

### FD360/CF360

### MAINTENANCE MANUAL

This maintenance manual is intended as a trouble-shooting guide for isolating faults down to the replaceable subassembly level. Schematics are supplied as an aid in examining signals. No attempt is made to explain the operation fully enough to isolate faults down to the individual component level, however, it should be possible given the right test equipment and experience.

It is recommended that OEM customers who are maintaining large numbers of FD360/CF360 systems stock the subsystem level spares for use in field repairs. A recommended Spares List is given in the Appendix.

#### **SYMPTOM**

## POSSIBLE CAUSES (See Appendix for Signal Locations)

# Drive Fail Status, Drive Motor does not run

- 1. Drive not up to speed yet. Software should allow 6-7 seconds after closing door.
- 2. Diskette jammed. Open door. Reinsert Diskette. Try again. Diskette may be out of tolerance. Try another Diskette.
- 3. Check +24 Volt supply. Pins E (+24V return) and F (+24V) on MUX PCB power connector. Voltage with both drives running s/b 24.0 Volts +10%.
- 4. Check cable connections. Ribbon connector. Power connector. Drive connector.
- 5. Try swapping MUX cards. If problem remains with drive, then check DRFAL signal. Should be low when door is open. Should go high 5 seconds after door is closed. Should hear motor start.
- 6. Is a valid unit selected? Check SEL 0\*, SEL 1\*, SEL2\*, SEL 3\*. Should be logic "0" for selected drive. All others should be logic "1". Check command load unit/sector and data in lines.

## Head Loads, but does not seek

- 1. Head may be past track 76. Issue Seek 0 Command and retry.
- 2. Diskette may be bad. Try another.
- 3. Check -5V at pin A of MUX card. Check -12V supply at pin 1 of MUX card. Tolerance nominally ±5%.
- 4. Check 10ms signal. When seeking, 10ms should be high for 10-11 msec, then low for about 1 us, then high, etc. Adjust frequency if necessary.
- 5. In a dual (or more) drive system, if one unit seeks OK and the other doesn't, try swapping MUX's. If problem now is in the other drive, replace the MUX. If the same drive is bad, replace drive.
- 6. If both drives will not seek, verify that the SEEK signal goes high. If the SEEK signal does not go high, check that the SEEK command, 05, is coming from the CPU on the CPU 0\* CPU 7\* lines.

#### SYMPTOM

#### POSSIBLE CAUSES (CON'T.)

Head Loads, but does not seek
 (con't.)

7. If SEEK signal does go high, check for how long. 5-10 ms indicates CRC error in ID sector. 700 ms indicates no data being read from Diskette. Replace controller

CRC Errors

- 1. Excessive wear on Diskette. Replace Diskette.
- 2. Diskette not seated. Reinsert and retry, put system in a read loop.
- 3. Sync scope on INDEX signal, positive edge. Look at two signals with two traces of the scope. On "A" trace look at the DAFLD signal. With the other trace look at CRCAZ signal. Twenty six DAFLD pulses should occur for each sync. At the end of each DAFLD, CRCAZ should go high momentarily. If the momentary high is not present, it is due to CRC error on Diskette or controller failure. Try a known good Diskette. If still bad, replace controller.

Seeks to wrong track

1. Bad controller. Replace.

One bit of data is bad on read

- 1. Bad controller or interface. Write a pattern of all one's and examine input and output of read buffer. Inputs should be all ones during DAFLD time. Sync on NXDFD signal. Cycle on read. Output should be all one's also. Repeat with all zero pattern.
- 2. Check data in signals DIO-DI7 with data pattern above. Sync on GASTS signal. Data in lines should be one/zero during the time GASTS is logic zero.

One bit of data is bad on write

- 1. Verify that data written previously can be read correctly.
- 2. Write all one's pattern continuously to one sector. Check inputs to write buffer DOO-DO7 and outputs of write buffer during NXDFD signal.

Reads wrong sector

1. Put system into continuous read loop on the correct sector. Examine NXDFD signal. It should be about 5 msec long. If it does not go high at all then the sector cannot be decoded from any ID field. Check SEC 0\* - SEC 4\* signals (negative true) to verify sector is being loaded correctly.

#### SYMPTOM

## POSSIBLE CAUSES (CON'T.)

# Reads wrong sector (con't.)

- 2. If NXDFD is only about 100 us long, there is a CRC error in the ID filed. Try a new Diskette.
- 3. If NXDFD is about 10 ms long, then the address mark at the beginning of the data field is not being detected. Try writing the sector again.
- 4. NXDFD is correct period but still wrong sector, check SEC 0\* SEC 4\* (negative true)

# Head seeks, but moves in two or more stages

- 1. Put system into continuous loop of Seek 0 and Seek to track 4C (HEX). Check timing of 10MS signal. When seeking 10MS should be high for 10-11 ms and low for 1 us. Adjust timing if necessary.
- 2. Bad Diskette, try another.
- 3. Bad drive, check wear and friction of head stepper stage.
- 4. Check connectors, MUX to controller, MUX to drive.

#### Busy does not set

- 1. Check that Read, Write or Seek commands are being received.
- 2. Check 10MS signal. It should be a 10 MHz signal.

# APPENDIX A

# GLOSSARY OF SIGNALS

SIGNAL	DESCRIPTION	SOURCE
SEEK	Seek Command Latch	B1-10
SEEK 0	Seek 0 Command Latch	B1-12
READ	Read Command Latch	B1-2
READ CRC	Read CRC Command Latch	B1-7
WRITE	Write Command Latch	B1-5
WRDDA	Write Deleted Data Address Mark Command Latch	B1-15
Clear*	Clear Signal (Neg true)	C3-6
Gasts	Gate Status if True, Gate Read Data if False	A3-12
LDTRA	Load Track Address	B2-10
LDU.S	Load Unit/Sector	B2-8
LDWRD*	Load Write Buffer (Neg true)	B3-6
RBOUT*	Shift Read Buffer (Neg true)	A6-11
CLREF*	Clear Error Flags	A5-1
BUSY	Controller Busy	D4-5
DONE	Controller Done Pulse (2 us)	D1-13
IDFLD	ID Field Time	F12-3
GAP2	Gap between ID and Data	F12-5
DAFLD	Data (Sector) Time	E9-3
Index	Index Hole Time	F14-1
GAP3	Gap between Data and ID	G15-10
WRTEN	Write Enable Time	F4-8
CO,1*	Write Clock Time	G4-6
C20.21*	Write Data Time	G4-8

## APPENDIX A

# GLOSSARY OF SIGNALS (CON'T.)

SIGNAL	DESCRIPTION	SOURCE
SDIN	Serial Data into CRC Register	E3-3
SDOUT	Serial Data out of CRC Register	D7-12
WDATA*	Write Data Composite (Neg true)	F1-13
ID*	ID Field Address Mark Detect	C12-12
Data*	Data Field Address Mark Detect	C6-8
Sep Clock*	Separated Clock (Neg true)	E7-3
Sep Data*	Separated Data (Neg true)	E16-6
HIGHI*	High Current Adjust Above Track 43	C13-10
10M	10 Megahertz Clock	C3-11
WBO-WB7	Write Buffer Output	A16,B16-14,4,12,
P8DO-P8D7	Read Buffer Output	D14,D15-14,4,12,7
FDDAM	Found Deleted Data Address Mark Latch	D6-5
10MS	10 msec Timing Signal for Head Step	A7-13
SLEW	Head Slew one shot	D1-5
STOUT*	Step Head out towards Track 0 (Neg true)	B7-3
STIN*	Step Head in towards Track 76 (Neg true)	B8-12
TRO	Track O Switch	E7-4
SEC 0*- SEC 4*	Sector Latch (Neg true)	A13-1, 14,11,8 A12-1
UN0	Unit Select Bit 0	A12-10
UN 1	Unit Select Bit 1	A12-9
NXDFD	Next Data Field	D6-3
QHDLD	Head Load Latch	D4-3

# APPENDIX A

# GLOSSARY OF SIGNALS (CON'T.)

SIGNAL	DESCRIPTION	SOURCE
SELO*	Select Unit 0 (Neg true)	E13-11
SEL1*	Select Unit 1 (Neg true)	E13-9
SEL2*	Select Unit 2 (Neg true)	E13-7
SEL3*	Select Unit 3 (Neg true)	E13-5
CRC	Cyclic Redundancy Check Latch	E9-5
WRPRO	Write Protect	E2-8
DRFAL	Drive Fail	E2-13
CRCAZ	CRC Register Equals Zero	D8-10
CPUO*- CPU7*	Command Output Bits 0-7 (Neg true)	A9-1,2,4,9,11,13 B9-11,13
CD00*- CD07*	Data Output Bits 0-7 (Neg true)	B9-1,3, A11-1,3,5, 9,11,13

APPENDIX B
RECOMENDED SPARES

1COM	MODEL	FD360	FLUPPY	DISK	2121FW

ITEM	MODEL	DESCRIPTION	UNIT PRICE	*
1.	FD400	Pertec Floppy Disk Drive	\$ 650.00	4
2.	CF360	Controller/Formatter P.C. Board Set	850.00	2
.3.	360-20	Multiplexer P.C. Card (MUX)	50.00	2
4.	360-22	2 Drive Cable from Controller to Drives	50.00	2
5.	360-24	4 Drive Cable	80.00	1
6.	360-25	50 Pin Jumper Cable between Controller Boards	30.00	3
7.	360-26	40 Pin Jumper Cable between Controller Boards	30.00	3
8.	360-27	Computer to FD360 Cable Assembly	50.00	5
9.	360-101	Power Supply Assembly +24V, +5V, -12V prewired	250.00	2
10.	225-20621-401- 117	Connector - MUX power	5.00	10
11.	225-21021-401- 117	Connector - Controller power	5.00	10

<sup>\*</sup> Recommended inventory quantity per 100 installed FD360 units

NOTE: Prices shown valid at time of publication, but subject to change without notice.

Please ask for price quotation before ordering.

