A,B	
Ø13 Ø31	234		SBB	H	REGISTER A CONTAINS X
Ø13 Ø32	147		MOV	H,A	H = XY/8
Ø13 Ø33	Ø51		DAD	H	
Ø13 Ø34	Ø51		DAD	H	
Ø13 Ø35	Ø51		DAD	H	
Ø13 Ø36	Ø51		DAD	H	
Ø13 Ø37	Ø51		DAD	H	
Ø13 Ø4Ø	174		MOV	A,H	
Ø13 Ø41	312 Ø7Ø Ø13		JZ	ID1	
Ø13 Ø44	362 Ø7Ø Ø13		JP	ID2	
Ø13 Ø47	Ø57		CMA		COMPUTE FF DELAY
Ø13 Ø5Ø	3Ø6 ØØ2		ADI	2	ADD 1+1 FOR 2'S COMP
Ø13 Ø52	372 Ø62 Ø13		JM	ID3	
Ø13 Ø55	376 ØØ4		CPI	4	GREATER THAN THRESHOLD?

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
Ø13 Ø57	372 274 Ø12		JM	RD5	
Ø13 Ø62	315 172 Ø12	ID3	CALL	FF	
Ø13 Ø65	3Ø3 274 Ø12		JMP	RD5	
Ø13 Ø7Ø	Ø34	ID1	INR	E	Y = Ø?
Ø13 Ø71	Ø35		DCR	E	
Ø13 Ø72	312 1Ø5 Ø13		JZ	RD6	YES
Ø13 Ø75	3Ø6 ØØ6	ID2	ADI	6	
Ø13 Ø77	315 15Ø Ø12		CALL	FR	
Ø13 1Ø2	3Ø3 356 Ø12		JMP	RD2	
Ø13 1Ø5	1Ø2	RD6	MOV	B,D	COUNT
Ø13 1Ø6	321		POP	D	RETRIES, MODE
Ø13 1Ø7	3Ø5		PUSH	B	COUNT
Ø13 11Ø	Ø52 263 Ø12		LHLD	POINTR	
Ø13 113	345		PUSH	H	
Ø13 114	Ø41 ØØØ ØØØ		LXI	H,Ø	RESET CRC
Ø13 117	315 Ø25 Ø12	RD56	CALL	GET	
Ø13 122	Ø34		INR	E	
Ø13 123	Ø35		DCR	E	
Ø13 124	3Ø2 133 Ø13		JNZ	RD55	
Ø13 127	343		XTHL		SWITCH CRC, POINTER
Ø13 13Ø	161		MOV	M,C	STORE DATA
Ø13 131	Ø43		INX	H	BUMP POINTER
Ø13 132	343		XTHL		SWITCH CRC, POINTER
Ø13 133	ØØ5	RD55	DCR	B	DECREMENT COUNT
Ø13 134	3Ø2 117 Ø13		JNZ	RD56	
Ø13 137	3Ø1		POP	B	ADJUST STACK POINTER
Ø13 14Ø	3Ø1		POP	B	COUNT
Ø13 141	315 Ø25 Ø12		CALL	GET	
Ø13 144	315 Ø25 Ø12		CALL	GET	
Ø13 147	333 ØØ2		IN	TAPEIN	STATUS
Ø13 151	Ø37		RAR		OVERRUN?
Ø13 152	332 173 Ø13		JC	ALTRD	YES
Ø13 155	Ø37		RAR		
Ø13 156	Ø37		RAR		STOP?
Ø13 157	332 226 Ø13		JC	RD11	YES
Ø13 162	227		SUB	A	
Ø13 163	2Ø4		ADD	H	
Ø13 164	3Ø2 173 Ø13		JNZ	ALTRD	NO
Ø13 167	2Ø5		ADD	L	
Ø13 17Ø	312 2Ø5 Ø13		JZ	RD19	
Ø13 173	Ø76 ØØ5	ALTRD	MVI	A,5	GREATER THAN 1 BLOCK
Ø13 175	315 15Ø Ø12		CALL	FR	
Ø13 2ØØ	Ø76 ØØ1		MVI	A,1	ERROR = 1
Ø13 2Ø2	3Ø3 361 Ø12		JMP	RD8	
Ø13 2Ø5	12Ø	RD19	MOV	D,B	SAVE COUNT
Ø13 2Ø6	Ø25		DCR	D	DECREMENT SAVED COUNT
Ø13 2Ø7	315 Ø25 Ø12	RD9	CALL	GET	
Ø13 212	Ø24		INR	D	INCREMENT SAVED COUNT
Ø13 213	3Ø2 2Ø7 Ø13		JNZ	RD9	
Ø13 216	227		SUB	A	ERROR = Ø

<u>LOC</u>	<u>OBJ</u>	<u>LABEL</u>	<u>OP</u>	<u>OPERAND</u>	<u>COMMENT</u>
Ø13 217	311		RET		
Ø13 22Ø	346 ØØ4	RD1Ø	ANI	Ø4H	STOP?
Ø13 222	312 366 Ø12		JZ	RD52	NO
Ø13 225	321		POP	D	RETRIES, MODE
Ø13 226	315 117 Ø12	RD11	CALL	REWIND	
Ø13 231	Ø76 ØØ3		MVI	A,3	ERROR = 3
Ø13 233	3Ø3 361 Ø12		JMP	RD8	

## K. PHI-DECK MAINTENANCE

### Recommended Field Maintenance

This maintenance schedule consists of recommended maintenance operations to be performed in the field by operating personnel and service technicians. Schedule A consists of cleaning operations that should be performed every ten to twenty hours of operating time. Since the accumulation of dirt and tape oxide is highly dependent upon operating environment and the quality of tape used, the time interval for Schedule A can be varied according to system experience. The Schedule A cleaning operations are simple enough that they can be performed by operating personnel in many systems.

The items in Schedule B should be performed by technically skilled personnel.

### Required Equipment

#### For Schedule A

1. Tape head cleaner or pure isopropyl alcohol
2. Rubber drive cleaner
3. Cotton tip wood swabs (Q-Tips)
4. Soft bristled brush
5. Tape head demagnetizer

#### Additional Equipment for Schedule B

1. Lightweight machine oil
2. SAE 10 wt. oil
3. Speed test tape
4. Oscilloscope, frequency counter or wow and flutter meter with speed check capability

### Schedule A (10 to 20 hour intervals)

1. Remove accumulated dust, tape oxide particles, etc. with a soft bristled brush.
2. Clean magnetic head and tape guides with tape head cleaner or isopropyl alcohol.
3. Clean the capstan shaft with a cotton tip swap moistened with tape head cleaner. Do not allow tape head cleaner to run down the capstan shaft into the capstan bearing. Use only enough cleaning liquid on the cotton tip swab to remove tape oxide from the exposed portion of the capstan shaft.
4. Clean pinch roller with rubber drive cleaner or isopropyl alcohol.
5. Demagnetize the tape head using a tape head demagnetizer.

Schedule B (500 hour intervals)

1. Perform Schedule A.
2. Oil the capstan bearing using a drop of lightweight machine oil. Clean excess oil off the capstan shaft.
3. Oil the headbar pivot bushings with a drop or two of SAE 10 weight oil.
4. Check and adjust tape speed as described in the Motor Speed Calibration paragraph in section VI.

