

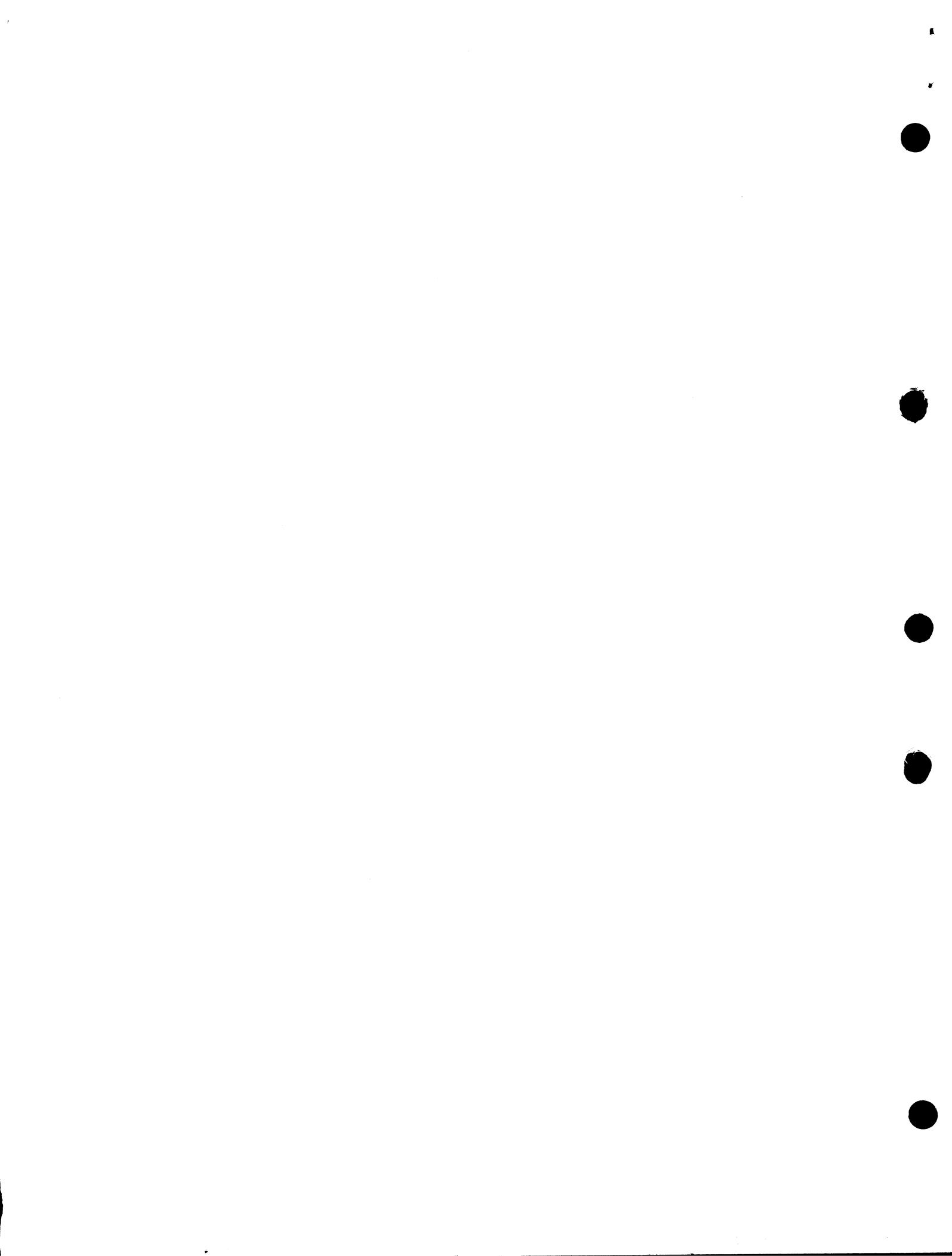
TITLE: Statistical Subroutines
Fixed Point Input

AUTHOR: William F. Burggrabe, Jr.
Compumatrix, Incorporated
Clayton 5, Missouri

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Computatix Statistical Subroutines

Fixed Point Input

I. Storage Allocation

A) Standard Subroutines

<u>Program#</u>	<u>Location</u>	<u>Description</u>
10.4	0000-0263	Program Input
11.2	0300-0563	Data Input (Fixed)
12.1a	0600-0850	Data Output (Fixed)
25.0R	0900-1163	Float - Unfloat
24.0	1200-2163	Floating Point Interpretive
11.6-12.6	2200-2763	Floating Point Input-Output
29.0	2800-2963	Matrix Inversion

B) Statistical Subroutines:

<u>Sample Problem</u>	<u>Location</u>	<u>Description</u>
1	3000-3218	Fixed Point Δ Matrix Prep, Print, Float
2	3219-3263*	Δ Matrix Scale
3	3300-3515	Calculate Means, Standard Deviations and Correlation Coefficient Δ Matrix (Print)
4a	3516-3606	Convert Δ Rij Matrix to \square Rij Matrix (Modified)

(Statistical subroutine - cont'd)

<u>Sample Problem</u>	<u>Location</u>	<u>Description</u>
5	3607-3660	Invert <input type="checkbox"/> Rij matrix and print
	3661	XPI600
6a	3662-4005	Compute and print: Beta Weights, Regression Coefficients; Partial Correlation Coefficient and Standard Error of the Independent Variables; the Constant Term (b_0) and its' standard error; the Sample Multiple Correlation Coefficient and Standard Error of Estimate; the Universe Multiple Correlation Coefficients and Standard Error of Estimate.
	4006	XZ0000 stop
7	4007-4060	Compute Y, \bar{Y}_{cal} ($\bar{Y}-\bar{Y}_{cal}$) and print (Fixed Point)
C)	<u>Data and Computational Storage</u>	
<u>Area</u>	<u>For</u>	<u>Required</u>
4100-4131	Standard Deviations	n
4132-4163	Coefficient of Equation	n
4200-6131	Δ Data matrix and correlation Coefficient Matrix <input type="checkbox"/> Rij matrix and inverse	$n^2 + 2n + 1$
4201-4201+n	Means	n
6132-6163	Scale Factors	(n+1)
6200-6231	Record	(n+1)
6232-6263	Temp. and Line Set	-----

(Data and Computational Storage - Con'd)

<u>Area</u>	<u>For</u>	<u>Required</u>
6300-6363	Temp. for Floating Point, etc.	-----
* Note:		
3219	XU3300 (To skip scaling)	
3219	XU3220 (To do scaling)	

3220	XR1200)	Enter Floating Point
3221	XU1200)	
3222	XI0000	Read Scale Factors
3223	XE0000	Exit F.P.
3224	Lo Matrix scaling sub.	

II. Operation:

- A) Load hex tapes A and B (See storage allocation A and B for tape contents). Note exception: 10.4 is not on tape A or B.
- B) Insert sample problem data tape in the typewriter and depress break points 4 and 8. Start the tape reading via a program input routine (10.0, 10.3 or 10.4). All start fill and transfers are on the tape.
- C) The computer will halt on the stop and transfer instruction (.0003000'). A start compute signal will initiate the computation (or B.P. 32 could have been depressed).
- D) The program will proceed to the completion of the regression analysis and then stop in location 4006 (XZ0000).
- E) A start compute signal will cause an entry into the subroutine to compute the residuals, ($Y - Y_{cal}$). Although the regression equation coefficients are stored correctly by the subroutine that computes them, they are in floating point and must be entered in the correct order in fixed point before the first record of the original data is read. This information is on the sample problem data tape.

III. Format:

- A) Set carriage return stop at 4.
- B) Set tabs at 12, 20, 28, 36, 44, etc. n+1 tabs. (8 numbers apart).
- C) For very large problems the automatic C.R. must be used or all spacing tabs in program 1 and 3 removed (see write ups) and a column type printout used.
- D) Since break points separate every major phase of this group of subroutines, these spaces may be used for exits to heading printing operations or other calculations, without disrupting actual program steps.

IV. General:

- A) The subroutine designated as "No. 2" (scaling) has not been used in this sample problem since then, in general, special handling would be required in the residual computation.
- B) The subroutines were assembled except for locations 3219-3223 and 4006 by filling the following subroutine Lo on top of the previous subroutine L_f.

FIXED POINT DATA

COMPUMATIX, INC.

SAMPLE PROBLEM STATISTICS SUBROUTINES

;0006232'

xz0010'	q of printout
xz0003'	no. of variables
xz0005'	no. of records
xz6200'	Lo. of record
xz4200'	Lo. of Δ data matrix
xz1200'	Lo. of floating point
xz4201'	Lo. of means
xz4100'	Lo. of standard deviations
xz0000'	Lo. of sq. Rij matrix
xz6132'	Lo. of scale factors
xz2800'	Lo. of matrix inversion (29.0)
xz4132'	Lo. of coefficients of regression equation

depress break points 4 and 8 for straight thru operation
 to the residual computation

.0003000'

data

```

0+056200'1'4'1'-0000000'
0+056200'1'1'4'3'-0000000'
0+056200'1'3'3'2'-0000000'
0+056200'1'6'2'5'-0000000'
0+056200'1'8'4'-0000000'

```

N	ΣX_1	ΣX_2	ΣY		
5.00000	18.00000	13.00000	15.00000		
	ΣX_1^2	$\Sigma X_1 X_2$	$\Sigma X_1 Y$		
	110.00000	25.00000	71.00000		
	ΣX_2^2	$\Sigma X_2 Y$			
	45.00000	32.00000			
		ΣY^2			
			55.00000		
\bar{X}_1	\bar{X}_2	\bar{Y}			
.3600000	01	.2600000	01	.3000000	01
σ_{x_1}		σ_{x_2}		σ_y	
.3006659	01	.1496663	01	.1414213	01
r ₁₁		r ₁₂		r _{1y}	
.1000000	01	.9688981-	00	.7996129	00
		r ₂₂		r _{2y}	
		.1000000	01	.6614376-	00
				r _{yy}	
				.1000000	01

Inverse of r_{ij} matrix

.6084443	02	.4759427	02	.1717134-	02		
.4759427	02	.3900739	02	.1225603-	02		
.1717134-	02	.1225603-	02	.6623824	01		
β_{x1}		b _{x1}		r _{1y,2}			
.2592361	01	.1219344	01	.8553412	00	σ_{bx1}	
β_{x2}		b _{x2}		r _{2y,2}			
.1850295	01	.1748364	01	.7624686	00	σ_{bx2}	
		b ₀				σ_{b0}	
		.5935385-	01			.3885488	00
R		σ_{EST}		\hat{R}		$\hat{\sigma}_{EST}$	
.9214280	00	.5494909	00	.8354996	00	.8688215	00

