

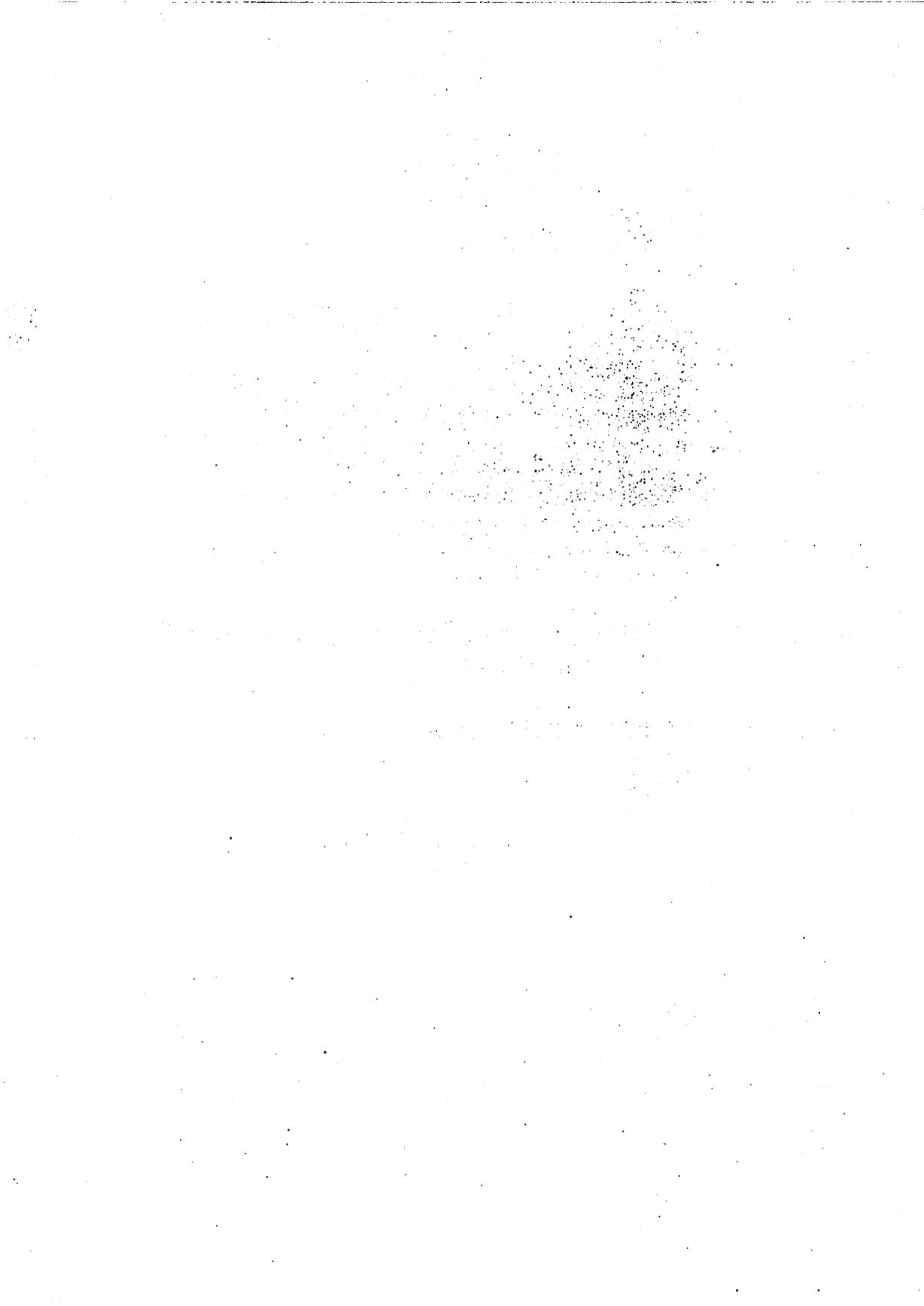
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CP/M[®] 2.2
Manual

MORROW DESIGNS 

Digital Research
CP/M® Manual
Vers. 2.2

- Section I:** **An Introduction to CP/M Features and
 Facilities**
- Section II:** **CP/M 2.2 Interface Guide**
- Section III:** **CP/M Context Editor (ED)**
- Section IV:** **CP/M Assembler (ASM)
 User's Guide**
- Section V:** **CP/M Dynamic Debugging Tool (DDT)
 User's Guide**
- Section VI:** **CP/M 2.2 Alteration Guide**
- 





**AN INTRODUCTION
TO CP/M FEATURES
AND FACILITIES**

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Introduction

CP/M is a monitor control program for microcomputer system development which uses IBM-compatible flexible disks for backup storage. Using a computer mainframe based upon Intel's 8080 microcomputer, CP/M provides a general environment for program construction, storage, and editing, along with assembly and program check-out facilities. An important feature of CP/M is that it can be easily altered to execute with any computer configuration which uses an Intel 8080 (or Zilog Z-80) Central Processing Unit, and has at least 16K bytes of main memory with up to four IBM-compatible diskette drives. Although the standard Digital Research version operates on a single-density Intel MDS 800, several different hardware manufacturers support their own input-output drivers for CP/M.

The CP/M monitor provides rapid access to programs through a comprehensive file management package. The file subsystem supports a named file structure, allowing dynamic allocation of file space as well as sequential and random file access. Using this file system, a large number of distinct programs can be stored in both source and machine executable form.

CP/M also supports a powerful context editor, Intel-compatible assembler, and debugger subsystem. Optional software includes a powerful Intel-compatible macro assembler, symbolic debugger, along with various high-level languages. When coupled with CP/M's Console Command Processor, the resulting facilities equal or excel similar large computer facilities.

CP/M is logically divided into several distinct parts:

BIOS	Basic I/O System (hardware dependent)
BDOS	Basic Disk Operating System
CCP	Console Command Processor
TPA	Transient Program Area

The BIOS provides the primitive operations necessary to access the diskette drives and to interface standard peripherals (teletype, CRT, Paper Tape Reader/Punch, and user-defined peripherals), and can be tailored by the user for any particular hardware environment by "patching" this portion of CP/M.

The BDOS provides disk management by controlling one or more disk drives containing independent file directories. The BDOS implements disk allocation strategies which provide fully dynamic file construction while

minimizing head movement across the disk during access. Any particular file may contain any number of records, not exceeding the size of any single disk. In a standard CP/M system, each disk can contain up to 64 distinct files. The BDOS has entry points which include the following primitive operations which can be programmatically accessed:

SEARCH	Look for a particular disk file by name.
OPEN	Open a file for further operations.
CLOSE	Close a file after processing.
RENAME	Change the name of a particular file.
READ	Read a record from a particular file.
WRITE	Write a record onto the disk.
SELECT	Select a particular disk drive for further operations.

The CCP provides symbolic interface between the user's console and the remainder of the CP/M system. The CCP reads the console device and processes commands which include listing the file directory, printing the contents of files, and controlling the operation of transient programs, such as assemblers, editors, and debuggers. The standard commands which are available in the CCP are listed in a following section.

The last segment of CP/M is the area called the Transient Program Area (TPA). **The TPA** holds programs which are loaded from the disk under command of the CCP. During program editing, for example, the TPA holds the CP/M text editor machine code and data areas. Similarly, programs created under CP/M can be checked out by loading and executing these programs in the TPA.

It should be mentioned that any or all of the CP/M component subsystems can be "overlaid" by an executing program. That is, once a user's program is loaded into the TPA, the CCP, BDOS, and BIOS areas can be used as the program's data area. A "bootstrap" loader is programmatically accessible whenever the BIOS portion is not overlaid; thus, the user program need only branch to the bootstrap loader at the end of execution, and the complete CP/M monitor is reloaded from disk.

It should be reiterated that the CP/M operating system is partitioned into distinct modules, including the BIOS portion which defines the hardware environment in which CP/M is executing. Thus, the standard system can be

easily modified to any non-standard environment by changing the peripheral drivers to handle the custom system.

An Overview of CP/M 2.0 Facilities

CP/M 2.0 is a high-performance single-console operating system which uses table driven techniques to allow field configuration to match a wide variety of disk capacities. All of the fundamental file restrictions are removed, while maintaining upward compatibility from previous versions of release 1. Features of CP/M 2.0 include field specification of one to sixteen logical drives, each containing up to eight megabytes. Any particular file can reach the full drive size with the capability to expand to thirty-two megabytes in future releases. The directory size can be field configured to contain any reasonable number of entries, and each file is optionally tagged with read/only and system attributes. Users of CP/M 2.0 are physically separated by user numbers, with facilities for file copy operations from one user area to another. Powerful relative-record random access functions are present in CP/M 2.0 which provide direct access to any of the 65536 records of an eight megabyte file.

All disk-dependent portions of CP/M 2.0 are placed into a BIOS-resident "disk parameter block" which is either hand coded or produced automatically using the disk definition macro library provided with CP/M 2.0. The end user need only specify the maximum number of active disks, the starting and ending sector numbers, the data allocation size, the maximum extent of the logical disk, directory size information, and reserved track values. The macros use this information to generate the appropriate tables and table references for use during CP/M 2.0 operation. Deblocking information is also provided which aids in assembly or disassembly of sector sizes which are multiples of the fundamental 128 byte data unit, and the system alteration manual includes general-purpose subroutines which use this deblocking information to take advantage of larger sector sizes. Use of these subroutines, together with the table driven data access algorithms, make CP/M 2.0 truly a universal data management system.

File expansion is achieved by providing up to 512 logical file extents, where each logical extent contains 16K bytes of data. CP/M 2.0 is structured, however, so that as much as 128K bytes of data is addressed by a single physical extent (corresponding to a single directory entry), thus maintaining compatibility with previous versions while taking full advantage of directory space.

Random access facilities are present in CP/M 2.0 which allow immediate reference to any record of an eight megabyte file. Using CP/M's unique data organization, data blocks are only allocated when actually required and movement to a record position requires little search time. Sequential file access is upwardly compatible from earlier versions to the full eight

megabytes, while random access compatibility stops at 512K byte files. Due to CP/M 2.0's simpler and faster random access, application programmers are encouraged to alter their programs to take full advantage of the 2.0 facilities.

Several CP/M 2.0 modules and utilities have improvements which correspond to the enhanced file system. STAT and PIP both account for file attributes and user areas, while the CCP provides a "login" function to change from one user area to another. The CCP also formats directory displays in a more convenient manner and accounts for both CRT and hard-copy devices in its enhanced line editing functions.

Functional Description of CP/M

The user interacts with CP/M primarily through the CCP, which reads and interprets commands entered through the console. In general, the CCP addresses one of several disks which are online (the standard system addresses up to four different disk drives). These disk drives are labelled A, B, C, and D. A disk is "logged in" if the CCP is currently addressing the disk. In order to clearly indicate which disk is the currently logged disk, the CCP always prompts the operator with the disk name followed by the symbol ">" indicating that the CCP is ready for another command. Upon initial start up, the CP/M system is brought in from disk A, and the CCP displays the message

xxK CP/M VER m.m

where xx is the memory size (in kilobytes) which this CP/M system manages, and m.m is the CP/M version number. All CP/M systems are initially set to operate in a 16K memory space, but can be easily reconfigured to fit any memory size on the host system. Following system signon, CP/M automatically logs in disk A, prompts the user with the symbol "A>" (indicating that CP/M is currently addressing disk "A"), and waits for a command. The commands are implemented at two levels: built-in commands and transient commands.

General Command Structure

Built-in commands are a part of the CCP program itself, while transient commands are loaded into the TPA from disk and executed. The built-in commands are

ERA	Erase specified files.
DIR	Displays file names in the directory.

REN	Rename the specified file.
SAVE	Save memory contents in a file.
TYPE	Type the contents of a file on the logged disk.
USER	Move to another area within the same directory.

Nearly all of the commands reference a particular file or group of files. The form of a file reference is specified below.

File References

A file reference identifies a particular file or group of files on a particular disk attached to CP/M. These file references can be either “unambiguous” (ufn) or “ambiguous” (afn). An unambiguous file reference uniquely identifies a single file, while an ambiguous file reference may be satisfied by a number of different files.

File references consist of two parts: the primary name and the secondary name. Although the secondary name is optional, it usually is generic; that is, the secondary name “ASM,” for example, is used to denote that the file is an assembly language source file, while the primary name distinguishes each particular source file. The two names are separated by a “.” as shown below:

pppppppp.sss

where pppppppp represents the primary name of eight characters or less, and sss is the secondary name of no more than three characters. As mentioned above, the name

pppppppp

is also allowed and is equivalent to a secondary name consisting of three blanks. The characters used in specifying an unambiguous file reference cannot contain any of the special characters

< > . , ; : = ? * []

while all alphanumerics and remaining special characters are allowed.

An ambiguous file reference is used for directory search and pattern matching. The form of an ambiguous file reference is similar to an unambiguous reference, except the symbol “?” may be interspersed throughout the primary and secondary names. In various commands throughout CP/M, the “?” symbol matches any character of a file name in the “?” position. Thus, the ambiguous reference

X?Z.C?M

is satisfied by the unambiguous file names

XYZ.COM

and

X3Z.CAM

Note that the ambiguous reference

.

is equivalent to the ambiguous file reference

?????????.???

while

pppppppp.*

and

*.sss

are abbreviations for

pppppppp.???

and

?????????.sss

respectively. As an example,

DIR *.*

is interpreted by the CCP as a command to list the names of all disk files in the directory, while

DIR X.Y

searches only for a file by the name X.Y. Similarly, the command

DIR X?Y.C?M

causes a search for all (unambiguous) file names on the disk which satisfy this ambiguous reference.

The following file names are valid unambiguous file references:

X	XYZ	GAMMA
X.Y	XYZ.COM	GAMMA.1

As an added convenience, the programmer can generally specify the disk drive name along with the file name. In this case, the drive name is given as a letter A through Z followed by a colon (:). The specified drive is then "logged in" before the file operation occurs. Thus, the following are valid file names with disk name prefixes:

A:X.Y	B:XYZ	C:GAMMA
Z:XYZ.COM	B:X.A?M	C:*.ASM

It should also be noted that all alphabetic lower case letters in file and drive names are always translated to upper case when they are processed by the CCP.

Switching Disks

The operator can switch the currently logged disk by typing the disk drive name (A, B, C, or D) followed by a colon (:) when the CCP is waiting for console input. Thus, the sequence of prompts and commands shown below might occur after the CP/M system is loaded from disk A:

16K CP/M VER 2.0

A>DIR

List all files on disk A.

SAMPLE ASM

SAMPLE PRN

A>B:

Switch to disk B.

B>Dir *.ASM

List all "ASM" files on B.

DUMP ASM

FILES ASM

B>A:

Switch back to A.

Form of Built-In Commands

The file and device reference forms described above can now be used to fully specify the structure of the built-in commands. In the description below, assume the following abbreviations:

ufn	unambiguous file reference
afn	ambiguous file reference
cr	carriage return

Further, recall that the CCP always translates lower case characters to

upper case characters internally. Thus, lower case alphabetic characters are treated as if they are upper case in command names and file references.

ERASE Command

ERA afn

The ERA (erase) command removes files from the currently logged-in disk (i.e., the disk name currently prompted by CP/M preceding the ">"). The files which are erased are those which satisfy the ambiguous file reference afn. The following examples illustrate the use of ERA:

ERA X.Y The file named X.Y on the currently logged disk is removed from the disk directory, and the space is returned.

ERA X.* All files with primary name X are removed from the current disk.

ERA *.ASM All files with secondary name ASM are removed from the current disk.

ERA X?Y.C?M All files on the current disk which satisfy the ambiguous reference X?Y.C?M are deleted.

ERA *.* Erase all files in the current user's directory. (See USER n, page 13.) The CCP prompts with the message
 ALL (Y/N)?
which requires a Y response before files are actually removed.

ERA B:*.PRN All files on drive B which satisfy the ambiguous reference ???????.PRN are deleted, independently of the currently logged disk.

DIRectory Command

DIR afn

The DIR (directory) command causes the names of all files which satisfy the ambiguous file name afn to be listed at the console device. As a special case, the command

DIR

lists the files on the currently logged disk (the command "DIR" is equivalent to the command "DIR *.*"). Valid DIR commands are shown below.

DIR X.Y

DIR X?Z.C?M

DIR ??Y

Similar to other CCP commands, the afn can be preceded by a drive name. The following DIR commands cause the selected drive to be addressed before the directory search takes place.

DIR B:

DIR B:X.Y

DIR B:*.A?M

If no files can be found on the selected diskette which satisfy the directory request, then the message "NOT FOUND" is typed at the console.

REName Command

REN ufn1 = ufn2

The REN (rename) command allows the user to change the names of files on disk. The file satisfying ufn2 is changed to ufn1. The currently logged disk is assumed to contain the file to rename (ufn1). The CCP also allows the user to type a left-directed arrow instead of the equal sign, if the user's console supports this graphic character. Examples of the REN command are

REN X.Y = Q.R The file Q.R is changed to X.Y.

REN XYZ.COM = XYZ.XXX The file XYZ.XXX is changed to XYZ.COM.

The operator can precede either ufn1 or ufn2 (or both) by an optional drive address. Given that ufn1 is preceded by a drive name, then ufn2 is assumed to exist on the same drive as ufn1. Similarly, if ufn2 is preceded by a drive name, then ufn1 is assumed to reside on that drive as well. If both ufn1 and ufn2 are preceded by drive names, then the same drive must be specified in both cases. The following REN commands illustrate this format.

REN A:X.ASM = Y.ASM The file Y.ASM is changed to X.ASM on drive A.

REN B:ZAP.BAS = ZOT.BAS The file ZOT.BAS is changed to ZAP.BAS on drive B.

REN B:A.ASM = B:A.BAK

The file A.BAK is renamed to A.ASM on drive B.

If the file ufn1 is already present, the REN command will respond with the error "FILE EXISTS" and not perform the change. If ufn2 does not exist on the specified diskette, then the message "NOT FOUND" is printed at the console.

SAVE Command

SAVE n ufn

The SAVE command places n pages (256-byte blocks) onto disk from the TPA and names this file ufn. In the CP/M distribution system, the TPA starts at 100H (hexadecimal), which is the second page of memory. Thus, if the user's program occupies the area from 100H through 2FFH, the SAVE command must specify two pages of memory. The machine code file can be subsequently loaded and executed. Examples are:

SAVE 3 X.COM

Copies 100H through 3FFH to X.COM.

SAVE 40 Q

Copies 100H through 28FFH to Q (note that 28 is the page count in 28FFH, and that $28H = 2 * 16 + 8 = 40$ decimal).

SAVE 4 X.Y

Copies 100H through 4FFH to X.Y.

The SAVE command can also specify a disk drive in the afn portion of the command, as shown below.

SAVE 10 B:ZOT.COM

Copies 10 pages (100H through 0AFFH) to the file ZOT.COM on drive B.

The SAVE operation can be used any number of times without altering the memory image.

TYPE Command

TYPE ufn

The TYPE command displays the contents of the ASCII source file ufn on the currently logged disk at the console device. Valid TYPE commands are

TYPE X.Y

TYPE X.PLM

TYPE XXX

The **TYPE** command expands tabs (clt-I characters), assuming tab positions are set at every eighth column. The ufn can also reference a drive name as shown below.

TYPE B:X.PRN The file X.PRN from drive B is displayed.

USER Command

USER n

Where n is an integer value in the range 0 to 15.

Upon cold start, the operator is automatically “logged” into user area number 0. The operator may issue the **USER** command at any time to move to another logical area within the same directory.

Drives which are logged in while addressing one user number are automatically active when the operator moves to another user number since a user number is simply a prefix which accesses particular directory entries on the active disks.

The active user number is maintained until changed by a subsequent **USER** command, or until a cold start operation when user 0 is again assumed.

Line Editing and Output Control

The CCP allows certain line editing functions while typing command lines. “Control” indicates that the Control key and the indicated key are to be pressed simultaneously. CCP commands can generally be up to 255 characters in length; they are not acted upon until the carriage return key is pressed.

rubout/delete	Remove and echo last character typed
Control C	Reboot CP/M when at beginning of line
Control E	Physical end of line: carriage is returned, but line is not sent until the carriage return key is depressed.

Control H	Backspace one character position. Produces the backspace overwrite function. Can be changed internally to another character, such as delete, through a simple single byte change.
Control J	Line feed. Terminates current input.
Control M	Carriage return. Terminates input.
Control R	Retype current command line after new line.
Control X	Backspace to beginning of current line.

The line editor keeps track of the current prompt column position so that the operator can properly align data input following a Control R or Control X command.

The control functions Control P and Control S affect console output as shown below.

Control P	Copy all subsequent console output to the currently assigned list device (see the STAT command). Output is sent to both the list device and the console device until the next Control P is typed.
Control S	Stop the console output temporarily. Program execution and output continue when the next character is typed at the console (e.g., another Control S). This feature is used to stop output on high speed consoles, such as CRT's, in order to view a segment of output before continuing.

Transient Commands

Transient commands are loaded from the currently logged disk and executed in the TPA. The transient commands defined for execution under the CCP are shown below. Additional functions can easily be defined by the user (see the LOAD command definition).

STAT	List the number of bytes of storage remaining on the currently logged disk, provide statistical information about particular files, and display or alter device assignment.
ASM	Load the CP/M assembler and assemble the specified program from disk.

LOAD	Load the file in Intel "hex" machine code format and produce a file in machine executable form which can be loaded into the TPA (this loaded program becomes a new command under the CCP).
DDT	Load the CP/M debugger into TPA and start execution.
PIP	Load the Peripheral Interchange Program for subsequent disk file and peripheral transfer operations.
ED	Load and execute the CP/M text editor program.
SUBMIT	Submit a file of commands for batch processing.
XSUB	Allow submitted commands to receive input from the submit file.
DUMP	Dump the contents of a file in hex.

Transient commands are specified in the same manner as built-in commands, and additional commands can be easily defined by the user. As an added convenience, the transient command can be preceded by a drive name, which causes the transient to be loaded from the specified drive into the TPA for execution. Thus, the command

B:STAT

causes CP/M to temporarily "log in" drive B for the source of the STAT transient, and then return to the original logged disk for subsequent processing.

The basic transient commands are listed in detail below.

STAT

The STAT command provides general statistical information about file storage and device assignment. It is initiated by typing one of the following forms:

STAT
STAT "command line"

Special forms of the "command line" allow the current device assignment to be examined and altered as well. The various command lines which can be specified are shown below, with an explanation of each form shown to the right.

STAT <cr>

If the user types an empty command line, the STAT transient calculates the storage remaining on all active drives, and prints a message

x: R/W, SPACE: nnnK

or

x: R/O, SPACE: nnnK

for each active drive x, where R/W indicates the drive may be read or written, and R/O indicates the drive is read only (a drive becomes R/O by explicitly setting it to read only, as shown below, or by inadvertently changing diskettes without performing a warm start). The space remaining on the diskette in drive x is given in kilobytes by nnn.

STAT x: <cr>

If a drive name is given, then the drive is selected before the storage is computed. Thus, the command "STAT B:" could be issued while logged into drive A, resulting in the message

BYTES REMAINING ON B: nnnK

STAT afn <cr>

The command line can also specify a set of files to be scanned by STAT. The files which satisfy afn are listed in alphabetical order, with storage requirements for each file under the heading

RECS	BYTS	EX	D:FILENAME.TYP
rrrr	bbbK	ee	d:pppppppp.sss

where rrrr is the number of 128-byte records allocated to the file, bbb is the number of kilobytes allocated to the file ($bbb = rrrr * 128 / 1024$), ee is the number of 16K extensions ($ee = bbb / 16$), d is the drive name containing the file (A...Z), pppppppp is the (up to) eight-character primary file name, and sss is the (up to) three-character secondary name. After listing the individual files, the storage usage is summarized.

STAT x:afn <cr>

As a convenience, the drive name can be given ahead of the afn. In this case, the specified drive is first selected, and the form "STAT afn" is executed.

STAT d:filename.typ \$S <cr>

("d:" is optional drive name and "filename.typ" is an unambiguous or ambiguous file name)

Produces the output display format:

Size	Recs	Bytes	Ext	Acc
48	48	6K	1	R/O A:ED.COM
55	55	12K	1	R/O (A:PIP.COM)
65536	128	2K	2	R/W A:X.DAT

The \$S parameter causes the "Size" field to be displayed. (The command may be used without the \$S if desired.) The Size field lists the virtual file size in records, while the "Recs" field sums the number of virtual records in each extent. For files constructed sequentially, the Size and Recs fields are identical. The "Bytes" field lists the actual number of bytes allocated to the corresponding file. The minimum allocation unit is determined at configuration time, and thus the number of bytes corresponds to the record count plus the remaining unused space in the last allocated block for sequential files. Random access files are given data areas only when written, so the Bytes field contains the only accurate allocation figure. In the case of random access, the Size field gives the logical end-of-file record position and the Recs field counts the logical records of each extent (each of these extents, however, may contain unallocated "holes" even though they are added into the record count). The "Ext" field counts the number of local 16K extents allocated to the file. The "Acc" field gives the R/O or R/W access mode, which is changed using the commands shown below. The parentheses shown around the PIP.COM file name indicate that it has the "system" indicator set, so that it will not be listed in DIR commands.

STAT d:filename.typ \$R/O <cr>

Places the file or set of files in a read-only status until changed by a subsequent STAT command. The R/O status is recorded in the directory with the file so that it remains R/O through intervening cold start operations. When a file is marked R/O, attempts to erase or write into the file result in a terminal BDOS message: Bdos Err on D: File R/O.

STAT d:filename.typ \$R/W <cr>

Places the file in a permanent read/write status.

STAT d:filename.typ \$SYS <cr>

Attaches the system indicator to the file.

STAT d:filename.typ \$DIR <cr>

Removes the system indicator from the file.

STAT d:DSK: <cr>

Lists the drive characteristics of the disk named by "d:" which is in the range A:, B:, ..., P:. The drive characteristics are listed in the format:

```
      d:  Drive Characteristics
65536:  128 Byte Record Capacity
      8192: Kilobyte Drive Capacity
      128: 32 Byte Directory Entries
       0: Checked Directory Entries
     1024: Records/Extent
      128: Records/Block
       58: Sectors/Track
        2: Reserved Tracks
```

The total record capacity is listed, followed by the total drive capacity listed in Kbytes. The number of checked entries is usually identical to the directory size for removable media, since this mechanism is used to detect changed media during CP/M operation without an intervening warm start. The number of records per extent determines the addressing capacity of each directory entry (1024 times 128 bytes, or 128K in the example above). The number of records per block shows the basic allocation size (in the example, 128 records/block times 128 bytes per record, or 16K bytes per block). The listing is then followed by the number of physical sectors per track and the number of reserved tracks.

STAT DSK: <cr>

Lists drive characteristics as above for all currently active drives.

STAT USR: <cr>

Produces a list of the user numbers which have files on the currently addressed disk. The display format is:

```
Active User : 0
```

```
Active Files: 0 1 3
```

where the first line lists the currently addressed user number, as set by the last CCP USER command, followed by a list of user numbers scanned from the current directory. In the above case, the active user number is 0 (default at cold start), with three user numbers which have

active files on the current disk. The operator can subsequently examine the directories of the other user numbers by logging in with USER 1, USER 2, or USER 3 commands, followed by a DIR command at the CCP level.

The STAT command also allows control over the physical to logical device assignment (see the IOBYTE function described in the "CP/M Interface Guide." In general, there are four logical peripheral devices which are, at any particular instant, each assigned to one of several physical peripheral devices. The four logical devices are named:

CON:	The system console device (used by CCP for communication with the operator)
RDR:	The paper tape reader device
PUN:	The paper tape punch device
LST:	The output list device

The actual devices attached to any particular computer system are driven by subroutines in the BIOS portion of CP/M. Thus, the logical RDR: device, for example, could actually be a high speed reader, Teletype reader, or cassette tape. In order to allow some flexibility in device naming and assignment, several physical devices are defined, as shown below:

TTY:	Teletype device (slow speed console)
CRT:	Cathode ray tube device (high speed console)
BAT:	Batch processing (console is current RDR:, output goes to current LST: device)
UC1:	User-defined console
PTR:	Paper tape reader (high speed reader)
UR1:	User-defined reader #1
UR2:	User-defined reader #2
PTP:	Paper tape punch (high speed punch)
UP1:	User-defined punch #1

UP2: User-defined punch #2
LPT: Line printer
UL1: User-defined list device #1

It must be emphasized that the physical device names may or may not actually correspond to devices which the names imply. That is, the PTP: device may be implemented as a cassette write operation, if the user wishes. The exact correspondence and driving subroutine is defined in the BIOS portion of CP/M. In the standard distribution version of CP/M, these devices correspond to their names on the MDS 800 development system.

The command:

STAT VAL: <cr>

produces a summary of the available status commands, resulting in the output:

Temp R/O Disk: d: = R/O

Set Indicator: d:filename.typ \$R/O \$R/W \$SYS \$DIR

Disk Status: DSK: d:DSK:

User Status: USR:

Iobyte Assign:

CON. = TTY:	CRT:	BAT:	UC1:
RDR: = TTY:	PTR:	UR1:	UR2:
PUN: = TTY:	PTP:	UP1:	UP2:
LST: = TTY:	CRT:	LPT:	UL1:

In each case, the logical device shown to the left can take any of the four physical assignments shown to the right on each line. The current logical to physical mapping is displayed by typing the command

STAT DEV: <cr>

which produces a listing of each logical device to the left, and the current corresponding physical device to the right. For example, the list might appear as follows:

CON: = CRT:
RDR: = UR1:
PUN: = PTP:
LST: = TTY:

The current logical to physical device assignment can be changed by typing a STAT command of the form

STAT ld1 = pd1, ld2 = pd2 , ... , ldn = pdn <cr>

where ld1 through ldn are logical device names, and pd1 through pdn are compatible physical device names (i.e., ldi and pdi appear on the same line in the "VAL:" command shown above). The following are valid STAT commands which change the current logical to physical device assignments:

STAT CON: = CRT: <cr>
STAT PUN: = TTY:,LST: = LPT:., RDR: = TTY: <cr>

ASM ufn

The ASM command loads and executes the CP/M 8080 assembler. The ufn specifies a source file containing assembly language statements where the secondary name is assumed to be ASM, and thus is not specified. The following ASM commands are valid:

ASM X

ASM GAMMA

The two-pass assembler is automatically executed. If assembly errors occur during the second pass, the errors are printed at the console.

The assembler produces a file

x.PRN

where x is the primary name specified in the ASM command. The PRN file contains a listing of the source program (with imbedded tab characters if present in the source program), along with the machine code generated for each statement and diagnostic error messages, if any. The PRN file can be listed at the console using the TYPE command, or sent to a peripheral device using PIP (see the PIP command structure below). Note also that the PRN file contains the original source program, augmented by miscellaneous assembly information in the leftmost 16 columns (program addresses and hexadecimal machine code, for example). Thus, the PRN file can serve as a

backup for the original source file: if the source file is accidentally removed or destroyed, the PRN file can be edited (see the ED operator's guide) by removing the leftmost 16 characters of each line (this can be done by issuing a single editor "macro" command). The resulting file is identical to the original source file and can be renamed (REN) from PRN to ASM for subsequent editing and assembly. The file

x.HEX

is also produced which contains 8080 machine language in Intel "hex" format suitable for subsequent loading and execution (see the LOAD command). For complete details of CP/M's assembly language program, see the "CP/M Assembler Language (ASM) User's Guide."

Similar to other transient commands, the source file for assembly can be taken from an alternate disk by prefixing the assembly language file name by a disk drive name. Thus, the command

ASM B:ALPHA <cr>

loads the assembler from the currently logged drive and operates upon the source program ALPHA.ASM on drive B. The HEX and PRN files are also placed on drive B in this case.

LOAD ufn cr

The LOAD command reads the file ufn, which is assumed to contain "hex" format machine code, and produces a memory image file which can be subsequently executed. The file name ufn is assumed to be of the form

x.HEX

and thus only the name x need be specified in the command. The LOAD command creates a file named

x.COM

which marks it as containing machine executable code. The file is actually loaded into memory and executed when the user types the file name x immediately after the prompting character ">" printed by the CCP.

In general, the CCP reads the name x following the prompting character and looks for a built-in function name. If no function name is found, the CCP searches the system disk directory for a file by the name

x.COM

If found, the machine code is loaded into the TPA, and the program executes. Thus, the user need only LOAD a hex file once; it can be subsequently executed any number of times by simply typing the primary name. In this way, the user can "invent" new commands in the CCP. (Initialized disks contain the transient commands as COM files, which can be deleted at the user's option.) The operation can take place on an alternate drive if the file name is prefixed by a drive name. Thus

LOAD B:BETA

brings the LOAD program into the TPA from the currently logged disk and operates upon drive B after execution begins.

It must be noted that the BETA.HEX file must contain valid Intel format hexadecimal machine code records (as produced by the ASM program, for example) which begin at 100H, the beginning of the TPA. Further, the addresses in the hex records must be in ascending order; gaps in unfilled memory regions are filled with zeroes by the LOAD command as the hex records are read. Thus, LOAD must be used only for creating CP/M standard "COM" files which operate in the TPA. Programs which occupy regions of memory other than the TPA can be loaded under DDT.

PIP

PIP is the CP/M Peripheral Interchange Program which implements the basic media conversion operations necessary to load, print, punch, copy, and combine disk files. The PIP program is initiated by typing one of the following forms

PIP <cr>
PIP "command line" <cr>

In both cases, PIP is loaded into the TPA and executed. In case 1, PIP reads command lines directly from the console, prompted with the "*" character, until an empty command line is typed (i.e., a single carriage return is issued by the operator). Each successive command line causes some media conversion to take place according to the rules shown below. Form 2 of the PIP command is equivalent to the first, except that the single command line given with the PIP command is automatically executed, and PIP terminates immediately with no further prompting of the console for input command lines. The form of each command line is

destination = source #1, source #2, ... , source #n <cr>

where "destination" is the file or peripheral device to receive the data, and "source #1, ..., source #n" represents a series of one or more files or devices which are copied from left to right to the destination.

When multiple files are given in the command line (i.e., $n > 1$), the individual files are assumed to contain ASCII characters, with an assumed CP/M end-of-file character (ctl-Z) at the end of each file (see the O parameter to override this assumption). The equal symbol (=) can be replaced by a left-oriented arrow, if your console supports this ASCII character, to improve readability. Lower case ASCII alphabets are internally translated to upper case to be consistent with CP/M file and device name conventions. Finally, the total command line length cannot exceed 255 characters (ctl-E can be used to force a physical carriage return for lines which exceed the console width).

The destination and source elements can be unambiguous references to CP/M source files, with or without a preceding disk drive name. That is, any file can be referenced with a preceding drive name (A:, B:, C:, or D:) which defines the particular drive where the file may be obtained or stored. When the drive name is not included, the currently logged disk is assumed. Further, the destination file can also appear as one or more of the source files, in which case the source file is not altered until the entire concatenation is complete. If the destination file already exists, it is removed if the command line is properly formed (it is not removed if an error condition arises). The following command lines (with explanations to the right) are valid as input to PIP:

X = Y <cr> Copy to file X from file Y, where X and Y are unambiguous file names; Y remains unchanged.

X = Y, Z <cr> Concatenate files Y and Z and copy to file X, with Y and Z unchanged.

X.ASM = Y.ASM,Z.ASM,FIN.ASM <cr> Create the file X.ASM from the concatenation of the Y, Z, and FIN files with type ASM.

NEW.ZOT = B:OLD.ZAP <cr> Move a copy of OLD.ZAP from drive B to the currently logged disk; name the file NEW.ZOT.

B:A.U. = B:B.V.A:C.W,D.X <cr> Concatenate file B.V from drive B with C.W from drive A and D.X. from the logged disk; create the file A.U on drive B.

For more convenient use, PIP allows abbreviated commands for transferring files between disk drives. The abbreviated forms are

PIP x: = afn <cr>

PIP x: = y:afn <cr>

PIP ufn = y: <cr>

PIP x:ufn = y: <cr>

The first form copies all files from the currently logged disk which satisfy the afn to the same file names on drive x (x = A...Z). The second form is equivalent to the first, where the source for the copy is drive y (y = A...Z). The third form is equivalent to the command "PIP ufn = y:ufn <cr>" which copies the file given by ufn from drive y to the file ufn on drive x. The fourth form is equivalent to the third, where the source disk is explicitly given by y.

Note that the source and destination disks must be different in all of these cases. If an afn is specified, PIP lists each ufn which satisfies the afn as it is being copied. If a file exists by the same name as the destination file, it is removed upon successful completion of the copy, and replaced by the copied file.

The following PIP commands give examples of valid disk-to-disk copy operations:

B: = *.COM <cr> Copy all files which have the secondary name "COM" to drive B from the current drive.

A: = B:ZAP.* <cr> Copy all files which have the primary name "ZAP" to drive A from drive B.

ZAP.ASM = B: <cr> Equivalent to ZAP.ASM = B:ZAP.ASM

B:ZOT.COM = A: <cr> Equivalent to B:ZOT.COM = A:ZOT.COM

B: = GAMMA.BAS <cr> Same as B:GAMMA.BAS = GAMMA.BAS

B: = A:GAMMA.BAS <cr> Same as
B:GAMMA.BAS = A:GAMMA.BAS

PIP also allows reference to physical and logical devices which are attached to the CP/M system. The device names are the same as given under the STAT command, along with a number of specially named devices. The logical

devices given in the STAT command are

CON: (console), RDR: (reader), PUN: (punch), and LST: (list)

while the physical devices are

TTY: (console, reader, punch, or list)
CRT: (console, or list), UC1: (console)
PTR: (reader), UR1: (reader), UR2: (reader)
PTP: (punch), UP1: (punch), UP2: (punch)
LPT: (list), UL1: (list)

(Note that the "BAT:" physical device is not included, since this assignment is used only to indicate that the RDR: and LST: devices are to be used for console input/output.)

The RDR, LST, PUN, and CON devices are all defined within the BIOS portion of CP/M, and thus are easily altered for any particular I/O system. (The current physical device mapping is defined by IOBYTE; see the "CP/M Interface Guide" for a discussion of this function). The destination device must be capable of receiving data (i.e., data cannot be sent to the punch), and the source devices must be capable of generating data (i.e., the LST: device cannot be read).

The additional device names which can be used in PIP commands are

NUL: Send 40 "nulls" (ASCII 0's) to the device (this can be issued at the end of punched output).

EOF: Send a CP/M end-of-file (ASCII ctl-Z) to the destination device (sent automatically at the end of all ASCII data transfers through PIP).

INP: Special PIP input source which can be "patched" into the PIP program itself: PIP gets the input data character-by-character by CALLing location 103H, with data returned in location 109H (parity bit must be zero).

OUT: Special PIP output destination which can be patched into the PIP program: PIP CALLs location 106H with data in register C for each character to transmit. Note that locations 109H through 1FFH of the PIP memory image are not used and can be replaced by special purpose drivers using DDT (see the DDT operator's manual).

PRN: Same as LST:, except that tabs are expanded at every eighth

character position, lines are numbered, and page ejects are inserted every 60 lines, with an initial eject (same as [t8np]).

File and device names can be interspersed in the PIP commands. In each case, the specific device is read until end-of-file (ctl-Z for ASCII files, and a real end of file for non-ASCII disk files). Data from each device or file is concatenated from left to right until the last data source has been read. The destination device or file is written using the data from the source files, and an end-of-file character (ctl-Z) is appended to the result for ASCII files. Note that if the destination is a disk file, a temporary file is created (\$\$\$secondary name) which is changed to the actual file name only upon successful completion of the copy. Files with the extension "COM" are always assumed to be non-ASCII.

The copy operation can be aborted at any time by depressing any key on the keyboard (a rubout suffices). PIP will respond with the message "ABORTED" to indicate that the operation was not completed. Note that if any operation is aborted, or if an error occurs during processing, PIP removes any pending commands which were set up while using the SUBMIT command.

It should also be noted that PIP performs a special function if the destination is a disk file with type "HEX" (an Intel hex formatted machine code file), and the source is an external peripheral device, such as a paper tape reader. In this case, the PIP program checks to ensure that the source file contains a properly formed hex file, with legal hexadecimal values and checksum records. When an invalid input record is found, PIP reports an error message at the console and waits for corrective action. It is usually sufficient to open the reader and rerun a section of the tape (pull the tape about 20 inches). When the tape is ready for the re-read, type a single carriage return at the console, and PIP will attempt another read. If the tape position cannot be properly read, simply continue the read (by typing a return following the error message), and enter the record manually with the ED program after the disk file is constructed. For convenience, PIP allows the end-of-file to be entered from the console if the source file is a RDR: device. In this case, the PIP program reads the device and monitors the keyboard. If ctl-Z is typed at the keyboard, then the read operation is terminated normally.

Valid PIP commands are shown below.

PIP LST: = X.PRN <cr> Copy X.PRN to the LST device and terminate the PIP program.

PIP <cr> Start PIP for a sequence of commands (PIP prompts with "***").

***CON: = X.ASM,Y.ASM,Z.ASM <cr>**

Concatenate three ASM files and copy to the CON device.

***X.HEX = CON:,Y.HEX,PTR: <cr>**

Create a HEX file by reading the CON (until a ctl-Z is typed), followed by data from Y.HEX, followed by data from PTR until a ctl-Z is encountered.

***<cr>**

Single carriage return stops PIP.

PIP PUN: = NUL:,X.ASM,EOF:,NUL: <cr>

Send 40 nulls to the punch device; then copy the X.ASM file to the punch, followed by an end-of-file (ctl-Z) and 40 more null characters.

The user can also specify one or more PIP parameters, enclosed in left and right square brackets, separated by zero or more blanks. Each parameter affects the copy operation, and the enclosed list of parameters must immediately follow the affected file or device. Generally, each parameter can be followed by an optional decimal integer value (the S and Q parameters are exceptions). The valid PIP parameters are listed below.

- B** Block mode transfer: data is buffered by PIP until an ASCII x-off character (ctl-S) is received from the source device. This allows transfer of data to a disk file from a continuous reading device, such as a cassette reader. Upon receipt of the x-off, PIP clears the disk buffers and returns for more input data. The amount of data which can be buffered is dependent upon the memory size of the host system (PIP will issue an error message if the buffers overflow).
- Dn** Delete characters which extend past column n in the transfer of data to the destination from the character source. This parameter is used most often to truncate long lines which are sent to a (narrow) printer or console device.
- E** Echo all transfer operations to the console as they are being performed.
- F** Filter form feeds from the file. All imbedded form feeds are removed. The P parameter can be used simultaneously to insert new form feeds.
- Gn** Get file from user number n. (n is the range 0-15.) Allows one user area to receive data files from another. If the operator has issued the

USER 4 command at the CCP level, the PIP statement

PIP X.Y = X.Y[G2]

reads file X.Y from user number 2 into user area number 4. You cannot copy files into a different area than the one which is currently addressed by the USER command.