Maintenance Guide

This maintenance schedule consists of recommended maintenance checks and operations to be performed in a facility equipped for tape deck repairs and maintenance. For greatest system reliability, this procedure should be performed on a regular basis at intervals of approximately 1,000 hours of tape deck operating time. Where such maintenance is not performed on a scheduled basis, this routine should be performed whenever a tape deck is returned to a repair facility for repairs.

Required Equipment

1. Tape head cleaner or pure isopropyl alcohol
2. Rubber drive cleaner
3. Lightweight machine oil
4. SAE 10 wt. oil
5. Cotton tip wood swabs (Q-Tips)
6. Soft bristled brush
7. Tape head demagnetizer
8. Information Terminals M-300 Tape head and guide gauge set
9. Oscilloscope
10. Test tapes
11. Miscellaneous hand tools
12. Frequency counter

Cleaning

1. Clean Phi-Deck thoroughly. Remove accumulated dust, tape oxide particles and lint with air hose or brush.
2. Demagnetize tape head.
3. Clean tape head and tape guides with liquid cleaner and cotton swab. Use only a commercial tape head cleaning fluid or pure isopropyl alcohol.
4. Clean capstan shaft with a cotton tip wood swab moistened with tape head cleaner. Do not allow tape head cleaner to run down the capstan shaft into the capstan bearing. Use only enough cleaning liquid on the cotton swab to remove tape oxide from the exposed portion of the capstan shaft.
5. Clean capstan drive rubber roller. Use rubber drive roller cleaner or pure isopropyl alcohol.

### Lubrication

1. Oil the headbar pivot bushings using a drop or two of SAE 10 weight oil. Wipe off excess oil.
2. Apply a drop of lightweight machine oil to the capstan bearing where the capstan shaft enters the bearing. Clean any excess oil from the capstan shaft.

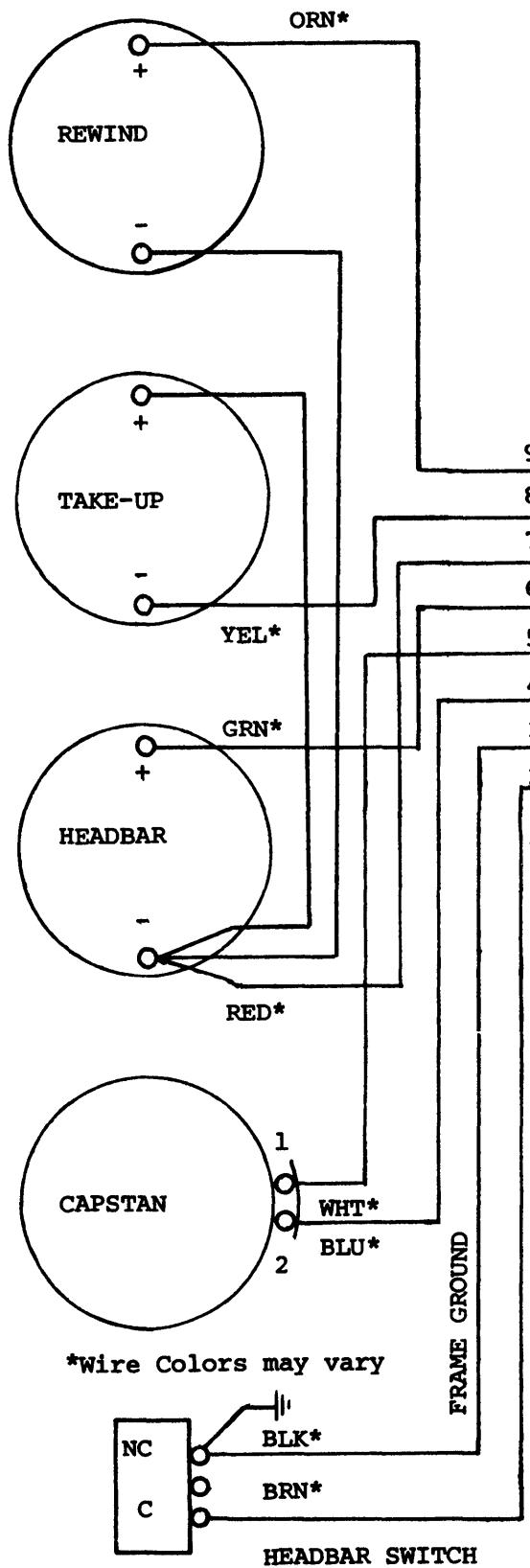
### Drive Belts

1. Remove the plastic cassette well and check the two reel drive belts. The belts should be replaced if there are any signs of splitting, cracking, or wear.
2. Check the belts for slippage by stalling the associated reel post while in the Fast Forward mode for the takeup reel and Rewind mode for the rewind reel. The belts should be replaced and the pulleys cleaned if there is belt slippage during the stalled condition.
3. Check the capstan flywheel drive belt for cracking, splitting, or wear. Replace if necessary.

### Alignment Checks and Adjustments

1. Using the Information Terminals M-300 gauge set and with the headbar engaged, check head depth of penetration, zenith and guide height. The parameters being out of tolerance indicate that the gearbox positioning may need to be adjusted to compensate for starwheel assembly wear.
2. If the previous checks indicate head misalignment due to gearbox positioning, perform gearbox assembly alignment procedure. If head alignment is correct, do not perform adjustment.
3. Check gearbox starwheel to headbar engage-disengage positioning. Adjust starwheel position sensing micro-switch for correct positioning if necessary.
4. Check pinch roller pressure and adjust if necessary.
5. Using a high quality tape with a continuously recorded tone or flux reversal pattern, check the play or read head output for signal levels and quality. Incorrect signals are indicative of head wear, head alignment or tape tracking problems.
6. Check tape speed and adjust as described in the Motor Speed Calibration paragraph in section VI.

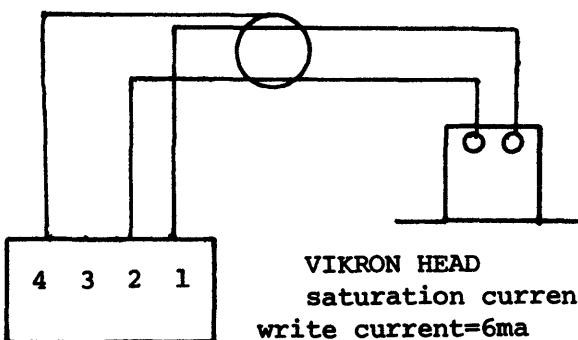
FIG. 5.1 PHI DECK WIRING



DECK WIRING  
MOTOR, HEAD, and SWITCH CONNECTIONS

NINE POSITION MOLEX CONNECTOR

POSITION 1 HAS NO CONNECTION



VIKRON HEAD  
saturation current=4ma  
write current=6ma  
read output=5.5mv  
bandwidth 100KHz

1. HDB
2. HDA
3. No Connection
4. HDGRND (Shield)

# The Digital Group Cassette Storage System

## System Improvements

The following suggestions consist of various hardware and software improvements that may be made to the Cassette Storage System. Each modification should be examined to verify that it has not already been implemented.