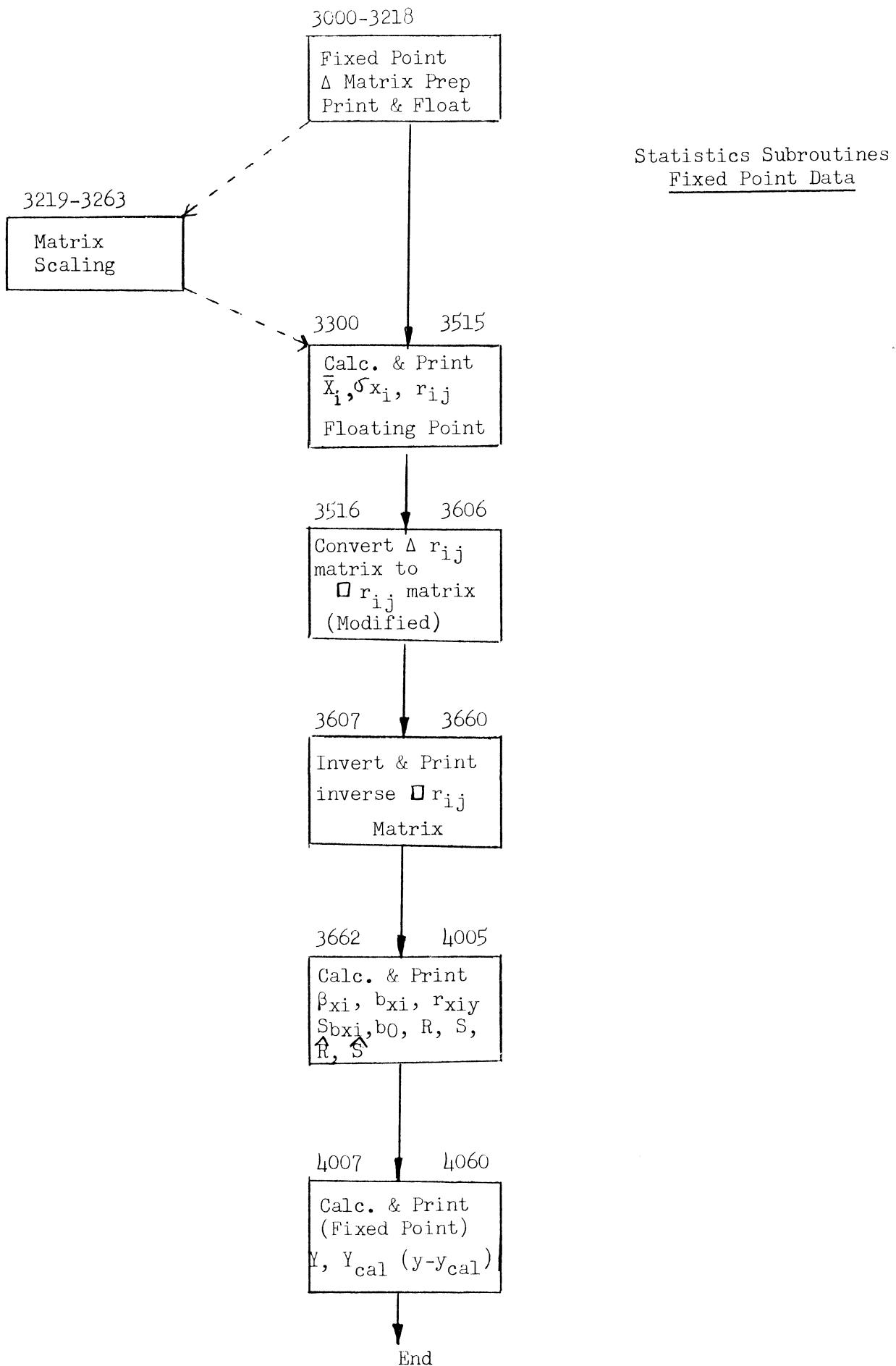
regression coefficients

6+054132' -5935385' 1219344' 1748365' -0000000'

data repeated to compute residuals

printout order Y, \bar{Y}_{cal} , ($Y - \bar{Y}_{cal}$)

	Y	\bar{Y}_{cal}	$(Y - \bar{Y}_{cal})$
0+056200' 1' 1' 4' 1' -0000000'	1.00000	1.05808	- .05808
0+056200' 1' 1' 4' 3' -0000000'	3.00000	2.27742	.72258
0+056200' 1' 3' 3' 2' -0000000'	2.00000	2.96774	- .96774
0+056200' 1' 6' 2' 5' -0000000'	5.00000	4.87741	.12259
0+056200' 1' 8' 1' 4' -0000000'	4.00000	3.81937	.18064



TITLE: Least Squares Fixed Point Triangular Matrix Preparation

AUTHOR: William F. Burggrabe
Compumatrix, Incorporated

DATE: August 31, 1961

PURPOSE: Given N records of n variables of the form 1, X_1 , X_2 , ... X_n , this subroutine will prepare a fixed point triangular matrix. The matrix rows are stored sequentially in the following format:

N	ΣX_1	ΣX_2	...	ΣX_n
	ΣX_1^2	$\Sigma X_1 X_2$...	$\Sigma X_1 X_n$
	ΣX_2^2
		.	.	.
			ΣX_n^2	

The matrix is then put into floating point form by sub 25.OR following an optional (T.C. down - no print out) fixed point matrix print out.

RESTRICTIONS:

- 1) All data are assumed to be at the same q, summations are computed at twice the data q.
- 2) The following subroutines are required:

<u>Linkage Location</u>	<u>Subroutine</u>	<u>Fixed Storage Location</u>
Lo + 155 and 156	11.2	0300-0563
Lo + 56 and 57	12.1 (a)	0600-0832 (0850)
Lo + 207 and 208	25.OR	0900-1163

- 3) The following information must be supplied:

Location:

6232 2 x q of data
6233 number of variables
6234 number of records
6235 Lo record
6236 Lo Δ matrix

- 4) If any summation exceeds the maximum possible number size for 2.q, an overflow stop will occur in Lo + 105, (in general the sum of squares terms will create the most difficulty) and the problem then must be rerun with a greater data q.
- 5) No limit to the number of records provided no overflow is encountered; the number of variables is limited only by available machine storage.

Required storage: Data Lo to Lo + n + 1

$$\text{Matrix Lo to Lo} + \frac{(n+1)(n+2)}{2}$$

- 6) Data Format:

Initial record.

P + qqRRRR ' 1 ' X₁ ' X₂ ' ... X_n ' -0000000 ''

Following records:

P + qq RRRR+l ' X₁ ' X₂ ' ... X_n ' -0000000 ''

where RRRR = Lo record as stored in (6235)

qq + Half of 2q as stored in (6232)

- 7) Only the record being processed is stored.

GENERAL INFORMATION ON METHOD:

Since little mathematical description need be given, a description of the program sequence will be outlined here:

- 1) Initialization

Clear the matrix storage area to zero

- 2) Semi-optimum matrix preparation.

N-records, n variables

- 3) Optional print out of fixed point matrix

(Transfer control up)

- 4) Conversion of fixed point matrix to floating point.

A break point stop separates each phase of the operation, as well as the processing of each record.

CODING INFORMATION:

- A) Storage: Subroutine 2 tracks 20 sectors

External storage 6232 thru 6236 as under restriction 3 and the following ...

6260 ctr
6261 n + 1 @ 29
6262 n + 2 @ 29
6263 (n+1) (n+2) @29
 2

Data Lo to Lo + n + 1
Matrix Lo to Lo + (n+1) (n+2)
 2

- B) Linkage and calling sequence: Since this is one of a group of statistical subroutines, location 6232 through 6263 have been reserved for initialization information and no calling sequence is required.

Linkage R Lo + 219

U Lo

- C) Input: As described under restriction 3 and 6

- D) Output: The computed matrix is stored sequentially beginning in the specified location. It may be printed out in fixed point in the following format:

as per 12.1a

N ΣX_1 ΣX_2 ... ΣX_n

as per 12.1a

Tab ΣX_1^2 $\Sigma X_1 X_2$... $\Sigma X_1 X_n$

Tab Tab ΣX_2^2 ... $\Sigma X_2 X_n$ etc.

(See sample problem)

The tabs may be suppressed by changing Lo + 0049 to U (Lo + 55).

E) Location of constants:

Lo + 110	l @ 3
Lo + 114	l @ 29
Lo + 115	l @ 29
Lo + 116	3wwj
Lo + 117	3wwj
Lo + 123	l @ 29

F) The actual matrix preparation time is approximately:

$$\frac{[(n+1)^2]}{12} \quad N \text{ sec: compute time, } + \frac{(n)}{3} \quad N \text{ sec.}$$

Data read time (Photo reader).

G) Program Stops:

Lo + 34 (Break Point 4)	after initialization
Lo + 37 (Break Point 8)	after completion of matrix prep.
Lo + 154 (Break Point 4)	after each record is processed.
Lo + 200 (Break Point 4)	after print out of matrix
Lo + 218 (Break Point 8)	after floating matrix.

FIXED POINT MATRIX PREPARATIONOperating Procedure:

Prepare data tape as per instructions under input and fill the required storage locations in 6232-6236 as under restriction 3. Insert data tape in reader and transfer to routine Lo or use a main program with the required linkage.

After initialization a stop (BP 4) in Lo + 34 will occur. Depression of start compute will cause the reading of the first record, the necessary computations for that record and an exit to (BP 4) in Lo + 154 prior to reading the next record. (This feature allows for machine stoppage on very large problems).

After all records have been processed, the program will halt on BP 8 in Lo + 37. If it is desired to eliminate the fixed point matrix print out, depress transfer control before continuing the program. This causes a transfer to Lo + 200 (BP 4) the end of the print sequence.
(NOTE: Depression of the transfer control switch during the printing operation will cause an exit from the print routine at the end of the particular line being printed).

A start compute signal will then cause the fixed point numbers to be floated. On completion of the float sequence, a terminal stop on BP 8 in Lo + 218 is executed, and a start compute signal will transfer control back to the main program.

SAMPLE PROBLEM FIXED POINT Δ MATRIX PREP.

;0006232'xz0010'	print q	}	External Storage
;0006233'xz0003'	no. variables		
;0006234'xz0005'	no. records		
;0006235'xz6200'	Lo record		
;0006236'xz5000'	Lo Δ matrix		

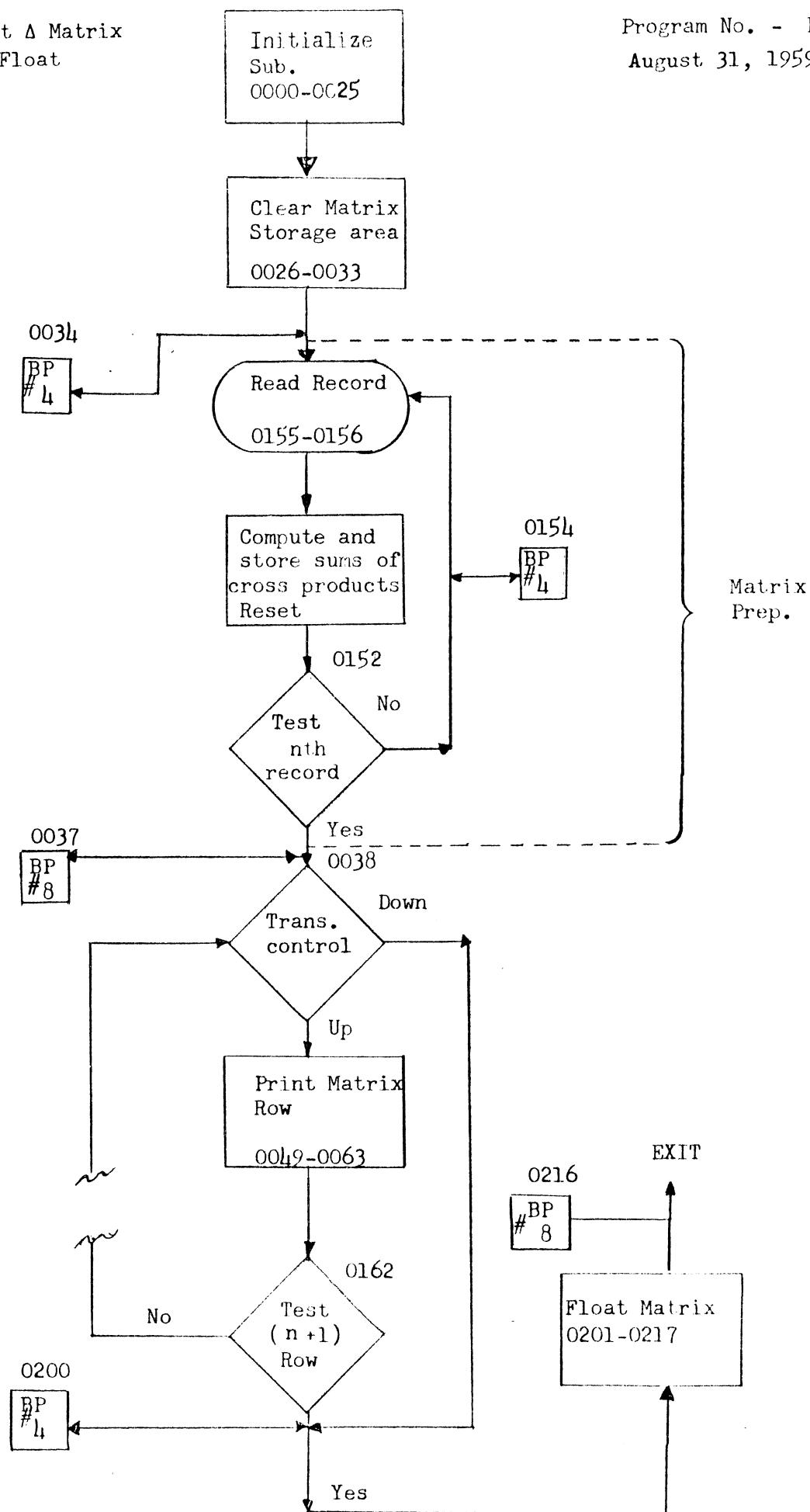
.0003000' transfer to matrix prep. data follows

0+056200'1'1'4'1'-0000000'	}	Data
0+056200'1'1'4'3'-0000000'		
0+056200'1'3'3'2'-0000000'		
0+056200'1'6'2'5'-0000000'		
0+056200'1'8'1'4'-0000000'		