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	,	DOM DISK DIAGNOSTICS		
•	COMMAND	ACTION	COMMENTS	POSSIBLE ERROR MESSAGE
· · · · · · · · · · · · · · · · · · ·	A	Send clear pulse to Floppy Disk Drive electronics.	May be used to halt disk operation provided key board response is available.	None
	Bu,t	Seek to specified track and verifies proper track was attained.	Time required = $\emptyset$ to .75 seconds (approximate)	None
_	Du,s	Reads from specified sector on current track to buffer.	Time required = .2 to 1 seconds (approximate)	Ø1
-	Fu,s	Writes from buffer to specified sector on current track.	Continuous test - no physical indication of test progress	
	Gu,s	Writes from buffer to specified sector on current track, then, checks by reading written data and compares to buffer.	Continuous test - no physical indication of test progress	Ø2 Ø3 Ø7
•	Hu	Seeks track Ø to track 76 verifying that respective tracks were attained.	Continuous test - repetitive head movement to and from extremes of travel	None
	. <b>I</b>	Selects each of the four drives.	Checks electronics regardless of physical drives installed. No physical indication of test progress.	<b>Ø</b> 4
	Ju	Seeks each track (Ø to 76) on unit specified. Writes track and sector number in each sector. Then reads to verify.	Approx. time required = 9 seconds per track for write cycle, 5 seconds per track for read cycle - total time = 17 minutes (approx.)	Ø1 Ø2 Ø5
	Ku	Repetitive J test.	Continuous test.	Ø1 Ø5 Ø2
	Lu	Repetitive J test read cycle only.	Continuous test.	Ø1 Ø5
	Mu	Writes deleted data mark on each sector of current track, then, checks by reading.	Approx. time required = 15 seconds.	Ø6

### DIAGNOSTIC ERROR MESSAGES

- XX Selected drive unit not in ready state
