M 300 CARD READER

April 1972



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TABLE OF CONTENTS

<u>Title</u>	Page No.
Introduction	1
General	1
Specifications	3
Operation	4
General	4
Initial Setup	4
Loading the Input Hopper	4
Unloading Stacker	6
Switches and Indicators	6
Rear Panel Switches	7
Operational Flow Chart	8
Theory of Operation	9
Card Track	9
Data Recovery	9
Oscillator/Four-Phase Clock Logic	14
Pick Control Logic	14
Sync Control Logic	17
Preset Counter Logic	17
Offset Count/Storage Register	21
Comparator Logic	21
Wide-Strobe Control Logic	23
Character Buffer/Output Logic	23
Column Counter Control Logic	26
Control Logic	26
Motion Check Logic	29
Lamp Drivers	29
Interface	30
General	30
Timing	30
Connectors	33
Signal Characteristics	35
Grounding	35

TABLE OF CONTENTS

Continued

<u>Title</u>	Page No.
Preventive Maintenance	36
General	36
Cleaning	36
Lubrication	38
Repair	39
General	39
Repair Procedures Table of Contents	39
Required Tools	39
Replacement of Main Drive Motor Belt	41
Replacement of Third Stacker Roller Drive Belt	44
Replacement of First and Second Stacker Roller Drive Belts	46
Replacement of First, Second, and Third Stacker Roller Bearing	s 47
Replacement of Solenoid	49
Replacement of Belt on Vacuum Pump Motor Assembly	51
Replacement and Adjustment of Magnetic Pickup	54
Replacement of Read Head, Light Station, Fourth and Fifth Stacker Roller Bearings, or First and Second Picker Roller Bearings	57
To Replace Read Head	60
To Replace Light Station	60
To Replace Fourth and Fifth Stacker Roller Bearings	61
To Replace First or Second Picker Roller Bearing	61
To Replace Picker Casting	61
Replacement of Picker	63
Adjustment of Picker Sector Travel	64
Replacement of Stacker Photocell	64
Replacement of Negator Spring	66
Replacement of Hopper Empty Switch	67
Replacement of Stacker Full Switch	67
Bottom Plate Component Location	68
Electrical Drawings Appe	ndix A
Parts List Appe	endix B
Signal Mnemonics and Abbreviations Appe	endix C

LIST OF ILLUSTRATIONS

Figure No.	<u>Title</u>	Page No
1	Three-Quarter Front View	2
2	Three-Quarter Rear View	2
3	Switch Location	5
4	Operational Flow Chart	8
5	M Series Card Reader Logic Block Diagram	10
6	Timing Relationship for Standard Punched Card	12
7	Oscillator/Four-Phase Clock Logic Block Diagram	15
8	Pick Control Logic Block Diagram	16
9	Sync Control Logic Block and Timing Diagram (Sheet 1 of 2)	18
9	Sync Control Logic Block and Timing Diagram (Sheet 2 of 2)	19
10	Preset Counter Logic Block Diagram	20
11	Comparator Logic Block Diagram	22
12	Wide-Strobe Control Logic Block Diagram	24
13	Character Buffer Storage Logic Block Diagram	25
14	Column Counter Control Logic Block Diagram	27
15	Control Logic Block and Timing Diagram	28
16	Standard Interface Timing for M Series Readers	31
17	Circuit Characteristics	35
18	Removal of Fan Filter	37
19	Solenoid Lubrication	38
20	Three-Quarter Front View	42
21	Three-Quarter Rear View	42
22	Bottom View Mainframe	43
23	Partial View Stacker Drive Train	43
24	Partial View Stacker Drive Train	45
25	Stacker Roller Bearings	48
26	Solenoid	50
27	Three-Quarter Rear View	52
28	Partial View Vacuum Pump Motor Assembly	52
29	Partial View Vacuum Pump Motor Assembly	53
30	Vacuum Pump Belt	53
31	Magnetic Pickup	55
32	Exposed Rear View	55
33	Card Cage Extended	56
34	Timing Disc Air-Gap Adjustment	. 56

LIST OF ILLUSTRATIONS

Continued

Figure No.	<u>Title</u>	Page No.
35	Bottom View Casting Socket Head Screws	59
36	Picker Casting Removed	59
37	Picker Casting Exposed View	62
38	Picker	62
39	Stacker Photocell	65
40	Stacker Assembly Rear View	65
41	Stacker Assembly Front View	67
42	Bottom Plate Component Location	68

INTRODUCTION

GENERAL

This manual provides operational, interface and maintenance information for the M 300 Punched Card Reader manufactured by Documation Incorporated. The manual is sectionalized to cover operational instructions, theory of operation, interface details, preventive maintenance, and repair. The appendix includes electrical schematics and wiring details.

The M 300 Card Reader shown in figures 1 and 2, is designed to read standard EIA 12-row, 80 column punched cards. The hopper capacity is adequate to hold approximately 1000 cards of .007" thickness. These are separated from the stack sequentially and moved past a photo transistor read station where the data is recognized in a serial, column-by-column manner. The cards are then stacked into the output hopper in the same order as they were originally put into the reader. The reading cycle is externally controlled for single card selection or continuous run. In the continuous mode, the reader will read 300 cards per minute.

The M Series card readers are specifically designed for continuous duty operation in adverse operational environments. The chassis is of heavy duty construction and all components have been chosen to provide for rugged, reliable performance. The vacuum-type picker has a remarkable tolerance to mutilated, warped, and edge-damaged cards. The short card track and gentle acceleration forces of the card handling mechanism yield insignificant wear so that card decks routinely last in excess of 1000 passes.

The information contained in this manual is accurate and complete as of the date of publication. Documation will continue to improve both its products and the effectiveness of its documentation. Comments and suggestions as to how this manual may be improved are solicited. Address comments to:

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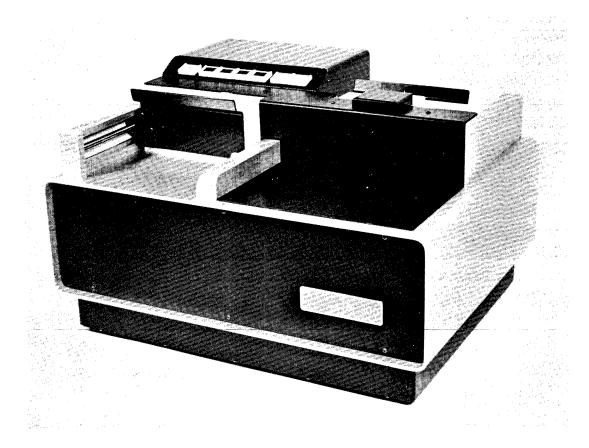


Figure 1. Three-Quarter Front View

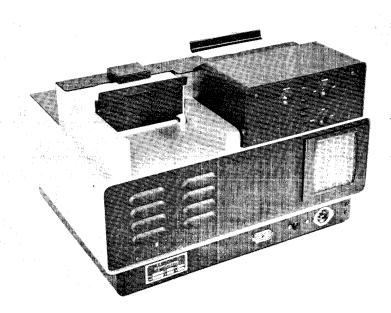


Figure 2. Three-Quarter Rear View

M 300 SUMMARY SPECIFICATIONS

Reading Speed:

300 cards per minute maximum in continuous run.

Single Card Cycle: 200 milliseconds.

Card Type:

Standard 80 column EIA card.

Control:

Demand feed, one card-at-a-time under external

program control. Reader will continuous run as

long as the Pick Command remains TRUE.

Hopper Size:

7.25 inches (approximately 1000 cards of 7 mill

thickness).

Stacker Size:

7.25 inches (approximately 1000 cards of 7 mill

thickness).

Power Requirements:

Voltage:

115 VAC \pm 15V, single phase, @ 60 hz (standard model)

230 VAC ± 30 V, single phase, @ 50 hz (export model)

Power:

1350 VA starting load for 3 sec

400 VA running load

Size:

Height:

13 9/16 inches

34.4 cm

Width:

23 1/16 inches

58.6 cm

Depth:

18 inches

45.7 cm

Weight:

76 1bs.

34.4 Kg

OPERATION

GENERAL

The following paragraphs provide description and instructions for normal operation of the M Series Card Readers. All operator controls and indicators are described with turn-on/shut-down instructions included. Refer to figure 3 for the location of switches and indicators mentioned in the following description.

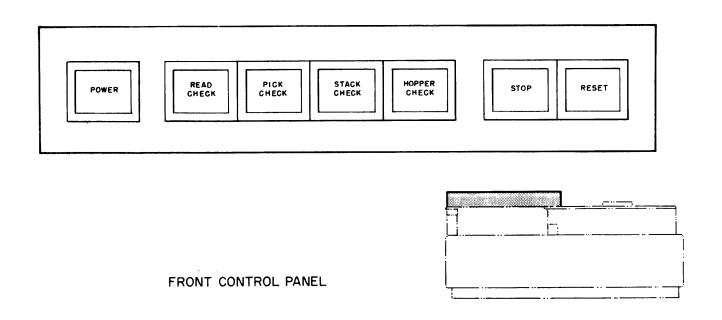
INITIAL SET-UP

- 1. Upon receipt of a new reader from the manufacturer, the two <u>red</u> 8-32 screws in the bottom plate must be removed. These lock the blower motor plate for shipment to prevent damage to the motor plate vibration isolators. If the reader is to be reshipped, these screws should be retained and reinserted prior to packing.
- 2. Plug in the AC power cord. Notice that this is a clockwise twist-lock connector.
 - 3. Switch the circuit breaker (rear base panel) to ON.
 - 4. Set the MODE switch (rear panel) in LOCAL.
 - 5. Set the SHUTDOWN switch (rear panel) in AUTO.
- 6. Press the POWER switch to energize the reader (blower will not come on at this time).
- 7. Press the LAMP TEST switch and observe that all front panel indicators illuminate.
 - 8. Load a deck of cards into the input hopper.
- 9. Press the RESET switch. The blower should come on and after a short delay (approx. 3 seconds), the cards should be picked and stacked. When the input hopper is empty, the blower should shutdown and the HOPPER CHECK light illuminate.
 - 10. This completes the initial off-line operational test.

LOADING THE INPUT HOPPER

Loading the input hopper with punched cards to be read is performed as follows:

1. Pull the hopper follower back with one hand and load the card deck into the hopper area; the first card to be read must be placed at the front with the "9" edge down, column 1 to the left. Continue placing cards into the input hopper until it is loosely filled (approximately 1000 cards).



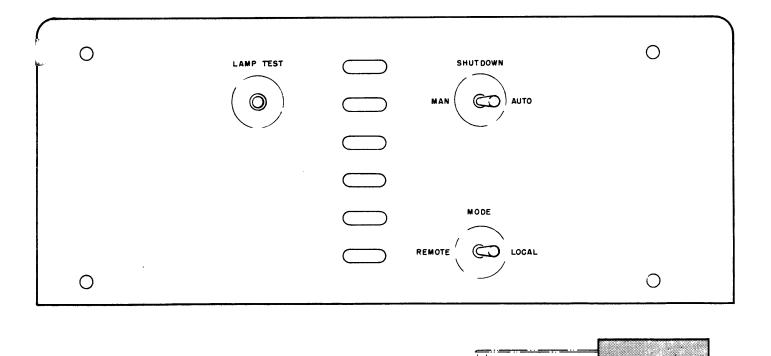


Figure 3. Switch Location

REAR PANEL

CAUTION

DO NOT PACK THE INPUT HOPPER SO FULL THAT THE RIFFLE ACTION IS INHIBITED

- 2. The hopper may be loaded while cards are being read if the operator is careful to keep tension on the front portion of the deck while loading additional cards at the rear. This is best done with the input hopper approximately $\frac{1}{2}$ to 1/3 full. Use just enough pressure to maintain the riffle action.
- 3. Unloading the input hopper is the reverse of the loading procedure. Normally all cards are processed through the reader; however, if it is necessary to unload the hopper, push the follower down and remove the card deck. If the cards are arranged in a particular order, exercise care in repacking them in their storage container so that the order is maintained.

UNLOADING STACKER

To unload the stacker, perform the following steps:

- 1. Pull stacker follower back with one hand and remove the front or rear portion of the card deck from the stacker area, being careful that deck order is maintained.
 - 2. The stacker may be unloaded while cards are being read.

SWITCHES AND INDICATORS

POWER (toggle circuit breaker and indicator)

All power to the card reader is controlled by this circuit breaker. Since the indicator is supplied by the +5V power supply, it is illuminated only when power has been applied to the entire AC distribution system. Toggling the switch (indicator is illuminated) in down position removes the power from the card reader.

STOP (momentary-action pushbutton/indicator switch)

Actuation of the STOP switch immediately overrides the PICK COMMAND and lowers the READY line. The card reader will stop operation after the card currently in the track is read completely; power is not removed from the reader by this action. The red STOP indicator is illuminated as soon as the switch is depressed.

RESET (momentary-action pushbutton/indicator switch)

Actuation of the RESET switch clears all error flip-flops and initializes all counters. The reset action is initiated by the return stroke of the RESET switch. The green RESET indicator is the READY signal that also appears at the output connector. The card reader is then ready to accept a PICK COMMAND.

READ CHECK (indicator)

The READ CHECK alarm indicator denotes that the card just read may be torn on the leading or trailing edges or have punches in the 0 or 81st columns. The READ CHECK will cause the reader to stop. If it occurs on all cards, it is an indication of a fault in the read electronics.

STACK CHECK (indicator)

The STACK CHECK alarm indicator denotes that the previous card was not fully seated in the output hopper. Check the card track to make sure it is clear and check the stacker for a badly mutilated card.

PICK CHECK (indicator)

The PICK CHECK alarm indicator denotes that a card has failed to reach the read station after a PICK COMMAND has been received. Inspect the cards in the input hopper for excessive leading edge damage, torn webs, or cards stapled together. If so, remove the staple or straighten the card and reinsert.

If no apparent card damage is present, check for excessive card deck warpage (in excess of 1") and/or ink glaze buildup on the picker face. Clean the picker face with solvent.

HOPPER CHECK (indicator)

The HOPPER CHECK alarm indicator denotes that either the input hopper is empty or the stack hopper is full. This is a normal operational occurrence.

REAR PANEL SWITCHES

LAMP TEST (pushbutton switch)

Depressing the LAMP TEST switch illuminates all front-panel indicators to determine if an indicator lamp is inoperative.

MODE (toggle switch)

When placed in the LOCAL position, this switch disables the PICK COMMAND input to the card reader and allows the operator to run the reader off-line by depressing the RESET pushbutton switch on the front panel. When placed in the REMOTE position, this switch enables the PICK COMMAND input to the card reader, which places the reader on-line for normal remote control operation. Data and other output signals are present at all times.

SHUTDOWN (toggle switch)

When placed in the MANUAL position, this switch energizes the blower for continuous operation whether or not cards are in the input hopper. When placed in the AUTO position, this switch provides an automatic shutdown of the blower

when the input hopper is emptied. The blower will automatically restart when cards are placed in the hopper and the RESET switch is depressed. Expect a delay of approximately 3 seconds for the blower to run up.

OPERATIONAL FLOW CHART

Figure 4 shows a flow chart of the sequence of events which may be encountered in operating the reader. If trouble is experienced, refer to this check list before calling for maintenance.

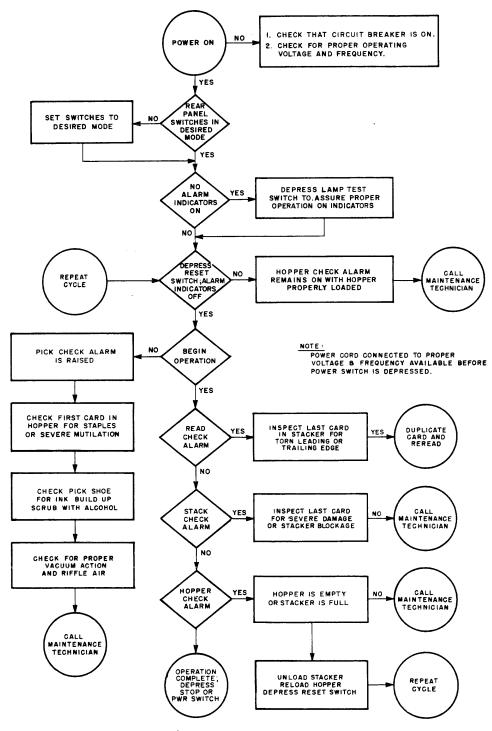


Figure 4. Operational Flow Chart

THEORY OF OPERATION

CARD TRACK

The Documation card reader line is unique in several respects, in that card wear is insignificant and a card jam is virtually an impossibility. The card track is designed around a patented vacuum picker which works in conjunction with riffle air in the input hopper to produce a card reader which is very tolerant to damaged cards. This tolerance extends to cards which have been badly worn, edge nicked, warped, bent, folded or otherwise damaged as a result of rough handling.

The riffle air acts on the first half inch of cards in the input hopper so that they stand apart, individually "air cushioned" from the rest of the card deck and each other. This prevents the cards from sticking together in case of static electricity, hole locking, or torn webs. Should the cards have been subjected to high humidity conditions prior to being loaded into the card reader, the riffle air also minimizes the effect of swelling or frictional increases between the cards.

The picker mechanism utilizes a strong vacuum to grasp the bottom card, and upon command, draw it away from the bottom of the stack. The card is smoothly accelerated through the wide throat into the constant speed drive rollers. The design of the vacuum picker and its associated throat block prevent the unit from double picking so well that cards which are even stapled together will not enter the card track. Should cards which are stapled or taped together be inadvertently put in the input hopper, the card reader will stop, indicating a FICK CHECK. The operator can remove the staples, separate the cards, reenter them in their proper position in the deck and resume reading.

The card track itself is very short so that at no time is more than one card in motion. The combination of damaged card tolerance, gentle card treatment and short card track have produced a card reader which is virtually jam proof. Card life has proven to be in excess of 1000 passes.

DATA RECOVERY

The logic block diagram for the M Series card reader is shown in figure 5. The description that follows applies to all Documation M Series punched card readers since the reliable recovery of data from cards passing down the card track is accomplished in the same manner regardless of track velocity.

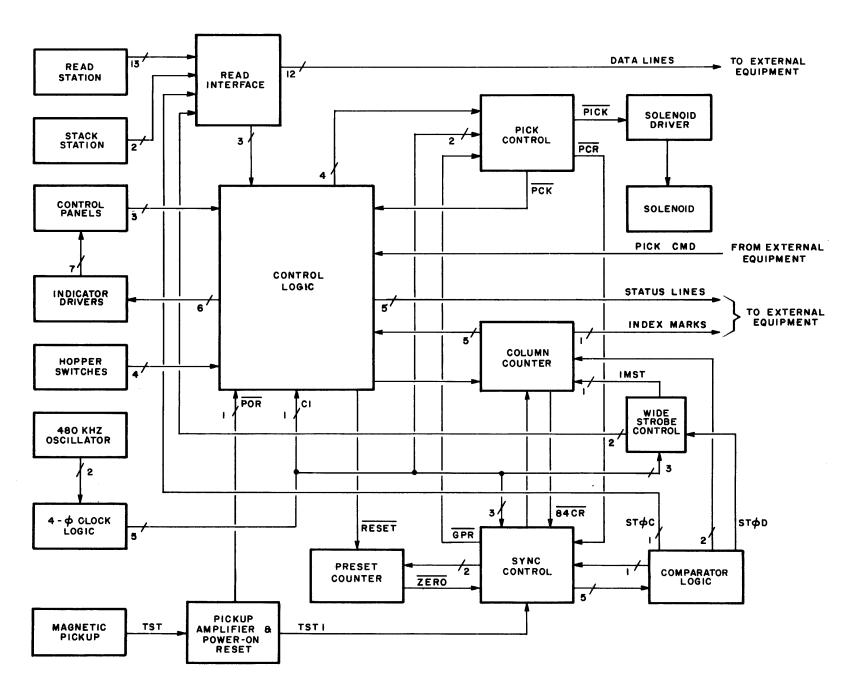


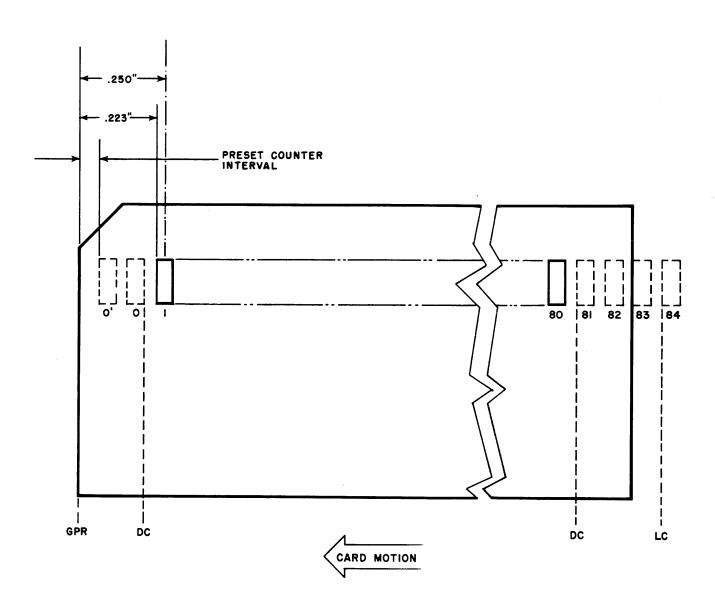
Figure 5. M Series Card Reader Logic Block Diagram

The heart of the card reader electronics is the control logic and sync control, where the internal logic timing and the movement of the card past the read station is synchronized to enable accurate sequential interpretation of the data on the card. Primary logic timing is established by the 480-KHz crystal oscillator and the associated four-phase clock logic, whose outputs are used to shift, store, and control other timing operations. Card movement speed is established by the hysteresis synchronous drive motor, belts and steel drive rollers. A timing disk consisting of a ferrous notched wheel is mounted on the drive roller shaft. Synchronization input to the logic is derived from the magnetic reluctance pickup associated with this timing disk. Sufficient resolution is provided such that two signals are produced by the pickup for each card data column as it is moved through the card track at the track speed of the particular M Series reader being used.