- H Hex data transfer: all data is checked for proper Intel hex file format. Non-essential characters between hex records are removed during the copy operation. The console will be prompted for corrective action in case errors occur.
- I Ignore “:00” records in the transfer of Intel hex format file (the I parameter automatically sets the H parameter).
- L Translate upper case alphabets to lower case.
- N Add line numbers to each line transferred to the destination, starting at one, and incrementing by 1. Leading zeroes are suppressed, and the number is followed by a colon. If N2 is specified, then leading zeroes are included, and a tab is inserted following the number. The tab is expanded if T is set.
- O Object file (non-ASCII) transfer: the normal CP/M end of file is ignored.
- Pn Include page ejects at every n lines (with an initial page eject). If n = 1 or is excluded altogether, page ejects occur every 60 lines. If the F parameter is used, form feed suppression takes place before the new page ejects are inserted.
- Qs↑z Quit copying from the source device or file when the string s (terminated by ctl-Z) is encountered.
- R Read system files. Allows files with the system attribute to be included in PIP transfers. Otherwise, system files are not recognized.
- Ss↑z Start copying from the source device when the string s is encountered (terminated by ctl-Z). The S and Q parameters can be used to “abstract” a particular section of a file (such as a subroutine). The start and quit strings are always included in the copy operation.

NOTE – the strings following the s and q parameters are translated to upper case by the CCP if form (2) of the PIP command is used. Form (1) of the PIP invocation, however, does not perform the

automatic upper case translation.

- (1) PIP <cr>
- (2) PIP "command line" <cr>

- Tn** Expand tabs (ctl-I characters) to every nth column during the transfer of characters to the destination from the source.
- U** Translate lower case alphabets to upper case during the copy operation.
- V** Verify that data has been copied correctly by rereading after the write operation (the destination must be a disk file).
- W** Write over R/O files without console interrogation. Under normal operation, PIP will not automatically overwrite a file which is set to a permanent R/O status. It advises the user of the R/O status and waits for overwrite approval. W allows the user to bypass this interrogation process.
- Z** Zero the parity bit on input for each ASCII character.

The following are valid PIP commands which specify parameters in the file transfer:

PIP X.ASM = B:[v] <cr> Copy X.ASM from drive B to the current drive and verify that the data was properly copied.

PIP LPT: = X.ASM[nt8u] <cr>
Copy X.ASM to the LPT: device; number each line, expand tabs to every eighth column, and translate lower case alphabets to upper case.

PIP PUN: = X.HEX[i],Y.ZOT[h] <cr>
First copy X.HEX to the PUN: device and ignore the trailing ":00" record in X.HEX; then continue the transfer of data by reading Y.ZOT, which contains hex records, including any ":00" records which it contains.

PIP X.LIB = Y.ASM [sSUBR1:↑z qJMP L3↑z] <cr>
Copy from the file Y.ASM into the file X.LIB. Start the copy when the string "SUBR1:" has been found, and quit copying after the string "JMP L3" is encountered.

PIP PRN: = X.ASM[p50] Send X.ASM to the LST: device, with line numbers, tabs expanded to every eighth column, and page ejects at every 50th line. Note that nt8p60 is the assumed parameter list for a PRN file; p50 overrides the default value.

Note that the PIP program itself is initially copied to a user area (so that subsequent files can be copied) using the SAVE command. The sequence of operations shown below effectively moves PIP from one user area to the next.

USER 0	login user 0
DDT PIP.COM (note PIP size s)	load PIP in memory
G0	return to CCP
USER 3	login user 3
SAVE s PIP.com	

where *s* is the integral number of memory “pages” (256 byte segments) occupied by PIP. The numbers *s* can be determined when PIP.COM is located under DDT, by referring to the value under the “NEXT” display. If for example, the next available address is 1D00, then PIP.COM requires 1C hexadecimal pages (or 1 times 16 + 12 = 28 pages), and thus the value of *s* is 28 in the subsequent save. Once PIP is copied in this manner, it can then be copied to another disk belonging to the same user number through normal PIP transfers.

ED

The ED program is the CP/M system context editor, which allows creation and alteration of ASCII files in the CP/M environment. Complete details of operation are given in Chapter 3 CP/M ED. In general, ED allows the operator to create and operate upon source files which are organized as a sequence of ASCII characters, separated by end-of-line characters (a carriage-return line-feed sequence). There is no practical restriction on line length (no single line can exceed the size of the working memory), which is instead defined by the number of characters typed between <cr>'s. The ED program has a number of commands for character string searching, replacement, and insertion, which are useful in the creation and correction of programs or text files under CP/M. Although the CP/M has a limited memory work space area (approximately 5000 characters in a 16K CP/M system), the file size which can be edited is not limited, since data is easily “paged” through this work area.

Upon initiation, ED creates the specified source file, if it does not exist, and opens the file for access. The programmer then “appends” data from the

source file into the work area, if the source file already exists (see the A command), for editing. The appended data can then be displayed, altered, and written from the work area back to the disk (see the W command). Particular points in the program can be automatically paged and located by context (see the N command), allowing easy access to particular portions of a large file.

Given that the operator has typed

```
ED X.ASM <cr>
```

the ED program creates an intermediate work file with the name

```
X.$$$
```

to hold the edited data during the ED run. Upon completion of ED, the X.ASM file (original file) is renamed to X.BAK, and the edited work file is renamed to X.ASM. Thus, the X.BAK file contains the original (unedited) file, and the X.ASM file contains the newly edited file. The operator can always return to the previous version of a file by removing the most recent version, and renaming the previous version. Suppose, for example, that the current X.ASM file was improperly edited; the sequence of CCP commands shown below would reclaim the backup file.

DIR X.* Check to see that BAK file is available.

ERA X.ASM Erase most recent version.

REN X.ASM=X.BAK Rename the BAK file to ASM.

Note that the operator can abort the edit at any point (reboot, power failure, ctl-C, or Q command) without destroying the original file. In this case, the BAK file is not created, and the original file is always intact.

The ED program also allows the user to “ping-pong” the source and create backup files between two disks. The form of the ED command in this case is

```
ED ufn d:
```

where ufn is the name of a file to edit on the currently logged disk and d is the name of an alternate drive. The ED program reads and processes the source file, and writes the new file to drive d, using the name ufn. Upon completion of processing, the original file becomes the backup file. Thus, if the operator is addressing disk A, the following command is valid:

ED X.ASM B:

which edits the file X.ASM on drive A, creating the new file X.\$\$\$ on drive B. Upon completion of a successful edit, A:X.ASM is renamed to A:X.BAK, and B:X.\$\$\$ is renamed to B:X.ASM. For user convenience, the currently logged disk becomes drive B at the end of the edit. Note that if a file by the name B:X.ASM exists before the editing begins, the message

FILE EXISTS

is printed at the console as a precaution against accidentally destroying a source file. In this case, the operator must first ERASE the existing file and then restart the edit operation.

Similar to other transient commands, editing can take place on a drive different from the currently logged disk by preceding the source file name by a drive name. Examples of valid edit requests are shown below

ED A:X.ASM Edit the file X.ASM on drive A, with new file and backup on drive A.

ED B:X.ASM A: Edit the file X.ASM on drive B to the temporary file X.\$\$\$ on drive A. On termination of editing, change X.ASM on drive B to X.BAK, and change X.\$\$\$ on drive A to X.ASM.

ED takes file attributes into account. If the operator attempts to edit a read/only file, the message

****FILE IS READ/ONLY****

appears at the console. The file can be loaded and examined, but cannot be altered in any way. Normally the operator simply ends the edit session, and uses STAT to change the file attribute to R/W. If the edited file has the system attribute set, the message

"SYSTEM" FILE NOT ACCESSIBLE

is displayed at the console, and the edit session is aborted. Again, the STAT program can be used to change the system attribute if desired.

SUBMIT

The SUBMIT command allows CP/M commands to be batched together for

automatic processing. The format of SUBMIT is: SUBMIT ufn parm #1...parm #n⟨cr⟩.

The ufn given in the SUBMIT command must be the filename of a file which exists on the currently logged disk, with an assumed file type of "SUB." The SUB file contains CP/M prototype commands, with possible parameter substitution. The actual parameters parm #1 ... parm #n are substituted into the prototype commands, and, if no errors occur, the file of substituted commands is processed sequentially by CP/M.

The prototype command file is created using the ED program, with interspersed "\$" parameters of the form

\$1 \$2 \$3 ... \$n

corresponding to the number of actual parameters which will be included when the file is submitted for execution. When the SUBMIT transient is executed, the actual parameters parm #1 ... parm #n are paired with the formal parameters \$1 ...\$n in the prototype commands. If the number of formal and actual parameters does not correspond, then the submit function is aborted with an error message at the console. The SUBMIT function creates a file of substituted commands with the name

\$\$\$SUB

on the logged disk. When the system reboots (at the termination of the SUBMIT), this command file is read by the CCP as a source of input, rather than the console. If the SUBMIT function is performed on any disk other than drive A, the commands are not processed until the disk is inserted into drive A and the system reboots. Further, the user can abort command processing at any time by typing a rubout when the command is read and echoed. In this case, the \$\$\$SUB file is removed, and the subsequent commands come from the console. Command processing is also aborted if the CCP detects an error in any of the commands. Programs which execute under CP/M can abort processing of command files when error conditions occur by simply erasing any existing \$\$\$SUB file.

In order to introduce dollar signs into a SUBMIT file, the user may type a "\$\$" which reduces to a single "\$" within the command file. Further, an up-arrow symbol "↑" may precede an alphabetic character x, which produces a single ctl-x character within the file.

The last command in a SUB file can initiate another SUB file, thus allowing chained batch commands.

Suppose the file ASMBL.SUB exists on disk and contains the prototype

commands

```
ASM $1
DIR $1.*
ERA *.BAK
PIP $2:=$1.PRN
ERA $1.PRN
```

and the command

```
SUBMIT ASMBL X PRN <cr>
```

is issued by the operator. The SUBMIT program reads the ASMBL.SUB file, substituting "X" for all occurrences of \$1 and "PRN" for all occurrences of \$2, resulting in a \$\$\$SUB file containing the commands

```
ASM X
DIR X.*
ERA *.BAK
PIP PRN:=X.PRN
ERA X.PRN
```

which are executed in sequence by the CCP.

The SUBMIT function can access a SUB file which is on an alternate drive by preceding the file name by a drive name. Submitted files are only acted upon, however, when they appear on drive A. Thus, it is possible to create a submitted file on drive B which is executed at a later time when it is inserted in drive A.

XSUB

XSUB extends the power of the SUBMIT facility to include character input during program execution as well as entering command lines. The XSUB command is included as the first line of your submit file and, when executed, self-relocates directly below the CCP.

All subsequent submit command lines are processed by XSUB, so that programs which read buffered console input (BDOS function 10) receive their input directly from the submit file. For example, the file SAVER.SUB could contain the submit lines:

```
XSUB
DDT
I$1.HEX
R
G0
SAVE 1 $2.COM
```

with a subsequent SUBMIT command:

```
SUBMIT SAVER X Y
```

which substitutes X for \$1 and Y for \$2 in the command stream. The XSUB program loads, followed by DDT which is sent the command lines "IX.HEX" "R" and "G0", thus returning to the CCP. The final command "SAVE 1 Y.COM" is processed by the CCP.

The XSUB program remains in memory, and prints the message

```
(xsub active)
```

on each warm start operation to indicate its presence. Subsequent submit command streams do not require the XSUB, unless an intervening cold start has occurred. Note that XSUB must be loaded after DESPOOL, if both are to run simultaneously.

DUMP

The DUMP program types the contents of the disk file (ufn) at the console in hexadecimal form. The file contents are listed sixteen bytes at a time, with the absolute byte address listed to the left of each line in hexadecimal. Long typeouts can be aborted by pushing the rubout key during printout. (The source listing of the DUMP program is given in the "CP/M Interface Guide" as an example of a program written for the CP/M environment.)

BDOS Error Messages

There are three error situations which the Basic Disk Operating System intercepts during file processing. When one of these conditions is detected, the BDOS prints the message:

```
BDOS ERR ON x: error
```

where x is the drive name, and "error" is one of the three error messages:

```
BAD SECTOR
SELECT
READ ONLY
```

The "BAD SECTOR" message indicates that the disk controller electronics has detected an error condition in reading or writing the diskette. This condition is generally due to a malfunctioning disk controller, or an extremely worn diskette. If you find that your system reports this error more than once a month, you should check the state of your controller electronics, and the condition of your media. You may also encounter this condition in reading files generated by a controller produced by a different manufacturer. Even though controllers are claimed to be IBM-compatible, one often finds small differences in recording formats. The MDS-800 controller, for example, requires two bytes of one's following the data CRC byte, which is not required in the IBM format. As a result, diskettes generated by the Intel MDS can be read by almost all other IBM-compatible systems, while disk files generated on other manufacturers' equipment will produce the "BAD SECTOR" message when read by the MDS. In any case, recovery from this condition is accomplished by typing a `ctl-C` to reboot (this is the safest!), or a return, which simply ignores the bad sector in the file operation. Note, however, that typing a return may destroy your diskette integrity if the operation is a directory write, so make sure you have adequate backups in this case.

The "SELECT" error occurs when there is an attempt to address a drive beyond the A through D range. In this case, the value of `x` in the error message gives the selected drive. The system reboots following any input from the console.

The "READ ONLY" message occurs when there is an attempt to write to a diskette which has been designated as read-only in a `STAT` command, or has been set to read-only by the BDOS. In general, the operator should reboot CP/M either by using the warm start procedure (`ctl-C`) or by performing a cold start whenever the diskettes are changed. If a changed diskette is to be read but not written, BDOS allows the diskette to be changed without the warm or cold start, but internally marks the drive as read-only. The status of the drive is subsequently changed to read/write if a warm or cold start occurs. Upon issuing this message, CP/M waits for input from the console. An automatic warm start takes place following any input.

The first part of the document discusses the importance of maintaining accurate records of all transactions. It emphasizes that proper record-keeping is essential for the integrity of the financial system and for the ability to detect and prevent fraud. The text outlines the various methods used to collect and analyze data, including the use of computerized systems and manual audits. It also discusses the challenges of data collection and the need for standardized procedures to ensure consistency and reliability of the information.

The second part of the document focuses on the role of the auditor in the financial reporting process. It describes the responsibilities of the auditor, including the need to provide an independent and objective assessment of the financial statements. The text also discusses the importance of communication between the auditor and the management of the entity being audited, and the need for transparency in the reporting process.

The third part of the document discusses the impact of the financial reporting process on the economy and the public. It highlights the importance of accurate financial information for investors, creditors, and other stakeholders. The text also discusses the role of the financial reporting process in promoting transparency and accountability in the financial system, and the need for ongoing monitoring and improvement of the process.

CP/M 2.2 INTERFACE GUIDE

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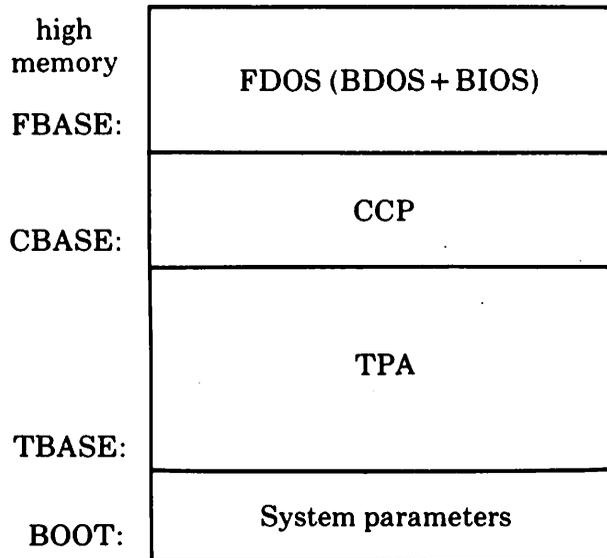
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Introduction

This manual describes CP/M, release 2, system organization including the structure of memory and system entry points. The intention is to provide the necessary information required to write programs which operate under CP/M, and which use the peripheral and disk I/O facilities of the system.

CP/M is logically divided into four parts, called the Basic I/O System (BIOS), the Basic Disk Operating System (BDOS), the Console command processor (CCP), and the Transient Program Area (TPA). The BIOS is a hardware-dependent module which defines the exact low level interface to a particular computer system which is necessary for peripheral device I/O. The BIOS and BDOS are logically combined into a single module with a common entry point, and referred to as the FDOS. The CCP is a distinct program which uses the FDOS to provide a human-oriented interface to the information which is cataloged on the backup storage device. The TPA is an area of memory (i.e., the portion which is not used by the FDOS and CCP) where various non-resistant operating system commands and user programs are executed. The lower portion of memory is reserved for system information and is detailed in later sections. Memory organization of the CP/M system is shown below:



In standard CP/M 2.0,

BDOS size:	E00H bytes
CCP size:	800H bytes

All standard CP/M versions assume $BOOT = 0000H$, which is the base of random access memory. The machine code found at location $BOOT$ performs a system "warm start" which loads and initializes the programs and variables necessary to return control to the CCP. Thus, transient programs need only jump to location $BOOT$ to return control to CP/M at the command level. Further, the standard versions assume $TBASE = BOOT + 0100H$ which is normally location $0100H$. The principal entry point to the FDOS is at location $BOOT + 0005H$ (normally $0005H$) where a jump to $TBASE$ is found. The address field at $BOOT + 0006H$ (normally $0006H$) contains the value of $TBASE$ and can be used to determine the size of available memory, assuming the CCP is being overlaid by a transient program.

Transient programs are loaded into the TPA and executed as follows. The operator communicates with the CCP by typing command lines following each prompt. Each command line takes one of the forms:

```
command
command file1
command file1 file2
```

where "command" is either a built-in function such as `DIR` or `TYPE`, or the name of a transient command or program. If the command is a built-in function of CP/M, it is executed immediately. Otherwise, the CCP searches the currently addressed disk for a file by the name

command.COM

If the file is found, it is assumed to be a memory image of a program which executes in the TPA, and thus implicitly originates at $TBASE$ in memory. The CCP loads the `COM` file from the disk into memory starting at $TBASE$ and possibly extending up to $CBASE$.

If the command is followed by one or two file specifications, the CCP prepares one or two file control block (FCB) names in the system parameter area. These optional FCB's are in the form necessary to access files through the FDOS, and are described in the next section.

The transient program receives control from the CCP and begins execution, perhaps using the I/O facilities of the FDOS. The transient program is "called" from the CCP, and thus can simply return to the CCP upon completion of its processing, or can jump to $BOOT$ to pass control back to CP/M. In the first case, the transient program must not use memory above $CBASE$, while in the latter case, memory up through $TBASE-1$ is free.

The transient program may use the CP/M I/O facilities to communicate with the operator's console and peripheral devices, including the disk subsystem. The I/O system is accessed by passing a "function number" and an "information address" to CP/M through the FDOS entry point at BOOT + 0005H. In the case of a disk read, for example, the transient program sends the number corresponding to a disk read, along with the address of an FCB to the CP/M FDOS. The FDOS, in turn, performs the operation and returns with either a disk read completion indication or an error number indicating that the disk read was unsuccessful. The function numbers and error indicators are given below.

Operating System Call Conventions

The purpose of this section is to provide detailed information for performing direct operating system calls from user programs.

CP/M facilities which are available for access by transient programs fall into two general categories: simple device I/O, and disk file I/O. The simple device operations include:

- Read a Console Character
- Write a Console Character
- Read a Sequential Tape Character
- Write a Sequential Tape Character
- Write a List Device Character
- Get or Set I/O Status
- Print Console Buffer
- Read Console Buffer
- Interrogate Console Ready

The FDOS operations which perform disk Input/Output are

- Disk System Reset
- Drive Selection
- File Creation
- File Open
- File Close
- Directory Search
- File Delete
- File Rename
- Random or Sequential Read
- Random or Sequential Write
- Interrogate Available Disks
- Interrogate Selected Disk
- Set DMA Address
- Set/Reset File Indicators

As mentioned above, access to the FDOS functions is accomplished by passing a function number and information address through the primary entry point at location BOOT + 0005H. In general, the function number is passed in register C with the information address in the double byte pair DE. Single byte values are returned in register A, with double byte values returned in HL (a zero value is returned when the function number is out of range). For reasons of compatibility, register A = L and register B = H upon return in all cases. Note that the register passing conventions of CP/M agree with those of Intel's PL/M systems programming language. The list of CP/M function numbers is given below.

0 System Reset	19 Delete File
1 Console Input	20 Read Sequential
2 Console Output	21 Write Sequential
3 Reader Input	22 Make File
4 Punch Output	23 Rename File
5 List Output	24 Return Login Vector
6 Direct Console I/O	25 Return Current Disk
7 Get I/O Byte	26 Set DMA Address
8 Set I/O Byte	27 Get Addr (Alloc)
9 Print String	28 Write Protect Disk
10 Read Console Buffer	29 Get R/O Vector
11 Get Console Status	30 Set File Attributes
12 Return Version Number	31 Get Addr (Disk Parms)
13 Reset Disk System	32 Set/Get User Code
14 Select Disk	33 Read Random
15 Open File	34 Write Random
16 Close File	35 Compute File Size
17 Search for First	36 Set Random Record
18 Search for Next	

(Functions 28 and 32 should be avoided in application programs to maintain upward compatibility with MP/M.)

Upon entry to a transient program, the CCP leaves the stack pointer set to an eight level stack area with the CCP return address pushed onto the stack, leaving seven levels before overflow occurs. Although this stack is usually not used by a transient program (i.e., most transients return to the CCP through a jump to location 0000H), it is sufficiently large to make CP/M system calls since the FDOS switches to a local stack at system entry. The following assembly language program segment, for example, reads characters continuously until an asterisk is encountered, at which time control returns to the CCP (assuming a standard CP/M system with BOOT + 0000H):

```

BDOS    EQU    0005H    ;STANDARD CP/M ENTRY
CONIN   EQU    1       ;CONSOLE INPUT FUNCTION
;
NEXTC:  ORG    0100H    ;BASE OF TPA
        MVI    C,CONIN ;READ NEXT CHARACTER
        CALL   BDOS    ;RETURN CHARACTER IN (A)
        CPI    '*'     ;END OF PROCESSING?
        JNZ   NEXTC   ;LOOP IF NOT
        RET                    ;RETURN TO CCP
        END

```

CP/M implements a named file structure on each disk, providing a logical organization which allows any particular file to contain any number of records from completely empty, to the full capacity of the drive. Each drive is logically distinct with a disk directory and file data area. The disk file names are in three parts: the drive select code, the file name consisting of one to eight non-blank characters, and the file type consisting of zero to three non-blank characters. The file type names the generic category of a particular file, while the file name distinguishes individual files in each category. The file types listed below name a few generic categories which have been established, although they are generally arbitrary:

ASM	Assembler Source	PLI	PL/I Source File
PRN	Printer Listing	REL	Relocatable Module
HEX	Hex Machine Code	TEX	TEX Formatter Source
BAS	Basic Source File	BAK	ED Source Backup
INT	Intermediate Code	SYM	SID Symbol File
COM	CCP Command File	\$\$\$	Temporary File

Source files are treated as a sequence of ASCII characters, where each "line" of the source file is followed by a carriage-return line-feed sequence (0DH followed by 0AH). Thus one 128 byte CP/M record could contain several lines of source text. The end of an ASCII file is denoted by a control-Z character (1AH) or a real end of file, returned by the CP/M read operation. Control-Z characters embedded within machine code files (e.g., COM files) are ignored, however, and the end of file condition returned by CP/M is used to terminate read operations.

Files in CP/M can be thought of as a sequence of up to 65536 records of 128 bytes each, numbered from 0 through 65535, thus allowing a maximum of 8 megabytes per file. Note, however, that although the records may be considered logically contiguous, they may not be physically contiguous in the disk data area. Internally, all files are broken into 16K byte segments called logical extents, so that counters are easily maintained as 8-bit values. Although the decomposition into extents is discussed in the paragraphs which follow, they are of no particular consequence to the programmer since each extent is automatically accessed in both sequential and random access modes.

In the file operations starting with function number 15, DE usually addresses a file control block (FCB). Transient programs often use the default file control block area reserved by CP/M at location BOOT + 005CH (normally 005CH) for simple file operations. The basic unit of file information is a 128 byte record used for all file operations, thus a default location for disk I/O is provided by CP/M at location BOOT + 0080H (normally 0080H) which is the initial default DMA address (see function 26). All directory operations take place in a reserved area which does not affect write buffers as was the case in release 1, with the exception of Search First and Search Next, where compatibility is required.

The File Control Block (FCB) data area consists of a sequence of 33 bytes for sequential access and a series of 36 bytes in the case that the file is accessed randomly. The default file control block normally located at 005CH can be used for random access files, since the three bytes starting at BOOT + 007DH are available for this purpose. The FCB format is shown with the following fields:

dr	f1	f2	/	/	f8	t1	t2	t3	ex	s1	s2	rc	d0	/	/	dn	cr	r0	r1	r2
00	01	02	...	08	09	10	11	12	13	14	15	16	...	31	32	33	34	35		

where

- dr drive code (0 - 16)
 0 => use default drive for file
 1 => auto disk select drive A,
 2 => auto disk select drive B,
 ...
 16 => auto disk select drive P.
- f1 . . f8 contain the file name in ASCII upper case, with high bit = 0
- t1,t2,t3 contain the file type in ASCII upper case, with high bit = 0
 t1', t2', and t3' denote the bit of these positions,
 t1' = 1 => Read/Only file,
 t2' = 1 => SYS file, no DIR list
- ex contains the current extent number, normally set to 00 by the
 user, but in range 0 - 31 during file I/O
- s1 reserved for internal system use
- s2 reserved for internal system use, set to zero on call to OPEN,
 MAKE, SEARCH
- rc record count for extent "ex," takes on values from 0 - 128

- d0 . . dn filled-in by CP/M, reserved for system use

- cr current record to read or write in a sequential file operation,
 normally set to zero by user

- r0,r1,r2 optional random record number in the range 0-65535, with
 overflow to r2, r0,r1 constitute a 16-bit value with low byte r0,
 and high byte r1

Each file being accessed through CP/M must have a corresponding FCB which provides the name and allocation information for all subsequent file operations. When accessing files, it is the programmer's responsibility to fill the lower sixteen bytes of the FCB and initialize the "cr" field. Normally, bytes 1 through 11 are set to the ASCII character values for the file name and file type, while all other fields are zero.

FCB's are stored in a directory area of the disk, and are brought into central memory before proceeding with file operations (see the OPEN and MAKE functions). The memory copy of the FCB is updated as file operations take place and later recorded permanently on disk at the termination of the file operation (see the CLOSE command).

The CCP constructs the first sixteen bytes of two optional FCB's for a transient by scanning the remainder of the line following the transient name, denoted by "file1" and "file2" in the prototype command line described above, with unspecified fields set to ASCII blanks. The first FCB is constructed at location BOOT + 005CH, and can be used as-is for subsequent file operations. The second FCB occupies the d0 . . . dn portion of the first FCB, and must be moved to another area of memory before use. If, for example, the operator types

PROGRAMME B:X.ZOT Y.ZAP

the file PROGRAMME.COM is loaded into the TPA, and the default FCB at BOOT + 005CH is initialized to drive code 2, file name "X" and file type "ZOT". The second drive code takes the default value 0, which is placed at BOOT + 006CH, with the file name "Y" placed into location BOOT + 006DH and file type "ZAP" located 8 bytes later at BOOT + 0075H. All remaining fields through "cr" are set to zero. Note again that it is the programmer's responsibility to move this second file name and type to another area, usually a separate file control block, before opening the file which begins at BOOT + 005CH, due to the fact that the open operation will overwrite the second name and type.

If no file names are specified in the original command, then the fields beginning at BOOT + 005DH and BOOT + 006DH contain blanks. In all

cases, the CCP translates lower case alphabets to upper case to be consistent with the CP/M file naming conventions.

As an added convenience, the default buffer area at location BOOT + 0080H is initialized to the command line tail typed by the operator following the program name. The first position contains the number of characters, with the characters themselves following the character count. Given the above command line, the area beginning at BOOT + 0080H is initialized as follows:

BOOT + 0080H:

```
+00 +01 +02 +03 +04 +05 +06 +07 +08 +09 +10 +11 +12 +13 +14
 14 " " "B" ":" "X" "." "Z" "O" "T" " " "Y" "." "Z" "A" "P"
```

where the characters are translated to upper case ASCII with uninitialized memory following the last valid character. Again, it is the responsibility of the programmer to extract the information from this buffer before any file operations are performed, unless the default DMA address is explicitly changed.

The individual functions are described in detail in the pages which follow.

FUNCTION 0: System Reset

Entry Parameters :

Register C: 00H

The system reset function returns control to the CP/M operating system at the CCP level. The CCP re-initializes the disk subsystem by selecting and logging-in disk drive A. This function has exactly the same effect as a jump to location BOOT.

FUNCTION 1: CONSOLE INPUT

Entry Parameters :

Register C: 01H

Returned Value :

Register A: ASCII Character

The console input function reads the next console character to register A. Graphic characters, along with carriage return, line feed, and backspace (ctl-H) are echoed to the console. Tab characters (ctl-I) are expanded in columns of eight characters. A check is made for start/stop scroll (ctl-S) and start/stop printer echo (ctl-P). The FDOS does not return to the calling program until a character has been typed, thus suspending execution of a character if not ready.

FUNCTION 2: CONSOLE OUTPUT

Entry Parameters :

Register C: 02H
Register E: ASCII Character

The ASCII character from register E is sent to the console device. Similar to function 1, tabs are expanded and checks are made for start/stop scroll and printer echo.

FUNCTION 3: READER INPUT

Entry Parameters :

Register C: 03H

Returned Value :

Register A: ASCII Character

The Reader Input function reads the next character from the logical reader into register A. Control does not return until the character has been read.

FUNCTION 4: PUNCH OUTPUT

Entry Parameters :

Register C: 04H
Register E: ASCII Character

The Punch Output function sends the character from register E to the logical punch device.

FUNCTION 5: LIST OUTPUT

Entry Parameters :

Register C: 05H
Register E: ASCII Character

The List Output function sends the ASCII character in register E to the logical listing device.

FUNCTION 6: DIRECT CONSOLE I/O

Entry Parameters:

Register C: 06H
Register E: 0FFH (input) or
char (output)

Returned Value :

Register A: char or status
(no value)

Direct console I/O is supported under CP/M for those specialized applications where unadorned console input and output is required. Use of this function should, in general, be avoided since it bypasses all of CP/M's normal control character functions (e.g., control-S and control-P). Programs which perform direct I/O through the BIOS under previous releases of CP/M, however, should be changed to use direct I/O under BDOS so that they can be fully supported under future releases of MP/M and CP/M.

Upon entry to function 6, register E either contains hexadecimal FF, denoting a console input request, or register E contains an ASCII character. If the input value is FF, then function 6 returns A = 00 if no character is ready, otherwise A contains the next console input character.

If the input value in E is not FF, then function 6 assumes that E contains a valid ASCII character which is sent to the console.

FUNCTION 7: GET I/O BYTE

Entry Parameters:

Register C: 07H

Returned Value:

Register A: I/O Byte Value

The Get I/O Byte function returns the current value of IOBYTE in register A.

FUNCTION 8: SET I/O BYTE

Entry Parameters:

Register C: 08H
Register E: I/O Byte Value

The Set I/O Byte function changes the system IOBYTE value to that given in register E.

FUNCTION 9: PRINT STRING

Entry Parameters:

Register C: 09H

Registers DE: String Address

The Print String function sends the character string stored in memory at the location given by DE to the console device, until a "\$" is encountered in the string. Tabs are expanded as in function 2, and checks are made for start/stop scroll and printer echo.

FUNCTION 10: READ CONSOLE BUFFER

Entry Parameters:

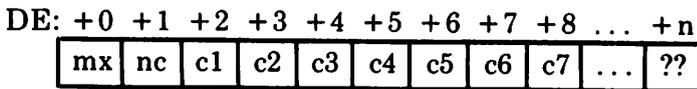
Register C: 0AH

Registers DE: Buffer Address

Returned Value :

Console Characters in Buffer

The Read Buffer function reads a line of edited console input into a buffer addressed by registers DE. Console input is terminated when either the input buffer overflows. The Read Buffer takes the form:



where "mx" is the maximum number of characters which the buffer will hold (1 to 255), "nc" is the number of characters read (set by FDOS upon return), followed by the characters read from the console. If $nc < mx$, then uninitialized positions follow the last character, denoted by "??" in the above figure. A number of control functions are recognized during line editing:

- rub/del removes the echoes the last character
- ctl-C reboots when at the beginning of line
- ctl-E causes physical end of line
- ctl-H backspaces one character position
- ctl-J (line feed) terminates input line
- ctl-M (return) terminates input line
- ctl-R retypes the current line after new line
- ctl-X backspaces to beginning of current line

Note also that certain functions which return the carriage to the leftmost

position (e.g., ctl-X) do so only to the column position where the prompt ended (in earlier releases, the carriage returned to the extreme left margin). This convention makes operator data input and line correction more legible.

FUNCTION 11: GET CONSOLE STATUS

Entry Parameters:

Register C: 0BH

Return Value :

Register A: Console Status

The Console Status function checks to see if a character has been typed at the console. If a character is ready, the value 0FFH is returned in register A. Otherwise a 00H value is returned.

FUNCTION 12: RETURN VERSION NUMBER

Entry Parameters:

Register C: 0CH

Returned Value :

Registers HL: Version Number

Function 12 provides information which allows version independent programming. A two-byte value is returned, with H=00 designating the CP/M release (H=01 for MP/M), and L=00 for all releases previous to 2.0. CP/M 2.0 returns a hexadecimal 20 in register L, with subsequent version 2 releases in the hexadecimal range 21, 22, through 2F. Using function 12, for example, you can write application programs which provide both sequential and random access functions, with random access disabled when operating under early releases of CP/M.

FUNCTION 13: RESET DISK SYSTEM

Entry Parameters:

Register C: 0DH

The Reset Disk Function is used to programmatically restore the file system to a reset state where all disks are set to read/write (see functions 28 and 29), only disk drive A is selected, and the default DMA address is reset to BOOT+0080H. This function can be used, for example, by an application program which requires a disk change without a system reboot.

FUNCTION 14: SELECT DISK

Entry Parameters:

Register C: 0EH
Register E: Selected Disk

The Select Disk function designates the disk drive named in register E as the default disk for subsequent file operations, with E = 0 for drive A, 1 for drive B, and so-forth through 15 corresponding to drive P in a full sixteen drive system. The drive is placed in an "on-line" status which, in particular, activates its directory until the next cold start, warm start, or disk system reset operation. If the disk media is changed while it is on-line, the drive automatically goes to a read/only status in a standard CP/M environment (see function 28). FCB's which specify drive code zero (dr = 00H) automatically reference the currently selected default drive. Drive code values between 1 and 16, however, ignore the selected default drive and directly reference drives A through P.

FUNCTION 15: OPEN FILE

Entry Parameters:

Register C: 0FH
Registers DE: FCB Address

Returned Value :

Register A: Directory Code

The Open File operation is used to activate a file which currently exists in the disk directory for the currently active user number. The FDOS scans the referenced disk directory for a match in positions 1 through 14 of the FCB referenced by DE (byte s1 is automatically zeroed), where an ASCII question mark (3FH) matches any directory character in any of these positions. Normally, no question marks are included and, further, bytes "ex" and "s2" of the FCB are zero.

If a directory element is matched, the relevant directory information is copied into bytes d0 through dn of the FCB, thus allowing access to the files through subsequent read and write operations. Note that an existing file must not be accessed until a successful open operation is completed. Upon return, the open function returns a "directory code" with the value 0 through 3 if the open was successful, or 0FFH (255 decimal) if the file cannot be found. If question marks occur in the FCB then the first matching FCB is activated. Note that the current record ("cr") must be zeroed by the program if the file is to be accessed sequentially from the first record.

FUNCTION 16: CLOSE FILE

Entry Parameters :

Register C: 10H
Registers DE: FCB Address

Returned Value :

Register A: Directory Code

The Close File function performs the inverse of the open file function. Given that the FCB addressed by DE has been previously activated through an open or make function (see functions 15 and 22), the close function permanently records the new FCB in the referenced disk directory. The FCB matching process for the close is identical to the open function. The directory code returned for a successful close operation is 0, 1, 2, or 3, while a 0FFH (255 decimal) is returned if the file name cannot be found in the directory. A file need not be closed if only read operations have taken place. If write operations have occurred, however, the close operation is necessary to permanently record the new directory information.

FUNCTION 17: SEARCH FOR FIRST

Entry Parameters :

Register C: 11H
Registers DE: FCB Address

Returned Value :

Register A: Directory Code

Search First scans the directory for a match with the file given by the FCB addressed by DE. The value 255 (hexadecimal FF) is returned if the file is not found, otherwise 0, 1, 2, or 3 is returned indicating the file is present. In the case that the file is found, the current DMA address is filled with the record containing the directory entry, and the relative starting position is $A * 32$ (i.e., rotate the A register left 5 bits, or ADD A five times). Although not normally required for application programs, the directory information can be extracted from the buffer at this position.

An ASCII question mark (63 decimal, 3F hexadecimal) in any position from "fl" through "ex" matches the corresponding field of any directory entry on the default or auto-selected disk drive. If the "dr" field contains an ASCII question mark, then the auto disk selected function is disabled, the default disk is searched, with the search function returning any matched entry, allocated or free, belonging to any user number. This latter function is not normally used by application programs, but does allow complete flexibility to scan all current directory values. If the "dr" field is not a question mark, the "s2" byte is automatically zeroed.

FUNCTION 18: SEARCH FOR NEXT

Entry Parameters :

Register C: 12H

Returned Value :

Register A: Directory Code

The Search Next function is similar to the Search First function, except that the directory scan continues from the last matched entry. Similar to function 17, function 18 returns the decimal value 255 in A when no more directory items match.

FUNCTION 19: DELETE FILE

Entry Parameters :

Register C: 13H

Registers DE: FCB Address

Returned Value :

Register A: Directory Code

The Delete File function removes files which match the FCB addresses by DE. The filename and type may contain ambiguous references (i.e., question marks in various positions), but the drive select code cannot be ambiguous, as in the Search and Search Next functions.

Function 19 returns a decimal 255 if the referenced file or files cannot be found, otherwise a value in the range 0 to 3 is returned.

FUNCTION 20: READ SEQUENTIAL

Entry Parameters :

Register C: 14H

Registers DE: FCB Address

Returned Value :

Register A: Directory Code

Given that the FCB addressed by DE has been activated through an open or make function (numbers 15 and 22), the Read Sequential function reads the next 128 byte record from the file into memory at the current DMA address. The record is read from position "cr" of the extent, and the "cr" field is automatically incremented to the next record position. If the "cr" field overflows then the next logical extent is automatically opened and the "cr" field is reset to zero in preparation for the next read operation. The value 00H

is returned in the A register if the read operation was successful, while a non-zero value is returned if no data exists at the next record position (e.g., end of file occurs).

FUNCTION 21: WRITE SEQUENTIAL

Entry Parameters :

Register C: 15H
Registers DE: FCB Address

Returned Value :

Register A: Directory Code

Given that the FCB addressed by DE has been activated through an open or make function (numbers 15 and 22), the Write Sequential function writes the 128 byte data record at the current DMA address to the file named by the FCB. The record is placed at position "cr" of the file, and the "cr" field is automatically incremented to the next record position. If the "cr" field overflows then the next logical extent is automatically opened and the "cr" field is reset to zero in preparation for the next write operation. Write operations can take place into an existing file, in which case newly written records overlay those which already exist in the file. Register A = 00H upon return from a successful write operation, while a non-zero value indicates an unsuccessful write due to a full disk.

FUNCTION 22: MAKE FILE

Entry Parameters :

Register C: 16H
Registers DE: FCB Address

Returned Value :

Register A: Directory Code

The Make File operation is similar to the open file operation except that the FCB must name a file which does not exist in the currently referenced disk directory (i.e., the one named explicitly by a non-zero "dr" code, or the default disk if "dr" is zero). The FDOS creates the file and initializes both the directory and main memory value to an empty file. The programmer must ensure that no duplicate file names occur, and a preceding delete operation is sufficient if there is any possibility of duplication. Upon return, register A = 0, 1, 2, or 3 if the operation was successful and 0FFH (255 decimal) if no more directory space is available. The make function has the side-effect of activating the FCB and thus a subsequent open is not necessary.

FUNCTION 23: RENAME FILE

Entry Parameters :

Register C: 17H
Registers DE: FCB Address

Returned Value :

Register A: Directory Code

The Rename function uses the FCB addressed by DE to change all occurrences of the file named in the first 16 bytes to the file named in the second 16 bytes. The drive code "dr" at position 0 is used to select the drive, while the drive code for the new file name at position 16 of the FCB is assumed to be zero. Upon return, register A is set to a value between 0 and 3 if the rename was successful, and 0FFH (255 decimal) if the first file name could not be found in the directory scan.

FUNCTION 24: RETURN LOGIN VECTOR

Entry Parameters :

Register C: 18H

Returned Value :

Registers HL: Login Vector

The login vector value returned by CP/M is a 16-bit value in HL, where the least significant bit of L corresponds to the first drive A, and the high order bit of H corresponds to the sixteenth drive, labelled P. A "0" bit indicates that the drive is not on-line, while a "1" bit marks a drive that is actively on-line due to an explicit disk drive selection, or an implicit drive select caused by a file operation which specified a non-zero "dr" field. Note that compatibility is maintained with earlier releases, since registers A and L contain the same values upon return.

FUNCTION 25: RETURN CURRENT DISK

Entry Parameters :

Register C: 19H

Returned Value :

Register A: Current Disk

Function 25 returns the currently selected default disk number in register A. The disk numbers range from 0 through 15 corresponding to drives A through P.

FUNCTION 26: SET DMA ADDRESS

Entry Parameters :

Regular C: 1AH
Registers DE: DMA Address

“DMA” is an acronym for Direct Memory Address, which is often used in connection with disk controllers which directly access the memory of the mainframe computer to transfer data to and from the disk subsystem. Although many computer systems use non-DMA access (i.e., the data is transferred through programmed I/O operations), the DMA address has, in CP/M, come to mean the address at which the 128 byte data record resides before a disk write and after a disk read. Upon cold start, warm start, or disk system reset, the DMA address is automatically set to BOOT + 0080H. The Set DMA function, however, can be used to change this default value to address another area of memory where the data records reside. Thus, the DMA address becomes the value specified by DE until it is changed by a subsequent Set DMA function, cold start, warm start, or disk system reset.