**NOTE:** The hardware modifications are applicable only to The Digital Group B and C version controller cards. This board is identified by part number DG-0006-B or DG-0006-C on the right edge of the card. It is suggested that owners of A-version cards (DG-0006-A) purchase the controller upgrade kit. Refer to the schematic and parts placement diagram of the Cassette Storage System when making the hardware modifications.

### Problems and associated modifications:

- I. A. Symptom: The Phideck head may attempt to engage when power is initially applied to the system.  
B. Modification (applicable only for B-version cards):
  1. Replace R42 with a 22K ohm resistor.
  2. Install a 4.7mfd, or greater tantalum capacitor from pin B (MANSTOP) on the dual 36-pin edge to GND.
- II. A. Symptom: The head will not engage properly or at all if a slow forward command is issued while the tape is moving in a fast forward mode.  
B. Modification (applicable only for B-version cards): See Fig. 1
  1. Cut the printed circuit trace leading to pin 4 of IC17 on the component side of the card.
  2. Solder a short piece of wire between pin 4 and 5 of IC17 on the circuit side of the card.

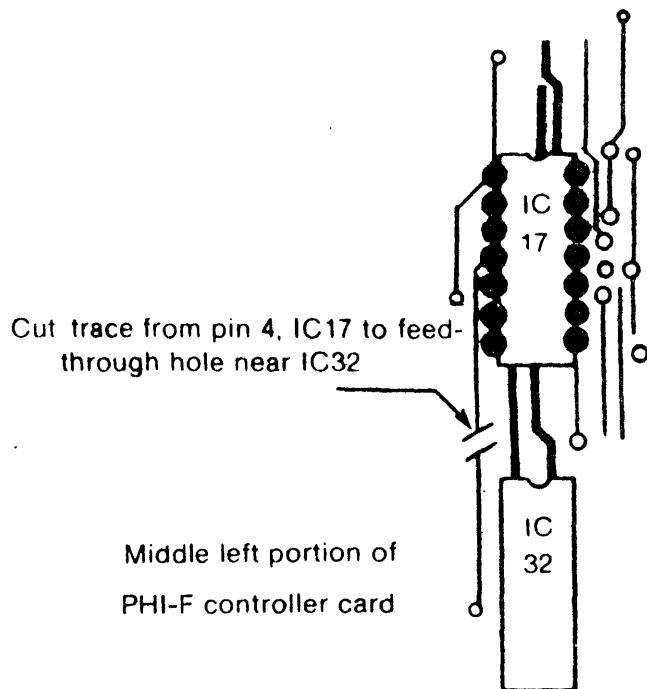


FIGURE 1

- III. A. Symptom: Abnormally high soft error rate with some types of tapes or cassettes.  
NOTE: This modification will reduce the speed tolerance from 20% to approximately 15%, which should be sufficient for most applications.
- B. Modification:  
1. Replace R50 with a 33K ohm resistor.  
2. Replace C27 with a 4.7mfd tantalum capacitor.
- IV. A. Symptom: Several problems have arisen with the use of some cassette tapes, such as: long leaders, C60 or longer tapes with abnormally low drag, and tape jumping off the internal guides of the cassette, thus creasing the tape.
- B. Modification: Figures 1 and 2 contain software modifications that should be made to the system. There are two listings, one for the driver routines located at octal 011000 and another for the same driver routines located at octal 344000 in PHIMON. These changes will cure the above symptom and also provide a slight improvement in the access time of the Cassette Storage System.
- C. Procedure for modifying PHIMON:  
1. Power on system.  
2. Type DTO, then hit RETURN.  
3. Make the modifications shown in Figure 1 to the driver routines using DTO.  
4. Return to PHIMON using the reset button.  
5. Place a blank tape in drive #1.  
6. Type ZE!#1, then hit RETURN.  
7. Type BU#1, then hit RETURN.  
8. When the operation is finished, drive #1 will contain a system tape with the modifications.  
9. This new tape may now be used as your new system tape for all future operations.

WARNING: Do not use the modified version of PHIMON to save data or tapes with unmodified PHIMON or the directory will be lost. It is recommended that new tapes be generated using the modified PHIMON, and PIP be used transfer the data on the old tapes to the new ones.

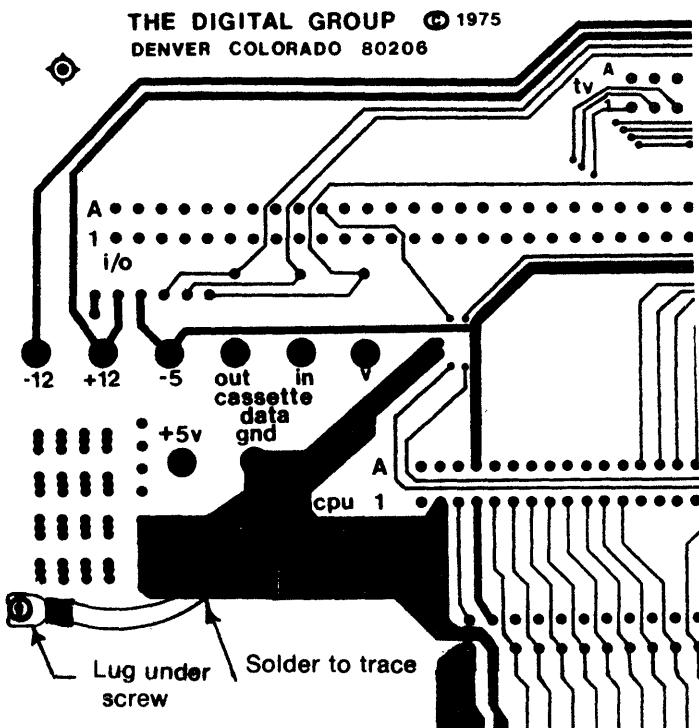
- V. A. Symptom: The head on a Phideck may bang in and out when power is turned on or after a static discharge to the system cabinet or electronics.
- B. Solution:  
1. Immediately turn off power to the system.  
2. Move the system to an area that does not have a carpet or other static-producing media.  
3. Inspect all drives to be sure all the heads are disengaged. If one is engaged, turn the engage cam on the left side of the drive counter clockwise until the head is disengaged.
- VI. A. Symptom: Excessive errors on tapes due to contamination resulting from removing tapes from the drives without the tapes being rewound.
- B. Solution: Rewind all tapes before removing them from the drives. The following HOME command should be added to the PHIMON operating system tape to aid the user in rewinding tapes.
- C. HOME Command  
1. Usage  
The HOme command allows the user to quickly rewind any Phideck drive. The command is executed by typing:  
`<HO#N or`  
`<HOME#N`  
The "<" indicates the prompt on the monitor. N is the drive number (0-3). Drive number 0 will be rewound if N is not specified.
2. Inserting the HOME Routine  
a. Load PHIMON as usual.  
b. Type AL #10, then hit RETURN.  
c. Type DTO, then hit RETURN.  
d. Type 010207 Octal.  
e. Using DTO and referring to Figure 2, type Overlay 10 into memory.  
f. Press the (ESC) key.  
g. Type IN#10, then hit RETURN.  
h. Type DTO, then hit RETURN.

