

# GENERAL PROGRAM LIBRARY

Relocation Offsets

9.2.012

DR. JOHN MANIOTES  
COMPUTER TECHNOLOGY DEPT.  
PURDUE UNIVERSITY  
CALUMET CAMPUS  
HAMMOND, IN 46323

9.2.012

COMPUTER  
TECHNOLOGY

Disclaimer

Although this program was tested by its author prior to submission, no warranty, express or implied, is made by the author, 1620 USERS Group, or IBM as to the accuracy and functioning of the program and related program material and no responsibility is assumed by the author, 1620 USERS Group, or IBM in connection therewith.

Modifications or revisions to this program, as they occur, will be announced in the appropriate Catalog of Programs for IBM Data Processing Systems. When such an announcement occurs, users should order a complete new program from the Program Information Department.

## 1620 USERS GROUP PROGRAM REVIEW AND EVALUATION

(fill out in typewriter or pencil, do not use ink)

Program No. \_\_\_\_\_

Date \_\_\_\_\_

Program Name: \_\_\_\_\_

1. Does the abstract adequately describe what the program is and what it does? Yes \_\_\_ No \_\_\_

Comment \_\_\_\_\_

2. Does the program do what the abstract says? Yes \_\_\_ No \_\_\_

Comment \_\_\_\_\_

3. Is the Description clear, understandable, and adequate? Yes \_\_\_ No \_\_\_

Comment \_\_\_\_\_

4. Are the Operating Instructions understandable and in sufficient detail? Yes \_\_\_ No \_\_\_

Comment \_\_\_\_\_

Are the Sense Switch options adequately described (if applicable)? Yes \_\_\_ No \_\_\_

Are the mnemonic labels identified or sufficiently understandable? Yes \_\_\_ No \_\_\_

Comment \_\_\_\_\_

5. Does the source program compile satisfactorily (if applicable)? Yes \_\_\_ No \_\_\_

Comment \_\_\_\_\_

6. Does the object program run satisfactorily? Yes \_\_\_ No \_\_\_

Comment \_\_\_\_\_

7. Number of test cases run \_\_\_\_\_. Are any restrictions as to data, size, range, etc. covered adequately in description? Yes \_\_\_ No \_\_\_

Comment \_\_\_\_\_

8. Does the Program Meet the minimal standards of the 1620 Users Group? Yes \_\_\_ No \_\_\_

Comment \_\_\_\_\_

9. Were all necessary parts of the program received? Yes \_\_\_ No \_\_\_

Comment \_\_\_\_\_

10. Please list on the back any suggestions to improve the usefulness of the program. These will be passed onto the author for his consideration.

Please return to:

Your Name \_\_\_\_\_

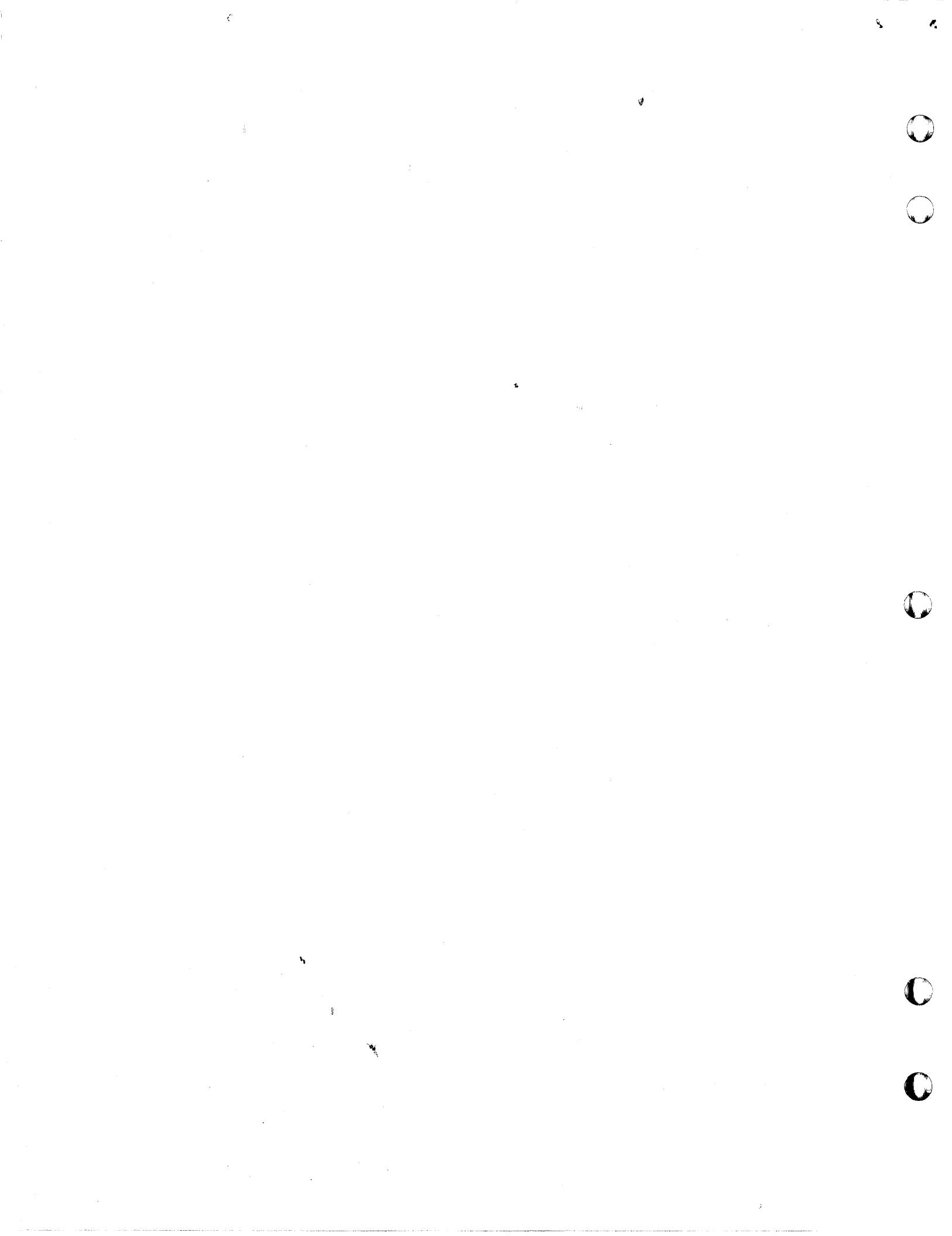
Mr. Richard L. Pratt  
Data Corporation  
7500 Old Xenia Pike  
Dayton, Ohio 45432

Company \_\_\_\_\_

Address \_\_\_\_\_

User Group Code \_\_\_\_\_

THIS REVIEW FORM IS PART OF THE 1620 USER GROUP ORGANIZATION'S PROGRAM REVIEW AND EVALUATION PROCEDURE. NONMEMBERS ARE CORDIALLY INVITED TO PARTICIPATE IN THIS EVALUATION.