FUNCTION 27: GET ADDR (ALLOC)

Entry Parameters :

Register C: 1BH

Returned Value :

Registers HL: ALLOC Address

An “allocation vector” is maintained in main memory for each on-line disk drive. Various system programs use the information provided by the allocation vector to determine the amount of remaining storage (see the STAT program). Function 27 returns the base address of the allocation vector for the currently selected disk drive. The allocation information may, however, be invalid if the selected disk has been marked read/only. Although this function is not normally used by application programs, additional details of the allocation vector are found in the “CP/M Alteration Guide.”

FUNCTION 28: WRITE PROTECT DISK

Entry Parameters :

Register C: 1CH

The disk write protect function provides temporary write protection for the currently selected disk. Any attempt to write to the disk, before the next cold or warm start operation produces the message

Bdos Err on d: R/O

FUNCTION 29: GET READ/ONLY VECTOR

Entry Parameters :

Register C: 1DH

Returned Value :

Registers HL: R/O Vector Value

Function 29 returns a bit vector in register pair HL which indicates drives which have the temporary read/only bit set. Similar to function 24, the least significant bit corresponds to drive A, while the most significant bit corresponds to drive P. The R/O bit is set either by the explicit call to function 28, or by the automatic software mechanisms within CP/M which detect changed disks.

FUNCTION 30: SET FILE ATTRIBUTES

Entry Parameters :

Register C: 1EH

Registers DE: FCB Address

Returned Value :

Register A: Directory Code

The Set File Attributes function allows programmatic manipulation of permanent indicators attached to files. In particular, the R/O and System attributes (t1' and t2') can be set or reset. The DE pair addresses an unambiguous file name with the appropriate attributes set or reset. Function 30 searches for a match, and changes the matched directory entry to contain the selected indicators. Indicators f1' through f4' are not presently used, but may be useful for applications programs, since they are not involved in the matching process during file open and close operations. Indicators f5' through f8' and t3' are reserved for future system expansion.

FUNCTION 31: GET ADDR (DISK PARMS)

Entry Parameters :

Register C: 1FH

Returned Value :

Registers HL: DPB Address

The address of the BIOS resident disk parameter block is returned in HL as a result of this function call. This address can be used for either of two purposes. First, the disk parameter values can be extracted for display and

space computation purposes, or transient programs can dynamically change the values of current disk parameters when the disk environment changes, if required. Normally, application programs will not require this facility.

FUNCTION 32: SET/GET USER CODE

Entry Parameters :

Register C: 20H
Register E: 0FFH (get or
User Code (set))

Returned Value :

Register A: Current Code or
(no value)

An application program can change or interrogate the currently active user number by calling function 32. If register E = 0FFH, then the value of the current user number is returned in register A, where the value is in the range 0 to 31. If register E is not 0FFH, then the current user number is changed to the value of E (modulo 32).

FUNCTION 33: READ RANDOM

Entry Parameters :

Register C: 21H
Registers DE: FCB Address

Returned Value :

Register A: Return Code

The Read Random function is similar to the sequential file read operation of previous releases, except that the read operation takes place at a particular record number, selected by the 24-bit value constructed from the three byte field following the FCB (byte positions r0 at 33, r1 at 34, and r2 at 35). Note that the sequence of 24 bits is stored with least significant byte first (r0), middle byte next (r1), and high byte last (r2). CP/M does not reference byte r2, except in computing the size of a file (function 35). Byte r2 must be zero, however, since a non-zero value indicates overflow past the end of file.

Thus, the r0,r1 byte pair is treated as a double-byte, or "word" value, which contains the record to read. This value ranges from 0 to 65535, providing access to any particular record of the 8 megabyte file. In order to process a file using random access, the base extent (extent 0) must first be opened. Although the base extent may or may not contain any allocated data, this ensures that the file is properly recorded in the directory, and is visible in DIR requests. The selected record number is then stored into the random record field (r0,r1), and the BDOS is called to read the record. Upon return from the

call, register A either contains an error code, as listed below, or the value 00 indicating the operation was successful. In the latter case, the current DMA address contains the randomly accessed record. Note that contrary to the sequential read operation, the record number is not advanced. Thus, subsequent random read operations continue to read the same record.

Upon each random read operation, the logical extent and current record values are automatically set. Thus, the file can be sequentially read or written, starting from the current randomly accessed position. Note, however, that in this case, the last randomly read record will be re-read as you switch from random mode to sequential read, and the last record will be re-written as you switch to a sequential write operation. You can, of course, simply advance the random record position following each random read or write to obtain the effect of a sequential I/O operation.

Error codes returned in register A following a random read are listed below.

- 01 reading unwritten data
- 02 (not returning in random mode)
- 03 cannot close current extent
- 04 seek to unwritten extent
- 05 (not returned in read mode)
- 06 seek past physical end of disk

Error code 01 and 04 occur when a random read operation accesses a data block which has not been previously written, or an extent which has not been created, which are equivalent conditions. Error 3 does not normally occur under proper system operation, but can be cleared by simply re-reading, or re-opening extent zero as long as the disk is not physically write protected. Error code 06 occurs whenever byte r2 is non-zero under the current 2.0 release. Normally, non-zero return codes can be treated as missing data, with zero return codes indicating operation complete.

FUNCTION 34: WRITE RANDOM

Entry Parameters :

Register C: 22H
Registers DE: FCB Address

Returned Value :

Register A: Return Code

The Write Random operation is initiated similar to the Read Random call, except that data is written to the disk from the current DMA address. Further, if the disk extent or data block which is the target of the write has not yet been allocated, the allocation is performed before the write operation

continues. As in the Read Random operation, the random record number is not changed as a result of the write. The logical extent number and current record positions of the file control block are set to correspond to the random record which is being written. Again, sequential read or write operations can commence following a random write, with the notation that the currently addressed record is either read or rewritten again as the sequential operation begins. You can also simply advance the random record position following each write to get the effect of a sequential write operation. Note that in particular, reading or writing the last record of an extent in random mode does not cause an automatic extent switch as it does in sequential mode.

The error codes returned by a random write are identical to the random read operation with the addition of error code 05, which indicates that a new extent cannot be created due to directory overflow.

FUNCTION 35: COMPUTE FILE SIZE

Entry Parameters :

Register C: 23H

Registers DE: FCB Address

Returned Value :

Random Record Field Set

When computing the size of a file, the DE register pair addresses an FCB in random mode format (bytes r0, r1, and r2 are present). The FCB contains an unambiguous file name which is used in the directory scan. Upon return, the random record bytes contain the "virtual" file size which is, in effect, the record address of the record following the end of the file. If, following a call to function 35, the high record byte r2 is 01, then the file contains the maximum record count 65536. Otherwise, bytes r0 and r1 constitute a 16-bit value (r0 is the least significant byte, as before) which is the file size.

Data can be appended to the end of an existing file by simply calling function 35 to set the random record position to the end of file, then performing a sequence of random writes starting at the preset record address

The virtual size of a file corresponds to the physical size when the file is written sequentially. If, instead, the file was created in random mode and "holes" exist in the allocation, then the file may in fact contain fewer records than the size indicates. If, for example, only the last record of an eight megabyte file is written in random mode (i.e., record number 65535), then the virtual size is 65536 records, although only one block of data is actually allocated.

FUNCTION 36: SET RANDOM RECORD

Entry Parameters :

Register C: 24H
Registers DE: FCB Address

Returned Value :

Random Record Field Set

The Set Random Record function causes the BDOS to automatically produce the random record position from a file which has been read or written sequentially to a particular point. The function can be useful in two ways.

First, it is often necessary to initially read and scan a sequential file to extract the position of various "key" fields. As each key is encountered, function 36 is called to compute the random record position for the data corresponding to this key. If the data unit size is 128 bytes, the resulting record position is placed into a table with the key for later retrieval. After scanning the entire file and tabularizing the keys and their record numbers, you can move instantly to a particular keyed record by performing a random read using the corresponding random record number which was saved earlier. The scheme is easily generated when variable record lengths are involved since the program need only store the buffer-relative byte position along with the key and record number in order to find the exact starting position of the keyed data at a later time.

A second use of function 36 occurs when switching from a sequential read or write over to random read or write. A file is sequentially accessed to a particular point in the file, function 36 is called which sets the record number, and subsequent random read and write operations continue from the selected point in the file.

Sample File-to-File Copy Program

The program shown below provides a relatively simple example of file operations. The program source file is created as COPY.ASM using the CP/M ED program and then assembled using ASM or MAC, resulting in a "HEX" file. The LOAD program is then used to produce a COPY.COM file which executes directly under the CCP. The program begins by setting the stack pointer to a local area, and then proceeds to move the second name from the default area at 006CH to a 33-byte file control block called DFCB. The DFCB is then prepared for file operations by clearing the current record field. At this point, the source and destination FCB's are ready for processing since the SFCB at 005CH is properly set-up by the CCP upon entry to the COPY program. That is, the first name is placed into the default FCB, with

the proper fields zeroed, including the current record field at 007CH. The program continues by opening the source file, deleting any existing destination file, and then creating the destination file. If all this is successful, the program loops at the label COPY until each record has been read from the source file and placed into the destination file. Upon completion of the data transfer, the destination file is closed and the program returns to the CCP command level by jumping to BOOT.

```

;          sample file-to-file copy program
;
;          at the ccp level, the command
;
;          copy a:x.y b:u.v
;
;          copies the file named x.y from drive
;          a to a file named u.v on drive b.
;
0000 = boot    equ    0000h    ; system reboot
0005 = bdos   equ    0005h    ; bdos entry point
005c = fcbl   equ    005ch    ; first file name
005c = sfcbl  equ    fcbl     ; source fcb
006c = fcb2   equ    006ch    ; second file name
0080 = dbuff  equ    0080h    ; default buffer
0100 = tpa    equ    0100h    ; beginning of tpa
;
0009 = printf equ    9        ; print buffer func#
000f = openf  equ    15       ; open file func#
0010 = closef equ    16       ; close file func#
0013 = deletef equ    19      ; delete file func#
0014 = readf  equ    20       ; sequential read
0015 = writef equ    21       ; sequential write
0016 = makef  equ    22       ; make file func#
;
0100      org    tpa        ; beginning of tpa
0100 311b02 lxi    sp,stack; local stack
;
;          move second file name to dfcb
0103 0e10    mvi    c,16      ; half an fcb
0105 116c00  lxi    d,fcbl     ; source of move
0108 21da01  lxi    h,dfcbl     ; destination fcb
010b la      mfcbl: ldax   d        ; source fcb
010c 13      inx    d        ; ready next
010d 77      mov    m,a      ; dest fcb
010e 23      inx    h        ; ready next
010f 0d      dcr    c        ; count 16...0
0110 c20b01  jnz   mfcbl     ; loop 16 times
;
;          name has been moved, zero cr
0113 af      xra    a        ; a = 00h
0114 32fa01  sta    dfcbl     ; current rec = 0
;
;          source and destination fcb's ready
;
0117 115c00  lxi    d,sfcbl     ; source file
011a cd6901  call   open        ; error if 255
011d 118701  lxi    d,nofile; ready message
0120 3c      inr    a        ; 255 becomes 0
0121 cc6101  cz     finis      ; done if no file
;
;          source file open, prep destination
0124 11da01  lxi    d,dfcbl     ; destination
0127 cd7301  call   delete      ; remove if present
;
012a 11da01  lxi    d,dfcbl     ; destination
012d cd8201  call   make        ; create the file
0130 119601  lxi    d,nodir     ; ready message

```

```

0133 3c          inr    a      ; 255 becomes 0
0134 cc6101     cz     finis   ; done if no dir space
;
; source file open, dest file open
; copy until end of file on source
;
0137 115c00    copy:   lxi    d,sfcb ; source
013a cd7801     call   read   ; read next record
013d b7         ora    a      ; end of file?
013e c25101     jnz    eofile  ; skip write if so
;
; not end of file, write the record
0141 11da01     lxi    d,dfcb ; destination
0144 cd7d01     call   write  ; write record
0147 11a901     lxi    d,space ; ready message
014a b7         ora    a      ; 00 if write ok
014b c46101     cml   finis   ; end if so
014e c33701     jmp    copy   ; loop until eof
;
eofile: ; end of file, close destination
0151 11da01     lxi    d,dfcb ; destination
0154 cd6e01     call   close  ; 255 if error
0157 21bb01     lxi    h,wrprot; ready message
015a 3c         inr    a      ; 255 becomes 00
015b cc6101     cz     finis   ; shouldn't happen
;
; copy operation complete, end
015e 11cc01     lxi    d,normal; ready message
;
finis: ; write message given by de, reboot
0161 0e09       mvi    c,printf
0163 cd0500     call   bdos   ; write message
0166 c30000     jmp    boot   ; reboot system
;
; system interface subroutines
; (all return directly from bdos)
;
0169 0e0f       open:  mvi    c,openf
016b c30500     jmp    bdos
;
016e 0e10       close: mvi    c,closef
0170 c30500     jmp    bdos
;
0173 0e13       delete: mvi   c,deletef
0175 c30500     jmp    bdos
;
0178 0e14       read:  mvi    c,readf
017a c30500     jmp    bdos
;
017d 0e15       write: mvi    c,writef
017f c30500     jmp    odos
;
0182 0e16       make:  mvi    c,makef
0184 c30500     jmp    bdos
;
; console messages
0187 6e6120fnofile: db    'no source file$'
0196 6e6f209nodir: db    'no directory space$'
01a9 6f7574tspace: db    'out of data space$'
01b0 7772695wrprot: db    'write protected?$'
01c0 636f700normal: db    'copy complete$'
;
; data areas
01ca          dfcb:  ds    33      ; destination fcb
01fa =        dfcbcr equ  dfcb+32 ; current record
;
01fb          ds    32      ; 16 level stack
0210          end

```

Note that there are several simplifications in this particular program. First, there are no checks for invalid file names which could, for example, contain ambiguous references. This situation could be detected by scanning the 32 byte default area starting at location 005CH for ASCII question marks. A check should also be made to ensure that the file names have, in fact, been included (check locations 005DH and 006DH for non-blank ASCII characters). Finally, a check should be made to ensure that the source and destination file names are different. A speed improvement could be made by buffering more data on each read operation. One could, for example, determine the size of memory by fetching FBASE from location 0006H and use the entire remaining portion of memory for a data buffer. In this case, the programmer simply resets the DMA address to the next successive 128 byte area before each read. Upon writing to the destination file, the DMA address is reset to the beginning of the buffer and incremented by 128 bytes to the end as each record is transferred to the destination file.

Sample File Dump Utility.

The file dump program shown below is slightly more complex than the single copy program given in the previous section. The dump program reads an input file, specified in the CCP command line, and displays the content of each record in hexadecimal format at the console. Note that the dump program saves the CCP's stack upon entry, resets the stack to a local area, and restores the CCP's stack before returning directly to the CCP. Thus, the dump program does not perform warm start at the end of processing.

```

; DUMP program reads input file and displays hex data
;
0100          org      100h
0005 =      bdos     equ      0005h    ;dos entry point
0001 =      cons    equ      1        ;read console
0002 =      typef   equ      2        ;type function
0009 =      prkfb   equ      9        ;buffer print entry
000b =      brkfb   equ      11       ;break key function (true if char
000f =      openf   equ      15       ;file open
0014 =      readf   equ      20       ;read function
;
005c =      fcb     equ      5ch      ;file control block address
0080 =      buff   equ      80h      ;input disk buffer address
;
;      non graphic characters
000d =      cr     equ      0dh      ;carriage return
000a =      lf     equ      0ah      ;line feed
;
;      file control block definitions
005c =      fcbdn  equ      fcb+0    ;disk name
005d =      fcbfn  equ      fcb+1    ;file name
0065 =      fcbft  equ      fcb+9    ;disk file type (3 characters)
0068 =      fcbri  equ      fcb+12   ;file's current reel number
006b =      fcbrc  equ      fcb+15   ;file's record count (0 to 128)
007c =      fcbr  equ      fcb+32   ;current (next) record number (0
007d =      fcbln  equ      fcb+33   ;fcb length
;
;      set up stack
0100 210000   lxi      h,0
0103 39       dad      sp
;      entry stack pointer in hl from the ccp

```

```

0104 221502      shld   oldsp
;               set sp to local stack area (restored at finis)
0107 315702      lxi    sp,stktop
;               read and print successive buffers
010a cdcl01      call   setup ;set up input file
010d feff        cpi    255 ;255 if file not present
010f c21b01      jnz   openok ;skip if open is ok
;
;               file not there, give error message and return
0112 11f301     lxi    d,opnmsg
0115 cd9c01     call   err
0118 c35101     jmp    finis ;to return
;
openok:         ;open operation ok, set buffer index to end
011b 3e80       mvi    a,80h
011d 321302     sta   ibp ;set buffer pointer to 80h
;               hl contains next address to print
0120 210000     lxi    h,0 ;start with 0000
;
gloop:
0123 e5         push   h ;save line position
0124 cda201     call   gnb
0127 e1         pop    h ;recall line position
0128 da5101     jc    finis ;carry set by gnb if end file
012b 47         mov    b,a
;               print hex values
;               check for line fold
012c 7d         mov    a,l
012d e60f      ani    0fh ;check low 4 bits
012f c24401     jnz   nonum
;               print line number
0132 cd7201     call   crlf
;
;               check for break key
0135 cd5901     call   break
;               accum lsb = 1 if character ready
0138 0f        rrc    ;into carry
0139 da5101     jc    finis ;don't print any more
;
013c 7c        mov    a,h
013d cd8f01     call   phex
0140 7d        mov    a,l
0141 cd8f01     call   phex
nonum:
0144 23        inx    h ;to next line number
0145 3e20      mvi    a,' '
0147 cd6501     call   pchar
014a 78        mov    a,b
014b cd8f01     call   phex
014e c32301     jmp    gloop
;
finis:
;               end of dump, return to ccp
;               (note that a jmp to 0000h reboots)
0151 cd7201     call   crlf
0154 2a1502     lhld  oldsp
0157 f9        sphl
;               stack pointer contains ccp's stack location
0158 c9        ret    ;to the ccp
;
;
;               subroutines
;
break:         ;check break key (actually any key will do)
0159 e5d5c5     push  h! push b; environment saved
015c 0e0b      mvi    c,brkf
015e cd0500     call   bdos
0161 c1d1e1     pop   b! pop d! pop h; environment restored
0164 c9        ret
;
pchar:        ;print a character

```

```

0165 e5d5c5      push h! push d! push b; saved
0168 0e02        mvi     c,typef
016a 5f          mov     e,a
016b cd0500      call   bdos
016e c1d1e1      pop b! pop d! pop h; restored
0171 c9          ret

;
; crlf:
0172 3e0d        mvi     a,cr
0174 cd6501      call   pchar
0177 3e0a        mvi     a,lf
0179 cd6501      call   pchar
017c c9          ret

;
;
; pnib: ;print nibble in reg a
017d e60f        ani     0fh      ;low 4 bits
017f fe0a        cpi     10
0181 d28901      jnc     pl0
;          ; less than or equal to 9
0184 c630        adi     '0'
0186 c38b01      jmp     prn
;
;          ; greater or equal to 10
0189 c637        pl0:    adi     'a' - 10
018b cd6501      prn:   call   pchar
018e c9          ret

;
; phex: ;print hex char in reg a
018f f5          push   psw
0190 0f          rrc
0191 0f          rrc
0192 0f          rrc
0193 0f          rrc
0194 cd7d01      call   pnib      ;print nibble
0197 f1          pop    psw
0198 cd7d01      call   pnib
019b c9          ret

;
; err: ;print error message
;          ; d,e addresses message ending with "$"
019c 0e09        mvi     c,printf      ;print buffer function
019e cd0500      call   bdos
01a1 c9          ret

;
;
; gnb: ;get next byte
01a2 3a1302      lda     ibp
01a5 fe80        cpi     80h
01a7 c2b301      jnz     g0
;          ; read another buffer
;
;
;
01aa cdce01      call   disk
01ad b7          ora     a          ;zero value if read ok,
01ae cab301      jz     g0          ;for another byte
;          ; end of data, return with carry set for eof
01b1 37          stc
01b2 c9          ret

;
; g0: ;read the byte at buff+reg a
01b3 5f          mov     e,a      ;ls byte of buffer index
01b4 1600        mvi     d,0      ;double precision index to de
01b6 3c          inr     a        ;index=index+1
01b7 321302      sta     ibp      ;back to memory
;          ; pointer is incremented
;          ; save the current file address
01ba 218000      lxi     h,buff
01bd 19          dad     d
;          ; absolute character address is in hl
01be 7e          mov     a,m

```

```

;      byte is in the accumulator
01bf b7      ora      a      ;reset carry bit
01c0 c9      ret
;
;setup: ;set up file
;      open the file for input
01c1 af      xra      a      ;zero to accum
01c2 327c00  sta      fcbr   ;clear current record
;
01c5 115c00  lxi      d,fcbr
01c8 0e0f    mvi      c,openf
01ca cd0500  call    bdos
;      255 in accum if open error
01cd c9      ret
;
diskr: ;read disk file record
01ce e5d5c5  push h! push d! push b
01d1 115c00  lxi      d,fcbr
01d4 0e14    mvi      c,readf
01d6 cd0500  call    bdos
01d9 c1d1e1  pop b! pop d! pop h
01dc c9      ret
;
;      fixed message area
01dd 46494c0 signon: db      'file du p version 2.0$'
01f3 0d0a4e0 opnmsg: db      cr,lf,'no input file present on disk$'
;
;      variable area
0213      ibp:      ds      2      ;input buffer pointer
0215      oldsp:   ds      2      ;entry sp value from ccp
;
;      stack area
0217      stktop:  ds      64     ;reserve 32 level stack
;
0257      end

```

Sample Random Access Program.

This manual is concluded with a rather extensive, but complete example of random access operation. The program listed below performs the simple function of reading or writing random records upon command from the terminal. Given that the program has been created, assembled, and placed into a file labelled RANDOM.COM, the CCP level command:

RANDOM X.DAT

starts the test program. The program looks for a file by the name X.DAT (in this particular case) and, if found, proceeds to prompt the console for input. If not found, the file is created before the prompt is given. Each prompt takes the form

next command?

and is followed by operator input, terminated by a carriage return. The input commands take the form

nW nR Q

where n is an integer value in the range 0 to 65535, and W, R, and Q are simple command characters corresponding to random write, random read, and quit processing, respectively. If the W command is issued, the RANDOM program issues the prompt

type data:

The operator then responds by typing up to 127 characters, followed by a carriage return. RANDOM then writes the character string into the X.DAT file at record n. If the R command is issued, RANDOM reads record number n and displays the string value at the console. If the Q command is issued, the X.DAT file is closed, and the program returns to the console command processor. In the interest of brevity, the only error message is

error, try again

The program begins with an initialization section where the input file is opened or created, followed by a continuous loop at the label "ready" where the individual commands are interpreted. The default file control block at 005CH and the default buffer at 0080H are used in all disk operations. The utility subroutines then follow, which contain the principal input line processor, called "readc." This particular program shows the elements of random access processing, and can be used as the basis for further program development.

```

;*****
;*
;* sample random access program for cp/m 2.0
;*
;*****
0100      org.      100h      ;base of tpa
;
0000 =    reboot   equ      0000h  ;system reboot
0005 =    bdos     equ      0005h  ;bdos entry point
;
0001 =    coninp   equ      1       ;console input function
0002 =    conout   equ      2       ;console output function
0009 =    pstring  equ      9       ;print string until '$'
000a =    rstring  equ      10      ;read console buffer
000c =    version  equ      12      ;return version number
000f =    openf    equ      15      ;file open function
0010 =    closef   equ      16      ;close function
0016 =    makef    equ      22      ;make file function
0021 =    readr    equ      33      ;read random
0022 =    writerr  equ      34      ;write random
;
005c =    fcb      equ      005ch   ;default file control block
007d =    ranrec   equ      fcb+33   ;random record position
007f =    ranovf   equ      fcb+35   ;high order (overflow) byte
0080 =    buff     equ      0080h   ;buffer address
;
000d =    cr       equ      0dh      ;carriage return
000a =    lf       equ      0ah      ;line feed
;
;*****
;*
;* load SP, set-up file for random access
;*
;*****

```

```

0100 31bc0      lxi      sp,stack
;
;
0103 0e0c      mvi      c,version
0105 cd050     call     bdos
0108 fe20      cpi      20h      ;version 2.0 or better?
010a d2160     jnc      versok
;
010d 111b0     lxi      d,badver
0110 cdda0     call     print
0113 c3000     jmp      reboot
;
versok:
;
0116 0e0f      mvi      c,openf ;open default fcb
0118 115c0     lxi      d,fcf
011b cd050     call     bdos
011e 3c        inr      a      ;err 255 becomes zero
011f c2370     jnz      ready
;
0122 0e16      mvi      c,makef
0124 115c0     lxi      d,fcf
0127 cd050     call     bdos
012a 3c        inr      a      ;err 255 becomes zero
012b c2370     jnz      ready
;
012e 113a0     lxi      d,nospace
0131 cdda0     call     print
0134 c3000     jmp      reboot ;back to ccp
;
;*****
;*
;* loop back to "ready" after each command      *
;*
;*****
;
ready:
;
0137 cde50     call     readcom ;read next command
013a 227d0     shld    ranrec ;store input record#
013d 217f0     lxi      h,ranovf
0140 3600      mvi      m,0      ;clear high byte if set
0142 fe51      cpi      'Q'      ;quit?
0144 c2560     jnz      notq
;
0147 0e10      mvi      c,closef
0149 115c0     lxi      d,fcf
014c cd050     call     bdos
014f 3c        inr      a      ;err 255 becomes 0
0150 cab90     jz      error ;error message, retry
0153 c3000     jmp      reboot ;back to ccp
;
;*****
;*
;* end of quit command, process write          *
;*
;*****
notq:
;
0156 fe57      cpi      'W'
0158 c2890     jnz      notw
;
;
015b 114d0     lxi      d,datmsg
015e cdda0     call     print ;data prompt
0161 0e7f      mvi      c,127 ;up to 127 characters
0163 21800     lxi      h,buff ;destination

```

```

loop:   ;read next character to buff
0166 c5   push   b       ;save counter
0167 e5   push   h       ;next destination
0168 cdc20 call   getchr  ;character to a
016b e1   pop    h       ;restore counter
016c c1   pop    b       ;restore next to fill
016d fe0d cpi    cr      ;end of line?
016f ca780 jz     erloop
;
0172 77   mov    m,a
0173 23   inx   h       ;next to fill
0174 0d   dcr   c       ;counter goes down
0175 c2660 jnz   rloop   ;end of buffer?
erloop:
;
0178 3600 mvi   m,0
;
;
017a 0e22 mvi   c,writer
017c 115c0 lxi   d,fcbl
017f cd050 call  bdos
0182 b7   ora   a       ;error code zero?
0183 c2b90 jnz   error   ;message if not
0186 c3370 jmp   ready   ;for another record
;
;*****
;*
;* end of write command, process read
;*
;*****
notw:
;
0189 fe52 cpi   'R'
018b c2b90 jnz   error   ;skip if not
;
;
018e 0e21 mvi   c,readr
0190 115c0 lxi   d,fcbl
0193 cd050 call  bdos
0196 b7   ora   a       ;return code 00?
0197 c2b90 jnz   error
;
;
019a cdcf0 call  crlf   ;new line
019d 0e80 mvi   c,128  ;max 128 characters
019f 21800 lxi   h,buff ;next to get
wloop:
01a2 7e   mov    a,m   ;next character
01a3 23   inx   h     ;next to get
01a4 e67f  ani   7fh   ;mask parity
01a6 ca370 jz     ready ;for another command if 00
01a9 c5   push  b     ;save counter
01aa e5   push  h     ;save next to get
01ab fe20 cpi   ' '   ;graphic?
01ad d4c80 cnc   putchr ;skip output if not
01b0 e1   pop    h
01b1 c1   pop    b
01b2 0d   dcr   c     ;count=count-1
01b3 c2a20 jnz   wloop
01b6 c3370 jmp   ready
;
;*****
;*
;* end of read command, all errors end-up here
;*
;*****
error:
01b9 11590 lxi   d,errmsg
01bc cdda0 call  print
01bf c3370 jmp   ready

```

```

;
;*****
;*
;* utility subroutines for console i/o
;*
;*****
getchr:
    ;read next console character to a
    mvi    c,coninp
    01c2 0e01    call    bdos
    01c4 cd050   ret
    01c7 c9

;
putchr:
    ;write character from a to console
    mvi    c,conout
    01c8 0e02    mov     e,a    ;character to send
    01ca 5f      call    bdos   ;send character
    01cb cd050   ret
    01ce c9

;
crlf:
    ;send carriage return line feed
    mvi    a,cr    ;carriage return
    01cf 3e0d    call    putchr
    01d1 cdc80   mvi    a,lf    ;line feed
    01d4 3e0a    call    putchr
    01d6 cdc80   ret
    01d9 c9

;
print:
    ;print the buffer addressed by de until $
    push   d
    01da d5      call    crlf
    01db cdcf0   pop    d        ;new line
    01de dl      mvi    c,pstring
    01df 0e09    call    bdos   ;print the string
    01e1 cd050   ret
    01e4 c9

;
readcom:
    ;read the next command line to the conbuf
    lxi    d,prompt
    01e5 116b0   call    print  ;command?
    01e8 cdda0   mvi    c,rstring
    01eb 0e0a    lxi    d,conbuf
    01ed 117a0   call    bdos   ;read command line
    01f0 cd050   ; command line is present, scan it

    01f3 21000   lxi    h,0    ;start with 0000
    01f6 117c0   lxi    d,conlin;command line
    01f9 la      readc: ldax   d        ;next command character
    01fa 13      inx    d        ;to next command position
    01fb b7      ora    a        ;cannot be end of command
    01fc c8      rz

    ; not zero, numeric?
    01fd d630   sui    '0'
    01ff fe0a   cpi    10     ;carry if numeric
    0201 d2130   jnc    endrd
    ; add-in next digit
    0204 29     dad    h        ;*2
    0205 4d     mov    c,l
    0206 44     mov    b,h     ;bc = value * 2
    0207 29     dad    h        ;*4
    0208 29     dad    h        ;*8
    0209 09     dad    b        ;*2 + *8 = *10
    020a 85     add    l        ;+digit
    020b 6f     mov    l,a
    020c d2f90   jnc    readc   ;for another char
    020f 24     inr    h        ;overflow
    0210 c3f90   jmp    readc   ;for another char
    endrd:

;
    end of read, restore value in a
    0213 c630   adi    '0'     ;command
    0215 fe61   cpi    'a'     ;translate case?

```

```

0217 d8          rc
;               lower case, mask lower case bits
0218 e65f       ani      101$1111b
021a c9         ret
;
;*****
;*
;* string data area for console messages
;*
;*****
badver:
021b 536f79     db      'sorry, you need cp/m version 2$'
nospace:
023a 4e6f29     db      'no directory space$'
datmsg:
024d 547970     db      'type data: $'
errmsg:
0259 457272     db      'error, try again.$'
prompt:
026b 4e6570     db      'next command? $'
;
;*****
;*
;* fixed and variable data area
;*
;*****
027a 21        conbuf: db      conlen ;length of console buffer
027b          consiz: ds      1      ;resulting size after read
027c          conlin: ds     32     ;length 32 buffer
0021 =        conlen equ     $-consiz
;
029c          ds      32      ;16 level stack
stack:
02bc          end

```

Again, major improvements could be made to this particular program to enhance its operation. In fact, with some work, this program could evolve into a simple data base management system. One could, for example, assume a standard record size of 128 bytes, consisting of arbitrary fields within the record. A program, called GETKEY, could be developed which first reads a sequential file and extracts a specific field defined by the operator. For example, the command

GETKEY NAMES.DAT LASTNAME 10 20

would cause GETKEY to read the data base file NAMES.DAT and extract the "LASTNAME" field from each record, starting at position 10 and ending at character 20. GETKEY builds a table in memory consisting of each particular LASTNAME field, along with its 16-bit record number location within the file. The GETKEY program then sorts this list, and writes a new file, called LASTNAME.KEY, which is an alphabetical list of LASTNAME fields with their corresponding record numbers. (This list is called an "inverted index" in information retrieval parlance.)

Rename the program shown above as QUERY, and massage it a bit so that it reads a sorted key file into memory. The command line might appear as:

QUERY NAMES.DAT LASTNAME.KEY

Instead of reading a number, the QUERY program reads an alphanumeric string which is a particular key to find in the NAMES.DAT data base. Since the LASTNAME.KEY list is sorted, you can find a particular entry quite rapidly by performing a “binary search,” similar to looking up a name in the telephone book. That is, starting at both ends of the list, you examine the entry halfway in between and, if not matched, split either the upper half or the lower half for the next search. You’ll quickly reach the item you’re looking for (in $\log_2(n)$ steps) where you’ll find the corresponding record number. Fetch and display this record at the console, just as we have done in the program shown above.

At this point you’re just getting started. With a little more work, you can allow a fixed grouping size which differs from the 128 byte record shown above. This is accomplished by keeping track of the record number as well as the byte offset within the record. Knowing the group size, you randomly access the record containing the proper group, offset to the beginning of the group within the record read sequentially until the group size has been exhausted.

Finally, you can improve QUERY considerably by allowing boolean expressions which compute the set of records which satisfy several relationships, such as a LASTNAME between HARDY and LAUREL, and an AGE less than 45. Display all the records which fit this description. Finally, if your lists are getting too big to fit into memory, randomly access your key files from the disk as well. One note of consolation after all this work: if you make it through the project, you’ll have no more need for this manual!

System Function Summary

FUNC	FUNCTION NAME	INPUT PARAMETERS	OUTPUT RESULTS
0	System Reset	none	none
1	Console Input	none	A = char
2	Console Output	E = char	none
3	Reader Input	none	A = char
4	Punch Output	E = char	none
5	List Output	E = char	none
6	Direct Console I/O	see def	see def
7	Get I/O Byte	none	A = IOBYTE
8	Set I/O Byte	E = IOBYTE	none
9	Print String	DE = .Buffer	none
10	Read Console Buffer	DE = .Buffer	see def
11	Get Console Status	none	A = 00/FF
12	Return Version Number	none	HL = Version*
13	Reset Disk System	none	see def
14	Select Disk	E = Disk Number	see def
15	Open File	DE = .FCB	A = Dir Code
16	Close File	DE = .FCB	A = Dir Code
17	Search for First	DE = .FCB	A = Dir Code
18	Search for Next	none	A = Dir Code
19	Delete File	DE = .FCB	A = Dir Code
20	Read Sequential	DE = .FCB	A = Err Code
21	Write Sequential	DE = .FCB	A = Err Code
22	Make File	DE = .FCB	A = Dir Code
23	Rename File	DE = .FCB	A = Dir Code
24	Return Login Vector	none	HL = Login Vect*
25	Return Current Disk	none	A = Cur Disk #
26	Set DMA Address	DE = .DMA	none
27	Get Addr(Alloc)	none	HL = .Alloc
28	Write Protect Disk	none	see def
29	Get R/O Vector	none	HL = R/O Vect*
30	Set File Attributes	DE = .FCB	see def
31	Get Addr (disk parms)	none	HL = .DPB
32	Set/Get User Code	see def	see def
33	Read Random	DE = .FCB	A = Err Code
34	Write Random	DE = .FCB	A = Err Code
35	Compute File Size	DE = .FCB	r0, r1, r2
36	Set Random Record	DE = .FCB	r0, r1, r2

*Note that A = L, and B = H upon return

**ED: A CONTEXT EDITOR
FOR THE CP/M DISK SYSTEM
USER'S MANUAL**

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1. The first part of the document discusses the importance of maintaining accurate records of all transactions and activities. It emphasizes that this is essential for ensuring transparency and accountability in the organization's operations.

2. The second part outlines the various methods and tools used to collect and analyze data. This includes both traditional manual methods and modern digital technologies, highlighting the benefits of automation and data integration.

3. The third part focuses on the role of data in decision-making. It explains how data-driven insights can help identify trends, anticipate challenges, and optimize resource allocation, leading to more informed and effective strategic decisions.

4. The fourth part addresses the challenges associated with data management, such as data security, privacy concerns, and the need for skilled personnel. It offers practical solutions and best practices to mitigate these risks and ensure the integrity and confidentiality of the data.

5. The final part concludes by summarizing the key findings and recommendations. It stresses the ongoing nature of data management and the need for continuous improvement and adaptation to changing technological and organizational requirements.

Introduction to ED

ED is the context editor for CP/M, and is used to create and alter CP/M source files. ED is initiated in CP/M by typing

$$\text{ED } \left\{ \begin{array}{l} \langle \text{filename} \rangle \\ \langle \text{filename} \rangle \cdot \langle \text{filetype} \rangle \end{array} \right\}$$

In general, ED reads segments of the source file given by $\langle \text{filename} \rangle$ or $\langle \text{filename} \rangle \cdot \langle \text{filetype} \rangle$ into central memory, where the file is manipulated by the operator, and subsequently written back to disk after alterations. If the source file does not exist before editing, it is created by ED and initialized to empty. The overall operation of ED is shown in Figure 1.

ED Operation

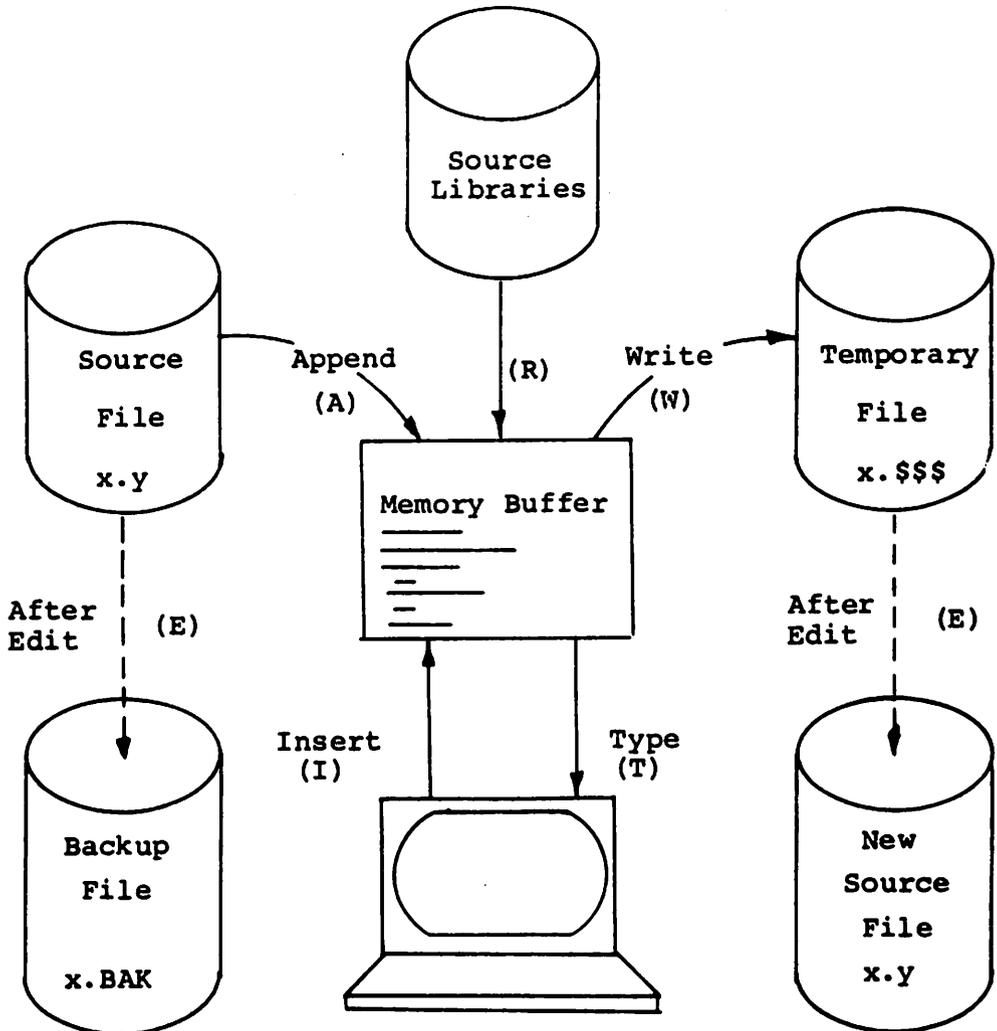
ED operates upon the source file, denoted in Figure 1 by $x.y$, and passes all text through a memory buffer where the text can be viewed or altered (the number of lines which can be maintained in the memory buffer varies with the line length, but has a total capacity of about 6000 characters in a 16K CP/M system). Text material which has been edited is written onto a temporary work file under command of the operator. Upon termination of the edit, the memory buffer is written to the temporary file, followed by any remaining (unread) text in the source file. The name of the original file is changed from $x.y$ to $x.BAK$ so that the most recent previously edited source file can be reclaimed if necessary (see the CP/M commands ERASE and RENAME). The temporary file is changed from $x.***$ to $x.y$ which becomes the resulting edited file.

The memory buffer is logically between the source file and working file as shown in Figure 2.

Text Transfer Functions

Given that n is an integer value in the range 0 through 65535, the following ED commands transfer lines of text from the source file through the memory buffer to the temporary (and eventually final) file:

Figure 1. Overall ED Operation



Note: the ED program accepts both lower and upper case ASCII characters as input from the console. Single letter commands can be typed in either case. The U command can be issued to cause ED to translate lower case alphabetic characters to upper case as characters are filled to the memory buffer from the console. Characters are echoed as typed without translation, however. The -U command causes ED to revert to "no translation" mode. ED starts with an assumed -U in effect.

