## MASSACHUSETTS INSTITUTE OF TECHNOLOGY

## PROJECT MAC

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## A Glossary of Vision Terms

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All programs are found on the Vision tape in the file noted under the program name. Underlined terms are included in the glossary.

A global variable used to generate ellipses.

Angbtn (Subr) Angles New LPSBRS 4-21 (Angbin Pl P2 P3) P<sub>i</sub> are <u>points</u>. Returns 0 where:

radians

Arrayp(Expr) Region Subrs (Arrayp Name Arg L) Where L =  $(n_1 n_2 ... n_j)$ Approximately (Array (Eval Name) (Eval Arg)  $n_1 n_2 ... n_j$ ). Prints an error message if
there is insufficient room.

В

Bind (Expr) Gen Stuff A global variable used to generate ellipses. (Bind  $L_1$   $L_2$ ) where  $L_1$  is a list of atoms and  $L_2$  is a list of S-expressions. Bind binds the values of the S-expressions (they too may be atoms) to the atoms.

Bindq (Fexpr) Gen Stuff (Bindq  $(A_1 \ A_2 \ \dots \ A_n)$   $(S_1 \ S_2 \ \dots \ S_n)$ ). Same as: (Bind (Quote  $(A_1 \ A_2 \ \dots \ A_n)$ ) Quote  $(S_1 \ S_2 \ \dots \ S_n \ )$ )).

Body

A semi-global variable assumed by <u>iterate</u> to name an expression to be repeatedly evaluated.

Bndry (Fexpr) Region Subrs (Bndry A) Approximately equivalent to: (Setq A (Cons Den (Cdr (Region Pt Pred Lowpt Uppt)))). Boundary

Bstcrv (Expr) Bstcrv 4-21 LPSBRS 4-21 A connected set of <u>points</u> of a <u>region</u> all of which neighbor <u>points</u> outside the region.

(<u>Points</u> diagonally across from each other in a square are not connected but they are neighbors).

(Bstcrv L) where L = (Ind L<sub>1</sub>); and L<sub>1</sub> =  $(P_1 \ P_2 \ ... \ P_n)$ ; Ind  $\varepsilon$  {0 1 2 } for straight line, concave, convex;  $P_i$  are points. If Ind = 0 Bstcrv is the identity function. Otherwise, if the points can be approximated by a circular or elliptical arc, Bstcrv yields: (IND 'ELLIPSE'  $P_0$   $n_1$   $n_2$   $\alpha$   $P_1$  $\beta$ ) where:

IND is unchanged;

'ELLIPSE' is the type of curve, as opposed to hyperbolic; P<sub>0</sub> is a point representing the center of the ellipse; n<sub>1</sub> is a LISP number for the length of the principal semi-axis; n<sub>2</sub> is for the secondary semi-axis;

 $\alpha$  is an angle  $-\pi/2 < \alpha \le \pi/2$  measuring the tilt of the principal axis from the horizontal, about the center of the ellipse;

 $P_1$ ,  $\beta$  specify the segment of the curve in the following manner: "beginning at point  $P_1$  and using  $P_0$  as center point, take B radians about  $P_0$ , in the clockwise direction if IND = 1, otherwise in the counterclockwise direction. This is the relevant segment.

For second-degree curves which are not ellipses,

Bstcrv returns the general equation coefficients and the first and last <u>points</u> on the arc. E.g. (IND Name A B C D E  $P_1$   $P_2$ ) where Name is Hyper or Parab and the best fit curve is  $Ax^2 + Bxy + Cy^2 + Dx + Ey = 1$ . Bstcrv requires floating point input <u>points</u>.

(Callf  $F_n Arg_1 Arg_2 ... Arg_n$ )  $(F_n (Eval Arg_1)(Eval Arg_2) ... (Eval Arg_n)$ ).

 $\begin{array}{l} {\rm L} = ({\rm L}_1 \ . \ ({\rm L}_2 \ . \ (. \ . \ . \ . \ ({\rm L}_n \ . \ L) \ . \ .))) \ \ {\rm is} \\ {\rm a \ circular \ list.} \ \ ({\rm Cdr} \ \ ({\rm Cdr} \ \ (. \ . \ . \ ({\rm Cdr} \ L) \ . \ .))) \\ {\rm results \ in \ L, \ if \ there \ are \ n \ \underline{Cdr}'s.} \end{array}$ 

(Cleartab) sets all <u>Hashtab</u> entries to <u>Nil</u>.