When a PICK COMMAND is received from the external program control, card processing will be started provided no alarm conditions exist with the card reader powered up. The Pick Control logic then produces a PICK signal to the Solenoid Driver, a PCLK signal to the control logic, and a pick-command reset (PCR) to the sync control. These actions initialize the various control circuits and energize the solenoid to pick a punched card from the input hopper. If a card does not reach the read station, the PICK CHECK alarm is raised.

The read station and stack station utilize phototransistor sensor arrays to both read the card hole pattern and to monitor card movement. When a card is picked and moved into the card track, the leading edge is detected by the first phototransistor in the read station to go dark. This produces a Good Pick Reset (GPR). As the card continues to move past the read station, the various control circuits are synchronized with the card movement to enable interpretation of the column data contained in the card hole patterns and to output this data at the same timing point for each of the 80 columns.

Since GPR is generated by the leading edge of the card, its occurrence is also utilized to start the synchronization process necessary for the precise generation of the data column strobes. At GPR, the Preset Counter is enabled to produce an interval equivalent to the time it takes the card to move 0.049 inches. The value of this preset interval is different for each reader model and is hard-wired into the counter. Its value establishes the time that should elapse from the detection of the leading edge of the card to the occurrence of the first possible data column 0' (see figure 6). The first two data holes



NOTES:

- (1) DASHED LINES INDICATE PSEUDO HOLES IN CARD.
- (2) DC = DARK CHECK LC = LIGHT CHECK GPR = GOOD PICK RESET
- (3) HOLE SIZE EXAGGERATED FOR EXPLANATION.

Figure 6. Timing Relationship for Standard Punched Card

are actually pseudo-columns, since by EIA standard, no data appears in the first 0.223 inches of the card.

When the Preset Counter ZERO signal is produced, indicating the end of the preset period and the start of card data columns, the Offset Count is set to synchronize the card reader logic to the signals from the magnetic pickup. This offset is the value of the count accrued during the time from the beginning of pseudo-column 0' to the second occurrence of a signal from the timing disk (TST). Refer to page 21, paragraph OFFSET COUNT/STORAGE REGISTER for the detailed discussion. Once established, this relationship will remain constant for the rest of the data columns on that card. Since two TST pulses are provided for each data column, every second TST pulse starts the Offset Counter in the comparator which counts until it matches the value of the Offset Storage. Thus, the offset value is determined and stored at the beginning of each card, then utilized to establish the same data-read point for each of the 80 data columns on that card. Since each offset comparison is derived from the timing disk signal (TST), the strobes are hence precisely locked to the progress of the card past the read station. This synchronization is accomplished within the comparator logic, which produces the strobe signals. Figure 6 shows the basic punched card with its relation to GPR, pseudo holes, and data column holes.

The STØC signals from the comparator logic are counted by the Column Counter to produce the character-count strobes, index-marker strobes, and light/dark-check strobes required for each card. The STØD is used to start the Wide-Strobe Control logic, which establishes the timing point for the index marker strobe (the spacing of the index markers will vary according to the speed of the model being used); the Wide-Strobe Control logic also produces the column data enables that are used to store data for each column into the storage registers in the interface logic. The index marks and the twelve data lines are then made available to the external equipment via the output/interface connector (J2).

This summarizes the function accomplished by the logic circuits supplied with each card reader. The following sections describe each operational block in more detail. The reader should familiarize himself with the various signal mnemonics used in the text description since it will aid in interpreting the detailed logic schematics contained in the appendix.

OSCILLATOR/FOUR-PHASE CLOCK LOGIC

A general block diagram and timing diagram of the Oscillator/Four-Phase Clock logic is shown in figure 7. The oscillator is a 480-KHz, crystal-controlled clock assembly manufactured by Motorola with TTL compatible outputs. The two-stage control register divides the oscillator output by four and provides phasing to the control gates. These gates are then strobed by the inverted clock signal to produce the four phases of output clock for internal timing as one-microsecond wide signals, shifted by approximately one microsecond from each other. The C1 clock is the inverted output of one flip-flop in the two-stage control register and is a symmetrical squarewave approximately 8.33 microseconds wide (120 KHz frequency).

PICK CONTROL LOGIC (Sync Card)

The function of the Pick Control logic (figure 8) is to:

- 1. Receive the clocked pick command (PCLK) from the control logic
- 2. Generate the solenoid drive pulse (PICK)
- 3. Wait out the interval while the card leading edge is accelerated to the read station (between 14 to 27 ms)
- 4. If the leading edge has not arrived in 50 ms, generate another solenoid drive pulse $(\overline{\text{PICK}})$
- 5. Repeat the pick attempt six times and if the leading edge has not appeared, generate a pick fail alarm (PSET).

When the external program PICK COMMAND is received after power-on reset (POR) has occurred and if no alarm condition exists (READY line raised), the control logic initiates the pick sequence by gating the C1 clock to produce PCLK. The PCLK signal is counted by two decade counter stages and a six-stage binary counter in the Pick Control logic. Decode gates are provided to set and later reset a solenoid control FF generating a timed solenoid drive pulse (PICK), which energizes the pick solenoid to move the bottom punched card into the card track.

If the <u>card</u> is not picked, the six-stage binary counter continues to receive the \overline{PCLK} signal and after approximately 50 ms rolls over to begin another up-count. This recycles the solenoid control FF through its set/reset sequence and produces another pick attempt. Each solenoid drive signal is counted by a three stage binary counter and after \underline{six} complete pick attempts, an alarm signal (\overline{PSET}) is generated to disable the pick control and indicate a PICK CHECK.

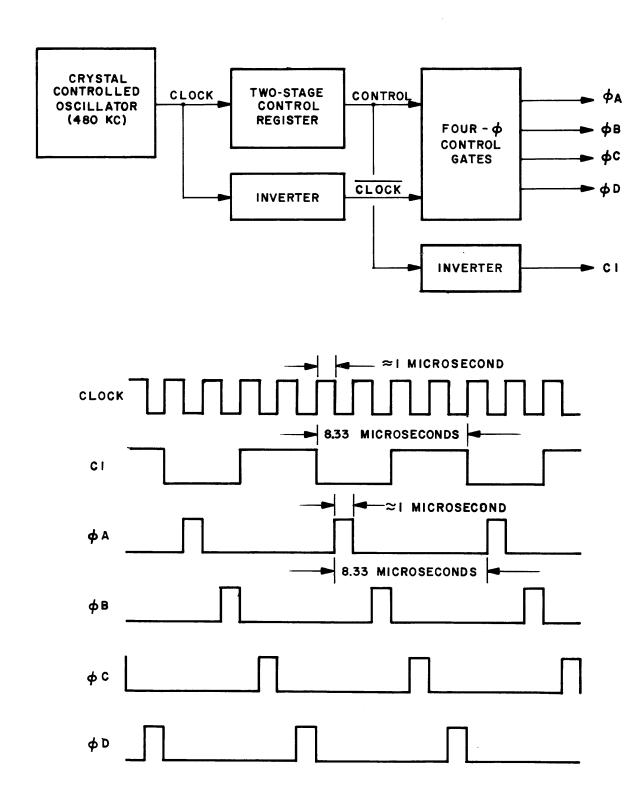
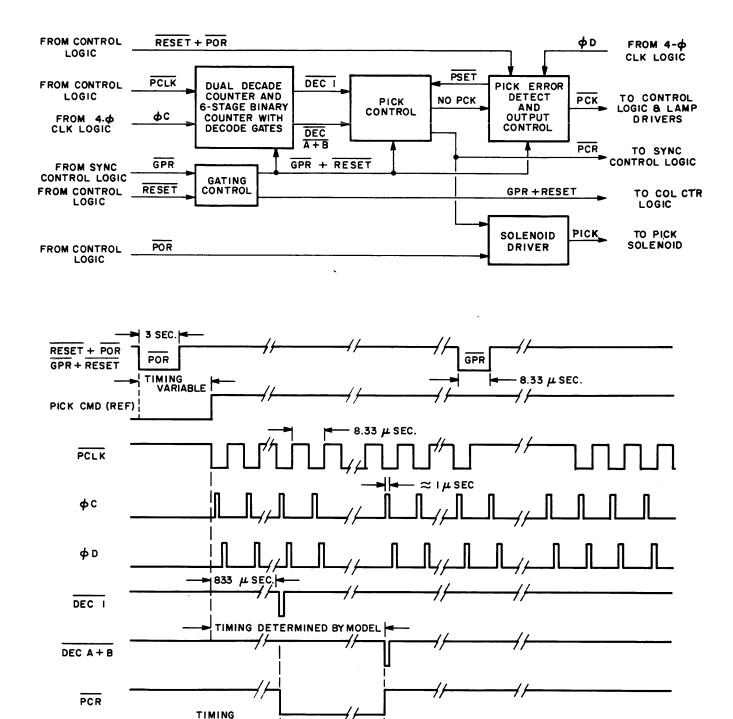


Figure 7. Oscillator/Four-Phase Clock Logic Block Diagram



NOTE: TIMING NOT SHOWN TO SCALE.

DETERMINED BY MODEL

PCD

GPR

84CR (REF)

Figure 8. Pick Control Logic Block Diagram

TIMING DETERMINED BY MODEL-

TIMING DETERMINED BY MODEL

If a card is picked at any time before the end of the sixth attempt, a Good Pick Reset (GPR) is produced to reset the Pick Control logic counters until the end of the read cycle for the picked card. The GPR pulse is generated when the leading edge of a card first reaches the read station. The end of the read cycle is defined as the 84th pseudo-column (84CR) passing the read station (see figure 6). The 84CR signal, generated by the Column Counter logic, enables the PCLK to be started again if the external program PICK COMMAND is still present and the READY line is still raised. The above cycle repeats until all cards in the input hopper have been processed or until an error condition occurs.

SYNC CONTROL LOGIC

The Sync Control logic (figure 9) provides data readout synchronization from the timing disk. The timing disk is mounted on the same shaft as the first capstan roller. This capstan roller engages the card as it is released by the picker and thereafter determines the speed at which the card will be moved through the card track. The asynchronous card pick sequence causes the card to arrive at the read station at an arbitrary time in relation to the timing disk. The edge of the ferrous alloy timing disk is provided with gear-type serrations such that two flux reversals occur for each column of data on the card moving down the card track. These are sensed by the magnetic pickup and its associated amplifier to produce two TST1 signals for each column of data.

From figure 6 it can be seen that the first one-quarter inch of a punched card, (which contains no data per EIA standard) could have two data columns punched into it. The M Series reader logic assumes the presence of these columns as if they do exist and they are called column 0' (first pseudo-column occurring after the leading edge) and column 0 (second pseudo-column).

PRESET COUNTER LOGIC

The TST1 signals produced by the timing disk pickup amplifier are gated with the internal logic clock to produce the TST2 signals as positive-going, 8.33-microsecond output pulses that are phased to \emptyset C of the four-phase clock. When GPR occurs, the PRCLK signal is started by the store and offset control logic circuits. This clock signal is used to drive the Preset Counter logic. See figure 10. The Preset Counter is used to produce the delay necessary while the card moves the distance from the leading edge of the card to the beginning of pseudo-column 0'. This value is different for each track velocity used in the various M Series card readers. The occurrence of the GPR signal is used

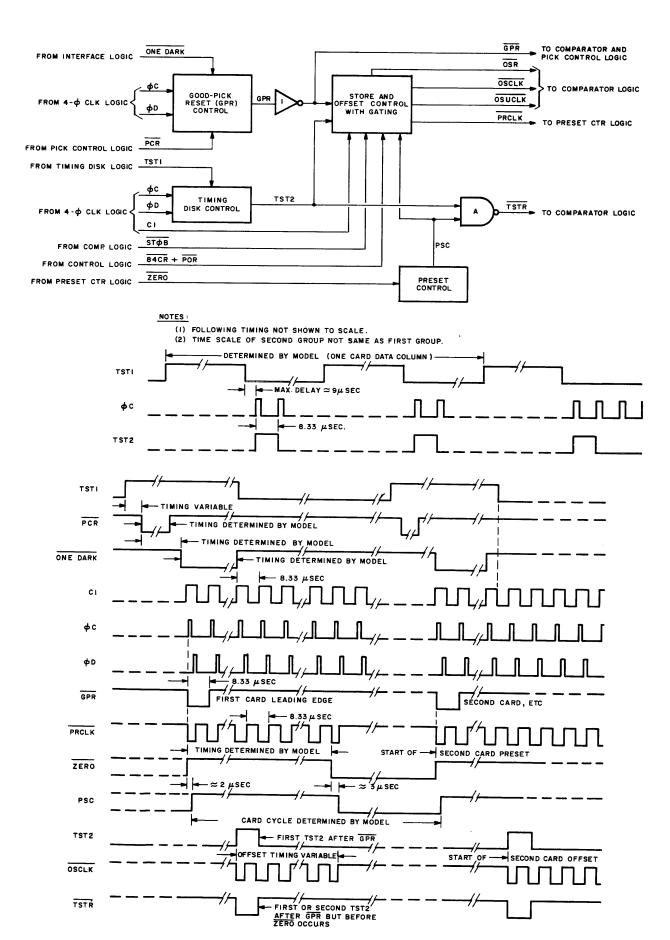
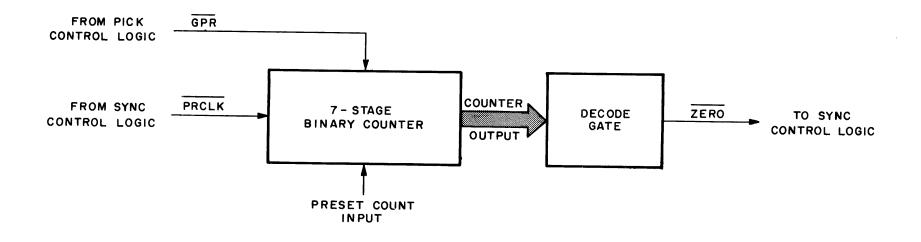


Figure 9. Sync Control Logic Block and Timing Diagram (Sheet 1 of 2).

19

Figure 9. Sync Control Logic Block and Timing Diagram (Sheet 2 of 2)



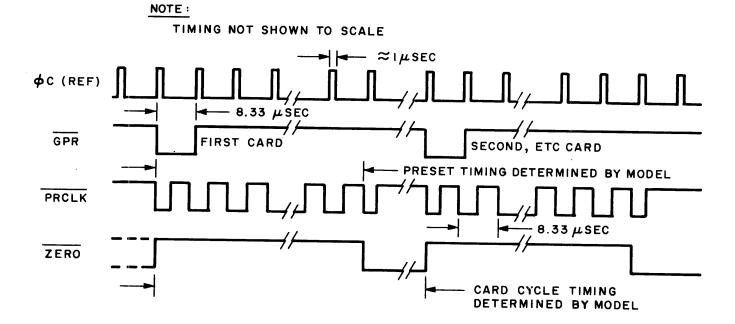


Figure 10. Preset Counter Logic Block Diagram

to "jam" set a hard-wired binary value into the Preset Counter and then when PRCLK is enabled, the counter counts up to all one's. This ZERO value is detected and defines the beginning of pseudo-column 0'.

OFFSET COUNT/STORAGE REGISTER

Since the leading edge of the card may arrive at the read station at an arbitrary time in relation to the TST signals, it is necessary to determine this "offset" so that later data column strobes generated from the occurrence of the TST1 signals will continue to be offset by the same amount for all 80 columns of that particular card. It should be noted that this offset interval between TST and the data column strobes will be different for each <u>successive</u> card, but is constant within each card.

The first TST2 after GPR starts the OSCLK signal, which is used to trigger the offset storage counter. These circuits count and store the time interval between the TST2 signal and the end of preset interval (i.e., beginning of pseudo-column 0'). If two TST2 signals occur before the preset timing is complete (as indicated by generation of $\overline{\text{ZERO}}$), the second TST2 resets the Offset Counter and its counting begins again (i.e., the shortest time interval between TST2 signals and end of preset timing is always selected). This "offset" interval is the synchronizing point that establishes the beginning of each of the remaining 80 data columns on that particular card.

The initialization reset for the Offset Counter is produced by TSTR, which is generated by the first and/or second TST2 signal after GPR but before ZERO occurs. After the preset timing ZERO is produced, the PRCLK, OSCLK, and TSTR circuits are inhibited until the next GPR is generated; however, the second, fourth, sixth, etc., TST2 signal after ZERO is used to produce the OSR and OSUCLK signals. These two signals enable the Offset Comparator circuits to reproduce a time interval equal to the original offset count for each of the 80 columns of data in a punched card. In turn, this synchronizes various timing strobes within the card reader to allow for stable recovery of the data in each card column.

COMPARATOR LOGIC

As explained above, the Comparator Logic (figure 11) stores the offset interval and uses its value to generate the 80 data column strobes and index marks for external equipment synchronization.

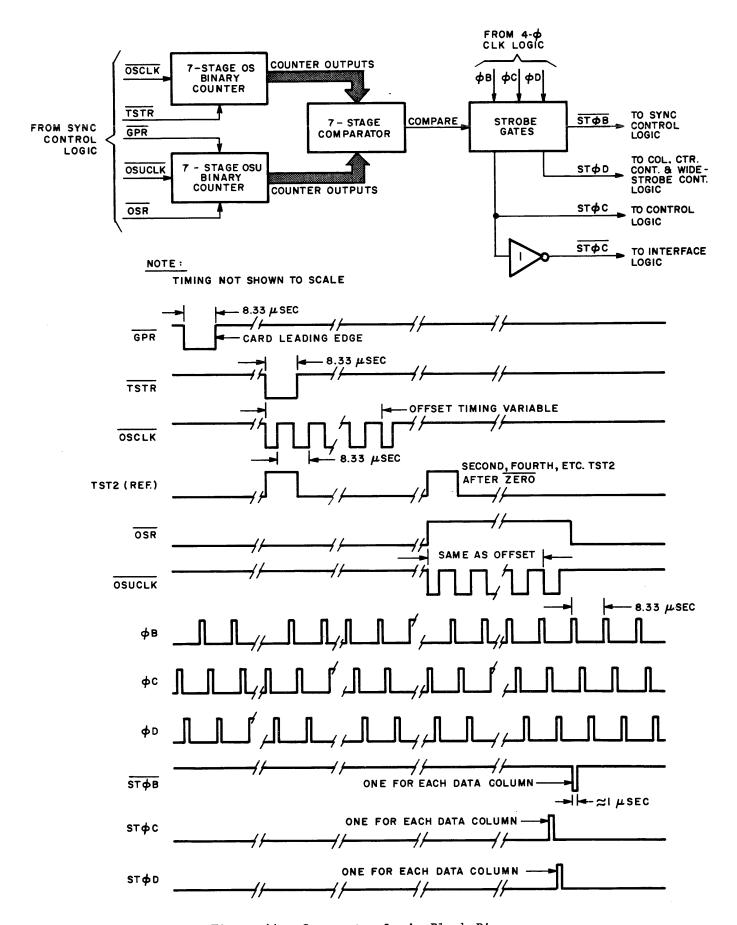


Figure 11. Comparator Logic Block Diagram

The OSR signal, which is raised by the second, fourth, etc., TST2 signal after the ZERO detect point occurs, allow the Offset Counter to be up-counted by the OSUCLK signal from sync control. A seven-stage, parallel comparator circuit recognizes when this count has equalled the binary value stored in the seven-stage offset counter. This up-count interval is regenerated 80 times as the card moves past the read station. Hence, by using this technique of reestablishing the value of the offset interval at the beginning of each card, the 80 data strobes are able to readjust for the arbitrary leading edge arrival.

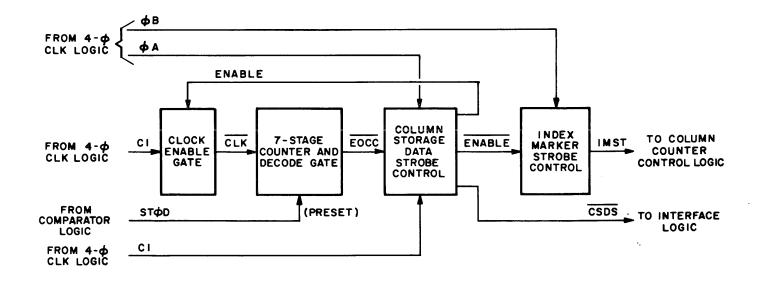
The output of the comparator logic is a sequence of four pulses which actually initiate the various strobe actions. These are derived from the fourphase clock as follows: $\overline{ST\emptyset C}$ occurs first, followed by $\overline{ST\emptyset D}$, $\overline{ST\emptyset A}$, and $\overline{ST\emptyset B}$ ($\overline{ST\emptyset B}$ is used to reset the compare cycle).

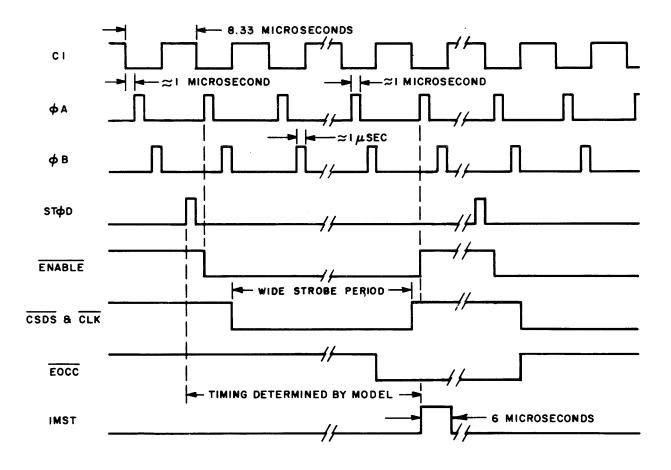
WIDE-STROBE CONTROL LOGIC

The Wide-Strobe Control logic (figure 12) is used to produce the index marker strobes (IMST) and the column storage data strobe (CSDS). The STØD signal, generated by the comparator logic, presets a seven-stage counter to a binary value determined by the card reader model. The counter then counts to all ones and in so doing, opens the Character Buffer gates for a time interval controlled by the hard-wired binary value. During the count cycle of the counter, any TRUE signals from the 12 read station sensors will be stored into the latch-type storage registers of the Character Buffer. At the end of the count cycle, the index marker strobe control circuits produce the six-microsecond wide IMST signal, which is routed through the column-counter logic to produce the Index Marks for external equipment synchronization. This insures that the data for the particular column being read is stored properly, allowing transients to settle out before the Index Mark is transmitted.