Figure 2. Memory Buffer Organization

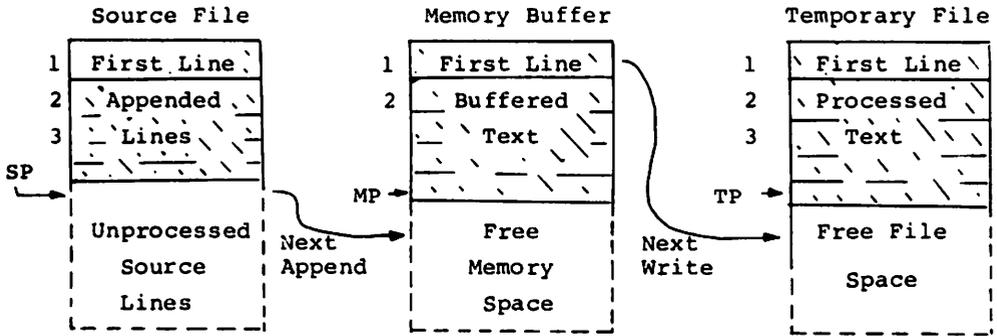
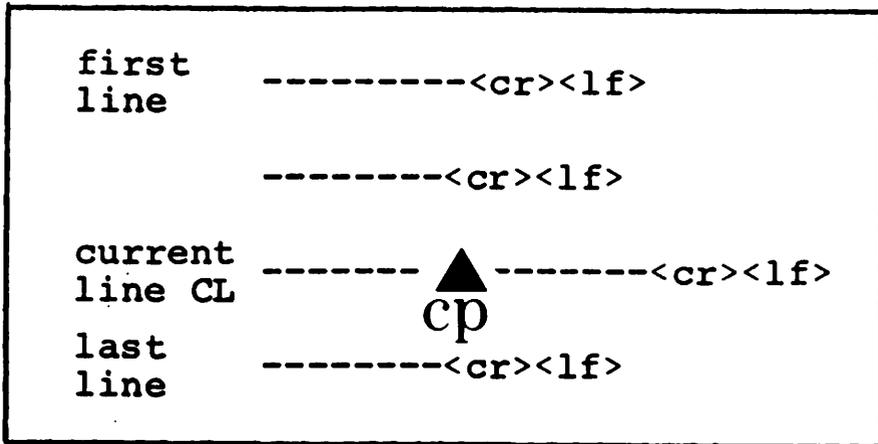


Figure 3. Logical Organization of Memory Buffer

Memory Buffer



- nA<cr>*** Append the next n unprocessed source lines from the source file at SP to the end of the memory buffer at MP. Increment SP and MP by n.
- nW<cr>** Write the first n lines of the memory buffer to the temporary file free space. Shift the remaining lines n + 1 through MP to the top of the memory buffer. Increment TP by n.
- E<cr>** End the edit. Copy all buffered text to temporary file, and copy all unprocessed source lines to the temporary file. Rename files as described previously.
- H<cr>** Move to head of new file by performing automatic E command. Temporary file becomes the new source file, the memory buffer is emptied, and a new temporary file is created (equivalent to issuing an E command, followed by a reinvoation of ED using x.y as the file to edit).
- O<cr>** Return to original file. The memory buffer is emptied, the temporary file is deleted, and the SP is returned to position 1 of the source file. The effects of the previous editing commands are thus nullified.
- Q<cr>** Quit edit with no file alterations, return to CP/M.

There are a number of special cases to consider. If the integer n is omitted in any ED command where an integer is allowed, then 1 is assumed. Thus, the commands A and W append one line and write 1 line, respectively. In addition, if a pound sign (#) is given in the place of n, then the integer 65535 is assumed (the largest value for n which is allowed). Since most reasonably sized source files can be contained entirely in the memory buffer, the command #A is often issued at the beginning of the edit to read the entire source file to memory. Similarly, the command #W writes the entire buffer to the temporary file. Two special forms of the A and W commands are provided as a convenience. The command 0A fills the current memory buffer to at least half-full, while 0W writes lines until the buffer is at least half empty. It should also be noted that an error is issued if the memory buffer size is exceeded. The operator may then enter any command (such as W) which does not increase memory requirements. The remainder of any partial line read during the overflow will be brought into memory on the next successful append.

*<cr>represents the carriage-return key

Memory Buffer Organization

The memory buffer can be considered a sequence of source lines brought in with the A command from a source file. The memory buffer has an associated (imaginary) character pointer (CP) which moves throughout the memory buffer under command of the operator. The memory buffer appears logically as shown in Figure 3 where the dashes represent characters of the source line of indefinite length, terminated by carriage return (<cr>) and line feed (<lf>) characters, and \uparrow_{cp} represents the imaginary character pointer. Note that the CP is always located ahead of the first character of the first line, behind the last character of the last line, or between two characters. The current line CL is the source line which contains the CP.

Memory Buffer Operation

Upon initiation of ED, the memory buffer is empty (i.e., CP is both ahead and behind the first and last character). The operator may either append lines (A command) from the source file, or enter the lines directly from the console with the insert command

I<cr>

ED then accepts any number of input lines, where each line terminates with a <cr> (the <lf> is supplied automatically), until a control-z (denoted by ↑z) is typed by the operator. The CP is positioned after the last character entered. The sequence

```
I<cr>
NOW IS THE<cr>
TIME FOR<cr>
ALL GOOD MEN<cr>
↑z
```

leaves the memory buffer as shown below

```
NOW IS THE<cr><lf>
TIME FOR<cr><lf>
ALL GOOD MEN<cr><lf> $\uparrow_{cp}$ 
```

Various commands can then be issued which manipulate the CP or display source text in the vicinity of the CP. The commands shown below with a preceding n indicate that an optional unsigned value can be specified. When preceded by ±, the command can be unsigned, or have an optional preceding plus or minus sign. As before, the pound sign (#) is replaced by 65535. If an integer n is optional, but not supplied, then n = 1 is assumed. Finally, if a plus sign is optional, but none is specified, then + is assumed.

- ± B⟨cr⟩** move CP to beginning of memory buffer if + , and to bottom if -.
- ± nC⟨cr⟩** move CP by ± n characters (toward front of buffer if +), counting the ⟨cr⟩⟨lf⟩ as two distinct characters.
- ± nD⟨cr⟩** delete n characters ahead of CP if plus and behind CP if minus.
- ± nK⟨cr⟩** kill (i.e. remove) ± n lines of source text using CP as the current reference. If CP is not at the beginning of the current line when K is issued, then the characters before CP remain if + is specified, while the characters after CP remain if - is given in the command.
- ± nL⟨cr⟩** if n = 0, move CP to the beginning of the current line (if it is not already there). If n ≠ 0, first move the CP to the beginning of the current line, and then move it to the beginning of the line which is n lines down (if +) or up (if -). The CP will stop at the top or bottom of the memory buffer if too large a value is specified.
- ± nT⟨cr⟩** If n = 0 then type the contents of the current line up to CP. If n = 1 then type the contents of the current line from CP to the end of the line. If n > 1 then type the current line along with n-1 lines which follow, if + is specified. Similarly, if n > 1 and - is given, type the previous n lines, up to the CP. The break key can be depressed to abort long type-outs.
- ± n⟨cr⟩** equivalent to ± nLT, which moves up or down and types a single line.

Command Strings

Any number of commands can be typed contiguously (up to the capacity of the CP/M console buffer), and are executed only after the ⟨cr⟩ is typed. Thus, the operator may use the CP/M console command functions to manipulate the input command.

- Rubout** remove the last character
- Control-X** delete the entire line
- Control-C** re-initialize the CP/M System

Control-E return carriage for long lines without transmitting buffer
(max 128 chars)

Suppose the memory buffer contains the characters shown in the previous section, with the CP following the last character of the buffer. The command strings shown below produce the results shown to the right.

Command String	Effect	Resulting Memory Buffer
B2T<cr>	move to beginning of buffer and type 2 lines: "NOW IS THE TIME FOR"	▲ _{cp} NOW IS THE<cr><lf> TIME FOR<cr><lf> ALL GOOD MEN<cr><lf>
5C0T<cr>	move CP 5 characters and type the beginning of the line "NOW I"	NOW I ▲ _{cp} S THE <cr><lf>
2L-T<cr>	move two lines down and type previous line "TIME FOR"	NOW IS THE <cr><lf> TIME FOR<cr><lf> ▲ _{cp} ALL GOOD MEN<cr><lf>
-L#K<cr>	move up one line, delete 65535 lines which follow	NOW IS THE<cr><lf>▲ _{cp}
I<cr> TIME TO<cr> INSERT<cr> ↑z	insert two lines of text	NOW IS THE<cr><lf> TIME TO<cr><lf> INSERT<cr><lf>▲ _{cp}
-2L#T<cr>	move up two lines, and type 65535 lines ahead of CP "NOW IS THE"	NOW IS THE<cr><lf>▲ _{cp} TIME TO<cr><lf> INSERT<cr><lf>
<cr>	move down one line and type one line "INSERT"	NOW IS THE<cr><lf> TIME TO<cr><lf>▲ _{cp} INSERT <cr><lf>

Text Search and Alteration

ED also has a command which locates strings within the memory buffer. The command takes the form

$$n^F c_1 c_2 \dots c_k \left\{ \begin{array}{c} \langle cr \rangle \\ \uparrow z \end{array} \right\}$$

where c_1 through c_k represent the characters to match followed by either a $\langle cr \rangle$ or control $-z$.* ED starts at the current position of CP and attempts to match all k characters. The match is attempted n times, and if successful, the CP is moved directly after the character c_k . If the n matches are not successful, the CP is not moved from its initial position. Search strings can include $\uparrow l$ (control-l), which is replaced by the pair of symbols $\langle cr \rangle \langle lf \rangle$.

The following commands illustrate the use of the F command:

Command String	Effect	Resulting Memory Buffer
B#T $\langle cr \rangle$	move to beginning and type entire buffer	\uparrow_{cp} NOW IS THE $\langle cr \rangle \langle lf \rangle$ TIME FOR $\langle cr \rangle \langle lf \rangle$ ALL GOOD MEN $\langle cr \rangle \langle lf \rangle$
FS T $\langle cr \rangle$	find the end of the string "S T"	NOW IS T \uparrow_{cp} HE $\langle cr \rangle \langle lf \rangle$
FI $\uparrow z$ 0TT	find the next "I" and type to the CP then type the remainder of the current line: "TIME FOR"	NOW IS THE $\langle cr \rangle \langle lf \rangle$ T \uparrow_{cp} I ME FOR $\langle cr \rangle \langle lf \rangle$ ALL GOOD MEN $\langle cr \rangle \langle lf \rangle$

An abbreviated form of the insert command is also allowed, which is often used in conjunction with the F command to make simple textual changes. The form is:

$$I c_1 c_2 \dots c_n \uparrow z \quad \text{or} \\ I c_1 c_2 \dots c_n \langle cr \rangle$$

where c_1 through c_n are characters to insert. If the insertion string is terminated by a $\uparrow z$, the characters c_1 through c_n are inserted directly following the CP, and the CP is moved directly after character c_n . The action is the same if the command is followed by a $\langle cr \rangle$ except that a $\langle cr \rangle \langle lf \rangle$ is automatically inserted into the text following character c_n . Consider the following command sequences as examples of the F and I commands:

*The control-z is used if additional commands will be typed following the $\uparrow z$.

Command String	Effect	Resulting Memory Buffer
BITHIS IS ↑z⟨cr⟩	Insert "THIS IS" at the beginning of the text	THIS IS ^{cp} ▲ NOW THE⟨cr⟩⟨lf⟩ TIME FOR ⟨cr⟩⟨lf⟩ ALL GOOD MEN⟨cr⟩⟨lf⟩
FTIME↑z-4DIPLACE↑z⟨cr⟩	find "TIME" and delete it; then insert "PLACE"	THIS IS NOW THE⟨cr⟩⟨lf⟩ PLACE ^{cp} ▲ FOR⟨cr⟩⟨lf⟩ ALL GOOD MEN⟨cr⟩⟨lf⟩
3FO↑z-3D5DICHANGES↑⟨cr⟩	find third occurrence of "O" (i.e. the second "O" in GOOD), delete previous 3 characters; then insert "CHANGES"	THIS IS NOW THE⟨cr⟩⟨lf⟩ PLACE FOR⟨cr⟩⟨lf⟩ ALL CHANGES ^{cp} ▲⟨cr⟩⟨lf⟩
-8CISOURCE⟨cr⟩	move back 8 characters and insert the line "SOURCE⟨cr⟩⟨lf⟩"	THIS IS NOW THE⟨cr⟩⟨lf⟩ PLACE FOR⟨cr⟩⟨lf⟩ ALL SOURCE⟨cr⟩⟨lf⟩ ^{cp} ▲CHANGES⟨cr⟩⟨lf⟩

ED also provides a single command which combines the F and I commands to perform simple string substitutions. The command takes the form

$$n S c_1 c_2 \dots c_k \uparrow z d_1 d_2 \dots d_m \left\{ \begin{array}{l} \langle cr \rangle \\ \uparrow z \end{array} \right\}$$

and has exactly the same effect as applying the command string

$$F c_1 c_2 \dots c_k \uparrow z -k D I d_1 d_2 \dots d_m \left\{ \begin{array}{l} \langle cr \rangle \\ \uparrow z \end{array} \right\}$$

a total of n times. That is, ED searches the memory buffer starting at the current position of CP and successively substitutes the second string for the first string until the end of buffer, or until the substitution has been performed n times.

As a convenience, a command similar to F is provided by ED which automatically appends and writes lines as the search proceeds. The form is

$$n N c_1 c_2 \dots c_k \left\{ \begin{array}{l} \langle cr \rangle \\ \uparrow z \end{array} \right\}$$

which searches the entire source file for the n th occurrence of the string $c_1c_2 \dots c_k$ (recall that **F** fails if the string cannot be found in the current buffer). The operation of the **N** command is precisely the same as **F** except in the case that the string cannot be found within the current memory buffer. In this case, the entire memory contents is written (i.e., an automatic **#W** is issued). Input lines are then read until the buffer is at least half full, or the entire source file is exhausted. The search continues in this manner until the string has been found n times, or until the source file has been completely transferred to the temporary file.

A final line editing function, called the juxtaposition command takes the form

$$n J c_1c_2 \dots c_k \uparrow z d_1d_2 \dots d_m \uparrow z e_1e_2 \dots e_q \left\{ \begin{array}{l} \langle cr \rangle \\ \uparrow z \end{array} \right\}$$

with the following action applied n times to the memory buffer: search from the current CP for the next occurrence of the string $c_1c_2 \dots c_k$. If found, insert the string $d_1, d_2 \dots, d_m$, and move CP to follow d_m . Then delete all characters following CP up to (but not including) the string e_1, e_2, \dots, e_q , leaving CP directly after d_m . If e_1, e_2, \dots, e_q cannot be found, then no deletion is made. If the current line is

\uparrow_{cp} NOW IS THE TIME $\langle cr \rangle \langle lf \rangle$

Then the command

JW $\uparrow z$ WHAT $\uparrow z \uparrow l$ $\langle cr \rangle$

Results in

NOW WHAT \uparrow_{cp} $\langle cr \rangle \langle lf \rangle$

(Recall that $\uparrow l$ represents the pair $\langle cr \rangle \langle lf \rangle$ in search and substitution strings).

It should be noted that the number of characters allowed by ED in the **F**, **S**, **N**, and **J** commands is limited to 100 symbols.

Source Libraries

ED also allows the inclusion of source libraries during the editing process with the **R** command. The form of this command is

R f₁f₂ . . . f_n↑z or

R f₁f₂ . . . f_n<cr>

where f₁f₂ . . . f_n is the name of a source file on the disk with an assumed filetype of 'LIB'. ED reads the specified file, and places the characters into the memory buffer after CP, in a manner similar to the I command. Thus, if the command

RMACRO<cr>

is issued by the operator, ED reads from the file MACRO.LIB until the end-of-file, and automatically inserts the characters into the memory buffer.

Repetitive Command Execution

The macro command M allows the ED user to group ED commands together for repeated evaluation. The M command takes the form:

$$n M c_1 c_2 \dots c_k \left\{ \begin{array}{l} \langle cr \rangle \\ \uparrow z \end{array} \right\}$$

where c₁c₂ . . . c_k represent a string of ED commands, not including another M command. ED executes the command string n times if n>1. If n = 0 or 1, the command string is executed repetitively until an error condition is encountered (e.g., the end of the memory buffer is reached with an F command).

As an example, the following macro changes all occurrences of GAMMA to DELTA within the current buffer, and types each line which is changed:

MFGAMMA↑z-5DIDELTA↑z0TT<cr>

or equivalently

MSGAMMA↑zDELTA↑z0TT<cr>

ED Error Conditions

On error conditions, ED prints the last character read before the error, along with an error indicator:

? unrecognized command

- > memory buffer full (use one of the commands D, K, N, S, or W to remove characters), F, N, or S strings too long.
- # cannot apply command the number of times specified (e.g., in F command)
- O cannot open LIB file in R command

Cyclic redundancy check (CRC) information is written with each output record under CP/M in order to detect errors on subsequent read operations. If a CRC error is detected, CP/M will type

PERM ERR DISK d

where d is the currently selected drive (A, B, . . .). The operator can choose to ignore the error by typing any character at the console (in this case, the memory buffer data should be examined to see if it was incorrectly read), or the user can reset the system and reclaim the backup file, if it exists. The file can be reclaimed by first typing the contents of the BAK file to ensure that it contains the proper information:

TYPE x.BAK<cr>

where x is the file being edited. Then remove the primary file:

ERA x.y<cr>

and rename the BAK file:

REN x.y = x.BAK<cr>

The file can then be re-edited, starting with the previous version.

Summary of Control Characters

The following table summarizes the Control characters and commands available in ED:

Control Character	Function
↑c	system reboot
↑e	physical <cr><lf> (not actually entered in command)

↑i	logical tab (cols 1, 8, 15, . . .)
↑l	logical <cr><lf> in search and substitute strings
↑x	line delete
↑z	string terminator
rubout	character delete
break	discontinue command (e.g., stop typing)

Summary of ED Commands

Command	Function
nA	append lines
± B	begin bottom of buffer
± nC	move character positions
± nD	delete characters
E	end edit and close files (normal end)
nF	find string
H	end edit, close and reopen files
I	insert characters
nJ	place strings in juxtaposition
± nK	kill lines
± nL	move down/up lines
nM	macro definition
nN	find next occurrence with autoscan

O	return to original file
± nP	move and print pages
Q	quit with no file changes
R	read library file
nS	substitute strings
± nT	type lines
± U	translate lower to upper case if U, no translation if -U
nW	write lines
nZ	sleep
± n⟨cr⟩	move and type (± nLT)

ED Text Editing Commands

The ED context editor contains a number of commands which enhance its usefulness in text editing. The improvements are found in the addition of line numbers, free space interrogation, and improved error reporting.

The context editor issued with CP/M produces absolute line number prefixes when the "V" (Verify Line Numbers) command is issued. Following the V command, the line number is displayed ahead of each line in the format:

nnnnn:

where nnnnn is an absolute line number in the range 1 to 65535. If the memory buffer is empty, or if the current line is at the end of the memory buffer, then nnnnn appears as 5 blanks.

The user may reference an absolute line number by preceding any command by a number followed by a colon, in the same format as the line number display. In this case, the ED program moves the current line reference to the absolute line number, if the line exists in the current memory buffer. Thus the command

345:T

is interpreted as “move to absolute line 345, and type the line.” Note that absolute line numbers are produced only during the editing process, and are not recorded with the file. In particular, the line numbers will change following a deleted or expanded section of text.

The user may also reference an absolute line number as a backward or forward distance from the current line by preceding the absolute line number by a colon. Thus, the command

:400T

is interpreted as “type from the current line number through the line whose absolute number is 400.” Combining the two line reference forms, the command

345::400T

for example, is interpreted as “move to absolute line 345, then type through absolute line 400.” Note that absolute line references of this sort can precede any of the standard ED commands.

A special case of the V command, “0V,” prints the memory buffer statistics in the form:

free/total

where “free” is the number of free bytes in the memory buffer (in decimal), and “total” is the size of the memory buffer.

ED also includes a “block move” facility implemented through the “X” (Xfer) command. The form

nX

transfers the next n lines from the current line to a temporary file called

X\$\$\$\$\$\$\$.LIB

which is active only during the editing process. In general, the user can reposition the current line reference to any portion of the source file and transfer lines to the temporary file. The transferred lines accumulate one after another in this file, and can be retrieved by simply typing:

R

which is the trivial case of the library read command. In this case, the entire transferred set of lines is read into the memory buffer. Note that the X command does not remove the transferred lines from the memory buffer, although a K command can be used directly after the X, and the R command does not empty the transferred line file. That is, given that a set of lines has been transferred with the X command, they can be re-read any number of times back into the source file. The command

OX

is provided, however, to empty the transferred line file.

Note that upon normal completion of the ED program through Q or E, the temporary LIB file is removed. If ED is aborted through Control-C, the LIB file will exist if lines have been transferred, but will generally be empty (a subsequent ED invocation will erase the temporary file).

Due to common typographical errors, ED requires several potentially disastrous commands to be typed as single letters, rather than in composite commands. The commands

E (end), H (head), O (original), Q (quit)

must be typed as single letter commands.

ED also prints error messages in the form

BREAK "x" AT c

where x is the error character, and c is the command where the error occurred.

**CP/M ASSEMBLER (ASM)
USER'S GUIDE**

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Dear Sir,

I have the honor to acknowledge the receipt of your letter of the 14th inst. in relation to the above mentioned matter. The same has been referred to the proper authorities for their consideration. I am sorry that I cannot give you a more definite answer at this time, but I will be glad to advise you as soon as a final decision has been reached.

Very respectfully,
[Signature]

[Name]
[Title]

[Address]

[City, State]

[Phone Number]

[Additional Information]

[Closing Remarks]

[Final Signatures]

Introduction

The CP/M assembler reads assembly language source files from the diskette, and produces 8080 machine language in Intel hex format. The CP/M assembler is initiated by typing

ASM filename

or

ASM filename.parms

In both cases, the assembler assumes there is a file on the diskette with the name

filename.ASM

which contains an 8080 assembly language source file. The first and second forms shown above differ only in that the second form allows parameters to be passed to the assembler to control source file access and hex and print file destinations.

In either case, the CP/M assembler loads, and prints the message

CP/M ASSEMBLER VER n.n

where n.n is the current version number. In the case of the first command, the assembler reads the source file with assumed file type "ASM" and creates two output files.

filename.HEX

and

filename.PRN

The "HEX" file contains the machine code corresponding to the original program in Intel hex format, and the "PRN" file contains an annotated listing showing generated machine code, error flags, and source lines. If errors occur during translation, they will be listed in the PRN file as well as at the console.

The second command form can be used to redirect input and output files from their defaults. In this case, the "parms" portion of the command is a three letter group which specifies the origin of the source file, the destination of the hex file, and the destination of the print file. The form is

filename.p1p2p3

where p1, p2, and p3 are single letters

- p1: A,B, ..., Y designates the disk name which contains the source file
- p2: A,B, ..., Y designates the disk name which will receive the hex file
Z skips the generation of the hex file
- p3: A,B, ..., Y designates the disk name which will receive the print file
X places the listing at the console
Z skips generation of the print file

Thus, the command

ASM X.AAA

indicates that the source file (X.ASM) is to be taken from disk A, and that the hex (X.HEX) and the print (X.PRN) files are to be created also on disk A. This form of the command is implied if the assembler is run from disk A. That is, given that the operator is currently addressing disk A, the above command is equivalent to

ASM X

The command

ASM X.ABX

indicates that the source file is to be taken from disk A, the hex file is placed on disk B, and the listing file is to be sent to the console. The command

ASM X.BZZ

takes the source file from disk B, and skips the generation of the hex and print files. (This command is useful for fast execution of the assembler to check program syntax.)

The source program format is compatible with both the Intel 8080 assembler (macros are not currently implemented in the CP/M assembler, however), as well as the Processor Technology Software Package #1 assembler. That is, the CP/M assembler accepts source programs written in either format. There are certain extensions in the CP/M assembler which make it somewhat easier to use. These extensions are described below.

Program Format

An assembly language program acceptable as input to the assembler consists of a sequence of statements of the form

```
line# label operation operand ;comment
```

where any or all of the fields may be present in a particular instance. Each assembly language statement is terminated with a carriage return and line feed (the line feed is inserted automatically by the ED program), or with the character "!" which is treated as an end-of-line by the assembler (thus, multiple assembly language statements can be written on the same physical line if separated by exclamation symbols).

The line# is an optional decimal integer value representing the source program line number, which is allowed on any source line to maintain compatibility with the Processor Technology format. In general, these line numbers will be inserted if a line-oriented editor is used to construct the original program, and thus ASM ignores this field if present.

The label field takes the form

```
identifier
```

or

```
identifier:
```

and is optional, except where noted in particular statement types. The identifier is a sequence of alphanumeric characters (alphabetic and numbers), where the first character is alphabetic. Identifiers can be freely used by the programmer to label elements such as program steps and assembler directives, but cannot exceed 16 characters in length. All characters are significant in an identifier, except for the embedded dollar symbol (\$) which can be used to improve readability of the name. Further, all lower case alphabetic characters are treated as if they were upper case. Note that the ":" following the identifier in a label is optional (to maintain compatibility between Intel and Processor Technology). Thus, the following are all valid instances of labels

```
x          x y      long$name  
x :        y x 1 :  longer$name$data:  
X 1 Y 2 X 1 x 2  x234$5678$9012$3456:
```

The operation field contains either an assembler directive, or pseudo operation, or an 8080 machine operation code. The pseudo operations and machine operation codes are described below.

The operand field of the statement, in general, contains an expression formed out of constants and labels, along with arithmetic and logical operations on these elements. Again, the complete details of properly formed expressions are given below.

The comment field contains arbitrary characters following the “;” symbol until the next real or logical end-of-line. These characters are read, listed, and otherwise ignored by the assembler. In order to maintain compatibility with the Processor Technology assembler, the CP/M assembler also treats statements which begin with a “*” in column one as comment statements, which are listed and ignored in the assembly process. Note that the Processor Technology assembler has the side effect in its operation of ignoring the characters after the operand field has been scanned. This causes an ambiguous situation when attempting to be compatible with Intel’s language, since arbitrary expressions are allowed in this case. Hence, programs which use this side effect to introduce comments, must be edited to place a “;” before these fields in order to assemble correctly.

The assembly language program is formulated as a sequence of statements of the above form, terminated optionally by an END statement. All statements following the END are ignored by the assembler.

Forming the Operand

In order to completely describe the operation codes and pseudo operations, it is necessary to first present the form of the operand field, since it is used in nearly all statements. Expressions in the operand field consist of simple operands (labels, constants, and reserved words), combined in properly formed subexpressions by arithmetic and logical operators. The expression computation is carried out by the assembler as the assembly proceeds. Each expression must produce a 16-bit value during the assembly. Further, the number of significant digits in the result must not exceed the intended use. That is, if an expression is to be used in a byte move immediate instruction, then the most significant 8 bits of the expression must be zero. The restrictions on the expression significance are given with the individual instructions.

Labels

As discussed above, a label is an identifier which occurs on a particular statement. In general, the label is given a value determined by the type of statement which it precedes. If the label occurs on a statement which generates machine code or reserves memory space (e.g, a MOV instruction, or a DS pseudo operation), then the label is given the value of the program address which it labels. If the label precedes an EQU or SET, then the label

is given the value which results from evaluating the operand field. Except for the SET statement, an identifier can label only one statement.

When a label appears in the operand field, its value is substituted by the assembler. This value can then be combined with other operands and operators to form the operand field for a particular instruction.

Numeric Constants

A numeric constant is a 16-bit value in one of several bases. The base, called the radix of the constant, is denoted by a trailing radix indicator. The radix indicators are

B	binary constant (base 2)
O	octal constant (base 8)
Q	octal constant (base 8)
D	decimal constant (base 10)
H	hexadecimal constant (base 16)

Q is an alternate radix indicator for octal numbers since the letter O is easily confused with the digit 0. Any numeric constant which does not terminate with a radix indicator is assumed to be a decimal constant.

A constant is thus composed as a sequence of digits, followed by an optional radix indicator, where the digits are in the appropriate range for the radix. That is binary constants must be composed of 0 and 1 digits, octal constants can contain digits in the range 0 - 7, while decimal constants contain decimal digits. Hexadecimal constants contain decimal digits as well as hexadecimal digits A (10D), B (11D), C (12D), D (13D), E (14D), and F (15D). Note that the leading digit of a hexadecimal constant must be a decimal digit in order to avoid confusing a hexadecimal constant with an identifier (a leading 0 will always suffice). A constant composed in this manner must evaluate to a binary number which can be contained within a 16-bit counter, otherwise it is truncated on the right by the assembler. Similar to identifiers, imbedded "\$" are allowed within constants to improve their readability. Finally, the radix indicator is translated to upper case if a lower case letter is encountered. The following are all valid instances of numeric constants

1234	1234D	1100B	1111\$0000\$1111\$0000B
1234H	0FFEh	3377O	33\$77\$22Q
3377o	0fe3h	1234d	0ffff

Reserved Words

There are several reserved character sequences which have predefined meanings in the operand field of a statement. The names of 8080 registers are given below, which, when encountered, produce the value shown to the right.

A	7
B	0
C	1
D	2
E	3
H	4
L	5
M	6
SP	6
PSW	6

(Again, lower case names have the same values as their upper case equivalents.) Machine instructions can also be used in the operand field, and evaluate to their internal codes. In the case of instructions which require operands, where the specific operand becomes a part of the binary bit pattern of the instruction (e.g, MOV A,B), the value of the instruction (in this case MOV) is the bit pattern of the instruction with zeroes in the optional fields (e.g, MOV produces 40H).

When the symbol "\$" occurs in the operand field (not imbedded within identifiers and numeric constants) its value becomes the address of the next instruction to generate, not including the instruction contained within the current logical line.

String Constants

String constants represent sequences of ASCII characters, and are represented by enclosing the characters within apostrophe symbols ('). All strings must be fully contained within the current physical line (thus allowing "!" symbols within strings), and must not exceed 64 characters in length. The apostrophe character itself can be included within a string by representing it as a double apostrophe (the two keystrokes"), which becomes a single apostrophe when read by the assembler. In most cases, the string length is restricted to either one or two characters (the DB pseudo operation is an exception), in which case the string becomes an 8 or 16 bit value, respectively. Two character strings become a 16-bit constant, with the second character as the low order byte, and the first character as the high order byte.

The value of a character is its corresponding ASCII code. There is no case translation within strings, and thus both upper and lower case characters can be represented. Note however, that only graphic (printing) ASCII characters are allowed within strings. Valid strings are

```
'A'      'AB'    'ab'    'c'
''''     'a''''  ''''''  ''''''
'Walla Walla Wash.'
'She said "Hello" to me.'
'I said "Hello" to her.'
```

Arithmetic and Logical Operators

The operands described above can be combined in normal algebraic notation using any combination of properly formed operands, operators, and parenthesized expressions. The operators recognized in the operand field are

a + b	unsigned arithmetic sum of a and b
a - b	unsigned arithmetic difference between a and b
+ b	unary plus (produces b)
- b	unary minus (identical to 0 - b)
a * b	unsigned magnitude multiplication of a and b
a / b	unsigned magnitude division of a by b
a MOD b	remainder after a / b
NOT b	logical inverse of b (all 0's become 1's, 1's become 0's), where b is considered a 16-bit value
a AND b	bit-by-bit logical and of a and b
a OR b	bit-by-bit logical or of a and b
a XOR b	bit-by-bit logical exclusive or of a and b
a SHL b	the value which results from shifting a to the left by an amount b, with zero fill
a SHR b	the value which results from shifting a to the right by an amount b, with zero fill

In each case, a and b represent simple operands (labels, numeric constants, reserved words, and one or two character strings), or fully enclosed parenthesized subexpressions such as

```
10 + 20      10h + 37Q      L1 / 3  (L2 + 4) SHR 3
('a' and 5fh) + '0'      ('B' + B) OR (PSW + M)
(1 + (2 + c)) shr (A - (B + 1))
```

Note that all computations are performed at assembly time as 16-bit unsigned operations. Thus, -1 is computed as 0-1 which results in the value 0ffffh (i.e., all 1's). The resulting expression must fit the operation code in which it is used. If, for example, the expression is used in a ADI (add

immediate) instruction, then the high order eight bits of the expression must be zero. As a result, the operation "ADI -1" produces an error message (-1 becomes 0ffffh which cannot be represented as an 8 bit value), while "ADI (-1) AND 0FFH" is accepted by the assembler since the "AND" operation zeroes the high order bits of the expression.

Precedence of Operators

As a convenience to the programmer, ASM assumes that operators have a relative precedence of application which allows the programmer to write expressions without nested levels of parentheses. The resulting expression has assumed parentheses which are defined by the relative precedence. The order of application of operators in unparenthesized expressions is listed below. Operators listed first have highest precedence (they are applied first in an unparenthesized expression), while operators listed last have lowest precedence. Operators listed on the same line have equal precedence, and are applied from left to right as they are encountered in an expression

* / MOD SHL SHR
 - +
 NOT
 AND
 OR XOR

Thus, the expressions shown to the left below are interpreted by the assembler as the fully parenthesized expressions shown to the right below

a * b + c	(a * b) + c
a + b * c	a + (b * c)
a MOD b * c SHL d	((a MOD b) * c) SHL d
a OR b AND NOT c + d SHL e	a OR (b AND (NOT (c + (d SHL e))))

Balanced parenthesized subexpressions can always be used to override the assumed parentheses, and thus the last expression above could be rewritten to force application of operators in a different order as

(a OR b) AND (NOT c) + d SHL e

resulting in the assumed parentheses

(a OR b) AND ((NOT c) + (d SHL e))

Note that an unparenthesized expression is well-formed only if the expression which results from inserting the assumed parentheses is well-formed.

Assembler Directives

Assembler directives are used to set labels to specific values during the assembly, perform conditional assembly, define storage areas, and specify starting addresses in the program. Each assembler directive is denoted by a “pseudo operation” which appears in the operation field of the line. The acceptable pseudo operations are

ORG	set the program or data origin
END	end program, optional start address
EQU	numeric “equate”
SET	numeric “set”
IF	begin conditional assembly
ENDIF	end of conditional assembly
DB	define data bytes
DW	define data words
DS	define data storage area

The ORG Directive

The ORG statement takes the form

label ORG expression

where “label” is an optional program label, and expression is a 16-bit expression, consisting of operands which are defined previous to the ORG statement. The assembler begins machine code generation at the location specified in the expression. There can be any number of ORG statements within a particular program, and there are no checks to ensure that the programmer is not defining overlapping memory areas. Note that most programs written for the CP/M system begin with an ORG statement of the form

ORG 100H

which causes machine code generation to begin at the base of the CP/M transient program area. If a label is specified in the ORG statement, then the label is given the value of the expression (this label can then be used in the operand field of other statements to represent this expression).

The END Directive

The END statement is optional in an assembly language program, but if it is present it must be the last statement (all subsequent statements are ignored in the assembly). The two forms of the END directive are

```
label    END
label    END    expression
```

where the label is again optional. If the first form is used, the assembly process stops, and the default starting address of the program is taken as 0000. Otherwise, the expression is evaluated, and becomes the program starting address (this starting address is included in the last record of the Intel formatted machine code "hex" file which results from the assembly). Thus, most CP/M assembly language programs end with the statement

```
END 100H
```

resulting in the default starting address of 100H (beginning of the transient program area).

The EQU Directive

The EQU (equate) statement is used to set up synonyms for particular numeric values. The form is

```
label    EQU    expression
```

where the label must be present, and must not label any other statement. The assembler evaluates the expression, and assigns this value to the identifier given in the label field. The identifier is usually a name which describes the value in a more human-oriented manner. Further, this name is used throughout the program to "parameterize" certain functions. Suppose for example, that data received from a Teletype appears on a particular input port, and data is sent to the Teletype through the next output port in sequence. The series of equate statements could be used to define these ports for a particular hardware environment

```
TTYBASE EQU 10H           ;BASE PORT NUMBER FOR TTY
TTYIN   EQU TTYBASE      ;TTY DATA IN
TTYOUT  EQU TTYBASE+1;TTY DATA OUT
```

At a later point in the program, the statements which access the Teletype could appear as

```
IN TTYIN ;READ TTY DATA TO REG - A
...
OUT TTYOUT ;WRITE DATA TO TTY FROM REG-A
```

making the program more readable than if the absolute I/O ports had been used. Further, if the hardware environment is redefined to start the Teletype communications ports at 7FH instead of 10H, the first statement need only be changed to

```
TTYBASE EQU 7FH ;BASE PORT NUMBER FOR TTY
```

and the program can be reassembled without changing any other statements.

The SET Directive

The SET statement is similar to the EQU, taking the form

```
label SET expression
```

except that the label can occur on other SET statements within the program. The expression is evaluated and becomes the current value associated with the label. Thus, the EQU statement defines a label with a single value, while the SET statement defines a value which is valid from the current SET statement to the point where the label occurs on the next SET statement. The use of the SET is similar to the EQU statement, but is used most often in controlling conditional assembly.

The IF and ENDIF Directives

The IF and ENDIF statements define a range of assembly language statements which are to be included or excluded during the assembly process. The form is

```
IF expression
statement #1
statement #2
...
statement #n
ENDIF
```

Upon encountering the IF statement, the assembler evaluates the expression following the IF (all operands in the expression must be defined ahead of the IF statement). If the expression evaluates to a non-zero value, then statement #1 through statement #n are assembled; if the expression

evaluates to zero, then the statements are listed but not assembled. Conditional assembly is often used to write a single “generic” program which includes a number of possible run-time environments, with only a few specific portions of the program selected for any particular assembly. The following program segments for example, might be part of a program which communicates with either a Teletype or a CRT console (but not both) by selecting a particular value for TTY before the assembly begins

```

TRUE    EQU    0FFFFH    ;DEFINE VALUE OF TRUE
FALSE   EQU    NOT TRUE  ;DEFINE VALUE OF FALSE
;
TTY     EQU    TRUE      ;TRUE IF TTY, FALSE IF CRT
;
TTYBASE EQU    10H      ;BASE OF TTY I/O PORTS
CRTBASE EQU    20H      ;BASE OF CRT I/O PORTS
        IF     TTY      ;ASSEMBLE RELATIVE TO
                        TTYBASE
CONIN   EQU    TTYBASE   ;CONSOLE INPUT
CONOUT  EQU    TTYBASE+1;CONSOLE OUTPUT
        ENDIF
;
        IF     NOT TTY   ;ASSEMBLE RELATIVE TO
                        CRTBASE
CONIN   EQU    CRTBASE   ;CONSOLE INPUT
CONOUT  EQU    CRTBASE+1;CONSOLE OUTPUT
        ENDIF
...
IN     CONIN    ;READ CONSOLE DATA
...
OUT    CONOUT   ;WRITE CONSOLE DATA

```

In this case, the program would assemble for an environment where a Teletype is connected, based at port 10H. The statement defining TTY could be changed to

```
TTY     EQU    FALSE
```

and, in this case, the program would assemble for a CRT based at port 20H.

The DB Directive

The DB directive allows the programmer to define initialized storage areas in single precision (byte) format. The statement form is

```
label    DB    e#1, e#2, ..., e#n
```

where e#1 through e#n are either expressions which evaluate to 8-bit values (the high order eight bits must be zero), or are ASCII strings of length no greater than 64 characters. There is no practical restriction on the number of expressions included on a single source line. The expressions are evaluated and placed sequentially into the machine code file following the last program address generated by the assembler. String characters are similarly placed into memory starting with the first character and ending with the last character. Strings of length greater than two characters cannot be used as operands in more complicated expressions (i.e., they must stand alone between the commas). Note that ASCII characters are always placed in memory with the parity bit reset (0). Further, recall that there is no translation from lower to upper case within strings. The optional label can be used to reference the data area throughout the remainder of the program. Examples of valid DB statements are

```

data:    DB 0,1,2,3,4,5
         DB data and 0ffh,5,377Q,1+2+3+4
signon:  DB 'please type your name',cr,lf,0
         DB 'AB' SHR 8, 'C', 'DE' AND 7FH

```

The DW Directive

The DW statement is similar to the DB statement except double precision (two byte) words of storage are initialized. The form is

```
label    DW    e#1, e#2, ..., e#n
```

where e#1 through e#n are expressions which evaluate to 16-bit results. Note that ASCII strings of length one or two characters are allowed, but strings longer than two characters disallowed. In all cases, the data storage is consistent with the 8080 processor: the least significant byte of the expression is stored first in memory, followed by the most significant byte. Examples are

```

doub:    DW    0ffefh,doub + 4,signon-$,255 + 255
         DW    'a', 5, 'ab', 'CD', 6 shl 8 or 11b

```

The DS Directive

The DS statement is used to reserve an area of uninitialized memory, and takes the form

```
label    DS    expression
```

where the label is optional. The assembler begins subsequent code generation after the area reserved by the DS. Thus, the DS statement given above has exactly the same effect as the statement

label: EQU \$;LABEL VALUE IS CURRENT CODE LOCATION
 ORG \$ + expression ;MOVE PAST RESERVED AREA

Operation Codes

Assembly language operation codes form the principal part of assembly language programs, and form the operation field of the instruction. In general, ASM accepts all the standard mnemonics for the Intel 8080 microcomputer, which are given in detail in the Intel manual *8080 Assembly Language Programming Manual*. Labels are optional on each input line and, if included, take the value of the instruction address immediately before the instruction is issued. The individual operators are listed briefly in the following sections for completeness, although it is understood that the Intel manuals should be referenced for exact operator details. In each case,

- e3 represents a 3-bit value in the range of 0-7 which can be one of the predefined registers A, B, C, D, E, H, L, M, SP, or PSW.
- e8 represents an 8-bit value in the range 0-255
- e16 represents a 16-bit value in the range 0-65535

which can themselves be formed from an arbitrary combination of operands and operators. In some cases, the operands are restricted to particular values within the allowable range, such as the PUSH instruction. These cases will be noted as they are encountered.

In the sections which follow, each operation code is listed in its most general form, along with a specific example, with a short explanation and special restrictions.

Jumps, Calls and Returns

The Jump, Call and Return instructions allow several different forms which test the condition flags set in the 8080 microcomputer CPU. The forms are

JMB	e16	JMP	L1	Jump unconditionally to label
JNZ	e16	JMP	L2	Jump on non zero condition to label
JZ	e16	JMP	100H	Jump on zero condition to label
JNC	e16	JNC	L1+4	Jump no carry to label
JC	e16	JC	L3	Jump on carry to label
JPO	e16	JPO	\$+8	Jump on parity odd to label
JPE	e16	JPE	L4	Jump on even parity to label
JP	e16	JP	GAMMA	Jump on positive result to label

JM	e16	JM	al	Jump on minus to label
CALL	e16	CALL	S1	Call subroutine unconditionally
CNZ	e16	CNZ	S2	Call subroutine if non zero flag
CZ	e16	CZ	100H	Call subroutine on zero flag
CNC	e16	CNC	S1 + 4	Call subroutine if no carry set
CC	e16	CC	S3	Call subroutine if carry set
CPO	e16	CPO	\$ + 8	Call subroutine if parity odd
CPE	e16	CPE	S4	Call subroutine if parity even
CP	e16	CP	GAMMA	Call subroutine if positive result
CM	e16	CM	b1\$c2	Call subroutine if minus flag
RST	e3	RST	0	Programmed "restart," equivalent to CALL 8*e3, except one byte call
RET				Return from subroutine
RNZ				Return if non zero flag set
RZ				Return if zero flag set
RNC				Return if no carry
RC				Return if carry flag set
RPO				Return if parity is odd
RPE				Return if parity is even
RP				Return if positive result
RM				Return if minus flag is set

Immediate Operand Instructions

Several instructions are available which load single or double precision registers, or single precision memory cells, with constant values, along with instructions which perform immediate arithmetic or logical operations on the accumulator (register A).