(Complement L<sub>1</sub> L<sub>2</sub>) yields L'<sub>1</sub> which is L<sub>1</sub> with all occurrences of elements from L<sub>2</sub> removed.

(Cos X). Returns cosine of X radians.

(Curve L) where L is a list of Bstcrv outputs representing a boundary to a region. Curve returns a name-- e.g. "funny looking thing" -- describing the shape of the region so bounded.

(DD M S). (DT (Quote M) (Quote S)).

A global variable used to determine the density of <u>points</u> to be read from the <u>vidisector</u>. If Den is n, every nthe <u>point</u> is read.

Callf (Fexpr) Region Subrs

Circular list

Cleartab (Expr) Region Subrs

Complement (Expr) Region Subrs

Cos (Expr)
Gen Stuff

Curve (Expr) DT Etal

DD (Fexpr) DT Etal Conv 9

Den

Den (Fexpr) Region Subrs (Den X). Sets Den to X.

Disgen (Fexpr) Region Subrs (Disgen A L) where L = (d, L<sub>1</sub> L<sub>2</sub> . . . L<sub>n</sub>) and L<sub>i</sub> are lists of points. Using <u>Dlist</u>, constructs an <u>array</u> on A to plot the points in the L<sub>i</sub> Assuming the scope is in parameter mode, initializes it to point mode for <u>Dlist</u>'s instructions. Terminates display instructions by resetting scope to parameter mode and stopping display. The element d is a density number.

Disp (Fexpr) Region Subrs

(Disp A) inserts <u>array</u> A at the head of <u>Dislist</u> (with a single <u>cons</u>) causing A to be interpreted by display mechanisms.

Display (Fexpr) Region Subrs (Display  $F_n$   $Arg_1$   $Arg_2$   $Arg_3$  . . .  $Arg_n$ ). Approximately: The sequence

i) (F<sub>n</sub> (Quote Ptlist) Arg<sub>2</sub> Arg<sub>3</sub> . . . Arg<sub>n</sub>)

ii) (Disgen Arg, Ptlist)

iii) (Disp Arg,)

Dlist (Expr) Region Subrs (Dlist L M) where L is a list of <u>points</u> and M a number. Assuming an <u>array Object</u> and an index <u>I</u> generates instructions to the scope to display, in <u>point mode</u>, the <u>points</u> in L. Dlist first multiplies each coordinate of each point by M (assuming that the <u>points</u> had at one point been <u>scale</u> d). <u>I</u> is left pointing to that element of the <u>array</u> following the last one entered by Dlist.

DT (Expr) DT Etal Conv 9

ELLIPSE (Fexpr) Gen Stuff

Erase (Fexpr) Region Subrs

Finc

(DT M S) where M is a <u>model</u> and S is a <u>scene</u>,

it returns a series of L, where

L<sub>i</sub> = ((Eval M) i IS (R<sub>i</sub> . . . R<sub>ij</sub>))Its Value

is a list of regions not used in found figures. Each L<sub>i</sub> represents an instance of a figure in the <u>scene</u> which matches the <u>model</u>. In L<sub>i</sub>, the R<sub>ij</sub>'s are the <u>regions</u> which compose the figure. E.g. L<sub>i</sub> might be "cube i is A C D.

(Ellipse  $n_1$   $n_2$   $X_S$   $Y_S$  p f). Sets up global variables to generate points of an ellipse. The ellipse has axes parallel to the coordinate axes. That parallel to the X - axis has length 2N,; the other has length  $2N_2$ . The ellipse passes through the points (XS, YS), (XS -  $\frac{n_1}{2}$ , YS -  $\frac{n_2}{2}$ ),  $(XS - n_1, YS)$  and  $(X - \frac{n_1}{2}, YS + \frac{n_2}{2})$  at its axis extremities. The global variable param determines which point on the ellipse is generated. The last input element has as value a function (which is bound to the global variable f i n c) and is used to increment param. The first four variables are bound to the atoms  $\Lambda$ , B, Xshift and Yshift respectively. See Genpoint. (Erase A, A, . . . An). Removes all named arrays from Dislist and thus from the scope.

A global variable used in curve generation. See ellipse, line, genpoint. Genpoint (Expr)
Gen Stuff

Hashpt (Expr) Region Subrs

Hashtab (Array) Region Subrs

Hist (Expr) Region Subrs (Genpoint) Evaluates the expressions bound to X and Y and delivers the CONS' ED result as the current point on a desired curve. It is assumed that X, Y have had expressions bound to them intended to generate points. See ellipse, line. Also, it is assumed i) that param is used in the point generating expressions to determine which point to produce, and ii) that a function has been bound to finc which increments the parameter as one wishes. Generate, then, after generating the current point, applies finc to param in preparation for the next point.