- i. Using DTO and referring to Figure 3, type in the changes to the command table and the Home Routine.
- j. Press the (ESC) Key.
- k. Type BUILD, then hit RETURN.
- l. Modifications to PHIMON are now complete.

- VII. A. Symptom: Poor performance due to type of tape being used.
- B. Solution: Use only types of tape recommended by the Digital Group.
1. Digital Group audio cassettes are available in quantities of 1, 5 or 10 cassettes. Order number Cassette10 for 10 tapes, Cassette5 for 5 tapes.
  2. Use only high quality, low noise audio cassettes. Avoid high-output, chromium dioxide or any other special purpose tapes.
- VIII. A. Symptom: Excessive noise caused by a ground loop in system ground, resulting in excessive soft errors during read.
- B. Solution: Modify your system by grounding the system motherboard to the chassis. For a Digital Group system, this is best accomplished by soldering a short piece of 14 gauge wire to the ground plane on the top side of the motherboard and connecting the other end under a motherboard mounting screw with a lug affixed to the wire.

See the accompanying figure below.

**NOTE:** If, after accomplishing all the modifications and following all our suggestions, you are still unable to get satisfactory operation of your Phideck system, send your Phideck components or, for best results, your complete system, to us for repair and/or evaluation. It will be returned to you operational and with an extended 90-day warranty. Consult the Digital Group repair fee schedule for the cost of this service.



# PATCH SHEET FOR PHIMON

Figure 1 — Modifications to PHIMON

ADDRESS	OBJECT CODE		
064265	0100	ORG	EQU 344000
344062	0110	ST	ORG+62
344062	0120	****	FIVE SECOND DELAY FOR BLOCK 0. ****
344062 062	0130	DB	062
344202	0140	ST	ORG+202
344202	0150	****	BACKSPACE SEVERAL BLOCKS BEFORE CHECK READ
344202 003	0160	DB	003
345165	0170	ST	ORG+1165
345165	0180	****	JUMP TO STOP. ***
345165 303 302 345	0190	JP	STOP
345277	0200	ST	ORG+1277
345277	0210	****	STOP ROUTINE AND FAST REVERSE CORRECTION.
345277 303 322 345	0220	JP	RD51
345302 315 233 345	0230	STOP	CALL CMDOUT STOP ROUTINE
345305 076 001	0240	LD	A,1 .1 SECOND
345307 315 201 345	0250	CALL	DELAY
345312 301	0260	POP	BC
345313 311	0270	RET	
345314 315 150 345	0280	FHCCOR	CALL FR FAST REVERSE CORRECTION
345317 303 356 345	0290	JP	RD2
345322 016 340	0300	RD51	LD C,0E0H READ
345324 315 233 345	0310	CALL	CMDOUT
345327 006 110	0320	RD50	LD B,110 14 SECONDS
346036	0330	ST	ORG+2036
346036	0340	****	SEARCH IMPROVEMENT. ***
346036 174	0350	LD	A,H
346037 051	0360	ADD	HL,HL
346040 312 070 346	0370	JP	Z, ID1
346043 362 075 346	0380	JP	P, ID2
346046 204	0390	ADD	H
346051	0400	ST	ORG+2051
346051	0410	****	MORE SEARCH IMPROVEMENT. ***
346051 001	0420	DB	1
346056	0430	ST	ORG+2056
346056	0440	****	MORE SEARCH IMPROVEMENT. ***
346056 003	0450	DB	3
346075	0460	ST	ORG+2075
346075	0470	****	MORE SEARCH IMPROVEMENT. ***
346075 204	0480	ID2	ADD H
346076 007	0490	RLCA	
346077 306 005	0500	ADD	5
346101 303 314 345	0510	JP	FRCOR
346174	0520	ST	ORG+2174
346174	0530	****	LAST OF SEARCH IMPROVEMENT. ***
346174 003	0540	DB	3
346175	0550	****	EXTERNAL REFERENCES. ***
346175	0560	CMDOUT	EQU ORG+1233
346175	0570	DELAY	EQU ORG+1201
346175	0580	FR	EQU ORG+1150
346175	0590	ID1	EQU ORG+2070
346175	0600	RD2	EQU ORG+1356
346175	0610	END	

# PATCH SHEET FOR PHIDECK DRIVER

Figure 2 — Modifications to the Phi-Deck Driver Routines

## ADDRESS

ADDRESS	OBJECT CODE	0100 ORG EQU 011000
064240		0110 ST ORG+62
011062		0120 **** FIVE SECOND DELAY FOR FLOCK 0. ****
011062		0130 DB 062
062		
011202		0140 ST ORG+202
011202		0150 **** BACKSPACE SEVERAL BLOCKS BEFORE CHECK READ.
011202		0160 DB 003
003		
012165		0170 ST ORG+1165
012165		0180 **** JUMP TO STOP. ****
012165 303 302 012		0190 JP STOP
012277		0200 ST ORG+1277
012277		0210 **** STOP ROUTINE AND FAST REVERSE CORRECTION.
012277 303 322 012		0220 JP RD51
012302 315 233 012		0230 STOP CALL CMDOUT STOP ROUTINE
012305 076 001		0240 LD A,1 .1 SECOND
012307 315 201 012		0250 CALL DELAY
012312 301		0260 POP BC
012313 311		0270 RET
012314 315 150 012		0280 FRCOR CALL FR FAST REVERSE CORRECTION
012317 303 356 012		0290 JP RD2
012322 016 340		0300 RD51 LD C,0E0H READ
012324 315 233 012		0310 CALL CMDOUT
012327 006 110		0320 RD50 LD B,110 14 SECONDS
013036		0330 ST ORG+2036
013036		0340 **** SEARCH IMPROVEMENT. ****
013036 174		0350 LD A,H
013037 051		0360 ADD HL,HL
013040 312 070 013		0370 JP Z, ID1
013043 362 075 013		0380 JP P, ID2
013046 204		0390 ADD H
013051		0400 ST ORG+2051
013051		0410 **** MORE SEARCH IMPROVEMENT. ****
013051		0420 DB 1
001		
013056		0430 ST ORG+2056
013056		0440 **** MORE SEARCH IMPROVEMENT. ****
013056		0450 DB 3
003		
013075		0460 ST ORG+2075
013075		0470 **** MORE SEARCH IMPROVEMENT. ****
013075 204		0480 ID2 ADD H
013076 007		0490 RLCA
013077 306 005		0500 ADD 5
013101 303 314 012		0510 JP FRCOR
013174		0520 ST ORG+2174
013174		0530 **** LAST OF SEARCH IMPROVEMENT. ****
013174		0540 DB 3
003		
013175		0550 **** EXTERNAL REFERENCES. ****
013175		0560 CMDOUT EQU ORG+1233
013175		0570 DELAY EQU ORG+1201
013175		0580 FR EQU ORG+1150
013175		0590 ID1 EQU ORG+2070
013175		0600 RD2 EQU ORG+1356
013175		0610 END

## PHIMON HOME COMMAND

LOCATION			
010207 OBJECT CODE	0100	ST	010207
010207	0110	*	PATCHES TO OVERLAY 10 FOR HOME COMMAND
010207 310 317	0120	DC	'HO'
010211 355 345	0130	DW	345355
010213 016	0140	DB	016
010214 332 305	0150	DC	'ZE'
010216 362 357	0160	DW	357362
010220 012	0170	DB	012
010221 311 316	0180	DC	'IN'
010223 363 345	0190	DW	345363
010225 362 364	0210	DW	364362
010227 065	0220	DB	065
010230 000	0230	DB	000