MVI e3,e8	MVI	B,255	Move immediate data to register A, B, C, D, E, H, L, or M (memory)
ADI e8	ADI	1	Add immediate operand to A with- out carry
ACI e8	ACI	0FFH	Add immediate operand to A with carry
SUI e8	SUI	L + 3	Subtract from A without borrow (carry)
SBI e8	SBI	L AND 11B	Subtract from A with borrow (carry)
ANI e8	ANI	\$ AND 7FH	Logical "and" A with immediate data
XRI e8	XRI	1111\$0000B	"Exclusive or" A with immediate data
ORI e8	ORI	L AND 1 + 1	Logical "or" A with immediate data

CPI e8	CPI 'a'	Compare A with immediate data (same as SUI except register A not changed)
LXI e3,e16	LXI B,100H	Load extended immediate to register pair (e3 must be equivalent to B,D,H, or SP)

Increment and Decrement Instructions

Instructions are provided in the 8080 repertoire for incrementing or decrementing single and double precision registers. The instructions are

INR e3	INR E	Single precision increment register (e3 produces one of A, B, C, D, E, H, L, M)
DCR e3	DCR A	Single precision decrement register (e3 produces one of A, B, C, D, E, H, L, M)
INX e3	INX SP	Double precision increment register pair (e3 must be equivalent to B,D,H, or SP)
DCX e3	DCX B	Double precision decrement register pair (e3 must be equivalent to B,D,H, or SP)

Data Movement Instructions

Instructions which move data from memory to the CPU and from CPU to memory are given below

MOV e3,e3	MOV A,B	Move data to leftmost element from rightmost element (e3 produces one of A, B, C, D, E, H, L, or M). MOV M,M is disallowed
LDAX e3	LDAX B	Load register A from computed address (e3 must produce either B or D)
STAX e3	STAX D	Store register A to computed address (e3 must produce either B or D)
LHLD e16	LHLD L1	Load HL direct from location e16 (double precision load to H and L)
SHLD e16	SHLD L5 + x	Store HL direct to location e16 (double precision store from H and L to memory)

LDA e16	LDA Gamma	Load register A from address e16
STA e16	STA X3-5	Store register A into memory at e16
POP e3	POP PSW	Load register pair from stack, set SP (e3 must produce one of B, D, H, or PSW)
PUSH e3	PUSH B	Store register pair into stack, set SP (e3 must produce one of B, D, H, or PSW)
IN e8	IN 0	Load register A with data from port e8
OUT e8	OUT 255	Send data from register A to port e8
XTHL		Exchange data from top of stack with HL
PCHL		Fill program counter with data from HL
SPHL		Fill stack pointer with data from HL
XCHG		Exchange DE pair with HL pair

Arithmetic Logic Unit Operations

Instructions which act upon the single precision accumulator to perform arithmetic and logic operations are

ADD e3	ADD B	Add register given by e3 to accumulator without carry (e3 must produce one of A, B, C, D, E, H, or L)
ADC e3	ADC L	Add register to A with carry, e3 as above
SUB e3	SUB H	Subtract reg e3 from A without carry, e3 is defined as above
SBB e3	SBB 2	Subtract register e3 from A with carry, e3 defined as above
ANA e3	ANA 1+1	Logical "and" reg with A, e3 as above
XRA e3	XRA A	"Exclusive or" with A, e3 as above
ORA e3	ORA B	Logical "or" with A, e3 defined as above
CMP e3	CMP H	Compare register with A, e3 as above
DAA		Decimal adjust register A based upon last arithmetic logic unit operation
CMA		Complement the bits in register A

STC		Set the carry flag to 1
CMC		Complement the carry flag
RLC		Rotate bits left, (re)set carry as a side effect (high order A bit becomes carry)
RRC		Rotate bits right, (re)set carry as side effect (low order A bit becomes carry)
RAL		Rotate carry/A register to left (carry is involved in the rotate)
RAR		Rotate carry/A register to right (carry is involved in the rotate)
DAD e3	DAD B	Double precision add register pair e3 to HL (e3 must produce B, D, H, or SP)

Control Instructions

The four remaining instructions are categorized as control instructions, and are listed below

HLT	Halt the 8080 processor
DI	Disable the interrupt system
EI	Enable the interrupt system
NOP	No operation

Error Messages

When errors occur within the assembly language program, they are listed as single character flags in the leftmost position of the source listing. The line in error is also echoed at the console so that the source listing need not be examined to determine if errors are present. The error codes are

- D Data error: element in data statement cannot be placed in the specified data area
- E Expression error: expression is ill-formed and cannot be computed at assembly time
- L Label error: label cannot appear in this context (may be duplicate label)
- N Not implemented: features which will appear in future ASM versions (e.g., macros) are recognized, but flagged in this version

- O Overflow: expression is too complicated (i.e., too many pending operators) to compute; simplify it
- P Phase error: label does not have the same value on two subsequent passes through the program
- R Register error: the value specified as a register is not compatible with the operation code
- V Value error: operand encountered in expression is improperly formed

Several error messages are printed which are due to terminal error conditions

NO SOURCE FILE PRESENT	The file specified in the ASM command does not exist on disk
NO DIRECTORY SPACE	The disk directory is full; erase files which are not needed, and retry
SOURCE FILE NAME ERROR	Improperly formed ASM file name (e.g., it is specified with “?” fields)
SOURCE FILE READ ERROR	Source file cannot be read properly by the assembler, execute a TYPE to determine the point of error
OUTPUT FILE WRITE ERROR	Output files cannot be written properly, most likely cause is a full disk; erase and retry
CANNOT CLOSE FILE	Output file cannot be closed, check to see if disk is write protected

A Sample Session

The following session shows interaction with the assembler and debugger in the development of a simple assembly language program.

ASM SORT Assemble SORT. ASM

CP/M ASSEMBLER - VER 1 0

015C next free address
003H USE FACTOR % of table used 00 to FF (hexadecimal)
END OF ASSEMBLY

DIR SORT *

SORT ASM source file
SORT BAK backup from last edit
SORT PRN print file (contains tab characters)
SORT HEX machine code file
A)TYPE SORT PRN

machine code location	generated machine code	Source line
0100		SORT PROGRAM IN CP/M ASSEMBLY LANGUAGE START AT THE BEGINNING OF THE TRANSIENT PROGRAM AREA ORG 100H
0100	214601	SORT LXI H,SW ;ADDRESS SWITCH TOGGLE
0103	3601	MVI M,1 ;SET TO 1 FOR FIRST ITERATION
0105	214701	LXI H,1 ;ADDRESS INDEX
0108	3600	MVI M,0 ;I = 0
010A	7E	COMP: COMPARE I WITH ARRAY SIZE
010B	FE09	MOV A,M ;A REGISTER = I
010D	D21901	CP1 N-1 ;CY SET IF I < (N-1)
		JNC CONT ;CONTINUE IF I <= (N-2)
0110	214601	END OF ONE PASS THROUGH DATA
0113	7EB7C20001	LXI H,SW ;CHECK FOR ZERO SWITCHES MOV A,M! ORA A! JNZ SORT ;END OF SORT IF SW=0
0118	FF	RST 7 ;GO TO THE DEBUGGER INSTEAD OF RE:
0119	5F16002148	CONT: CONTINUE THIS PASS
0121	4E792346	ADDRESSING I, SO LOAD AV(I) INTO REGISTERS MOV E,A! MVI D,0! LXI H,AV! DAD D! DAD D MOV C,M! MOV A,C! INX H! MOV B,M LOW ORDER BYTE IN A AND C, HIGH ORDER BYTE IN B
0125	23	MOV H AND L TO ADDRESS AV(I+1) INX H
0126	965778239E	COMPARE VALUE WITH REGS CONTAINING AV(I) SUB M! MOV D,A! MOV A,B! INX H! SBB M ;SUBTRACT
0128	DA3F01	BORROW SET IF AV(I+1) > AV(I) JC INCI ;SKIP IF IN PROPER ORDER
012E	B2CA3F01	CHECK FOR EQUAL VALUES ORA D! JZ INCI ;SKIP IF AV(I) = AV(I+1)
0132	5670205E	MOV D,M! MOV M,B! DCX H! MOV E,M
0136	712B722B73	MOV M,C! DCX H! MOV M,D! DCX H! MOV M,E
013B	21460134	INCREMENT SWITCH COUNT LXI H,SW! INR M

```

INCREMENT I
013F 21470134C3INCI: LXI H,I! INR M! JMP COMP

```

DATA DEFINITION SECTION

```

0146 00 SU: DB 0 ,RESERVE SPACE FOR SWITCH COUNT
0147 I: DS 1 ,SPACE FOR INDEX
0148 050064001EAV DU 5,100,30,50,20,7,1000,300,100,-32767
000A N EQU ($-AV)/2 ,COMPUTE N INSTEAD OF PRE
015C ← equate value END

```

A)TYPE SORT: HEX

```

.10010000214601360121470136007EFE09D2190140
.100110002146017EB7C20001FF5F16002148011903
.10012000194E79234623965778239EDA3F01B2CAA7
.100130003F0156702B5E712B722B732146013421C7
.07014000470134C30A01006E
.10014000050064001E00320014000700E0032C01B0
.04015000640001B00E
.0000000000

```

machine code
in HEX format

A)DDT SORT: HEX start debug run

16K DDT VER 1 0

NEXT PC

015C 0000 default address (no address on END statement)

-XP

P=0000 100 change PC to 100

-UFFFF untrace for 65535 steps

abort with
rubout

C0Z0M0E010 A=00 B=0000 D=0000 H=0000 S=0100 P=0100 LXI H,0146;0100

-T10 trace 10₁₆ steps

```

C0Z0M0E010 A=01 B=0000 D=0000 H=0146 S=0100 P=0100 LXI H,0146
C0Z0M0E010 A=01 B=0000 D=0000 H=0146 S=0100 P=0103 MVI M,01
C0Z0M0E010 A=01 B=0000 D=0000 H=0146 S=0100 P=0105 LXI H,0147
C0Z0M0E010 A=01 B=0000 D=0000 H=0147 S=0100 P=0108 MVI M,00
C0Z0M0E010 A=01 B=0000 D=0000 H=0147 S=0100 P=010A MOV A,M
C0Z0M0E010 A=00 B=0000 D=0000 H=0147 S=0100 P=0108 CPI 09
C1Z0M1E010 A=00 B=0000 D=0000 H=0147 S=0100 P=010D JNC 0119
C1Z0M1E010 A=00 B=0000 D=0000 H=0147 S=0100 P=0110 LXI H,0146
C1Z0M1E010 A=00 B=0000 D=0000 H=0146 S=0100 P=0113 MOV A,M
C1Z0M1E010 A=01 B=0000 D=0000 H=0146 S=0100 P=0114 ORA A
C0Z0M0E010 A=01 B=0000 D=0000 H=0146 S=0100 P=0115 JNZ 0100
C0Z0M0E010 A=01 B=0000 D=0000 H=0146 S=0100 P=0100 LXI H,0146
C0Z0M0E010 A=01 B=0000 D=0000 H=0146 S=0100 P=0103 MVI M,01
C0Z0M0E010 A=01 B=0000 D=0000 H=0146 S=0100 P=0105 LXI H,0147
C0Z0M0E010 A=01 B=0000 D=0000 H=0147 S=0100 P=0108 MVI M,00
C0Z0M0E010 A=01 B=0000 D=0000 H=0147 S=0100 P=010A MOV A,M;0100
-A10D

```

stopped at
10BH

010D JC 119 change to a jump on carry

0110

-XP

P=0100 100 reset program counter back to beginning of program

-T10 trace execution for 10H steps

```

C0Z0M0E010 A=00 B=0000 D=0000 H=0147 S=0100 P=0100 LXI H,0146
C0Z0M0E010 A=00 B=0000 D=0000 H=0146 S=0100 P=0103 MVI M,01
C0Z0M0E010 A=00 B=0000 D=0000 H=0146 S=0100 P=0105 LXI H,0147
C0Z0M0E010 A=00 B=0000 D=0000 H=0147 S=0100 P=0108 MVI M,00
C0Z0M0E010 A=00 B=0000 D=0000 H=0147 S=0100 P=010A MOV A,M
C0Z0M0E010 A=00 B=0000 D=0000 H=0147 S=0100 P=0108 CPI 09
C1Z0M1E010 A=00 B=0000 D=0000 H=0147 S=0100 P=010D JC 0119
C1Z0M1E010 A=00 B=0000 D=0000 H=0147 S=0100 P=0119 MOV E,A
C1Z0M1E010 A=00 B=0000 D=0000 H=0147 S=0100 P=011A MVI D,00
C1Z0M1E010 A=00 B=0000 D=0000 H=0147 S=0100 P=011C LXI H,0148
C1Z0M1E010 A=00 B=0000 D=0000 H=0148 S=0100 P=011F DAD D
C0Z0M1E010 A=00 B=0000 D=0000 H=0148 S=0100 P=0120 DAD D

```

altered instruction

```

C020M1E010 A=00 B=0000 D=0000 H=0148 S=0100 P=0121 MOV C,M
C020M1E010 A=00 B=0005 D=0000 H=0148 S=0100 P=0122 MOV A,C
C020M1E010 A=05 B=0005 D=0000 H=0148 S=0100 P=0123 INX H
C020M1E010 A=05 B=0005 D=0000 H=0149 S=0100 P=0124 MOV B,M+0125
-L100

```

```

0100 LXI H,0146
0103 MVI M,01
0105 LXI H,0147
0108 MVI M,00
010A MOV A,M
010B CPI 09
010D JC 0119
0110 LXI H,0146
0113 MOV A,M
0114 ORA A
0115 JNZ 0100
-L

```

list some code from 100H

Automatic
breakpoint

```

0116 RST 07
0119 MOV E,A
011A MVI D,00
011C LXI H,0148

```

list more

- abort list with rubout

-G, 110 start program from current PC (0125H) and run in real time to 11BH

•0127 stopped with an external interrupt 7 from front panel (program was looping indefinitely)
-T4 look at looping program in trade mode

```

C020M0E010 A=38 B=0064 D=0006 H=0156 S=0100 P=0127 MOV D,A
C020M0E010 A=38 B=0064 D=3806 H=0156 S=0100 P=0128 MOV A,B
C020M0E010 A=00 B=0064 D=3806 H=0156 S=0100 P=0129 INX H
C020M0E010 A=00 B=0064 D=3806 H=0157 S=0100 P=012A SBB M+012B
-D148

```

data is sorted, but program doesn't stop

```

0148 05 00 07 00 14 00 1E 00
0150 32 00 64 00 64 00 2C 01 E8 03 01 00 00 00 00 00 2 D D
0160 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00

```

- G0 return to CP/M

DDT SORT, HEX reload the memory image

```

16K DDT VER 1.0
NEXT PC
015C 0000
-XP

```

P=0000 100 Set PC to beginning of program

-L10D list bad opcode

```

010D JNC 0119
0110 LXI H,0146

```

- abort list with rubout

-A10D assemble new opcode

```

010D JC 119

```

```

0110

```

-L100 list starting section of program

```

0100 LXI H,0146
0103 MVI M,01
0105 LXI H,0147
0108 MVI M,00

```

- abort list with rubout

-A103 change "switch" initialization to 00

0103 MVI M,0

0105

-^C return to CP/M with ctrl-c (G0 works as well)

SAVE 1 SORT.COM save 1 page (256 bytes, from 100H to 1FFMH) on disk in case we have to reload later

A>DDT SORT.COM restart DDT with saved memory image

16K DDT VER 1.0

NEXT PC

0200 0100 "COM" file always starts with address 100H

-G run the program from PC=100H

*0110 programmed stop (RST 7) encountered

-D140

0140 05 00 07 00 14 00 1E 00 ← data properly sorted
 0150 32 00 64 00 64 00 2C 01 EB 03 01 00 00 00 00 00 00 2 D D ,
 0160 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
 0170 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00

- G0 return to CP/M

ED SORT.ASM make changes to original program

ctrl-Z

*N,0 Z0TT find next "0"

MVI M,0 ;I = 0

*- up one line in text

LXI H,1 ;ADDRESS INDEX

*- up another line

MVI M,1 ;SET TO 1 FOR FIRST ITERATION

*KT kill line and type next line

LXI H,1 ;ADDRESS INDEX

*I insert new line

MVI M,0 ;ZERO SW

*T

LXI H,1 ;ADDRESS INDEX

*NJNC Z0T

JNC *T

CONT ;CONTINUE IF I (<= (N-2))

*-2D1C Z0LT

JC CONT ;CONTINUE IF I (<= (N-2))

*E

← source from disk A

← hex to disk A

ASM SORT AAZ ← skip pm file

CP/M ASSEMBLER - VER 1.0

015C next address to assemble

007H USE FACTOR

END OF ASSEMBLY

DDT SORT.HEX test program changes

16K DDT VER 1.0

NEXT PC

015C 0000

-G100

*0110

-D140

0140 05 00 07 00 14 00 1E 00 ← data sorted
 0150 32 00 64 00 64 00 2C 01 EB 03 01 00 00 00 00 00 00 2 D D ,
 0160 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00

- abort with rubout

-G0 return to CP/M — program checks OK.

**CP/M DYNAMIC DEBUGGING TOOL (DDT)
USER'S GUIDE**

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Introduction

The DDT program allows dynamic interactive testing and debugging of programs generated in the CP/M environment. The debugger is initiated by typing one of the following commands at the CP/M Console Command level

```
DDT  
DDT filename.HEX  
DDT filename.COM
```

where “filename” is the name of the program to be loaded and tested. In both cases, the DDT program is brought into main memory in the place of the Console Command Processor (refer to the CP/M Interface Guide for standard memory organization), and thus resides directly below the Basic Disk Operating System portion of CP/M. The BDOS starting address, which is located in the address field of the JMP instruction at location 5H, is altered to reflect the reduced Transient Program Area size.

The second and third forms of the DDT command shown above perform the same actions as the first, except there is a subsequent automatic load of the specified HEX or COM file. The action is identical to the sequence of commands

```
DDT  
I filename.HEX or I filename.COM  
R
```

where the I and R commands set up and read the specified program to test. (See the explanation of the I and R commands below for exact details.)

Upon initiation, DDT prints a sign-on message in the format

```
nnK DDT-s VER m.m
```

where nn is the memory size (which must match the CP/M system being used), s is the hardware system which is assumed, corresponding to the codes

D	Digital Research standard version
M	MDS version
I	IMSAI standard version
O	Omron systems
S	Digital Systems standard version

and m.m is the revision number.

Following the sign on message, DDT prompts the operator with the character “-” and waits for input commands from the console. The operator can type any of several single character commands, terminated by a carriage return to execute the command. Each line of input can be line-edited using the standard CP/M controls

rubout	remove the last character typed
Control-X	remove the entire line, ready for re-typing
Control-C	system reboot

Any command can be up to 32 characters in length (an automatic carriage return is inserted as the 33rd character), where the first character determines the command type

A	enter assembly language mnemonics with operands
D	display memory in hexadecimal and ASCII
F	fill memory with constant data
G	begin execution with optional breakpoints
I	set up a standard input file control block
L	list memory using assembler mnemonics
M	move a memory segment from source to destination
R	read program for subsequent testing
S	substitute memory values
T	trace program execution
U	untraced program monitoring
X	examine and optionally alter the CPU state

The command character, in some cases, is followed by zero, one, two, or three hexadecimal values which are separated by commas or single blank characters. All DDT numeric output is in hexadecimal form. In all cases, the commands are not executed until the carriage return is typed at the end of the command.

At any point in the debug run, the operator can stop execution of DDT using either a Control-C or G0 (jmp to location 0000H), and save the current memory image using a SAVE command of the form

SAVE n filename.COM

where n is the number of pages (256 byte blocks) to be saved on disk. The number of blocks can be determined by taking the high order byte of the top load address and converting this number to decimal. For example, if the highest address in the Transient Program Area is 1234H then the number of pages is 12H, or 18 in decimal. Thus the operator could type a Control-C during the debug run, returning to the Console Processor level, followed by

SAVE 18 X.COM

The memory image is saved as X.COM on the diskette, and can be directly executed by simply typing the name X. If further testing is required, the memory image can be recalled by typing

DDT X.COM

which reloads the previously saved program from location 100H through page 18 (12FFH). The machine state is not a part of the COM file, and thus the program must be restarted from the beginning in order to properly test it.

DDT Commands

The individual commands are given below in some detail. In each case, the operator must wait for the prompt character (-) before entering the command. If control is passed to a program under test, and the program has not reached a breakpoint, control can be returned to DDT by executing a RST 7 from the front panel (note that the rubout key should be used instead if the program is executing a T or U command). In the explanation of each command, the command letter is shown in some cases with numbers separated by commas, where the numbers are represented by lower case letters. These numbers are always assumed to be in a hexadecimal radix, and from one to four digits in length (longer numbers will be automatically truncated on the right).

Many of the commands operate upon a "CPU state" which corresponds to the program under test. The CPU state holds the registers of the program being debugged, and initially contains zeroes for all registers and flags except for the program counter (P) and stack pointer (S), which default to 100H. The program counter is subsequently set to the starting address given in the last record of a HEX file if a file of this form is loaded (see the I and R commands).

The A (Assemble) Command

DDT allows inline assembly language to be inserted into the current memory image using the A command which takes the form

As

where s is the hexadecimal starting address for the inline assembly. DDT prompts the console with the address of the next instruction to fill, and reads the console, looking for assembly language mnemonics (see the Intel 8080 Assembly Language Reference Card for a list of mnemonics), followed by register references and operands in absolute hexadecimal form. Each successive load address is printed before reading the console. The A command terminates when the first empty line is input from the console.

Upon completion of assembly language input, the operator can review the memory segment using the DDT disassembler. (See the L command.)

Note that the assembler/disassembler portion of DDT can be overlaid by the transient program being tested, in which case the DDT program responds with an error condition when the A and L commands are used.

The D (Display) Command

The D command allows the operator to view the contents of memory in hexadecimal and ASCII formats. The forms are

D
Ds
Ds,f

In the first case, memory is displayed from the current display address (initially 100H), and continues for 16 display lines. Each display line takes the form shown below

```
aaaa bb cccccccccccccc
```

where aaaa is the display address in hexadecimal, and bb represents data present in memory starting at aaaa. The ASCII characters starting at aaaa are given to the right (represented by the sequence of c's), where non-graphic characters are printed as a period (.) symbol. Note that both upper and lower case alphabetic characters are displayed, and thus will appear as upper case symbols on a console device that supports only upper case. Each display line gives the values of 16 bytes of data, except that the first line displayed is truncated so that the next line begins at an address which is the multiple of 16.

The second form of the D command shown above is similar to the first, except that the display address is first set to address s. The third form causes the display to continue from address s through address f. In all cases, the display address is set to the first address not displayed in this command, so that a continuing display can be accomplished by issuing successive D commands with no explicit addresses.

Excessively long displays can be aborted by pushing the rubout key.

The F (Fill) Command

The F command takes the form

Fs,f,c

where s is the starting address, f is the final address, and c is a hexadecimal byte constant. The effect is as follows: DDT stores the constant c at address s, increments the value of s and tests against f. If s exceeds f then the operation terminates, otherwise the operation is repeated. Thus, the fill command can be used to set a memory block to a specific constant value.

The G (Go) Command

Program execution is started using the G command, with up to two optional breakpoint addresses. The G command takes one of the forms

G
Gs
Gs,b
Gs,b,c
G,b
G,b,c

The first form starts execution of the program under test at the current value of the program counter in the current machine state, with no breakpoints set (the only way to regain control in DDT is through a RST 7 execution). The current program counter can be viewed by typing an X or XP command. The second form is similar to the first except that the program counter in the current machine state is set to address s before execution begins. The third form is the same as the second, except that program execution stops when address b is encountered (b must be in the area of the program under test). The instruction at location b is not executed when the breakpoint is encountered. The fourth form is identical to the third, except that two breakpoints are specified, one at b and the other at c. Encountering either breakpoint causes execution to stop, and both breakpoints are subsequently

cleared. The last two forms take the program counter from the current machine state, and set one and two breakpoints, respectively.

Execution continues from the starting address in real-time to the next breakpoint. That is, there is no intervention between the starting address and the break address by DDT. Thus, if the program under test does not reach a breakpoint, control cannot return to DDT without executing a RST 7 instruction. Upon encountering a breakpoint, DDT stops execution and types

*d

where d is the stop address. The machine state can be examined at this point using the X (Examine) command. The operator must specify breakpoints which differ from the program counter address at the beginning of the G command. Thus, if the current program counter is 1234H, then the commands

G,1234

and

G400,400

both produce an immediate breakpoint, without executing any instructions whatsoever.

The I (Input) Command

The I command allows the operator to insert a file name into the default file control block at 5CH (the file control block created by CP/M for transient programs is placed at this location; see the CP/M Interface Guide). The default FCB can be used by the program under test as if it had been passed by the CP/M Console Processor. Note that this file name is also used by DDT for reading additional HEX and COM files. The form of the I command is

Ifilename

or

Ifilename.filetype

If the second form is used, and the filetype is either HEX or COM, then subsequent R commands can be used to read the pure binary or hex format machine code (see the R command for further details).

The L (List) Command

The L command is used to list assembly language mnemonics in a particular program region. The forms are

L
Ls
Ls,f

The first command lists twelve lines of disassembled machine code from the current list address. The second form sets the list address to s, and then lists twelve lines of code. The last form lists disassembled code from s through address f. In all three cases, the list address is set to the next unlisted location in preparation for a subsequent L command. Upon encountering an execution breakpoint, the list address is set to the current value of the program counter (see the G and T commands). Again, long typeouts can be aborted using the rubout key during the list process.

The M (Move) Command

The M command allows block movement of program or data areas from one location to another in memory. The form is

Ms,f,d

where s is the start address of the move, f is the final address of the move, and d is the destination address. Data is first moved from s to d, and both addresses are incremented. If s exceeds f then the move operation stops, otherwise the move operation is repeated.

The R (Read) Command

The R command is used in conjunction with the I command to read COM and HEX files from the diskette into the transient program area in preparation for the debut run. The forms are

R
Rb

where b is an optional bias address which is added to each program or data address as it is loaded. The load operation must not overwrite any of the system parameters from 000H through 0FFH (i.e., the first page of memory). If b is omitted, then b = 0000 is assumed. The R command requires a previous I command, specifying the name of a HEX or COM file. The load address for

each record is obtained from each individual HEX record, while an assumed load address of 100H is taken for COM files. Note that any number of R commands can be issued following the I command to re-read the program under test, assuming the tested program does not destroy the default area at 5CH. Further, any file specified with the filetype "COM" is assumed to contain machine code in pure binary form (created with the LOAD or SAVE command), and all others are assumed to contain machine code in Intel hex format (produced, for example, with the ASM command).

Recall that the command

DDT filename.filetype

which initiates the DDT program is equivalent to the commands

```
DDT
-Ifilename.filetype
-R
```

Whenever the R command is issued, DDT responds with either the error indicator "?" (file cannot be opened, or a checksum error occurred in a HEX file), or with a load message taking the form

```
NEXT PC
nnnn pppp
```

where nnnn is the next address following the loaded program, and pppp is the assumed program counter (100H for COM files, or taken from the last record if a HEX file is specified).

The S (Set) Command

The S command allows memory locations to be examined and optionally altered. The form of the command is

```
Ss
```

where s is the hexadecimal starting address for examination and alteration of memory. DDT responds with a numeric prompt, giving the memory location, along with the data currently held in the memory location. If the operator types a carriage return, then the data is not altered. If a byte value is typed, then the value is stored at the prompted address. In either case, DDT continues to prompt with successive addresses and values until either a period (.) is typed by the operator, or an invalid input value is detected.

The T (Trace) Command

The T command allows selective tracing of program execution for 1 to 65535 program steps. The forms are

T
Tn

In the first case, the CPU state is displayed, and the next program step is executed. The program terminates immediately, with the termination address displayed as

*hhhh

where hhhh is the next address to execute. The display address (used in the D command) is set to the value of H and L, and the list address (used in the L command) is set to hhhh. The CPU state at program termination can then be examined using the X command.

The second form of the T command is similar to the first, except that execution is traced for n steps (n is a hexadecimal value) before a program breakpoint occurs. A breakpoint can be forced in the trace mode by typing a rubout character. The CPU state is displayed before each program step is taken in trace mode. The format of the display is the same as described in the X command.

Note that program tracing is discontinued at the interface to CP/M, and resumes after return from CP/M to the program under test. Thus, CP/M functions which access I/O devices, such as the diskette drive, run in real-time, avoiding I/O timing problems. Programs running in trace mode execute approximately 500 times slower than real time since DDT gets control after each user instruction is executed. Interrupt processing routines can be traced, but it must be noted that commands which use the breakpoint facility (G, T, and U) accomplish the break using a RST 7 instruction, which means that the tested program cannot use this interrupt location. Further, the trace mode always runs the tested program with interrupts enabled, which may cause problems if asynchronous interrupts are received during tracing.

Note also that the operator should use the rubout key to get control back to DDT during trace, rather than executing a RST 7, in order to ensure that the trace for the current instruction is completed before interruption.

The U (Untrace) Command

The U command is identical to the T command except that intermediate program steps are not displayed. The untrace mode allows from 1 to 65535 (0FFFFH) steps to be executed in monitored mode, and is used principally to retain control of an executing program while it reaches steady state conditions. All conditions of the T command apply to the U command.

The X (Examine) Command

The X command allows selective display and alteration of the current CPU state for the program under test. The forms are

X
Xr

where r is one of the 8080 CPU registers

C	Carry Flag	(0/1)
Z	Zero Flag	(0/1)
M	Minus Flag	(0/1)
E	Even Parity Flag	(0/1)
I	Interdigit Carry	(0/1)
A	Accumulator	(0-FF)
B	BC register pair	(0-FFFF)
D	DE register pair	(0-FFFF)
H	HL register pair	(0-FFFF)
S	Stack Pointer	(0-FFFF)
P	Program Counter	(0-FFFF)

In the first case, the CPU register state is displayed in the format

CfZfMfEfIf A = bb B = dddd D = dddd H = dddd S = dddd P = dddd inst

where f is a 0 or 1 flag value, bb is a byte value, and dddd is a double byte quantity corresponding to the register pair. The "inst" field contains the disassembled instruction which occurs at the location addressed by the CPU state's program counter.

The second form allows display and optional alteration of register values, where r is one of the registers given above (C, Z, M, E, I, A, B, D, H, S, or P). In each case, the flag or register value is first displayed at the console. The DDT program then accepts input from the console. If a carriage return is typed, then the flag or register value is not altered. If a value in the proper range is typed, then the flag or register value is altered. Note that BC, DE,


```

0000 = ← LEN EQU $-VECT ,LENGTH
0121 Value of ← LARGE: DS 1 ,LARGEST VALUE ON EXIT
0122 Equate ← END

```

A>

DDT SCAN. HEX

Start Debugger using hex format machine code

16K DDT VER 1.0

NEXT PC

0121 0000

-X ← last load address + 1

C0Z0M0E010 A=00 B=0000 D=0000 H=0000 S=0100 P=0000 OUT 7F PC=0

next instruction to execute at

-XP

Examine registers before debug run

P=0000 100

Change PC to 100

-X

Look at registers again

C0Z0M0E010 A=00 B=0000 D=0000 H=0000 S=0100 P=0100 MVI B,00

PC changed

Next instruction to execute at PC=100

-L100

```

0100 MVI B,00
0102 MVI C,00
0104 LXI H,0119
0107 MOV A,M
0108 SUB C
0109 JNC 010D
010C MOV C,A
010D INX H
010E DCR B
010F JNZ 0107
0112 MOV A,C

```

Disassembled Machine Code at 100H (See Source Listing for comparison)

-L

```

0113 STA 0121
0116 JMP 0000
0119 STAX B
011A NOP
011B INR B
011C INX B
011D DCR B
011E MVI B,01
0120 DCR B
0121 LXI D,2200
0124 LXI H,0200

```

A little more machine code (note that Program ends at location 116 with a JMP to 0000)

-R116

enter inline assembly mode to change the JMP to 0000 into a RST 7, which will cause the program under test to return to DDT if 116H is ever executed.

0116 RST 7

0117 (single carriage return stops assembly mode)

-L113 List Code at 113H to check that RST 7 was properly inserted

```

0113 STA 0121 ← in place of JMP
0116 RST 07 ←
0117 NOP
0118 NOP
0119 STAX B
011A NOP
011B INR B
011C INX B

```

-X

Look at registers

C0Z0M0E010 A=00 B=0000 D=0000 H=0000 S=0100 P=0100 MVI B,00

-I

Execute Program for one step.

initial CPU state, before is executed

C0Z0M0E010 A=00 B=0000 D=0000 H=0000 S=0100 P=0100 MVI B,00+0102

-I

Trace one step again (note 08H in B)

automatic breakpoint

C0Z0M0E010 A=00 B=0800 D=0000 H=0000 S=0100 P=0102 MVI C,00+0104

-T Trace again (Register C is cleared)

C0Z0M0E010 A=00 B=0000 D=0000 H=0000 S=0100 P=0104 LXI H,0119+0107

-T3 Trace three steps

C0Z0M0E010 A=00 B=0000 D=0000 H=0119 S=0100 P=0107 MOV A,H
C0Z0M0E010 A=02 B=0000 D=0000 H=0119 S=0100 P=0108 SUB C
C0Z0M0E011 A=02 B=0000 D=0000 H=0119 S=0100 P=0109 JNC 010D+010D

-D119 Display memory starting at 119H.

Automatic breakpoint at 10DH

Address	Hex Data	Program data
0119	02 00 04 03 05 06 01	
0120	05 11 00 22 21 00 02 7E EB 77 13 23 EB 0B 78 B1	Lower case x
0130	C2 27 01 C3 03 29 00 00 00 00 00 00 00 00 00	
0140	00 00 00 00 00 00 00 00 00 00 00 00 00 00 00	
0150	00 00 00 00 00 00 00 00 00 00 00 00 00 00 00	
0160	00 00 00 00 00 00 00 00 00 00 00 00 00 00 00	Data is displayed in ASCII with a "0" in the position of non-graphic characters
0170	00 00 00 00 00 00 00 00 00 00 00 00 00 00 00	
0180	00 00 00 00 00 00 00 00 00 00 00 00 00 00 00	
0190	00 00 00 00 00 00 00 00 00 00 00 00 00 00 00	
01A0	00 00 00 00 00 00 00 00 00 00 00 00 00 00 00	
01B0	00 00 00 00 00 00 00 00 00 00 00 00 00 00 00	
01C0	00 00 00 00 00 00 00 00 00 00 00 00 00 00 00	

-X Current CPU state

C0Z0M0E011 A=02 B=0000 D=0000 H=0119 S=0100 P=010D INX H

-T5 Trace 5 steps from current CPU state

C0Z0M0E011 A=02 B=0000 D=0000 H=0119 S=0100 P=010D INX H
C0Z0M0E011 A=02 B=0000 D=0000 H=011A S=0100 P=010E DCR B
C0Z0M0E011 A=02 B=0700 D=0000 H=011A S=0100 P=010F JNZ 0107 Breakpoint
C0Z0M0E011 A=02 B=0700 D=0000 H=011A S=0100 P=0107 MOV A,H
C0Z0M0E011 A=00 B=0700 D=0000 H=011A S=0100 P=0108 SUB C+0109

-U5 Trace without listing intermediate states

C0Z1M0E111 A=00 B=0700 D=0000 H=011A S=0100 P=0109 JNC 010D+0108

-X CPU State at end of U5

C0Z0M0E111 A=04 B=0600 D=0000 H=011B S=0100 P=0108 SUB C

-G Run program from current PC until completion (in real-time) breakpoint at 116H, caused by executing RST 7 in machine code

*0116

-X CPU state at end of program

C0Z1M0E111 A=00 B=0000 D=0000 H=0121 S=0100 P=0116 RST 07

-XP examine and change program counter

P=0116 100

-X

C0Z1M0E111 A=00 B=0000 D=0000 H=0121 S=0100 P=0100 MVI B,08

-T10 Trace 10 (hexadecimal) steps

first data element current largest value subtext for comparison A(C)

C0Z1M0E111 A=00 B=0000 D=0000 H=0121 S=0100 P=0100 MVI B,08
C0Z1M0E111 A=00 B=0000 D=0000 H=0121 S=0100 P=0102 MVI C,00
C0Z1M0E111 A=00 B=0000 D=0000 H=0121 S=0100 P=0104 LXI H,0119
C0Z1M0E111 A=00 B=0000 D=0000 H=0119 S=0100 P=0107 MOV A,H
C0Z1M0E111 A=02 B=0000 D=0000 H=0119 S=0100 P=0108 SUB C

```

C0Z0M0E011 A=02 B=0000 D=0000 H=0119 S=0100 P=0109 JNC 010D
C0Z0M0E011 A=02 B=0000 D=0000 H=0119 S=0100 P=010D INX H
C0Z0M0E011 A=02 B=0000 D=0000 H=011A S=0100 P=010E DCR B
C0Z0M0E011 A=02 B=0700 D=0000 H=011A S=0100 P=010F JNZ 0107
C0Z0M0E011 A=02 B=0700 D=0000 H=011A S=0100 P=0107 MOV A,M
C0Z0M0E011 A=00 B=0700 D=0000 H=011A S=0100 P=0108 SUB C
C0Z1M0E111 A=00 B=0700 D=0000 H=011A S=0100 P=0109 JNC 010D
C0Z1M0E111 A=00 B=0700 D=0000 H=011A S=0100 P=010D INX H
C0Z1M0E111 A=00 B=0700 D=0000 H=011B S=0100 P=010E DCR B
C0Z0M0E111 A=00 B=0600 D=0000 H=011B S=0100 P=010F JNZ 0107
C0Z0M0E111 A=00 B=0600 D=0000 H=011B S=0100 P=0107 MOV A,M*0108

```

-A109

0109 JC 10D

Insert a "hot patch" into the machine code to change the JNC to JC

Program should have moved the value from A into C since A>C. Since this code was not executed, it appears that the JNC should have been a JC instruction

-G0

Stop DDT so that a version of the patched program can be saved

SAVE 1 SCAN.COM

Program resides on first page, so save 1 page.

A>DDT SCAN.COM

Restart DDT with the saved memory image to continue testing

16K DDT VER 1.0

NEXT PC

0200 0100

-L100

List some code

```

0100 MVI B,00
0102 MVI C,00
0104 LXI H,0119
0107 MOV A,M
0108 SUB C
0109 JC 010D
010C MOV C,A
010D INX H
010E DCR B
010F JNZ 0107
0112 MOV A,C

```

Previous patch is present in X.COM

-XF

P=0100

-T10

Trace to see how patched version operates

Data is moved from A to C

```

C0Z0M0E010 A=00 B=0000 D=0000 H=0000 S=0100 P=0100 MVI B,00
C0Z0M0E010 A=00 B=0000 D=0000 H=0000 S=0100 P=0102 MVI C,00
C0Z0M0E010 A=00 B=0000 D=0000 H=0000 S=0100 P=0104 LXI H,0119
C0Z0M0E010 A=00 B=0000 D=0000 H=0119 S=0100 P=0107 MOV A,M
C0Z0M0E010 A=02 B=0000 D=0000 H=0119 S=0100 P=0108 SUB C
C0Z0M0E011 A=02 B=0000 D=0000 H=0119 S=0100 P=0109 JC 010D
C0Z0M0E011 A=02 B=0000 D=0000 H=0119 S=0100 P=010C MOV C,A
C0Z0M0E011 A=02 B=0002 D=0000 H=0119 S=0100 P=010D INX H
C0Z0M0E011 A=02 B=0002 D=0000 H=011A S=0100 P=010E DCR B
C0Z0M0E011 A=02 B=0702 D=0000 H=011A S=0100 P=010F JNZ 0107
C0Z0M0E011 A=02 B=0702 D=0000 H=011A S=0100 P=0107 MOV A,M
C0Z0M0E011 A=00 B=0702 D=0000 H=011A S=0100 P=0108 SUB C
C1Z0M1E010 A=FE B=0702 D=0000 H=011A S=0100 P=0109 JC 010D
C1Z0M1E010 A=FE B=0702 D=0000 H=011A S=0100 P=010D INX H
C1Z0M1E010 A=FE B=0702 D=0000 H=011B S=0100 P=010E DCR B
C1Z0M0E111 A=FE B=0602 D=0000 H=011B S=0100 P=010F JNZ 0107*0107

```

-X

breakpoint after 16 steps

C1Z0M0E111 A=FE B=0602 D=0000 H=011B S=0100 P=0107 MOV A,M

-G.108

Run from current PC and breakpoint at 108H

*0108

-X

next data item

C1Z0M0E111 A=04 B=0602 D=0000 H=011B S=0100 P=0108 SUB C

-I

Single step for a few cycles

C020M0E111 A=04 B=0602 D=0000 H=011B S=0100 P=0100 SUB C,0109

-I

C020M0E011 A=02 B=0602 D=0000 H=011B S=0100 P=0109 JC 010D+010C

-X

C020M0E011 A=02 B=0602 D=0000 H=011B S=0100 P=010C MOV C,A

-G

Run to completion

*0116

-X

C021M0E111 A=03 B=0003 D=0000 H=0121 S=0100 P=0116 RST 07

-S121

look at the value of "LARGE"

0121 03 Wrong Value!