CHARACTER BUFFER/OUTPUT LOGIC

The output of the 12 phototransistor sensor arrays is gated to the Character Buffer by the wide strobe signal ($\overline{\text{CSDS}}$) as described above. Any TRUE level received from the read array during the duration of this $\overline{\text{CSDS}}$ enable will be stored and will appear on the output line. It will remain until the Character Buffer is reset by the $\overline{\text{STØC}}$ signal. Refer to figure 13 for the block diagram and timing relationships. It is important to note that data is only guaranteed to be present from the trailing edge of the $\overline{\text{CSDS}}$ pulse to a point shortly before $\overline{\text{STØC}}$. The guarantee period is different for each reader model and even though a generous delay is guaranteed, it is good practice to accept the data as soon as offered by

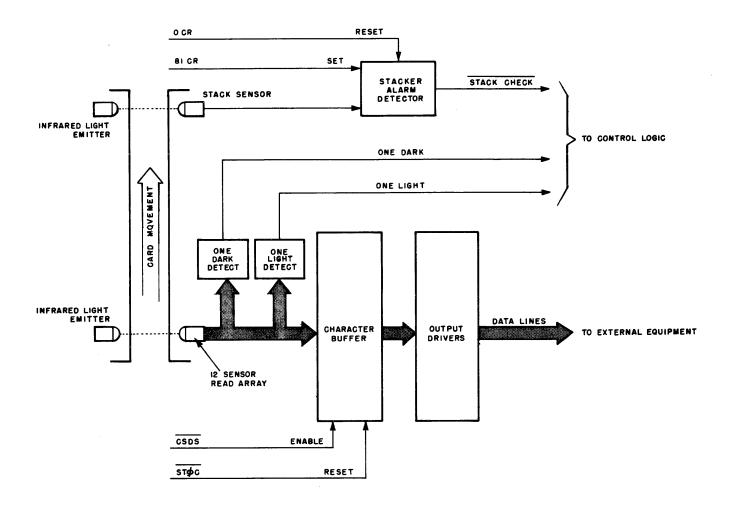




NOTES:

- (1) STOD SYNCHRONIZED TO CARD DATA COLUMNS.
- (2) TIMING NOT SHOWN TO SCALE.

Figure 12. Wide-Strobe Control Logic Block Diagram



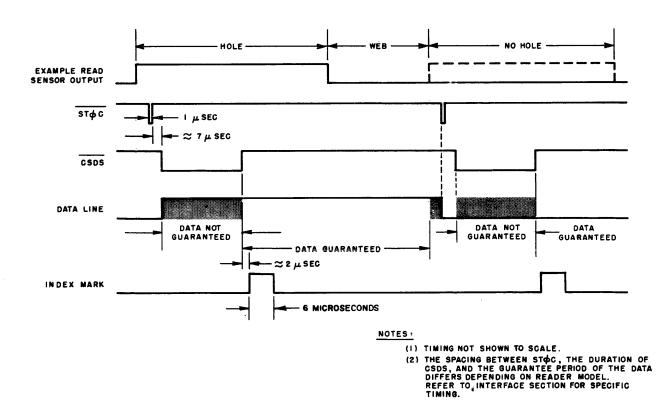


Figure 13. Character Buffer Storage Logic Block Diagram

the Index Mark. Either the leading or trailing edge of the Index Mark (IM) may be used to accept the data. The data signals will have settled by the occurrence of IM.

The ONE LIGHT and ONE DARK signals are derived if any <u>one</u> sensor goes light or dark. These signals are sent to the Control logic where they are interrogated at the proper time (see figure 6) to establish that the card does not have leading or trailing edge tears (Dark Check) and that the sensor array is responding to its stimuli properly (Light and Dark Check).

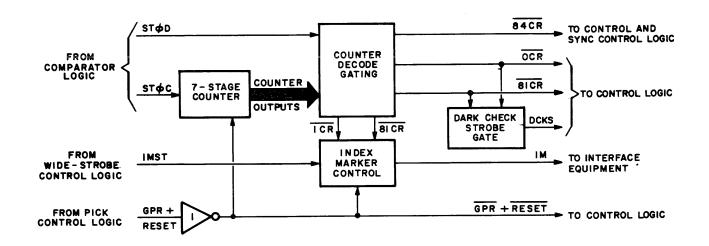
COLUMN COUNTER CONTROL LOGIC

The Column-Counter Control logic (figure 14) is initialized by GPR to begin counting the number of data columns read as the card moves past the read station. The seven-stage binary counter is triggered by STØC, which is synchronized to the data column of a card. The counter decode gating recognizes OCR (pseudo-column 0) and 81CR (pseudo-column 81) to produce the two dark checks (DCKS). This provides the dark check of the read station at the beginning and end of the card being read. The counter decode gating circuits also detect 1CR (enable) and 81CR (disable) to control the Index Marker generation. The 84CR count recognition is used to initiate the Light Check and to indicate the end of the read cycle. This signal also re-establishes the readiness of the card reader to accept the next pick command (provided no alarm conditions have occurred for the card being processed).

CONTROL LOGIC

The Control logic (figure 15) contains the error alarm detection circuits, ready-condition detect circuits, and pick control and gating circuits.

The Pick Check control circuits signal the fact that a card has been picked (i.e., no PCK alarm signal has occurred), to the Read Check Control logic. Unless two successful Dark Checks are received, an automatic Dark Check alarm is generated. In like manner, a successful Light Check must be received prior to the 84CR (end of card read cycle) to prevent a READ CHECK. In other words, a READ CHECK is not generated when this logic senses the successful occurrence of two dark checks (0th pseudo-column and 81st pseudo-column), and that a successful light check has occurred prior to the generation of 84CR.



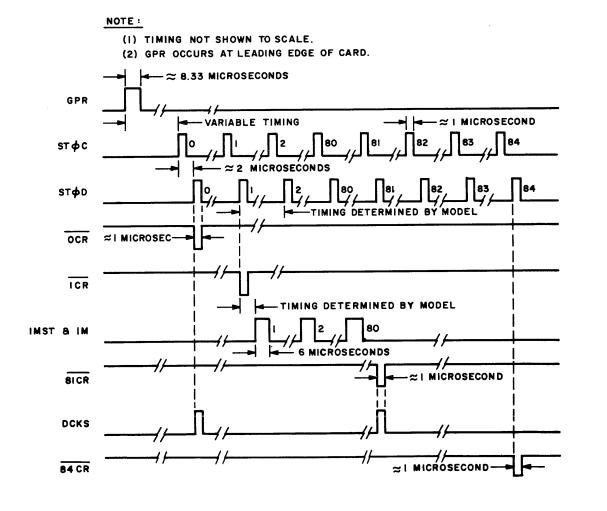


Figure 14. Column Counter Control Logic Block Diagram

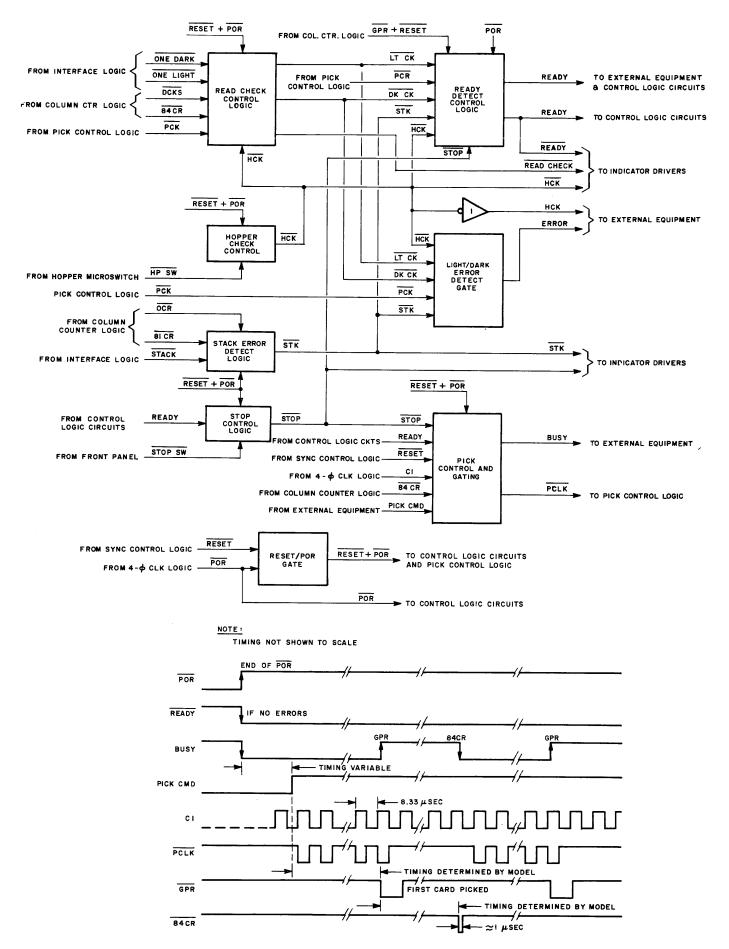


Figure 15. Control Logic Block and Timing Diagram

The Error Detect gate recognizes a data error condition from any of the above detect circuits and provides an ERROR signal to the external equipment. Simultaneously the particular alarm condition indicator on the card reader front control panel is illuminated. The Hopper Check Control circuits utilize the microswitch in the riffle cap to sense when the hopper is empty of cards. Another microswitch in the stacker follower assembly senses when the output stacker is full of cards. Either of these conditions will generate the $\overline{\text{HCK}}$ alarm.

The Stop Control logic detects the fact that the STOP pushbutton switch on the card reader front control panel has been depressed or that a light/ dark check error has occurred to lower the READY line. The Ready Detect control logic utilizes the fact that no alarm conditions exist to raise the READY line for external program control and internal control use. The READY line is lowered at the instant of error detection but the card reader operation is not stopped until after the present card is processed completely.

MOTION CHECK LOGIC

The stack check sensor (see figure 13) is located at the exist of the card track and detects that the tail of a card is clear of the card track (hence, fully seated in the output stacker). The Stack Alarm logic is designed to test that the stack sensor made a dark-to-light transition (i.e., track clear) between the time a 81CR signal occurs (card tail leaving the read station) and the OCR signal of the next card. Should this transition not have taken place, a STACK CHECK alarm is generated. This signal is combined with the Pick Check alarm to generate a MOTION CHECK alarm to the external equipment should either condition occur. The card reader is stopped and the READY line goes FALSE.

LAMP DRIVERS

The lamp drivers amplifiers provide the current drive for the alarm indicators on the front control panel. The LAMP TEST input to the lamp driver circuits enables the output drivers for all indicators simultaneously, providing the operator with a rapid check to determine that all #328 bulbs are good.

INTERFACE

GENERAL

This section covers the interface between the M Series punched card readers and the equipment into which it transfers data.

TIMING

In interfacing the M Series card readers to an external system or card reader controller, the designer should appreciate that three separate categories of interface signals are being dealt with. The first are the signals which control and report the status of card processing, the second are the data signals themselves with their associated index marks, and the third are the various alarm signals provided. In the description following, the designer should refer to the timing diagram shown in figure 16.

Pick Control

The PICK COMMAND initiates the card read cycle, and depending upon its duration, the card reader will either continuous run or operate in a card-at-a-time mode. This signal can be presented to the reader at any time, but the reader will only accept it when the READY line is TRUE. The READY signal indicates that the card reader is cleared of errors and is ready to receive a PICK COMMAND from the external program control. A visual indication of the READY line is the green RESET indicator on the front control panel.

The conditions which must be present for the READY line to be TRUE are:

- 1. Power applied and the 3 second run-up completed.
- 2. The input hopper has been loaded.
- 3. Depressing the RESET pushbutton switch will bring the READY line TRUE.

Should all of the above conditions be satisified, the presence of a PICK COMMAND signal will generate the PICK pulse to the picker solenoid. The first card is introduced into the card track, and after a delay (see A, figure 16), the leading edge will arrive at the read station. The BUSY signal will go TRUE as soon as the leading edge of the card enters the read station.

To initiate the card pick cycle, the PICK COMMAND must be present for at least 1 microsecond (us) concurrently with the READY signal. Once the pick cycle is initiated, the PICK COMMAND line is ignored until the BUSY signal goes

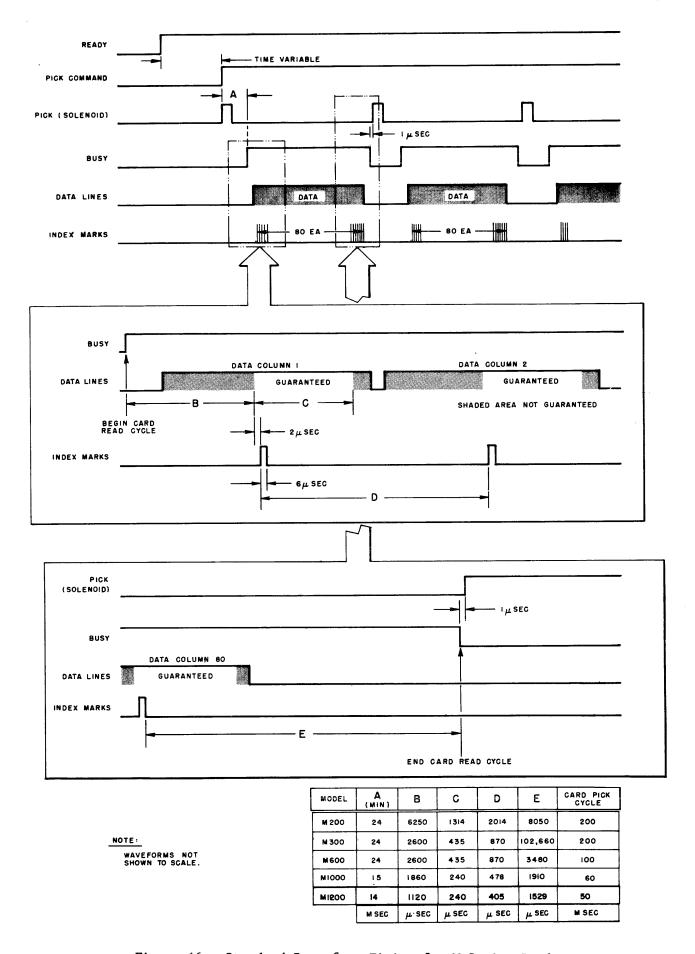


Figure 16. Standard Interface Timing for M Series Readers

FALSE, indicating the end of the card read cycle. In card-at-a-time operation, it is suggested that the PICK COMMAND be retained TRUE until receipt of the column 1 index mark. In the continuous run mode, the PICK COMMAND may be left in the TRUE condition and a new PICK signal will be automatically generated within 1 us of the BUSY signal going FALSE.

Should the picker fail to engage the card, the Pick Control logic will wait 50 milliseconds (ms) and automatically try again. It will continue to generate a PICK pulse every 50 ms until 6 attempts have been made. After 6 attempts have been unsuccessful (300 ms), a PICK CHECK alarm will be generated, disabling the READY line.

Data Readout

The card read cycle starts with the recognition that the card leading edge has entered the read station. At this time the BUSY line goes TRUE. Eighty equally spaced Index Marks of 6 us duration are generated while the BUSY signal is present. The time spacing of the Index Marks and the BUSY signal are shown by intervals B, D, and E on figure 16.

It can be seen from the timing diagram that data signals may appear on the data output lines before the occurrence of the associated Index Mark. Since torn webs are sometimes encountered which could partially obscure the hole, all Documation card readers feature a wide data acceptance interval to provide greater tolerance to this damage. During this interval, any signal from the read station sensors indicates a hole, and therefore is recognized as a valid data bit and is stored into the Character Buffer. Since the contents of the Character Buffer are subject to change throughout this interval, the data is not guaranteed until the end of the acceptance interval. This period is terminated 2 us prior to the Index Mark.

By the time the Index Mark is generated, the data will have been read, stored, and the data lines should have settled. Data levels are guaranteed to remain on the output lines available for transfer to the external equipment for interval C. The data lines may actually remain TRUE longer than the guaranteed period; however, the absolute duration of the data signal is not controlled as it will very slightly due to variations in the track speed of the card reader.

Alarms

A description of the standard alarm signals provided in the M Series reader follows:

Hopper Check

The HOPPER CHECK signal remains FALSE during normal card reader operation, but goes TRUE if either the input hopper is empty or the output stacker is full. If the input hopper is empty and the SHUTDOWN switch is in AUTO position, the blower is also automatically switched off; when the input is reloaded and RESET pressed, the blower is automatically re-energized.

When the last card leaves the input hopper, the switch which senses the empty condition immediately signals a HOPPER CHECK and disables the READY signal. This occurs at about the time that the 16th data column is being read. The reader continues the read cycle; however, when the BUSY line next goes FALSE the reader is stopped. In the case of a full output stacker, the HOPPER CHECK signal only appears at the end of the read cycle during which it occurred.

Error

The ERROR signal is produced by failure of the light or dark check. This usually indicates that a card has a tear at the leading or trailing edge (DARK CHECK). If the read station should experience an emitter/sensor failure while reading a card, the LIGHT CHECK will pick it up. Either type of failure will be signalled by the ERROR line going TRUE and a READ CHECK indication on the front panel.

Motion Check

The MOTION CHECK signal is a composite of the PICK CHECK and STACK CHECK alarm. Both alarms are conditions requiring operator intervention and are furnished to the interface as a single alarm line. The condition is displayed on the front panel indicator lights as either a PICK CHECK or a STACK CHECK. The MOTION CHECK signal will occur within 300 ms of the initiation of an unsuccessful pick attempt or in time to inhibit the picking of the second card after the stacker sensor detects that a card is not completely clear of the card track.

CONNECTORS

The 38 pin output connector provides access for all control, data and alarm lines. A separate twist-lock connector provides entry for AC power. The output connector is Elco part no. 00-8016-038-000-707 and the mating connector is Elco part no. 00-8016-038-217-704. This mating connector assembly is available from Documation and is shipped unassembled as a kit with connector base, cover and 38 solder type pins (#60-8017-0513).

The power connector is Hubbell part no. 7486. The mating connector is Hubbell part no. 7484. The mating AC power connector is supplied on the standard accessory power cord; however, it is identified in case it is desired to fabricate a special power interface.

SIGNAL CONNECTOR PIN LIST

PIN	SIGNAL	DESCRIPTION	PIN	SIGNAL	DESCRIPTION
A	D12	Row 12 Data	X	D7 (RET)	
В	D11	Row 11 Data	Y	D8	Row 8 Data
С	D 0	Row 0 Data	Z	D9	Row 9 Data
D	D1	Row 1 Data	AA	IM	Index Mark
E	D12 (RET)		ВВ	RDY	Ready
F	D11 (RET)		CC	D8 (RET)	
Н	DO (RET)		DD	D9 (RET)	
J	D1 (RET)		EE	IM (RET)/GRD	Signal Ground
K	D2	Row 2 Data	FF	RDY (RET)	
L	D3	Row 3 Data	HH	ERROR	Error
M	D4	Row 4 Data	JJ	НСК	Hopper Check
N	D5	Row 5 Data	KK	MOCK	Motion Check
P	D2 (RET)		LL	PC	Pick Command
R	D3 (RET)		MM	BSY	Busy
S	D4 (RET)		NN	Error (RET)	
T	D5 (RET)		PP	HCK (RET)	
U	D6	Row 6 Data	RR	MOCK (RET)	
V	D7	Row 7 Data	SS	PC (RET)	
W	D6 (RET)		TT	BSY (RET)	

POWER CONNECTOR PIN LIST

PIN	SIGNAL	
W	Safety ground	(green)
X	Neutral	(white)
Y	115 Volts	(black)

SIGNAL CHARACTERISTICS

The standard interface is supplied as the output of TTL type 7404. Signal sense is specified as a Logical TRUE and is a positive level, Logical FALSE is a ground level. Circuit characteristics are shown in figure 17. Other output drive configurations are available.

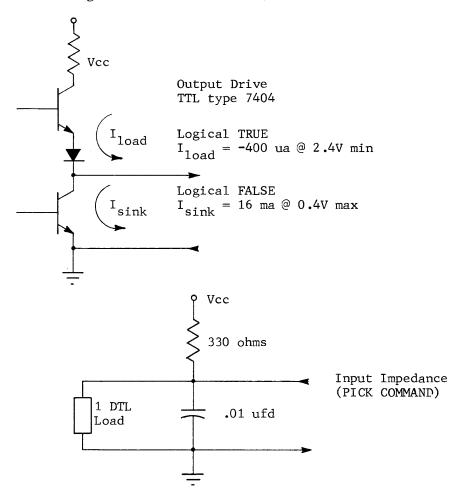


Figure 17. Circuit Characteristics

GROUNDING

Grounding within the M Series card readers maintains AC power and signal ground separate. Signal ground is the logic power return (Vcc return) and is transformer isolated from the AC power distribution system. The chassis is protected by connection to the safety wire (green) in the AC power cord.

It is recommended that twisted pair cable be used to connect the M Series card readers to external equipment. The signal returns should be terminated as close as possible to the signal receivers. It should be noted that pin EE (Index Mark return) is designated as SIGNAL GROUND on the pin assignment chart. If twisted pair interconnection is not used, it is recommended that pin EE be connected to the external equipment signal return.

PREVENTIVE MAINTENANCE

GENERAL

The following paragraphs provide information for preventive maintenance and general care of the M Series card readers. The M Series card readers are of rugged construction and are designed to provide many hours of failsafe, reliable operation; as such, preventive maintenance consists primarily of routine cleaning.

CLEANING

Picker Shoe

IMPORTANT

AFTER EACH 40 HOURS OF OPERATION, THE NEO-PRENE SURFACE OF THE PICKER SECTOR SHOULD BE WIPED WITH A SOLVENT SUCH AS DENATURED ALCOHOL OR LACQUER THINNER.