(Hashpt P) where P = (X · Y), inserts the number Y into the <u>list</u> pointed to by the element which corresponds to X in the <u>array Hashtab</u>.

Names a one dimensional <u>array</u> (or array name) used to store <u>points</u> of a two dimensional grid. The one dimension corresponds to the first (left, <u>Car</u>) side of a <u>point</u>. The <u>array</u> is as long as necessary to accommodate all possible horizontal values between selected limits (see <u>lowpt</u> and <u>uppt</u>). Each entry in the <u>array</u> points to a list of second coordinate values.

(Hist Fn P1 P2 L) where P1 and P2 are points,

L and  $F_n$  are a function of a single point, e.g.,  $(F_nP)$  is an intensity. Using  $P_1$  and  $P_2$  as Lowpt and Uppt, Hist adds to L a list of ordered pairs. The first element of each is a value of  $F_n$ ; the second is the number of times that value occurred.

Ι

A global name often used as an array index.

Iterate (Fexpr) Gen Stuff (Iterate  $(a_1 \ S_1)(a_2 \ S_2) \dots )(a_n \ S_n)$ ) where one of the  $a_i$ 's is body and another is <u>terminate</u>. Iterate first binds the values of the  $S_i$  to the  $a_i$ . Then it evaluates body until the evaluation of <u>terminate</u> is T, at which point it returns <u>result</u>. (<u>Result</u> is nil unless set otherwise).

Lengthc (Expr) Region Subrs (Lengthc L) where L is a <u>circular list</u>, returns the length of L.

Line (Fexpr) Gen Stuff (Line  $n_1$   $n_2$  p s f) Line sets up global variables with which <u>generate</u> generates a line. The variables  $(n_1$ ,  $n_2$ ) are a point through which the line passes when <u>param</u> is zero. The variable p is bound to <u>param</u>; s is the slope of the line; f is bound to finc.

Lineprint Region Subrs (Lineprint) prints on line printer
i) (Lowpt Uppt Den) on one line

Lowpt

ii) The array determined by Lowpt Uppt Den in lines.

A global variable point whose coordinates are used as lower bounds. Lowpt and Uppt define a rectangle in the vidisector's range. Lowpt defines the lower left corner and uppt the upper right.

Lowpt (Fexpr) Region Subr (Lowpt X Y). Lowpt set to (X · Y).

Memhash (Expr) Region Subrs (Memhash P) where P = (X · Y) yields:
i) T if the point is in <u>Hashtab</u>;
ii) Nil if not.

Mode1

A model is an atom which has on its property list, under "regions," a list of lists. Each one of these is of the form: an atom followed by a list of properties and pointers. For example, to define a pyramid with two of its sides visible:

(Defprop Pyramid(

(A (Neighbor B) (Shape Triangle))

(B (Neighbor A) (Shape Triangle))) Regions)

NZP (Expr) Region Subrs

(NZP P)

(Not (Zerop (Space (Car P)(Cdr P))))

Object

A global name often used as an <u>array</u> name's name.

Param

A global variable used in curve generation. See ellipse, line, genpoint.

Param2 (Expr) Region Subrs (Param2 Mode Light Pen Stop Scale Intensity) generates (and stores in the <u>array Object</u>) a display word intended to be interpreted in the parameter mode. The arguments mean what they seem to mean. (See page 63 of PDP-6 Manual.) Param2 uses and increments <u>I</u> as index for the <u>array</u>.

Point

Coordinate points normally used to refer to the two dimensional <u>vidisector</u> are assumed to be <u>dotted pairs</u>. The horizontal coordinate comes first  $(\dot{X} \cdot Y)$ .

Point2 (Expr) Region Subrs (Point2 Axis Mode Light Pen Intensity Position) is to point mode as <a href="Param2">Param2</a> is to parameter mode.

Polyseg (Expr) Poly Grfth

Pred

Predicate (Fexpr) Region Subrs

Pt

Pt (Fexpr) Region Subrs

Raster (Fexpr) Region Subrs

Reclaim (Fexpr) Region Subrs

Region (Expr) Region Subrs (Polyseg L) where L is a list of <u>points</u> which is a <u>boundary</u>. Polyseg returns a list of <u>points</u> which is a polygonal approximation to the <u>boundary</u> (except that the <u>points</u> in the output are a factor of 4 times larger than those in the input).