RELOCATION OFFSETS

PROGRAM MANUAL

DECK KEY

P. O. Roberts

CIVIL ENGINEERING SYSTEMS LABORATORY  
Massachusetts Institute of Technology

October, 1961

Publication 147

Deck	1	Source Relocation Offsets Pt. II
Deck	2	Source Relocation Offsets Pt. I
Deck	3	Object Relocation Offsets Pt. I
Deck	4	Object Relocation Offsets Pt. II

Sponsored by  
Massachusetts Department of Public Works  
In co-operation with  
U. S. Bureau of Public Roads  
Contract 1017-Mass HPS-1(16)

1620 9.2.012

## ACKNOWLEDGEMENTS

The author wishes to gratefully acknowledge the research support provided by the Massachusetts Department of Public Works in cooperation with the U.S. Bureau of Public Roads. The support has made possible investigations in the economical location and design of highway facilities in the search for new and better methods of highway engineering.

## RELOCATION OFFSETS

by  
P. O. Roberts  
Assistant Professor of Civil Engineering  
M.I.T. Civil Engineering Systems Laboratory

### Purpose

Frequently during the course of designing a highway or railroad, situations arise in which the design engineer would like to change the alignment that has been chosen. This can occur because of a misjudgment of the quantities incurred or because of a change in the design situation, such as the continued growth of a subdivision or opposition of the public to the destruction of a park or historic building. Frequently, the change involved is small enough that the original survey information is still valid and usable.

Whatever the reason for the change, the work involved in recomputation is formidable. New geometry must be calculated. Equivalent stations on the new centerline must be calculated and offset distance from the original survey line, or base line, to the new centerline must be established. These offsets are then used for correcting the cross section sheets. The program is designed to relieve the burden of computation which alignment changes place on the engineer. See Figure 1.

### Description

The program is accomplished in two parts. Part One computes the geometry of the baseline and the new centerline, given the state plane coordinates of the P.I.'s and one parameter defining each curve. Part Two works with the table of geometry prepared by Part One and computes the centerline stations and offsets for each baseline station.

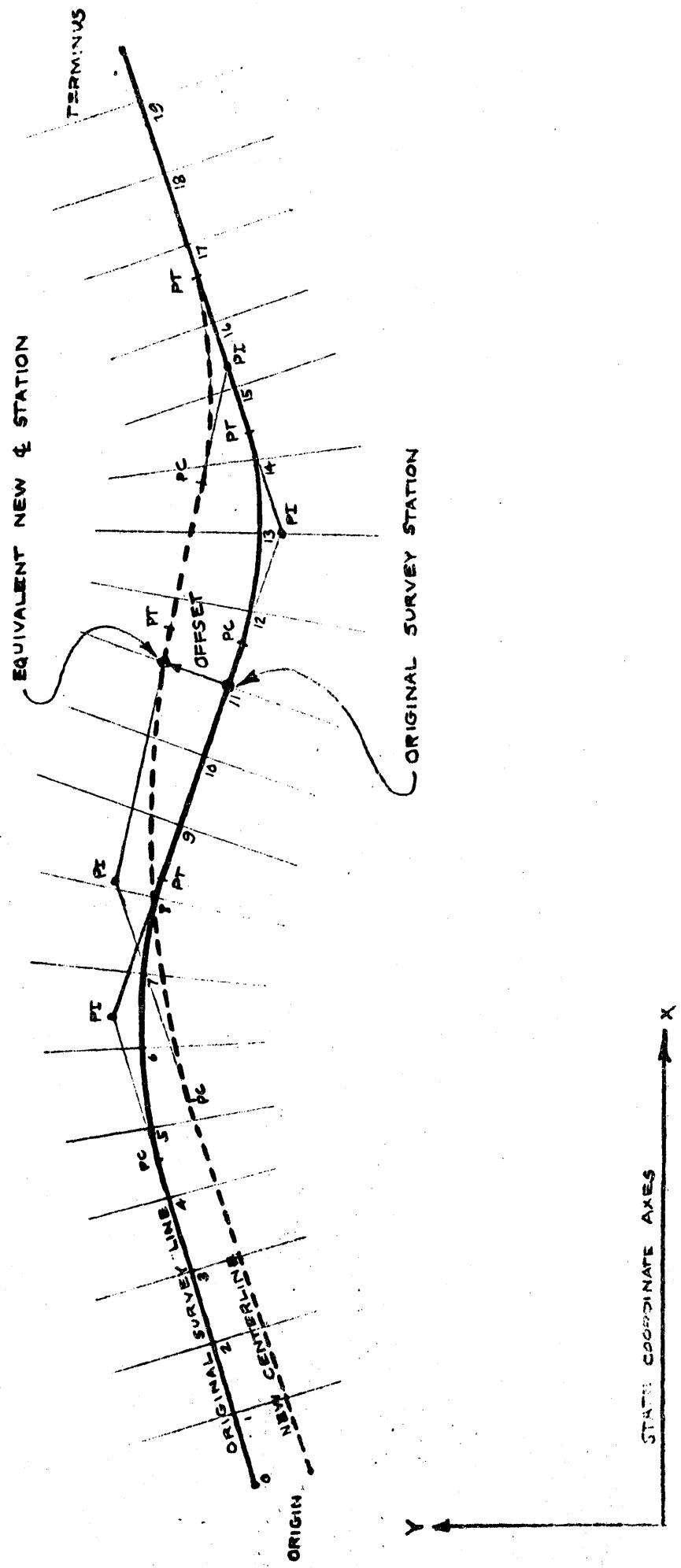


FIGURE 1

## RELOCATION OFFSETS MACRO BLOCK DIAGRAM

### Program Operation - Part One

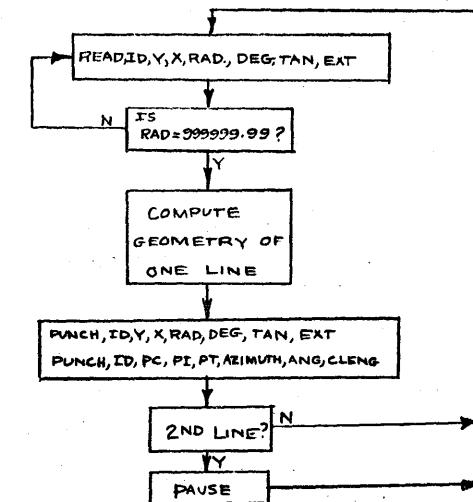
The geometry computation is performed as follows:

1. The point identification, state plane coordinates of the P.I., and either the radius, the degree of curvature, the tangent length, or the external distance is given for each P.I. on the baseline.
2. The cards containing this information are read in and stored in memory. The geometry computations are performed and punched out P.I. by P.I.
3. The program then cycles back to the beginning and reads the same information for each P.I. on the centerline.
4. As the output for each P.I. is computed and output, a geometry table is built up in memory. The P.C., P.T., and P.I. stations, the azimuth of each line, and the deflection angle at each turning point are output for use by the engineer.