This will remove the glaze buildup from the ink which rubs off of the cards. This is especially prevalent where new cards are used exclusively. If this glaze is allowed to remain, it reduces the coefficient of friction of the picker sector to the point that erratic pick operation may result.

After each 160 hours of operation, the picker sector should be examined to see if any of the vacuum holes have become plugged with lint, trash, or card meal which the solvent scrub has failed to dislodge. If so, gently push this debris through the holes with a paper clip while the reader is on. The vacuum system will remove the debris.

Casting Assemblies

After each 160 hours of operation, the card track should be cleaned. Using a 5/64 Allen wrench, remove four button head screws (3), figure 20, holding top panel cover. Remove this cover and use a vacuum cleaner to remove any card debris buildup around the picker and stacker castings. Use a small brush to clean around the picker and stacker rollers and picker sector.

Cooling Fan

The cooling fan air-intake screen performs the function of preventing dirt and dust from entering the card reader interior. Depending upon the

operational atmosphere, the screen should be cleaned as necessary. Use a flatblade screwdriver and remove the screen (Figure 18); then clean in a solvent or use a vacuum cleaner as necessary.

Exterior Cleaning

The exterior M Series Card Readers should be cleaned as often as practical. Wipe the exterior with a clean, lint-free cloth saturated with a mild solvent such as denatured alcohol or household ammonia after each 40-hour operational period. If persistent dirt buildup is present, the exterior should be rubbed down with a heavier solvent. Attention to this routine will keep the anodized finish of the reader with a like-new appearance indefinitely.

LUBRICATION

Rotary Solenoid

The rollers of the rotary solenoid normally require grease only after 40 million cards have been processed through the reader. Since there is a possibility that the grease may dry out in certain low humidity localities, it is advised to lubricate these rollers every six months. Apply one drop of Ledex

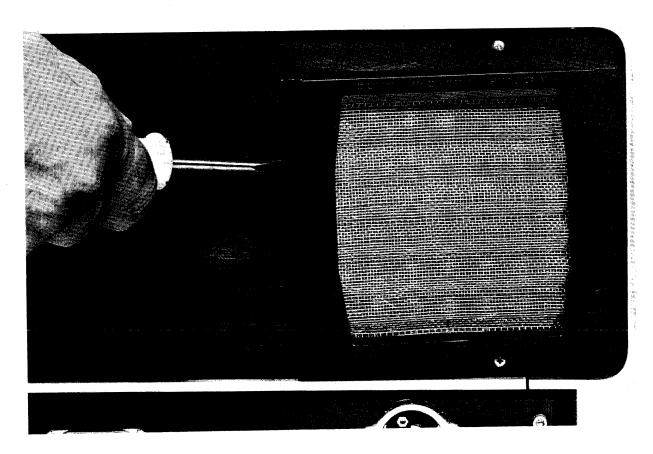


Figure 18. Removal of Fan Screen

No. 2 lubricant to each of the three roller grease points (figure 19). A lubricant kit is available from Ledex Inc., Dayton, Ohio (Part No. 124048-001) or from Documation, Incorporated.

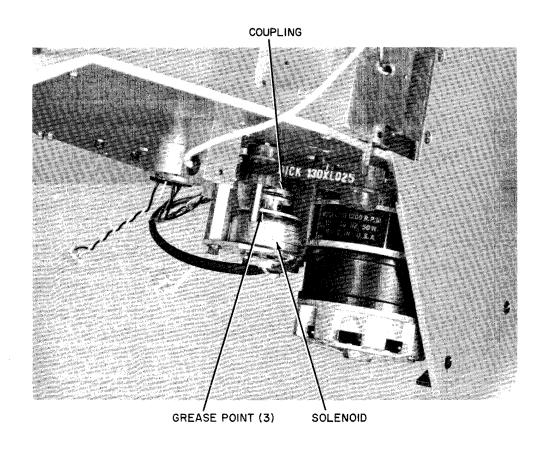


Figure 19. Solenoid Lubrication

REPAIR

GENERAL

The following repair procedures detail step by step methods for those parts for which replacement may be required during the life of the reader. It is recommended that these procedures are followed closely and performed by a person familiar with tools, their use and assembly/disassembly techniques.

REPAIR PROCEDURES TABLE OF CONTENTS

	<u>Title</u>	Page	No.
1.	Replacement of Main Drive Motor Belt	41	
2.	Replacement of Third Stacker Roller Drive Belt	44	
3.	Replacement of First and Second Stacker Roller Driver Belts	46	
4.	Replacement of First, Second, and Third Stacker Roller Bearings	47	
5.	Replacement of Solenoid	49	
6.	Replacement of Belt on Vacuum Pump Motor Assembly	51	
7.	Replacement and Adjustment of Magnetic Pickup	54	
8.	Replacement of Read Head, Light Station, Fourth and Fifth	57	
	Stacker Roller Bearings, or First and Second Picker Roller		
	Bearings		
9.	To replace Read Head	60	
10.	To replace Light Station	60	
11.	To replace Fourth and Fifth Stacker Roller Bearings	61	
12.	To replace First or Second Picker Roller Bearings	61	
13.	To replace Picker Casting	61	
14.	Replacement of Picker	63	
15.	Adjustment of Picker Sector Travel	64	
16.	Replacement of Stacker Photocell	64	
17.	Replacement of Negator Spring	66	
18.	Replacement of Hopper Empty Switch	67	
19.	Replacement of Stacker Full Switch	67	
20.	Bottom Plate Component Location	68	

REQUIRED TOOLS

The following tools are required to perform assembly/disassembly on the M Series Card Readers.

Description

Manufacturer and Part Number of Special Tools

1/16" - Allen Screwdriver

3/32" - Allen Wrench (long arm)

5/64" - Allen Wrench (long arm)

7/64" - Allen Wrench (long arm)

1/8" - Allen Wrench (long arm)

9/64" - Allen Wrench (long arm)

.050" - Allen Wrench (short arm)

1/16" - Allen Wrench (short arm)

AMP Extraction Tool

"AMP Leaf Contact" Extraction Tool

"AMP Modified Fork" Contact Extraction Tool

"AMP Mod IV" Contact Extraction Tool

Deutsch Insertion/Extraction Tool
 (mounted on base plate)

Elco Extraction Tool

Elco Insertion Tool

Feeler Gauge Set 0.0015" thru 0.025"

Flat Nose Pliers

Knife Blade - 2 1/2" blade

Medium Flat Blade Screwdriver 3" long

Medium Flat Blade Screwdriver 6" long

6" Metal Scale, decimal/fraction per inch

1/4" - Open End or Socket Wrench

11/32" - Open End or Socket Wrench

7/16" - Open End or Socket Wrench

#1 Phillips Screwdriver 6" long

#2 Phillips Screwdriver 6" long

Printed Circuit Card Extender

#2 Retaining Ring Remover

Side Cutter

Solder Removal Tool

60-watt Soldering Iron

32-oz. Spring Scale

AMP 91022-1

AMP 465195-2 or 465275-1

AMP 91037-2

AMP 91029-1A

NAS 1664-16

Elco 061877-02

Elco 061742-04

Documation P/N 1040405

REPLACEMENT OF MAIN DRIVE MOTOR BELT

- 1. Using a 5/64 Allen wrench, remove six 6x32 button head screws (1) retaining front panel and remove front panel, figure 20.
- 2. Using a 5/64 Allen wrench, remove six 6x32 button head screws 2 holding rear panel, move rear panel out slightly, disconnect fan motor connector, and remove rear panel, figures 21 and 32.
- 3. Using a 9/64 Allen wrench, LOOSEN three 8x32 socket head motor plate mounting screws (bottom of mainframe). REMOVE the fourth motor plate mounting screw, figure 22.
- 4. Using a 5/64 Allen wrench, LOOSEN one 8x32 set screw in timing disk, figure 23.

CAUTION

REMOVE TIMING DISK USING EXTREME CARE NOT TO DAMAGE THE TEETH ON DISK. WRAP DISK IN SOFT TISSUE WHILE NOT IN THE READER.

- 5. Using 3/32 Allen wrench, LOOSEN set screw in fifth stacker roller nylon pulley, figure 23.
 - 6. Remove pulley from stacker-roller shaft.
 - 7. Remove main drive motor belt, figure 23.
 - 8. To replace main drive motor belt, figure 23
 - a. Place belt over main drive motor pulley.
 - b. Slip belt over fourth stacker roller pulley.
 - c. Place belt over fifth stacker roller pulley.
 - d. Replace this pulley on fifth stacker roller shaft.
- 9. Push fifth stacker roller pulley up against mainframe, then pull VERY SLIGHTLY downward making sure pulley is free from mainframe.
 - 10. Locate pulley so that set screw is on flat side of shaft.

CAUTION

USING MODERATE TORQUE, TIGHTEN PULLEY SET SCREW. DO NOT OVERTORQUE OR DAMAGE WILL RESULT TO PULLEY.

11. Replace timing disk on fifth stacker roller shaft and line up teeth on timing disk with tip on magnetic pickup. Using a feeler gauge, .007 to .008, check for clearance between the timing disk and magnetic pickup tip. If out of

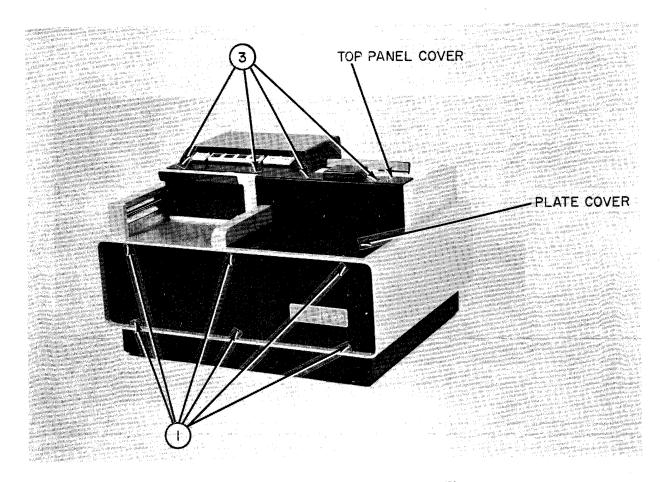


Figure 20. Three-Quarter Front View

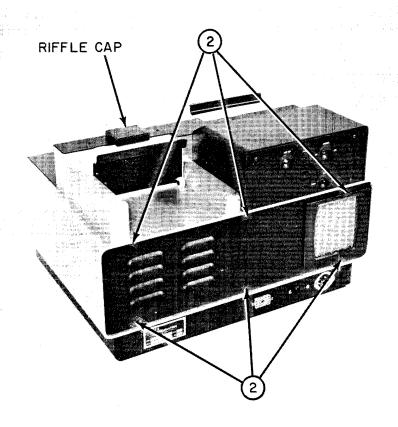


Figure 21. Three-Quarter Rear View

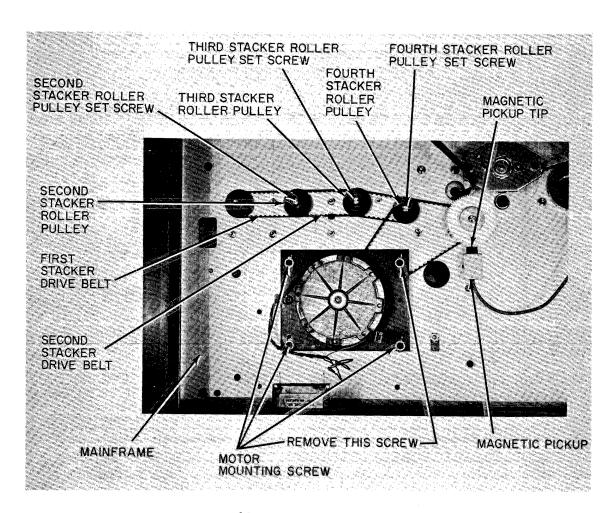


Figure 22. Bottom View Mainframe

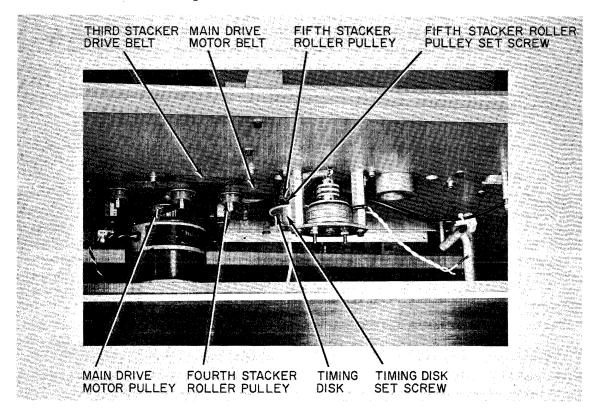


Figure 23. Partial View Stacker Drive Train

clearance, use steps 10 and 11 of Replacement and Adjustment of Magnetic Pickup Head for readjustment, figure 34.

NOTE

Before tightening timing disk set screw, check to make sure timing disk teeth are precisely in a horizontal plane with the magnetic pickup tip.

- 12. Tighten the motor plate mounting screws allowing sufficient slack for the plate to move easily.
- 13. Attach a 32-ounce spring scale with a round hook end to the main motor drive shaft.
- 14. Apply 24 ounces of force to the motor shaft. This will apply the correct tension to the main drive motor belt.
- 15. With this force applied, tighten the four motor plate mounting screws, figure 22.

CAUTION

BELT TENSION IS A CRITICAL ADJUSTMENT; EXERCISE CARE THAT TENSION IS CORRECT TO PREVENT EXCESSIVE BELT AND MOTOR SHAFT BEARING WEAR.

REPLACEMENT OF THIRD STACKER ROLLER DRIVE BELT

- 1. Using steps 1 and 2 of Replacement of Main Drive Motor Belt, remove front and rear panels, figures 20 and 21.
- 2. Using a 9/64 Allen wrench, LOOSEN four 8x32 socket head motor plate mounting screws (bottom of chassis). Push motor toward front of card reader releasing tension on motor drive belt, figure 22.
- 3. Using a 3/32 Allen wrench, LOOSEN set screws in third and fourth stacker roller pulleys, figure 24.
- 4. Rotate third and fourth stacker roller pulleys and belts pulling downward; remove third and fourth stacker roller pulleys and third stacker drive belt, figure 24.
- 5. Replace third belt between two loose pulleys; work pulleys with belt onto third and fourth stacker roller shafts until pulleys are next to mainframe.

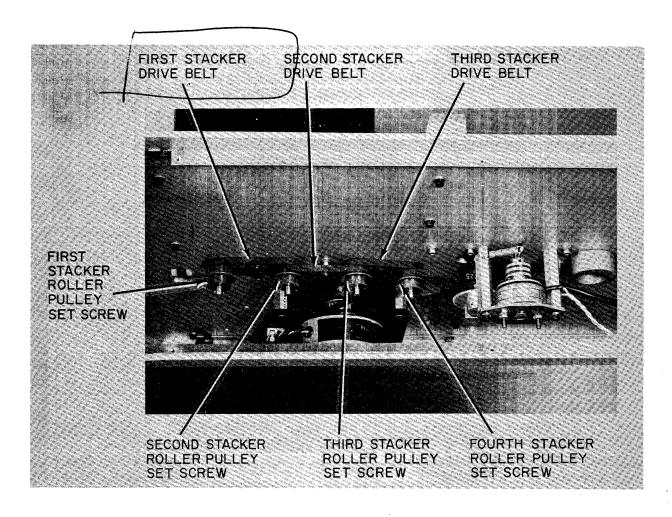


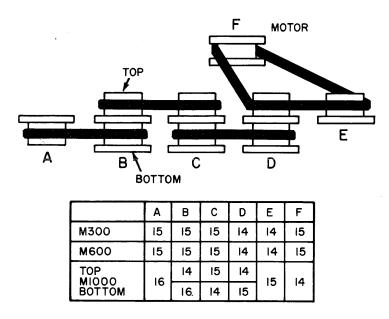
Figure 24. Partial View Stacker Drive Train

CAUTION

PULLEY CONFIGURATION MUST BE MAINTAINED.

MAKE SURE CORRECT PULLEY IS INSTALLED

ON RESPECTIVE SHAFT.



Pulley Configuration - Number of Teeth and Location.

- 6. Pull third and fourth pulleys VERY SLIGHTLY downward making sure pulleys are free from mainframe.
- 7. Position third and fourth stacker roller pulleys so that set screws are on the flat side of the shafts.

CAUTION

USING MODERATE TORQUE, TIGHTEN PULLEY
SET SCREWS. DO NOT OVERTORQUE OR DAMAGE
WILL RESULT TO PULLEY.

- 8. Replace drive motor belt over fourth stacker roller pulley, figure 23.
- 9. Adjust tension on drive motor belt using steps 12, 13, 14 and 15 of procedure to Replace Main Drive Motor Belt.

REPLACEMENT OF FIRST AND SECOND STACKER ROLLER DRIVE BELTS

NOTE

It is not necessary to loosen the motor plate mounting screws for this procedure.

- 1. To replace either the first or second stacker roller drive belt, LOOSEN the set screw in the second stacker roller pulley using a 3/32 Allen wrench, figure 24.
 - 2. Work the second stacker roller pulley downward and remove.
 - 3. Replace first or second stacker drive belt or both, as necessary.
- 4. Replace second stacker roller pulley on shaft working belts into slots on pulley, then place pulley next to mainframe.
- 5. Pull second pulley VERY SLIGHTLY downward making sure pulley is free from mainframe.
 - 6. Locate stacker roller pulley set screw on flat side of shaft.

CAUTION

USING MODERATE TORQUE, TIGHTEN PULLEY SET SET SCREWS. DO NOT OVERTORQUE OR DAMAGE WILL RESULT TO PULLEY.

REPLACEMENT OF FIRST, SECOND, AND THIRD STACKER ROLLER BEARINGS

- 1. Using a 5/64 Allen wrench, remove four button head screws 3, figure 20, holding top panel cover.
- 2. Using a 5/64 Allen wrench, remove six 6x32 button head screws (1), figure 20, retaining front panel and remove front panel.
- 3. Tape together 1/2" thickness of cards and use to prop stacker tray in extended position.
- 4. Using a 3/32 Allen wrench, LOOSEN set screw in the pulley on the roller assembly that is to be removed, figure 24.
- 5. Turning pulley slightly left and right, work pulley downward out of belt slots and remove pulley from shaft.
- 6. Using a 1/16 Allen wrench, LOOSEN set screw in the bottom stacker roller of assembly to be removed. Remove stacker roller, figure 25.
 - 7. Remove bottom bearing spacer washer from stacker shaft, figure 25.
- 8. Lift stacker shaft straight up out of stacker casting. Note there is another spacer washer between the top roller and bearing seat, figure 25.
 - 9. Using a knife blade, pry out top or bottom bearing to be replaced.

NOTE

The bearings are a loose pressfit into the casting. If the bearings appear difficult to remove, use a slender tool such as a small Allen screwdriver and tap the edge of the bearing from the inside of the stacker shaft hole.

- 10. Reassemble in reverse order of disassembly, making sure spacer washers are reinstalled between top and bottom rollers and bearing seats.
- 11. Place .010 feeler gauge between mainframe and bottom stacker roller, apply firm finger pressure at the top stacker roller and tighten set screw in the bottom stacker roller.

NOTE

It is important to check that there is no vertical play in the stacker shaft after tightening the roller set screws.

12. When replacing pulley, make sure set screw is on the flat side of the shaft, and that the pulley flange is oriented toward the bottom of the shaft.

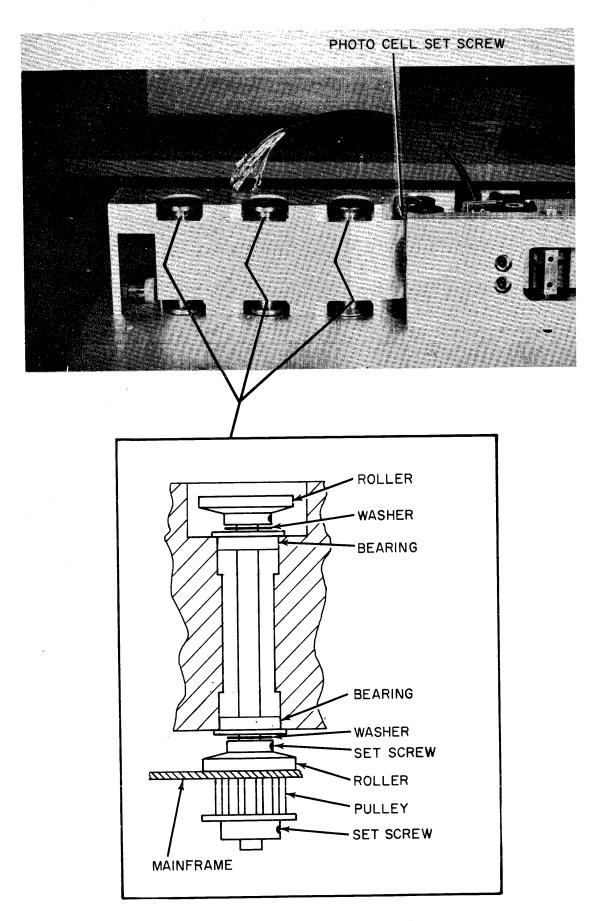


Figure 25. Stacker Roller Bearings

CAUTION

USING MODERATE TORQUE, TIGHTEN PULLEY SET SCREWS. DO NOT OVERTORQUE OR DAMAGE WILL RESULT TO PULLEY. REFER TO PAGE 45 FOR CORRECT PULLEY CONFIGURATION.

REPLACEMENT OF SOLENOID

- 1. Using steps 1 and 2 of Replacement of Main Drive Motor Belt, remove front and rear panels, figures 20 and 21.
- Unsolder the two white leads from the solenoid driver circuit board, figure 26.
 - 3. Remove solenoid return spring from spring post and arm stud, figure 26.
- 4. Using an .050 Allen wrench, LOOSEN two set screws in the top solenoid coupling, figure 26.
- 5. Using a 9/64 Allen wrench, remove two 8x32 socket head screws (9) holding solenoid mounting plate, figure 26.
 - 6. Remove solenoid downward.