A global variable which is intended to reference a predicate of a single point.

(Predicate P) sets Pred to P.

A global variable used as a point.

(Pt X Y). Sets <u>Pt</u> to (X · Y).

(Raster A) Approximately equivalent to: (Setq A(List Den (Scan Pred (Scale Lowpt) (Scale Uppt)))).

(Reclaim A) resets BPORG to just prior to the Array A.

(Region P<sub>1</sub> Pred P<sub>2</sub> P<sub>3</sub>) where the P<sub>i</sub> are points and Pred is a predicate, yields a list L = (N B<sub>1</sub> B<sub>2</sub> · · · B<sub>j</sub>) where N is the number of points found in the region and each B<sub>i</sub> is a list of points which form one boundary of the region, R, defined:

i) R contains P<sub>1</sub>; ii) All points in R are connected to P<sub>1</sub>; iii) All points in R satisfy

the predicate Pred; iv) All points in R are

within the bounds P<sub>2</sub> and P<sub>3</sub> considered as <u>lowpt</u> and <u>uppt</u>.

A connected set of <u>points</u> all of which satisfy some particular <u>predicate</u>.

A region is an atom which has on its property list the properties "Neighbors" and "Shape".

Corresponding to "Neighbors" is a list of atoms which are neighboring regions of the given atom. Corresponding to "Shape" is a shape name.

(Remhash P) where P = (X · Y), removes all references to that point from <u>Hashtab</u>.

(Scale P) where P = (X · Y) is a <u>point</u> (used for <u>vidisector</u> referencing). Yields P' = (X/Den · Y/Den).

(Scan  $P_r$   $P_1$   $P_2$ ) where  $P_r$  is a <u>predicate</u> and  $P_1$  are <u>points</u>. Yields a list of <u>points</u> satisfying the <u>predicate</u> and within the rectangle defined by  $P_1$  and  $P_2$  as <u>Lowpt</u> and <u>Uppt</u> respectively.

A scene is an atom which has on its property list, under "regions" a list of atoms corresponding to <u>regions</u> in the scene. (Sclear). (Setq Dislist Nil).

(Sets L) were L is  $((a_1 S_1) (a_i S_2) \dots (a_n S_n))$  For each i, binds the value of the S-expression  $S_i$  to the atom  $a_i$ .

Region

Region

Remhash (Expr) Region Subrs

Scale (Expr) Region Subrs

Scan (Expr) Region Subr

Scene

Sclear (Fexpr) Region Subrs

Sets (Expr) Gen Stuff Setq (Fexpr) Gen Stuff

Shape (Expr) Region Subrs

Sin (Expr)
Gen Stuff

Terminate

Topology (Expr) Topo System  $(Setq (a_1 S_1)(a_2 S_2) (a_n S_n))$ 

For each i, binds the value of the S-expression S<sub>i</sub> to the atom a<sub>i</sub>.

(Shape  $L_1 L_2 N$ ) where  $L_1 = ((R_1 L_{11})(R_2 L_{12}) ... (R_n L_{1n}))$ 

$$L_2 = (B_1 B_2 \dots B_n)$$

 $R_i$  is a <u>topology</u>-coded descriptive name of a region;  $L_{li}$  is a list of neighbors of  $R_i$ 

B<sub>i</sub> is a description of the boundary R<sub>i</sub> suitable for input to <u>Curve</u>. Shape builds a description of this scene suitable for <u>DT</u> and stores the <u>region</u> list under (Eval N), which must be an atom.

(Sin X) Returns sin of X radians.

A semi-global variable assumed by <u>iterate</u> to name an expression which is a predicate for a terminating condition.

(Topolog N) where N is the number of squares in a line. Topolog finds regions and generates names for them. It also notes relationships between them. To Regionlist, Topolog binds the list of regions. To each region, Topolog binds the properties: Nucleus, followed by a list of points found; Neighbors, followed by a list of neighboring regions; Outerbound, followed by a list of points; Innerbound, followed by a list of points forming inner bounds.

Uppt

Uppt (Fexpr) Region Subr

Х

X shift

Y

Y shift

A global variable point whose coordinates are used as upper bounds. (See <u>lowpt</u>).

(Uppt X Y). Sets <u>Uppt</u> to (X · Y).

Global variables used to generate  $\underline{\text{ellipses}}$  and  $\underline{\text{lines}}$ .