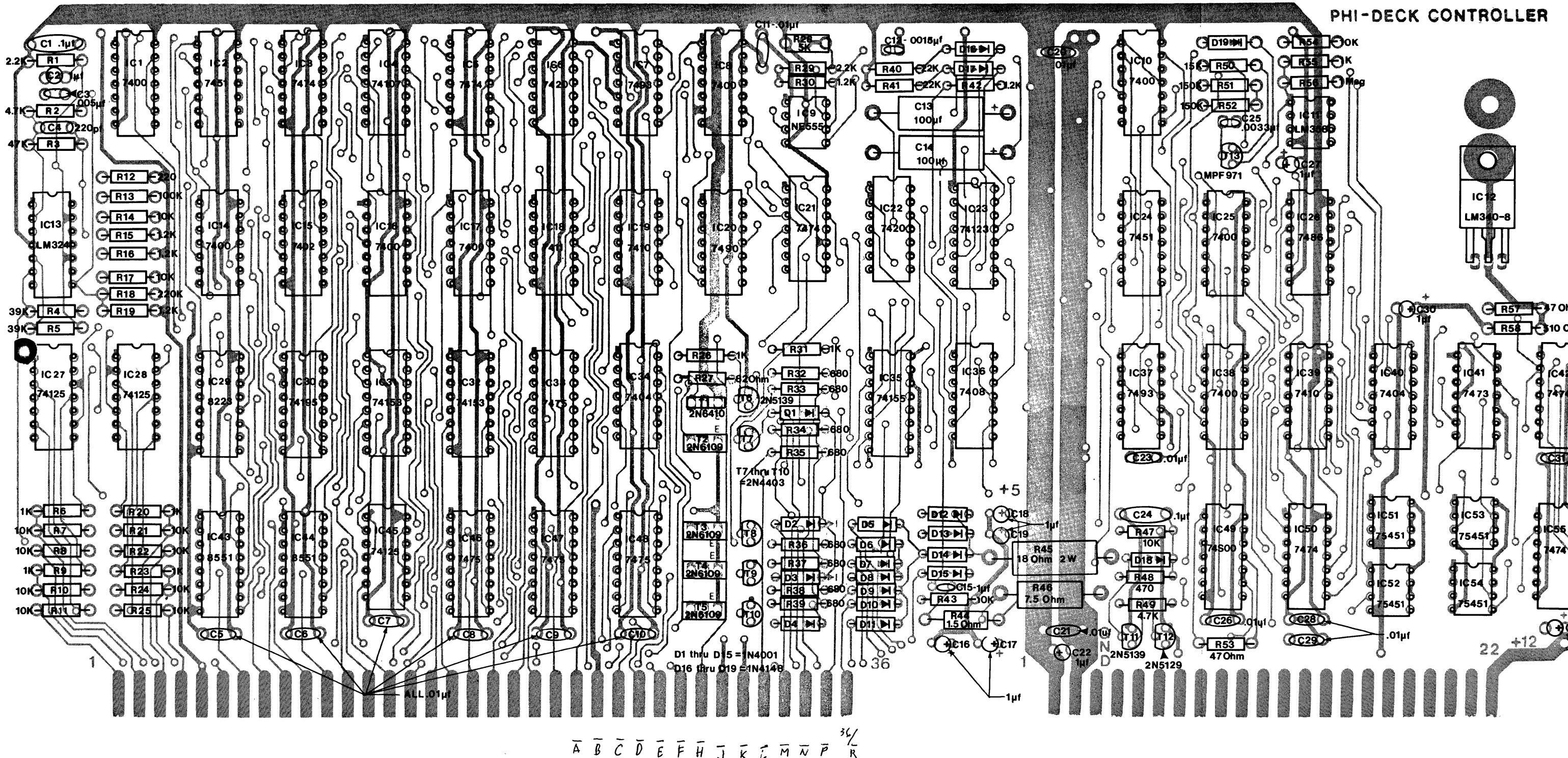
FIGURE 3 -- Patches to Help Overlay

### LOCATION

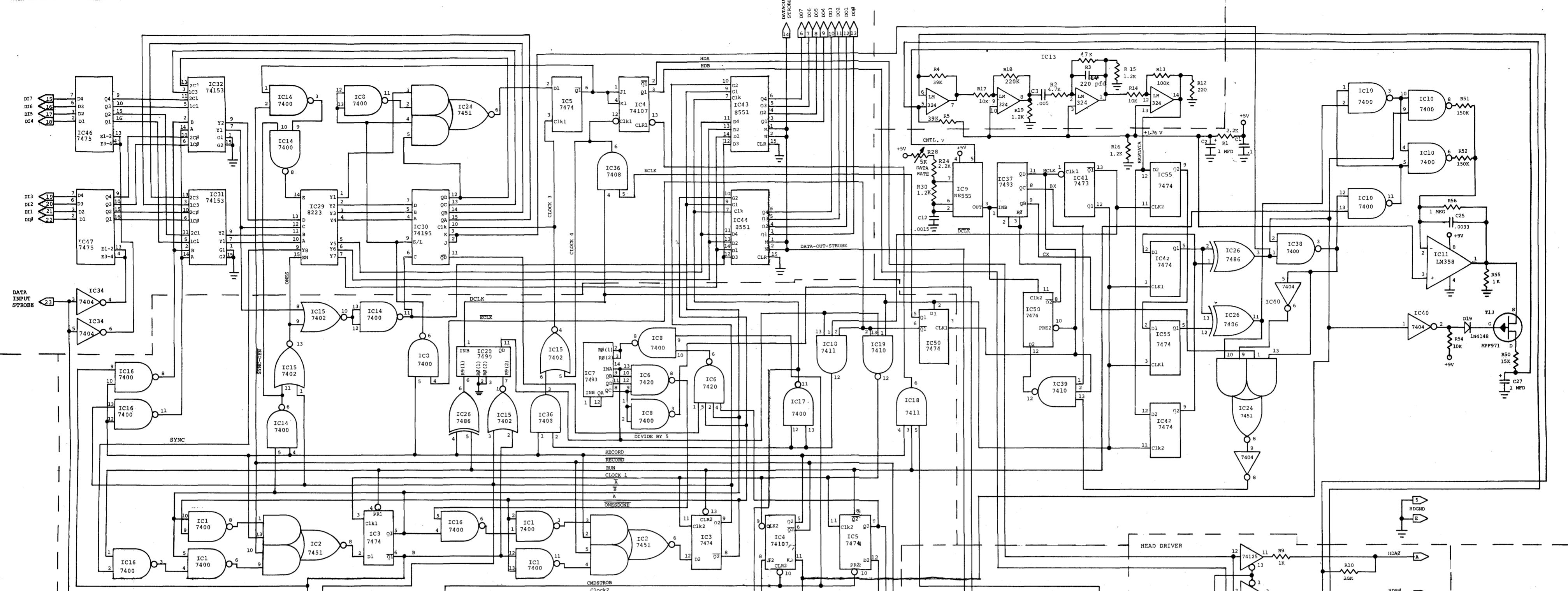
340146 OBJECT CODE	0240	ST	340146
340146	0250	*	MODIFICATION TO PHIMON TO ADD 'HOME'
340146	0260	*	COMMAND, WHICH WILL REWIND THE SPECIFIED
340146	0270	*	PHIDECK DRIVE UNIT. BY TOM COX
340146	0280	*	
340146	0290	*	FORMAT >HOME#N
340146	0300	*	
340146	0310	*	NEW ENTRY FOR COMMAND TABLE
340146 020	0320	COMTAB DB	020
340262	0330	ST	340262
340262 310 317	0340	DC	'HO'
340264 352 343	0350	DW	HOME
340266 000	0360	DB	0
343352	0370	ST	343352
343352	0380	*	ROUTINE TO REWIND SPECIFIED DECK
343352 315 162 341	0390	HOME	CALL DECKSL
343355 315 117 345	0400		CALL REWIND
343360 303 042 340	0410		JP COMAND
343363	0420	DECKSL	EQU 341162
343363	0430	REWIND	EQU 345117
343363	0440	COMAND	EQU 340042