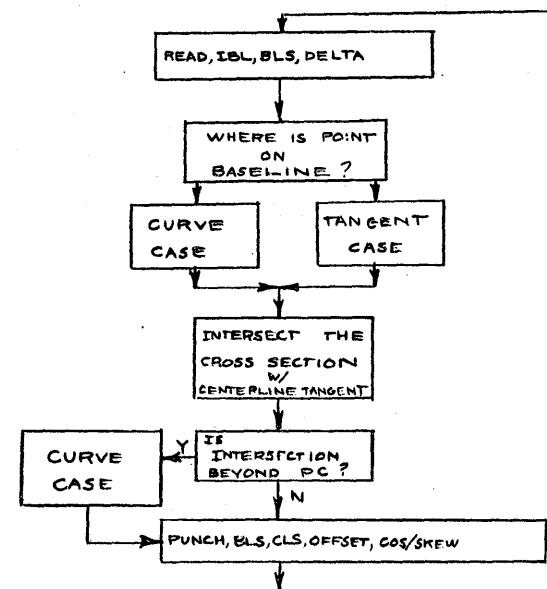
### Program Operation - Part Two

The second program operates with the geometry table left in memory by program one and with a starting baseline station number and increment of advance.

1. The baseline station number is used to compute the coordinates of that point on the baseline and the azimuth of the cross section located at that point.
2. The line originating at the point where the cross section crosses the baseline and with an azimuth normal to the baseline is intersected with the centerline. The station of intersection offset and skew are determined. This information is output for each increment as designated on the input.



PART 1  
GEOMETRY



PART 2  
OFFSETS

### Features

1. The station number of the origin is placed in the radius field on the input card.
2. Only one of the curve parameters need be specified. The others are entered as zero. If more than one is entered, the first is used.
3. The termini of both baseline and centerline alignments are indicated by placing 999999.99 in the radius field of the input card.
4. Several baselines and/or centerlines can be handled continuously. Intermediate termini of each line are indicated by 888888.88 in the radius field.
5. After an intermediate terminus, the radius field of the following card is expected to contain the origin station number of the new line. If this number is zero, the terminus station of the previous line is assigned.
6. The starting station and the increment of advance of the stations on the baseline are specified on the first input card to part two. The stationing is automatically increased by the amount of the increment until the stationing exceeds the value on the next card, or until the baseline numbers fail to match. When this happens, the values on the second card replace those in memory.

### Restrictions

1. A total of 30 P.I. points can be handled. P.I. points include origins and termini as well as P.I.'s on both the centerline and baseline.
2. All values on the input cards must be entered as either a number or as zero. They may not be left blank.

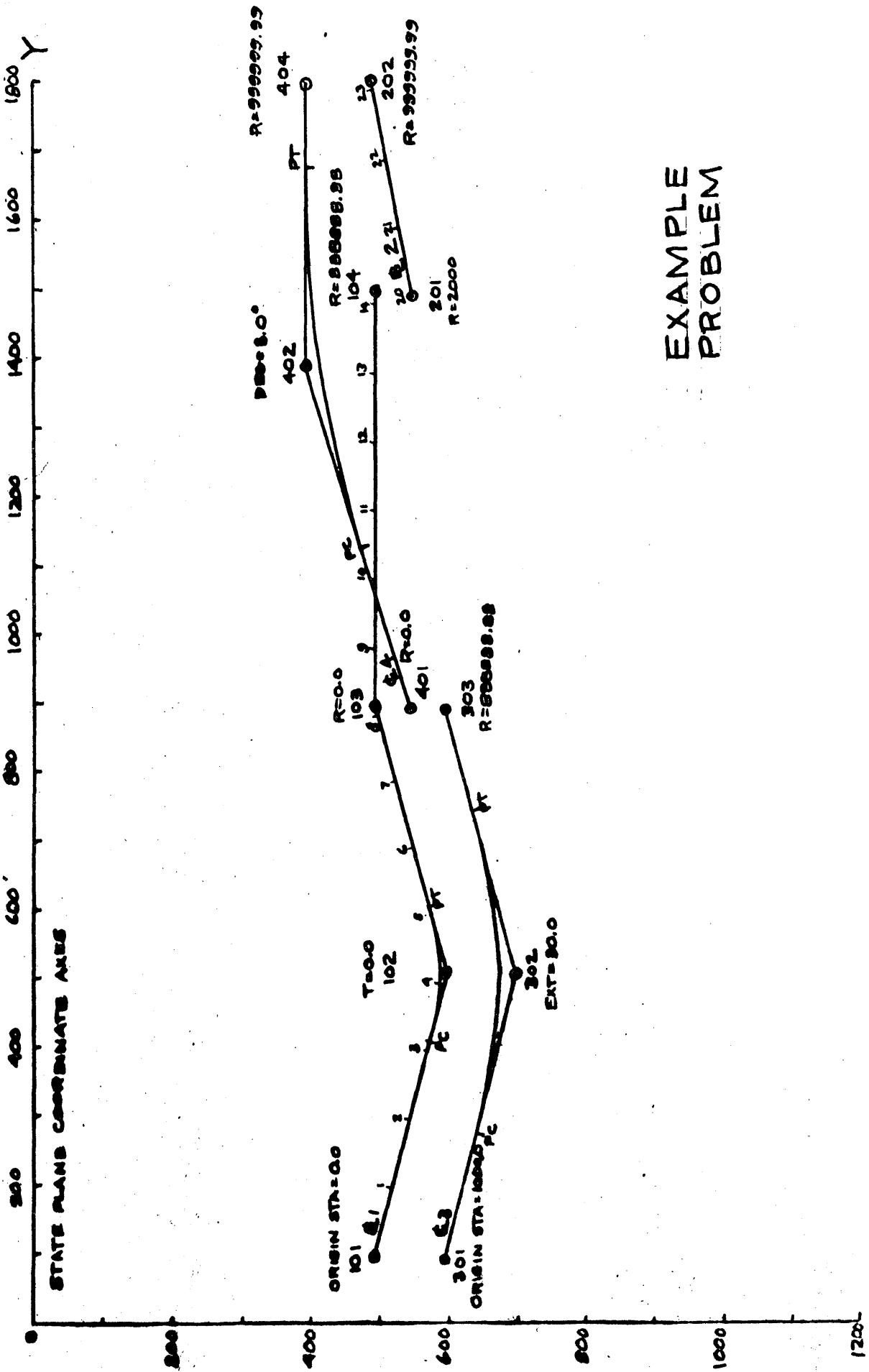
3. Accuracy is determined by the number of significant digits in the input. Eight significant digits are accepted by the program.
4. Each P.I. must be numbered with a four digit ID number. The units and tens position should contain the point number (which is not used by the program). The hundreds and thousands digits must contain the baseline or centerline number. These numbers must match those on the part two input cards.
5. Situations in which the baseline and centerline are going in opposite directions should be avoided. The program will not establish an intersection when the azimuths of the two lines involved are more than 90 degrees apart.