NOTE

Viewing the bottom of the solenoid plate, note that the solenoid mounting holes are not in line with the mounting plate holes. To ensure that the solenoid is reinstalled correctly, make sure the wires are extending from the right side (viewed from the front of the reader) and that the forwardmost solenoid mounting hole is on the right side.

- 7. Using an 11/32 wrench, temove two 8x32 mounting nuts (10), figure 26.
- 8. Using a .050 Allen wrench, LOOSEN two set screws retaining the coupling on the solenoid shaft. Remove coupling, figure 26.
 - 9. Install new solenoid.

NOTE

Remove the set screws from the coupling and replace using LOCKTITE GRADE C. All operational and mounting type hardware, with the exception of panel screws, should be replaced using LOCKTITE GRADE C.

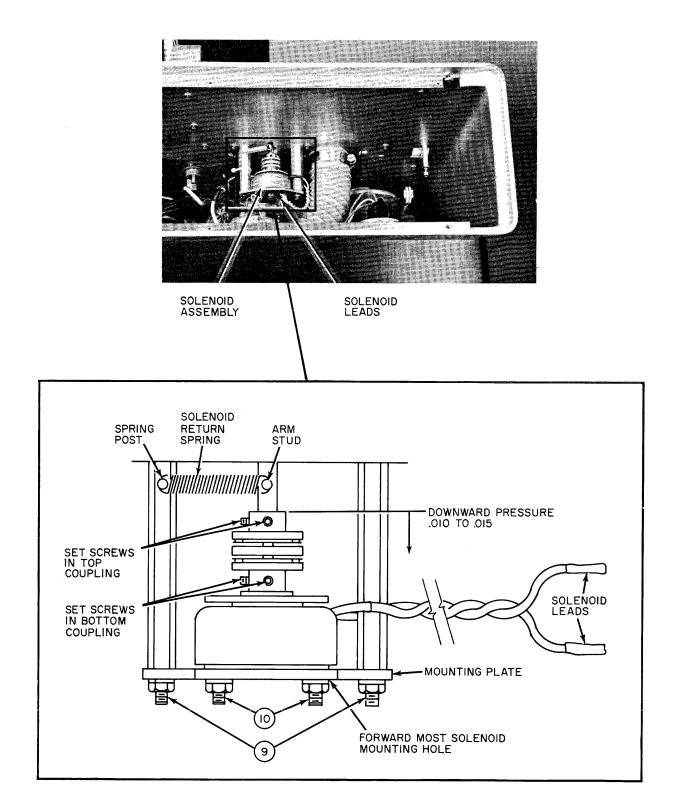


Figure 26. Solenoid

- 10. Replace the coupling locating the bottom coupling set screws on the two flat sides of the shaft.
- 11. Tighten the bottom coupling set screws and replace the solenoid on the mounting plate making sure holes are in the proper position, with wires extending from the right side, figure 26.
 - 12. Replace solenoid on mounting posts.
- 13. Replace the solenoid return spring between the spring post and the arm stud, figure 26.
- 14. Preload the solenoid coupling by pressing downward .010 to .015 and tighten the top coupling set screws, figure 26.

NOTE

The solenoid will turn as the set screws are tightened to the flat sides of the shaft. This is a natural built-in alignment. This alignment prevents the solenoid from bottoming-out during operation.

15. Resolder the solenoid leads to the output terminals on the solenoid driver circuit board, figure 26.

REPLACEMENT OF BELT ON VACUUM PUMP MOTOR ASSEMBLY

- 1. Remove front and rear panels. Refer to steps 1 and 2 of Replacement of Main Drive Motor Belt, figures 20 and 21.
 - 2. Remove four Phillips head screws (4) at rear of subframe panel, figure 27.
- 3. Remove five Phillips head screws (5) on bottom, rear edge of card reader, holding subframe panel, figure 27.

NOTE

Tag the wires to be removed in the following step. They must be replaced on the proper terminals.

- 4. Remove two connectors from capacitor and one connector from relay disconnecting vacuum pump motor, figure 28.
- 5. Loosen vacuum hose clamp on vacuum pump and remove hose from pump, figure 28.
- 6. Using a .050 Allen wrench, LOOSEN #440 set screw in vacuum tube elbow and pull elbow downward, figure 29.

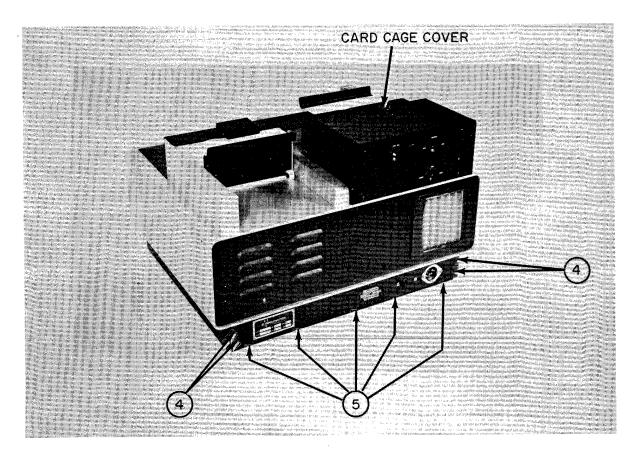


Figure 27. Three-Quarter Rear View

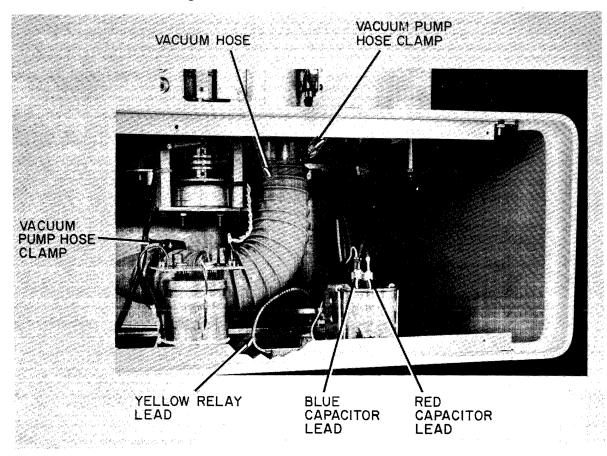


Figure 28. Partial View Vacuum Pump Motor Assembly

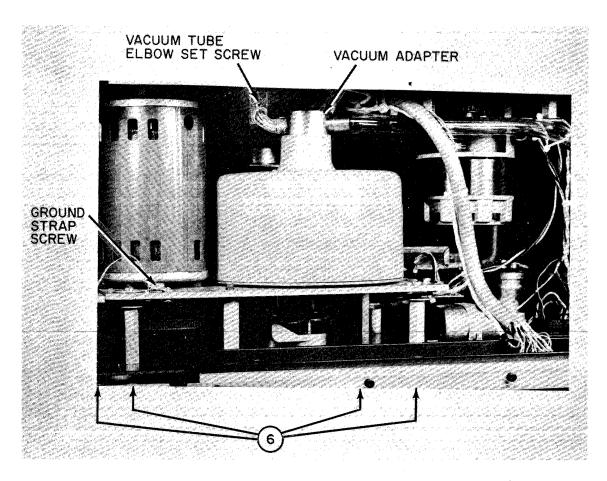


Figure 29. Partial View Vacuum Pump Motor Assembly

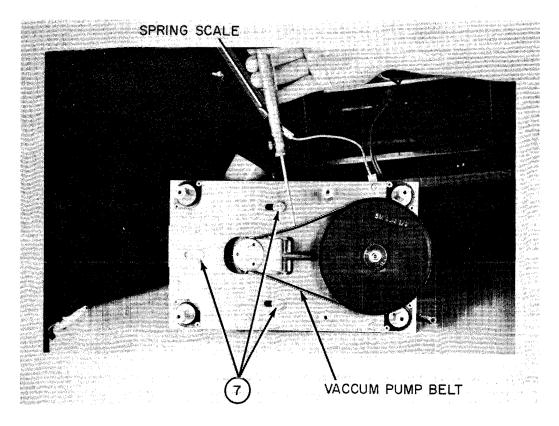


Figure 30. Vacuum Pump Belt

- 7. Remove vacuum adapter from top of vacuum pump assembly and remove from card reader, figure 29. The adapter is a press fit and will lift out with a slight upward pressure.
 - 8. Remove screw holding ground strap to subframe, figure 29.
- 9. Remove four Phillips head screws 6 located on bottom of card reader chassis (holding vacuum pump motor assembly), figure 29.
 - 10. The vacuum pump assembly may now be removed from the card reader.
- 11. LOOSEN the three hex bolts (7) holding the vacuum pump in place, figure 30.
 - 12. Replace vacuum pump belt, figure 30.
- 13. Using a spring scale, adjust vacuum pump for a belt tension of 4-6 ounces. This is about 3/64" belt deflection, figure 30.
- 14. With the appropriate belt tension applied, tighten the three hex vacuum pump mounting bolts, figure 30.
- 15. Reinstall the vacuum pump assembly into the card reader in reverse order of disassembly.

REPLACEMENT AND ADJUSTMENT OF MAGNETIC PICKUP

- 1. Using a 5/64 Allen wrench, remove six 6x32 button head screws holding rear panel, move rear panel out slightly, disconnect blower motor connector and remove rear panel, figures 21 and 32.
- 2. Using a .050 Allen wrench, LOOSEN #440 set screw in vacuum tube elbow, figure 29, and move elbow downward.
- 3. Remove vacuum adapter from top of vacuum pump assembly and remove from card reader. The adapter is a press fit into the vacuum assembly and will lift out with a slight upward pressure, figure 29.
- 4. Using a 1/16 Allen wrench, LOOSEN set screw in magnetic pickup mounting block, figure 31.
 - 5. Remove magnetic pickup from mounting block, figure 31.
- 6. Remove card cage cover by sliding backward about 2" and lifting upward, figure 27.
- 7. Using a 9/64 Allen wrench, remove three socket head screws (8) holding card cage in place. Move card cage to rear and remount using two rear screws, figures 32 and 33.
 - 8. Remove all cards from card cage, figure 33.

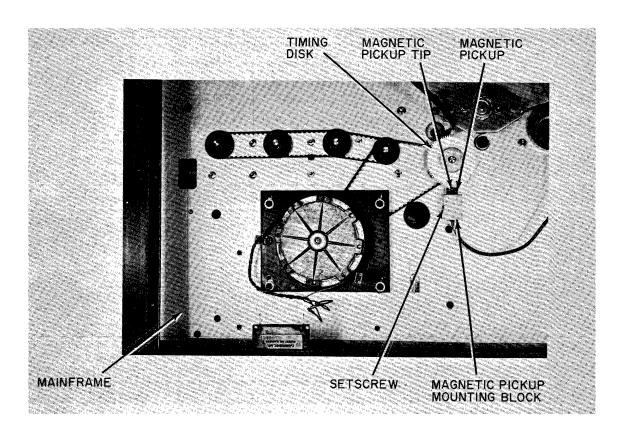


Figure 31. Magnetic Pickup

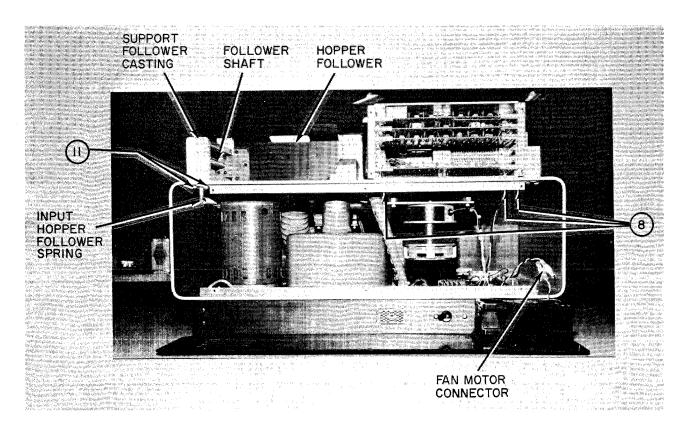


Figure 32. Exposed Rear View

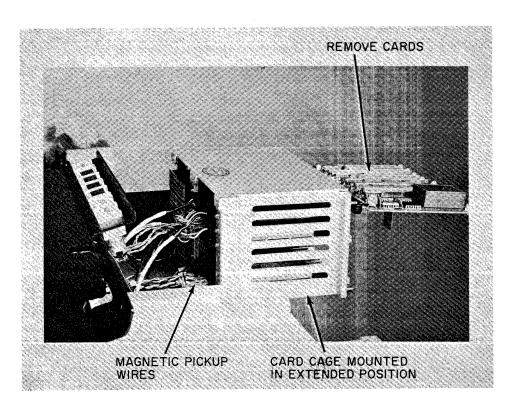


Figure 33. Card Cage Extended

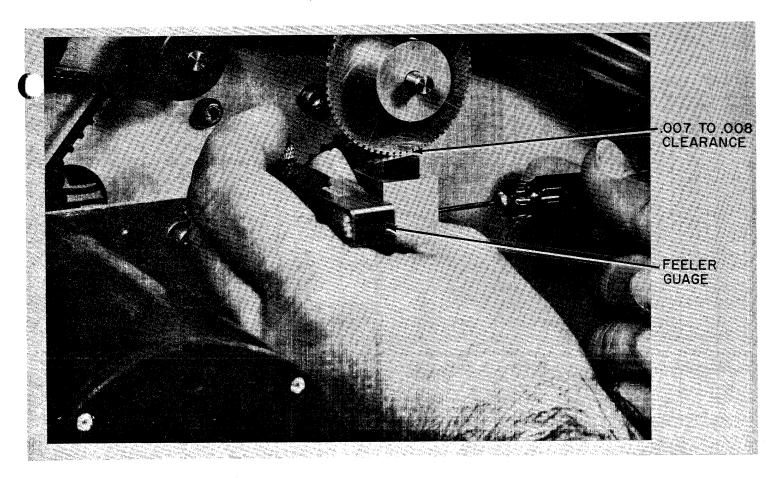


Figure 34. Timing Disc Air-Gap Adjustment

NOTE

Tag two magnetic pickup wires so that they can be identified with their proper position in the card cage connector, figure 33.

- 9. Using AMP tool 465195-2, remove two magnetic pickup wires from card cage connectors.
- 10. Replace wires from new magnetic pickup unit into their proper positions in the card cage connector.
 - 11. Insert the pickup unit into the mounting block, figure 31.
- 12. Using a feeler gauge, adjust spacing between timing disk and tip of pickup unit for .007 to .008, figure 34.
- 13. With feeler gauge in place, use a 1/16 Allen wrench to tighten the set screw in the mounting block, figure 34.
 - 14. Replace vacuum adapter on top of vacuum pump assembly, figure 29.
 - 15. Replace vacuum tube elbow and tighten set screw, figure 29.
- 16. Replace cards in cage, remount cage in normal position, replace card cage cover, and rear panel.

REPLACEMENT OF READ HEAD, LIGHT STATION, FOURTH AND FIFTH STACKER ROLLER BEARINGS, OR FIRST AND SECOND PICKER ROLLER BEARINGS

NOTE

Use the following fifteen procedures to remove the picker casting. The picker casting must be removed to accomplish any of the above four repairs.

- 1. Remove front and rear panels. Refer to steps 1 and 2 of Replacement of Main Drive Motor Belt and figures 20 and 21.
- 2. Using a 5/64 Allen wrench, remove four button head screws 3, holding top panel cover, figure 20.
 - 3. Using a flat-blade knife, pry off black plate cover, figure 20.

NOTE

This cover is secured with Goodyear Pliobond adhesive and will release with a moderate pressure.

- 4. Using MWK solvent, clean bottom of black plate cover and top of chassis.
 - 5. Remove input hopper follower spring from post, figure 32.
- 6. Using a 9/64 Allen wrench, remove two socket head screws (1) holding support follower casting, figure 32.
 - 7. Remove follower shaft, figure 32.
 - 8. Move hopper follower to rear of card reader, figure 32.
- 9. Using a 9/64 Allen wrench, remove two socket head screws (12) holding edge guide casting, figure 35.
- 10. Using a .050 Allen wrench, LOOSEN vacuum tube elbow set screw, figure 29. Slide elbow off vacuum tube and move to left.
- 11. Remove vacuum adapter, from top of vacuum pump assembly and remove from card reader, figure 29. The adapter is a press fit and will lift out with a slight upward pressure.
- 12. Using medium flat-blade screw driver, LOOSEN screw on two large vacuum hose clamps, remove vacuum hose, figure 28.
 - 13. Remove return solenoid spring, figure 26.
- 14. Using a .050 Allen wrench, LOOSEN two top solenoid coupling set screws, figure 26.

NOTE

When reassembling, preload the solenoid coupling pressing downward .010 to .015 and tighten the coupling set screws, figure 26, after applying LOCKTITE GRADE C to the set screws.

- 15. Using a 9/64 Allen wrench, remove two socket head screws (9) holding solenoid assembly, figure 26. Lay solenoid assembly on baseplate.
- 16. Using a 9/64 Allen wrench, remove six socket head screws (13) holding picker casting, figure 35.
- 17. Remove nylon tie-down holding light station cable on solenoid mounting post, figure 35.
 - 18. Remove nylon tie-down holding hopper-empty switch cable, figure 37.
 - 19. Lift picker casting straight up and lay on cloth on chassis, figure 36.

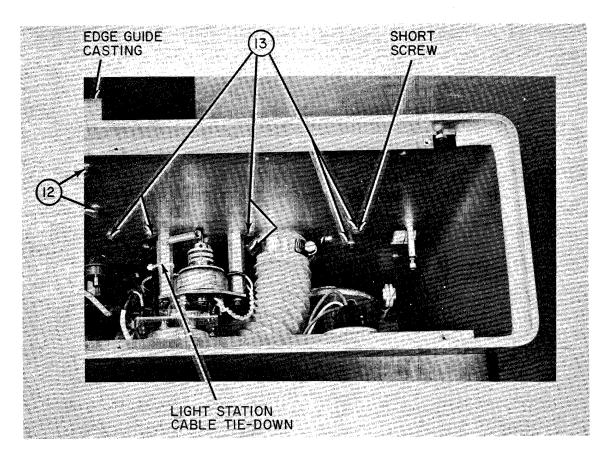


Figure 35. Bottom View Casting Socket Head Screws

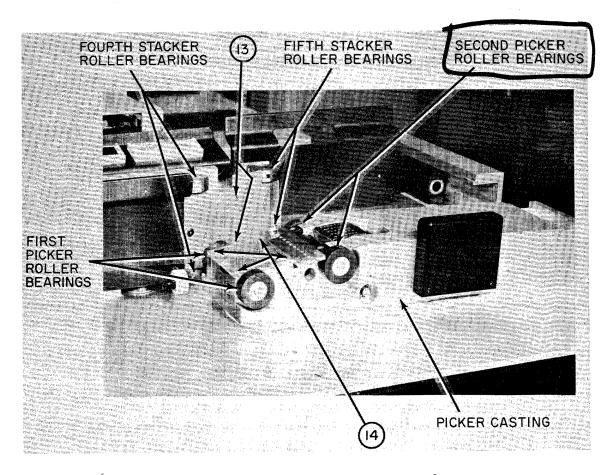
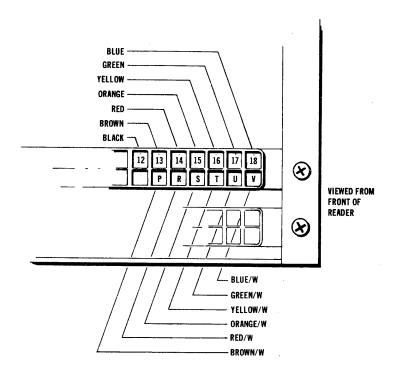


Figure 36. Picker Casting Removed

TO REPLACE READ HEAD

- 1. Remove card cage cover by sliding backward about 2" and lifting upward, figure 27.
- 2. Using a 9/64 Allen wrench, remove three socket head screws $\boxed{8}$ holding card cage in place. Move card cage to rear and remount using two rear screws, figures 32 and 33.
 - 3. Remove all cards from card cage, figure 33.
- 4. Using AMP tool 465195-2, remove read head wires from connector per the following diagram.



- 5. Remove two 440x1/4 flat head Phillips screws \bigcirc 13 to remove read head, figure 36.
- $\ensuremath{\text{6.}}$ Replace read head and connectors in card cage making sure wires are installed in proper color coded positions.

TO REPLACE LIGHT STATION

1. Remove four 256x1/4 flat head Phillips screws (14) to remove light station, figure 36.

- 2. Slide off nylon tie-down holding light station cable connector on power supply.
 - 3. Remove light station connector from power supply.
- 4. Replace light station, plug connector into power supply, and replace tie-downs.

TO REPLACE FOURTH AND FIFTH STACKER ROLLER BEARINGS, Refer to figure 36

- 1. Perform step 1 of Replacement of Third Stacker Roller Drive Belt.
- 2. Perform steps 4 through 12 of Replacement of First, Second and Third Stacker Roller Bearings to replace fourth or fifth stacker roller bearings as necessary. When replacing the fifth stacker roller bearings, the timing disk must be removed by using a 5/64 Allen wrench to LOOSEN one 8x32 set screw in timing disk, figure 23.

CAUTION

REMOVE TIMING DISK USING EXTREME CARE NOT TO DAMAGE THE TEETH ON DISK. WRAP DISK IN SOFT TISSUE WHILE NOT IN THE READER.

3. Perform steps 11 through 15 of Replacement of Main Drive Motor Belt to replace timing disk and readjust drive motor belt tension.

TO REPLACE FIRST OR SECOND PICKER ROLLER BEARINGS, Refer to figure 36

- 1. To replace the first picker roller bearings, LOOSEN the set screw in the bottom roller. Remove picker roller.
- 2. To replace the second picker roller bearings, LOOSEN the set screw in the top or bottom roller. The shaft of either may then be removed from the center of the casting.
- 3. To replace bearings, perform steps 7 through 11 of Replacement of First, Second, and Third Stacker Roller Bearings.

TO REPLACE PICKER CASTING

- 1. Set picker casting in place, figure 37.
- 2. Using LOCKTITE GRADE C, set all six socket head screws (13), figure 35, but do not tighten.