5.00000	18.00000	13.00000	15.00000
110.00000	25.00000	71.00000	32.00000
	45.00000		55.00000

TITLE: Fixed Point Δ Matrix
Prep. and Float

Program No. - F2-129 -1
August 31, 1959



LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL						PAGE 1 / 5
JOB NO.	PROGRAM NO. F2-129	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review		DATE 4-18-59	
PROBLEM: Given: N records of n variables; prepare Δ Fixed point matrix & Float.						TRACK 00
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION		CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS		
	/					
	/	0 0 0 0	X, B 6 2 3 3	'	n @ 29	$n =$ (No. of variables)
		0 1	A 0 1 1 4	'	1 @ 29	
		0 2	X, H 6 2 6 1	'	(n+1) @ 29	
		0 3	A 0 1 1 4	'	$\frac{1}{\square} 1 @ 29$	
		0 4	X, H 6 2 6 2	'	(n+2) @ 29	gives
		0 5	X, N 6 2 6 1	'	(n+1) @ 29	$\frac{(n+1)(n+2)}{2} @ 27$
		0 6	M 0 1 1 0	'	1 @ 3	give $\frac{(n+1)(n+2)}{2} @ 29$
		0 7	X, C 6 2 6 3	'	$\frac{1}{\square} \frac{(n+1)(n+2)}{2} @ 29$	
		0 8	X, B 6 2 3 5	'	Lo Record	
		0 9	Y 0 1 0 0	'		
		1 0	Y 0 1 0 1	'		(Init. Matrix Prep.)
		1 1	Y 0 1 1 3	'	$\frac{1}{\square}$	
		1 2	X, A 6 2 6 1	'	(n+1) @ 29	→ Record $L_f + 1$
		1 3	Y 0 1 1 1	'		
		1 4	X, B 6 2 3 6	'	Lo Δ Matrix	
		1 5	Y 0 1 0 5	'	$\frac{1}{\square}$	
		1 6	Y 0 1 0 6	'		(Init. Matrix Prep.)
		1 7	Y 0 1 1 8	'		
		1 8	Y 0 0 2 7	'		(Init. Clear Drum)
		1 9	Y 0 0 5 5	'	$\frac{1}{\square}$	(Init. Print)
		2 0	Y 0 2 0 6	'		{ Init. Float
		2 1	Y 0 2 1 0	'		
		2 2	X, A 6 2 6 3	'	$\frac{(n+1)(n+2)}{2} @ 29$	
		2 3	X, C 6 2 6 0	'	$\frac{1}{\square} \text{Temp (Matrix } L_f + 1) @ 29$	
		2 4	X, S 6 2 3 4	'	No records @ 29	} Init. Matrix
		2 5	C 0 1 2 1	'	Matrix Prep ctr.	} Prep. counter
		2 6	B 0 0 4 6	'	0	
		2 7	C []	'	$\frac{1}{\square}$ Matrix area	} Clear storage area
		2 8	B 0 0 2 7	'	Add in matrix	
		2 9	A 0 1 1 4	'	1 @ 29	
		3 0	Y 0 0 2 7	'		
		3 1	E 0 1 1 7	'	$\frac{1}{\square} XZ 6363$	Mask

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 2 /5		
JOB NO.	PROGRAM NO. F2-129	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 4-18-59			
PROBLEM: Δ Fixed point Matrix and Float					TRACK 00		
PROGRAM INPUT CODES	S T O R E	LOCATION	INSTRUCTION		S T O R E	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
	/						
	/	<input checked="" type="checkbox"/>					
		0 0 3 2	X S 6 2 6 0	/	Matrix Lf +1		
		3 3	T 0 0 2 6	/			
		3 4	X Z 0 4 0 0	/	BP 4 - stop after initialization		
		3 5	R 0 1 2 4	/	<input checked="" type="checkbox"/> Δ Matrix Prep.		
		3 6	U 0 1 5 5	/	<input checked="" type="checkbox"/> Linkage		
		3 7	X Z 0 8 0 0	/	BP 8 - stop after matrix prep.		
		3 8	8 9 0 T 0 2 0 0	/	→ skip matrix print out		
		3 9	X B 6 2 6 1	/	<input checked="" type="checkbox"/> (n+1) @ 29		
		4 0	X C 6 2 6 0	/	temp 1 - no. of numbers to print	" " " "	
		4 1	X B 6 2 6 0	/	" " " "	" "	
		4 2	N 0 0 5 2	/	1@ 25		
		4 3	X A 6 2 3 2	/	<input checked="" type="checkbox"/> print q gives XZ[NNqq]		
		4 4	Y 0 0 5 8	/		set up Z inst.	
		4 5	X P 1 6 0 0	/	cr.		
		4 6	X Z 0 0 0 0	/	delay & zero (0026)		
		4 7	X B 6 2 6 0	/	<input checked="" type="checkbox"/> temp 1 no. of no.s to print		
		4 8	X S 6 2 6 1	/	(n+1) @ 29		
		4 9	T 0 0 5 1	/	→ print tab		
		5 0	U 0 0 5 5	/	exit tab loop		
		5 1	X P 2 4 0 0	/	<input checked="" type="checkbox"/> tab		
		5 2	X Z 0 0 1 6	/	delay & 1 @ 25 (0042)		
		5 3	A 0 1 1 4	/	1 @ 29		
		5 4	U 0 0 1 9	/	loop		
		5 5	B []	/	<input checked="" type="checkbox"/> Lo first no. in row		
		5 6	X R 0 6 0 5	/			
		5 7	X U 0 6 0 0	/			
		5 8	X Z []	/	no & q		
		5 9	X B 6 2 6 0	/	<input checked="" type="checkbox"/> temp 1	no. of no.s printed	
		6 0	A 0 0 5 5	/			
		6 1	Y 0 0 5 5	/			
		6 2	X B 6 2 6 0	/	temp 1	no. of no.s printed	
		6 3	U 0 1 5 9	/	<input checked="" type="checkbox"/> over matrix prep.		

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 3 / 5	
JOB NO.	PROGRAM NO. F2-129	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 4-18-59		
PROBLEM: Given: N records of n variables: prepare Δ Fixed point matrix & float.					TRACK 01	
PROGRAM INPUT CODES	PO STS	LOCATION	INSTRUCTION	PO STS	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/	X _j (k+1) @ q				
	0 1 0 0	B [] [] []	/		0 ≤ k ≤ n-1	
	0 1	M [] [] []	/		X _j (k+1) @ q	0 ≤ k ≤ n-1
	0 2	U 0 1 0 5	/			
	0 3		/	X _i @ q		
	0 4		/			
	0 5	A [] [] []	/	$\sum_{k=1}^K X_i X_j @ 2q$		
	0 6	C [] [] []	/	$\sum_{i=1}^n X_i X_j @ 2q$		
	0 7	B Q 1 0 6	/	X _i @ q		
	0 8	A Q 1 2 3	/	1 @ 29		
	0 9	U Q 1 2 6	/			
, 0 0 0	0 0 1 6	' 1 0 1 0 0 0 0 0 0 0	/	1 @ 3		
	1 1		/	Data Lo + n + 1 * Data L _f + 1		
	1 2		/			
	1 3		/	Data Lo		
	1 4		/	1 @ 29		
	1 5		/	1 @ 29		
	1 6	3 w _i w _j	/	XZ 6363 Mask		
	1 7	3 w _i w _j	/	" "		
	1 8		/	Δ Matrix Lo		
	1 9		/	X _i @ q		
	2 0		/			
	2 1		/	-n (Records @ 29)		
	2 2	P 1 0 0 0	/	c.r. (Hex)		
	2 3		/	1 @ 29 & delay		
	2 4	U Q 0 0 0 0	/	Exit matrix prep ← R here		
	2 5		/			
	2 6	Y Q 1 0 5	/			
	2 7	Y Q 1 0 6	/	X _i @ q		
	2 8	B Q 1 0 0	/			
	2 9	A Q 1 1 5	/	1 @ 29		
	3 0	E Q 1 1 6	/	3wwj		
	3 1	Y Q 1 0 0	/	X _i @ q		

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 4 /5		
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 4-18-59			
PROBLEM: Δ Fixed point matrix and float					TRACK 01		
PROGRAM INPUT CODES	PO STO	LOCATION	INSTRUCTION		PO STO	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
	/						
	/	<input checked="" type="checkbox"/>					
		0 1 3 2	S 0 1 1 1	/		data L _f +1	
		3 3	T 0 1 0 0	/		(Back to complete row)	
		3 4	B 0 1 0 1	/	<input checked="" type="checkbox"/>	1 @ 29	
		3 5	A 0 1 1 4	/	<input checked="" type="checkbox"/>		
		3 6	Y 0 1 0 1	/			
		3 7	Y 0 1 0 0	/			
		3 8	E 0 1 1 7	/	<input checked="" type="checkbox"/>	3wwj	
		3 9	S 0 1 1 1	/	<input checked="" type="checkbox"/>	Data L _f +1	
		4 0	T 0 1 0 0	/		(Begin new row)	
		4 1	B 0 1 1 3	/	<input checked="" type="checkbox"/>	Data Lo	
		4 2	Y 0 1 0 0	/	<input checked="" type="checkbox"/>		
		4 3	Y 0 1 0 1	/	<input checked="" type="checkbox"/>		
		4 4	U 0 1 4 6	/			
		4 5					
		4 6	B [0118]	/	<input checked="" type="checkbox"/>	Δ Matrix Lo	
		4 7	Y 0 1 0 5	/	<input checked="" type="checkbox"/>		
		4 8	Y 0 1 0 6	/			
		4 9	B 0 1 2 1	/		-n @ 29	
		5 0	A 0 1 1 5	/		1 @ 29	
		5 1	H 0 1 2 1	/	<input checked="" type="checkbox"/>		
		5 2	T 0 1 5 4	/			
		5 3	U 0 1 2 2	/		matrix prep exit →	
		5 4	X Z 0 4 0 0	/		BP 4 stop after each record	
		5 5	X R 0 3 0 8	/	<input checked="" type="checkbox"/>		← U here
		5 6	X U 0 3 0 0	/			
		5 7	U 0 1 0 0	/			
		5 8					
		5 9	S 0 1 1 4	/	<input checked="" type="checkbox"/>	1 @ 29	
		6 0	X H 6 2 6 0	/		temp no. of nos to print	
		6 1	S 0 1 1 4	/		1 @ 29	
		6 2	8 0 0 T 0 2 0 0	/		exit print out of matrix	
		6 3	U 0 0 4 1	/	<input checked="" type="checkbox"/>	back to print new line	

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 5 / 5	
JOB NO.	PROGRAM NO. F2-129	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 4-18-59		
PROBLEM: Δ Fixed Point Matrix and Float					TRACK 02	
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/	X Z 0 4 0 0	/	BP 4 stop		
	0 2 0 0	X B 6 2 3 2	/	2q @ 29		
	0 1	Y 0 2 1 0 9	/			
	0 2	X B 6 2 3 6	/	Δ Matrix Io $(n+1)(n+2)$ @ 2		
	0 3	X A 6 2 6 3	/			
	0 4	X C 6 2 6 0	/	ctr		
	0 5	B []	/	$\sum X_i X_j @ 2q$		
	0 6	X R 0 9 2 5	/			
	0 7	X U 0 9 0 0	/			
	0 8	Z []	/	q of no. to float.		
	0 9	C []	/	floated no. store		
	1 0	B 0 2 0 6	/			
	1 1	A 0 1 1 4	/	1 @ 29		
	1 2	Y 0 2 0 6	/			
	1 3	Y 0 2 1 0	/			
	1 4	E 0 1 1 7	/	3wwj Mask		
	1 5	X S 6 2 6 0	/	Matrix L _f + 1		
	1 6	T 0 2 0 6	/			
	1 7	X Z 0 8 0 0	/	BP 8 stop after float.		
	1 8	U []	/	Exit sub.		
	1 9		/	open		
	2 0		/			
	2 1		/			
	2 2		/			
	2 3		/			
	2 4		/			
	2 5		/			
	2 6		/			
	2 7		/			
	2 8		/			
	2 9		/			
	3 0		/			
	3 1		/			

TITLE: Triangular Matrix Scaling

AUTHOR: William F. Burggrabe
Compumatrix, Incorporated

DATE: September 4, 1959

PURPOSE: Given a matrix in floating point of the form ...