- Ø1 Cyclic redundant check character error on 5 con.
  secutive attempts to read.

Format = \( \psi \) TTSS Where: \( \psi \) = message

TT = track on which

error occurred

SS = sector

\$2 - Cyclic redundant check character error on 5 consecutive attempts to write.

Format =  $\emptyset$ 2TTSS Where:  $\emptyset$ 2 = message

TT = Track on which

error occurred

SS = sector

Ø3 - Read/write test data error.

Format =  $\emptyset$ 3RREEBB Where:  $\emptyset$ 3 = message

RR = data read EE = data expected BB = byte number (hex)

Ø4 - Unit select error.

Format = \$4SSAA Where: \$4 = message

SS = number of unit

actually selected

AA = number of unit at-

tempted to selected

Ø5 - Seek error.

Format = Ø5RREETTSS Where: Ø5 = message

RR = data read

EE = data expected to be

read

TT = track number SS = sector number

Ø6 - Deleted data mark error.

Format =  $\emptyset$ 6SS Where:  $\emptyset$ 6 = message

SS = sector number

Ø7 - Deleted data mark error on read/write test.

Format =  $\emptyset$ 7

6741 VARIEL AVENUE - CANOGA PARK - CALIFORNIA 91303 - PHONE: (213) 348-1391

SCHEMATIC AND LOGIC DIAGRAMS MODEL FD360

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DRAWING NUMBERS PCS

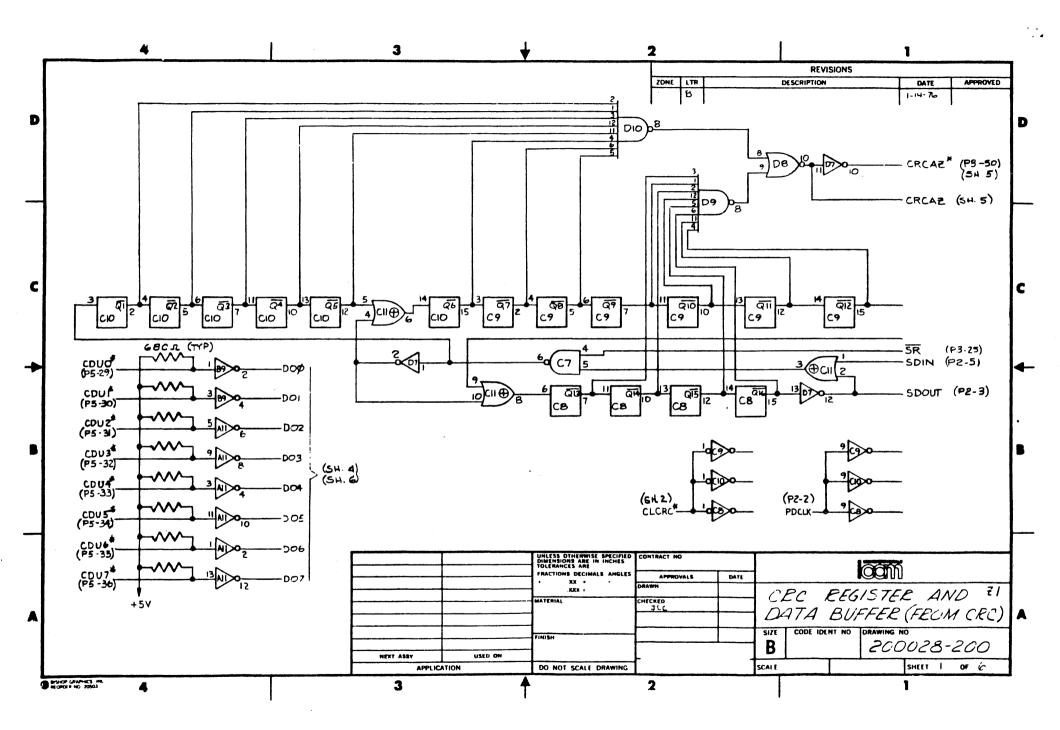
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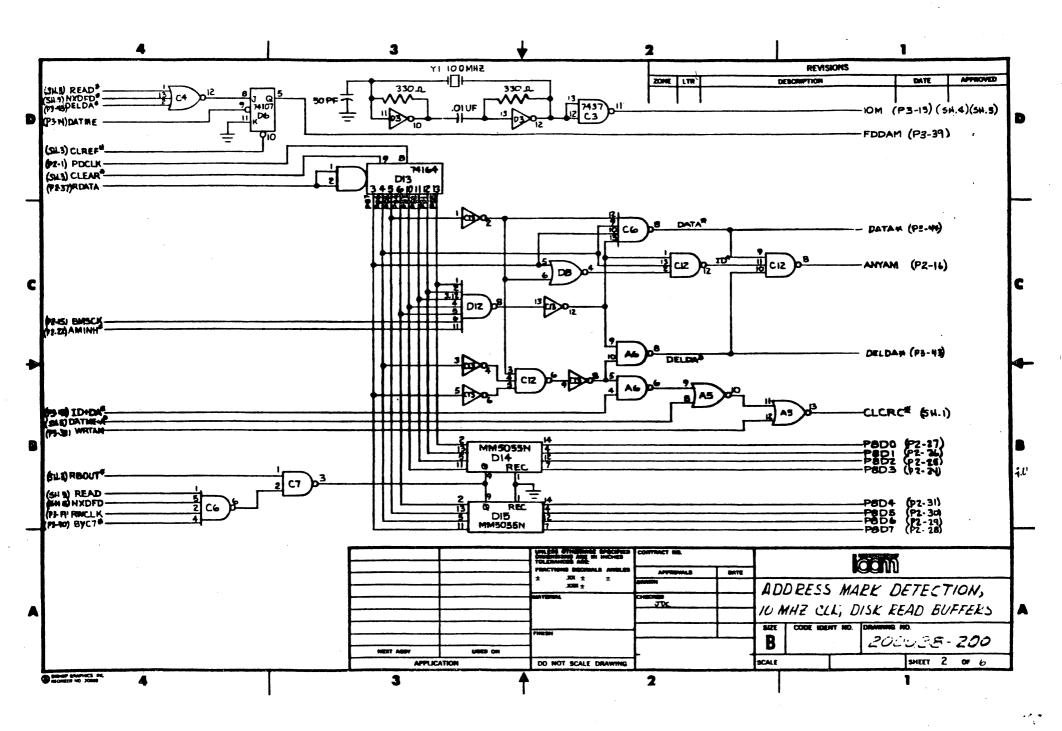
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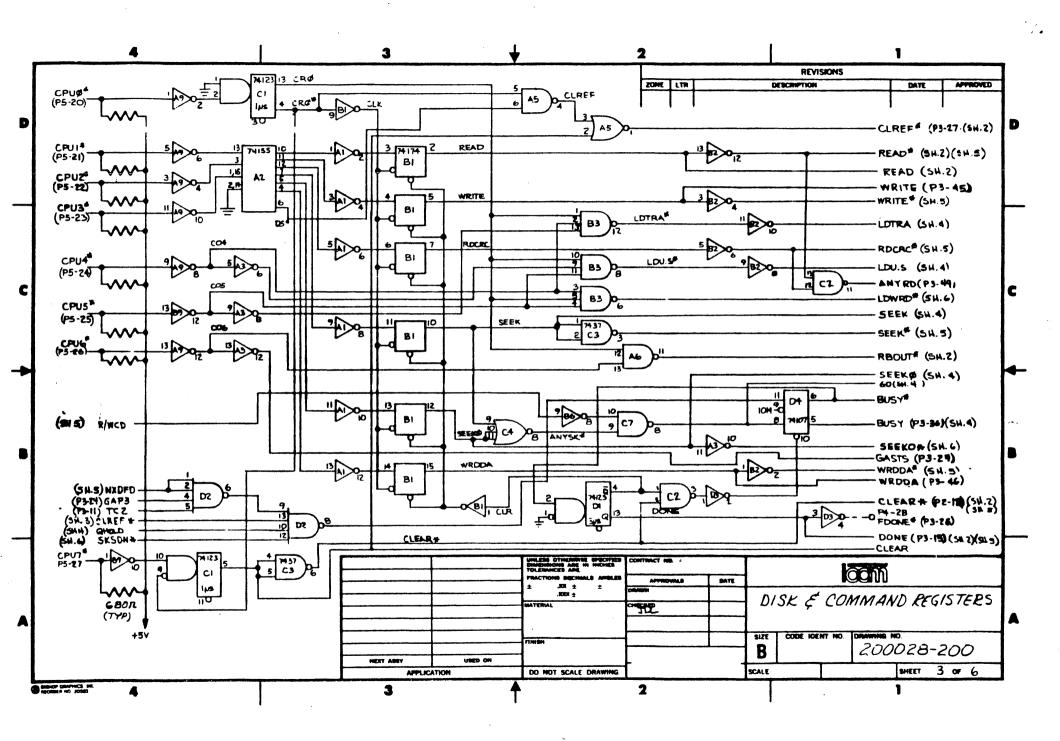
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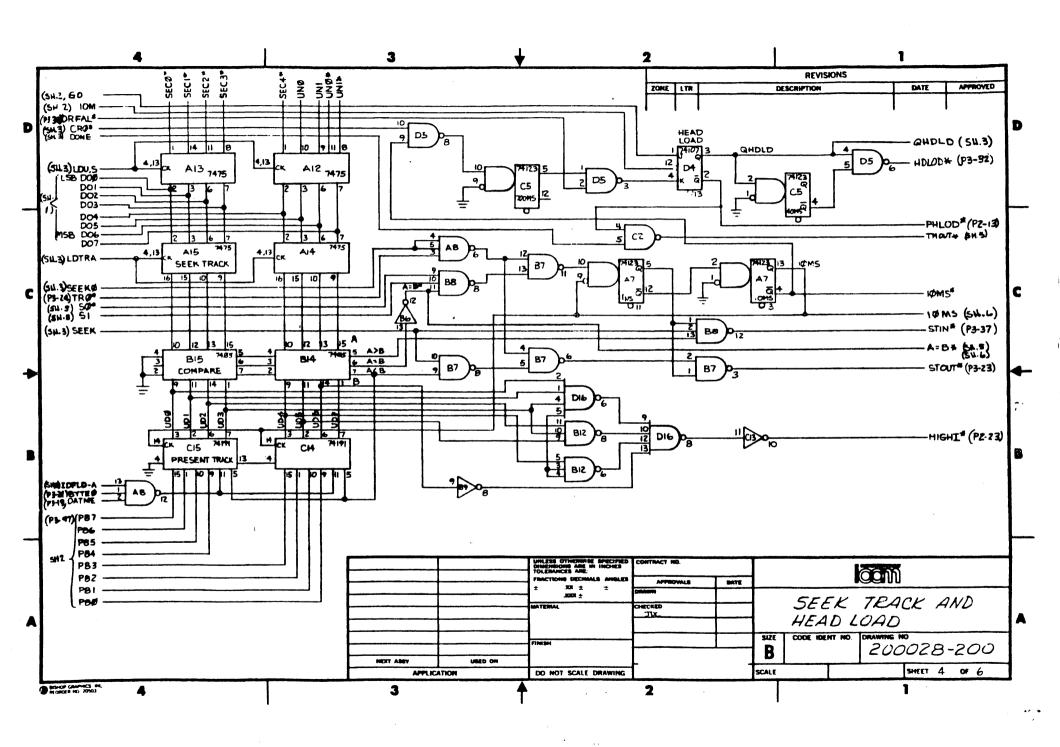
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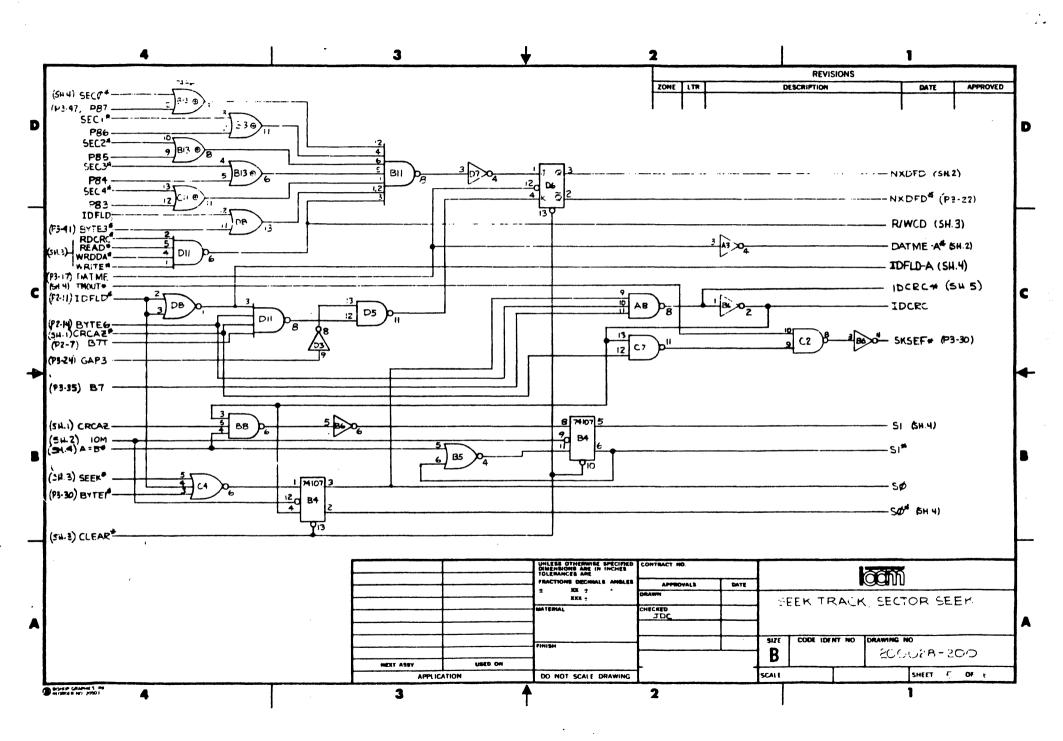
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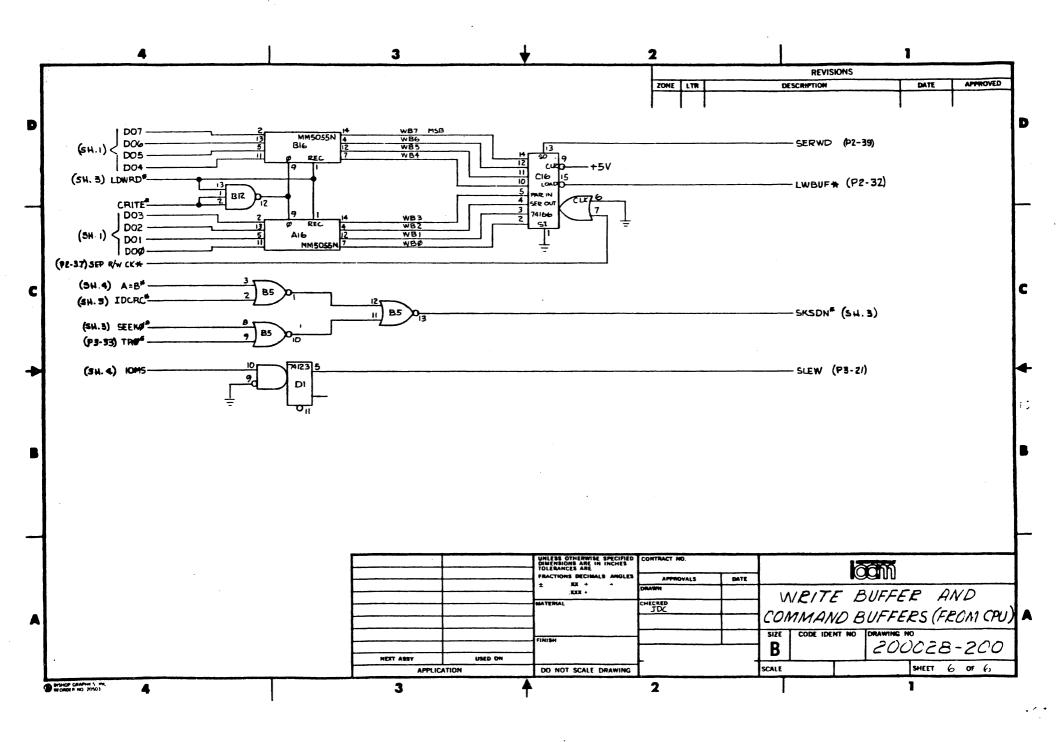