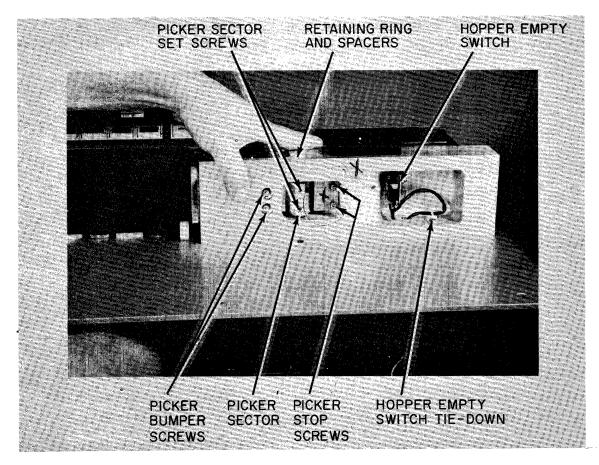


Figure 37. Picker Casting Exposed View

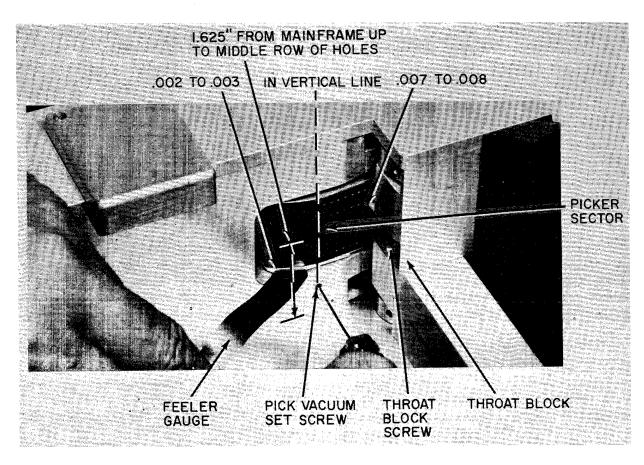


Figure 38. Picker

- 3. With hand pressure applied between picker casting and stacker casting as in figure 37, tighten six picker casting mounting screws.
- 4. The remainder of the reader may now be assembled in reverse order of disassembly. Refer to page 45 for correct pulley configuration.

REPLACEMENT OF PICKER

- 1. Using a 5/64 Allen wrench, remove four button head screws (3) holding top panel cover, figure 20.
 - 2. Perform steps 1 and 3 through 6 of Replacement of Solenoid Assembly.
- 3. Remove input-hopper follower spring from post and move hopper follower to rear of card reader, figure 32.
- 4. Using a #2 retaining ring remover tool, remove the retaining ring from the top of the picker shaft, figure 37.
 - 5. Remove spacers located under the retaining ring, figure 37.

CAUTION

ALL OF THE SPACERS MUST BE REPLACED IN REASSEMBLY.



- 6. Using a 5/64 Allen wrench, LOOSEN two set screws holding picker sector, figure 37.
 - 7. Remove picker shaft from bottom of chassis.
 - 8. Using a Phillips screwdriver, remove throat block, figure 38.
 - 9. Remove picker sector from rear side of picker casting, figure 38.
 - 10. Replace picker sector, shaft, spacers, and retaining ring.
 - 11. Adjust shaft to place sector set screws on flat side of shaft.
- 12. Using a 6" metal ruler, measure 1.625" from the mainframe up to the center of the row of holes on the picker sector, figure 38.
- 13. Retaining this measurement, tighten the two picker sector set screws, figure 37.
 - 14. Using a .050 Allen wrench, LOOSEN the pick vacuum set screw, figure 38.
- 15. Using a feeler gauge, adjust clearance between pick vacuum tube plate and picker sector for .002 to .003. Tighten pick vacuum set screw, figure 38.
- 16. Replace solenoid and adjust top solenoid coupling using step 14 of Replacement of Solenoid Assembly.
 - 17. Replace throat block but do not tighten screw, figure 38.

- 18. Using a feeler gauge, adjust throat pick for clearance of .007 to .008 between throat block and picker sector and tighten screw, figure 38.
 - 19. Replace hopper follower spring.
 - 20. Replace top cover and front and rear panels.

ADJUSTMENT OF PICKER SECTOR TRAVEL

- 1. Using a 5/64 Allen wrench, remove four button head screws 3 holding top panel cover, figure 20.
- 2. Using a 5/64 Allen wrench, LOOSEN the two 6 x 32 picker stop socket head screws, figure 37.
- 3. Adjust picker stop so that the last row of holes in picker sector is in a vertical line with the pick vacuum set screw, figure 38. Tighten the two picker stop socket head screws.
- 4. Using a 9/64 Allen wrench, LOOSEN the two 8 x 32 picker bumper socket head screws, figure 37.
- 5. Adjust the picker bumper so that a card picked by hand just makes contact with the first set of rollers. Tighten the top picker bumper socket head screws.
- 6. Reassemble in reverse order of disassembly and check reader for proper pick action.

REPLACEMENT OF STACKER PHOTOCELL

- 1. Using a 5/64 Allen wrench, remove four button head screws (3) holding top panel cover, figure 20.
- Remove card cage cover, sliding backward about 2" and lifting off, figure 27.
- 3. Using a 5/64 Allen wrench, remove six 6 x 32 button head screws (3) holding rear panel, move rear panel out slightly, disconnect fan motor connector, and remove rear panel, (8), figures 21 and 32.
- 4. Using a 9/64 Allen wrench, remove three socket head screws (8) holding card cage in place. Move card cage to rear and remount using two rear screws, figures 32 and 33.
 - 5. Remove all cards from card cage, figure 33.
- 6. Using a 1/16 Allen wrench, LOOSEN set screw in top fourth stacker roller. Remove stacker roller.

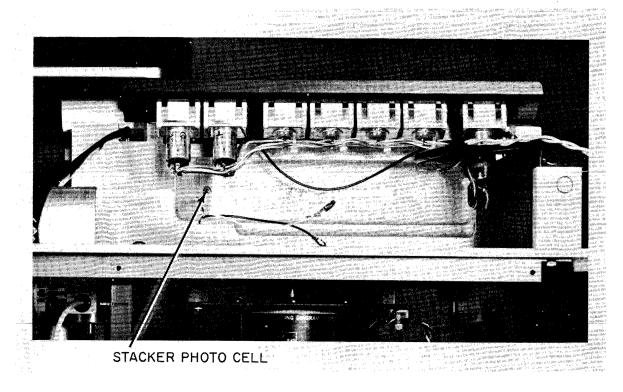


Figure 39. Stacker Photocell

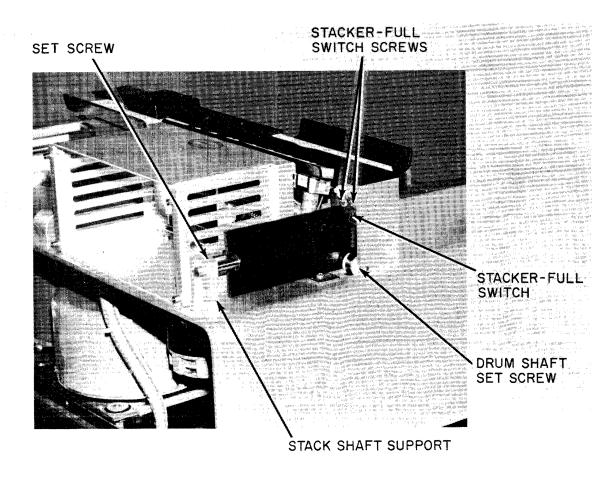


Figure 40. Stacker Assembly Rear View

- 7. Using a 1/16 Allen SCREWDRIVER, LOOSEN set screw in stacker casting holding stacker photocell, figure 25.
- 8. Tag black and white wires from photocell. Using AMP tool 465195-2, remove connectors from card cage.
 - 9. Remove photocell from rear of stacker casting, figure 39.
- 10. Replace photocell, align photocell flush with stacker casting faceplate, and tighten photocell set screw.
 - 11. Replace connectors in card cage.
- 12. Replace stacker roller making sure there is no vertical play in stacker roller shaft. Refer to step 11 of Replacement of First, Second and Third Stacker Roller Bearings.
 - 13. Reassembly in reverse order of disassembly.

REPLACEMENT OF NEGATOR SPRING

- 1. Remove card cage cover, sliding backward about 2" and lifting off, figure 27.
- 2. Using a 1/16 Allen wrench, LOOSEN set screw in stack shaft support, figure 40.
- 3. Remove two Phillips screws holding hopper full switch and move switch to the side.
- 4. Using a 5/64 Allen wrench, remove six 6 x 32 button head screws (1) retaining front panel and remove front panel, figure 20.
- 5. Using a 9/64 Allen wrench, remove two socket head screws (15) holding stacker support follower shaft casting, figure 41.
 - 6. Remove stacker shaft.
- 7. Move follower assembly toward front of card reader until screw holding negator spring appears on bottom of stacker shaft slide. Remove this screw, figure 41.
- 8. Using a .050 Allen wrench, LOOSEN set screw holding spring drum shaft, figure 20.
- 9. Push drum shaft in toward center of card reader and remove drum and spring.
 - 10. Replace spring drum and tighten set screw.
 - 11. Reassemble in reverse order of disassembly.

REPLACEMENT OF HOPPER EMPTY SWITCH

- 1. Using a 5/64 Allen wrench, remove four button head screws (3) figure 20, holding top panel cover.
- 2. Using a 3/32 Allen wrench, remove two socket head screws holding riffle cap, figure 21.
 - 3. Remove two connectors from hopper empty switch, figure 37.
- 4. Using a 1/16 Allen wrench, remove two button head screws holding switch, figure 37.
- 5. Replace switch and adjust so that microswitch is mechanically activated with card in hopper and disengaged with hopper empty.
 - 6. Reassemble in reverse order of disassembly.

REPLACEMENT OF STACKER FULL SWITCH

- 1. Remove card cage cover, sliding backward about 2" and lifting off, figure 27.
 - 2. Remove two Phillips head screws holding stacker full switch, figure 40.
 - 3. Unsolder leads from switch, and replace.
- 4. Remount switch and adjust so that switch is mechanically activated when stacker is almost full.
 - 5. Replace card cage cover.

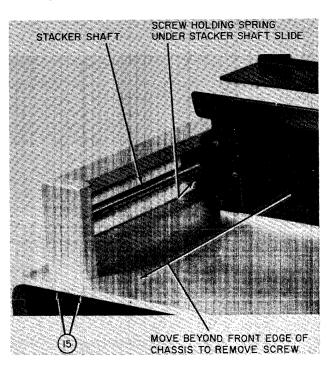


Figure 41. Stacker Assembly Front View

BOTTOM PLATE COMPONENT LOCATION

Figure 42 is an overall view of the Reader's Bottom Plate Component Location. This figure can be used as an aid for component locations and placements.

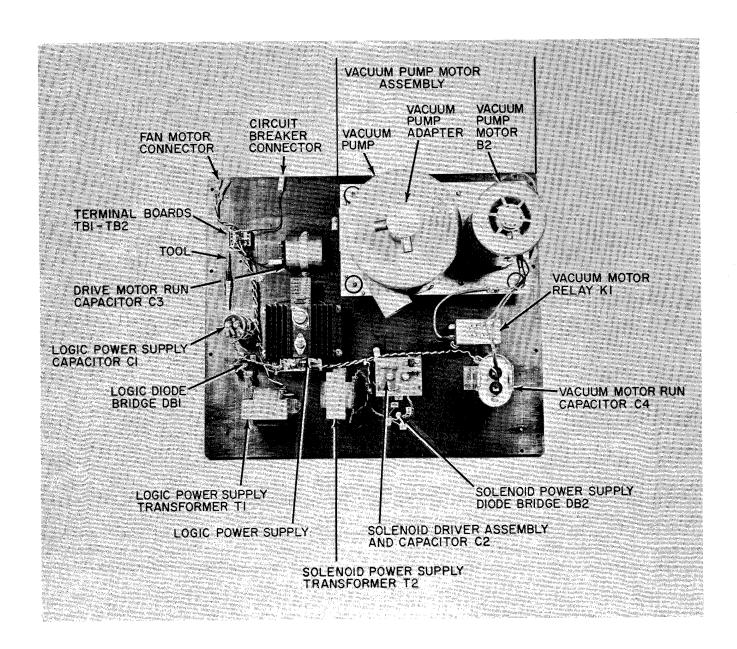


Figure 42. Bottom Plate Component Location

APPENDIX A

ELECTRICAL DRAWINGS

The electrical drawings included as part of this manual represent the standard Documation card reader. If special electrical drawings are required, they will be included as reduced bluelines and will supersede the standard drawings.

NOTES:

THIS SYMBOL 7 - C CATES C-ANSES

THE WIRING FOR THE Y ODO

SO SWITCH SHOWN IN "OUTPUT STACKER
FULL" CONDITION.

SWITCH SHOWN IN "INPUT HOPPER EMPTY" CONDITION.

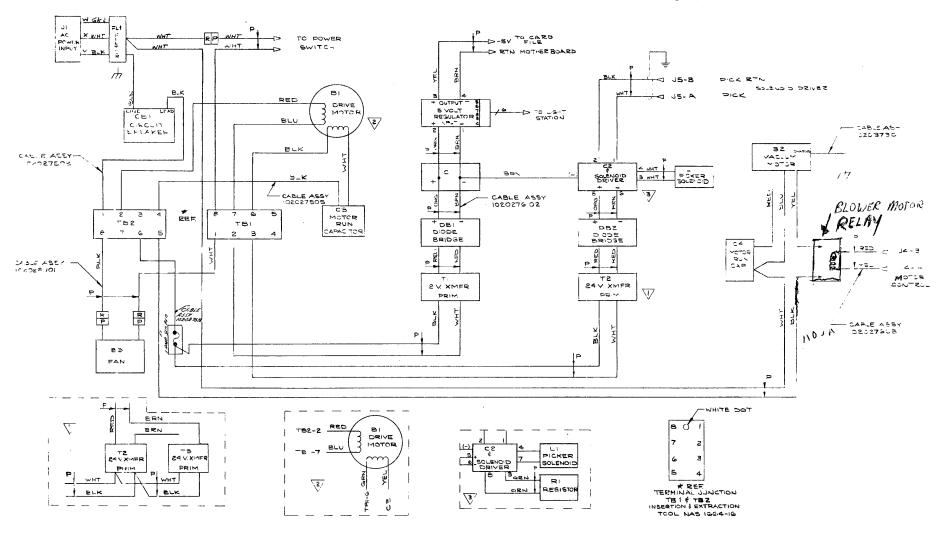


Figure Al. Wiring Diagram (Sheet 1 of 2) Dwg. No. 1040754A

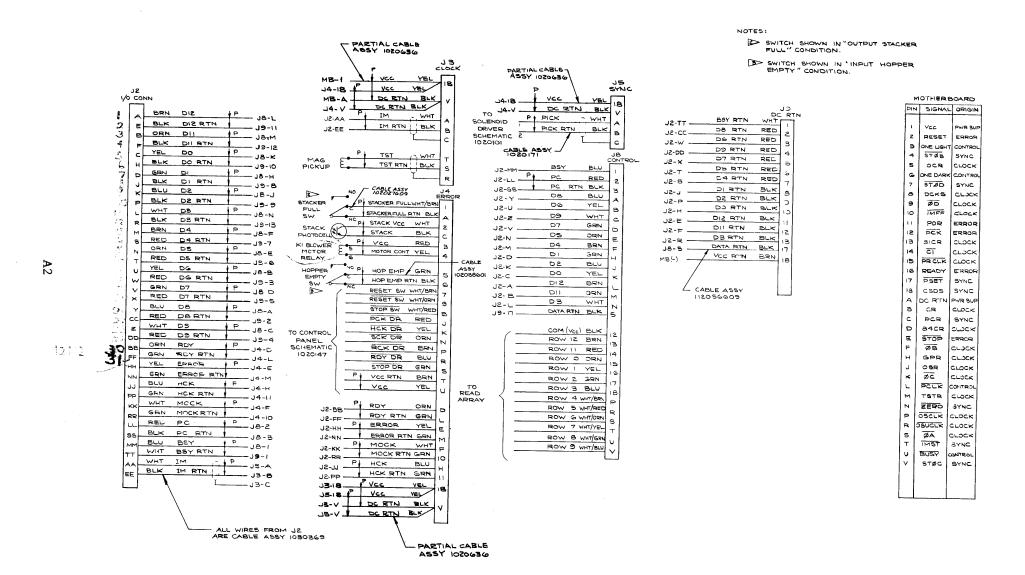


Figure Al. (Sheet 2 of 2)

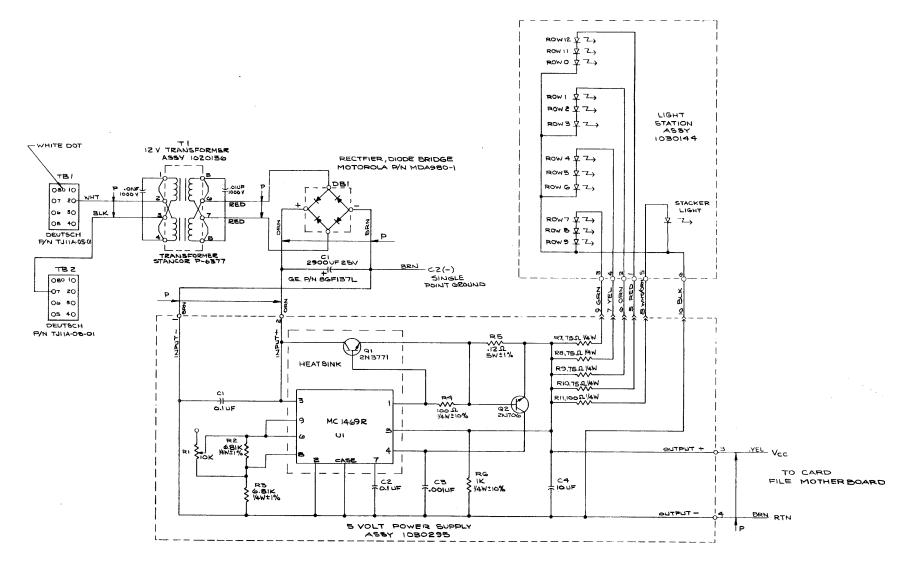


Figure A2. 5 Volt Power Supply Dwg. No. 1040506

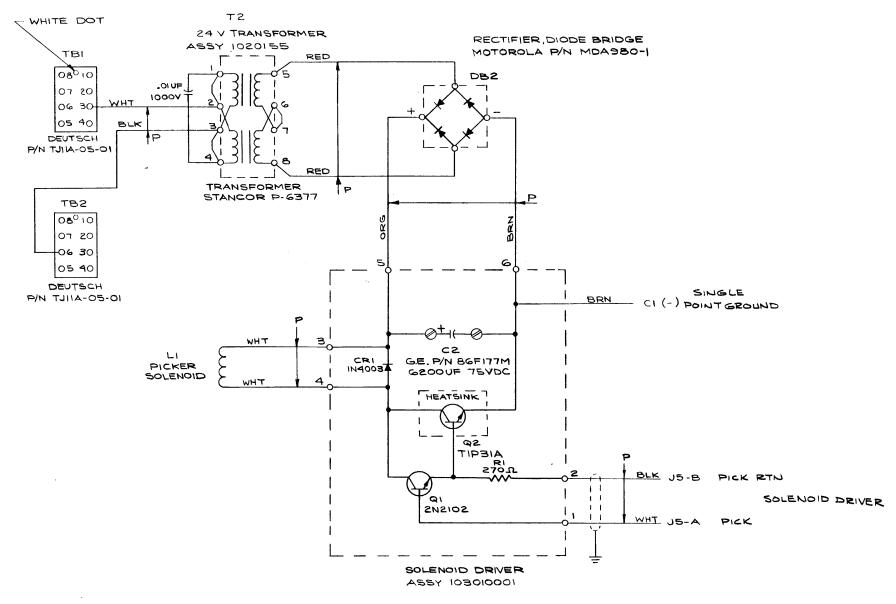
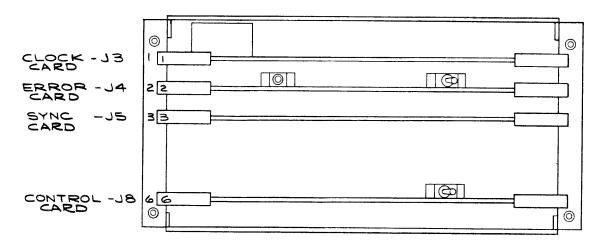


Figure A3. Solenoid Driver Dwg. No. 1030505



CARD FILE, REAR VIEW

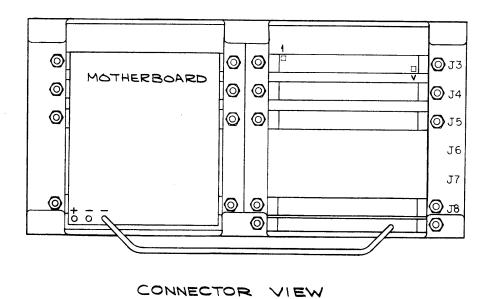
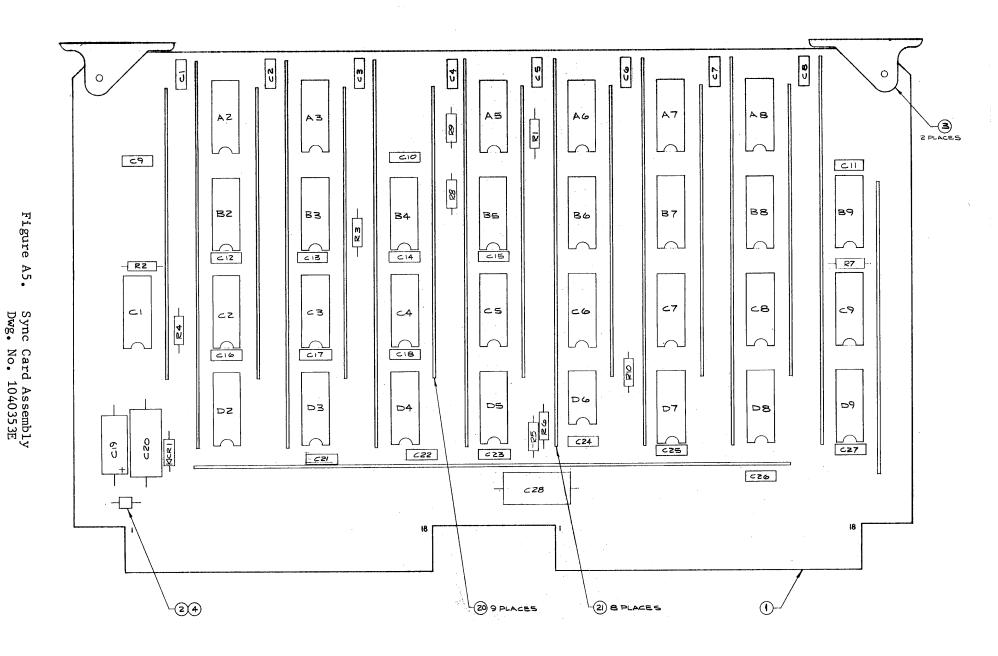