$$\begin{array}{cccccc} N & \Sigma \frac{x_1}{c_1} & \Sigma \frac{x_2}{c_2} & \dots & \Sigma \frac{x_n}{c_n} \\ & \Sigma \left(\frac{x_1}{c_1} \right)^2 & \Sigma \frac{x_1}{c_1} & \times & \frac{x_2}{c_2} & \dots \Sigma \frac{x_1}{c_1} \times \frac{x_n}{c_n} \\ & & & & & \cdot \\ & & & & & \cdot \\ & & & & & \cdot \\ & & & & & \Sigma \left(\frac{x_n}{c_n} \right)^2 \end{array}$$

and scale factors l , c_1 , $c_2 \dots c_n$ compute the matrix.

$$\begin{array}{cccccc} N & \Sigma x_1 & \Sigma x_2 & \Sigma x_3 & \dots & \Sigma x_n \\ & \Sigma x_1^2 & \Sigma x_1 x_2 & & \dots & \Sigma x_1 x_n \\ & & & & & \cdot \\ & & & & & \cdot \\ & & & & & \cdot \\ & & & & & \Sigma x_n^2 \end{array}$$

RESTRICTIONS:

- 1) The following locations must contain:

6236 Lo matrix

6237 Lo floating point 24.0

6241 Lo scale factors

6261 (n+1) @ 29 - matrix order

- 2) The scale factors in floating point must be stored in the same order as the matrix components.
- 3) Normal limitations of 24.0, 11.6-12.6.
- 4) All scale factors must be stored, (i.e.) where a scale factor is unity it must be stored

$$(1 \times 1 \times N = N, 1 \times C_1 \times \frac{x_1}{C_1} = x_1, \text{ etc.})$$

CODING INFORMATION:

- A) Subroutine storage - 41 sectors

External Storage	6236	Lo Δ matrix
	6237	Lo floating point
	6241	Lo scale factors
	6260	Temp storage
	6261	(n+1) @ 29*

- B) Linkage

R Lo + 40

U Lo

- C) Input - the following must be stored in memory

- 1) Δ matrix in floating point
- 2) Scale factors in floating point

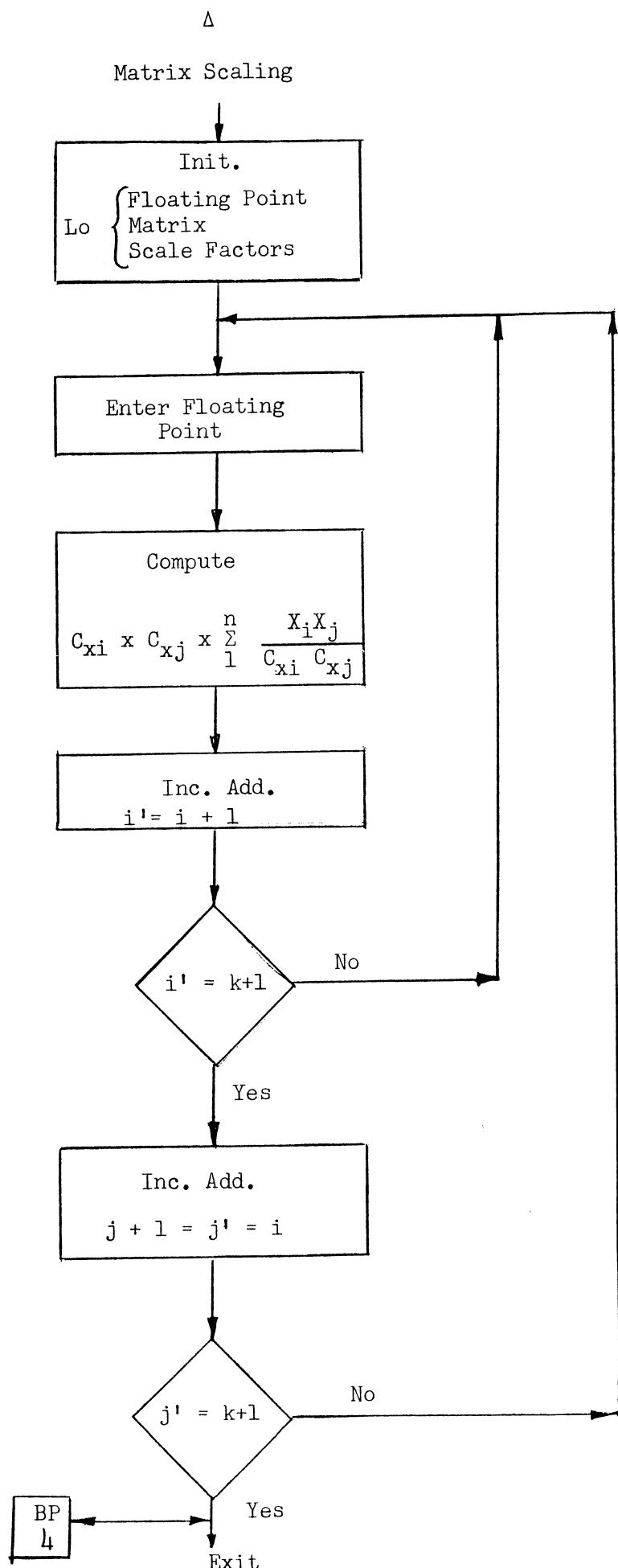
- D) Output scaled Δ matrix. Stored in the same location as unscaled matrix.

- E) Constants

Lo + 30	XZ6363 mask
Lo + 31	1 @ 29

- F) Timing (n+1)(n+2) x .65 sec.

* From CI Δ matrix prep. routines



LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL				PAGE OF 1 / 2
JOB NO.	PROGRAM NO. F2-129	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 10-4-59
PROBLEM: Matrix Scale				TRACK 00

PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION		STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
	/						
	/						
			X B	6 2 3 7	/	Lo F. P.	
			Y	0 0 1 1	/		
			Y	0 0 1 2	/		
			X B	6 2 3 6	/	Lo Matrix	
			Y	0 0 1 3	/		
			Y	0 0 1 7	/		
			X B	6 2 4 1	/	Lo Scale Factors	
			Y	0 0 1 4	/		
			Y	0 0 1 6	/		
			X A	6 2 6 1	/	(n+1)@ 29 → L _f +1 (Scale Factors)	
			X Y	6 2 6 0	/		
			R []		/	✓ F.P. Linkage	
			U []		/		
			P []		/	$\sum X_i X_j$	
			M []		/	C _{x_i}	
			X U	0 0 0 0	/	✓ Acc → Mult	
			M []		/	C _{x_j}	
			H []		/	C _{x_i} C _{x_j} $\sum X_i X_j$	
			X E	0 0 0 0	/	Exit F.P.	
			B	0 0 1 3	/	✓ Add of $\sum X_i X_j$	
			A	0 0 3 1	/	1 @ 29	
			Y	0 0 1 3	/		
			Y	0 0 1 7	/		
			B	0 0 1 4	/	✓ Add. of C _{x_i}	
			A	0 0 3 1	/	1 @ 29	
			Y	0 0 1 4	/		
			E	0 0 3 0	/	mask	
			X S	6 2 6 0	/	✓ L _f +1 of C _x 's	
			T	0 0 1 1	/	loop	
			U	0 0 3 2	/		
			X Z	6 3 6 3	/	mask	
			X Z	0 0 0 1	/	✓ 1 @ 29	

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL				PAGE OF 2 / 2
JOB NO. F2-129	PROGRAM NO. F2-129	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 10-4-59
PROBLEM: Matrix Scale				TRACK 00

PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION		STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
	1						
	1	X					
		0 0 3 2	B	0 0 1 6	'		
		3 3	A	0 0 3 1	'	1 @ 29	
		3 4	Y	0 0 1 4	'		
		3 5	Y	0 0 1 6	'	X	
		3 6	E	0 0 3 0	'		
		3 7	X S	6 2 6 0	'		
		3 8	T	0 0 1 1	'	loop	
		3 9	X Z	0 4 0 0	'	X BP 4 stop after scaling	
		4 0	U	[]	'		
		4 1			'		
		4 2			'		
		4 3			'	X	
		4 4			'		
		4 5			'		
		4 6			'		
		4 7			'	X	
		4 8			'		
		4 9			'		
		5 0			'		
		5 1			'	X	
		5 2			'		
		5 3			'		
		5 4			'		
		5 5			'	X	
		5 6			'		
		5 7			'		
		5 8			'		
		5 9			'	X	
		6 0			'		
		6 1			'		
		6 2			'		
		6 3			'	X	

Royal McBee Corporation
DATA PROCESSING DIV.
PORT CHESTER, NEW YORK



TITLE: Calculation of Means, Standard Deviations and Correlation Coefficient Triangular Matrix

AUTHOR: William F. Burggrabe, Jr.
Compumatrix, Incorporated

DATE: September 23, 1959

PURPOSE: Given a floating point Δ matrix as prepared by either the fixed or floating point Δ matrix preparation subroutine, compute the means, standard deviation and the all simple correlation coefficients.

n = Number variables

N = Number records

The Rij matrix replaces all cross product terms in the original matrix. The means and standard deviations (n values each) will be stored in the correct order starting in the Lo specified. Each value is printed out in normal floating point form as computed. (See sample problem)

RESTRICTIONS:

- 1) Normal restrictions of 24.0, 11.6-12.6
- 2) Required computational storage

mean Lo thru Lo + (n-1)

σ_x Lo thru Lo + (n-1)

Δ Data matrix Lo thru Lo + $\frac{(n+1)(n+2)}{2}$ -1

Δ Rij matrix replaces all but first row of Δ data matrix

- 3) The following information must be supplied:

Location 6233 n @ 29
 6236 Lo Δ data matrix
 6237 Lo floating point
 6238 Lo means
 6239 Lo standard deviations

6258)
 6259) Temp. storage area
 6260)

6261 n + 1 @ 29*

*Supplied by Compumatrix, Inc. Δ Matrix Prep. Progs.

- 4) Output: 24.0 - 12.6 format

GENERAL INFORMATION ON METHOD:

The equations used are:

$$1) \bar{x}_i = \frac{\sum x_i}{N}$$

- 2) Standard deviation

$$\sigma_{x_i} = \sqrt{\frac{\sum x_i^2}{N} - (\bar{x})^2}$$

- 3) Correlation coefficient

$$R_{ij} = \frac{\frac{\sum x_i x_j}{N} - \bar{x}_i \bar{x}_j}{\sigma_{x_i} \sigma_{x_j}}$$

CODING INFORMATION:

- A) Storage - subroutine 2 tracks and 17 sectors

Calculated storage as described above under "restrictions" 2 and 3

- B) No calling sequence required.

Linkage (R Lo + 216
 (U Lo

- C) Input: None

- D) Output: Format of 24.0 - 12.6

All answers are printed as computed. The correct number of tabs precedes the printing of each diagonal element of Rij matrix (See sample problem). The tabs may be eliminated by changing t[0209] in 0207 to u[0208] or u0127.

- E) Constants 0024 1 @ 29
 0201 XZ6363 Mask

and areas mentioned under Restriction (3).

F) Timing: The approximate times including printing are:

Means: 3 n sec.

Standard Deviations: 4 n sec.