### Operating Instructions

1. PARITY switch on STOP.
2. I/O switch on STOP.
3. O Flow switch on PROGRAM.
4. Program Switches  
Switch 1 on for typed output  
Margins - 14 and 95  
Tabs- 22, 34, 46, 58, 70, 82
5. Press - RESET.
6. Ready read hopper with Part One Program followed by geometry input cards.
7. Press - LOAD.
8. Ready punch hopper with blanks.
9. Press - PUNCH START.
10. When program has read all cards and punched output, it will stop with a 48 in the operation register.
11. Press - RESET.
12. Ready read hopper with Part Two Program followed by the Baseline Station input cards.
13. Press - LOAD.
14. Program will stop on a 37 read instruction in the operation register after punching output.

9

EXAMPLE PROBLEM



## **EXAMPLE PROBLEM**

## RELOCATION OFFSETS

**INPUT FORM 1**

ENGINEERED POZ  
DATE 14 OCT 61  
PROJECT EXAMPLE

## GEOMETRY INPUT

**NOTE:** 1. All points must have point numbers with appropriate E or E numbers.  
2. A value of 999999.99 in the radius column terminates the line.  
3. A value of 888888.88 in the radius column sets up an intermediate terminus.

## RELOCATION OFFSETS

ENGINEER PDK  
DATE 14 OCT 61  
PROJECT EXAMPLE

## INPUT FORM 2

## BASELINE INPUT

**NOTE:** If all stations are odd set Increment of Advance arbitrarily large.

## RELOCATION OFFSETS OUTPUT DATA

POINT	GEOMETRY OUTPUT					
	X/PC	Y/PI	R/PT	D/AZ	T/ANG	E/CLENG
101	500.00000	100.00000	.00000000	.00000000	.00000000	.00000000
101	.00000000	.00000000	.00000000	14.036246	.00000000	.00000000
102	600.00000	500.00000	399.99993	14.323947	99.999994	12.310558
102	312.31042	412.31041	508.29335	345.96376	-28.072491	195.98293
103	500.00000	900.00000	.00000000	.00000000	.00000000	.00000000
103	820.60377	820.60377	820.60377	.00000000	14.036246	.00000000
104	500.00000	1500.00000	888888.88			
104	1420.6036	1420.6036	1420.6036			
201	550.00000	1500.00000	2000.0000	.00000000	.00000000	.00000000
201	2000.00000	2000.00000	2000.0000	350.53768	.00000000	.00000000
202	500.00000	1800.00000	999999.99			
202	2304.1379	2304.1379	2304.1379			
301	600.00000	100.00000	1000.0000	.00000000	.00000000	.00000000
301	1000.00000	1000.00000	1000.0000	14.036246	.00000000	.00000000
302	700.00000	500.00000	974.77287	5.8778595	243.69325	30.000000
302	1168.6172	1412.3104	1646.2143	345.96376	-28.072491	477.59718
303	600.00000	900.00000	888888.88			
303	1814.8315	1814.8315	1814.8315			
401	550.00000	900.00000	1814.8315	.00000000	.00000000	.00000000
401	1814.8315	1814.8315	1814.8315	343.30076	.00000000	.00000000
402	400.00000	1400.00000	1909.8593	3.0000000	280.30781	20.460514
402	2056.5387	2336.8465	2613.1801	.00000000	16.699245	556.64148
403	400.00000	1800.00000	999999.99			
403	2732.8722	2732.8722	2732.8722			

## SOURCE LANGUAGE LISTING

BL	OFFSETS OUTPUT			
	BL STA	CL STA	OFF	COS ANG
1	100.00000	1075.7464	97.014230	1.0000000
1	200.00000	1175.7490	96.988070	.99997324
1	300.00000	1275.9644	91.109430	.99394231
1	400.00000	1394.9944	82.391260	.99991534
1	500.00000	1516.2619	88.469440	.99366932
1	600.00000	1618.4773	96.619620	.99959515
1	700.00000	1718.4814	97.014238	1.0000000
1	800.00000	1848.5383	48.193600	.99982753
1	900.00000	1897.7233	26.182357	.95782552
1	1000.00000	2002.1264	-3.8179427	.95782552
1	1100.00000	2106.3430	-33.139600	.96499239
1	1200.00000	2209.2707	-57.446400	.97771940
1	1300.00000	2311.0171	-76.144900	.98751011
1	1400.00000	2411.9016	-89.402200	.99445141
2	2010.00000	2419.3218	-140.43650	.99797536
2	2020.00000	2429.3468	-139.77230	.99762776
2	2030.00000	2439.3705	-139.05500	.99725273
2	2040.00000	2449.3992	-130.28730	.99685002
2	2050.00000	2459.4393	-137.46500	.99641932
2	2060.00000	2469.4779	-136.59000	.99596115
2	2070.00000	2479.5207	-135.66200	.99547526
2	2080.00000	2489.5717	-134.68100	.99496141
2	2090.00000	2499.6241	-133.64600	.99441993
2	2100.00000	2509.6747	-132.55500	.99385099
2	2110.00000	2519.7393	-131.41800	.99325370

C RELOCATION OFFSETS / PART 1

C P. O. ROBERTS / JULY, 1961

C MIT CIVIL ENGINEERING SYSTEMS LABORATORY

C SW 1 ON FOR TYPED OUTPUT / MAR 14, 95 / TABS 22, 34, 46, 58, 70, 82

DIMENSION ID(30), Y(30), X(30), R(30), PC(30), PT(30), PT(30), OFFD(3)

DIMENSION D(30), T(30), E(30)

C INITIALIZE

100 I=0

C READ ROUTINE

DO 262 N=1,2

ID(31)=J

DO 120 J=1,30

I=I+1

READ, ID(I), X(I), Y(I), R(I), D(I), T(I), E(I)

IF(R(I)=999999.98) 120, 140, 140

120 CONTINUE

140 I=I-J+1

200 ISW1=1

ISW3=1

RI=R(I)

PI(I)=RI

PC(I)=RI

PT(I)=RI

C=0.0

T(I)=0.