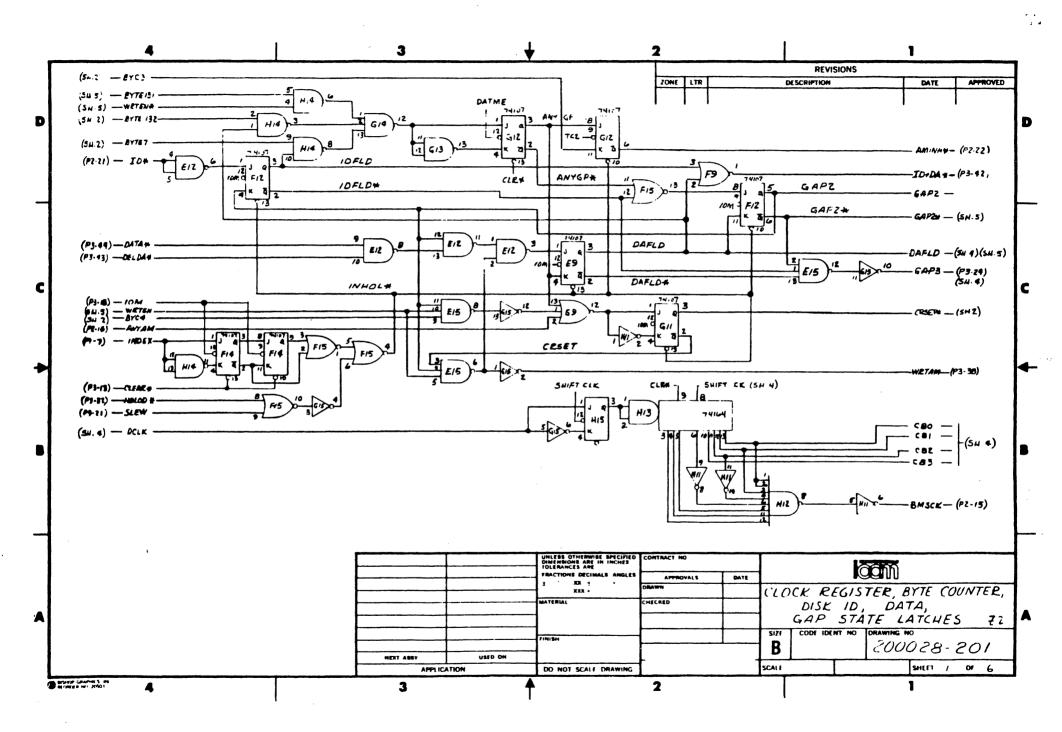


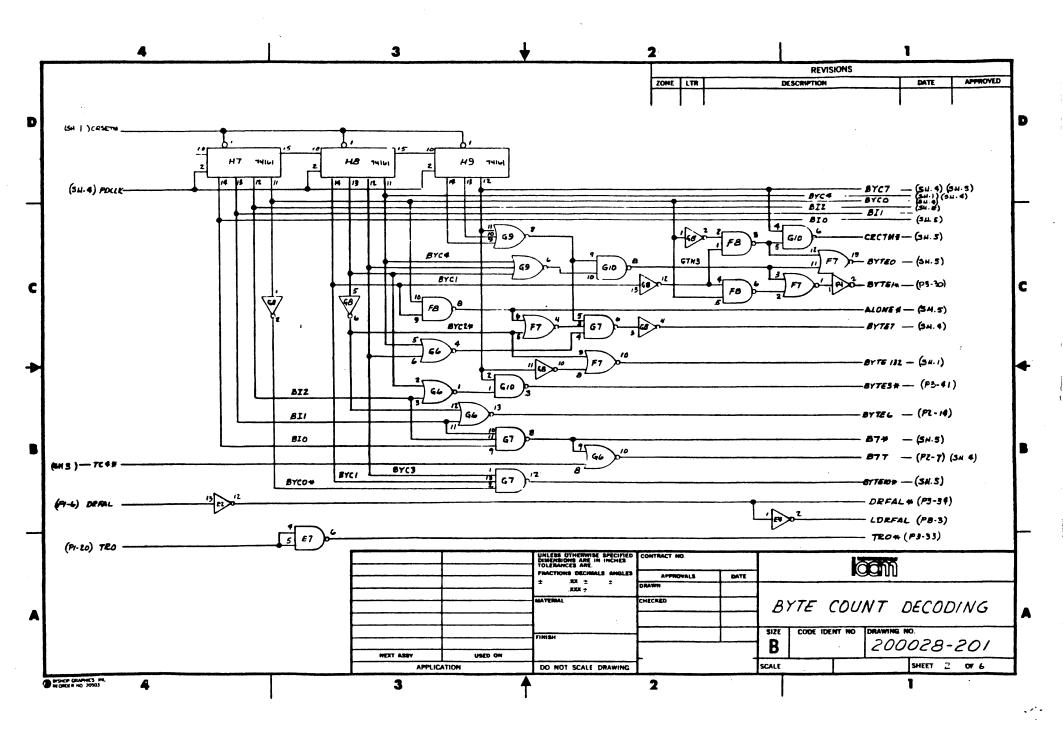


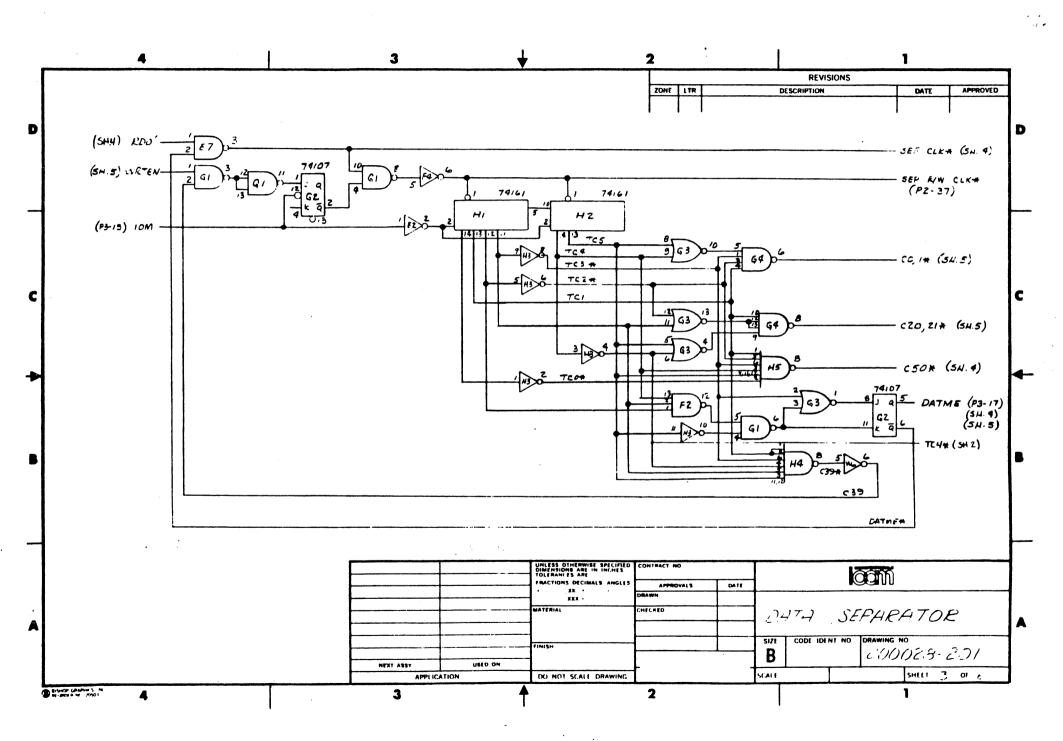


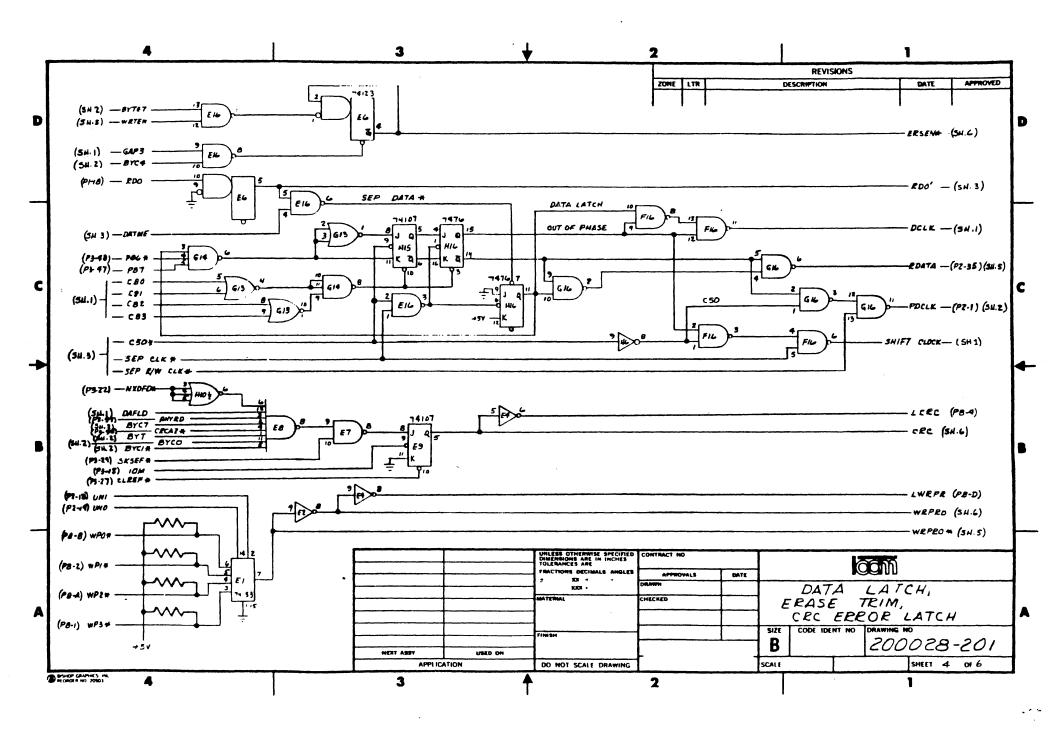


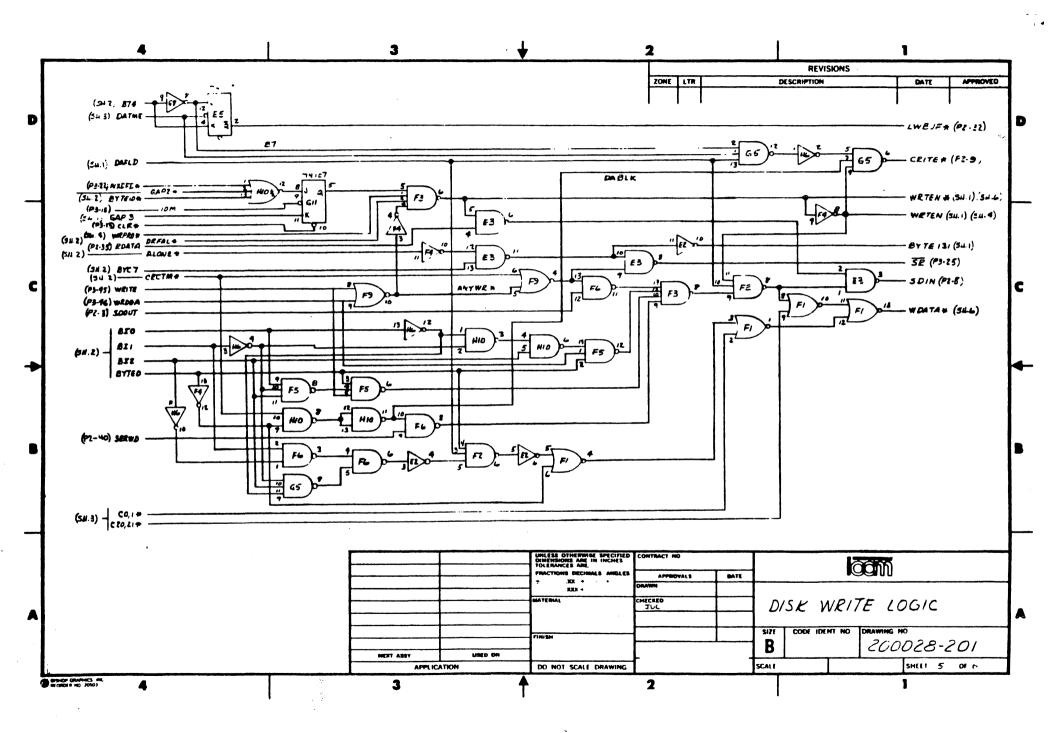


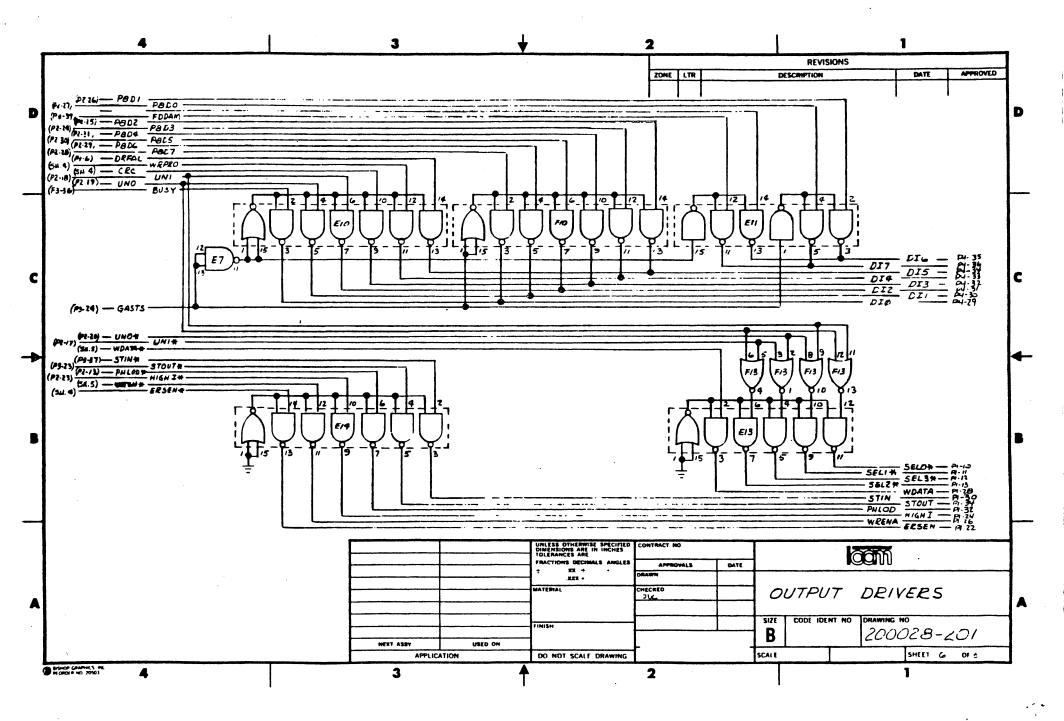


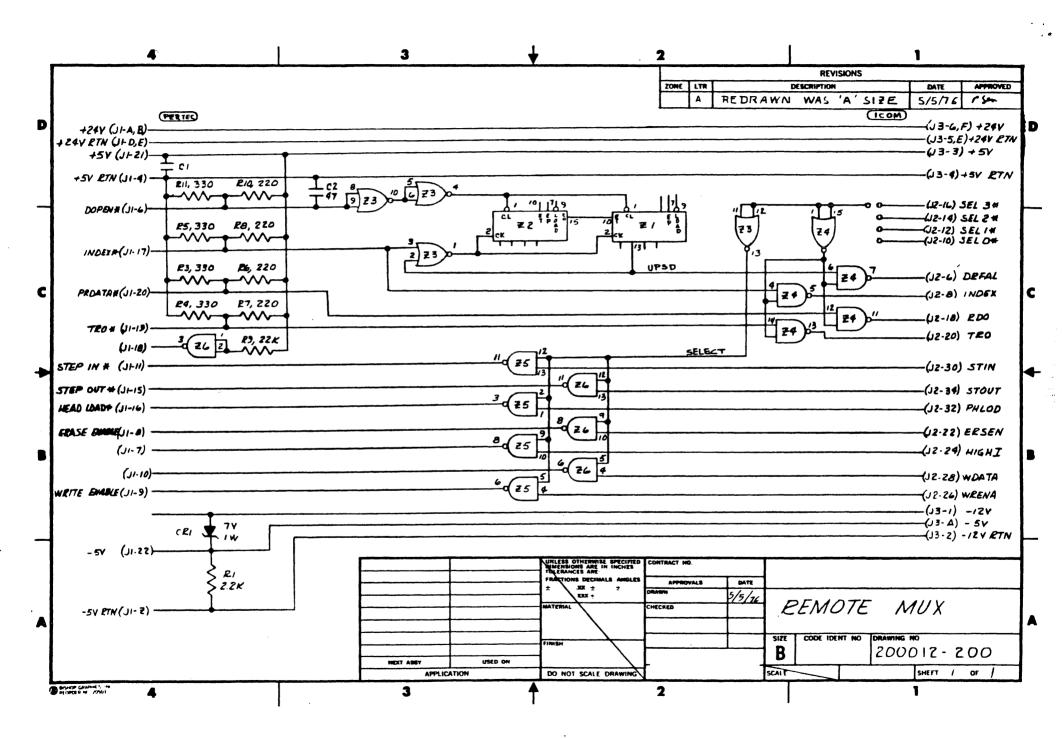




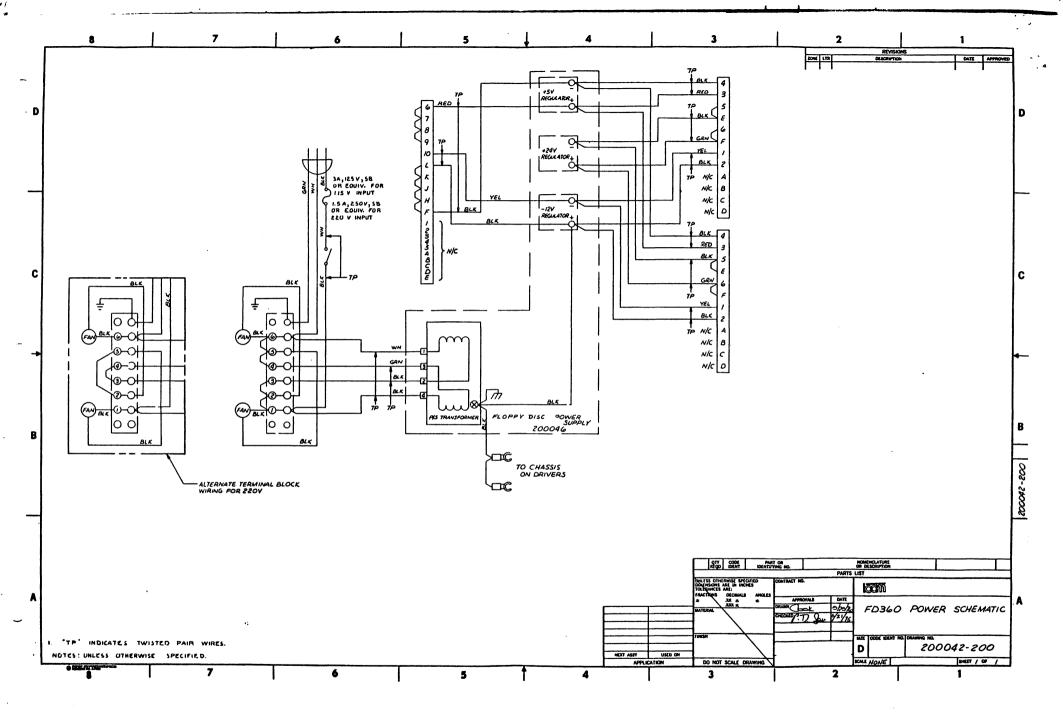




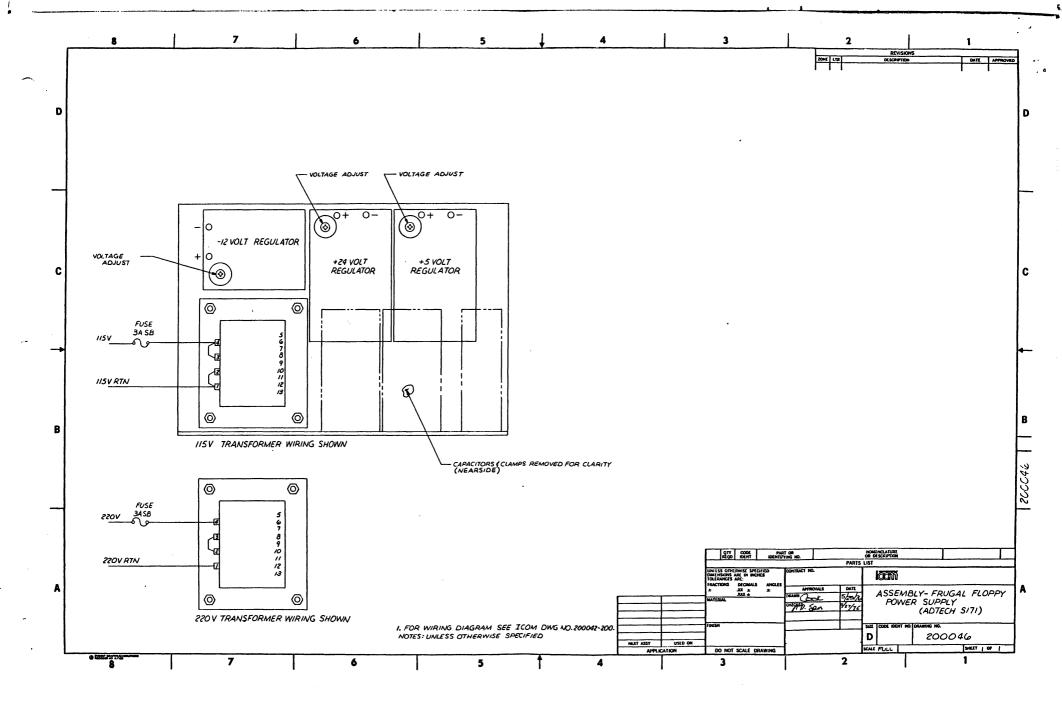




	불위가 끝드는 이 눈으로 살고 하고 살고 있는 것이 되는 것이 없다.
	한 팀 그림은 어떤 그를 내려왔다. 그는 그는 그를 다 하다 그를 된
	경기 전 실험을 하고 있는 그 사람들은 그는 그를 받는 것 같아 있다.
그 시민 그 하는 사람들은 그 가는 이 얼마를 받았다.	도로 살아가 여자들을 하고 하는데 하는 이번 이번 이번 사람이 그리는 그는
그 그 한 그림이 되고 하는 그를 받았다.	
	함께 나는 일을 마하일 때에 가는 그는 사람이라는 게 되어 있다.
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당했다면 내용하는 물로 하는 이번 하는 그를 된다고 했다.	
	공원 - 본 대통령인 이 어렸다면 모든 이 사용을 하고 있는 모든 모든
- 발표하다 기업에 발표하다는 이 이 경기를 받는 것이다. - 발표하다 보고 있는 사람들은 사람들은 사람들은 사람들이 되었다.	그림 사람들은 이번 시간 얼마나 있다는 그들은 것이다.
	불교 민준은 할 것으로 사용한 회에 가입하는 경험 그리는 그리고 되었다. 이 나는
네이지는 그의 내의 그렇게 하는 요한 밤중요한다.	소리의 발표 그리지를 가득하는 살았다는 사람들이 지원하는 사람들은 사람이다.
요한 이 회사 하는 이렇지 그 전하셨습니까?	가 함께 가는 많은 것이 되었다. 이 사는 사는 사는 사람들은 사용을 하는 것이다. 그는 사는 사람들은 사람들이 되었다. 사용 사용 하는 것이 있는 사용이 가는 사용이 가장하게 되었다. 그 사용이 가장 하는 것이다.