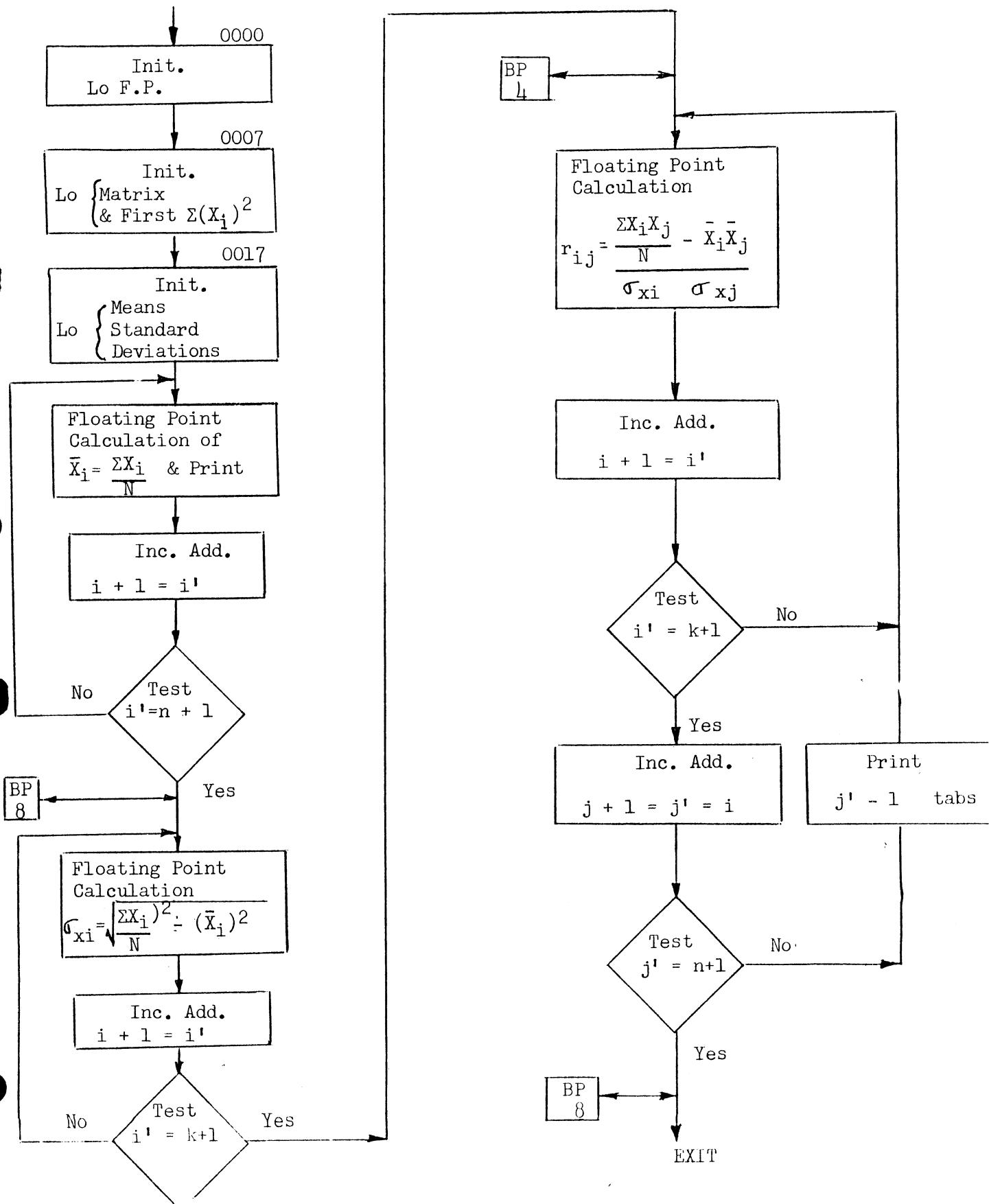
Rij matrix: n(n+1) x 2.25 sec.

Where n is the total number of variables.

G) Program stops:

0051	Breakpoint 8	\bar{x}_i calculations complete
0022	Breakpoint 4	σ_{x_i} calculation complete
0215	Breakpoint 8	Rij calculation complete

Flow Diagram Calculation of Means, Standard Deviations and Correlation Coefficient Triangular Matrix Floating Point



LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 1 / 5	
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 4-20-59		
PROBLEM: Given: Δ Matrix; Compute & Print \bar{X}_i , σ_{x_i} , Rij Matrix (F.P.)					TRACK 00	
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	'					
	' <input checked="" type="checkbox"/>					
	' 0 0 0	X,B 6,2,3 7	'		Lo Floating Point	
	' 0 1	Y 0 0 3 3	'		mean } sub	
	' 0 2	Y 0 0 3 4	'		mean }	
	' 0 3	Y 0 0 5 5	' <input checked="" type="checkbox"/>	σ_{x_i} l } sub		
	' 0 4	Y 0 0 5 6	'	σ_{x_i})		
	' 0 5	Y 0 1 2 7	'	rij } sub		
	' 0 6	Y 0 1 2 8	'	rij)		
	' 0 7	X,B 6,2,3 6	' <input checked="" type="checkbox"/>	Lo Δ Matrix		
	' 0 8	Y 0 0 3 6	'	mean }		
	' 0 9	Y 0 0 6 1	'	σ }	Lo of N	
	' 1 0	Y 0 1 3 3	'	rij)		
	' 1 1	A 0 0 2 4	' <input checked="" type="checkbox"/>	1 @ 29 n		
	' 1 2	Y 0 0 3 5	'	Lo first $\Sigma(X_i)$ (for mean)		
	' 1 3	X,A 6,2,3 3	'	gives Lo first $\Sigma(X_i)^2$ (n @ 29)		
	' 1 4	Y 0 0 6 0	'	σ_{x_i} sub		
	' 1 5	Y 0 1 3 2	' <input checked="" type="checkbox"/>	rij) sub		
	' 1 6	Y 0 1 3 7	'	rij)		
	' 1 7	X,B 6,2,3 8	'	Lo mean		
	' 1 8	Y 0 0 3 7	'	mean sub		
	' 1 9	Y 0 0 5 7	' <input checked="" type="checkbox"/>	σ_{x_i}) sub		
	' 2 0	Y 0 0 5 8	'	σ_{x_i})		
	' 2 1	Y 0 1 2 9	'	rij		
	' 2 2	Y 0 1 3 0	'	rij		
	' 2 3	X,P 1,6,0 0	' <input checked="" type="checkbox"/>	cr.		
	' 2 4	X,Z 0 0 0 1	'	delay & 1 @ 29		
	' 2 5	X,B 6,2,3 9	'	Lo standard deviations		
	' 2 6	Y 0 1 0 0	'	σ_{x_i} sub		
	' 2 7	Y 0 1 3 5	' <input checked="" type="checkbox"/>			
	' 2 8	Y 0 1 3 6	'			
	' 2 9	X,B 6,2,3 6	'	Lo Δ Matrix		
	' 3 0	X,A 6,2,6 1	'	n + 1 @ 29		
	' 3 1	X,C 6,2,6 0	' <input checked="" type="checkbox"/>	mean L _f +1	to test out	

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 2 / 5
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 4-20-59	
PROBLEM: Given: Δ Matrix. Compute & Print \bar{X}_i , σx_i , Rij Matrix					
PROGRAM INPUT CODES	STOP STOP	LOCATION	INSTRUCTION OPERATION ADDRESS	CONTENTS OF ADDRESS	NOTES
	/				
	/ <input checked="" type="checkbox"/>				
	0 0	3 2	X P 1 6 0 0	'	cr.
		3 3	R []	'	} F. Point
		3 4	U []	'	
		3 5	B []	' <input checked="" type="checkbox"/> n ΣX_i	
		3 6	D []	'	No. of records
		3 7	H []	'	\bar{X}_i
		3 8	X P 0 0 0 0	'	Print \bar{X}_i
		3 9	X E 0 0 0 0	' <input checked="" type="checkbox"/>	Exit floating point
		4 0	B 0 0 3 7	'	Add \bar{X}_i
		4 1	A 0 0 2 4	'	1 @ 29
		4 2	Y 0 0 3 7	'	
		4 3	B 0 0 3 5	' <input checked="" type="checkbox"/>	Add ΣX_i
		4 4	A 0 0 2 4	'	1 @ 29
		4 5	Y 0 0 3 5	'	
		4 6	E 0 2 0 1	' 3WWJ	mask
		4 7	X S 6 2 6 0	' <input checked="" type="checkbox"/>	
		4 8	T 0 0 3 3	'	loop back n times
		4 9	X P 1 6 0 0	'	cr.
		5 0	X Z 0 0 0 0	'	delay
		5 1	X Z 0 8 0 0	' <input checked="" type="checkbox"/>	BP 8 stop after means
		5 2	X B 6 2 6 1	'	(n+1) @ 29
		5 3	X C 6 2 6 0	'	Temp 1 (Ctr)
		5 4	X P 1 6 0 0	'	Δ Matrix Lf + 1 (Set for σx_i) (Temp 1)
		5 5	R []	' <input checked="" type="checkbox"/>	F.P.
		5 6	U []	'	
		5 7	P []	'	\bar{X}_i
		5 8	M []	'	\bar{X}_i
		5 9	X H 6 2 5 9	' <input checked="" type="checkbox"/> n 2 ΣX_i^2	Temp 2 (\bar{X}_i) ²
		6 0	B []	'	No of records
		6 1	D []	'	
		6 2	X S 6 2 5 9	' <input checked="" type="checkbox"/> \bar{X}_i^2	
		6 3	X R 0 0 0 0	' <input checked="" type="checkbox"/> ✓	

LGP-30 CODING SHEET

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE 4 OF 5		
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 4-20-59			
PROBLEM: Given: Δ Matrix; Compute & Print X_i , σ_{X_i} , Rij Matrix (F.P.)					TRACK 01		
PROGRAM INPUT CODES	P O S T	LOCATION	INSTRUCTION		P O S T	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
		1					
		1					
		0 1 3 2	B []	1		$\sum X_i X_j$	
		3 3	D []	1		No of records	
		3 4	X S 6 2 5 8	1		Temp 3	
		3 5	D []	1	<input checked="" type="checkbox"/>	σx_i	
		3 6	D []	1	<input checked="" type="checkbox"/>	σx_j	
		3 7	H []	1		rij	
		3 8	X P 0 0 0 0	1		Print rij	
		3 9	X E 0 0 0 0	1	<input checked="" type="checkbox"/>	Exit F.P.	
		4 0	B 0 1 3 2	1		add $\sum X_i X_j$	
		4 1	A 0 0 2 4	1		1 @ 29	
		4 2	Y 0 1 3 2	1			
		4 3	Y 0 1 3 7	1	<input checked="" type="checkbox"/>		
		4 4	B 0 1 3 6	1		add σx_j	
		4 5	A 0 0 2 4	1		1 @ 29	
		4 6	Y 0 1 3 6	1	<input checked="" type="checkbox"/>		
		4 7	B 0 1 3 0	1	<input checked="" type="checkbox"/>	add \bar{X}_j	
		4 8	A 0 0 2 4	1		1 @ 29	
		4 9	Y 0 1 3 0	1			
		5 0	E 0 2 0 1	1		3wwj mask	
		5 1	X S 6 2 6 0	1	<input checked="" type="checkbox"/>	mean $L_f + 1$	
		5 2	T 0 1 2 7	1			
		5 3	B 0 1 3 5	1		add σx_i	
		5 4	A 0 0 2 4	1	<input checked="" type="checkbox"/>	1 @ 29	
		5 5	Y 0 1 3 5	1	<input checked="" type="checkbox"/>		
		5 6	Y 0 1 3 6	1			
		5 7	B 0 1 2 9	1		add \bar{X}_i	
		5 8	A 0 0 2 4	1	<input checked="" type="checkbox"/>	1 @ 29	
		5 9	Y 0 1 2 9	1	<input checked="" type="checkbox"/>		
		6 0	Y 0 1 3 0	1			
		6 1	E 0 2 0 1	1		3wwj mask	
		6 2	X S 6 2 6 0	1	<input checked="" type="checkbox"/>	mean $L_f + 1$	
		6 3	T 0 2 0 2	1	<input checked="" type="checkbox"/>		

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 5 / 5
JOB NO.	PROGRAM NO. F2-129	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 4-20-59	
PROBLEM:	Given: A Matrix; Compute & Print X_i , σX_i , Rij Matrix (F. P.)				TRACK 02
PROGRAM INPUT CODES	STO	LOCATION	INSTRUCTION OPERATION ADDRESS	STO	CONTENTS OF ADDRESS
					NOTES
	/				
	/ <input checked="" type="checkbox"/>				
		0 2 0 , 0	U 0 2 1 , 3	/	Exit Path \rightarrow
		0 1	X Z 6 3 6 , 3	/	Mask for extract's
		0 2	X P 1 6 0 , 0	/	cr.
		0 3	X B 6 2 5 , 9	/ <input checked="" type="checkbox"/>	tab ctr.]
		0 4	A 0 0 2 , 4	/	l @ 29 { increase tab ctr by one
		0 5	X C 6 2 5 , 9	/	
		0 6	X S 6 2 5 , 9	/	make acc. negative
		0 7	T 0 2 0 , 9	/ <input checked="" type="checkbox"/>	Print tab
		0 8	U 0 1 2 , 7	/	Exit tab loop
		0 9	X Z 0 0 0 , 0	/	delay
		1 0	X P 2 4 0 , 0	/	tab
		1 1	A 0 0 2 , 4	/ <input checked="" type="checkbox"/>	l @ 29
		1 2	U 0 2 0 , 7	/	loop
		1 3	X P 1 6 0 , 0	/	cr.
		1 4	X Z 0 0 0 , 0	/	
		1 5	X Z 0 8 0 , 0	/ <input checked="" type="checkbox"/>	
		1 6	U []	/	
		1 7		/	
		1 8		/	
		1 9		/ <input checked="" type="checkbox"/>	
		2 0		/	
		2 1		/	
		2 2		/	
		2 3		/ <input checked="" type="checkbox"/>	
		2 4		/	
		2 5		/	
		2 6		/	
		2 7		/ <input checked="" type="checkbox"/>	
		2 8		/	
		2 9		/	
		3 0		/ <input checked="" type="checkbox"/>	
		3 1		/	



CARRIAGE RETURN

TITLE: Convert Triangular Rij matrix to a square Rij matrix - modified.