201 ISW4=1

GO TO 10

206 IF(ISW1=2) 248, 210, 210

248 ISW1=2

ANG1=0.0

ALENG=0.0

GO TO 232

210 ANGI= AZ-AZO

212 IF(ANGI=3.1415927) 211, 211, 214

211 ANGI=ANGI+6.2831854

GO TO 212

214 ANGI=ANGI-6.2831854

IF(ANGI) 208, 209, 209

208 DS=-1.0000000

GO TO 205

209 DS=1.0000000

205 ANG=ANGI/2.

C FIND WHICH IS GIVEN

IF(R(I)) 221, 216, 221

216 IF(D(I)) 221, 217, 219

217 IF(T(I)) 221, 218, 220

218 IF(E(I)) 221, 222, 223

C IF D IS GIVEN

219 R(I)=5729.5780/D(I)

GO TO 221

C IF T IS GIVEN

220 R(I)=T(I)\*COS(ANG)/SIN(ANG)\*DS

GO TO 221

C IF E IS GIVEN

223 R(I)=E(I)/(1./COS(ANG)-1.)

GO TO 221

C IF NONE ARE GIVEN

```

222 D(I)=0.0
      GO TO 215
221 D(I)=5729.5780/R(I)
215 T(I)=R(I)*(SIN(ANG)/COS(ANG))*DS
      PC(I)=PI(I)-T(I)
      ALENG=ANGI*R(I)*DS
      PT(I)=PC(I)+ALENG
      E(I)=(1./COS(ANG)-1.)*R(I)
      ANGIO=ANGI*57.295780
232 AZOUT= AZ*57.295780
      IF(SENSE SWITCH 1)233,234
233 PRINT, ID(I), X(I), Y(I), R(I), D(I), T(I), E(I)
      PRINT, ID(I), PC(I), PI(I), PT(I), AZOUT, ANGIO, ALENG
      GO TO 235
234 PUNCH, ID(I), X(I), Y(I), P(I), D(I), T(I), F(I)
      PUNCH, ID(I), PC(I), PI(I), PT(I), AZOUT, ANGIO, ALENG
235 PI(I+1)=PT(I)-T(I)+C
      AZO=AZ
      I=I+1
240 IF(R(I)=888888.87)242,244,244
242 CONTINUE
      GO TO 201
244 PC(I)=PI(I)
      PT(I)=PI(I)
      IF(SENSE SWITCH 1)245,246
245 PRINT, ID(I), X(I), Y(I), R(I)
      PRINT, ID(I), PC(I), PI(I), PT(I)
      GO TO 260

```

```

246 PUNCH, ID(I), X(I), Y(I), R(I)
      PUNCH, ID(I), PC(I), PI(I), PT(I)
260 IF(R(I)=999999.98)250,262,262
262 CONTINUE
      PAUSE
      GO TO 100
250 I=I+1
      IF(R(I))200,252,200
252 R(I)=PI(I-1)
      GO TO 200
C   AZIMUTH DISTANCE SUBROUTINE
10  A=X(I+1)-X(I)
      B=Y(I+1)-Y(I)
      PIE=3.1415927
11  C=SQR(A**2+B**2)
      IF(A)15,12,15
12  IF(B)13,14,14
13  AZ=PIE
      GO TO 18
14  AZ=0.0
      GO TO 18
15  ANG=ATN(R/A)
16  IF(A)19,12,17
17  AZ=(PIE/2.0)-ANG
      GO TO 18
19  AZ=(1.5*PIE)-ANG
18  GO TO (206,100), ISW4
      END

```

C RELOCATION OFFSETS / PART 2  
 C P. O. ROBERTS / JULY, 1961  
 C MIT CIVIL ENGINEERING SYSTEMS LABORATORY  
 DIMENSION ID(31), Y(30), X(30), R(30), PC(30), PI(30), PT(30), OFFD(3)  
 C READ TERRAIN  
 K=ID(31)+1  
 J=1  
 STA=-888888.88  
 READ, IBLB, BLSB, DELTB  
 IBL=IBLB  
 408 STA=BLSB  
 READ, IBLA, BLSA, DELTA  
 IF(J=1) 409, 509, 409  
 442 BLSB=BLSB+DELTB  
 STA=BLSB  
 IBL=IBLB  
 409 IF(IBLA-IBLB) 420, 410, 420  
 410 IF(STA-BLSA) 1500, 500, 420  
 420 BLSB=BLSA  
 IBLB=IBLA  
 DELTB=DELTA  
 GO TO 408  
 C COMPUTE COORDINATES ON BASELINE  
 509 BLSB=BLSB-DELTB  
 510 J=J+1  
 I=J  
 C GEOMETRY SUBROUTINE  
 ISW1=1  
 I=I-1

202 ISW2=1  
 ISW3=1  
 ISW4=1  
 C GO TO AZ DIS 1  
 C AZIMUTH DISTANCE SUBROUTINE  
 10 A=X(I+1)-X(I)  
 B=Y(I+1)-Y(I)  
 11 C=SQR(A\*\*2+B\*\*2)  
 AZ=0.0  
 IF(C=.0000) 118, 18, 12  
 12 ANG=1.0  
 TF(B) 3, 4, 4  
 3 ANG=-1.0  
 4 B=ABSF(A/C)  
 P=SQR(ABSF(1.0-B)/2.0)  
 AZ=SINF(P)  
 DO 14 L=1, 50  
 ANGI=P-SINF(AZ)  
 IF(ANGI-.1E-05) 15, 15, 14  
 14 AZ=AZ+ANGI  
 15 AZ=(ANG\*AZ)\*2.  
 IF(A) 17, 16, 16  
 16 AZ=1.5707964-AZ  
 GO TO 18  
 17 AZ=4.7123890+AZ  
 18 GO TO (206, 605, 660, 685), ISW2  
 206 IF(ISW1-2) 207, 210, 201  
 207 AZR=AZ

```

I=I+1
ISW1=2
500 I=.J
PCI=PC(I)
AZ0=AZB
C CHECK FOR MATCHING BASELINES
IF(IBL*2-(ID(I-1)/100+ID(I)/100))510,515,510
515 IF(STA-PT(I-1))442,520,520
520 IF(R(I)-888888.88)525,530,530
525 IF(STA-PCI)530,530,545
210 ANGI= AZ-AZ0
C ADJUST ANGLES TO LESS THAN 180 DEGREES
212 IF(ANGI-3.1415927) 211,211,214
211 ANGI=ANGI+6.2831854
GO TO 212
214 ANGI=ANGI-6.2831854
IF(ISW4-1)204,204,690
C COMPUTE SIGN OF DEFLECTION ANGLE
204 DS=1.0
IF(ANGI)208,205,205
208 DS=-1.0
205 ANG=ANGI/2.
C COMPUTE CURVE TANGENT
RI=R(I)
TANG=RI*(SIN(ANG)/COS(ANG))*DS
AZ=AZ0+3.1415927
C FIND COORDINATES OF PC
DIS=TANG

```

```

ISW5=1
XI=X(I)
YI=Y(I)
C GO TO COORD 1
C COMPUTE COORDINATES SUBROUTINE
20 XI=XI+DIS*SIN(AZ)
YI=YI+DIS*COS(AZ)
GO TO (216,217,540,680),ISW5
216 PCX=XI
PCY=YI
C FIND COORDINATES OF CIRCLE CENTER
AZ=AZ0+DS*1.5707964
DIS=RI
ISW5=2
GO TO 20
C GO TO COORD 2
217 XO=XI
YO=YI
PCAZ=AZ
IF(ISW3-2) 550,655,690
C TANGENT CASE
530 DIS=PI(I)-STA
AZMIT=AZ0+1.5707964
ISW5=3
AZ=AZ0+3.1415927
XI=X(I)
YI=Y(I)
GO TO 20

```

C GO TO COORD 3  
 545 IF(STA-PT(I))1202,510,510  
 C CURVE CASE  
 550 ANG=(STA-PCI)/RI  
 X1=X0  
 Y1=Y0  
 DIS=DS\*(-RI)  
 AZMIT=AZO+1.5707964+DS\*ANG  
 AZ=AZMIT  
 ISW5=3  
 GO TO 20  
 C STORE BASELINE COORDINATES  
 540 CORDX=XI  
 CORDY=YI  
 C COMPUTE INTERSECTION ON CENTERLINE  
 600 I=K  
 601 ISW2=2  
 GO TO 10  
 C GO TO AZ DIS 2  
 605 I=I+1  
 AZ1=AZMIT  
 AZ2=AZ+3.1415927  
 A=X(I)-CORDX  
 B=Y(I)-CORDY  
 C=SIN(AZ1-AZ2)  
 IF(C+.00001)632,638,638  
 638 OFF=888888.88  
 DIS=-888888.88