0122 00

0123 22

0124 21

0125 00

0126 02

End of the S command

0127 7E

-L100

```

0100 MVI B,03
0102 MVI C,00
0104 LXI H,0119
0107 MOV A,M
0108 SUB C
0109 JC 010D
010C MOV C,A
010D INX H
010E DCR B
010F JNZ 0107
0112 MOV A,C

```

Review the code

-L

```

0113 STA 0121
0116 RST 07
0117 NOP
0118 NOP
0119 STAX B
011A NOP
011B INR B
011C INX B
011D DCR B
011E MVI B,01
0120 DCR B

```

-XP

P=0116 100 Reset the PC

-I Single step, and watch data values

C021M0E111 A=03 B=0003 D=0000 H=0121 S=0100 P=0100 MVI B,03+0102

-I

C021M0E111 A=03 B=0003 D=0000 H=0121 S=0100 P=0102 MVI C,00+0104

-I

C021M0E111 A=03 B=0000 D=0000 H=0121 S=0100 P=0104 LXI H,0119+0107

-I

count set
"largest" set

```

                                ↙ base address of data set
C021M0E111 A=03 B=0000 D=0000 H=0119 S=0100 P=0107 MOV  A,M+0108
-I
C021M0E111 A=02 B=0000 D=0000 H=0119 S=0100 P=0108 SUB  C+0109
-I
C020M0E011 A=02 B=0000 D=0000 H=0119 S=0100 P=0109 JC   010D+010C
-I
C020M0E011 A=02 B=0000 D=0000 H=0119 S=0100 P=010C MOV  C,A+010D
-I
C020M0E011 A=02 B=0002 D=0000 H=0119 S=0100 P=010D INX  H+010E
-I
C020M0E011 A=02 B=0002 D=0000 H=011A S=0100 P=010E DCR  B+010F
-I
C020M0E011 A=02 B=0702 D=0000 H=011A S=0100 P=010F JNZ  0107+0107
-I
C020M0E011 A=02 B=0702 D=0000 H=011A S=0100 P=0107 MOV  A,M+0108
-I
C020M0E011 A=00 B=0702 D=0000 H=011A S=0100 P=0108 SUB  C+0109
-I
C120M1E010 A=FE B=0702 D=0000 H=011A S=0100 P=0109 JC   010D+010D
-I
C120M1E010 A=FE B=0702 D=0000 H=011A S=0100 P=010D INX  H+010E
-L100

```

```

0100 MVI  B,08
0102 MVI  C,00
0104 LXI  H,0119
0107 MOV  A,M
0108 SUB  C
0109 JC   010D
010C MOV  C,A
010D INX  H
010E DCR  B
010F JNZ  0107
0112 MOV  A,C
-W108

```

← This should have been a CMP so that register A would not be destroyed.

```
0108 CMP C    hot patch at 108H changes SUB to CMP
```

```
0109
```

```
-L0    stop DDT for SAVE
```

```
SAVE 1 SCAN.COM
```

save memory image
Restart DDT

```
H>DDT SCAN.COM
```

```
16K DDT VER 1.0
```

```
NEXT PC
```

```
0200 0100
```

```
-XF
```

```
F=0100
```

-L116

0116 RST 07
0117 NOP
0118 NOP
0119 STAX B
011A NOP
- (rubout)

} Look at code to see if it was properly loaded
(long typeout aborted with rubout)

-G.116 Run from 100H to completion

*0116

-XC Look at Carry (accidental typo)

C1

-X Look at CPU state

C121M0E111 A=06 B=0006 D=0000 H=0121 S=0100 P=0116 RST 07

-S121 Look at "Large" — it appears to be correct.

0121 06

0122 00

0123 22 .

-G0 stop DDT

ED SCAN.ASM Re-edit the source program, and make both changes

```
*NSUB
*0LT
SUB C ;LARGER VALUE IN C?
*SSUBZCMPZ0LT
CMP C ;LARGER VALUE IN C?
*
JNC NFOUND ;JUMP IF LARGER VALUE NOT FOUND
*SNCZCZ0LT
JC NFOUND ;JUMP IF LARGER VALUE NOT FOUND
*E
```

HSM SCAN.AAZ Re-assemble, selecting source from disk A
hex to disk A
CP/M ASSEMBLER - VER 1 0 print to Z (selects no print file)

0122
302H USE FACTOR
END OF ASSEMBLY

DDT SCAN HEX Re-run debugger to check changes

16K DDT VER 1.0
NEXT PC
0121 0000
-L116

0116 JMP 0000 check to ensure end is still at 116H
0119 STAX B
011A NOP
011B INR B
- (rubout)

-G100.116 Go from beginning with breakpoint at end

*0110 breakpoint reached
-D121 Look at "LARGE" correct value computed

0121 00 00 22 21 00 02 7E E8 77 13 23 EB 00 78 B1 . "LARGE" X
0130 C2 27 01 C3 03 29 00 00 00 00 00 00 00 00 00 00
0140 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00

- (rubout) aborts long typeout

-G0 stop DDT, debug session complete

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CP/M 2.2 ALTERATION GUIDE

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1. The first part of the document discusses the importance of maintaining accurate records of all transactions and activities. It emphasizes that proper record-keeping is essential for transparency and accountability, particularly in financial matters. This section also touches upon the legal implications of failing to maintain such records, which can lead to severe consequences for individuals and organizations alike.

2. The second part of the document delves into the specific requirements for record-keeping, including the types of records that must be maintained, the frequency of updates, and the methods used to store and retrieve information. It provides a detailed overview of the various types of records, such as financial statements, contracts, and correspondence, and explains how they should be organized and managed to ensure easy access and accuracy.

3. The third part of the document focuses on the role of technology in record-keeping. It discusses the benefits of using digital tools and software to manage records, such as increased efficiency, reduced risk of loss, and improved security. It also addresses the challenges associated with digital record-keeping, such as data migration and the need for robust backup and recovery plans.

4. The fourth part of the document provides a comprehensive guide to the legal and regulatory requirements for record-keeping. It covers the various laws and regulations that govern record-keeping practices, including those related to data privacy, financial reporting, and industry-specific regulations. It also provides practical advice on how to ensure compliance with these requirements, including the importance of staying up-to-date on changes in the law.

5. The fifth part of the document discusses the importance of record-keeping in the context of business operations. It explains how accurate records can help businesses make informed decisions, identify trends, and improve their overall performance. It also highlights the role of records in resolving disputes and protecting the interests of all parties involved.

6. The sixth part of the document provides a detailed overview of the various types of records that must be maintained, including financial records, legal records, and operational records. It explains the specific requirements for each type of record and provides practical advice on how to manage them effectively. It also discusses the importance of maintaining records for a sufficient period of time to ensure that they are available when needed.

7. The seventh part of the document focuses on the role of record-keeping in the context of data privacy and security. It discusses the various laws and regulations that govern data privacy, such as the General Data Protection Regulation (GDPR) and the California Consumer Privacy Act (CCPA). It also provides practical advice on how to ensure that records are stored and managed in a secure and compliant manner, including the importance of using encryption and access controls.

8. The eighth part of the document provides a comprehensive overview of the various tools and software that are available for record-keeping. It discusses the benefits of using these tools, such as increased efficiency and reduced risk of loss, and provides a detailed overview of the various options available. It also provides practical advice on how to choose the right tool for your needs, taking into account factors such as budget, scalability, and integration with other systems.

9. The ninth part of the document discusses the importance of record-keeping in the context of business continuity and disaster recovery. It explains how accurate records can help businesses recover from a disaster and resume operations as quickly as possible. It also provides practical advice on how to ensure that records are protected and available in the event of a disaster, including the importance of having a robust backup and recovery plan.

10. The tenth part of the document provides a detailed overview of the various challenges associated with record-keeping and provides practical advice on how to overcome them. It discusses the importance of having a clear record-keeping policy, the need for regular training and education, and the importance of staying up-to-date on changes in the law and technology. It also provides practical advice on how to ensure that records are maintained in a secure and compliant manner, including the importance of using encryption and access controls.

Introduction

The standard CP/M system assumes operation on an Intel MDS-800 microcomputer development system, but is designed so that the user can alter a specific set of subroutines which define the hardware operating environment. In this way, the user can produce a diskette which operates with any IBM-3741 format compatible drive controller and other peripheral devices.

Although standard CP/M 2.2 is configured for single density floppy disks, field-alteration features allow adaptation to a wide variety of disk subsystems from single drive minidisks through high-capacity "hard disk" systems. In order to simplify the following adaptation process, we assume that CP/M 2.2 will first be configured for single density floppy disks where minimal editing and debugging tools are available. If an earlier version of CP/M is available, the customizing process is eased considerably. In this latter case, you may wish to briefly review the system generation process, and skip to later sections which discuss system alteration for non-standard disk systems.

In order to achieve device independence, CP/M is separated into three distinct modules:

- BIOS — basic I/O system which is environment dependent
- BDOS — basic disk operating system which is not dependent upon the hardware configuration
- CCP — the console command processor which uses the BDOS

Of these modules, only the BIOS is dependent upon the particular hardware. That is, the user can "patch" the distribution version of CP/M to provide a new BIOS which provides a customized interface between the remaining CP/M modules and the user's own hardware system. The purpose of this document is to provide a step-by-step procedure for patching your new BIOS into CP/M.

If CP/M is being tailored to your computer system for the first time, the new BIOS requires some relatively simple software development and testing. The standard BIOS is listed in Appendix B, and can be used as a model for the customized package. A skeletal version of the BIOS is given in Appendix C which can serve as the basis for a modified BIOS. In addition to the BIOS, the user must write a simple memory loader, called GETSYS, which brings the operating system into memory. In order to patch the new BIOS into CP/M, the user must write the reverse of GETSYS, called PUTSYS, which places an altered version of CP/M back onto the diskette. PUTSYS can be derived from GETSYS by changing the disk read commands into disk write commands. Sample skeletal GETSYS and PUTSYS programs are described in Section 3, and listed in Appendix D. In order to make the CP/M system work automatically, the user must

also supply a cold start loader, similar to the one provided with CP/M (listed in Appendices A and B). A skeletal form of a cold start loader is given in Appendix E which can serve as a model for your loader.

First Level System Regeneration

The procedure to follow to patch the CP/M system is given below in several steps. Address references in each step are shown with a following "H" which denotes the hexadecimal radix, and are given for a 20K CP/M system. For larger CP/M systems, add a "bias" to each address which is shown with a "+b" following it, where b is equal to the memory size — 20K. Values for b in various standard memory sizes are

24K:	$b = 24K - 20K = 4K = 1000H$
32K:	$b = 32K - 20K = 12K = 3000H$
40K:	$b = 40K - 20K = 20K = 5000H$
48K:	$b = 48K - 20K = 28K = 7000H$
56K:	$b = 56K - 20K = 36K = 9000H$
62K:	$b = 62K - 20K = 42K = A800H$
64K:	$b = 64K - 20K = 44K = B000H$

Note: The standard distribution version of CP/M is set for operation within a 20K memory system. Therefore, you must first bring up the 20K CP/M system, and then configure it for your actual memory size (see Second Level System Generation).

- (1) Review Section 4 and write a GETSYS program which reads the first two tracks of a diskette into memory. The data from the diskette must begin at location 3380H. Code GETSYS so that it starts at location 100H (base of the TPA), as shown in the first part of Appendix d.
- (2) Test the GETSYS program by reading a blank diskette into memory, and check to see that the data has been read properly, and that the diskette has not been altered in any way by the GETSYS program.
- (3) Run the GETSYS program using an initialized CP/M diskette to see if GETSYS loads CP/M starting at 3380H (the operating system actually starts 128 bytes later at 3400H).
- (4) Review Section 4 and write the PUTSYS program which writes memory starting at 3380H back onto the first two tracks of the diskette. The PUTSYS program should be located at 200H, as shown in the second part of Appendix D.
- (5) Test the PUTSYS program using a blank uninitialized diskette by writing a portion of memory to the first two tracks; clear memory and read it back using GETSYS. Test PUTSYS completely, since this

program will be used to alter CP/M on disk.

- (6) Study Sections 5, 6, and 7, along with the distribution version of the BIOS given in Appendix B, and write a simple version which performs a similar function for the customized environment. Use the program given in Appendix C as a model. Call this new BIOS by the name CBIOS (customized BIOS). Implement only the primitive disk operations on a single drive, and simple console input/output functions in this phase.
- (7) Test CBIOS completely to ensure that it properly performs console character I/O and disk reads and writes. Be especially careful to ensure that no disk write operations occur accidentally during read operations, and check that the proper track and sectors are addressed on all reads and writes. Failure to make these checks may cause destruction of the initialized CP/M system after it is patched.
- (8) Referring to Figure 1 in Section 5, note that the BIOS is placed between locations 4A00H and 4FFFH. Read the CP/M system using GETSYS and replace the BIOS segment by the new CBIOS developed in step (6) and tested in step (7). This replacement is done in the memory of the machine, and will be placed on the diskette in the next step.
- (9) Use PUTSYS to place the patched memory image of CP/M onto the first two tracks of a blank diskette for testing.
- (10) Use GETSYS to bring the copied memory image from the test diskette back into memory at 3380H, and check to ensure that it has loaded back properly (clear memory, if possible, before the load). Upon successful load, branch to the cold start code at location 4A00H. The cold start routine will initialize page zero, then jump to the CCP at location 3400H which will call the BDOS, which will call the CBIOS. The CBIOS will be asked by the CCP to read sixteen sectors on track 2, and if successful, CP/M will type "A ", the system prompt.

When you make it this far, you are almost on the air. If you have trouble, use whatever debug facilities you have available to trace and breakpoint your CBIOS.

- (11) Upon completion of step (10), CP/M has prompted the console for a command input. Test the disk write operations by typing

SAVE 1 X.COM

(recall that all commands must be followed by a carriage return).

CP/M should respond with another prompt (after several disk accesses):

A

If it does not, debug your disk write functions and retry.

- (12) Then test the directory command by typing

DIR

CP/M should respond with

A: X COM

- (13) Test the erase command by typing

ERA X.COM

CP/M should respond with the A prompt. When you make it this far, you should have an operational system which will only require a bootstrap loader to function completely.

- (14) Write a bootstrap loader which is similar to GETSYS, and place it on track 0, sector 1 using PUTSYS (again using the test diskette, not the distribution diskette). See Sections 5 and 8 for more information on the bootstrap operation.
- (15) Retest the new test diskette with the bootstrap loader installed by executing steps (11), (12), and (13). Upon completion of these tests, type a control-C (control and C keys simultaneously). The system should then execute a "warm start" which reboots the system, and types the A prompt.
- (16) At this point, you probably have a good version of your customized CP/M system on your test diskette. Use GETSYS to load CP/M from your test diskette. Remove the test diskette, place the distribution diskette (or a legal copy) into the drive, and use PUTSYS to replace the distribution version by your customized version. Do not make this replacement if you are unsure of your patch since this step destroys the system which was sent to you from Digital Research.
- (17) Load your modified CP/M system and test it by typing

DIR

CP/M should respond with a list of files which are provided on the

initialized diskette. One such file should be the memory image for the debugger, called DDT.COM.

NOTE: from now on, it is important that you always reboot the CP/M system (ctl-C is sufficient) when the diskette is removed and replaced by another diskette, unless the new diskette is to be read only.

(18) Load and test the debugger by typing

DDT

(see the document "CP/M Dynamic Debugging Tool (DDT)" for operating procedures. You should take the time to become familiar with DDT, it will be your best friend in later steps.)

(19) Before making further CBIOS modifications, practice using the editor (see the ED user's guide), and assembler (see the ASM user's guide). Then recode and test the GETSYS, PUTSYS, and CBIOS programs using ED, ASM, and DDT. Code and test a COPY program which does a sector-to-sector copy from one diskette to another to obtain back-up copies of the original diskette (**NOTE:** read your CP/M Licensing Agreement; it specifies your legal responsibilities when copying the CP/M system). Place the copyright notice

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on each copy which is made with your COPY program.

(20) Modify your CBIOS to include the extra functions for punches, readers, signon messages, and so-forth, and add the facilities for additional disk drives, if desired. You can make these changes with the GETSYS and PUTSYS programs which you have developed, or you can refer to the following section, which outlines CP/M facilities which will aid you in the regeneration process.

You now have a good copy of the customized CP/M system. Note that although the CBIOS portion of CP/M which you have developed belongs to you, the modified version of CP/M which you have created can be copied for your use only (again, read your Licensing Agreement), and cannot be legally copied for anyone else's use.

It should be noted that your system remains file-compatible with all other CP/M systems, (assuming media compatibility, of course) which allows transfer of non-proprietary software between users of CP/M.

Second Level System Generation

Now that you have the CP/M system running, you will want to configure CP/M for your memory size. In general, you will first get a memory image of CP/M with the "MOVCPM" program (system relocater) and place this memory image into a named disk file. The disk file can then be loaded, examined, patched, and replaced using the debugger, and system generation program. For further details on the operation of these programs, see the "Guide to CP/M Features and Facilities" manual.

Your CBIOS and BOOT can be modified using ED, and assembled using ASM, producing files called CBIOS.HEX and BOOT.HEX, which contain the machine code for CBIOS and BOOT in Intel hex format.

To get the memory image of CP/M into the TPA configured for the desired memory size, give the command:

```
MOVCPM xx *
```

where "xx" is the memory size in decimal K bytes (e.g., 32 for 32K). The response will be:

```
CONSTRUCTING xxK CP/M VERS 2.0  
READY FOR "SYSGEN" OR  
"SAVE 34 CPMxx.COM"
```

At this point, an image of a CP/M in the TPA configured for the requested memory size. The memory image is at location 0900H through 227FH. (i.e., The BOOT is at 0900H, the CCP is at 980H, the BDOS starts at 1180H, and the BIOS is at 1F80H.) Note that the memory image has the standard MDS-800 BIOS and BOOT on it. It is now necessary to save the memory image in a file so that you can patch your CBIOS and CBOOT into it:

```
SAVE 34 CPMxx.COM
```

The memory image created by the "MOVCPM" program is offset by a negative bias so that it loads into the free area of the TPA, and thus does not interfere with the operation of CP/M in higher memory. This memory image can be subsequently loaded under DDT and examined or changed in preparation for a new generation of the system. DDT is loaded with the memory image by typing:

```
DDT CPMxx.COM
```

```
Load DDT, then read the CPM  
image
```

DDT should respond with

NEXT PC
2300 0100

—

(The DDT prompt)

You can then use the display and disassembly commands to examine portions of the memory image between 900H and 227FH. Note, however, that to find any particular address within the memory image, you must apply the negative bias to the CP/M address to find the actual address. Track 00, sector 01 is loaded to location 900H (you should find the cold start loader at 900H to 97FH), track 00, sector 02 is loaded into 980H (this is the base of the CCP), and so-forth through the entire CP/M system load. In a 20K system, for example, the CCP resides at the CP/M address 3400H, but is placed into memory at 980H by the SYSGEN program. Thus, the negative bias, denoted by n , satisfies

$$3400H + n = 980H, \text{ or } n = 980H - 3400H$$

Assuming two's complement arithmetic, $n = D580H$, which can be checked by

$$3400H + D580H = 10980H = 0980H \text{ ignoring high-order overflow).}$$

Note that for larger systems, n satisfies

$$\begin{aligned} (3400H + b) + n &= 980H, \text{ or} \\ n &= 980H - (3400H + b), \text{ or} \\ n &= D580H - b. \end{aligned}$$

The value of n for common CP/M systems is given below

memory size	bias b	negative offset n
20K	0000H	$D580H - 0000H = D580H$
24K	1000H	$D580H - 1000H = C580H$
32K	3000H	$D580H - 3000H = A580H$
40K	5000H	$D580H - 5000H = 8580H$
48K	7000H	$D580H - 7000H = 6580H$
56K	9000H	$D680H - 9000H = 4580H$
62K	A800H	$D580H - A800H = 2D80H$
64K	B000H	$D580H - B000H = 2580H$

Assume, for example, that you want to locate the address x within the memory image loaded under DDT in a 20K system. First type

Hx,n

Hexadecimal sum and difference

assume that your CBIOS is being integrated into a 20K CP/M system, and thus is originated at location 4A00H. In order to properly locate the CBIOS in the memory image under DDT, we must apply the negative bias n for a 20K system when loading the hex file. This is accomplished by typing

RD580

Read the file with bias D580H

Upon completion of the read, re-examine the area where the CBIOS has been loaded (use an "L1F80" command), to ensure that it was loaded properly. When you are satisfied that the change has been made, return from DDT using a control-C or "G0" command.

Now use SYSGEN to replace the patched memory image back onto a diskette (use a test diskette until you are sure of your patch), as shown in the following interaction

SYSGEN	Start the SYSGEN program
SYSGEN	VERSION 2.0
SYSGEN VERSION 2.0	Sign-on message from SYSGEN
SOURCE DRIVE NAME (OR RETURN TO SKIP)	Respond with a carriage return to skip the CP/M read operation since the system is already in memory.
DESTINATION DRIVE NAME (OR RETURN TO REBOOT)	Respond with "B" to write the new system to the diskette in drive B.
DESTINATION ON B, THEN TYPE RETURN	Place a scratch diskette in drive B, then type return.
FUNCTION COMPLETE	
DESTINATION DRIVE NAME (OR RETURN TO REBOOT)	

Place the scratch diskette in your drive A, and then perform a coldstart to bring up the new CP/M system you have configured.

Test the new CP/M system, and place the Digital Research copyright notice on the diskette, as specified in your Licensing Agreement:

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Sample GETSYS and PUTSYS Program

The following program provides a framework for the GETSYS and PUTSYS programs referenced in Section 2. The READSEC and WRITESEC subroutines must be inserted by the user to read and write the specific sectors.

```

; GETSYS PROGRAM — READ TRACKS 0 AND 1 TO MEMORY AT 3380H
; REGISTER USE
; A (SCRATCH REGISTER)
; B TRACK COUNT (0, 1)
; C SECTOR COUNT (1,2,...,26)
; DE (SCRATCH REGISTER PAIR)
; HL LOAD ADDRESS
; SP SET TO STACK ADDRESS
;
START: LXI SP,3380H ;SET STACK POINTER TO SCRATCH AREA
       LXI H, 3380H ;SET BASE LOAD ADDRESS
       MVI B, 0 ;START WITH TRACK 0
RDTRK: MVI C,1 ;READ NEXT TRACK (INITIALLY 0)
       ;READ STARTING WITH SECTOR 1
RDSEC: ; READ NEXT SECTOR
       CALL READSEC ;USER-SUPPLIED SUBROUTINE
       LXI D,128 ;MOVE LOAD ADDRESS TO NEXT 1/2 PAGE
       DAD D ;HL = HL + 128
       INR C ;SECTOR = SECTOR + 1
       MOV A,C ;CHECK FOR END OF TRACK
       CPI 27
       JC RDSEC ;CARRY GENERATED IF SECTOR 27
;
; ARRIVE HERE AT END OF TRACK, MOVE TO NEXT TRACK
       INR B
       MOV A,B ;TEST FOR LAST TRACK
       CPI 2
       JC RDTRK ;CARRY GENERATED IF TRACK 2
;
; ARRIVE HERE AT END OF LOAD, HALT FOR NOW
       HLT
;
; USER-SUPPLIED SUBROUTINE TO READ THE DISK
READSEC:
; ENTER WITH TRACK NUMBER IN REGISTER B,
; SECTOR NUMBER IN REGISTER C, AND
; ADDRESS TO FILL IN HL
       PUSH B ;SAVE B AND C REGISTERS
       PUSH H ;SAVE HL REGISTERS
       .....
perform disk read at this point, branch to
label START if an error occurs
       .....
       POP H ;RECOVER HL
       POP B ;RECOVER B AND C REGISTERS
       RET ;BACK TO MAIN PROGRAM
END START

```

Note that this program is assembled and listed in Appendix C for reference purposes, with an assumed origin of 100H. The hexadecimal operation codes which are listed on the left may be useful if the program has to be entered through your machine's front panel switches.

The PUTSYS program can be constructed from GETSYS by changing only a few operations in the GETSYS program given above, as shown in Appendix D. The register pair HL become the dump address (next address to write), and operations upon these registers do not change within the program. The READSEC subroutine is replaced by a WRITESEC subroutine which performs the opposite function: data from address HL is written to the track given by register B and sector given by register C. It is often useful to combine GETSYS and PUTSYS into a single program during the test and development phase, as shown in the Appendix.

Diskette Organization

The sector allocation for the standard distribution version of CP/M is given here for reference purposes. The first sector (see table on the following page) contains an optional software boot section. Disk controllers are often set up to bring track 0, sector 1 into memory at a specific location (often location 0000H). The program in this sector, called BOOT, has the responsibility of bringing the remaining sectors into memory starting at location 3400H+b. If your controller does not have a built-in sector load, you can ignore the program in track 0, sector 1, and begin the load from track 0 sector 2 to location 3400H+b.

As an example, the Intel MDS-800 hardware cold start loader brings track 0, sector 1 into absolute address, 3000H. Upon loading this sector, control transfers to location 3000H, where the bootstrap operation commences by loading the remainder of track 0, and all of track 1 into memory, starting at 3400H+b. The user should note that this bootstrap loader is of little use in a non-MDS environment, although it is useful to examine it since some of the boot actions will have to be duplicated in your cold start loader.

Track#	Sector#	Page#	Memory Address	CP/M Module name
00	01		(boot address)	Cold Start Loader
00	02	00	3400H+b	CCP
"	03	"	3480H+b	"
"	04	01	3500H+b	"
"	05	"	3580H+b	"
"	06	02	3600H+b	"
"	07	"	3680H+b	"
"	08	03	3700H+b	"
"	09	"	3780H+b	"
"	10	04	3800H+b	"
"	11	"	3880H+b	"
"	12	05	3900H+b	"
"	13	"	3980H+b	"
"	14	06	3A00H+b	"
"	15	"	3A80H+b	"
"	16	07	3B00H+b	"
00	17	"	3B80H+b	CCP
00	18	08	3C00H+b	BDOS
"	19	"	3C80H+b	"
"	20	09	3D00H+b	"
"	21	"	3D80H+b	"
"	22	10	3E00H+b	"
"	23	"	3E80H+b	"
"	24	11	3F00H+b	"
"	25	"	3F80H+b	"
"	26	12	4000H+b	"
01	01	"	4080H+b	"
"	02	13	4100H+b	"
"	03	"	4180H+b	"
"	04	14	4200H+b	"
"	05	"	4280H+b	"
"	06	15	4300H+b	"
"	07	"	4380H+b	"
"	08	16	4400H+b	"
"	09	"	4480H+b	"
"	10	17	4500H+b	"
"	11	"	4580H+b	"
"	12	18	4600H+b	"
"	13	"	4680H+b	"
"	14	19	4700H+b	"
"	15	"	4780H+b	"
"	16	20	4800H+b	"
"	17	"	4880H+b	"
"	18	21	4900H+b	"
01	19	"	4980H+b	BDOS
01	20	22	4A00H+b	BIOS
"	21	"	4A80H+b	"
"	23	23	4B00H+b	"
"	24	"	4B80H+b	"
"	25	24	4C00H+b	"
01	26	"	4C80H+b	BIOS
02-76	01-26			(directory and data)

(All Information Contained Herein is Proprietary to Digital Research.)

The Bios Entry Points

The entry points into the BIOS from the cold start loader and BDOS are detailed below. Entry to the BIOS is through a "jump vector" located at 4A00H+b, as shown below (see Appendices B and C, as well). The jump vector is a sequence of 17 jump instructions which send program control to the individual BIOS subroutines. The BIOS subroutines may be empty for certain functions (i.e., they may contain a single RET operation) during regeneration of CP/M, but the entries must be present in the jump vector.

The jump vector at 4A00H+b takes the form shown below, where the individual jump addresses are given to the left:

4A00H+b	JMP BOOT	; ARRIVE HERE FROM COLD START LOAD
4A03H+b	JMP WBOOT	; ARRIVE HERE FOR WARM START
4A06H+b	JMP CONST	; CHECK FOR CONSOLE CHAR READY
4A09H+b	JMP CONIN	; READ CONSOLE CHARACTER IN
4A0CH+b	JMP CONOUT	; WRITE CONSOLE CHARACTER OUT
4A0FH+b	JMP LIST	; WRITE LISTING CHARACTER OUT
4A12H+b	JMP PUNCH	; WRITE CHARACTER TO PUNCH DEVICE
4A15H+b	JMP READER	; READ READER DEVICE
4A18H+b	JMP HOME	; MOVE TO TRACK 00 ON SELECTED DISK
4A1BH+b	JMP SELDSK	; SELECT DISK DRIVE
4A1EH+b	JMP SETTRK	; SET TRACK NUMBER
4A21H+b	JMP SETSEC	; SET SECTOR NUMBER
4A24H+b	JMP SETDMA	; SET DMA ADDRESS
4A27H+b	JMP READ	; READ SELECTED SECTOR
4A2AH+b	JMP WRITE	; WRITE SELECTED SECTOR
4A2DH+b	JMP LISTST	; RETURN LIST STATUS
4A30H+b	JMP SECTTRAN	; SECTOR TRANSLATE SUBROUTINE

Each jump address corresponds to a particular subroutine which performs the specific function, as outlined below. There are three major divisions in the jump table: the system (re)initialization which results from calls on BOOT and WBOOT, simple character I/O performed by calls on CONST, CONIN, CONOUT, LIST, PUNCH, READER, and LISTST, and diskette I/O performed by calls on HOME, SELDSK, SETTRK, SETSEC, SETDMA, READ, WRITE, and SECTTRAN.

All simple character I/O operations are assumed to be performed in ASCII, upper and lower case, with high order (parity bit) set to zero. An end-of-file condition for an input device is given by an ASCII control-z (1AH). Peripheral devices are seen by CP/M as "logical" devices, and are assigned to physical devices within the BIOS.

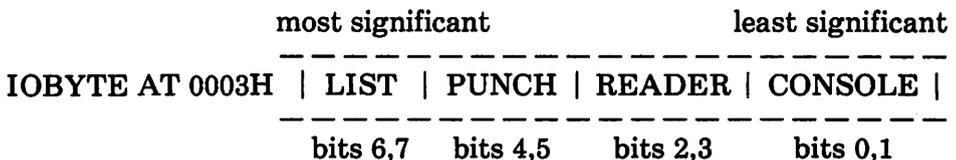
In order to operate, the BDOS needs only the CONST, CONIN, and CONOUT subroutines (LIST, PUNCH, and READER may be used by PIP, but not the BDOS). Further, the LISTST entry is used currently only by DESPOOL, and thus, the initial version of CBIOS may have empty subroutines for the remaining ASCII devices.

The characteristics of each device are

- CONSOLE** The principal interactive console which communicates with the operator, accessed through **CONST**, **CONIN**, and **CONOUT**. Typically, the **CONSOLE** is a device such as a **CRT** or **Teletype**.
- LIST** The principal listing device, if it exists on your system, which is usually a hard-copy device, such as a printer or **Teletype**.
- PUNCH** The principal tape punching device, if it exists, which is normally a high-speed paper tape punch or **Teletype**.
- READER** The principal tape reading device, such as a simple optical reader or **Teletype**.

Note that a single peripheral can be assigned as the **LIST**, **PUNCH**, and **READER** device simultaneously. If no peripheral device is assigned as the **LIST**, **PUNCH**, or **READER** device, the **CBIOS** created by the user may give an appropriate error message so that the system does not "hang" if the device is accessed by **PIP** or some other user program. Alternately, the **PUNCH** and **LIST** routines can just simply return, and the **READER** routine can return with a **1AH** (ctl-Z) in reg **A** to indicate immediate end-of-file.

For added flexibility, the user can optionally implement the "IOBYTE" function which allows reassignment of physical and logical devices. The **IOBYTE** function creates a mapping of logical to physical devices which can be altered during **CP/M** processing (see the **STAT** command). The definition of the **IOBYTE** function corresponds to the Intel standard as follows: a single location in memory (currently location **0003H**) is maintained, called **IOBYTE**, which defines the logical to physical device mapping which is in effect at a particular time. The mapping is performed by splitting the **IOBYTE** into four distinct fields of two bits each, called the **CONSOLE**, **READER**, **PUNCH**, and **LIST** fields, as shown below:



The value in each field can be in the range 0-3, defining the assigned source or destination of each logical device. The values which can be assigned to each field are given below

CONSOLE field (bits 0,1)

- 0 — console is assigned to the console printer device (TTY:)
- 1 — console is assigned to the CRT device (CRT:)
- 2 — batch mode: use the READER as the CONSOLE input, and the LIST device as the CONSOLE output (BAT:)
- 3 — user defined console device (UC1:)

READER field (bits 2,3)

- 0 — READER is the Teletype device (TTY:)
- 2 — READER is the high-speed reader device (RDR:)
- 2 — user defined reader # 1 (UR1:)
- 3 — user defined reader # 2 (UR2:)

PUNCH field (bits 4,5)

- 0 — PUNCH is the Teletype device (TTY:)
- 1 — PUNCH is the high speed punch device (PUN:)
- 2 — user defined punch # 1(UP1:)
- 3 — user defined punch # 2 (UP2:)

LIST field (bits 6,7)

- 0 — LIST is the Teletype device (TTY:)
- 1 — LIST is the CRT device (CRT:)
- 2 — LIST is the line printer device (LPT:)
- 3 — user defined list device (UL1:)

Note again that the implementation of the IOBYTE is optional, and affects only the organization of your CBIOS. No CP/M systems use the IOBYTE (although they tolerate the existence of the IOBYTE at location 0003H), except for PIP which allows access to the physical devices, and STAT which allows logical-physical assignments to be made and/or displayed (for more information, see the "CP/M Features and Facilities Guide"). In any case, the IOBYTE implementation should be omitted until your basic CBIOS is fully implemented and tested; then add the IOBYTE to increase your facilities.

Disk I/O is always performed through a sequence of calls on the various disk access subroutines which set up the disk number to access, the track and sector on a particular disk, and the direct memory access (DMA) address involved in the I/O operation. After all these parameters have been set up, a call is made to the READ or WRITE function to perform the actual I/O operation. Note that there is often a single call to SELDSK to select a disk drive, followed by a

number of read or write operations to the selected disk before selecting another drive for subsequent operations. Similarly, there may be a single call to set the DMA address, followed by several calls which read or write from the selected DMA address before the DMA address is changed. The track and sector subroutines are always called before the READ or WRITE operations are performed.

Note that the READ and WRITE routines should perform several retries (10 is standard) before reporting the error condition to the BDOS. If the error condition is returned to the BDOS, it will report the error to the user. The HOME subroutine may or may not actually perform the track 00 seek, depending upon your controller characteristics; the important point is that track 00 has been selected for the next operation, and is often treated in exactly the same manner as SETTRK with a parameter of 00.

The exact responsibilities of each entry point subroutine are given below:

BOOT

The BOOT entry point gets control from the cold start loader and is responsible for basic system initialization, including sending a signon message (which can be omitted in the first version). If the IOBYTE function is implemented, it must be set at this point. The various system parameters which are set by the WBOOT entry point must be initialized, and control is transferred to the CCP at 3400H+b for further processing. Note that reg C must be set to zero to select drive A.

WBOOT

The WBOOT entry point gets control when a warm start occurs. A warm start is performed whenever a user program branches to location 0000H, or when the CPU is reset from the front panel. The CP/M system must be loaded from the first two tracks of drive A up to, but not including, the BIOS (or CBIOS, if you have completed your patch). System parameters must be initialized as shown below:

location 0,1,2	set to JMP WBOOT for warm starts (0000H: JMP 4A03H+b)
location 3	set initial value of IOBYTE, if implemented in your CBIOS
location 5,6,7	set to JMP BDOS, which is the primary entry point to CP/M for transient programs. (0005H: JMP 3C06H+b)

(see Section 9 for complete details of page zero use) Upon completion of the initialization, the WBOOT program must branch to the CCP at 3400H+b to (re)start the system. Upon entry to the CCP, register C is set to the drive to select after system initialization.

- CONST** Sample the status of the currently assigned console device and return 0FFH in register A if a character is ready to read, and 00H in register A if no console characters are ready.
- CONIN** Read the next console character into register A, and set the parity bit (high order bit) to zero. If no console character is ready, wait until a character is typed before returning.
- CONOUT** Send the character from register C to the console output device. The character is in ASCII, with high order parity bit set to zero. You may want to include a time-out on a line feed or carriage return, if your console device requires some time interval at the end of the line (such as a TI Silent 700 terminal). You can, if you wish, filter out control characters which cause your console device to react in a strange way (a control-z causes the Lear Seigler terminal to clear the screen, for example).
- LIST** Send the character from register C to the currently assigned listing device. The character is in ASCII with zero parity.
- PUNCH** Send the character from register C to the currently assigned punch device. The character is in ASCII with zero parity.
- READER** Read the next character from the currently assigned reader device into register A with zero parity (high order bit must be zero), an end of file condition is reported by returning an ASCII control-z (1AH).
- HOME** Return the disk head of the currently selected disk (initially disk A) to the track 00 position. If your controller allows access to the track 0 flag from the drive, step the head until the track 0 flag is detected. If your controller does not support this feature, you can translate the HOME call into a call on SETTRK with a parameter of 0.
- SELDSK** Select the disk drive given by register C for further operations, where register C contains 0 for drive A, 1 for drive B, and so-forth up to 15 for drive P (the standard CP/M distribution version supports four drives). On each disk select, SELDSK must return in HL the base address of a 16-byte area, called the Disk Parameter Header, described

in the Section 10. For standard floppy disk drives, the contents of the header and associated tables does not change, and thus the program segment included in the sample CBIOS performs this operation automatically. If there is an attempt to select a non-existent drive, SELDSK returns HL=0000H as an error indicator. Although SELDSK must return the header address on each call, it is advisable to postpone the actual physical disk select operation until an I/O function (seek, read or write) is actually performed, since disk selects often occur without ultimately performing any disk I/O, and many controllers will unload the head of the current disk before selecting the new drive. This would cause an excessive amount of noise and disk wear.

SETTRK Register BC contains the track number for subsequent disk accesses on the currently selected drive. You can choose to seek the selected track at this time, or delay the seek until the next read or write actually occurs. Register BC can take on values in the range 0-76 corresponding to valid track numbers for standard floppy disk drives, and 0-65535 for non-standard disk subsystems.

SETSEC Register BC contains the sector number (1 through 26) for subsequent disk accesses on the currently selected drive. You can choose to send this information to the controller at this point, or instead delay sector selection until a read or write operation occurs.

SETDMA Register BC contains the DMA (disk memory access) address for subsequent read or write operations. For example, if B = 00H and C = 80H when SETDMA is called, then all subsequent read operations read their data into 80H through 0FFH, and all subsequent write operations get their data from 80H through 0FFH, until the next call to SETDMA occurs. The initial DMA address is assumed to be 80H. Note that the controller need not actually support direct memory access. If, for example, all data is received and sent through I/O ports, the CBIOS which you construct will use the 128 byte area starting at the selected DMA address for the memory buffer during the following read or write operations.

READ Assuming the drive has been selected, the track has been set, the sector has been set, and the DMA address has been specified, the READ subroutine attempts to read one sector based upon these parameters, and returns the following error codes in register A:

0	no errors occurred
1	non-recoverable error condition occurred

Currently, CP/M responds only to a zero or non-zero value as the return code. That is, if the value in register A is 0 then CP/M assumes that the disk operation completed properly. If an error occurs, however, the CBIOS should attempt at least 10 retries to see if the error is recoverable. When an error is reported the BDOS will print the message "BDOS ERR ON x: BAD SECTOR". The operator then has the option of typing <cr> to ignore the error, or ctl-C to abort.

- WRITE** Write the data from the currently selected DMA address to the currently selected drive, track, and sector. The data should be marked as "non deleted data" to maintain compatibility with other CP/M systems. The error codes given in the READ command are returned in register A, with error recovery attempts as described above.
- LISTST** Return the ready status of the list device. Used by the DESPOOL program to improve console response during its operation. The value 00 is returned in A if the list device is not ready to accept a character, and 0FFH if a character can be sent to the printer. Note that a 00 value always suffices.
- SECTRAN** Performs sector logical to physical sector translation in order to improve the overall response of CP/M. Standard CP/M systems are shipped with a "skew factor" of 6, where six physical sectors are skipped between each logical read operation. This skew factor allows enough time between sectors for most programs to load their buffers without missing the next sector. In particular computer systems which use fast processors, memory, and disk subsystems, the skew factor may be changed to improve overall response. Note, however, that you should maintain a single density IBM compatible version of CP/M for information transfer into and out of your computer system, using a skew factor of 6. In general, SECTRAN receives a logical sector number in BC, and a translate table address in DE. The sector number is used as an index into the translate table, with the resulting physical sector number in HL. For standard systems, the tables and indexing code is provided in the CBIOS and need not be changed.

A Sample BIOS

The program shown in Appendix C can serve as a basis for your first BIOS. The simplest functions are assumed in this BIOS, so that you can enter it through the front panel, if absolutely necessary. Note that the user must alter and insert code into the subroutines for CONST, CONIN, CONOUT, READ, WRITE, and WAITIO subroutines. Storage is reserved for user-supplied code in these regions. The scratch area reserved in page zero (see Section 9) for the BIOS is used in this program, so that it could be implemented in ROM, if desired.

Once operational, this skeletal version can be enhanced to print the initial sign-on message and perform better error recovery. The subroutines for LIST, PUNCH, and READER can be filled-out, and the IOBYTE function can be implemented.

A Sample Cold Start Loader

The program shown in Appendix D can serve as a basis for your cold start loader. The disk read function must be supplied by the user, and the program must be loaded somehow starting at location 0000. Note that space is reserved for your patch so that the total amount of storage required for the cold start loader is 128 bytes. Eventually, you will probably want to get this loader onto the first disk sector (track 0, sector 1), and cause your controller to load it into memory automatically upon system start-up. Alternatively, you may wish to place the cold start loader into ROM, and place it above the CP/M system. In this case, it will be necessary to originate the program at a higher address, and key-in a jump instruction at system start-up which branches to the loader. Subsequent warm starts will not require this key-in operation, since the entry point 'WBOOT' gets control, thus bringing the system in from disk automatically. Note also that the skeletal cold start loader has minimal error recovery, which may be enhanced on later versions.

Reserved Locations in Page Zero

Main memory page zero, between locations 00H and 0FFH, contains several segments of code and data which are used during CP/M processing. The code and data areas are given below for reference purposes.

Locations	Contents
from to	
000H — 0002H	Contains a jump instruction to the warm start entry point at location 4A03H+b. This allows a simple programmed restart (JMP 0000H) or manual restart from the front panel.

0003H — 0003H	Contains the Intel standard IOBYTE, which is optionally included in the user's CBIOS, as described in Section 6.
0004H — 0004H	Current default drive number (0=A, . . . ,15=P).
0005H — 0007H	Contains a jump instruction to the BDOS, and serves two purposes: JMP 0005H provides the primary entry point to the BDOS, as described in the manual "CP/M Interface Guide," and LHL 0006H brings the address field of the instruction to the HL register pair. This value is the lowest address in memory used by CP/M (assuming the CCP is being overlaid). Note that the DDT program will change the address field to reflect the reduced memory size in debug mode.
0008H — 0027H	(interrupt locations 1 through 5 not used)
0030H — 0037H	(interrupt location 6, not currently used — reserved)
0038H — 003AH	Restart 7 — Contains a jump instruction into the DDT or SID program when running in debug mode for programmed breakpoints, but is not otherwise used by CP/M.
003BH — 003FH	(not currently used — reserved)
0040H — 004FH	16 byte area reserved for scratch by CBIOS, but is not used for any purpose in the distribution version not used for any purpose in the distribution version of CP/M
0050H — 005BH	(not currently used — reserved)
005CH — 007CH	default file control block produced for a transient program by the Console Command Processor.
007DH — 007FH	Optional default random record position
0080H — 00FFH	default 128 byte disk buffer (also filled with the command line when a transient is loaded under the CCP).

Note that this information is set-up for normal operation under the CP/M system, but can be overwritten by a transient program if the BDOS facilities are not required by the transient.

If, for example, a particular program performs only simply I/O and must

begin execution at location 0, it can be first loaded into the TPA, using normal CP/M facilities, with a small memory move program which gets control when loaded (the memory move program must be control from location 0100H, which is the assumed beginning of all transient programs). The move program can then proceed to move the entire memory image down to location 0, and pass control to the starting address of the memory load. Note that if the BIOS is overwritten, or if location 0 (containing the warm start entry point) is overwritten, the the programmer must bring the CP/M system back into memory with a cold start sequence.