	그는 아이들은 이 바람들에게 하다 하는 것으로 살아 있다.
	그리고 말을 하는 것들은 경찰이 되는 바람이 되는 것이 되는 것이 없다.
그렇게 되는 사람들이 얼마나 하는 사람이다.	회사 경기를 하게 되었다고 보다했다. 그 아니라 아니다
	보험, 회가, 회원, 전환 그리면 가는 사람들이 가는 그리는 사람들이 되다.
그림님이, 이탈리는 아니라 이 연락하셨다.	
- 존속하는 본 시간 시간 하는 사람들은 모든 기를 받는다.	[[[마마마마마마마마마마마마마마마마마마마마마마
	보고 많은 단민이를 맞으면 전환인 보세요. 그 그는 그릇이 먹는 것 같아요.
보면 돼 그리고 그리는 어떻게 됐다.	아이들을 보고 하고 아이는 바람이 하고 있는 그는 나는 때문에 모든 것이다. 그
사용하신 이 아이들도 나는 그녀를 주었다.	
	하는 사람들은 살아 많은 사람들이 들어 하는 것이 되는 것을 살아가셨다는데 되는
그렇는 그 사람이 이번 때문에 다양하고 있다.	하다 이 유럽에 살고 반으로 다른 보다 보는 사람이 있는 사람이 받다.
그런데 살기가 들어가게 그리고 그릇돼 같아.	
	지원하는 경기 보고 제가 보험을 받았다. 그 얼마가 보고 하는 그 없는 것이다.
	그 등학자 되고 있을 것이 하면 가장 하는 것이 없는 것이 없는 것이다.
그를 하는 것들이 되는 것이 되는 것이 되는 것을 모르다	
얼마 얼마 그 보는 것이다. 이 불투자 본 시발화	
	사용 사용 보다 보다는 경기를 가져 있는 것들이 되었다. 그 사용
	DB (1982) : : : : : : : : : : : : : : : : : : :
그리고 50년 전에 가게 되었다. 그리고 10년 시간 그런 그는 그를 가장하다. - "사람들이 10년 1일 대한 10년 10년 10년 11년 11년 11년 11년 11년 11년 11년	요즘 하는 아들은 일반 이 맛이네요 살았다면 나는 사람이 되었다면 다른다.
	현실 보고 있는 것이 되었다. 그런 사람들은 사람들은 사람들은 사람들은 사람들은 사람들은 사람들은 사람들은
보이다. 그리는 아이들은 얼마를 가게 되었다.	아이들 하는 사람들은 아이들에게 되었다면서 그 그리고 있다면서 하다면 되었다.
	하고 하고 하지 않아 아내는 것으로 살아 얼굴하고 있는 이번 얼굴 등 사이를 살아왔다.