GO TO 610  
 C COMPUTE OFFSET FROM BL TO CL AND DISTANCE FROM PI  
 632 DO 636 L=1,2  
 DIS=OFF  
 OFF=(A\*COS(AZ1)-B\*SIN(AZ1))/C  
 636 AZ1=AZ2  
 610 ANG=AZ  
 CLS=PI(I)-DIS  
 C IS INTERSECTION BEYOND THE PC  
 IF(CLS-PC(I))625,625,640  
 C IS ALIGNMENT FINISHED  
 640 IF(R(I)-888888.881642,642,442  
 641 I=I+1  
 642 IF(ID(I)/100-ID(I+1)/100)641,645,641  
 645 AZ0=AZ  
 K=I-1  
 GO TO 601  
 C IS ALIGNMENT BEYOND THE PREVIOUS PT  
 625 IF(CLS-PT(I-1))628,626,626  
 626 IF(I-K-1)698,698,697  
 697 K=K+1  
 GO TO 698  
 628 IF(I-K-1)650,442,650  
 C INTERSECTION ON CURVE  
 650 I=I-1  
 ISW3=2  
 ISW4=1  
 GO TO 210

C GO TO LAST PART OF GEOM 2

655 A=XO-CORDX  
B=YO-CORDY  
ISW2=3  
GO TO 11

C GO TO LAST PART OF AZ DIS 3

C COMPUTE CURVE OFFSET

660 ANG=AZ-AZMIT  
A=C\*COS(ANG)  
B=C\*SIN(ANG)  
OFF=A-DS\*SQR(IRI\*\*2-B\*\*2)

C GET COORDINATES OF INTERSECTION POINT

XI=CORDX  
YI=CORDY  
AZ=AZMIT  
DIS=OFF  
ISW5=4  
GO TO 20

C GO TO COORD 4

C GET AZIMUTH OF RADIUS

680 A=XO-XI  
B=YO-YI  
ISW2=4  
GO TO 11

C GO TO AZ DIS 4

C COMPUTE ANGLE SUBTENDED

685 ANGI=AZ-PCA2  
ISW4=3

GO TO 212

C GO TO GEOM 3

C COMPUTE CLS AND LOCAL AZIMUTH FOR CURVE INTERSECTION

690 CLS=PC(I)+ANGI\*RI\*DS  
ANG=AZ0+ANGI  
698 ANG =SIN(AZMIT-ANG)  
IF(SENSE SWITCH 1)699,700

699 PRINT,IBL,STA,CLS,OFF,ANG  
GO TO 442

700 PUNCH,IBL,STA,CLS,OFF,ANG  
GO TO 442

END

REFERENCES

- (1) "Using New Methods In Highway Location", Paul Roberts, Photogrammetric Engineering, June, 1957
- (2) Digital Terrain Model Approach To Highway Earthwork Analysis, C. L. Miller, MDPW - BPR Research Project Report, Massachusetts Institute of Technology, August, 1957
- (3) The Skew System For Highway Earthwork Analysis, C. L. Miller, Massachusetts Institute of Technology, MDPW - BPR Research Project Report, September, 1957
- (4) Earthwork Data Procurement By Photogrammetric Methods, C. L. Miller, and T. H. Kvalstad, Highway Research Board Bulletin 199
- (5) "The Digital Terrain Model - Theory And Application", C. L. Miller, and R. A. Laflamme, Photogrammetric Engineering, June, 1958
- (6) Digital Terrain Model System Manual, C. L. Miller, and R. A. Laflamme, MDPW - BPR Research Project Report, Massachusetts Institute of Technology, December 1958
- (7) The Digital Terrain Model System of Providing Highway Location And Design Information, C. L. Miller, Proceedings Of The American Association Of State Highway Officials, Committee Meeting, San Francisco, December 1958
- (8) Preliminary Report on The Digital Terrain Data Recorder, C. L. Miller, and E. P. Gladding, MDPW - BPR Research Project Report, May 1959
- (9) Zone Cost Evaluation Program EA-2, C. L. Miller, and D. E. Weisberg, MDPW - BPR Research Project Report, Massachusetts Institute of Technology, October 1960
- (10) Digital Terrain Model System DTM II Manual, P. O. Roberts, C. L. Miller and R. A. Laflamme, MDPW - BPR Research Project Report, Massachusetts Institute of Technology, November 1960
- (11) A New Technique For The Prediction Of Vehicle Operating Cost In Connection With Highway Design, A. S. Lang, and D. H. Robbins, MDPW - BPR Research Project Report, Massachusetts Institute Of Technology, November 1960
- (12) Use Of Digital Computers In Land Cost Evaluation, D. E. Weisberg, Unpublished S. M. Thesis, Massachusetts Institute Of Technology, June 1961
- (13) Highway Location Evaluation, P. O. Roberts, Proceedings Of The Electronics Committee Of The American Association Of State Highway Officials, Boston, August 1961

```

C   RELOCATION OFFSETS / PART 1
C   P. O. ROBERTS / JULY, 1961
C   MIT CIVIL ENGINEERING SYSTEMS LABORATORY
C   JN 1 ON FOR TYPED OUTPUT / MAR 14, 95 / TABS 22,34 46 58,70,82
C   DIMENSION ID(31),Y(30),X(30),R(30),PC(30),PT(30),OFFD(3)
C   DIMENSION D(30),T(30),E(30)
C   INITIALIZE
100  I=0
C   READ ROUTINE
D- 262 N=1,2
ID(31)=J
DO 120 J=1,30
I=I+1
READ, ID(I), X(I), Y(I), R(I), D(I), T(I), E(I)
IF(R(I)-999999.98)120,140,140
120 CONTINUE
140 I=I-J+1
200 ISW1=1
ISW3=1
RI=R(I)
PI(I)=RI
PC(I)=RI
PT(I)=RI
C=0.0
T(I)=0.
201 ISW4=1
GO TO 10
206 IF(ISW1-2)248,210,210
248 ISW1=2
ANGIO=0.0
ALENG=0.0
GO TO 232
210 ANGI= AZ-AZ0
212 IF(ANGI-3.1415927) 211,211,214
211 ANGI=ANGI+.2831854
GO TO 212
214 ANGI=ANGI-6.2831854
IF(ANGI)208,209,209
208 DS=-1.0000000
GO TO 205
209 DS=1.0000000
205 ANG=ANGI/2.
C   FIND WHICH IS GIVEN
IF(R(I))221,216,221
216 IF(D(I))221,217,219
217 IF(T(I))221,218,220
218 IF(E(I))221,222,223
C   IF D IS GIVEN
219 R(I)=5729.5780/D(I)
GO TO 221
C   IF T IS GIVEN
220 R(I)=T(I)*COS(ANG)/SIN(ANG)*DS
GO TO 221
C   IF E IS GIVEN
223 R(I)=E(I)/(1./COS(ANG)-1.)
GO TO 221
C   IF NONE ARE GIVEN
222 D(I)=0.0
GO TO 215
221 D(I)=5729.5780/R(I)
215 T(I)=R(I)*(SIN(ANG)/COS(ANG))*DS