Disk Parameter Tables

Tables are included in the BIOS which describe the particular characteristics of the disk subsystem used with CP/M. These tables can be either hand-coded, as shown in the sample CBIOS in Appendix C, or automatically generated using the DISKDEF macro library, as shown in Appendix B. The purpose here is to describe the elements of these tables.

In general, each disk drive has an associated (16-byte) disk parameter header which both contains information about the disk drive and provides a scratchpad area for certain BDOS operations. The format of the disk parameter header for each drive is shown below

Disk		Parameter			Header		
XLT	0000	0000	0000	DIRBUF	DPB	CSV	ALV
16b	16b	16b	16b	16b	16b	16b	16b

where each element is a word (16-bit) value. The meaning of each Disk Parameter Header (DPH) element is

- XLT** Address of the logical to physical translation vector, if used for this particular drive, or the value 0000H if no sector translation takes place (i.e., the physical and logical sector numbers are the same). Disk drives with identical sector skew factors share the same translate tables.
- 0000** Scratchpad values for use within the BDOS (initial value is unimportant).
- DIRBUF** Address of a 128 byte scratchpad area for directory operations within BDOS. All DPH's address the same scratchpad area.
- DPB** Address of a disk parameter block for this drive. Drives with identical disk characteristics address the same disk parameter block.

CSV Address of a scratchpad area used for software check for changed disks. This address is different for each DPH.

ALV Address of a scratchpad area used by the BDOS to keep disk storage allocation information. This address is different for each DPH.

Given n disk drives, the DPH's are arranged in a table whose first row of 16 bytes corresponds to drive 0, with the last row corresponding to drive $n-1$. The table thus appears as

DPBASE:

00		XLT 00		0000		0000		0000		DIRBUF		DBP 00		CSV 00		ALV 00	
01		XLT 01		0000		0000		0000		DIRBUF		DBP 01		CSV 01		ALV 01	
(and so-forth through)																	
$n-1$		XLT $n-1$		0000		0000		0000		DIRBUF		DBP $n-1$		CSV $n-1$		ALV $n-1$	

where the label DBASE defines the base address of the DPH table.

A responsibility of the SELDSK subroutine is to return the base address of the DPH for the selected drive. The following sequence of operations returns the table address, with a 0000H returned if the selected drive does not exist.

```
NDISKS    EQU    4
NDISKS    EQU    4    ;NUMBER OF DISK DRIVES
```

.....
SELDSK:

```
      ;SELECT DISK GIVEN BY BC
      LXI    H,000H       ;ERROR CODE
      MOV    A,C           ;DRIVE OK?
      CPI    NDISKS       ;CY IF SO
      RNC                 ;RET IF ERROR
      ;NO ERROR, CONTINUE
      MOV    L,C           ;LOW (DISK)
      MOV    H,B           ;HIGH (DISK)
      DAD    H             ;*2
      DAD    H             ;*4
      DAD    H             ;*8
      DAD    H             ;*16
      LXI    D,DPBASE     ;FIRST DPH
      DAD    D             ;DPH (DISK)
      RET
```

The translation vectors (XLT 00 through XLTn-1) are located elsewhere in the BIOS, and simply correspond one-for-one with the logical sector numbers zero through the sector count-1. The Disk Parameter Block (DPB) for each drive is more complex. A particular DPB, which is addressed by one or more DPH's, takes the general form

SPT	BSH	BLM	EXM	DSM	DRM	AL0	AL1	CKS	OFF
16b	8b	8b	8b	16b	16b	8b	8b	16b	16b

where each is a byte or word value, as shown by the "8b" or "16b" indicator below the field.

- SPT** is the total number of sectors per track
- BSH** is the data allocation block shift factor, determined by the data block allocation size.
- EXM** is the extent mask, determined by the data block allocation size and the number of disk blocks.
- DSM** determines the total storage capacity of the disk drive
- DRM** determines the total number of directory entries which can be stored on this drive AL0,AL1 determine reserved directory blocks.
- CKS** is the size of the directory check vector
- OFF** is the number of reserved tracks at the beginning of the (logical) disk.

The values of BSH and BLM determine (implicitly) the data llocation size BLS, which is not an entry in the disk parameter block. Given that the designer has selected a value for BLS, the values of BSH and BLM are shown in the table below

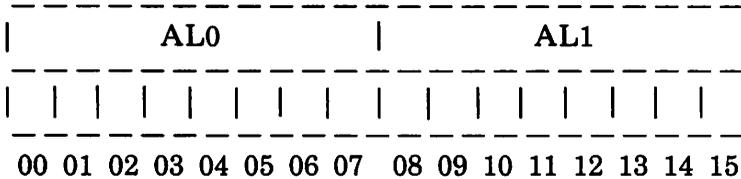
BLS	BSH	BLM
1,024	3	7
2,048	4	15
4,096	5	31
8,192	6	63
16,384	7	127

where all values are in decimal. The value of EXM depends upon both the BLS and whether the DSM value is less than 256 or greater than 255, as shown in the following table

BLS	DSM < 256	DSM > 255
1,024	0	N/A
2,048	1	0
4,096	3	1
8,192	7	3
16,384	15	7

The value of DSM is the maximum data block number supported by this particular drive, measured in BLS units. The product BLS times (DSM + 1) is the total number of bytes held by the drive and, of course, must be within the capacity of the physical disk, not counting the reserved operating system tracks.

The DRM entry is the one less than the total number of directory entries, which can take on a 16-bit value. The values of AL0 and AL1, however, are determined by DRM. The two values AL0 and AL1 can together be considered a string of 16-bits, as shown below.



where position 00 corresponds to the high order bit of the byte labelled AL0, and 15 corresponds to the low order bit of the byte labelled AL1. Each bit position reserves a data block for number of directory entries, thus allowing a total of 16 data blocks to be assigned for directory entries (bits are assigned starting at 00 and filled to the right until position 15). Each directory entry occupies 32 bytes, resulting in the following table

BLS	Directory Entries
1,024	32 times # bits
2,048	64 times # bits
4,096	128 times # bits
8,192	256 times # bits
16,384	512 times # bits

Thus, if DRM = 127 (128 director entries), and BLS = 1024, then there are 32 directory entries per block, requiring 4 reserved blocks. In this case, the 4 high order bits of AL0 are set, resulting in the values AL0 = 0F0H and AL1 = 00H.

The CKS value is determined as follows: if the disk drive media is removable, then $CKS = (DRM + 1) / 4$, where DRM is the last directory entry number. If the media is fixed, then set $CKS = 0$ (no directory records are checked in this case).

Finally, the OFF field determines the number of tracks which are skipped at the beginning of the physical disk. This value is automatically added whenever SETTRK is called, and can be used as a mechanism for skipping reserved operating system tracks, or for partitioning a large disk into smaller segmented sections.

To complete the discussion of the DPB, recall that several DPH's can address the same DPB if their drive characteristics are identical. Further, the DPB can be dynamically changed when a new drive is addressed by simply changing the pointer in the DPH since the BDOS copies the DPB values to a local area whenever the SELDSK function is invoked.

Returning back to the DPH for a particular drive, note that the two address values CSV and ALV remain. Both addresses reference an area of uninitialized memory following the BIOS. The areas must be unique for each drive, and the size of each area is determined by the values in the DPB.

The size of the area addressed by CSV is CKS bytes, which is sufficient to hold the directory check information for this particular drive. If $CKS = (DRM+1)/4$, then you must reserve $(DRM+1)/4$ bytes for directory check use. If $CKS = 0$, then no storage is reserved.

The size of the area addressed by ALV is determined by the maximum number of data blocks allowed for this particular disk, and is computed as $(DSM/8)+1$.

The CBIOS shown in Appendix C demonstrates an instance of these tables for standard 8'' single density drives. It may be useful to examine this program, and compare the tabular values with the definitions given above.

The DISKDEF Macro Library

A macro library is shown in Appendix F, called DISKDEF, which greatly simplifies the table construction process. You must have access to the MAC macro assembler, of course, to use the DISKDEF facility, while the macro library is included with all CP/M 2.0 distribution disks.

A BIOS disk definition consists of the following sequence of macro statements:

```

MACLIB      DISKDEF
.....
DISKS       n
DISKDEF     0,...
DISKDEF     1,...
.....
DISKDEF     n-1
.....
ENDEF

```

where the MACLIB statement loads the DISKDEF.LIB file (on the same disk as your BIOS) into MAC's internal tables. The DISKS macro call follows, which specifies the number of drives to be configured with your system, where n is an integer in the range 1 to 16. A series of DISKDEF macro calls then follow which define the characteristics of each logical disk, 0 through n-1 (corresponding to logical drives A through P). Note that the DISKS and DISKDEF macros generate the in-line fixed data tables described in the previous section, and thus must be placed in a non-executable portion of your BIOS, typically directly following the BIOS jump vector.

The remaining portion of your BIOS is defined following the DISKDEF macros, with the ENDEF macro call immediately preceding the END statement. The ENDEF (End of Diskdef) macro generates the necessary uninitialized RAM areas which are located in memory above your BIOS.

The form of the DISKDEF macro call is

```
DISKDEF dn,fsc,lsc,[skf],bls,dks,dir,cks,ofs,[0]
```

where

dn	is the logical disk number, 0 to n-1
fsc	is the first physical sector number (0 or 1)
lsc	is the last sector number
skf	is the optional sector skew factor
bls	is the data allocation block size
dir	is the number of directory entries
cks	is the number of "checked" directory entries
ofs	is the track offset to logical track 00
[0]	is an optional 1.4 compatibility flag

The value "dn" is the drive number being defined with this DISKDEF macro invocation. The "fsc" parameter accounts for differing sector numbering systems, and is usually 0 or 1. The "lsc" is the last numbered sector on a track. When present, the "skf" parameter defines the sector skew factor which is used to create a sector translation table according to the skew. If the number of sectors is less than 256, a single-byte table is created, otherwise each translation table element occupies two bytes. No

translation table is created if the `skf` parameter is omitted (or equal to 0). The `"bls"` parameter specifies the number of bytes allocated to each data block, and takes on the values 1024, 2048, 4096, 8192, or 16384. Generally, performance increases with larger data block sizes since there are fewer directory references and logically connected data records are physically close on the disk. Further, each directory entry addresses more data and the BIOS-resident ram space is reduced. The `"dks"` specifies the total disk size in `"bls"` units. That is, if the `bls = 2048` and `dks = 1000`, then the total disk capacity is 2,048,000 bytes. If `dks` is greater than 255, then the block size parameter `bls` must be greater than 1024. The value of `"dir"` is the total number of directory entries which may exceed 255, if desired. The `"cks"` parameter determines the number of directory items to check on each directory scan, and is used internally to detect changed disks during system operation, where an intervening cold or warm start has not occurred (when this situation is detected, CP/M automatically marks the disk read/only so that data is not subsequently destroyed). As stated in the previous section, the value of `cks = dir` when the media is easily changed, as is the case with a floppy disk subsystem. If the disk is permanently mounted, then the value of `cks` is typically 0, since the probability of changing disks without a restart is quite low. The `"ofs"` value determines the number of tracks to skip when this particular drive is addressed, which can be used to reserve additional operating system space or to simulate several logical drives on a single large capacity physical drive. Finally, the `[0]` parameter is included when file compatibility is required with versions of 1.4 which have been modified for higher density disks. This parameter ensures that only 16K is allocated for each directory record, as was the case for previous versions. Normally, this parameter is not included.

For convenience and economy of table space, the special form

```
DISKDEF      i,j
```

gives disk `i` the same characteristics as a previously defined drive `j`. A standard four-drive single density system, which is compatible with version 1.4, is defined using the following macro invocations:

```
DISKS        4
DISKDEF      0,1,26,6,1024,243,64,64,2
DISKDEF      1,0
DISKDEF      2,0
DISKDEF      3,0
. . . . .
ENDEF
```

with all disks having the same parameter values of 26 sectors per track (numbered 1 through 26), with 6 sectors skipped between each access, 1024 bytes per data block, 243 data blocks for a total of 243k byte disk capacity, 64 checked directory entries, and two operating system tracks.

The DISKS macro generates n Disk Parameter Headers (DPH's), starting at the DPH table address DPBASE generated by the macro. Each disk header block contains sixteen bytes, as described above, and correspond one-for-one to each of the defined drives. In the four drive standard system, for example, the DISKS macro generates a table of the form:

```
DPBASE EQU $
DPE0: DW XLT0,0000H,0000H,0000H,DIRBUF,DPB0,CSV0,ALV0
DPE1: DW XLT0,0000H,0000H,0000H,DIRBUF,DPB0,CSV1,ALV1
DPE2: DW XLT0,0000H,0000H,0000H,DIRBUF,DPB0,CSV2,ALV2
DPE3: DW XLT0,0000H,0000H,0000H,DIRBUF,DPB0,CSV3,ALV3
```

where the DPH labels are included for reference purposes to show the beginning table addresses for each drive 0 through 3. The values contained within the disk parameter header are described in detail in the previous section. The check and allocation vector addresses are generated by the ENDEF macro in the ram area following the BIOS code and tables.

Note that if the "skf" (skew factor) parameter is omitted (or equal to 0), the translation table is omitted, and a 0000H value is inserted in the XLT position of the disk parameter header for the disk. In a subsequent call to perform the logical to physical translation, SECTRAN receives a translation table address of DE = 0000H, and simply returns the original logical sector from BC in the HL register pair. A translate table is constructed when the skf parameter is present, and the (non-zero) table address is placed into the corresponding DPH's. The table shown below, for example, is constructed when the standard skew factor skf = 6 is specified in the DISKDEF macro call:

```
XLT0: DB 1,7,13,19,25,5,11,17,23,3,9,15,21
      DB 2,8,14,20,26,6,12,18,24,4,10,16,22
```

Following the ENDEF macro call, a number of uninitialized data areas are defined. These data areas need not be a part of the BIOS which is loaded upon cold start, but must be available between the BIOS and the end of memory. The size of the uninitialized RAM area is determined by EQU statements generated by the ENDEF macro. For a standard four-drive system, the ENDEF macro might produce

```
4C72 = BEGDAT EQU $
      (data areas)
4DB0 = ENDDAT EQU $
013C = DATSIZ EQU $-BEGDAT
```

which indicates that uninitialized RAM begins at location 4C72H, ends at 4DB0H-1, and occupies 013CH bytes. You must ensure that these addresses are free for use after the system is loaded.

After modification, you can use the STAT program to check your drive

characteristics, since STAT uses the disk parameter block to decode the drive information. The STAT command form

STAT d:DSK:

decodes the disk parameter block for drive d (d=A, . . . ,P) and displays the values shown below:

r: 128 Byte Record Capacity
k: Kilobyte Drive Capacity
d: 32 Byte Directory Entries
c: Checked Directory Entries
e: Records/ Extent
b: Records/ Block
s: Sectors/ Track
t: Reserved Tracks

Three examples of DISKDEF macro invocations are shown below with corresponding STAT parameter values (the last produces a full 8-megabyte system).

```
DISKDEF 0,1,58,,2048,256,128,128,2
r=4096, k=512, d=128, c=128, e=256, b=16, s=58, t=2
```

```
DISKDEF 0,1,58,,2048,1024,300,0,2
r=16384, k=2048, d=300, c=0, e=128, b=16, s=58, t=2
```

```
DISKDEF 0,1,58,,16384,512,128,128,2
r=65536, k=8192, d=128, c=128, e=1024, b=128, s=58, t=2
```

Sector Blocking and Deblocking

Upon each call to the BIOS WRITE entry point, the CP/M BDOS includes information which allows effective sector blocking and deblocking where the host disk subsystem has a sector size which is a multiple of the basic 128-byte unit. The purpose here is to present a general-purpose algorithm which can be included within your BIOS which uses the BDOS information to perform the operations automatically.

Upon each call to WRITE, the BDOS provides the following information in register C:

0 = normal sector write
1 = write to directory sector
2 = write to the first sector
of a new data block

Condition 0 occurs whenever the next write operation is into a previously written area, such as a random mode record update, when the write is to other than the first sector of an unallocated block, or when the write is not into the directory area. Condition 1 occurs when a write into the directory area is performed. Condition 2 occurs when the first record (only) of a newly allocated data block is written. In most cases, application programs read or write multiple 128 byte sectors in sequence, and thus there is little overhead involved in either operation when blocking and deblocking records since pre-read operations can be avoided when writing records.

Appendix G lists the blocking and deblocking algorithms in skeletal form (this file is included on your CP/M disk). Generally, the algorithms map all CP/M sector read operations onto the host disk through an intermediate buffer which is the size of the host disk sector. Throughout the program, values and variables which relate to the CP/M sector involved in a seek operation are prefixed by "sek", while those related to the host disk system are prefixed by "hst." The equate statements beginning on line 29 of Appendix G define the mapping between CP/M and the host system, and must be changed if other than the sample host system is involved.

The entry points BOOT and WBOOT must contain the initialization code starting on line 57, while the SELDSK entry point must be augmented by the code starting on line 65. Note that although the SELDSK entry point computes and returns the Disk Parameter Header address, it does not physically select the host disk at this point (it is selected later at READHST or WRITEHST). Further, SETTRK, SETSEC, and SETDMA simply store the values, but do not take any other action at this point. SECTRAN performs a trivial function of returning the physical sector number.

The principal entry points are READ and WRITE, starting on lines 110 and 125, respectively. These subroutines take the place of your previous READ and WRITE operations.

The actual physical read or write takes place at either WRITEHST or READHST, where all values have been prepared: hstdsk is the host disk number, hsttrk is the host track number, and hstsec is the host sector number (which may require translation to a physical sector number). You must insert code at this point which performs the full host sector read or write into, or out of, the buffer at hstbuf of length hstsiz. All other mapping functions are performed by the algorithms.

This particular algorithm was tested using an 80 megabyte hard disk unit which was originally configured for 128 byte sectors, producing approximately 35 megabytes of formatted storage. When configured for 512 byte host sectors, usable storage increased to 57 megabytes, with a corresponding 400% improvement in overall response. In this situation, there is no apparent overhead involved in deblocking sectors, with the

advantage that user programs still maintain the (less memory consuming) 128-byte sectors. This is primarily due, of course, to the information provided by the BDOS which eliminates the necessity for pre-read operations to take place.

APPENDIX A: THE MDS COLD START LOADER

```

;      MDS-800 Cold Start Loader for CP/M 2.0
;
;      Version 2.0 August, 1979
;
0000 = false    equ    0
ffff = true     equ    not false
0000 = testing  equ    false
;
      if      testing
bias   equ      03400h
      endif
      if      not testing
0000 = bias     equ    0000h
      endif
0000 = cpmb     equ    bias           ;base of dos load
0806 = bdos     equ    806h+bias      ;entry to dos for calls
1880 = bdose    equ    1880h+bias     ;end of dos load
1600 = boot     equ    1600h+bias     ;cold start entry point
1603 = rboot    equ    boot+3        ;warm start entry point
;
3000      org    3000h    ;loaded here by hardware
;
1880 = bdosl    equ    bdose-cpmb
0002 = ntrks    equ    2           ;tracks to read
0031 = bdoss    equ    bdosl/128    ;# sectors in bdos
0019 = bdos0    equ    25          ;# on track 0
0018 = bdosl    equ    bdoss-bdos0  ;# on track 1
;
f800 = mon80    equ    0f800h      ;intel monitor base
fff0 = rmon80   equ    0fff0h      ;restart location for mon80
0078 = base     equ    078h        ;'base' used by controller
0079 = rtype    equ    base+1      ;result type
007b = rbyte    equ    base+3      ;result byte
007f = reset    equ    base+7      ;reset controller
;
0078 = dstat    equ    base        ;disk status port
0079 = ilow     equ    base+1      ;low iopb address
007a = ihigh    equ    base+2      ;high iopb address
00ff = bsw      equ    0ffh        ;boot switch
0003 = recal    equ    3h          ;recalibrate selected drive
0004 = readf    equ    4h          ;disk read function
0100 = stack    equ    100h        ;use end of boot for stack
;
rstart:
3000 310001    lxi    sp,stack;in case of call to mon80
;      clear disk status
3003 db79      in     rtype
3005 db7b      in     rbyte
;      check if boot switch is off
coldstart:
3007 dbff      in     bsw
3009 e502      ani    02h
300b c20730    jnz    coldstart;switch on?

```

```

; clear the controller
300e d37f out reset ;logic cleared
;
;
3010 0602 mvi b,ntrks ;number of tracks to read
3012 214230 lxi h,iopb0
;
start:
;
; read first/next track into cpmb
3015 7d mov a,l
3016 d379 out ilow
3018 7c mov a,h
3019 d37a out ihigh
301b db78 wait0: in dstat
301d e604 ani 4
301f ca1b30 jz wait0
;
; check disk status
3022 db79 in rtype
3024 e603 ani llb
3026 fe02 cpi 2
;
; if testing
; cnc rmon80 ;go to monitor if ll or l0
; endif
; if not testing
3028 d20030 jnc rstart ;retry the load
; endif
;
; in rbyte ;i/o complete, check status
; if not ready, then go to mon80
302b db7b in rbyte
;
302d 17 ral
302e dc0fff cc rmon80 ;not ready bit set
3031 1f rar ;restore
3032 e61e ani 11110b ;overrun/addr err/seek/crc
;
; if testing
; cnz rmon80 ;go to monitor
; endif
; if not testing
3034 c20030 jnz rstart ;retry the load
; endif
;
;
; lxi d,iopbl ;length of iopb
3037 110700 lxi d,iopbl
303a 19 dad d ;addressing next iopb
303b 05 dcr b ;count down tracks
303c c21530 jnz start
;
;
; jmp boot, print message, set-up jmps
303f c30016 jmp boot
;
; parameter blocks

```

```

3042 80      iopb0:  db      80h      ;iocw, no update
3043 04      db      readf     ;read function
3044 19      db      bdos0    ;# sectors to read trk 0
3045 00      db      0         ;track 0
3046 02      db      2         ;start with sector 2, trk 0
3047 0000    dw      cpmb      ;start at base of bdos
0007 =      iopbl  equ      $-iopb0
;
3049 80      iopbl:  db      80h
304a 04      db      readf
304b 18      db      bdosl    ;sectors to read on track 1
304c 01      db      1         ;track 1
304d 01      db      1         ;sector 1
304e 800c    dw      cpmb+bdos0*128 ;base of second rd
3050      end

```

APPENDIX B: THE MDS BASIC I/O SYSTEM (BIOS)

```

;      mds-800 i/o drivers for cp/m 2.0
;      (four drive single density version)
;
;      version 2.0 august, 1979
;
0014 =  vers      equ      20      ;version 2.0
;
;      copyright (c) 1979
;      digital research
;      box 579, pacific grove
;      california, 93950
;
4a00      org      4a00h      ;base of bios in 20k system
3400 =    cpmb     equ      3400h      ;base of cpm ccp
3c06 =    bdos     equ      3c06h      ;base of bdos in 20k system
1600 =    cpml     equ      $-cpmb     ;length (in bytes) of cpm system
002c =    nsects   equ      cpml/128;number of sectors to load
0002 =    offset   equ      2         ;number of disk tracks used by cp
0004 =    cdisk    equ      0004h     ;address of last logged disk
0080 =    buff     equ      0080h     ;default buffer address
000a =    retry    equ      10        ;max retries on disk i/o before e
;
;      perform following functions
;      boot      cold start
;      wboot     warm start (save i/o byte)
;      (boot and wboot are the same for mds)
;      const     console status
;              reg-a = 00 if no character ready
;              reg-a = ff if character ready
;      conin     console character in (result in reg-a)
;      conout    console character out (char in reg-c)
;      list      list out (char in reg-c)
;      punch     punch out (char in reg-c)
;      reader    paper tape reader in (result to reg-a)
;      home      move to track 00
;
;      (the following calls set-up the io parameter bloc
;      mds, which is used to perform subsequent reads an
;      seldsk select disk given by reg-c (0,1,2...)
;      settrk set track address (0,...76) for sub r/w
;      setsec set sector address (1,...,26)
;      setdma set subsequent dma address (initially 80h)
;
;      read/write assume previous calls to set i/o parms
;      read      read track/sector to preset dma address
;      write     write track/sector from preset dma addres
;
;      jump vector for indiviual routines
4a00 c3b34a      jmp      boot
4a03 c3c34a      wboote: jmp      wboot
4a06 c3614b      jmp      const
4a09 c3644b      jmp      conin
4a0c c36a4b      jmp      conout

```

```

4a0f c36d4b      jmp      list
4a12 c3724b      jmp      punch
4a15 c3754b      jmp      reader
4a18 c3784b      jmp      home
4a1b c37d4b      jmp      seldsk
4a1e c3a74b      jmp      settrk
4a21 c3ac4b      jmp      setsec
4a24 c3bb4b      jmp      setdma
4a27 c3c14b      jmp      read
4a2a c3ca4b      jmp      write
4a2d c3704b      jmp      listst ;list status
4a30 c3b14b      jmp      sectran
;
maclib diskdef ;load the disk definition library
disks 4 ;four disks
4a33+= dpbase equ $ ;base of disk parameter blocks
4a33+824a00 dpe0: dw xlt0,0000h ;translate table
4a37+000000 dw 0000h,0000h ;scratch area
4a3b+6e4c73 dw dirbuf,dpb0 ;dir buff,param block
4a3f+0d4dee dw csv0,alv0 ;check, alloc vectors
4a43+824a00 dpe1: dw xlt1,0000h ;translate table
4a47+000000 dw 0000h,0000h ;scratch area
4a4b+6e4c73 dw dirbuf,dpb1 ;dir buff,param block
4a4f+3c4d1d dw csv1,alv1 ;check, alloc vectors
4a53+824a00 dpe2: dw xlt2,0000h ;translate table
4a57+000000 dw 0000h,0000h ;scratch area
4a5b+6e4c73 dw dirbuf,dpb2 ;dir buff,param block
4a5f+6b4d4c dw csv2,alv2 ;check, alloc vectors
4a63+824a00 dpe3: dw xlt3,0000h ;translate table
4a67+000000 dw 0000h,0000h ;scratch area
4a6b+6e4c73 dw dirbuf,dpb3 ;dir buff,param block
4a6f+9a4d7b dw csv3,alv3 ;check, alloc vectors
diskdef 0,1,26,6,1024,243,64,64,offset
4a73+= dpb0 equ $ ;disk parm block
4a73+1a00 dw 26 ;sec per track
4a75+03 db 3 ;block shift
4a76+07 db 7 ;block mask
4a77+00 db 0 ;extnt mask
4a78+f200 dw 242 ;disk size-1
4a7a+3f00 dw 63 ;directory max
4a7c+c0 db 192 ;alloc0
4a7d+00 db 0 ;allocl
4a7e+1000 dw 16 ;check size
4a80+0200 dw 2 ;offset
4a82+= xlt0 equ $ ;translate table
4a82+01 db 1
4a83+07 db 7
4a84+0d db 13
4a85+13 db 19
4a86+19 db 25
4a87+05 db 5
4a88+0b db 11
4a89+11 db 17
4a8a+17 db 23
4a8b+03 db 3

```

```

4a8c+09      db      9
4a8d+0f      db      15
4a8e+15      db      21
4a8f+02      db      2
4a90+08      db      8
4a91+0e      db      14
4a92+14      db      20
4a93+1a      db      26
4a94+06      db      6
4a95+0c      db      12
4a96+12      db      18
4a97+18      db      24
4a98+04      db      4
4a99+0a      db      10
4a9a+10      db      16
4a9b+16      db      22
              diskdef 1,0
4a73+=       dpb1     equ      dpb0      ;equivalent parameters
001f+=       als1     equ      als0      ;same allocation vector size
0010+=       css1     equ      css0      ;same checksum vector size
4a82+=       xlt1     equ      xlt0      ;same translate table
              diskdef 2,0
4a73+=       dpb2     equ      dpb0      ;equivalent parameters
001f+=       als2     equ      als0      ;same allocation vector size
0010+=       css2     equ      css0      ;same checksum vector size
4a82+=       xlt2     equ      xlt0      ;same translate table
              diskdef 3,0
4a73+=       dpb3     equ      dpb0      ;equivalent parameters
001f+=       als3     equ      als0      ;same allocation vector size
0010+=       css3     equ      css0      ;same checksum vector size
4a82+=       xlt3     equ      xlt0      ;same translate table
              ;      endif occurs at end of assembly
              ;
              ;      end of controller - independent code, the remaini
              ;      are tailored to the particular operating environm
              ;      be altered for any system which differs from the
              ;
              ;      the following code assumes the mds monitor exists
              ;      and uses the i/o subroutines within the monitor
              ;
              ;      we also assume the mds system has four disk drive
00fd =       revrt    equ      0fdh      ;interrupt revert port
00fc =       intc     equ      0fch      ;interrupt mask port
00f3 =       icon     equ      0f3h      ;interrupt control port
007e =       inte     equ      0111$1110b;enable rst 0(warm boot),rst 7
              ;
              ;      mds monitor equates
f800 =       mon80    equ      0f800h    ;mds monitor
ff0f =       rmon80   equ      0ff0fh    ;restart mon80 (boot error)
f803 =       ci       equ      0f803h    ;console character to reg-a
f806 =       ri       equ      0f806h    ;reader in to reg-a
f809 =       co       equ      0f809h    ;console char from c to console o
f80c =       po       equ      0f80ch    ;punch char from c to punch devic
f80f =       lo       equ      0f80fh    ;list from c to list device
f812 =       csts     equ      0f812h    ;console status 00/ff to register

```

```

;
; disk ports and commands
0078 = equ 78h ;base of disk command io ports
0078 = dstat equ base ;disk status (input)
0079 = rtype equ base+1 ;result type (input)
007b = rbyte equ base+3 ;result byte (input)
;
0079 = ilow equ base+1 ;iopb low address (output)
007a = ihigh equ base+2 ;iopb high address (output)
;
0004 = readf equ 4h ;read function
0006 = writf equ 6h ;write function
0003 = recal equ 3h ;recalibrate drive
0004 = iordy equ 4h ;i/o finished mask
000d = cr equ 0dh ;carriage return
000a = lf equ 0ah ;line feed
;
signon: ;signon message: xxk cp/m vers y.y
4a9c 0d0a0a db cr,lf,lf
4a9f 3230 db '20' ;sample memory size
4aa1 6b2043f db 'k cp/m vers '
4aad 322e30 db vers/10+'0','.',vers mod 10+'0'
4ab0 0d0a00 db cr,lf,0
;
boot: ;print signon message and go to ccp
; (note: mds boot initialized iobyte at 0003h)
4ab3 310001 lxi sp,buff+80h
4ab6 219c4a lxi h,signon
4ab9 cdd34b call prmsg ;print message
4abc af xra a ;clear accumulator
4abd 320400 sta cdisk ;set initially to disk a
4ac0 c30f4b jmp gocpm ;go to cp/m
;
;
wboot:; loader on track 0, sector 1, which will be skippe
; read cp/m from disk - assuming there is a 128 byt
; start.
;
4ac3 318000 lxi sp,buff ;using dma - thus 80 thru ff ok f
;
4ac6 0e0a mvi c,retry ;max retries
4ac8 c5 push b
wboot0: ;enter here on error retries
4ac9 010034 lxi b,cpmb ;set dma address to start of disk
4acc cdbb4b call setdma
4acf 0e00 mvi c,0 ;boot from drive 0
4ad1 cd7d4b call seldsk
4ad4 0e00 mvi c,0
4ad6 cda74b call settrk ;start with track 0
4ad9 0e02 mvi c,2 ;start reading sector 2
4adb cdac4b call setsec
;
; read sectors, count nsects to zero
4ade c1 pop b ;10-error count
4adf 062c mvi b,nsects

```

```

rdsec: ;read next sector
4ae1 c5      push    b      ;save sector count
4ae2 cdcl4b  call    read
4ae5 c2494b  jnz    booterr ;retry if errors occur
4ae8 2a6c4c  lhld   iod      ;increment dma address
4aeb 118000  lxi    d,128    ;sector size
4aee 19      dad    d      ;incremented dma address in hl
4aef 44      mov    b,h
4af0 4d      mov    c,l      ;ready for call to set dma
4af1 cdbb4b  call   setdma
4af4 3a6b4c  lda    ios      ;sector number just read
4af7 fela    cpi    26       ;read last sector?
4af9 da054b  jc     rd1
;
4afc 3a6a4c  lda    iot      ;get track to register a
4aff 3c      inr    a
4b00 4f      mov    c,a      ;ready for call
4b01 cda74b  call   settrk
4b04 af      xra    a      ;clear sector number
4b05 3c      rdl:   inr    a      ;to next sector
4b06 4f      mov    c,a      ;ready for call
4b07 cdac4b  call   setsec
4b0a c1      pop    b      ;recall sector count
4b0b 05      dcr    b      ;done?
4b0c c2e14a  jnz   rdsec
;
; done with the load, reset default buffer address
; gocpm: ;(enter here from cold start boot)
; enable rst0 and rst7
4b0f f3      di
4b10 3e12    mvi    a,12h   ;initialize command
4b12 d3fd    out    revrt
4b14 af      xra    a
4b15 d3fc    out    intc    ;cleared
4b17 3e7e    mvi    a,inte  ;rst0 and rst7 bits on
4b19 d3fc    out    intc
4b1b af      xra    a
4b1c d3f3    out    icon    ;interrupt control
;
; set default buffer address to 80h
4b1e 018000  lxi    b,buff
4b21 cdbb4b  call   setdma
;
; reset monitor entry points
4b24 3ec3    mvi    a,jmp
4b26 320000  sta    0
4b29 21034a  lxi    h,wboote
4b2c 220100  shld   1      ;jmp wboot at location 00
4b2f 320500  sta    5
4b32 21063c  lxi    h,bdos
4b35 220600  shld   6      ;jmp bdos at location 5
4b38 323800  sta    7*8    ;jmp to mon80 (may have been chan
4b3b 2100f8  lxi    h,mon80
4b3e 223900  shld   7*8+1
; leave iobyte set

```

```

;          previously selected disk was b, send parameter to
4b41 3a0400 ;          lda      cdisk ;last logged disk number
4b44 4f      ;          mov      c,a   ;send to ccp to log it in
4b45 fb      ;          ei
4b46 c30034 ;          jmp      cpmb
;
;          error condition occurred, print message and retry
booterr:
4b49 c1      ;          pop      b   ;recall counts
4b4a 0d      ;          dcr      c
4b4b ca524b ;          jz       booter0
;          try again
4b4e c5      ;          push     b
4b4f c3c94a ;          jmp      wboot0
;
booter0:
;          otherwise too many retries
4b52 215b4b ;          lxi      h,bootmsg
4b55 cdd34b ;          call     prmsg
4b58 c30fff ;          jmp      rmon80 ;mds hardware monitor
;
bootmsg:
4b5b 3f626f4 ;         db       '?boot',0
;
;
const: ;console status to reg-a
;       (exactly the same as mds call)
4b61 c312f8 ;       jmp      csts
;
conin: ;console character to reg-a
4b64 cd03f8 ;       call     ci
4b67 e67f   ;       ani      7fh   ;remove parity bit
4b69 c9     ;       ret
;
conout: ;console character from c to console out
4b6a c309f8 ;       jmp      co
;
list: ;list device out
;      (exactly the same as mds call)
4b6d c30ff8 ;       jmp      lo
;
listst:
;       return list status
4b70 af     ;       xra      a
4b71 c9     ;       ret          ;always not ready
;
punch: ;punch device out
;      (exactly the same as mds call)
4b72 c30cf8 ;       jmp      po
;
reader: ;reader character in to reg-a
;      (exactly the same as mds call)
4b75 c306f8 ;       jmp      ri
;
home: ;move to home position

```

```

;      treat as track 00 seek
4b78 0e00      mvi      c,0
4b7a c3a74b    jmp      settrk
;
seldsk: ;select disk given by register c
4b7d 210000    lxi      h,0000h ;return 0000 if error
4b80 79        mov      a,c
4b81 fe04      cpi      ndisks ;too large?
4b83 d0        rnc      ;leave hl = 0000
;
4b84 e602      ani      l0b ;00 00 for drive 0,1 and 10 10 fo
4b86 32664c    sta      dbank ;to select drive bank
4b89 79        mov      a,c ;00, 01, 10, 11
4b8a e601      ani      lb ;mds has 0,1 at 78, 2,3 at 88
4b8c b7        ora      a ;result 00?
4b8d ca924b    jz      setdrive
4b90 3e30      mvi      a,00110000b ;selects drive 1 in bank
setdrive:
4b92 47        mov      b,a ;save the function
4b93 21684c    lxi      h,iof ;io function
4b96 7e        mov      a,m
4b97 e6cf      ani      11001111b ;mask out disk number
4b99 b0        ora      b ;mask in new disk number
4b9a 77        mov      m,a ;save it in iopb
4b9b 69        moy      l,0
4b9c 2500      mvi      h,0 ;hl=disk number
4b9e 29        dad      h ;*2
4b9f 29        dad      h ;*4
4ba0 29        dad      h ;*8
4ba1 29        dad      h ;*16
4ba2 11334a    lxi      d,dpbase
4ba5 19        dad      d ;hl=disk header table address
4ba6 c9        ret
;
;
settrk: ;set track address given by c
4ba7 216a4c    lxi      h,iot
4baa 71        mov      m,c
4bab c9        ret
;
setsec: ;set sector number given by c
4bac 216b4c    lxi      h,ios
4baf 71        mov      m,c
4bb0 c9        ret
sectran:
;translate sector bc using table at de
4bb1 0600      mvi      b,0 ;double precision sector number i
4bb3 eb      xchg ;translate table address to hl
4bb4 09      dad      b ;translate(sector) address
4bb5 7e      mov      a,m ;translated sector number to a
4bb6 326b4c    sta      ios
4bb9 6f      moy      l,a ;return sector number in l
4bba c9      ret
;
setdma: ;set dma address given by regs b,c

```

```

4bbb 69          mov     l,c
4bbc 60          mov     h,b
4bbd 226c4c     shld   iod
4bc0 c9          ret

;
read:           ;read next disk record (assuming disk/trk/sec/dma
4bcl 0e04       mvi     c,readf ;set to read function
4bc3 cde04b     call    setfunc
4bc6 cdf04b     call    waitio  ;perform read function
4bc9 c9          ret     ;may have error set in reg-a

;
;
write:         ;disk write function
4bca 0e06       mvi     c,writf
4bcc cde04b     call    setfunc ;set to write function
4bcf cdf04b     call    waitio
4bd2 c9          ret     ;may have error set

;
;
utility subroutines
prmsg:        ;print message at h,l to 0
4bd3 7e         mov     a,m
4bd4 b7         ora     a      ;zero?
4bd5 c8         rz

;
;
more to print
4bd6 e5         push   h
4bd7 4f         mov     c,a
4bd8 cd6a4b     call   conout
4bdb e1         pop    h
4bdc 23         inx   h
4bdd c3d34b     jmp    prmsg

;
setfunc:
;
set function for next i/o (command in reg-c)
4be0 21684c     lxi    h,iof  ;io function address
4be3 7e         mov     a,m    ;get it to accumulator for maskin
4be4 e6f8       ani    lllll000b ;remove previous command
4be6 bl         ora     c      ;set to new command
4be7 77         mov     m,a    ;replaced in iopb

;
the mds-800 controller req's disk bank bit in sec
mask the bit from the current i/o function
4be8 e620       ani    00100000b ;mask the disk select bit
4bea 216b4c     lxi    h,ios   ;address the sector selec
4bed b6         ora     m      ;select proper disk bank
4bee 77         mov     m,a    ;set disk select bit on/o
4bef c9          ret

;
waitio:
4bf0 0e0a       mvi     c,retry ;max retries before perm error

rewait:
;
start the i/o function and wait for completion
4bf2 cd3f4c     call   intype  ;in rtype
4bf5 cd4c4c     call   inbyte  ;clears the controller

;
4bf8 3a664c     lda     dbank  ;set bank flags

```

```

4bfb b7          ora      a          ;zero if drive 0,1 and nz
4bfc 3e67        mvi      a,iopb and 0ffh ;low address for iopb
4bfe 064c        mvi      b,iopb shr 8    ;high address for iopb
4c00 c20b4c     jnz     iodrl          ;drive bank 1?
4c03 d379        out      ilow          ;low address to controlle
4c05 78          mov      a,b
4c06 d37a        out      ihigh         ;high address
4c08 c3104c     jmp     wait0          ;to wait for complete
;
iodrl:           ;drive bank 1
4c0b d389        out      ilow+10h       ;88 for drive bank 10
4c0d 78          mov      a,b
4c0e d38a        out      ihigh+10h
;
4c10 cd594c     wait0:  call     instat        ;wait for completion
4c13 e604        ani      iordy         ;ready?
4c15 ca104c     jz      wait0
;
; check io completion ok
4c18 cd3f4c     call     intype         ;must be io complete (00)
; 00 unlinked i/o complete, 01 linked i/o comple
; 10 disk status changed 11 (not used)
4c1b fe02        cpi      l0b           ;ready status change?
4c1d ca324c     jz      wready
;
; must be 00 in the accumulator
4c20 b7          ora      a
4c21 c2384c     jnz     werror         ;some other condition, re
;
; check i/o error bits
4c24 cd4c4c     call     inbyte
4c27 17          ral
4c28 da324c     jc      wready         ;unit not ready
4c2b 1f          rar
4c2c e6fe        ani      1111110b      ;any other errors?
4c2e c2384c     jnz     werror
;
; read or write is ok, accumulator contains zero
4c31 c9          ret
;
wready:         ;not ready, treat as error for now
4c32 cd4c4c     call     inbyte         ;clear result byte
4c35 c3384c     jmp     trycount
;
werror:         ;return hardware malfunction (crc, track, seek, e
; the mds controller has returned a bit in each pos
; of the accumulator, corresponding to the conditio
; 0 - deleted data (accepted as ok above)
; 1 - crc error
; 2 - seek error
; 3 - address error (hardware malfunction)
; 4 - data over/under flow (hardware malfunct
; 5 - write protect (treated as not ready)
; 6 - write error (hardware malfunction)
; 7 - not ready