AUTHOR: William F. Burggrabe, Jr.
Compumatrix, Incorporated

DATE: October 13, 1959

PURPOSE: Given a triangular matrix as prepared by the subroutine "Calculation of Means, Standard Deviations and Correlation Coefficient Matrix", convert the correlation coefficient portion to a square Rij matrix with the initial location of Δ Rij equal to the initial location of the \square Rij. This routine also sets automatically location 6240 to the correct address.

RESTRICTIONS:

- A) The Lo Δ Rij matrix = Lo \square Rij matrix
- B) The entire subroutine is in fixed point and will operate on both fixed and floating point format matrices, but will not operate on matrices in an extended range format.
- C) External storage as on attached sheet.

METHOD: The subroutine takes advantage of the symmetry of the matrix and sets cell ij = cell ji. A looping process builds both the row and column cells of the square matrix while stepping through the matrix from the bottom.

CODING INFORMATION:

- A) Storage: 56 sectors
- B) Constants: Lo + 51 l @2
Lo + 52 l@29
Lo + 53 Mask
- C) Linkage: R [Lo + 55]
U [Lo]
- D) Stops: Break point 4 at end of conversion
- E) Timing: Approximately $\frac{n(n+1)}{6}$ seconds

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE 1 / 1		
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 10-10-59			
PROBLEM: External Storage $\Delta \rightarrow \square$ Rij Modified					TRACK 62		
PROGRAM INPUT CODES	PO S	LOCATION	INSTRUCTION		PO S	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
	/				/		
	/	X 2 3 2			/		
		3 3	X, Z []]		/	n @ 29	No variables *
		3 4			/		
		3 5			/	X	
		3 6	X Z []]		/	Lo Δ data Matrix	*
		3 7			/		
		3 8			/		
		3 9			/	X	
		4 0	X, Z []]		/	Lo \square rij matrix	
		4 1			/		
		4 2			/		
		4 3			/	X	
		4 4			/	Note: * These locations	
		4 5			/	must be filled prior to	
		4 6			/	entry into the subroutine	
		4 7			/	X	
		4 8			/		
		4 9			/	Note : ✓ These locations	
		5 0			/	normally filled by Δ Matrix	
		5 1			/	X	Prep. sub.
		5 2			/		
		5 3			/		
		5 4			/		
		5 5			/	X	
		5 6			/		
		5 7			/		
		5 8			/	X	
		5 9			/	X	Temp. storage
		6 0			/		
		6 1			/	n + 1 @ 29	* ✓
		6 2			/		
		6 3			/	X	(n+1)(n+2) @ 29 * ✓

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 1 / 2	
JOB NO.	PROGRAM NO. F2-129	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 10-10-59		
PROBLEM: $\Delta \text{ rij} \rightarrow \square \text{ rij}$ Matrix Conversion					TRACK 00	
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
; 0 0 0	Lo	/				
/ 0 0 0	Lo	/	X B 6 2 3 6	/	Lo Δ data matrix	
		9 0 0 , 0	X A 6 2 6 3	/	$(n+1)(n+2)$ @ 29	
		0 1	S 0 0 5 2	/	l @ 29	
		0 2	Y 0 0 1 7	/	\square B[] Lf Δ data matrix	
		0 3	X B 6 2 3 6	/	Lo Δ data matrix	
		0 4	X A 6 2 6 1	/	n + 1 @ 29	
		0 5	X C 6 2 4 0	/	Lo Δ rij matrix & Lo \square rij matrix	
		0 6	X C 6 2 6 0	/	\square Temp 1 \rightarrow 0 } Init. ctr's	
		0 7	X C 6 2 5 9	/	Temp 2 \rightarrow 0 }	
		0 8	X C 6 2 5 8	/	Temp 3 \rightarrow 0 }	
		0 9	X B 6 2 3 3	/	n @ 29	
		1 0	X N 6 2 3 3	/	\square n @ 29	
		1 1	M 0 0 5 1	/	l @ 2 \rightarrow n^2 @ 29	
		1 2	X A 6 2 4 0	/	Lo \square rij matrix	
		1 3	S 0 0 5 2	/	l @ 29 \rightarrow Lf \square rij matrix	
		1 4	Y 0 0 1 8	/	\square H[]	
		1 5	Y 0 0 1 9	/	C[]	
		1 6	B []	/	rij Δ matrix	
		1 7	H []	/	rij \square (row)	
		1 8	C []	/	\square rji \square (col)	
		1 9	B 0 0 1 7	/	B[]	
		2 0	S 0 0 5 2	/	l @ 29	
		2 1	Y 0 0 1 7	/	B[]	
		2 2	B 0 0 1 8	/	\square H[]	
		2 3	S 0 0 5 2	/	l @ 29	
		2 4	Y 0 0 1 8	/	H[]	
		2 5	X Y 6 2 5 8	/	Temp 3	
		2 6	B 0 0 1 9	/	\square C[]	
		2 7	X S 6 2 3 3	/	n @ 29	
		2 8	Y 0 0 1 9	/	C[]	
		2 9	E 0 0 5 3	/	3wwj mask	
		3 0	X S 6 2 5 8	/	\square Temp 3	
		3 1				

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 2 / 2		
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 1-10-61			
PROBLEM: $A_{rij} \rightarrow \square_{rij}$ Matrix Conversion					TRACK 00		
PROGRAM INPUT CODES	P O S T R O S T	LOCATION	INSTRUCTION		P O S T R O S T	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
	/						
	/	X					
		0 0 3 2	T 0 0 3 4	/	test out		
		3 3	U 0 0 1 7	/	loop		
		3 4	B 0 0 1 9	/	C[]		
		3 5	X A 6 2 5 9	/	X temp 2	0,1,2,...n-1	
		3 6	Y 0 0 1 8	/	H[]		
		3 7	X B 6 2 5 9	/	Temp 2		
		3 8	A 0 0 5 2	/	l @ 29	inc. ctr 2	
		3 9	X C 6 2 5 9	/	X temp 2		
		4 0	X B 6 2 5 8	/	= old H[]		
		4 1	X A 6 2 6 0	/	temp 1	0,n,2n,...(n-1)n	
		4 2	Y 0 0 1 9	/	C[]		
		4 3	X B 6 2 6 0	/	X temp 1		
		4 4	X A 6 2 3 3	/	n @ 29	inc. ctr 1	
		4 5	X C 6 2 6 0	/	temp 1		
		4 6	B 0 0 1 8	/	H[]		
		4 7	E 0 0 5 3	/	3wwj	mask	
		4 8	X S 6 2 4 0	/	Lo \square rij matrix		
		4 9	T 0 0 5 4	/	test out		
		5 0	U 0 0 1 7	/	loop -->		
, 0 0 0	0 0 0 3	/	5 1 2 0 0 0 0 0 0	/	X l @ 2		
			5 2	/	l @ 29		
			5 3	/	mask		
			5 4	/	BP 4 stop	after conversion	
.	0 0 0	0 0 0 0	/	5 5 U []	/	exit	
			5 6	/			
			5 7	/			
			5 8	/			
			5 9	/	X		
			6 0	/			
			6 1	/			
			6 2	/			
			6 3	/	X		

TITLE: Compute and Print Matrix Inverse

AUTHOR: William F. Burggrabe, Jr.
Compumatrix, Incorporated

DATE: April 24, 1959

PURPOSE: A) Initialize and transfer control to the matrix inversion routine (29.0).
B) Printout the inverse if it is desired (Transfer control up)

RESTRICTIONS:

- 1) Normal restrictions of 24.0, 12.6 and 29.0
- 2) See attached sheet for external information that must be supplied.
- 3) Output - 12.6 format

CODING INFORMATION:

- A) Storage: 55 sectors and under two above.
- B) Linkage: R (Lo + 54)
U (Lo)
- C) Input: None
- D) Output: 12.6 format with a carriage return after each row.

NOTE: Transfer control down skips printing to Lo + 53.

E) Constants:

Lo + 28	l @ 29
Lo + 29	14 @ 29
Lo + 30	XZ0149
Lo + 31	l @ 14

F) Timing:

Inversion: Approximately $1.08 n^3$ seconds

Printout: Approximately $2 n^2$ seconds

G) Program Stops:

Lo + 15*	B.P. 8 inversion complete
Lo + 53	B.P. 4 printing complete

*Depression of transfer control before continuing causes a transfer to Lo + 53, thus eliminating the printing phase of the program.

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE 1 / 1	
JOB NO.	PROGRAM NO. F2-129	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 4-24-59		
PROBLEM: External Storage					TRACK 62	
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/			/		
	/	X		/		
		6 2 3 2		/		
		3 3	X Z []	/	n @ 29 = Matrix Order *	
		3 4		/		
		3 5		/	X	
		3 6		/		
		3 7	X Z []	/	Lo floating Point *	
		3 8		/		
		3 9		/	X	
		4 0	X Z []	/	Lo rij matrix *	
		4 1		/		
		4 2	X Z []	/	Lo inversion sub. 29.0 *	
		4 3		/	X	
		4 4		/		
		4 5		/	* Note: These locations	
		4 6		/	must be filled prior	
		4 7		/	X to entry into subroutine	
		4 8		/		
		4 9		/		
		5 0		/		
		5 1		/	X	
		5 2		/		
		5 3		/		
		5 4		/		
		5 5		/	X	
		5 6		/		
		5 7		/		
		5 8		/		
		5 9	[]	/	X Temp & ctr	
		6 0	[]	/	Temp & ctr	
		6 1		/		
		6 2		/		
		6 3		/	X	

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE 1 / 2		
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 4-24-59			
PROBLEM: Call-in, Compute & Print - Inverse (Rice F.P.M.I.)					TRACK 00		
PROGRAM INPUT CODES	P O STOP	LOCATION	INSTRUCTION		P O STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
; 0 0 0	1						
/ 0 0 0	1	X					
		0 0	0 0 0	X B 6 2 3 3	1	n @ 29	
			0 1	D 0 0 3 1	1	1 @ 14	
			0 2	X A 6 2 4 0	1	Lo rij matrix	
			0 3	C 0 0 1 4	1	X	
			0 4	X B 6 2 4 2	1	Lo matrix Inversion sub. (Rice M.I.)	
			0 5	Y 0 0 1 3	1		
			0 6	A 0 0 2 9	1	XZ 0 0 1 4	
			0 7	Y 0 0 1 2	1	X	
			0 8	A 0 0 3 0	1	XZ 0 1 4 9	
			0 9	Y 0 0 1 1	1		
			1 0	X B 6 2 3 7	1	Lo Floating Point	
			1 1	Y []	1	(Matrix Inversion Lo + 163)	
			1 2	R []	1	} Matrix Inversion Linkage	
			1 3	U []	1		
			1 4	[]	1	Code word	
			1 5	X Z 0 8 0 0	1	BP 8 stop after inversion	
			1 6	X C 6 2 6 0	1	Clear acc.	
			1 7	8 9 0 T 0 0 5 3	1	Skip inverse print-out	
			1 8	X C 6 2 6 0	1	ctr 1 → 0	
			1 9	X C 6 2 5 9	1	ctr 2 → 0	
			2 0	X B 6 2 3 7	1	Lo Floating Point	
			2 1	Y 0 0 3 2	1		
			2 2	Y 0 0 3 3	1		
			2 3	X B 6 2 4 0	1	Lo rij Matrix Inverse	
			2 4	Y 0 0 3 4	1		
			2 5	X P 1 6 0 0	1	C.R.	
			2 6	X Z 0 0 0 0	1	delay	
			2 7	U 0 0 3 2	1	transfer over constants	
			2 8	X Z 0 0 0 1	1	1 @ 29	
			2 9	X Z 0 0 1 4	1	14 @ 29	
			3 0	X Z 0 1 4 9	1	Used to set up Rice F.P.M.I.	(Lo + 163 in
			3 1	X Y 0 0 0 0	1	X	Rice F.P.M.I.
						1 @ 14	

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE 2	OF 2	
JOB NO.	PROGRAM NO. F2-129	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review		DATE 4-24-59		
PROBLEM: Call-in, Compute & Print - Inverse (Rice F.P.M.I.)					TRACK 00		
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION		STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
	/						
	/						
		3 2	R []		/	F.P. Linkage	
		3 3	U []		/		
		3 4	B []		/	No. to print	
		3 5	X P 0 0 0 0		/	Print No.	
		3 6	X E 0 0 0 0		/	Exit F.P.	
		3 7	B 0 0 3 4		/	add. of no. printed	
		3 8	A 0 0 2 8		/	1 @ 29	
		3 9	Y 0 0 3 4		/		
		4 0	X B 6 2 6 0		/	ctr 1	
		4 1	A 0 0 2 8		/	1 @ 29	
		4 2	X H 6 2 6 0		/	ctr 1	
		4 3	X S 6 2 3 3		/	n @ 29	
		4 4	T 0 0 3 2		/	loop n times	
		4 5	X P 1 6 0 0		/	cr.	
		4 6	X C 6 2 6 0		/	ctr 1 → 0	
		4 7	X B 6 2 5 9		/	ctr 2	
		4 8	A 0 0 2 8		/	1 @ 29	
		4 9	X H 6 2 5 9		/	ctr 2	
		5 0	X Z 0 0 0 0		/	delay	
		5 1	X S 6 2 3 3		/	n @ 29	
		5 2	T 0 0 3 2		/	loop n times	
		5 3	X Z 0 4 0 0		/	BP 4 stop after printing	
		5 4	U []		/	exit	
		5 5			/		
		5 6			/		
		5 7			/		
		5 8			/		
		5 9			/		
		6 0			/		
		6 1			/		
		6 2			/		
		6 3			/		

TITLE: Calculation of Beta Weights, Regression Coefficients; Partial Correlation Coefficient and Standard Error of the Independent Variables; the Constant Term (b_0) and its Standard Error; the Sample Multiple Correlation Coefficient and Standard Error of Estimate; the Universe Multiple Correlation Coefficient and Standard Error of Estimate.