Figure A4. Card File



A6

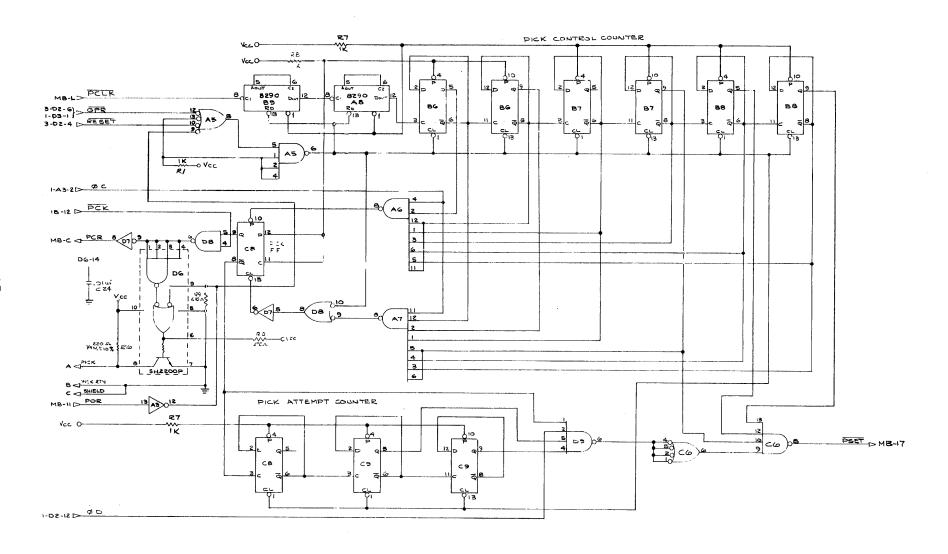


Figure A6. Sync Card Schematic (Sheet 1 of 3) Dwg. No. 1040604E

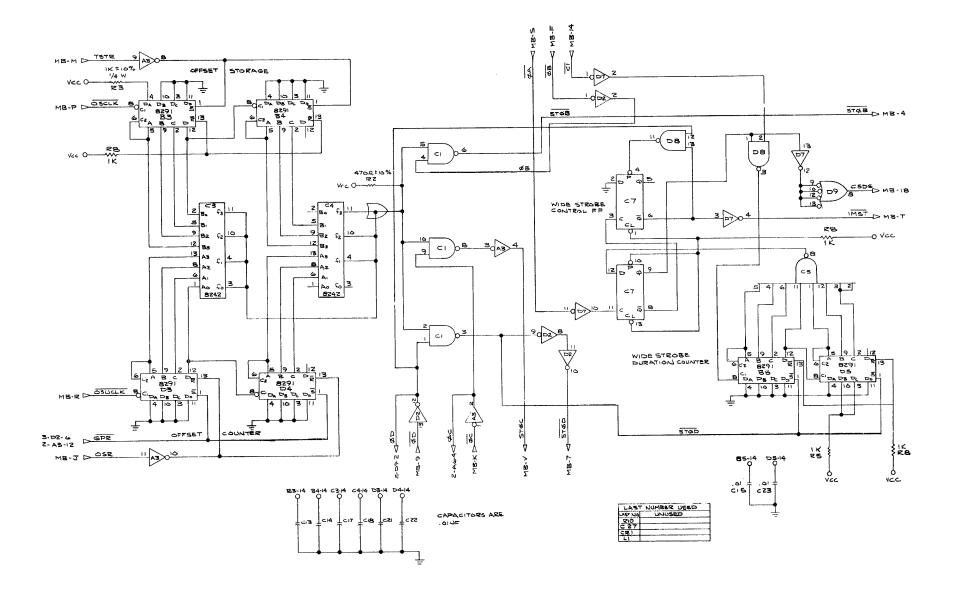
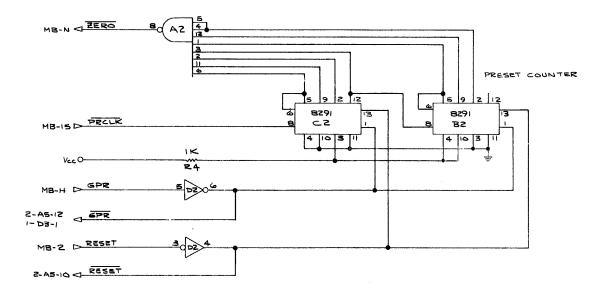


Figure A6. (Sheet 2 of 3)



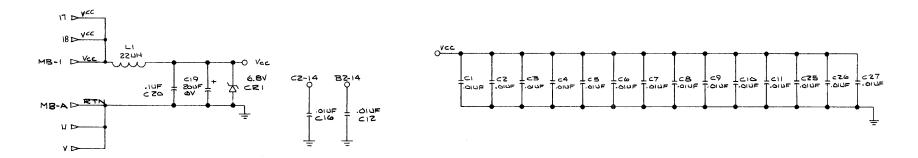


Figure A6. (Sheet 3 of 3)

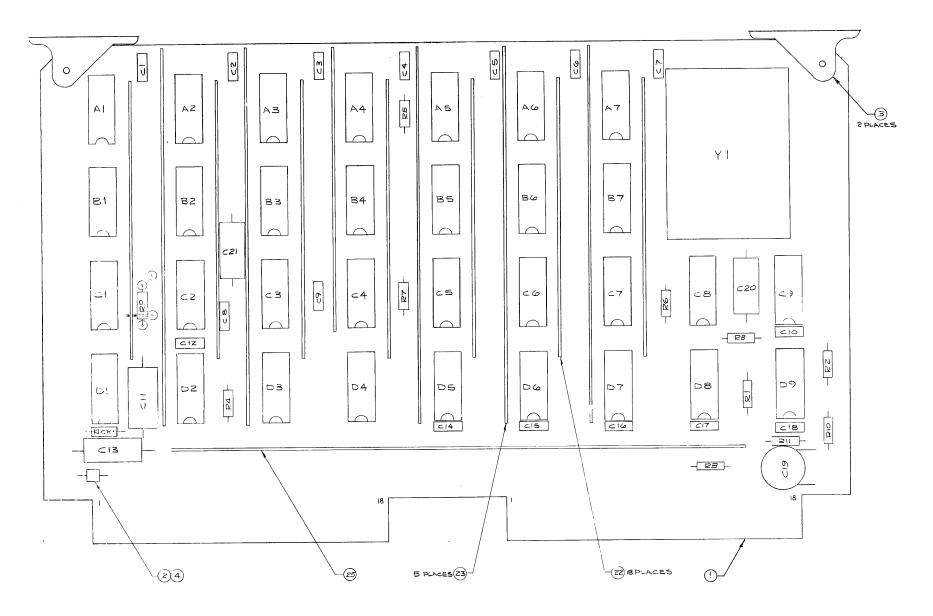


Figure A7. Clock Card Assembly Dwg. No. 1040765

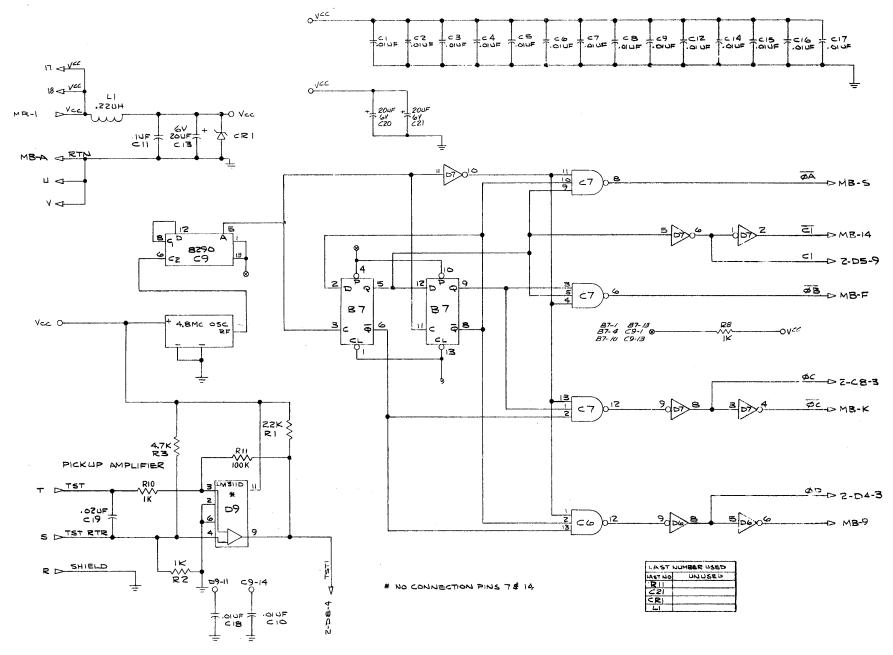


Figure A8. Clock Card Schematic (Sheet 1 of 3) Dwg. No. 1040802A

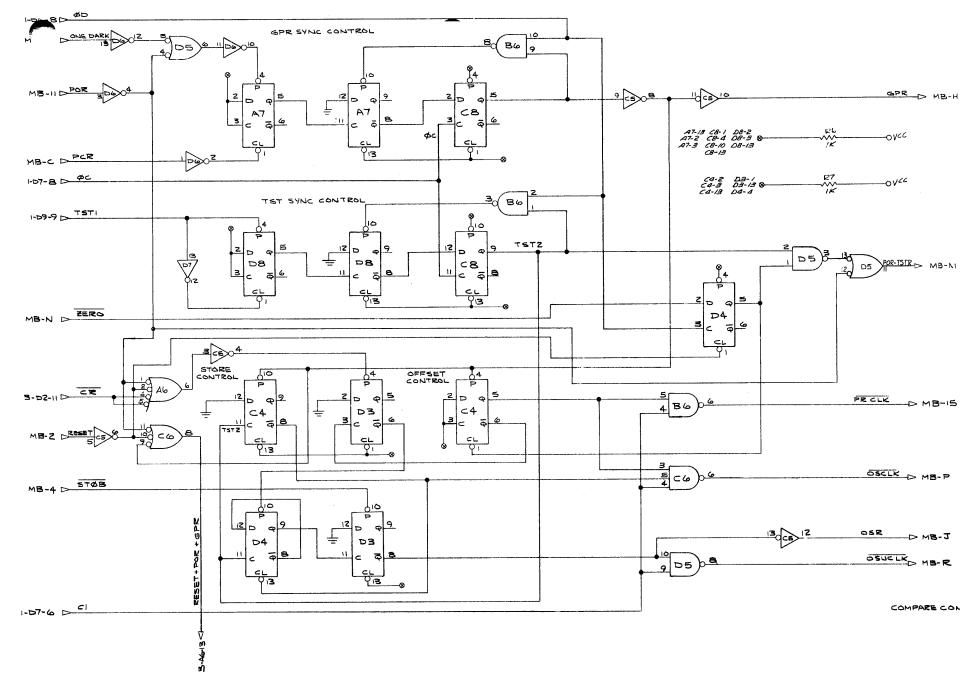


Figure A8. (Sheet 2 of 3)

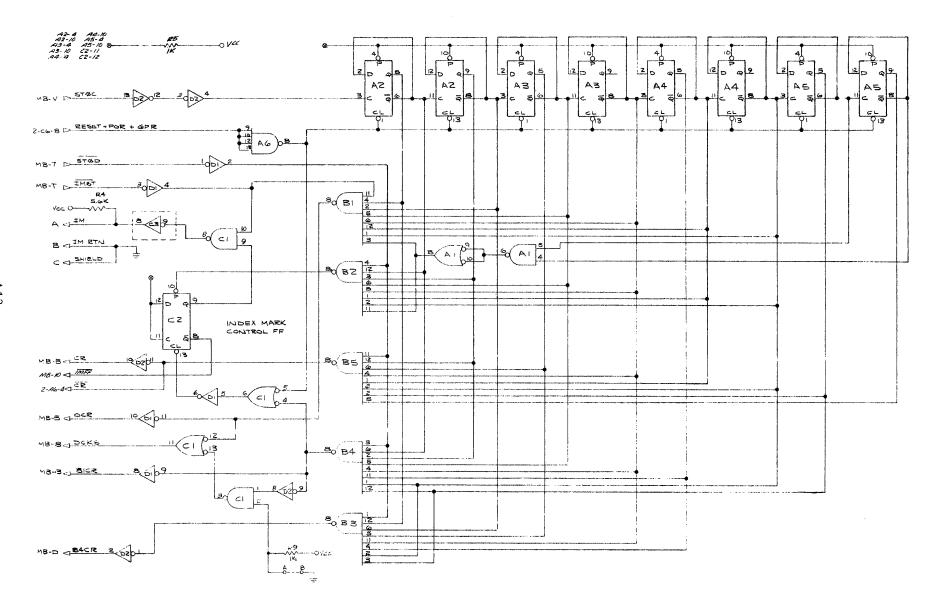


Figure A8. (Sheet 3 of 3)

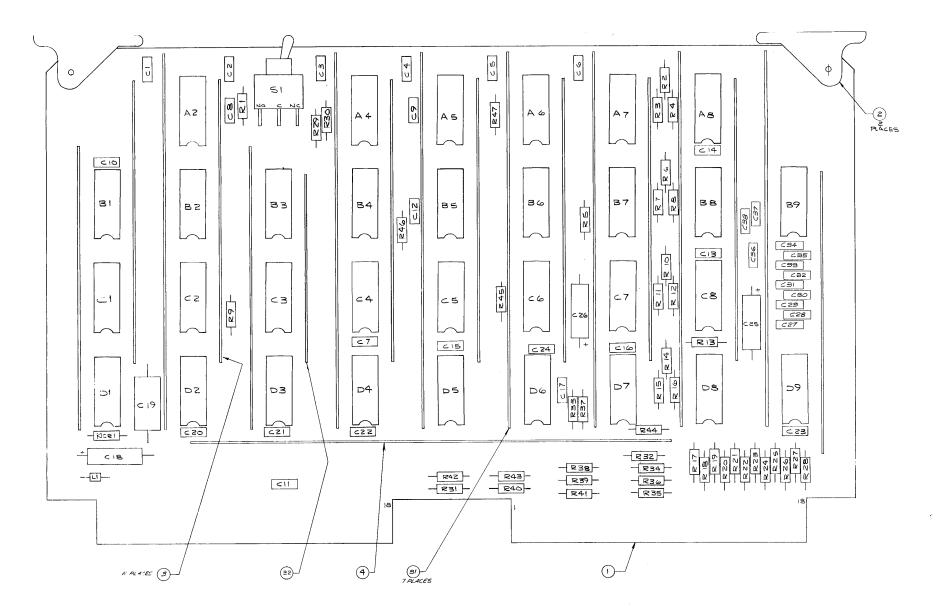


Figure A9. Control Card Assembly Dwg. No. 1040619D

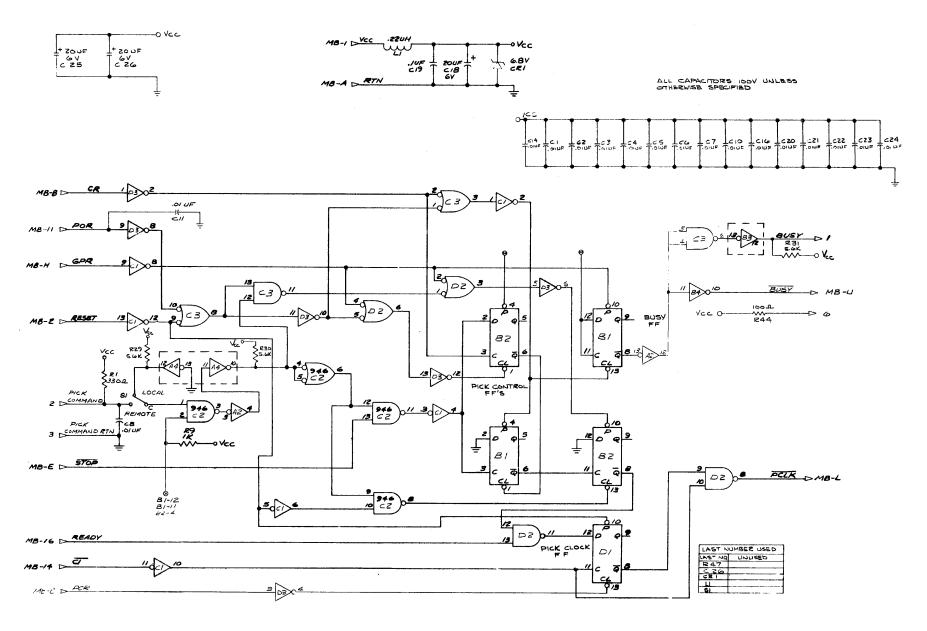


Figure A10. Control Card Schematic (Sheet 1 of 2) Dwg. No. 1040617D

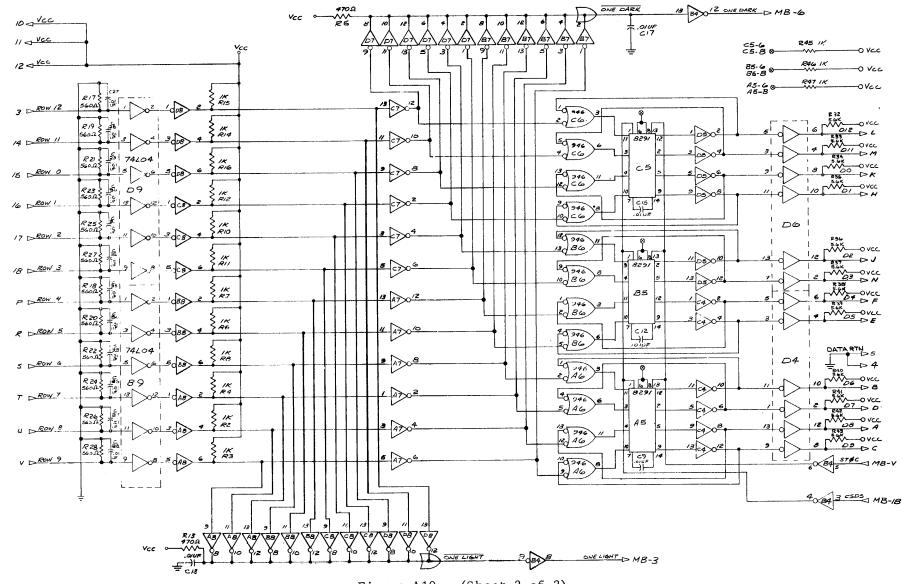


Figure A10. (Sheet 2 of 2)

Figure All. Error Card Assembly Dwg. No. 1040610B

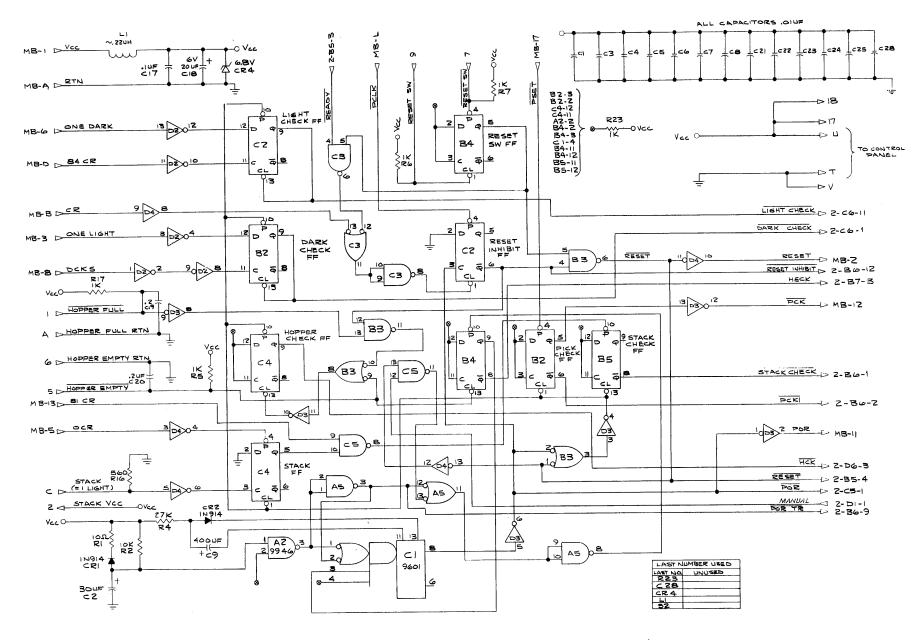


Figure A12. Error Card Schematic (Sheet 1 of 2) Dwg. No. 1040606B

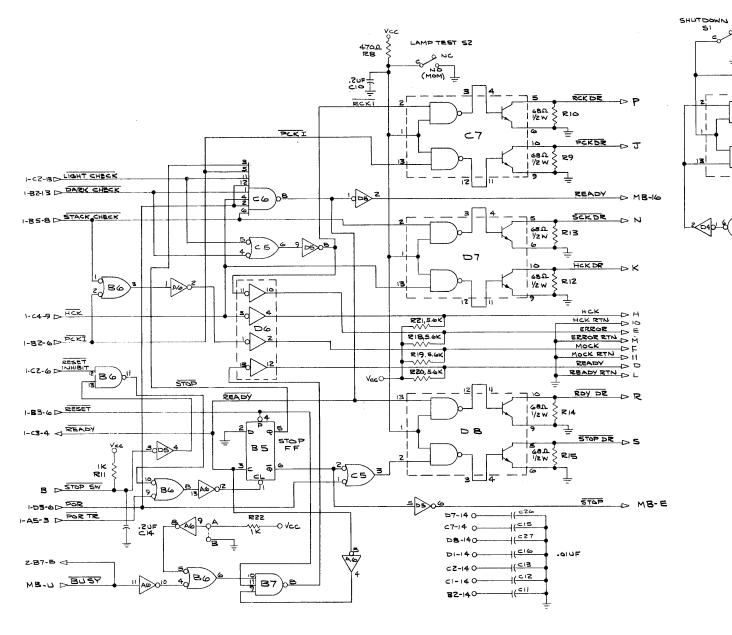


Figure A12. (Sheet 2 of 2)