```

PC(I)=PI(I)-T(I)  
 ALENG=ANGI\*R(I)\*DS  
 PT(I)=PC(I)+ALENG  
 E(I)=(1./COS(ANG)-1.)\*R(I)  
 ANGIO=ANGI\*57.295780  
 232 AZOUT= AZ#57.295780  
 IF(SENSE SWITCH 1)233,234  
 233 PRINT, ID(I), X(I), Y(I), R(I), D(I), T(I), E(I)  
 PRINT, ID(I), PC(I), PI(I), PT(I), AZOUT, ANGIO, ALENG  
 GO TO 235  
 234 PUNCH, ID(I), X(I), Y(I), R(I), D(I), T(I), E(I)  
 PUNCH, ID(I), PC(I), PI(I), PT(I), AZOUT, ANGIO, ALENG  
 235 PI(I+1)=PT(I)-T(I)+C  
 AZO=AZ  
 I=I+1  
 240 IF(R(I)-888888.87)242,244,244  
 242 CONTINUE  
 GO TO 201  
 244 PC(I)=PI(I)  
 PT(I)=PI(I)  
 IF(SENSE SWITCH 1)245,246  
 245 PRINT, ID(I), X(I), Y(I), R(I)  
 PRINT, ID(I), PC(I), PI(I), PT(I)  
 GO TO 260  
 246 PUNCH, ID(I), X(I), Y(I), R(I)  
 PUNCH, ID(I), PC(I), PI(I), PT(I)  
 260 IF(R(I)-999999.98)250,262,262  
 262 CONTINUE  
 PAUSE  
 GO TO 100  
 250 I=I+1  
 IF(R(I))200,252,200  
 252 R(I)=PI(I-1)  
 GO TO 200  
 C AZIMUTH DISTANCE SUBROUTINE  
 10 A=X(I+1)-X(I)  
 B=Y(I+1)-Y(I)  
 PIE=3.1415927  
 11 C=SQR(A\*\*2+B\*\*2)  
 IF(A)15,12,15  
 12 IF(B)13,14,14  
 13 AZ=PIE  
 GO TO 18  
 14 AZ=0.0  
 GO TO 18  
 15 ANG=ATN(B/A)  
 16 IF(A)19,12,17  
 17 AZ=(PIE/2.0)-ANG  
 GO TO 18  
 18 AZ=(1.5\*PIE)-ANG  
 18 GO TO (206,100), ISW4  
 END

C RELOCATION OFFSETS / PART 2  
 C P. O. ROBERTS / JULY, 1961  
 C MIT CIVIL ENGINEERING SYSTEMS LABORATORY  
 C DIMENSION ID(31), Y(30), X(30), R(30), PC(30), PI(30), PT(30), OFFD(3)  
 C READ TERRAIN  
 C K=ID(31)+1  
 C J=1  
 C STA=-888888.88  
 C READ, IBLSB, BLTB, DELTB  
 C IBL=IBLB  
 400 C STA=BLSB  
 C READ, IBLA, BLSA, DELTA  
 C IF(J-1)409,509,409  
 442 C BLTB=BLSB+DELT  
 C STA=BLSB  
 C IBL=IBLB  
 409 C IF(IBLA-IBLB)420,410,420  
 410 C IF(STA-BLSA)500,500,420  
 420 C BLTB=BLSA  
 C IBLB=IBLA  
 C DELTB=DELTA  
 C GO TO 408  
 C COMPUTE COORDINATES ON BASELINE  
 509 C BLTB=BLSB-DELT  
 510 C J=J+1  
 C I=J  
 C GEOMETRY SUBROUTINE  
 C ISW1=1  
 C I=I-1  
 202 C ISW2=1  
 C ISW3=1  
 C ISW4=1  
 C GO TO AZ DIS 1  
 C AZIMUTH DISTANCE SUBROUTINE  
 10 C A=X(I+1)-X(I)  
 B=Y(I+1)-Y(I)  
 11 C=SQR(A\*\*2+B\*\*2)  
 AZ=U.0  
 IF(C-.00001)18,18,12  
 12 ANG=1.0  
 IF(B)3,4,4  
 3 ANG=-1.0  
 4 B=ABSF(A/C)  
 P=SQR(ABSF(1.0-B)/2.)  
 AZ=SINF(P)  
 DO 14 L=1,50  
 ANGI=P-SINF(AZ)  
 IF(ANGI-.1E-05)15,15,14  
 14 AZ=AZ+ANGI  
 15 AZ=(ANG\*AZ)\*2.  
 IF(A)17,16,16  
 16 AZ=1.5707964-AZ  
 GO TO 18  
 17 AZ=4.7123890+AZ  
 18 GO TO (206,605,660,685), ISW2  
 206 IF(ISW1-2)207,210,201  
 207 AZB=AZ

29  
 500 I=J  
 PC=PC(I)