AUTHOR: William F. Burggrabe, Jr.
Compumatrix, Incorporated

DATE: May 26, 1960.

PURPOSE: Given the inverse of the correlation coefficient matrix, the means and standard deviations of the variables; compute and printout the above.

RESTRICTIONS:

- 1) The last row and column of the matrix contain elements corresponding to the dependent variable. (Explanation under "Method").
- 2) Normal restrictions of 24.0 and 12.6.
- 3) See attached sheet for external storage of information that must be supplied.
- 4) 25.0R in 0900.

METHOD:

A) Given a correlation coefficient matrix of the form:

	X ₁	X ₂	X ₃	...	Y
X ₁	R ₁₁	R ₁₂	R ₁₃	...	R _{1y}
X ₂	R ₂₁	R ₂₂	R ₂₃	...	R _{2y}
X ₃	R ₃₁	R ₃₂	R ₃₃	...	R _{3y}
⋮	⋮	⋮	⋮	⋮	⋮
⋮	⋮	⋮	⋮	⋮	⋮
⋮	⋮	⋮	⋮	⋮	⋮
Y	R _{y1}	R _{y2}			R _{yy}

An inverse of the (Rij) matrix is computed yielding:

	X_1	X_2	...	Y
X_1	$\frac{1}{v_{1,23} \dots y}$	$-\frac{\beta_{21,34} \dots}{v_{2,13} \dots y}$	\dots	$-\frac{\beta_{y1,23} \dots}{v_{y,123} \dots}$
X_2	$-\frac{\beta_{12,34} \dots}{v_{1,23} \dots y}$	$\frac{1}{v_{2,13} \dots y}$	\dots	$-\frac{\beta_{y2,13} \dots}{v_{y,123} \dots}$
\vdots	\vdots	\vdots		\vdots
Y	$-\frac{\beta_{1y,23} \dots}{v_{1,23} \dots y}$	$-\frac{\beta_{2y,13} \dots}{v_{2,13} \dots y}$	\dots	$\frac{1}{v_{y,123} \dots}$

B) Where:

1. The β 's, Beta weights, are equal to the coefficients of the equation:

$$\frac{y' - \bar{y}}{\sigma_y} = \beta_1 \frac{(x - \bar{x})_1}{\sigma_{x1}} + \beta_2 \frac{(x - \bar{x})_2}{\sigma_{x2}} + \dots + \beta_{n-1} \frac{(x - \bar{x})_{n-1}}{\sigma_{xn-1}}$$

y' = Predicted Value

$\beta_1 = \beta_{y1,23} \dots$

$\beta_2 = \beta_{y2,13} \dots$

\bar{x}_i, \bar{y} = means

σ_{xi}, σ_y = standard deviations

The β 's are obtained by dividing each column element by the principle diagonal element in that column.

NOTE: All β 's for all multiple regression equations (i.e., are available in the inverse.

2. The regression coefficients are obtained from the Beta weights as follows:

$$b_0 = \bar{Y} - \bar{X}_1 \frac{\sigma_y}{\sigma_{x1}} \beta_1 - \bar{X}_2 \frac{\sigma_y}{\sigma_{x2}} \beta_2 - \bar{X}_3 \frac{\sigma_y}{\sigma_{x3}} \beta_3 \dots$$

$$b_1 = \beta_1 \frac{\sigma_y}{\sigma_{x1}}$$

$$b_2 = \beta_2 \frac{\sigma_y}{\sigma_{x2}}, \text{ etc.}$$

3. The partial correlation coefficients are obtained by:

$$r^2_{ab,cde \dots} = \frac{\left(\frac{\beta_{ab,cde \dots}}{V_{a,bcde \dots}} \right) \cdot \left(\frac{\beta_{ba,cde \dots}}{V_{b,acde \dots}} \right)}{\left(\frac{1}{V_{a,bcde \dots}} \right) \cdot \left(\frac{1}{V_{b,acde \dots}} \right)}$$

However, because of the symmetry of the inverse,

$$\frac{\beta_{ab,cde \dots}}{V_{a,bcde \dots}} = \frac{\beta_{ba,cde \dots}}{V_{b,acde \dots}}$$

There, each partial correlation coefficient may be obtained by dividing the corresponding off principal diagonal element by the square root of the product of the row, column elements of the principal diagonal.

4. Standard error of regression coefficient --

$$S_{bi} = \hat{s} \cdot \sqrt{\frac{(1-r_{iy,123 \dots}^2)}{N \sigma_i^2 (1-R_{i,23 \dots}^2)}}$$

5. The regression multiple correlation coefficients for the n equations are computed as follows:

$$R^2_{a,bcde} = 1 - \frac{1}{\text{ath diag. element}}$$

or --

$$R = \sqrt{1 - \frac{1}{\left(\frac{1}{V_{y,123 \dots}} \right)}}$$

Etc.

6. The standard error of estimate is:

$$S = \sigma_y \sqrt{1 - R^2}$$

7. Universe multiple correlation coefficient --

$$\hat{R} = \sqrt{1 - (1-R^2) \left(\frac{N-1}{N-n} \right)}$$

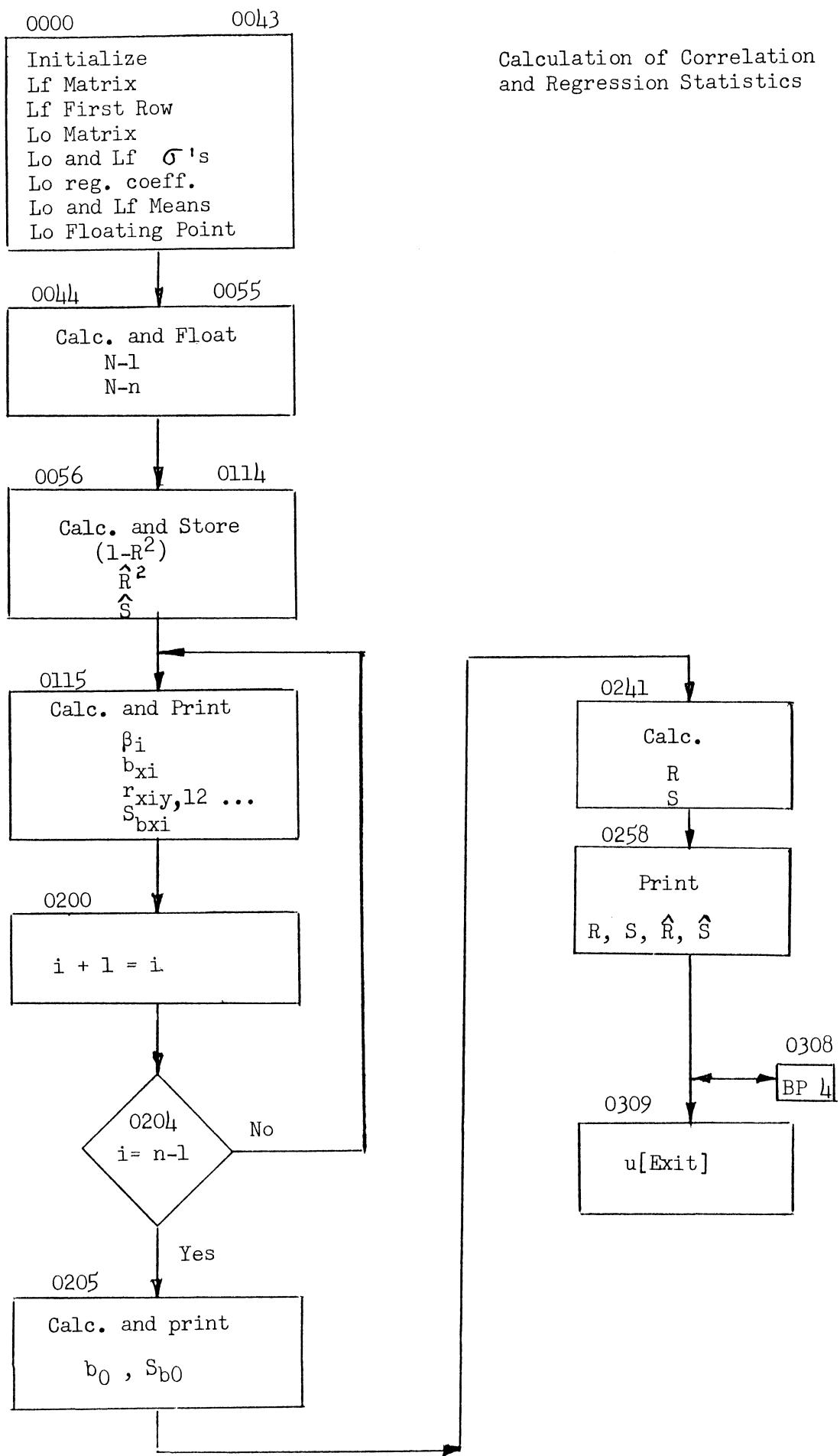
8. Universe standard error of estimate --

$$\hat{S} = \sigma_y \sqrt{(1-\hat{R}^2) \left(\frac{N}{N-1} \right)}$$

- C) The program that has been written assumes the dependent variable cells to occupy the last column and/or row. However, a routine could be written for any other designation, or since the program does not alter the inverse, rows and columns could be interchanged, to put the correct elements in the proper locations for this program.