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MANUAL (> 1-CB-12

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APPENDIX B

PARTS LIST

The following parts list includes all items that are considered field replaceable. Should damage occur through excessive abuse to such items as the picker casting, reader housing, etc., the reader should be returned to Documation Incorporated for repair

SCRIPTION	MANUFACTURER	PART NUMBER	QTY PER READER
P Modified Fork	AMP	583259-2LP	14
sy, Driver, Solenoid	Documation	1030100-01	1
sy, Follower, Picker	Documation	1230484	1
sy, Light Station	Documation	1030144	1
sy, P.C. Card, Clock	Documation	1040666-	1
sy, P.C. Card, Control	Documation	1040619-	1
sy, P.C. Card, Error	Documation	1040610-	1
sy, P.C. Card, Sync	Documation	1040353-	1
sy, Power Supply, 5V	Documation	1030295-02	1
ssy, Read Array	-Documation_	1020503-01	1
ssy, Solenoid	Documation	1020225	1
sy, Stack Photocell	Documation	1020382	1
sy, Switch, Hopper Empty	Documation	1020277	1
ssy, Switch, Stacker Full	Documation	1020211	1
sy, Timing Disc	Documation	1010223	1
sy, Transformer, 12V	Documation	1020156	1
sy, Transformer, 24V	Documation	1020155	1
aring, Sealed Ball	Kubar	SFR188TT(3)	10
aring, Sealed Ball	Kubar	SFR4TT(3)	10
lt, Blower	Gates	5M545	1
lt, Drive	Dick	80XL-025	$\frac{1}{2}$
t, Drive	Dick	160XL-025 _	1
lt, Drive	Dick	70XL-025	1
ower	Lamb	115626	1
ilb, 6V @ 0.2A	GE ~	#328	7
upacitor, 4600 uf @ 15 VDC	GE	86F119M	1
upacitor, Motor Run, 4 uf @ 330 VAC (supplied with Drive Motor)		KKX33U40 5 Q	1
pacitor, Motor Run, 17.5 uf @ 370 VAC	GE	45F279	1
pstan, Drive	Documation	1020059	4
rcuit Breaker, 8A	Airpax	UPG1162802	1
ntact	Elco	60-8017-0313	36
ntact, AMP Leaf, 18-21 ga.	AMP	42717 - 4LP	4
ntact, AMP Leaf, 22-26 ga.	AMP	42702-3LP	59
ntact, Terminal Junction	Deutsch	1841-1-5616	14
		1010105	7
upling, Solenoid	Documation	1010105	1

HOPPER Empty Switght 20027701

Hoppen Emply Switch

Bett Drive (80 xx 025)

Reset switch (5tent)

PICKER ASSY & BEARINGS CAPSTANS (ROLLGES)

BELT, DRICE 16 OXL-625

20027701 00000281 00000320

0000 1514 20002701 00000 283 00000 280

PARTS LIST

Lube, No. 2 Lube, No. 2 Motor, Drive, 1800 RPM @ 60 Hz Motor, Blower, 3350 RPM @ 60 Hz Mount, Rubber Mount, Rubber Mount, Rubber Lord Lopha Lord Lord Lord Lord Lord Lord Lord Lord Lord Lopha Lord Lord Lopha Lord Lord Lopha Lopha Lopha Lopha Lopha Lopha Lopha Lopha Lopha Loph	DESCRIPTION	MANUFACTURER	PART NUMBER	TY PEI
Motor, Drive, 1800 RPM @ 60 Hz Hurst HB-1800 1 Motor, Blower, 3350 RPM @ 60 Hz GE KCP19PG 1 Mount, Rubber Lord 100PD2 2 Mount, Rubber Lord 100PD4 2 Pickup Assy, Magnetic Documation 1020161 1 Power Cord Assy Documation 1020148 1 Pulley, Drive, Nylon Dick 15XL-037 3 Pulley, Drive, Nylon Dick 14XL-037 3 Pulley, Drive, Nylon Documation 132080404 2 Rectifier, Diode Bridge, 50V Motorola MDA980-1 2 Relay Hamlin 733-11-150 1 Shaft, Drive Roller Documation 1010032 2 Shaft, Pick Documation 1010039 1 Shaft, Stack Drive Documation 1010030-02 5 Shaft, Stack Drive Documation 1010030-03 1 Snap Ring, 1/4" Waldes 5100-2S 4 Spacer, Bearing W. Berg SS2-28 selec-30 ted 3 Spring, Negator Hunter SL5E17 1 Syring, Negator Hunter SL6F24 2 Spring, Solenoid Lee LE-026-C2-J 1 Switch, Alt. Act., White Barrier Dialco 513-1410-004 1 Switch, N.O., Snap Action Dialco 513-1610-004 1 Switch, N.O., SPST, White Barrier Dialco 513-0110-004 1 Tie, Cable Panduit SST-1 20	Housing, Output Conn. (J2)	Elco		1
Motor, Blower, 3350 RPM @ 60 Hz Mount, Rubber Lord MoPD4 2 Mount, Rubber Lord MoPD4 2 Mount, Rubber Documation Mo20161 1 Power Cord Assy Pulley, Drive, Nylon Motorola Moderation M	Lube, No. 2	Ledex	124048-001	1
Mount, Rubber Lord 100PD2 2 Mount, Rubber Lord 100PD4 2 Pickup Assy, Magnetic Documation 1020161 1 Power Cord Assy Documation 1020148 1 Pulley, Drive, Nylon Dick 15XL-037 3 Pulley, Drive, Nylon Documation 132080404 2 Rectifier, Diode Bridge, 50V Motorola MDA980-1 2 Relay Hamlin 733-11-150 1 Shaft, Drive Roller Documation 1010022 2 Shaft, Pick Documation 1010039 1 Shaft, Stack Drive Documation 1010030-02 5 Shaft, Stack Drive Documation 1010030-03 1 Spacer, Bearing W. Berg S52-28 J selector 10 Spring, Negator Hunter SL5E17 1 Spring, Negator Hunter SL6F24 2 Spring, Solenoid Lee LE-026-C2-J 1 Switch, Alt. Act., White Barrier <td>Motor, Drive, 1800 RPM @ 60 Hz</td> <td>Hurst</td> <td>HB-1800</td> <td>1</td>	Motor, Drive, 1800 RPM @ 60 Hz	Hurst	HB-1800	1
Mount, Rubber Lord 100PD4 2 Pickup Assy, Magnetic Documation 1020161 1 Power Cord Assy Documation 1020148 1 Pulley, Drive, Nylon Dick 15XL-037 3 Pulley, Drive, Nylon Documation 132080404 2 Rectifier, Diode Bridge, 50V Motorola MDA980-1 2 Relay Hamlin 733-11-150 1 Shaft, Drive Roller Documation 1010022 2 Shaft, Stack Drive Documation 1010039 1 Shaft, Stack Drive Documation 1010030-02 5 Shaft, Stack Drive Documation 1010030-02 5 Shaft, Stack Drive Documation 1010030-03 1 Spacer, Bearing W. Berg SS2-28 selec-28 selec-3 ted 10 Spring, Negator Hunter SL5E17 1 Spring, Negator Hunter SL6F24 2 Spring, Solenoid Lee LE-026-C2-J 1 <td< td=""><td>Motor, Blower, 3350 RPM @ 60 Hz</td><td>GE</td><td>KCP19PG</td><td>1</td></td<>	Motor, Blower, 3350 RPM @ 60 Hz	GE	KCP19PG	1
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Pulley, Drive, Nylon Dick 15XL-037 3 Pulley, Drive, Nylon Dick 14XL-037 3 Pulley, Drive, Nylon Documation 132080404 2 Rectifier, Diode Bridge, 50V Motorola MDA980-1 2 Relay Hamlin 733-11-150 1 Shaft, Drive Roller Documation 1010022 2 Shaft, Pick Documation 1010039 1 Shaft, Stack Drive Documation 1010030-02 5 Shaft, Stack Drive Documation 1010030-03 1 Snap Ring, 1/4" Waldes 5100-2S 4 Spacer, Bearing W. Berg SS2-28] selected 10 Spring, Negator Hunter SL5E17 1 Spring, Solenoid Lee LE-026-C2-J 1 Switch, Alt. Act., White Barrier Dialco 513-1410-004 1 Switch, N.O., Snap Action Dialco 513-0110-004 1 Tie, Cable Panduit SST-1 20	Pickup Assy, Magnetic	Documation	1020161	1
Pulley, Drive, Nylon Dick 14XL-037 3 Pulley, Drive, Nylon Documation 132080404 2 Rectifier, Diode Bridge, 50V Motorola MDA980-1 2 Relay Hamlin 733-11-150 1 Shaft, Drive Roller Documation 1010022 2 Shaft, Pick Documation 1010039 1 Shaft, Stack Drive Documation 1010030-02 5 Shaft, Stack Drive Documation 1010030-03 1 Snap Ring, 1/4" Waldes 5100-2S 4 Spacer, Bearing W. Berg SS2-28] selector 10 Spring, Negator Hunter SL5E17 1 Spring, Negator Hunter SL6F24 2 Spring, Solenoid Lee LE-026-C2-J 1 Switch, Alt. Act., White Barrier Dialco 513-1410-004 1 Switch, N.O., Spst, White Barrier Dialco 513-0110-004 1 Tie, Cable Panduit SST-1 20	Power Cord Assy	Documation	1020148	1
Pulley, Drive, Nylon Documation 132080404 2 Rectifier, Diode Bridge, 50V Motorola MDA980-1 2 Relay Hamlin 733-11-150 1 Shaft, Drive Roller Documation 1010022 2 Shaft, Pick Documation 1010039 1 Shaft, Stack Drive Documation 1010030-02 5 Shaft, Stack Drive Documation 1010030-03 1 Snap Ring, 1/4" Waldes 5100-2S 4 Spacer, Bearing W. Berg SS2-28 lec-28 lec-30 ted 10 Spring, Negator Hunter SL5E17 1 Spring, Negator Hunter SL6F24 2 Spring, Solenoid Lee LE-026-C2-J 1 Switch, Alt. Act., White Barrier Dialco 513-1410-004 1 Switch, N.O., Snap Action Dialco 513-0110-004 1 Tie, Cable Panduit SST-1 20	Pulley, Drive, Nylon	Dick	15XL-037	3
Rectifier, Diode Bridge, 50V Relay Hamlin 733-11-150 1 Shaft, Drive Roller Documation Documation 1010022 2 Shaft, Pick Documation Documation 1010039 1 Shaft, Stack Drive Documation Documation 1010030-02 5 Shaft, Stack Drive Documation 1010030-03 1 Snap Ring, 1/4" Waldes Spacer, Bearing W. Berg Ss2-28] selec- 10-30 Spring, Negator Hunter SL5E17 Spring, Negator Hunter SL6F24 Spring, Solenoid Lee LE-026-C2-J Switch, Alt. Act., White Barrier Dialco Switch, N.O., SpST, White Barrier Dialco Si3-0110-004 Tie, Cable Panduit SST-1 20	Pulley, Drive, Nylon	Dick	14XL-037	3
Hamlin 733-11-150 1	Pulley, Drive, Nylon	Documation	132080404	2
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Shaft, Pick Shaft, Stack Drive Shaft, Stack Drive Documation D	Relay	Hamlin	733-11-150	1 .
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Shaft, Stack Drive Documation 1010030-03 1 Snap Ring, 1/4" Waldes 5100-2S 4 Spacer, Bearing W. Berg SS2-28] selectored ted 10 Spring, Negator Hunter SL5E17 1 Spring, Negator Hunter SL6F24 2 Spring, Solenoid Lee LE-026-C2-J 1 Switch, Alt. Act., White Barrier Dialco 513-1410-004 1 Switch, N.O., Snap Action Dialco 513-1610-004 1 Switch, N.O., SPST, White Barrier Dialco 513-0110-004 1 Tie, Cable Panduit SST-1 20	Shaft, Pick	Documation	1010039	1
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Spring, Negator Spring, Solenoid Lee LE-026-C2-J Switch, Alt. Act., White Barrier Dialco Switch, N.O., Snap Action Dialco Dialco 513-1410-004 1 Switch, N.O., SPST, White Barrier Dialco 513-0110-004 1 Tie, Cable Panduit SST-1 20	Spacer, Bearing	W. Berg	SS2-28] selec-	10
Spring, Solenoid Lee LE-026-C2-J Switch, Alt. Act., White Barrier Dialco Switch, N.O., Snap Action Dialco Dialco Switch, N.O., SPST, White Barrier Dialco Dialco Si3-1610-004 1 Switch, N.O., SPST, White Barrier Dialco SST-1 20	Spring, Negator	Hunter	SL5E17	1
Switch, Alt. Act., White Barrier Dialco 513-1410-004 1 Switch, N.O., Snap Action Dialco 513-1610-004 1 Switch, N.O., SPST, White Barrier Dialco 513-0110-004 1 Tie, Cable Panduit SST-1 20	Spring, Negator	Hunter	SL6F24	2
Switch, N.O., Snap Action Dialco Switch, N.O., SPST, White Barrier Dialco Dialco 513-1610-004 1 Tie, Cable Panduit SST-1 20	Spring, Solenoid	Lee	LE-026-C2-J	1
Switch, N.O., SPST, White Barrier Dialco 513-0110-004 1 Tie, Cable Panduit SST-1 20	Switch, Alt. Act., White Barrier	Dialco	513-1410-004	1
Tie, Cable Panduit SST-1 20	Switch, N.O., Snap Action	Dialco	513-1610-004	. 1
	Switch, N.O., SPST, White Barrier	Dialco	513-0110-004	1
Tie, Cable Panduit SST-4 2	Tie, Cable	Panduit	SST-1	20
	Tie, Cable	Panduit	SST-4	2

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724-11-159 RELAY

29-18520 - 724-11-159 RELAY/

TMECC - RUSET SWITCH 51,3-1601-604

APPENDIX C

SIGNAL MNEMONICS AND ABBREVIATIONS

Appendix C contains the description, location and originating source for the Signal Mnemonics and Abbreviations used in this manual.

SIGNAL MNEMONICS AND ABBREVIATIONS

MNEMONIC	DESCRIPTION	LOCATION	ORIGINATING SOURCE
Vcc	+5 volts	MB-1	5 volt power supply (Mother Board)
RTN	+5 volt return	MB-A	5 volt power supply (Mother Board)
TST	Timing Strobe	J3-T	Reluctance Pickup
TST RTN	Timing Strobe Return	J3 - S	Reluctance Pickup
SHIELD	Shield for Timing Strobe	J3 - R	Reluctance Pickup
TST1	Timing Strobe One	D9- 9	Clock Card
ϕ A	Clock Phase A	MB-S	Clock Card
C1	Basic Clock	MB-14	Clock Card
ϕ B	Clock Phase B	MB-F	Clock Card
φC	Clock Phase C	MB-K	Clock Card
φD	Clock Phase D	MB-9	Clock Card
ONE DARK	Read Station Any Dark	MB-6	Control Card
POR	Power On Reset	MB-11	Error Card
PCR	Pick Control Reset	MB-C	Sync Card
ZERO	Preset Decode	MB-N	Sync Card
RESET	Gated Reset Switch	MB-2	Sync Card
ST ø B	Column Strobe Phase B	MB-4	Sync Card
GPR	Good Pick Reset	MB-H	Clock Card
TST2	Timing Strobe Two	C8-9	Clock Card
TSTR	Timing Strobe Reset	MB-N	Clock Card
PRCLK	Preset Clock	MB-15	Clock Card
OSCLK	Offset Clock	MB-P	Clock Card
OSR	Offset Reset	MB-J	Clock Card
OSUCLK	Offset Up-Clock	MB-R	Clock Card
STØC	Column Strobe Phase C	MB-V	Sync Card
ST ø D	Column Strobe Phase D	MB-7	Sync Card
IMST	Index Mark Strobes	MB-T	Sync Card
IM	Index Marks	J3 - A	Clock Card
IM RTN	Return for Index Marks	J3-B	Clock Card
SHIELD	Shield for Index Marks	J3-C	Clock Card
CR	Column Reset	мв-в	Clock Card
OCR	Zero Column Reset	MB-5	Clock Card

SIGNAL MNEMONICS AND ABBREVIATIONS (Continued)

MNEMONIC	DESCRIPTION	LOCATION	ORIGINATING SOURCE
DCKS	Dark Check Strobes	MB-8	Clock Card
81CR	81st Column Reset	MB-13	Clock Card
84CR	84th Column Reset	MB-D	Clock Card
PICK COMMAND	Pick Command Input	J8 - 2	Control Card
PICK COMMAND RTN	Pick Command Input Return	J8 - 3	Control Card
STOP	Stop	MB-E	Error Card
READY	Ready	MB-16	Error Card
BUSY	Busy Output	J8 - 1	Control Card
PCLK	Pick Clock	MB-L	Control Card
<i>l</i> cc	+5V to Read Sensor Array	J8-12	Control Card
Row 12	Read Sensor Input Row 12	J8 - 13	Control Card
Row 11	Read Sensor Input Row 11	J8 - 14	Control Card
Row 0	Read Sensor Input Row 0	J8 - 15	Control Card
Row 1	Read Sensor Input Row 1	J8 - 16	Control Card
low 2	Read Sensor Input Row 2	J8 - 17	Control Card
low 3	Read Sensor Input Row 3	J8 - 18	Control Card
low 4	Read Sensor Input Row 4	J8 - Р	Control Card
Row 5	Read Sensor Input Row 5	J8 - R	Control Card
low 6	Read Sensor Input Row 6	J8 - S	Control Card
low 7	Read Sensor Input Row 7	J8-T	Control Card
low 8	Read Sensor Input Row 8	J8 - U	Control Card
Row 9	Read Sensor Input Row 9	J8-V	Control Card
NE LIGHT	Read Station Any Light	MB-3	Control Card
012	Data Row 12 Output	J8-L	Control Card
011	Data Row 11 Output	J8 - M	Control Card
00	Data Row O Output	J8 - K	Control Card
01	Data Row 1 Output	J8 - H	Control Card
2	Data Row 2 Output	J8 - J	Control Card
3	Data Row 3 Output	J8-N	Control Card
94	Data Row 4 Output	J8 - F	Control Card
05	Data Row 5 Output	J8 - E	Control Card
TN	Data Drivers Return	J8 - 5	Control Card
06	Data Row 6 Output	J8 - B	Control Card

SIGNAL MNEMONICS AND ABBREVIATIONS (Continued)

MNEMONI C	DESCRIPTION	LOCATION	ORIGINATING SOURCE
D7	Data Row 7 Output	J8 - D	Control Card
D8	Data Row 8 Output	J8 - A	Control Card
D9	Data Row 9 Output	J8-C	Control Card
CSDS	Column Storage Data Strobe	MB-18	Sync Card
HOPPER FULL	Hopper Full Switch	J4-1	Error Card
HOPPER FULL RTN	Hopper Full Switch Return	J4-A	Error Card
HOPPER EMPTY RTN	Hopper Empty Switch Return	J4 - 6	Error Card
HOPPER EMPTY	Hopper Empty Switch	J4- 5	Error Card
STACK	Stack Sensor Input	J4 - С	Error Card
STACK Vcc	Stack Sensor +5 volts	J4- 2	Error Card
RESET SW	Reset Switch Normally Open	J4 - 9	Error Card
RESET SW	Reset Switch Normally Closed	J4- 7	Error Card
PSET	Pick Check Set	MB-17	Sync Card
LIGHT CHECK	Light Check	C2-9	Error Card
DARK CHECK	Dark Check	B2-9	Error Card
HECK	Hopper Empty Check	B4-8	Error Card
PCK	Pick Check	B2-5	Error Card
STACK CHECK	Output Stacker Check	B5-8	Error Card
PCKI	Pick Check Indicator	B2-2	Error Card
НСК	Input or Output Hopper Check	C4-9	Error Card
SHUTDOWN STATUS	Mode Switch Input	S1-C	Error Card
POR TR	Power on Reset Trigger	A5-12	Error Card
STOP SW	Stop Switch Input	J4-B	Error Card
RCK DR	Read Check Lamp Driver	J4 - P	Error Card
PCK DR	Pick Check Lamp Driver	J4 - P	Error Card
SCK DR	Stack Check Lamp Driver	J4-N	Error Card
HCK DR	Hopper Check Lamp Driver	J4 - K	Error Card
HCK	Hopper Check Output	J4-H	Error Card
HCK RTN	Hopper Check Output Return	J4-10	Error Card
ERROR	Error Output	J4- E	Error Card
ERROR RTN	Error Output Return	J4 - M	Error Card
MOCK	Motion Check Output	J4-F	Error Card

SIGNAL MNEMONICS AND ABBREVIATIONS (Continued)

MNEMONIC	DESCRIPTION	LOCATION	ORIGINATING SOURCE
MOCK RTN	Motion Check Output Return	J 4- 11	Error Card
READY	Ready Output	J4-D	Error Card
READY RTN	Ready Output Return	J4-L	Error Card
RDY DR	Ready Lamp Driver	J4-R	Error Card
STOP DR	Stop Lamp Driver	J4 - S	Error Card
PICK	Pick Driver Output	J5 - A	Sync Card
PICK RTN	Pick Driver Output Return	J5 - B	Sync Card
SHIELD	Shield for PICK	J5 - C	Sync Card
BUSY	Busy Signal	MB-U	Control Card