FIGURE 4 -- Patches to Command Table

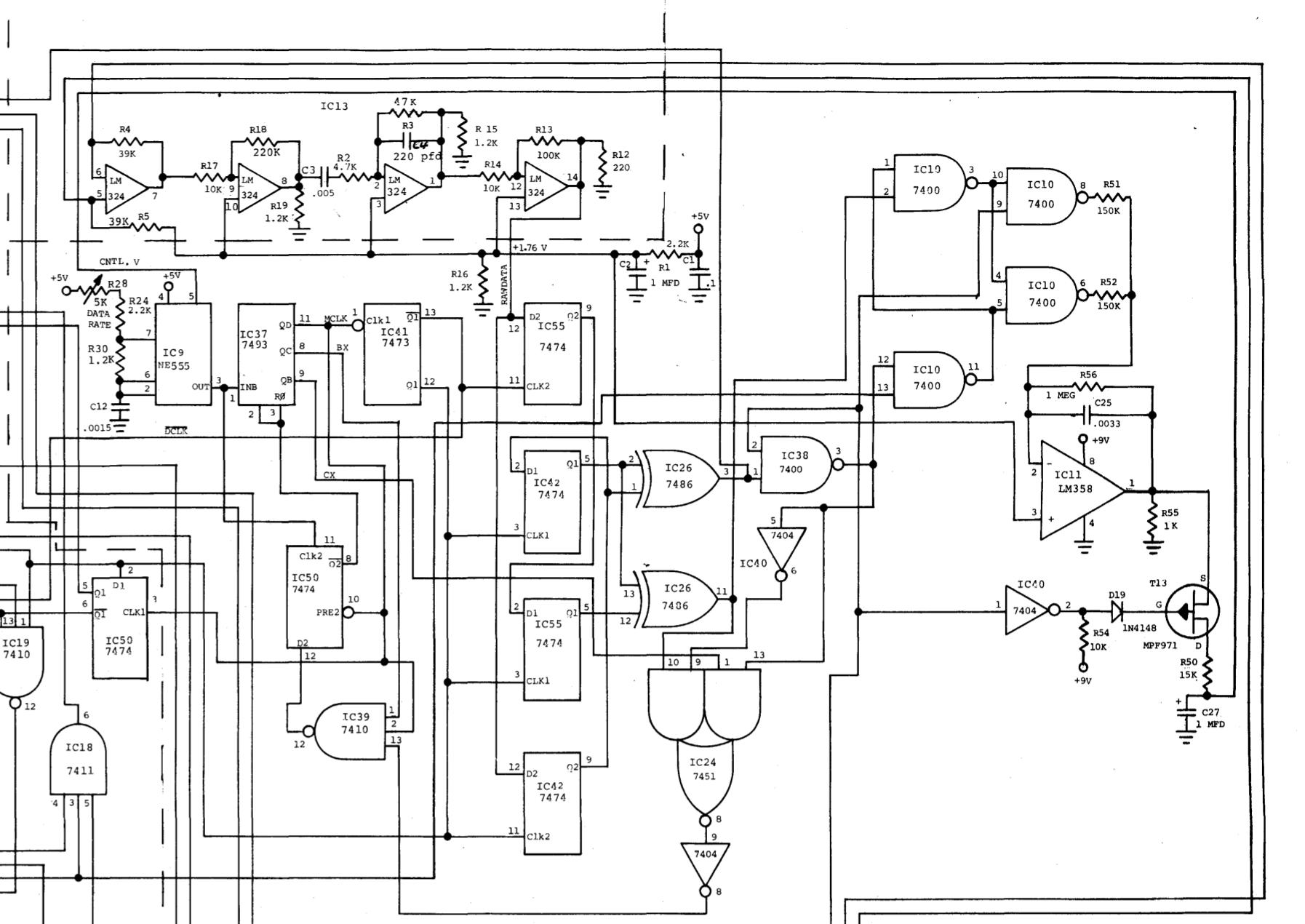
CSSB - 33 - CL



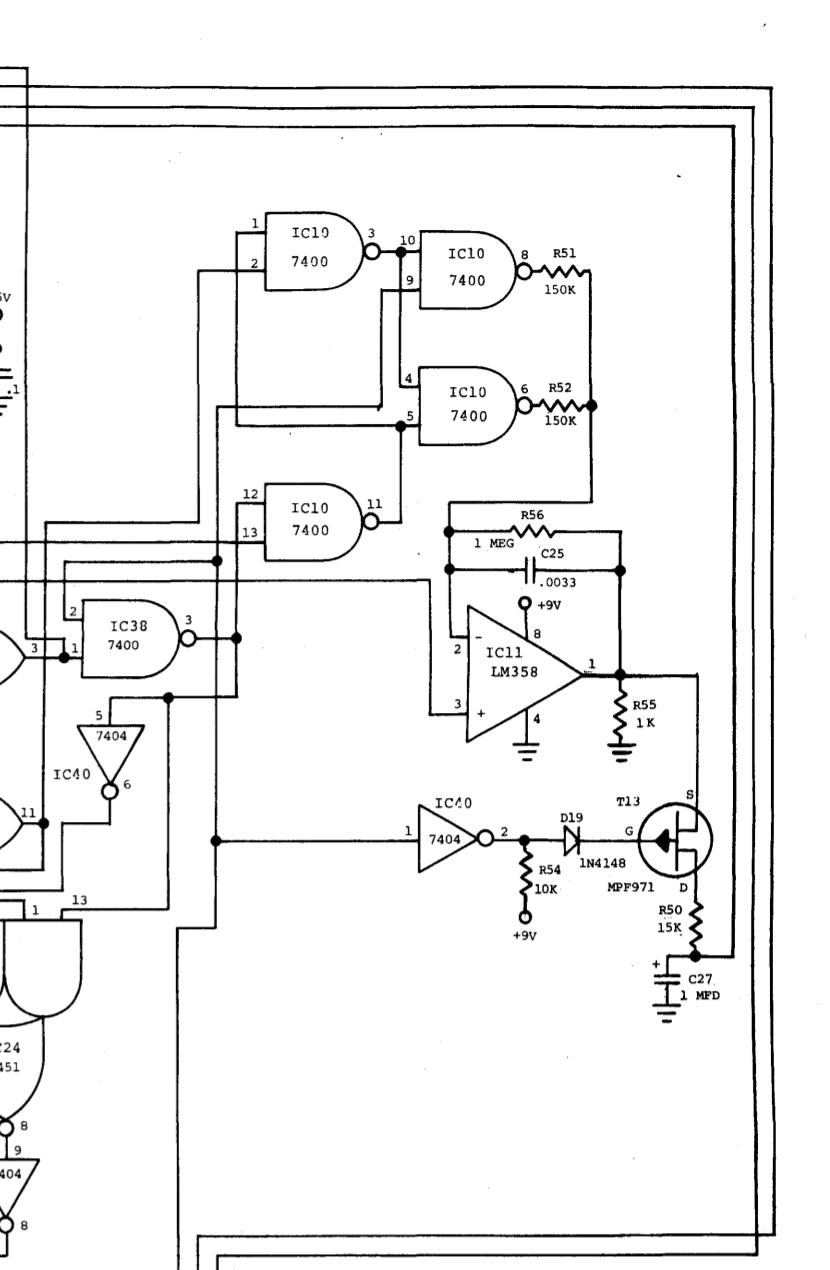
## DATA ENCODING AND SERIALIZATION



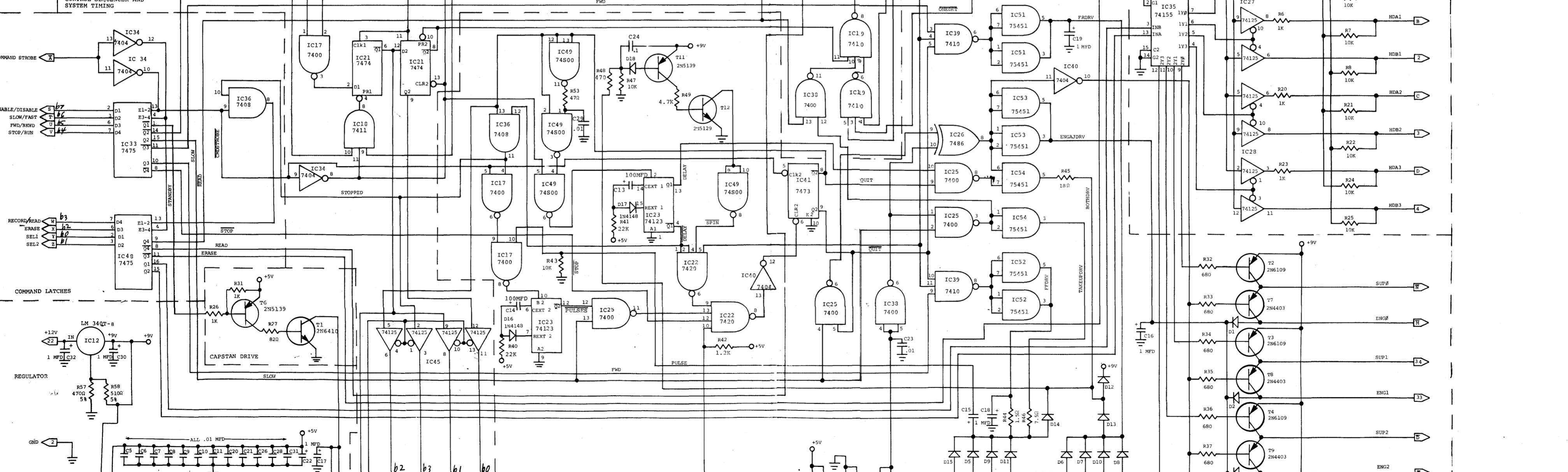
## HEAD PREPAMP AND WAVESHAPE

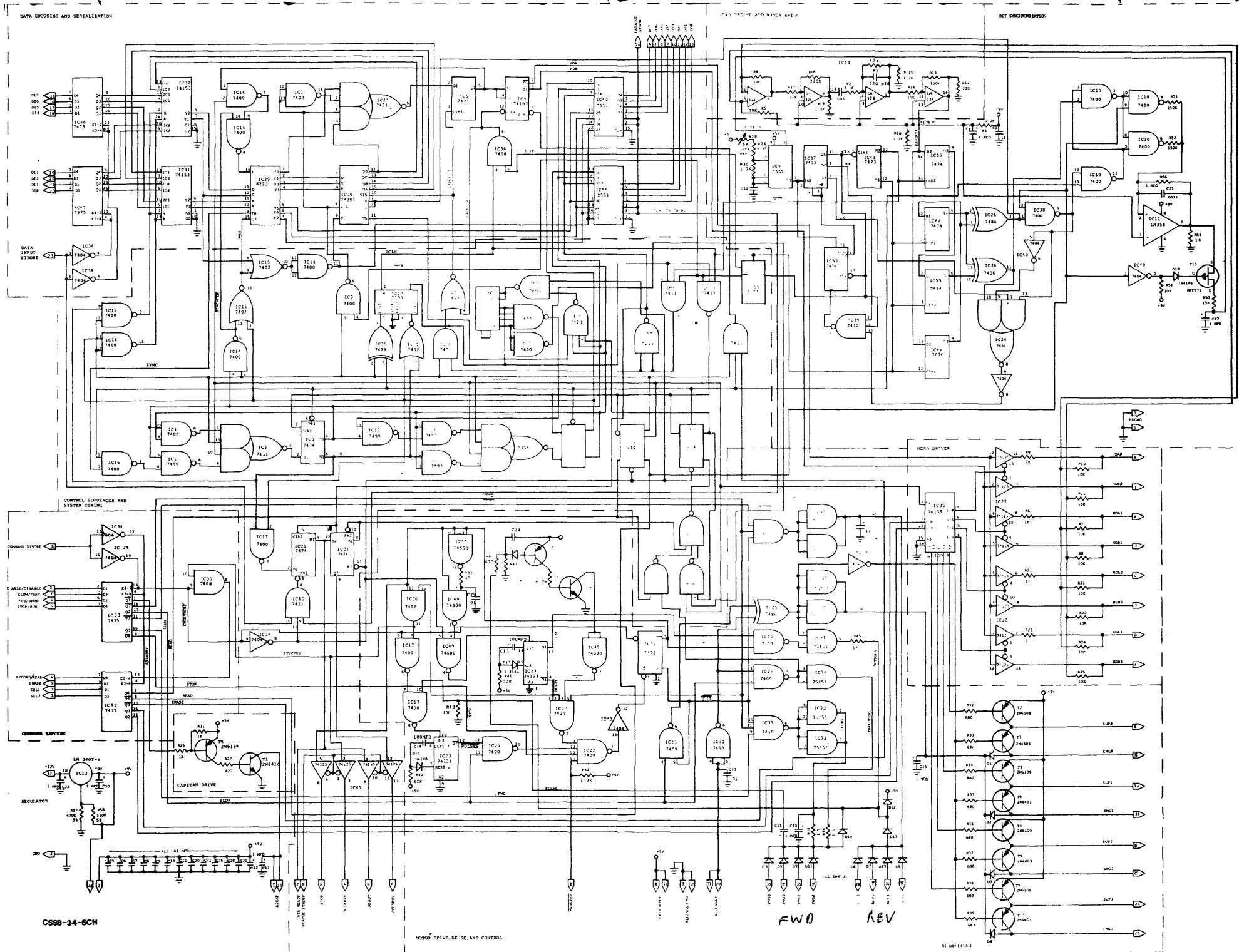


## BIT SYNCHRONIZATION



## CONTROL SEQUENCER AND SYSTEM TIMING





## TWO AND FOUR DRIVE CABINET ASSEMBLY INSTRUCTIONS

### CASSETTE STORAGE CABINET PARTS LIST

NOTE: Parts are subject to change without notice due to supplier availability.