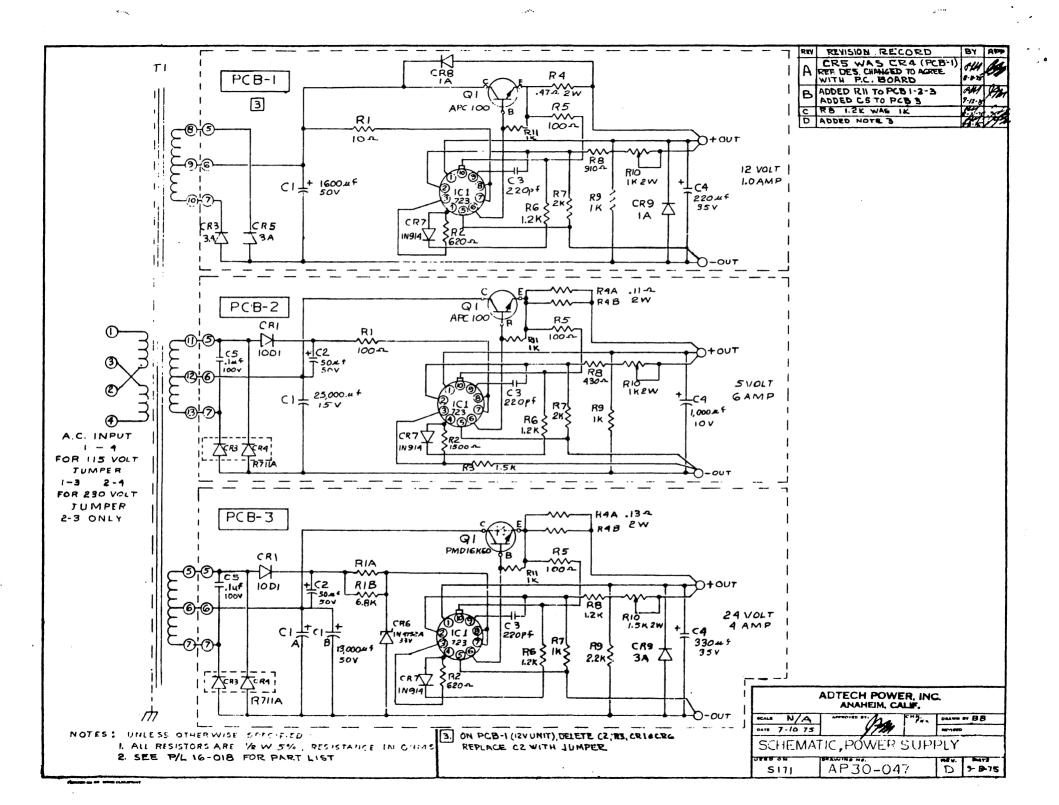


반요. 그는 그는 이렇게 하는 그림을 가려왔는 일반을 만했다. 그리고 있을 때문에 모양하고 있다.	
보고 생생을 되었습니다. 그는 보는 보는 이 사람들이 한 생활들을 받는 보는 것이라고 하시다. 이 이 이 이 이 사람들이 없는	
그는 사람이 되는 그리는 얼마를 하면 하는 사람이 가장 그렇게 되었다. 그는 그들은 사람들이 되었다.	
일 등 등 등 배크를 보면서 하기 되고 그렇는데, 그래요 나는 그래요 하는데, 그를 하는데 그를 보는데 보다 그를 보는데 그렇다는 그리고 있다.	
어른 바람이 살아도 이 없는 것이 하고 있는 사람들이 모든 사람들이 되었다. 그는 사람들이 되었다면 되었다.	
이 보고 하는 사람이 하는데 사람이 하는 것이다. 그렇게 되는 사람들은 사람들은 사람들이 모르게 되었다.	
그러운 그런 그는 그리고 한테를 하는 것도록 모든 부터를 느른번 것인데 아무리를 하고 된 번인 전환을 모나는데	
그리고 있다면 그렇지 않는데 그리다는 그는 그들은 사람들이 그리고 하는데 모든 사람들이 되었다.	
그는 하는 이 어릴 때를 하고 하는 이 번째도 모르는데 모델을 하면 이 그래면 하는 이번 모르되어 보았다.	
그리는 마시트 시민도 하면 그리고 아이들은 그는 생각 그는 생님, 그리는 그렇게 되었다. 그림은 말이 다음을 다 하다.	
이 사람들은 사람들은 살아가 되었다면 하는 것이 되었다. 어떻게 하는 것이 없는 것이 되었다는 것이 없다.	
일보다 하는데 그리가 모든 전환 전환 마스트리스 이번 등을 보고 하게 되는 것을 하는 것이 되었다. 그는 사람들은 모든 <b>사용하</b> 를 보고 있는데	
교육 발전하는 그는 이 명인이 하는 사람이 되었다. 하는 이 이 이 사람들은 사람들이 가는 사람들이 되었다.	
[[ - 도마 :	
어른 아이는 사람들은 그 모습니다. 아이는 아이들에게 가장하고 있으면 하는 사람들이 하고 있다면 다른 사람들이 살다.	
- : [The Book of Table 1] - Book of the State of the Book of the	
생활 사람들 계속 공연 사람들이 하시고 있는 사람들이 하면 생활을 가면 하는 것이 하시는 것이 되었다.	
이 보이는 이번 양성이 되는 이 사람들은 이 가는 사람이 얼마나 얼마를 받아 보는 아니는 사람이 없는 사람이 되었다.	
말하는 요즘 그리에 이 얼마가 그는 것은 사람들이 있다는 하루바다 된 것이는 이용에 비로 하는데 되었다.	
그렇게 그렇게 하다는 이 사람들은 그는 그러운 이 사람들이 되었다. 항상 사람들이 가장 마음을 하는 것을 하는 것이다.	
이 사이 이 이 있다는 사람이 되는 그는 이 모양되었다. 사람들 하면 하는 사람들이 모양하는 하는 이 사용에 나가 있다고 있다.	
하는 사람들이 하고 있는 것이 되었다. 그는 사람들에 보고 있는 것이 되었다는 것이 되었다. 그는 사람들이 되었다. 그런 하는 것이 하는 것이 하는 것이 되었다. 그는 것이 되었다는 것이 되었다. 그렇게 되었다는 것이 되었다.	
가는 사용하다 하고 있는 사용이 되었는데 보고 있다. 그리고 있다는 사용이 하는 사용이 되었다는데 보고 있는데 이 이숙에 보고 있다. 그리고 있는데 그런 사용이 되었다는데 하는데 보고 있는데 그런데 보고 있는데 그런데 그런데 그런데 그런데 그런데 그런데 그런데 그런데 그런데 그런	



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# PCC PERTEC COMPUTER CORPORATION

6741 VARIEL AVENUE - CANOGA PARK - CALIFORNIA 91303 - PHONE: (213) 348-1391

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INTERFACING GUIDE FOR

iCOM MODEL FD360/CF360

FLOPPY DISK SYSTEM

AND FRUGAL FLOPPY FF36

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- VII. Data Format
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March, 1977

## NOTICE

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#### I. GENERAL

The iCOM Model CF360 Controller/Formatter is designed for use by OEM's in industrial, commercial, and development applications. It is used in the iCOM FD360 series Floppy Disk System as well.

The CF360 can accomodate from one to four floppy disk drives and includes a general purpose interface compatible with most microprocessors and minicomputers.

The CF360 offers many features which reduce computer service overhead. For example, the controller is fully IBM 3740 and 3540 compatible, with all formatting and deformatting accomplished automatically within the controller. The controller also performs track seek/verify, and CRC (Cyclic Redundancy Check) generation and verification automatically.

Independent 128 byte (full-sector) input and output buffers offer the possibility for DMA or programmed I/O operation. The ability to write-protect individual drives also is provided by the controller.

Interface signals to the CPU/MPU are TTL compatible and consist of independent input and output parallel data lines and an 8 bit parallel control port. Upon command, controller status data is presented to the CPU via the input data lines.

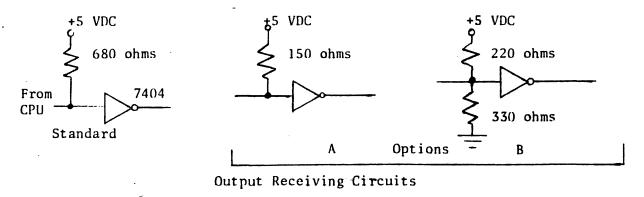
#### II. PHYSICAL DESCRIPTION

The CF360 is housed on two 7.25 X 15 inch (18.4 X 38.1 cm) printed circuit boards containing a total of about 125 IC's.

Interface connections are provided along one long edge of each board, obviating the need for back-plane wiring or a card cage.

#### III. ELECTRICAL INTERFACE

- 3.1 Signal Levels All signals are standard TTL-compatible negative true. Positive true all ports available as an option.
  - 3.1.1 Output to FD360 (negative true)
    Logic "O": 2.0V min to +5V max
    Logic "I": 0.0V min to 0.8V max
    Standard load is 1 TTL Gate (7404 plus 680 ohms to +5V (see Fig. 1).
    The two other input load variations as shown in Fig. 1 are available as options.



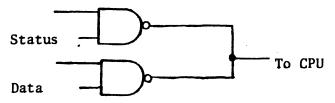
- 1 -

3.1.2 Input from FD360 (negative true)

Logic "0": 2.4V min

Logic "1": 0.0V min to 0.4V max

Current sink at logic "1" is 32 ma (See Fig. 2)



DM 8096 (Tri-State)

## Input Status/Data Drive Circuits

Fig. 2

3.2 Pin Configuration - Two 40 conductor 3M-type ribbon cables with socket connectors on each end are normally used for interfacing the CF360. Connectors which mate with the CF360 are 3M #3432-2002 (solder tail) or 3432-4005 (wire wrap posts).