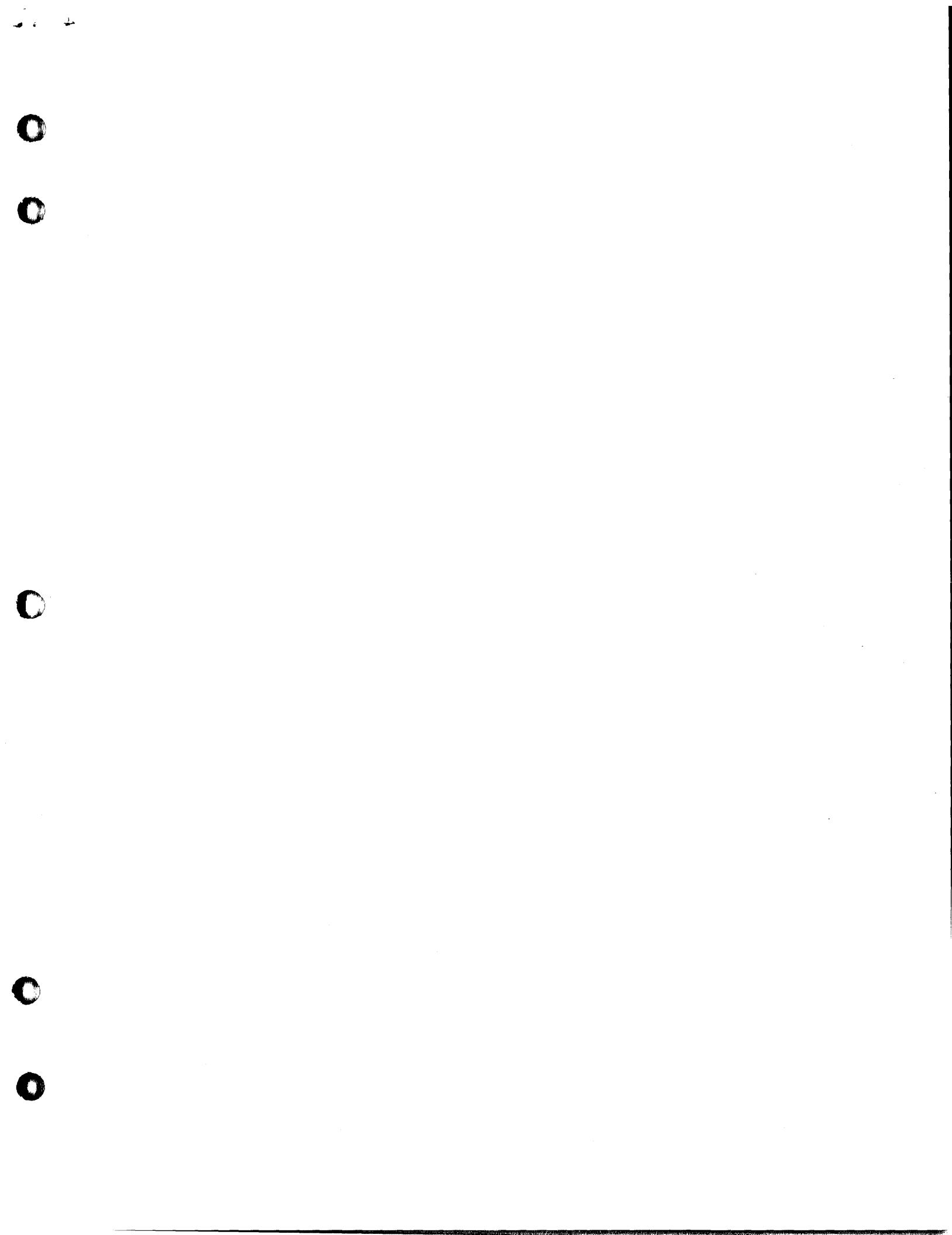
PAG

```

AZO=AZB
C CHECK FOR MATCHING BASELINES
IF(IBM*2-(ID(I-1)/100+ID(I)/100))510,515,510
515 IF(STA-PT(I-1))442,520,520
520 IF(R(I)-888888.881525,530,530
525 IF(STA-PC(I))530,530,545
210 ANGI= AZ-AZO
C ADJUST ANGLES TO LESS THAN 180 DEGREES
212 IF(ANGI-3.1415927) 211,211,214
211 ANGI=ANGI+6.2831854
GO TO 212
214 ANGI=ANGI-6.2831854
IF(ISW4-1)204,204,690
C COMPUTE SIGN OF DEFLECTION ANGLE
204 DS=1.0
IF(ANGI)208,205,205
208 DS=-1.0
205 ANG=ANGI/2.
C COMPUTE CURVE TANGENT
RI=R(I)
TANG=RI*(SIN(ANG)/COS(ANG))*DS.
AZ=AZ0+3.1415927
C FIND COORDINATES OF PC
DIS=TANG
ISW5=1
XI=X(I)
YI=Y(I)
C GO TO COORD 1
C COMPUTE COORDINATES SUBROUTINE
20 XI=XI+DIS*SIN(AZ)
YI=YI+DIS*COS(AZ)
GO TO (216,217,540,680),ISW5
216 PCX=XI
PCY=YI
C FIND COORDINATES OF CIRCLE CENTER
AZ=AZ0+DS*1.5707964
DIS=RI
ISW5=2
GO TO 20
C GO TO COORD 2
217 XO=XI
YO=YI
PCA=AZ
IF(ISW3-2) 550,655,690
C TANGENT CASE
530 DIS=PI(I)-STA
AZMIT=AZ0+1.5707964
ISW5=3
AZ=AZ0+3.1415927
XI=X(I)
YI=Y(I)
GO TO 20
C GO TO COORD 3
545 IF(STA-PT(I))202,510,510
C CURVE CASE
550 ANG=(STA-PC(I))/RI
XI=XO
YI=YO
DIS=DS*(-RI)
AZMIT=AZ0+1.5707964+DS*ANG
AZ=AZMIT
ISW5=3
GO TO 20
C STORE BASELINE COORDINATES
540 CORDX=XI
CORDY=YI
C COMPUTE INTERSECTION ON CENTERLINE
600 I=K
601 ISW2=2
GO TO 10
C GO TO AZ DIS 2
605 I=I+1
AZ1=AZMIT
AZ2=AZ+3.1415927
A=X(I)-CORDX
B=Y(I)-CORDY
C=SIN(AZ1-AZ2)
IF(C+.00001)632,638,638
638 OFF=888888.88
DIS=-888888.88
GO TO 610
C COMPUTE OFFSET FROM BL TO CL AND DISTANCE FROM PI
632 DO 636 L=1,2
DIS=OFF
OFF=(A*COS(AZ1)-B*SIN(AZ1))/C
636 AZ1=AZ2
610 ANG=AZ
CLS=PI(I)-DIS
C IS INTERSECTION BEYOND THE PC
IF(CLS-PC(I))625,625,640
C IS ALIGNMENT FINISHED
640 IF(R(I)-888888.88)642,642,642
641 I=I+1
642 IF(ID(I)/100-ID(I+1)/100)641,645,641
645 AZ0=AZ
K=I-1
GO TO 601
C IS ALIGNMENT BEYOND THE PREVIOUS PT
625 IF(CLS-PT(I-1))628,626,626
626 IF(I-K-1)698,698,697
697 K=K+1
GO TO 698
628 IF(I-K-1)650,442,650
C INTERSECTION ON CURVE
650 I=I-1
ISW3=2
ISW4=1
GO TO 210
C GO TO LAST PART OF GEOM 2
655 A=XO-CORDX
B=YU-CORDY
ISW2=3
GO TO 11
C GO TO LAST PART OF AZ DIS 3
C COMPUTE CURVE OFFSET
660 ANG=AZ-AZMIT

```

```
A=C*COS(ANG)
B=C*SIN(ANG)
OFF=A-DS*SQRT(RI**2-B**2)
C GET COORDINATES OF INTERSECTION POINT
XI=CORDX
YI=CORDY
AZ=AZMIT
DIS=OFF
ISW5=4
GO TO 20
C GO TO COORD 4
C GET AZIMUTH OF RADIUS
680 A=XO-XI
B=Y0-YI
ISW2=4
GO TO 11
C GO TO AZ DIS 4
C COMPUTE ANGLE SUBTENDED
685 ANGI=AZ-PCAZ
ISW4=3
GO TO 212
C GO TO GEOM 3
C COMPUTE CLS AND LOCAL AZIMUTH FOR CURVE INTERSECTION
690 CLS=PC(1)+ANGI*RI*DS
ANG=AZ0+ANGI
698 ANG =SIN(AZMIT-ANGI)
IF ISENSE SWITCH 11699,700
699 PRINT,IBL,STA,CLS,OFF,ANG
GO TO 442
700 PUNCH,IBL,STA,CLS,OFF,ANG
GO TO 442
END
```



THE COMPUTER MUSEUM HISTORY CENTER



1 026 2040 3

COMPUTER  
TECHNOLOGY