1	Upper Cover	Small parts bag (all cabinets):
1	Lower Cover	2 4-40x1/2" screws
2	Side Rails	2 4-40 nuts
1	Front Dress Panel	12 8-32x1/4" screws
1	Front Panel	2 8-32x1/2" screws
1	Rear Panel	18 6-32x1/2" screws
4	Rubber Furniture Guards	18 6-32 nuts 1 36 pin connector

## TWO AND FOUR DRIVE CABINET ASSEMBLY INSTRUCTIONS

### A. LOWER COVER

1. Locate the 4 holes nearest the corners. These will be used to mount the rubber feet. In addition, the 2 holes near the front lip will also be used to mount two of the drives. To mount a rubber foot, insert one 6-32x1/2" screw into the foot, then through the bottom of the lower cover.

NOTE: The two screws used to mount the front feet are also used to help mount two of the drives and extend up into the cabinet.

2. Position the drives over the remaining holes, then install the 6-32x1/2" screws through the drive legs and through the bottom cover. Do not tighten at this point.

### B. FRONT DRESS PANEL, REAR PANEL AND SIDE RAILS

1. Inspect the side rail and note that there is a small extension on each end. One extension is slightly longer than the other. THE END WITH THE LONGEST EXTENSION IS INTENDED TO GO TOWARD THE FRONT OF THE CABINET. After selecting the front end of each rail, attach each rail to the front and rear panels using eight 8-32x1/4" screws. The two outer-most holes on the rear panel are close to the bottom edge.
2. For two drive models without enclosed controller card and for four drive cabinet models, route the power and control wire cables down the side of the drives and out the round end slots provided in the rear panel.
3. Install the front/rear panel assembly on the lower cover with drives by setting the assembly down over the drives and into position in the lower cover. Pull excess cable through the rear panel. Screw the rear panel to the lower cover using the lower two holes on the rear panel that line up with the bracket on the lower cover. Attach using two 8-32x1/4" screws, no hex nuts required.

298-050 PHI-CAB DOC

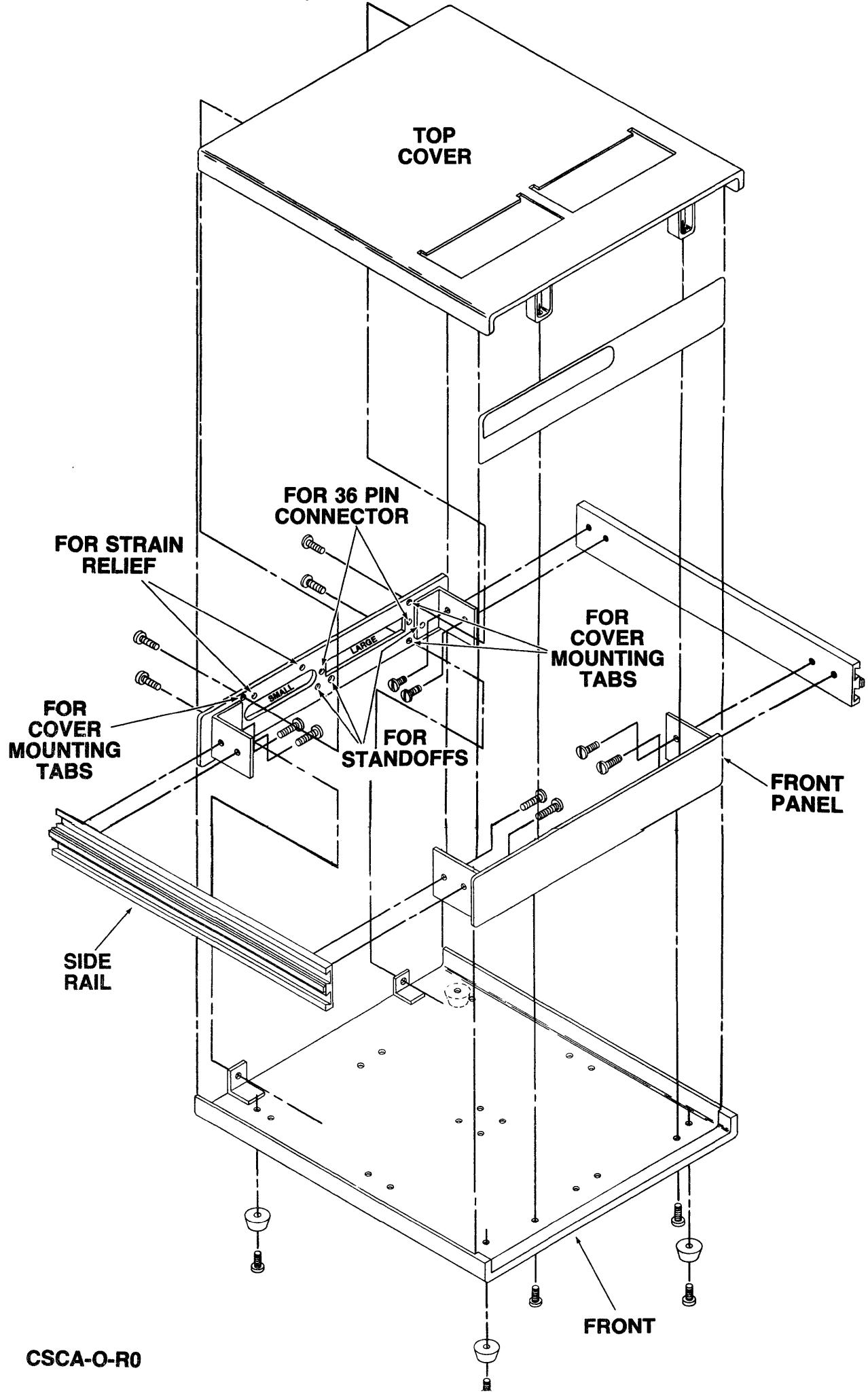
CSCA-0-R0

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C. UPPER COVER

1. Place the upper cover in place over the drives. This job is made easier by removing the plastic cassette cover (plastic door) which simply snaps out of the two hinges. Locate the cover over the drives and adjust the drives to center in the cutouts, then tighten the drive mounting screws.
2. Install two 8-32x1/4" screws through the rear panel at the upper two holes and lock the rear of the upper cover in place.
3. Install two 8-32x1/2" screws through two holes at the front of the cabinet bottom and lock the front of the upper cover in place. Do not over-tighten as these screws will not bottom out automatically. When they are snug, then STOP.



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