## 3.2.1 P4 Input Connector (to CPU)

PIN#	PIN#	SIGNAL NAME	DESCRIPTION
CPU Intf.	CF360 end	·	
	P4 1-27	-	Not used
P9 8	P4 28	Key or	Connector Key
		Done	Operation Done (option)
P9 9	P4 29	DI Ø	Data In Ø (LSB)/Busy
P9 10	P4 30	DI 1	Data In 1/ UNA
P9 11	P4 31	DI 2	Data In 2/ UN1 Unit Select
P9 12	P4 32	DI 3	Data In 3/ CRC Error
P9 13	P4 33	DI 4	Data In 4/ Write Protected
P9 14	P4 34	DI 5	Data In 5/ Drive Fail
P9 15	P4 35	DI 6	Data In 6/ Not Used
P9 16	P4 36	DI 7	Data In 7/ Deleted Data Address Mark
P9 17-20	P4 37-40	GRD	Signal Ground

## 3.2.2 P5 Output Connector (from CPU)

PIN# CPU Intf. end	PIN# CF360 end	SIGNAL NAME	DESCRIPTION	PIN# CPU Intf.	PIN# CF360 end	SIGNAL NAME	DESCI	RIPTI	ON	
	P5 1-18	_	Not Used		P5 28	Not Use	d			
P9 29	P5 19	Key	Connector Key	P9 39	P5 29	CDO &*	Data	Out	Ri+	đ
P9 30	P5 20	CPU Ø*	Command Strobe	P9 40	P5 30	CDO p	Data II	11	וו	μ 1
P9 31	P5 21	CPU 1*	Command Word		P5 31	CDO 1*	11	11	. 11	2
		CPU I.	Command word	P9 41	k2 21	CDO 2",				2
P9 32	P5 22	CPU 2*	11 11	P9 42	P5 32	CDO 3*	11	**	11	3
P9 33	P5 23	CPU 3*	11 11	P9 43	P5 33	CDO 4*	11	11	**	4
P9 34	P5 24	CPU 4*	11 11	P9 44	P5 34	CDO 5*	11	11	**	5
P9 35	P5 25	CPU 5*	11 11	P9 45	P5 35	CDO 6*	11	11	**	6
P9 36	P5 26	CPU 6*	11 11	P9 46	P5 36	CDO 7*	11	11.	**	7
P9 37	P5 27	CPU 7*	11 11	P9 47-50	P5 37-40	GRD	Signa	al Gi	roun	d

3.2.3 P8 Power, Write Protect, Miscellaneous (connects to J8 on Board Z2).

PIN#	SIGNAL NAME	DESCRIPTION				
P8 1	WP3*	Ground to Write Protect Unit 3				
P8 2	WP1*	Ground to Write Protect Unit 1				
Key						
P8 3	LDRFAL	LED Driver indicates Drive Fail Status				
P8 4	LCRC	LED Driver indicates CRC Error				
P8 5	LUN 1	LED Driver indicates Unit Select Bit 1 = 1				
P8 6,7,8,9	+5 V	+5 V input				
P8 10	-12 V	-12 V input				
P8 A	WP2*	Ground to Write Protect Unit 2				
P8 B	wpø*	Ground to Write Protect Unit Ø				
P8 C	L BUSY	LED Driver indicates Unit Busy				
P8 D	LWRPR	LED Driver indicates Unit Write Protected				
P8 E	LUN Ø	LED Driver indicates Unit Select Bit $\emptyset = 1$				
P8 F,H,J,K,L	GRD	Ground return for +5V and -12V				

# IV. POWER REQUIREMENTS

- 4.1 CF360 +5VDC, + 5% @ 6 Amps (Power requirements for connector J8 on -12VDC, + 5% @ 1 Amp the Z2 board.)
- 4.2 Disk Drive The CF360 is ideally suited for use with the Pertec FD400 drive. The FD400 requires +24V +5% @ 2 Amps Avg, 4 Amps Peak.

### V. COMMAND AND DATA STRUCTURE

### 5.1 Commands and Command Word Bits

COMMAND		CPU BIT		(NEGATIVE		TRUE)		HEX CODE	
	7	2	_	4	7	2		0	
	7	6	5	4	3	2	1	0	
Examine Status	0	0	0	0	0	0	0	0	00
Read	0	0	0	0	0	0	1	1	03
Write	0	0	O	0	0	1	0	1	05
Read CRC	0	0	0	0	0	1	1	1	07
Seek	0	0	0	0	1	0	0	1	09
Clear Error Flags	0	0	.0	0	1	0	1	1	OB
Seek Track Ø	0	0	O	0	1	1	0	1	OD
Write with DDAM*	0	0	0	0	1	1	1	1	0F
Load Track Address	0	0	0	1	0	0	0	1	11
Load Unit/Sector	Ō	0	1	0	0	0	0	1	21
Load Write Buffer	0	0	1	1	0	0	0	1	31
Shift Read Buffer	0	1	0	0	0	0	0	1	41
Clear	1	0	0	0	0	0	0	1	81
Examine Read Buffer	0	1	0	0	0	0	O	0	40

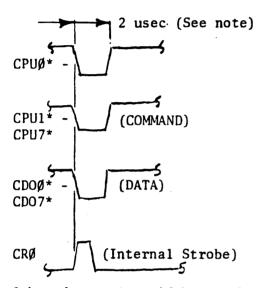
<sup>\*</sup> DDAM = Deleted Data Address Mark

Please refer to Fig. 3 for timing requirements of command and data outputs.

### 5.2 Status/Data Input Lines

```
DIØ
       Data In Ø / Busy
DI1
       Data In 1 / UN Ø Unit Select Code Bit Ø
DI2
       Data In 2 / UN 1 Unit Select Code Bit 1
DI3
       Data In 3 / Media Error or CRC Error
       Data In 4 / Selected Unit Write Protected
DI4
       Data In 5 / Drive Fail (not up to speed, etc.)
DI5
       Data In 6 / No status Bit (Always Logic 1)
DI6
       Data In 7 / Found Deleted Data Address Mark
DI7
```

Please refer to Figure 4 for timing of data and status inputs.



NOTE: Other date pulse widths can be accomodated, consult iCOM.

Shift Read
Buffer Cmd (41)

CPU 6\*
(neg true)

Valid Data

Valid

Valid Status

Input Status and Data Timing

Output Command and Data Timing

Fig. 3

Fig. 4

## 5.3 Data Output Lines

	*	— CDO Bit —	Range
	7 6 5	5 4 3 2 1	0 .
Track Address	Ø MSB Unit		LSB ØØ to 4C (HEX)
Unit/Sector	MSB LSB Ø	MSB Sector	LSB Unit 0-3 Sector 1-1A (HEX)
Write Buffer	MSB		LSB ØØ to FF (HEX)

### 5.4 Operation Sequences

#### 5.4.1 Seek

- a) Set up Data Out Bits 0-7 with Unit & Sector
- b) If track remains same, execute a load Unit/Sector Command (21). Otherwise, set up data out bits with Track Address
- c) Execute a load Track Address command (11)
- d) Execute a Seek command (09)
- e) If interrupt is used floppy will pulse "Done" when operation complete. More typically, the microcomputer should loop-on-busy as follows:
- f) Execute an Examine Status command
- g) Input the data lines and check the busy (=0 when done) and CRC bits.

#### 5.4.2 Seek Ø

- a) Always used on power up
- b) No track address necessary
- c) Execute a Seek Ø command (OD)
- d) Loop-on-busy as above. Selected unit will go to track  $\emptyset$ .

### 5.4.3 Read

- a) After seek to the correct track, unit and sector, execute read (03)
- b) Loop-on-busy
- c) Check CRC, reread if DI# = 1
- d) Execute examine read buffer (40)
- e) Input 1st character from data input lines
- f) Shift read buffer (41)
- g) Repeat (f) & (g) until 128 characters have been read.

### 5.4.4 Write

- a) Load write buffer by first setting up Data Out lines
- b) Execute Load Write Buffer (31)
- c) Repeat (a) and (b) above until 128 characters have been loaded
- d) Seek to correct track, unit, & sector
- e) Execute write (05)
- f) Execute read (CRC) (07) (Does not alter contents of read buffers) See also 6.1.2.
- g) Check CRC Bit and repeat (e) and (f) if CRC = 1. Write Buffer recirculates so it is not necessary to reload it to rewrite.

#### 5.4.5 Write with Deleted Data Address Mark

a) Same as write except that the data when written is automatically preceded by a Deleted Data Address Mark (DDAM) instead of by the standard Address Mark. When the same sector is later read, the Found Deleted Data Address Mark Status bit will be set on completion. This command can therefore be used to identify the data for some purpose. For example, a DDAM can be used to indicate the end of a long data field. It could also be used in some editing function.

### 5.4.6 Clear Error Flags

- a) Used to clear Deleted Data Address Mark and cyclic Reduncdancy Check status bits.
- c) Execute Clear Error Flags command (OB)

#### 5.4.7 Clear

- a) Execute Clear command (81)
- b) Halts any operation in process. Clears Busy and pulses Done.

#### 5.5 Status

- 5.5.1 7 Status Bits are returned on the Data Input Lines, DIØ thru DI 7, when command Bit 6, CPU 6\*, is logic Ø. All bits are negative true.
- 5.5.2 Busy. When logic "1", indicates that an operation is in process. When  $\overline{\text{logic}}$  "0", indicates operation done. Busy is also cleared by Clear, Clear Error Flags, or the head unloading.
- 5.5.3 UNØ, UN1 Unit Select Code Bits:

UN1 UNØ

0 0 = Unit 0 Selected

0 1 = Unit 1 Selected

1 0 = Unit 2 Selected

1 = Unit 3 Selected

- 5.5.4 Media Error or CRC Error. Indicates that the Read or Read (CRC) operation resulted in a data error. The status bit should be cleared by a Clear Error Flags command and the data should reread or rewritten.
- 5.5.5 <u>Selected Unit Write-Protected</u>. Each of the drives can be write-protected manually. If so protected this status bit will equal logic "1" when that unit is selected.
- 5.5.6 <u>Drive Fail</u>. Indicates that the selected drive is not ready because the door is open, or the drive is not up to speed, or no diskette is installed, or no drive is installed.
- 5.5.7 Found Deleted Data Address Mark. If on a Read command the data is preceded by a DDAM then this status bit is set. (See 5.4.5). Status bit is reset by the Clear Error Flags command.

### VI. OPERATION SEQUENCES AND TIMING

- 6.1 Functional Sequences and Characteristics
  - 6.1.1 <u>Seeks</u> The FD360/CF360 starts a seek operation by reading its present location from the ID field preceding each sector. A comparison is then made with the desired track address and the head is stepped in the correct direction until the head should be at the right track. The track address is read again and if it compares to the desired track the operation is done.

In some formats the track address may not correspond to the physical track number, due to tracks being declared down. The FD/CF360 will handle this format by seeking until the correct track address is found

It should be noted that a seek is necessary only to change tracks. To change sectors only, the Load Unit/Sector command is used.