```

```

;          (accumulator bits are numbered 7 6 5 4 3 2 1 0)
;
;          it may be useful to filter out the various condit
;          but we will get a permanent error message if it i
;          recoverable.  in any case, the not ready conditio
;          treated as a separate condition for later improve
trycount:
;          register c contains retry count, decrement 'til z
4c38 0d          dcr      c
4c39 c2f24b     jnz      await ;for another try
;
;          cannot recover from error
4c3c 3e01     mvi      a,1      ;error code
4c3e c9          ret
;
;          intype, inbyte, instat read drive bank 00 or 10
4c3f 3a664c   intype:  lda      dbank
4c42 b7          ora      a
4c43 c2494c   jnz      intypl ;skip to bank 10
4c46 db79     in       rtype
4c48 c9          ret
4c49 db89     intypl:  in       rtype+10h      ;78 for 0,1 88 for 2,3
4c4b c9          ret
;
4c4c 3a664c   inbyte:  lda      dbank
4c4f b7          ora      a
4c50 c2564c   jnz      inbytl
4c53 db7b     in       rbyte
4c55 c9          ret
4c56 db8b     inbytl:  in       rbyte+10h
4c58 c9          ret
;
4c59 3a664c   instat:  lda      dbank
4c5c b7          ora      a
4c5d c2634c   jnz      instal
4c60 db78     in       dstat
4c62 c9          ret
4c63 db88     instal:  in       dstat+10h
4c65 c9          ret
;
;
;          data areas (must be in ram)
4c66 00     dbank:  db       0          ;disk bank 00 if drive 0,1
;          ;          10 if drive 2,3
;
;          iopb:   ;io parameter block
4c67 80     db       80h        ;normal i/o operation
4c68 04     ioof:   db       readf    ;io function, initial read
4c69 01     ion:    db       1        ;number of sectors to read
4c6a 02     iot:    db       offset   ;track number
4c6b 01     ios:    db       1        ;sector number
4c6c 8000   iod:    dw       buff     ;io address
;
;
;          define ram areas for bdos operation

```

```

                                endef
4c6e+=      begdat  equ      $
4c6e+      dirbuf:  ds       128      ;directory access buffer
4cee+      alv0:    ds       31
4d0d+      csv0:    ds       16
4d1d+      alv1:    ds       31
4d3c+      csv1:    ds       16
4d4c+      alv2:    ds       31
4d6b+      csv2:    ds       16
4d7b+      alv3:    ds       31
4d9a+      csv3:    ds       16
4daa+=      enddat  equ      $
013c+=      datsiz  equ      $-begdat
4daa      end

```

APPENDIX C: A SKELETAL CBIOS

```

;       skeletal cbios for first level of cp/m 2.0 altera
;
0014 =  msize   equ     20           ;cp/m version memory size in kilo
;
;       "bias" is address offset from 3400h for memory sy
;       than 16k (referred to as "b" throughout the text)
;
0000 =  bias    equ     (msize-20)*1024
3400 =  ccp     equ     3400h+bias   ;base of ccp
3c06 =  bdos   equ     ccp+806h     ;base of bdos
4a00 =  bios    equ     ccp+1600h    ;base of bios
0004 =  cdisk   equ     0004h      ;current disk number 0=a,...,15=p
0003 =  iobyte  equ     0003h      ;intel i/o byte
;
4a00 =  org     bios    ;origin of this program
002c =  nsects  equ     ($-ccp)/128  ;warm start sector count
;
;       jump vector for individual subroutines
4a00 c39c4a   jmp     boot           ;cold start
4a03 c3a64a   wboote: jmp     wboot          ;warm start
4a06 c3114b   jmp     const          ;console status
4a09 c3244b   jmp     conin          ;console character in
4a0c c3374b   jmp     conout         ;console character out
4a0f c3494b   jmp     list           ;list character out
4a12 c34d4b   jmp     punch         ;punch character out
4a15 c34f4b   jmp     reader        ;reader character out
4a18 c3544b   jmp     home           ;move head to home positi
4al8 c35a4b   jmp     seldisk       ;select disk
4ale c37d4b   jmp     settrk        ;set track number
4a21 c3924b   jmp     setsec        ;set sector number
4a24 c3ad4b   jmp     setdma       ;set dma address
4a27 c3c34b   jmp     read          ;read disk
4a2a c3d64b   jmp     write         ;write disk
4a2d c34b4b   jmp     listst       ;return list status
4a30 c3a74b   jmp     sectran      ;sector translate
;
;       fixed data tables for four-drive standard
;       ibm-compatible 8" disks
;       disk parameter header for disk 00
4a33 734a00   dpbase: dw     trans,0000h
4a37 000000   dw     0000h,0000h
4a3b f04c8d   dw     dirbf,dpblk
4a3f ec4d70   dw     chk00,all00
;       disk parameter header for disk 01
4a43 734a00   dw     trans,0000h
4a47 000000   dw     0000h,0000h
4a4b f04c8d   dw     dirbf,dpblk
4a4f fc4d8f   dw     chk01,all01
;       disk parameter header for disk 02
4a53 734a00   dw     trans,0000h
4a57 000000   dw     0000h,0000h
4a5b f04c8d   dw     dirbf,dpblk
4a5f 0c4eae   dw     chk02,all02

```

```

;          disk parameter header for disk 03
4a63 734a00      dw      trans,0000h
4a67 000000      dw      0000h,0000h
4a6b f04c8d      dw      dirbf,dpblk
4a6f 1c4ecd      dw      chk03,all03
;
;          sector translate vector
4a73 01070d      trans:  db      1,7,13,19      ;sectors 1,2,3,4
4a77 19050b      db      25,5,11,17      ;sectors 5,6,7,8
4a7b 170309      db      23,3,9,15      ;sectors 9,10,11,12
4a7f 150208      db      21,2,8,14      ;sectors 13,14,15,16
4a83 141a06      db      20,26,6,12     ;sectors 17,18,19,20
4a87 121804      db      18,24,4,10     ;sectors 21,22,23,24
4a8b 1016        db      16,22         ;sectors 25,26
;
dpblk: ;disk parameter block, common to all disks
4a8d 1a00        dw      26             ;sectors per track
4a8f 03          db      3             ;block shift factor
4a90 07          db      7             ;block mask
4a91 00          db      0             ;null mask
4a92 f200        dw      242          ;disk size-1
4a94 3f00        dw      63            ;directory max
4a96 c0          db      192          ;alloc 0
4a97 00          db      0             ;alloc 1
4a98 1000        dw      16            ;check size
4a9a 0200        dw      2             ;track offset
;
;          end of fixed tables
;
;          individual subroutines to perform each function
boot: ;simplest case is to just perform parameter initi
4a9c af          xra      a             ;zero in the accum
4a9d 320300      sta      iobyte      ;clear the iobyte
4aa0 320400      sta      cdisk       ;select disk zero
4aa3 c3ef4a      jmp      gocpm        ;initialize and go to cp/
;
wboot: ;simplest case is to read the disk until all sect
4aa6 318000      lxi      sp,80h      ;use space below buffer f
4aa9 0e00        mvi      c,0         ;select disk 0
4aab cd5a4b      call     seldsk     ;select disk
4aae cd544b      call     home        ;go to track 00
;
4ab1 062c        mvi      b,nsects   ;b counts # of sectors to
4ab3 0e00        mvi      c,0         ;c has the current track
4ab5 1602        mvi      d,2         ;d has the next sector to
;          note that we begin by reading track 0, sector 2 s
;          contains the cold start loader, which is skipped
4ab7 210034      lxi      h,ccp      ;base of cp/m (initial lo
loadl: ;load one more sector
4aba c5          push     b           ;save sector count, current track
4abb d5          push     d           ;save next sector to read
4abc e5          push     h           ;save dma address
4abd 4a          mov      c,d         ;get sector address to register c
4abe cd924b      call     setsec     ;set sector address from register
4acl cl         pop      b           ;recall dma address to b,c

```

```

4ac2 c5      push    b      ;replace on stack for later recal
4ac3 cdad4b  call    setdma ;set dma address from b,c
;
;
drive set to 0, track set, sector set, dma address
4ac6 cdc34b  call    read
4ac9 fe00    cpi     00h    ;any errors?
4acb c2a64a   jnz     wboot  ;retry the entire boot if an erro
;
;
no error, move to next sector
4ace e1      pop     h      ;recall dma address
4acf 118000   lxi     d,128  ;dma=dma+128
4ad2 19      dad     d      ;new dma address is in h,l
4ad3 d1      pop     d      ;recall sector address
4ad4 c1      pop     b      ;recall number of sectors remaini
4ad5 05      dcr     b      ;sectors=sectors-1
4ad6 caef4a   jz      gocpm  ;transfer to cp/m if all have bee
;
;
more sectors remain to load, check for track chan
4ad9 14      inr     d
4ada 7a      mov     a,d    ;sector=27?, if so, change tracks
4adb felb    cpi     27
4add daba4a   jc     loadl  ;carry generated if sector<27
;
;
end of current track, go to next track
4ae0 1601    mvi     d,1    ;begin with first sector of next
4ae2 0c      inr     c      ;track=track+1
;
;
save register state, and change tracks
4ae3 c5      push    b
4ae4 d5      push    d
4ae5 e5      push    h
4ae6 cd7d4b  call    settrk ;track address set from register
4ae9 e1      pop     h
4aea d1      pop     d
4aeb c1      pop     b
4aec c3ba4a   jmp     loadl  ;for another sector
;
;
end of load operation, set parameters and go to c
gocpm:
4aef 3ec3    mvi     a,0c3h ;c3 is a jmp instruction
4af1 320000   sta     0      ;for jmp to wboot
4af4 21034a   lxi     h,wboote ;wboot entry point
4af7 220100   shld   1      ;set address field for jmp at 0
;
;
4afa 320500   sta     5      ;for jmp to bdos
4afd 21063c   lxi     h,bdos ;bdos entry point
4b00 220600   shld   6      ;address field of jump at 5 to bd
;
;
4b03 018000   lxi     b,80h  ;default dma address is 80h
4b06 cdad4b  call    setdma
;
;
4b09 fb      ei         ;enable the interrupt system
4b0a 3a0400   lda     cdisk  ;get current disk number
4b0d 4f      mov     c,a    ;send to the ccp
4b0e c30034   jmp     ccp    ;go to cp/m for further processin

```

```

;
;
;       simple i/o handlers (must be filled in by user)
;       in each case, the entry point is provided, with s
;       to insert your own code
;
const: ;console status, return 0ffh if character ready,
4b11      ds      10h      ;space for status subroutine
4b21 3e00 mvi      a,00h
4b23 c9    ret

;
conin:  ;console character into register a
4b24      ds      10h      ;space for input routine
4b34 e67f ani      7fh      ;strip parity bit
4b36 c9    ret

;
conout: ;console character output from register c
4b37 79    mov     a,c      ;get to accumulator
4b38      ds      10h      ;space for output routine
4b48 c9    ret

;
list:   ;list character from register c
4b49 79    mov     a,c      ;character to register a
4b4a c9    ret          ;null subroutine

;
listst: ;return list status (0 if not ready, 1 if ready)
4b4b af    xra     a      ;0 is always ok to return
4b4c c9    ret

;
punch:  ;punch character from register c
4b4d 79    mov     a,c      ;character to register a
4b4e c9    ret          ;null subroutine

;
;
reader: ;read character into register a from reader device
4b4f 3ela  mvi     a,lah      ;enter end of file for now (repla
4b51 e67f ani     7fh      ;remember to strip parity bit
4b53 c9    ret

;
;
;       i/o drivers for the disk follow
;       for now, we will simply store the parameters away
;       in the read and write subroutines
;
home:   ;move to the track 00 position of current drive
;       translate this call into a settrk call with param
4b54 0e00 mvi     c,0      ;select track 0
4b56 cd7d4b call    settrk
4b59 c9    ret          ;we will move to 00 on first read

;
seldsk: ;select disk given by register c
4b5a 210000 lxi    h,0000h   ;error return code
4b5d 79    mov     a,c
4b5e 32ef4c sta    diskno
4b61 fe04 cpi     4          ;must be between 0 and 3

```

```

4b63 d0      rnc          ;no carry if 4,5,...
;
4b64         ds          l0      ;space for disk select
;
4b6e 3aef4c  lda          diskno
4b71 6f      mov          l,a      ;l=disk number 0,1,2,3
4b72 2600    mvi          h,0      ;high order zero
4b74 29      dad          h      ;*2
4b75 29      dad          h      ;*4
4b76 29      dad          h      ;*8
4b77 29      dad          h      ;*16 (size of each header)
4b78 11334a lxi          d,dpbase
4b7b 19      dad          d      ;hl=.dpbase(diskno*16)
4b7c c9      ret
;
settrk: ;set track given by register c
4b7d 79      mov          a,c
4b7e 32e94c  sta          track
4b81         ds          l0h     ;space for track select
4b91 c9      ret
;
setsec: ;set sector given by register c
4b92 79      mov          a,c
4b93 32eb4c  sta          sector
4b96         ds          l0h     ;space for sector select
4ba6 c9      ret
;
sectran:
;translate the sector given by bc using the
;translate table given by de
4ba7 eb      xchg         ;hl=.trans
4ba8 09      dad          b      ;hl=.trans(sector)
4ba9 6e      mov          l,m     ;l = trans(sector)
4baa 2600    mvi          h,0     ;hl= trans(sector)
4bac c9      ret          ;with value in hl
;
setdma: ;set dma address given by registers b and c
4bad 69      mov          l,c     ;low order address
4bae 60      mov          h,b     ;high order address
4baf 22ed4c  shld        dmaad   ;save the address
4bb2         ds          l0h     ;space for setting the dma address
4bc2 c9      ret
;
read: ;perform read operation (usually this is similar
; so we will allow space to set up read command, th
; common code in write)
4bc3         ds          l0h     ;set up read command
4bd3 c3e64b  jmp         waitio  ;to perform the actual i/o
;
write: ;perform a write operation
4bd6         ds          l0h     ;set up write command
;
waitio: ;enter here from read and write to perform the ac
; operation. return a 00h in register a if the ope
; properly, and 01h if an error occurs during the r

```

```

;
;   in this case, we have saved the disk number in 'd
;   the track number in 'track' (0-76
;   the sector number in 'sector' (1-
;   the dma address in 'dmaad' (0-655
4be6          ds      256    ;space reserved for i/o drivers
4ce6 3e01     mvi      a,1    ;error condition
4ce8 c9       ret          ;replaced when filled-in
;
;   the remainder of the cbios is reserved uninitiali
;   data area, and does not need to be a part of the
;   system memory image (the space must be available,
;   however, between "begdat" and "enddat").
;
4ce9          track: ds      2      ;two bytes for expansion
4ceb          sector: ds     2      ;two bytes for expansion
4ced          dmaad: ds     2      ;direct memory address
4cef          diskno: ds     1      ;disk number 0-15
;
;   scratch ram area for bdos use
4cf0 =        begdat  equ     $      ;beginning of data area
4cf0          dirbf: ds    128     ;scratch directory area
4d70          all00: ds     31     ;allocation vector 0
4d8f          all01: ds     31     ;allocation vector 1
4dae          all02: ds     31     ;allocation vector 2
4dcd          all03: ds     31     ;allocation vector 3
4dec          chk00: ds     16     ;check vector 0
4dfc          chk01: ds     16     ;check vector 1
4e0c          chk02: ds     16     ;check vector 2
4e1c          chk03: ds     16     ;check vector 3
;
4e2c =        enddat  equ     $      ;end of data area
013c =        datsiz  equ     $-begdat;size of data area
4e2c          end

```

APPENDIX D: A SKELETAL GETSYS/PUTSYS PROGRAM

```

;      combined getsys and putsys programs from Sec 4.
;      Start the programs at the base of the TPA

0100          org      0100h

0014 =      msize   equ      20          ; size of cp/m in Kbytes

; "bias" is the amount to add to addresses for > 20k
;      (referred to as "b" throughout the text)

0000 =      bias    equ      (msize-20)*1024
3400 =      ccp     equ      3400h+bias
3c00 =      bdos    equ      ccp+0800h
4a00 =      bios    equ      ccp+1600h

;      getsys programs tracks 0 and 1 to memory at
;      3880h + bias

;      register          usage
;      a                (scratch register)
;      b                track count (0...76)
;      c                sector count (1...26)
;      d,e              (scratch register pair)
;      h,l              load address
;      sp               set to stack address

gstart:
0100 318033    lxi      sp,ccp-0080h          ; start of getsys
0103 218033    lxi      h,ccp-0080h          ; convenient plac
0106 0600      mvi      b,0                ; set initial loa
; start with trac
rd$trk:
0108 0e01      mvi      c,1                ; read next track
; each track star
rd$sec:
010a cd0003    call     read$sec          ; get the next se
010d 118000    lxi      d,128          ; offset by one s
0110 19        dad      d                ; (hl=hl+128)
0111 0c        inr      c                ; next sector
0112 79        mov      a,c                ; fetch sector nu
0113 felb     cpi      27          ; and see if la
0115 da0a01    jc       rdsec          ; <, do one more

; arrive here at end of track, move to next track

0118 04        inr      b                ; track = track+1
0119 78        mov      a,b                ; check for last
011a fe02     cpi      2                ; track = 2 ?
011c da0801    jc       rd$trk          ; <, do another

; arrive here at end of load, halt for lack of anything b

011f fb        ei
0120 76        hlt

```

```

;      putsys program, places memory image starting at
;      3880h + bias back to tracks 0 and 1
;      start this program at the next page boundary

0200          org      ($+0100h) and 0ff00h

put$sys:
0200 318033    lxi      sp,ccp-0080h      ; convenient plac
0203 218033    lxi      h,ccp-0080h      ; start of dump
0206 0600      mvi      b,0              ; start with trac

wr$trk:
0208 0e01      mvi      c,1              ; start with sect

wr$sec:
020a cd0004    call     write$sec           ; write one secto
020d 118000    lxi      d,128                    ; length of each
0210 19        dad      d                  ; <hl>=<hl> + 128
0211 0c        inr     c                    ; <c> = <c> + 1
0212 79        mov     a,c                  ; see if
0213 felb      cpi     27                    ; past end of t
0215 da0a02    jc      wr$sec              ; no, do another

; arrive here at end of track, move to next track

0218 04        inr     b                    ; track = track+1
0219 78        mov     a,b                  ; see if
021a fe02      cpi     2                    ; last track
021c da0802    jc      wr$trk              ; no, do another

; done with putsys, halt for lack of anything better

021f fb        ei
0220 76        hlt

; user supplied subroutines for sector read and write
; move to next page boundary

0300          org      ($+0100h) and 0ff00h

read$sec:
; read the next sector
; track in <b>,
; sector in <c>
; dmaaddr in <hl>

0300 c5        push    b
0301 e5        push    h

; user defined read operation goes here
0302          ds      64

0342 e1        pop     h
0343 c1        pop     b

```

```

0344 c9          ret
0400           org      ($+0100h) and 0ff00h      ; another page bo
write$sec:
                ; same parameters as read$sec
0400 c5          push    b
0401 e5          push    h
                ; user defined write operation goes here
0402           ds      64
0442 e1          pop     h
0443 c1          pop     b
0444 c9          ret
                ; end of getsys/putsys program
0445           end

```

APPENDIX E: A SKELETAL COLD START LOADER

```

; this is a sample cold start loader which, when modified
; resides on track 00, sector 01 (the first sector on the
; diskette). we assume that the controller has loaded
; this sector into memory upon system start-up (this pro-
; gram can be keyed-in, or can exist in read/only memory
; beyond the address space of the cp/m version you are
; running). the cold start loader brings the cp/m system
; into memory at "loadp" (3400h + "bias"). in a 20k
; memory system, the value of "bias" is 0000h, with large
; values for increased memory sizes (see section 2). afte
; loading the cp/m system, the clod start loader branches
; to the "boot" entry point of the bios, which begins at
; "bios" + "bias." the cold start loader is not used un-
; til the system is powered up again, as long as the bios
; is not overwritten. the origin is assumed at 0000h, an
; must be changed if the controller brings the cold start
; loader into another area, or if a read/only memory area
; is used.

```

```

0000          org      0          ; base of ram in cp/m
0014 =        msize   equ      20          ; min mem size in kbytes
0000 =        bias    equ      (msize-20)*1024 ; offset from 20k system
3400 =        ccp     equ      3400h+bias   ; base of the ccp
4a00 =        bios    equ      ccp+1600h    ; base of the bios
0300 =        biosl   equ      0300h      ; length of the bios
4a00 =        boot    equ      bios
1900 =        size    equ      bios+biosl-ccp ; size of cp/m system
0032 =        sects   equ      size/128    ; # of sectors to load

```

```

;          begin the load operation

```

```

cold:

```

```

0000 010200    lxi      b,2          ; b=0, c=sector 2
0003 1632     mvi      d,sects    ; d=# sectors to load
0005 210034    lxi      h,ccp         ; base transfer address

```

```

lsect: ; load the next sector

```

```

;          insert inline code at this point to
;          read one 128 byte sector from the
;          track given in register b, sector
;          given in register c,
;          into the address given by <hl>
;
;          branch to location "cold" if a read error occurs

```

```

; *****
; *
; *      user supplied read operation goes here...
; *
; *****

0008 c36b00      jmp      past$patch      ; remove this when patche
000b              ds      60h

      past$patch:
; go to next sector if load is incomplete
006b 15          dcr      d          ; sects=sects-1
006c ca004a      jz       boot          ; head for the bios

;      more sectors to load
;
; we aren't using a stack, so use <sp> as scratch registe
;      to hold the load address increment

006f 318000      lxi     sp,128          ; 128 bytes per sector
0072 39          dad     sp          ; <hl> = <hl> + 128

0073 0c          inr     c          ; sector = sector + 1
0074 79          mov     a,c
0075 felb       cpi     27          ; last sector of track?
0077 da0800      jc      lsect          ; no, go read another

; end of track, increment to next track

007a 0e01        mvi     c,1            ; sector = 1
007c 04          inr     b            ; track = track + 1
007d c30800      jmp     lsect          ; for another group
0080              end      ; of boot loader

```

APPENDIX F: CP/M DISK DEFINITION LIBRARY

```

1: ;           CP/M 2.0 disk re-definition library
2: ;
3: ;           Copyright (c) 1979
4: ;           Digital Research
5: ;           Box 579
6: ;           Pacific Grove, CA
7: ;           93950
8: ;
9: ;           CP/M logical disk drives are defined using the
10: ;          macros given below, where the sequence of calls
11: ;          is:
12: ;
13: ;          disks      n
14: ;          diskdef parameter-list-0
15: ;          diskdef parameter-list-1
16: ;          ...
17: ;          diskdef parameter-list-n
18: ;          endif
19: ;
20: ;          where n is the number of logical disk drives attached
21: ;          to the CP/M system, and parameter-list-i defines the
22: ;          characteristics of the ith drive (i=0,1,...,n-1)
23: ;
24: ;          each parameter-list-i takes the form
25: ;              dn,fsc,lsc,[skf],bls,dks,dir,cks,ofs,[0]
26: ;          where
27: ;          dn          is the disk number 0,1,...,n-1
28: ;          fsc         is the first sector number (usually 0 or 1)
29: ;          lsc         is the last sector number on a track
30: ;          skf         is optional "skew factor" for sector translate
31: ;          bls         is the data block size (1024,2048,...,16384)
32: ;          dks         is the disk size in bls increments (word)
33: ;          dir         is the number of directory elements (word)
34: ;          cks         is the number of dir elements to checksum
35: ;          ofs         is the number of tracks to skip (word)
36: ;          [0]        is an optional 0 which forces 16K/directory en
37: ;
38: ;          for convenience, the form
39: ;              dn,dm
40: ;          defines disk dn as having the same characteristics as
41: ;          a previously defined disk dm.
42: ;
43: ;          a standard four drive CP/M system is defined by
44: ;              disks      4
45: ;              diskdef 0,1,26,6,1024,243,64,64,2
46: ;          dsk          set      0
47: ;                      rept     3
48: ;          dsk          set      dsk+1
49: ;              diskdef %dsk,0
50: ;          endm
51: ;          endif
52: ;
53: ;          the value of "begdat" at the end of assembly defines t

```

```

54: ; beginning of the uninitialize ram area above the bios,
55: ; while the value of "enddat" defines the next location
56: ; following the end of the data area. the size of this
57: ; area is given by the value of "datsiz" at the end of t
58: ; assembly. note that the allocation vector will be qui
59: ; large if a large disk size is defined with a small blo
60: ; size.
61: ;
62: dskhdr macro dn
63: ;; define a single disk header list
64: dpe&dn: dw xlt&dn,0000h ;translate table
65: dw 0000h,0000h ;scratch area
66: dw dirbuf,dpb&dn ;dir buff,param block
67: dw csv&dn,alv&dn ;check, alloc vectors
68: endm
69: ;
70: disks macro nd
71: ;; define nd disks
72: ndisks set nd ;;for later reference
73: dpbase equ $ ;base of disk parameter blocks
74: ;; generate the nd elements
75: dsknxt set 0
76: rept nd
77: dskhdr %dsknxt
78: dsknxt set dsknxc+1
79: endm
80: endm
81: ;
82: dpbhdr macro dn
83: dpb&dn equ $ ;disk parm block
84: endm
85: ;
86: ddb macro data,comment
87: ;; define a db statement
88: db data comment
89: endm
90: ;
91: ddw macro data,comment
92: ;; define a dw statement
93: dw data comment
94: endm
95: ;
96: gcd macro m,n
97: ;; greatest common divisor of m,n
98: ;; produces value gcdn as result
99: ;; (used in sector translate table generation)
100: gcdm set m ;;variable for m
101: gcdn set n ;;variable for n
102: gcdr set 0 ;;variable for r
103: rept 65535
104: gcdx set gcdm/gcdn
105: gcdr set gcdm - gcdx*gcdn
106: if gcdr = 0
107: exitm
108: endif

```

```

109: gcdm      set      gcdn
110: gcdn      set      gcdr
111:           endm
112:           endm
113: ;
114: diskdef macro  dn,fsc,lsc,skf,bls,dks,dir,cks,ofs,kl6
115: ;;          generate the set statements for later tables
116:           if      nul lsc
117: ;;          current disk dn same as previous fsc
118: dpb&dn     equ      dpb&fsc ;equivalent parameters
119: als&dn     equ      als&fsc ;same allocation vector size
120: css&dn     equ      css&fsc ;same checksum vector size
121: xlt&dn     equ      xlt&fsc ;same translate table
122:           else
123: secmax     set      lsc-(fsc)      ;;sectors 0...secmax
124: sectors    set      secmax+1;;number of sectors
125: als&dn     set      (dks)/8      ;;size of allocation vector
126:           if      ((dks) mod 8) ne 0
127: als&dn     set      als&dn+1
128:           endif
129: css&dn     set      (cks)/4      ;;number of checksum elements
130: ;;          generate the block shift value
131: blkval     set      bls/128      ;;number of sectors/block
132: blkshf     set      0            ;;counts right 0's in blkval
133: blkmsk     set      0            ;;fills with 1's from right
134:           rept    16            ;;once for each bit position
135:           if      blkval=1
136:           exitm
137:           endif
138: ;;          otherwise, high order 1 not found yet
139: blkshf     set      blkshf+1
140: blkmsk     set      (blkmsk shl 1) or 1
141: blkval     set      blkval/2
142:           endm
143: ;;          generate the extent mask byte
144: blkval     set      bls/1024      ;;number of kilobytes/block
145: extmsk     set      0            ;;fill from right with 1's
146:           rept    16
147:           if      blkval=1
148:           exitm
149:           endif
150: ;;          otherwise more to shift
151: extmsk     set      (extmsk shl 1) or 1
152: blkval     set      blkval/2
153:           endm
154: ;;          may be double byte allocation
155:           if      (dks) > 256
156: extmsk     set      (extmsk shr 1)
157:           endif
158: ;;          may be optional [0] in last position
159:           if      not nul kl6
160: extmsk     set      kl6
161:           endif
162: ;;          now generate directory reservation bit vector
163: dirrem     set      dir          ;;# remaining to process

```

```

164: dirbks  set      bls/32  ;;number of entries per block
165: dirblk  set      0          ;;fill with 1's on each loop
166:         rept     16
167:         if      dirrem=0
168:         exitm
169:         endif
170: ;;      not complete, iterate once again
171: ;;      shift right and add 1 high order bit
172: dirblk  set      (dirblk shr 1) or 8000h
173:         if      dirrem > dirbks
174: dirrem  set      dirrem-dirbks
175:         else
176: dirrem  set      0
177:         endif
178:         endm
179: dpbhdr  dn          ;;generate equ $
180: ddw     %sectors,<;sec per track>
181: ddb     %blkshf,<;block shift>
182: ddb     %blkmsk,<;block mask>
183: ddb     %extmsk,<;extnt mask>
184: ddw     %(dks)-1,<;disk size-1>
185: udw     %(dir)-1,<;directory max>
186: adb     %dirblk shr 8,<;alloc0>
187: ddb     %dirblk and 0ffh,<;alloc1>
188: ddw     %(cks)/4,<;check size>
189: ddw     %ofs,<;offset>
190: ;;      generate the translate table, if requested
191:         if      nul skf
192: xlt&dn  equ      0          ;no xlate table
193:         else
194:         if      skf = 0
195: xlt&dn  equ      0          ;no xlate table
196:         else
197: ;;      generate the translate table
198: nxtsec  set      0          ;;next sector to fill
199: nxtbas  set      0          ;;mcves by one on overflow
200:         gcd     %sectors,skf
201: ;;      gcdn = gcd(sectors,skew)
202: neltst  set      sectors/gcdn
203: ;;      neltst is number of elements to generate
204: ;;      before we overlap previous elements
205: nelts   set      neltst ;;:counter
206: xlt&dn  equ      $          ;translate table
207:         rept   sectors ;;once for each sector
208:         if    sectors < 256
209:         ddb   %nxtsec+(fsc)
210:         else
211:         ddw   %nxtsec+(fsc)
212:         endif
213: nxtsec  set      nxtsec+(skf)
214:         if    nxtsec >= sectors
215: nxtsec  set      nxtsec-sectors
216:         endif
217: nelts   set      nelts-1
218:         if    nelts = 0

```

```

219: nxtbas set      nxtbas+1
220: nxtsec set      nxtbas
221: nelts  set      neltst
222:        endif
223:        endm
224:        endif    ;;end of nul fac test
225:        endif    ;;end of nul bls test
226:        endm
227: ;
228: defds  macro    lab,space
229: lab:    ds      space
230:        endm
231: ;
232: lds    macro    lb,dn,val
233:        defds   lb&dn,%val&dn
234:        endm
235: ;
236: ender  macro
237: ;;      generate the necessary ram data areas
238: begdat equ      $
239: dirbuf: ds      128      ;directory access buffer
240: dsknxt set      0
241:        rept    ndisks  ;;once for each disk
242:        lds    alv,%dsknxt,als
243:        lds    csv,%dsknxt,csv
244: dsknxt set      dsknxt+1
245:        endm
246: enddat equ      $
247: datsiz equ      $-begdat
248: ;;      db 0 at this point forces hex record
249:        endm

```

APPENDIX G: BLOCKING AND DEBLOCKING ALGORITHMS.

```

1: ;*****
2: ;*
3: ;*      Sector Deblocking Algorithms for CP/M 2.0      *
4: ;*
5: ;*****
6: ;
7: ;      utility macro to compute sector mask
8: smask      macro      hblk
9: ;;          compute log2(hblk), return @x as result
10: ;;         (2 ** @x = hblk on return)
11: @y         set      hblk
12: @x         set      0
13: ;;         count right shifts of @y until = 1
14:           rept      8
15:           if        @y = 1
16:           exitm
17:           endif
18: ;;         @y is not 1, shift right one position
19: @y         set      @y shr 1
20: @x         set      @x + 1
21:           endm
22:           endm
23: ;
24: ;*****
25: ;*
26: ;*      CP/M to host disk constants      *
27: ;*
28: ;*****
29: blksiz     equ      2048          ;CP/M allocation size
30: hstsiz     equ      512          ;host disk sector size
31: hstspt     equ      20           ;host disk sectors/trk
32: hstblk     equ      hstsiz/128   ;CP/M sects/host buff
33: cpmspt     equ      hstblk * hstspt ;CP/M sectors/track
34: secmsk     equ      hstblk-1     ;sector mask
35:           smask     hstblk       ;compute sector mask
36: secshf     equ      @x           ;log2(hstblk)
37: ;
38: ;*****
39: ;*
40: ;*      BDOS constants on entry to write      *
41: ;*
42: ;*****
43: wrall      equ      0            ;write to allocated
44: wrdir      equ      1            ;write to directory
45: wrual      equ      2            ;write to unallocated
46: ;
47: ;*****
48: ;*
49: ;*      The BDOS entry points given below show the      *
50: ;*      code which is relevant to deblocking only.      *
51: ;*
52: ;*****
53: ;

```

```

54: ;          DISKDEF macro, or hand coded tables go here
55: dpbase   equ      $          ;disk param block base
56: ;
57: boot:
58: wboot:
59:           ;enter here on system boot to initialize
60:         xra      a          ;0 to accumulator
61:         sta      hstact     ;host buffer inactive
62:         sta      unacnt     ;clear unalloc count
63:         ret
64: ;
65: seldsk:
66:         ;select disk
67:         mov      a,c          ;selected disk number
68:         sta      sekdisk     ;seek disk number
69:         mov      l,a          ;disk number to HL
70:         mvi      h,0
71:         rept     4            ;multiply by 16
72:         dad      h
73:         endm
74:         lxi      d,dpbase     ;base of parm block
75:         dad      d            ;hl=.dpb(curdisk)
76:         ret
77: ;
78: settrk:
79:         ;set track given by registers BC
80:         mov      h,b
81:         mov      l,c
82:         shld     sektrk      ;track to seek
83:         ret
84: ;
85: setsec:
86:         ;set sector given by register c
87:         mov      a,c
88:         sta      seksec      ;sector to seek
89:         ret
90: ;
91: setdma:
92:         ;set dma address given by BC
93:         mov      h,b
94:         mov      l,c
95:         shld     dmaadr
96:         ret
97: ;
98: sectran:
99:         ;translate sector number BC
100:        mov      h,b
101:        mov      l,c
102:        ret
103: ;

```

```

104: ;*****
105: ;*
106: ;*      The READ entry point takes the place of
107: ;*      the previous BIOS definition for READ.
108: ;*
109: ;*****
110: read:
111:      ;read the selected CP/M sector
112:      mvi    a,l
113:      sta    readop      ;read operation
114:      sta    rsflag     ;must read data
115:      mvi    a,wrua1
116:      sta    wrtype     ;treat as unalloc
117:      jmp    rwoper     ;to perform the read
118: ;
119: ;*****
120: ;*
121: ;*      The WRITE entry point takes the place of
122: ;*      the previous BIOS definition for WRITE.
123: ;*
124: ;*****
125: write:
126:      ;write the selected CP/M sector
127:      xra    a          ;0 to accumulator
128:      sta    readop     ;not a read operation.
129:      mov    a,c        ;write type in c
130:      sta    wrtype
131:      cpi    wrua1     ;write unallocated?
132:      jnz    chkuna    ;check for unalloc
133: ;
134: ;      write to unallocated, set parameters
135:      mvi    a,blksiz/128 ;next unalloc recs
136:      sta    unacnt
137:      lda    sekdisk    ;disk to seek
138:      sta    unadsk    ;unadsk = sekdisk
139:      lhld  sektrk
140:      shld  unatrkr    ;unatrkr = sektrk
141:      lda    seksec
142:      sta    unasec    ;unasec = seksec
143: ;
144: chkuna:
145:      ;check for write to unallocated sector
146:      lda    unacnt    ;any unalloc remain?
147:      ora    a
148:      jz    alloc     ;skip if not
149: ;
150: ;      more unallocated records remain
151:      dcr    a          ;unacnt = unacnt-1
152:      sta    unacnt
153:      lda    sekdisk    ;same disk?
154:      lxi    h,unadsk
155:      cmp    m          ;sekdisk = unadsk?
156:      jnz    alloc     ;skip if not
157: ;
158: ;      disks are the same

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159:      lxi      h,unatrck
160:      call     sektrckmp      ;sektrck = unatrck?
161:      jnz      alloc         ;skip if not
162:      ;
163:      ;      tracks are the same
164:      lda      seksec         ;same sector?
165:      lxi      h,unasec
166:      cmp      m              ;seksec = unasec?
167:      jnz      alloc         ;skip if not
168:      ;
169:      ;      match, move to next sector for future ref
170:      inr      m              ;unasec = unasec+1
171:      mov      a,m            ;end of track?
172:      cpi      cpmspt        ;count CP/M sectors
173:      jc       noovf         ;skip if no overflow
174:      ;
175:      ;      overflow to next track
176:      mvi      m,0           ;unasec = 0
177:      lhld     unatrck
178:      inx      h
179:      shld     unatrck       ;unatrck = unatrck+1
180:      ;
181:      noovf:
182:      ;      match found, mark as unnecessary read
183:      xra      a              ;0 to accumulator
184:      sta      rsflag         ;rsflag = 0
185:      jmp      rwoper         ;to perform the write
186:      ;
187:      alloc:
188:      ;      not an unallocated record, requires pre-read
189:      xra      a              ;0 to accum
190:      sta      unacnt         ;unacnt = 0
191:      inr      a              ;1 to accum
192:      sta      rsflag         ;rsflag = 1
193:      ;
194:      ;*****
195:      ;*
196:      ;*      Common code for READ and WRITE follows      *
197:      ;*
198:      ;*****
199:      rwoper:
200:      ;      enter here to perform the read/write
201:      xra      a              ;zero to accum
202:      sta      erflag         ;no errors (yet)
203:      lda      seksec         ;compute host sector
204:      rept     secshf
205:      ora      a              ;carry = 0
206:      rar      rar            ;shift right
207:      endm
208:      sta      sekfst         ;host sector to seek
209:      ;
210:      ;      active host sector?
211:      lxi      h,hstact       ;host active flag
212:      mov      a,m
213:      mvi      m,1           ;always becomes 1

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214:      ora      a                ;was it already?
215:      jz       filhst           ;fill host if not
216: ;
217: ;      host buffer active, same as seek buffer?
218:      lda      sekdisk
219:      lxi      h,hstdsk         ;same disk?
220:      cmp      m                ;sekdisk = hstdsk?
221:      jnz      nomatch
222: ;
223: ;      same disk, same track?
224:      lxi      h,hsttrk
225:      call     sektrkcmp        ;sektrk = hsttrk?
226:      jnz      nomatch
227: ;
228: ;      same disk, same track, same buffer?
229:      lda      sekhst
230:      lxi      h,hstsec         ;sekhst = hstsec?
231:      cmp      m
232:      jz       match           ;skip if match
233: ;
234: nomatch:
235:      lda      proper disk, but not correct sector
236:      lda      hstwrtr         ;host written?
237:      ora      a
238:      cnz      writehst        ;clear host buff
239: ;
240: filhst:
241:      ;may have to fill the host buffer
242:      lda      sekdisk
243:      sta      hstdsk
244:      lhld     sektrk
245:      shld     hsttrk
246:      lda      sekhst
247:      sta      hstsec
248:      lda      rsflag          ;need to read?
249:      ora      a
250:      cnz      readhst         ;yes, if 1
251:      xra      a                ;0 to accum
252:      sta      hstwrtr         ;no pending write
253: ;
254: match:
255:      ;copy data to or from buffer
256:      lda      seksec          ;mask buffer number
257:      ani      secmsk         ;least signif bits
258:      mov      l,a            ;ready to shift
259:      mvi      h,0            ;double count
260:      rept    7                ;shift left 7
261:      dad     h
262:      endm
263: ;      hl has relative host buffer address
264:      lxi      d,hstbuf
265:      dad     d                ;hl = host address
266:      xchg
267:      lhld     dmaadr         ;get/put CP/M data
268:      mvi      c,128          ;length of move

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269:      lda      readop          ;which way?
270:      ora      a
271:      jnz      rwmove          ;skip if read
272: ;
273: ;      write operation, mark and switch direction
274:      mvi      a,1
275:      sta      hstwrnt         ;hstwrnt = 1
276:      xchg     ;source/dest swap
277: ;
278: rwmove:
279: ;C initially 128, DE is source, HL is dest
280:      ldax    d                ;source character
281:      inx     d
282:      mov     m,a              ;to dest
283:      inx     h
284:      dcr     c                ;loop 128 times
285:      jnz     rwmove
286: ;
287: ;      data has been moved to/from host buffer
288:      lda     wrtype           ;write type
289:      cpi     wrdir           ;to directory?
290:      lda     erflag          ;in case of errors
291:      rnz     ;no further processing
292: ;
293: ;      clear host buffer for directory write
294:      ora     a                ;errors?
295:      rnz     ;skip if so
296:      xra     a                ;0 to accum
297:      sta     hstwrnt         ;buffer written
298:      call    writehst
299:      lda     erflag
300:      ret
301: ;
302: ;*****
303: ;*
304: ;*      Utility subroutine for 16-bit compare      *
305: ;*
306: ;*****
307: sektrkcmp:
308: ;HL = .unatrkr or .hsttrkr, compare with sektrk
309:      xchg
310:      lxi     h,sektrk
311:      ldax   d                ;low byte compare
312:      cmp    m                ;same?
313:      rnz   ;return if not
314: ;      low bytes equal, test high 1s
315:      inx   d
316:      inx   h
317:      ldax  d
318:      cmp   m                ;sets flags
319:      ret
320: ;

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```

321: ;*****
322: ;*
323: ;*      WRITEHST performs the physical write to      *
324: ;*      the host disk, READHST reads the physical   *
325: ;*      disk.                                         *
326: ;*
327: ;*****
328: writehst:
329: ;hstdsk = host disk #, hsttrk = host track #,
330: ;hstsec = host sect #. write "hstsiz" bytes
331: ;from hstbuf and return error flag in erflag.
332: ;return erflag non-zero if error
333: ret
334: ;
335: readhst:
336: ;hstdsk = host disk #, hsttrk = host track #,
337: ;hstsec = host sect #. read "hstsiz" bytes
338: ;into hstbuf and return error flag in erflag.
339: ret
340: ;
341: ;*****
342: ;*
343: ;*      Unitialized RAM data areas                    *
344: ;*
345: ;*****
346: ;
347: sekdisk: ds      1          ;seek disk number
348: sektrk:  ds      2          ;seek track number
349: seksec:  ds      1          ;seek sector number
350: ;
351: hstdsk:  ds      1          ;host disk number
352: hsttrk:  ds      2          ;host track number
353: hstsec:  ds      1          ;host sector number
354: ;
355: sekhst:  ds      1          ;seek shr secshf
356: hstact:  ds      1          ;host active flag
357: hstwrt:  ds      1          ;host written flag
358: ;
359: unacnt:  ds      1          ;unalloc rec cnt
360: unadsk:  ds      1          ;last unalloc disk
361: unatrck: ds      2          ;last unalloc track
362: unasec:  ds      1          ;last unalloc sector
363: ;
364: erflag:  ds      1          ;error reporting
365: rsflag:  ds      1          ;read sector flag
366: readop:  ds      1          ;1 if read operation
367: wrtype:  ds      1          ;write operation type
368: dmaadr:  ds      2          ;last dma address
369: hstbuf:  ds      hstsiz    ;host buffer
370: ;

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```
371: ;*****
372: ;*
373: ;*      The ENDEF macro invocation goes here      *
374: ;*
375: ;*****
376:      end
```