The seek Track  $\emptyset$  can be used to seek to track  $\emptyset$  without regard to the present track. It does not require a transfer of the Track Address. The Seek Track  $\emptyset$  should be used on power up and restart to initialize the head.

6.1.2 Read - A seek to the correct track is necessary unless the head is on the correct track already. A load Unit/Sector command selects the sector to be read, and the CF360 examines the ID Field preceding each Data Sector to find the correct sector. In a standard IBM format diskette, the sectors start at 1 following the index hole and increment to 26 (1A HEX) just before the index hole.

The CF360 automatically computes the CRC during the read and if an error is found the CRC status bit is set at the end of the read. Data from the sector is shifted into the Read Buffer at a 250 Khz rate. When the Read command is complete the first character of the sector is at the front of the read buffer. An examine Read Buffer command (40) will place the Read Buffer output on the Data Input Lines. A shift Read will shift the Read Buffer and place the Read Buffer output on the Data input lines. 127 shifts are thus required to read the 128 Bytes.

A read CRC does not load the data into the Read Buffer but merely tests CRC. This is commonly used following a Write to insure data integrity. Thus a Write operation can be executed and verified without destroying the Read Buffer. This is important in edit operations and for CPU's with small memory.

6.1.3 Write - A write operation writes the contents of the Write Buffer to the selected Unit/Sector. The location of the head while loading the Write Buffer does not matter. After the Write Buffer is loaded, a seek command will move the head to the desired track. The Write Command then causes the CF360 to begin examining each ID field for the correct sector. A field of 6 bytes of "O"'s will then be written preceding the intended location of the data sector. Next, the Address Mark is written (or DDAM if a Write Deleted Data Address Mark command). Then each byte of the Write Buffer is written out, followed by the CRC (2 Bytes) generated by the CF360. Finally, one byte of all zero's or all one's follows the CRC.

The data written should be read by a READ CRC command to insure the operation was valid.

#### 6.2 Operation Timing

### 6.2.1 Seek

Track to Track Head Load & Settling Time Maximum Seek Time, 77 tracks 10 msec 40 msec, maximum 820 msec

### 6.2.2 Read/Write

Sector Read/Write Time Average Latency (½ Rev) 6 msec 83 msec 1 msec

Minimum Latency
Read/Write Buffer Shift Rate:

DC to 500 Khz

#### VII. DATA FORMAT

7.1 The CF360/FD360 used standard IBM 33FD type diskettes such as those used in the IBM 3740 series equipment. It is completely media and format compatible. Type 33FD diskettes can be obtained from a number of sources, including iCOM.

### 7.2 Format Details (each Diskette)

77 tracks per diskette 00 thru 4C HEX 26 Sectors per track 01 thru 1A HEX 128 Bytes (8 Bits) per sector 256,256 Bytes Diskette 1,025,024 Bytes Per FD360 or CF360 using 4 drives.

#### VIII. TYPICAL MICROPROCESSOR INTERFACE SKETCH

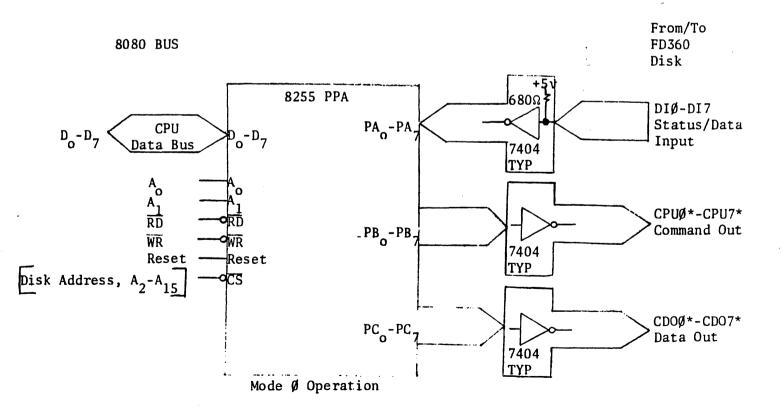


Fig. A-8080 Interface Sketch

### VIII. CON'T

NOTE: Fig. A, page 8 is <u>not</u> compatible with iCOM's FDOS-II software, and is shown only <u>as</u> an alternative hardware interface arrangement for custom system designs. Use Fig B below with iCOM's FDOS-II/8080 OEM software.

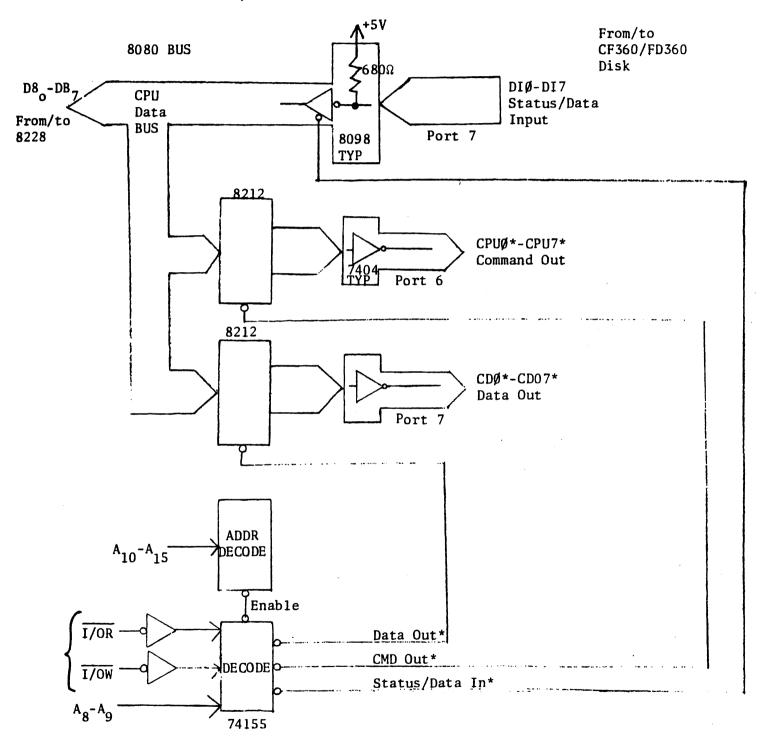


Fig. B 8080 Interface Sketch for use with iCOM FDOS-II/8080 OEM Software

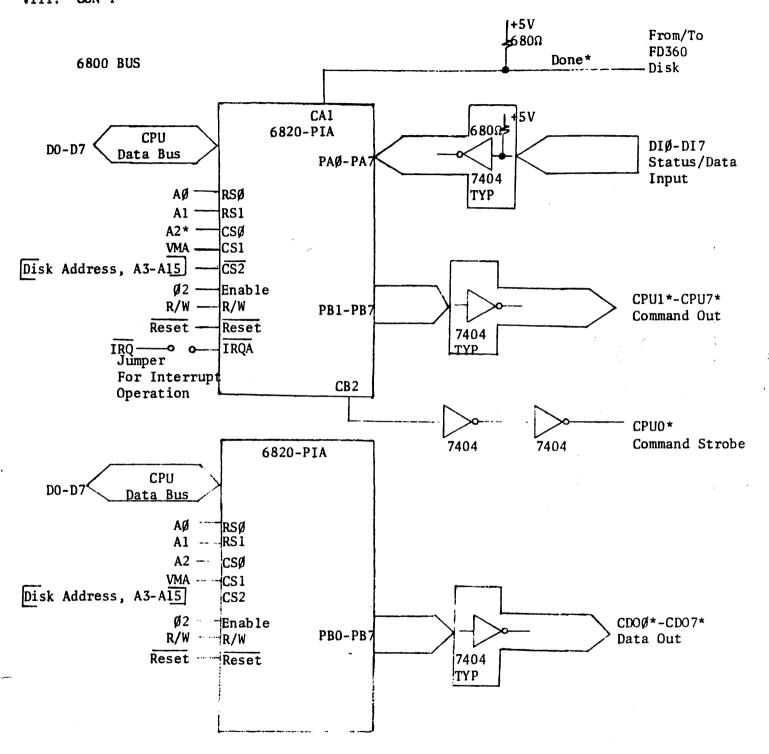


Fig. C-6800 Interface Sketch

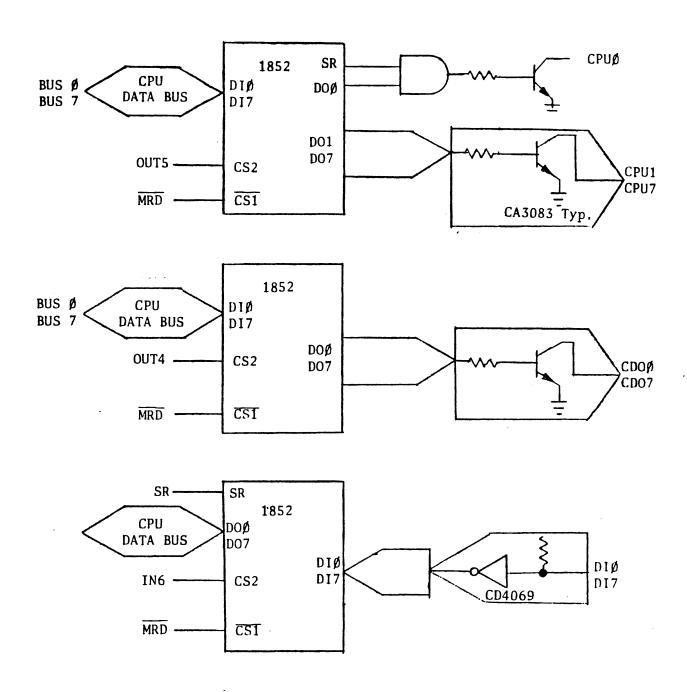


Fig. D 1852 Interface Sketch



### APPENDIX A

# Addendum for Frugal Floppy Model FF36

- A.1 Add section 3.2.4 as follows:
  - 3.2.4 P3 disk drive with remote mux power. (Connects to J3 on the remote mux board.)

PIN#	SIGNAL NAME	DESCRIPTION		
P3 1	-12 V DC	-12 V Input		
P3 2	-12 V RET	-12 V Return		
P3 3	+5 V DC	+5 V Input		
P3 4	+5 V RET	+5 V Return		
P3 5	+24 V RET	+24 V Return		
P3 E	+24 V RET	+24 V Return		
P3 6	+24 V DC	+24 V Input		
P3 F	+24 V DC	+24 V Input		

- A.2 Disregard Section 4.2 Use information as follows:
- 4.2 Disk Drive with Remote Mux
  - +24 V DC+ 10% at 2 amps averate, 4 amps peak.
    - +5 V DC $\pm$  5% at 1 amp maximum. -12 V DC $\pm$  5% at 0.3 amps peak.
  - Power spécified is for a single disk drive. If multiple drives are to be used, the power requirements must be multiplied by the number of drives used.

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