CODING INFORMATION:

- A) Storage 3 tracks 10 sectors plus external storage on attached sheet.
- B) Linkage R (Lo + 309)
U (Lo)
- C) Input None
- D) Output 12.6 - format (See sample problem)
- Order: $\beta_1, b_1, R_{1y}, 2 \dots S_{b1}$ C.R.
 $\beta_2, b_2, R_{2y}, 1 \dots S_{b2}$ C.R.
etc.
 $B_{n-1}, b_{n-1}, R_{n-ly}, 1 \dots$ C.R.
Tab b_0 Tab S_{b0} C.R.
C.R.
 $R, , S, \hat{R}, \hat{S}$
- E) Constants Lo + 226 1 @ 29
Lo + 240 1 @ 2
Lo + 148 Floating Point "1"
- F) Timing: Approximately 10 n seconds
- G) Stops: Lo + 308 B.P. 4 stop at completion of program



LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization					PAGE OF 1 / 1		
JOB NO.	PROGRAM NO. F2-129	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 1-15-60			
PROBLEM: External Storage					TRACK 62		
PROGRAM INPUT CODES	PO STO P	LOCATION	INSTRUCTION		STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
	/						
	/						
		6 2 3 2			/		
		3 3	X Z []		/	n @ 29 Order of Inverse	*
		3 4	X Z []		/	N @ 24 No of Records	*
		3 5			/		
		3 6			/		
		3 7	X Z []		/	Lo Floating Point	*
		3 8	X Z []		/	Lo Means	*
		3 9	X Z []		/	Lo Standard Deviations	*
		4 0	X Z []		/	Lo Inverse (rij Matrix)	*
		4 1			/		
		4 2			/		
		4 3	X Z []		/	Lo Regression Coefficients	*
		4 4			/		
		4 5			/		
		4 6			/	* Note: These locations must	
		4 7			/	be filled prior to entering	
		4 8			/	into subroutine.	
		4 9			/		
		5 0			/		
		5 1			/		
		5 2			/		
		5 3			/		
		5 4			/		
		5 5			/		
		5 6			/		
		5 7			/		
		5 8	[]		/	Temp	
		5 9	[]		/	Temp	
		6 0	[]		/	Temp	
		6 1	[]		/	n + 1 @ 29	*
		6 2			/		
		6 3			/		

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 1 / 7	
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 1-15-60		
PROBLEM: β_{xi} , b_{xi} , Partial Corr. Coeff, S_{bxi} , b_0 , & est, R , σ est, \hat{R} , $\hat{\sigma}$ est					TRACK 00	
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/					
		0 0 0 0 0	X, B 6 2 3 3	/	n @ 29	
		0 1	X, N 6 2 3 3	/	n @ 29	
		0 2	M 0 2 4 0	/	l @ 2	
		0 3	S 0 2 2 6	/	<input checked="" type="checkbox"/> l @ 29	
		0 4	X, A 6 2 4 0	/	Lo □ Matrix Inverse	
		0 5	Y 0 0 6 0	/	Add [1/V _n]	
		0 6	X, B 6 2 3 3	/	n @ 29	
		0 7	S 0 2 2 6	/	<input checked="" type="checkbox"/> l @ 29	
		0 8	X, H 6 2 5 4	/	Temp	ctr
		0 9	X, A 6 2 4 0	/	Lo □ Matrix Inverse	
		1 0	Y 0 1 1 7	/	- β_i/V_n	
		1 1	Y 0 1 3 1	/	<input checked="" type="checkbox"/>	
		1 2	X, B 6 2 4 0	/	Lo □ Matrix Inverse	
		1 3	Y 0 1 2 7	/	Add 1/V _i	
		1 4	X, B 6 2 3 9	/	Lo σ 's	
		1 5	Y 0 1 2 3	/	<input checked="" type="checkbox"/> Add [σ_{x_i}]	
		1 6	Y 0 1 4 0	/	"	
		1 7	Y 0 1 4 1	/	"	
		1 8	X, A 6 2 5 4	/	n-1 @ 29	
		1 9	Y 0 1 1 2	/	<input checked="" type="checkbox"/> Add [σ_y]	
		2 0	Y 0 1 2 2	/	"	
		2 1	Y 0 2 5 2	/	"	
		2 2	X, B 6 2 4 3	/	Lo reg. Coeff.	
		2 3	Y 0 2 3 1	/	<input checked="" type="checkbox"/> Add [b_0]	
		2 4	A 0 2 2 6	/	l @ 29	
		2 5	Y 0 1 2 4	/	Add [b_{xi}]	
		2 6	Y 0 2 1 0	/		
		2 7	X, B 6 2 3 8	/	<input checked="" type="checkbox"/> Lo Means	
		2 8	Y 0 2 0 9	/		
		2 9	X, A 6 2 5 4	/	n-1 @ 29	
		3 0	Y 0 2 2 9	/	Add \bar{Y}	
		3 1	X, B 6 2 3 7	/	<input checked="" type="checkbox"/> Lo Floating Point	

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL				PAGE OF 2 / 7		
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 1-15-60		
PROBLEM: β_{xi} , b_{xi} , Partial Corr. Coeff, S_{bxi} , b_0 , & est, R , σ_{est} , \hat{R} , $\hat{\sigma}_{est}$				TRACK 00		
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/ <input checked="" type="checkbox"/>					
	0 0 3 2	1 1 Y 0 0 5 7	/			
	1 3 3	1 1 Y 0 0 5 8	/			
	1 3 4	1 1 Y 0 1 1 5	/			
	1 3 5	1 1 Y 0 1 1 6	/ <input checked="" type="checkbox"/>			
	1 3 6	1 1 Y 0 2 0 7	/			
	1 3 7	1 1 Y 0 2 0 8	/			
	1 3 8	1 1 Y 0 2 2 7	/			
	1 3 9	1 1 Y 0 2 2 8	/ <input checked="" type="checkbox"/>			
	1 4 0	1 1 Y 0 2 4 1	/			
	1 4 1	1 1 Y 0 2 4 2	/			
	1 4 2	1 1 Y 0 2 5 8	/			
	1 4 3	1 1 Y 0 2 5 9	/ <input checked="" type="checkbox"/>			
	1 4 4	X B 6 2 3 4	/ n @ 29			
	1 4 5	S 0 2 2 6	/ l @ 29			
	1 4 6	X R 0 9 2 5	/ float 25.0R			
	1 4 7	X U 0 9 0 0	/ <input checked="" type="checkbox"/>			
	1 4 8	X Z 0 0 2 9	/			
	1 4 9	X C 6 2 5 7	/ n-1			
	1 5 0	X B 6 2 3 4	/ n @ 29			
	1 5 1	X S 6 2 3 3	/ <input checked="" type="checkbox"/> n @ 29			
	1 5 2	X R 0 9 2 5	/ float 25.0R			
	1 5 3	X U 0 9 0 0	/			
	1 5 4	X Z 0 0 2 9	/			
	1 5 5	X C 6 2 5 8	/ <input checked="" type="checkbox"/> n-P			
	1 5 6	X C 6 2 5 3	/ Temp → 0			
	1 5 7	R []	/ 24.0			
	1 5 8	U []	/			
	1 5 9	B 0 1 4 8	/ <input checked="" type="checkbox"/> "1"			
	1 6 0	D []	/ $1/V_n$			
	1 6 1	X H 6 2 5 9	/ $(1-R^2)$			
	1 6 2	X D 6 2 5 8	/			
	1 6 3	X H 6 2 5 8	/ <input checked="" type="checkbox"/> $(1-R^2)$ N.T.			

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PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 3 /7	
JOB NO.	PROGRAM NO. F2-129	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 1-15-60		
PROBLEM: $b_{xi}, b_{xj}, \text{ Partial Corr. Coeff, } S_{bxi}, b_o, \text{ & est, } R, \sigma_{\text{est}}, \hat{R}, \hat{\sigma}_{\text{est}}$					TRACK 01	
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/ <input checked="" type="checkbox"/>					
	0 1 0 0	X U	0 0 0 0	/	Acc. $\rightarrow M$	
	1 0 1	X M	6 2 5 7	/	(N-1) $\rightarrow (1-\hat{R}^2)$	
	1 0 2	X Y	0 0 0 0	/	change signs $\rightarrow -1 + \hat{R}^2$	
	1 0 3	A	0 1 4 8	/ <input checked="" type="checkbox"/>	"1" $\rightarrow \hat{R}^2$	
	1 0 4	X H	6 2 6 0	/		
	1 0 5	X B	6 2 5 7	/	N-1	
	1 0 6	A	0 1 4 8	/	1	
	1 0 7	X H	6 2 5 5	/ <input checked="" type="checkbox"/>	$\rightarrow n$	
	1 0 8	X U	0 0 0 0	/		
	1 0 9	X M	6 2 5 8	/	$\frac{1-\hat{R}^2}{(N-1)} \rightarrow \frac{(1-\hat{R})^2 N}{N-1}$	
	1 1 0	X R	0 0 0 0	/	$\sqrt{ }$	
	1 1 1	X U	0 0 0 0	/ <input checked="" type="checkbox"/>		
	1 1 2	M	[]	/	σ_y	
	1 1 3	X H	6 2 5 8	/	\hat{S}	
	1 1 4	X E	0 0 0 0	/	Exit	F.P.
	1 1 5	R	[]	/ <input checked="" type="checkbox"/>	24.0	
	1 1 6	U	[]	/		
	1 1 7	P	[]	/	$-\beta/V_n$	
	1 1 8	X M	6 2 5 9	/	V_n	
	1 1 9	X Y	0 0 0 0	/ <input checked="" type="checkbox"/>	Change Signs	
	1 2 0	X P	0 0 0 0	/	Print β_i	
	1 2 1	X U	0 0 0 0	/	Acc $\rightarrow M$	
	1 2 2	M	[]	/	σ_y	
	1 2 3	D	[]	/ <input checked="" type="checkbox"/>	σ_{xi}	
	1 2 4	H	[]	/	b_{xi}	
	1 2 5	X P	0 0 0 0	/		
	1 2 6	B	0 1 4 8	/	"1"	
	1 2 7	D	[]	/ <input checked="" type="checkbox"/>	$1/V_i$	
	1 2 8	X H	6 2 5 7	/	$(1-R_i^2)$	
	1 2 9	X M	6 2 5 7	/	$\beta_i \cdot V_i$	
	1 3 0	X U	0 0 0 0	/ <input checked="" type="checkbox"/>	$-\beta_j/V_j$	$-\beta_{iy} \cdot \beta_{yi}$
	3 1	M	[]	/ <input checked="" type="checkbox"/>		



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PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE 4 OF 7		
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 1-15-60			
PROBLEM: β_{xi} , b_{xi} , Partial Corr. Coeff, S_{bxi} , b_o , & est, R , σ_{est} , R , σ_{est}					TRACK 01		
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION		STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
	/						
	/	X					
		0,1,3,2	X,Y	0,0,0,0	/	r^2	
		1,3,3	X,H	6,2,5,6	/	rij.xxx	Partial rij.xxx
		1,3,4	X,R	0,0,0,0	/	\checkmark	
		1,3,5	X,P	0,0,0,0	/	X	
		1,3,6	B	0,1,4,8	/	"1"	
		1,3,7	X,S	6,2,5,6	/	r^2	
		1,3,8	X,D	6,2,5,7	/	$(1-R_i^2)$	
		1,3,9	X,D	6,2,5,5	/	X	N
		1,4,0	D	[]	/	σ_{xi}	
		1,4,1	D	[]	/	σ_{xi}	$(1-r^2)/N \sigma (1-R_i^2)$
		1,4,2	X,R	0,0,0,0	/	\checkmark	$\rightarrow \sqrt{C_{ij}}$
		1,4,3	X,U	0,0,0,0	/	X	Acc \rightarrow M
		1,4,4	X,M	6,2,5,8	/	$\hat{\sigma}_{est}$	
		1,4,5	X,P	0,0,0,0	/	Print	(S_{bxi})
		1,4,6	X,E	0,0,0,0	/	X	
		1,4,7	X,P	1,6,0,0	/	X	
,000	0,0,0,1	1	4,8	4,0,0,0,0,0,2	/	F.P. "1" & delay	
			1,4,9	B	0,1,1,7	/	Add $[-\beta_i/V_n]$
			1,5,0	X,A	6,2,3,3	/	$n @ 29$
			1,5,1	Y	0,1,1,7	/	X
			1,5,2	Y	0,1,3,1	/	
			1,5,3	B	0,1,2,3	/	$D[\sigma_{xi}]$
			1,5,4	A	0,2,2,6	/	$l @ 29$
			1,5,5	Y	0,1,2,3	/	X
			1,5,6	Y	0,1,4,0	/	
			1,5,7	Y	0,1,4,1	/	
			1,5,8	B	0,1,2,4	/	$H[b_{xi}]$
			1,5,9	A	0,2,2,6	/	X
			1,6,0	Y	0,1,2,4	/	$1 @ 29$
			1,6,1	B	0,1,2,7	/	$D[1/V_i]$
			1,6,2	X,A	6,2,6,1	/	$(n+1) @ 29$
			1,6,3	Y	0,1,2,?	/	X



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JOB NO. F2-129	PROGRAM NO. F2-129	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 1-15-60	TRACK 02		
PROBLEM: β_{xi} , b_{xi} , Partial Corr. Coeff, S_{bxi} , b_0 , & est, R, σ est, \bar{R} , $\hat{\sigma}$ est							
PROGRAM INPUT CODES	P STOP	LOCATION	INSTRUCTION		STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
	/						
	/	X B 6 2 5 3			/	Ctr	
		0 0	X A 0 2 2 6		/	1 @ 29	
		0 1	X H 6 2 5 3		/	Ctr	
		0 2	X S 6 2 5 4		/	<input checked="" type="checkbox"/> n - 1 @ 29	
		0 3	T 0 1 1 5		/		
		0 4	X C 6 2 5 3		/	Ctr	
		0 5	X C 6 2 5 6		/	Σ Area	
		0 6	R []		/	<input checked="" type="checkbox"/> 24.0	
		0 7	U []		/		
		0 8	P []		/	\bar{x}_i	
		0 9	M []		/	b_{xi}	
		1 0	X A 6 2 5 6		/	<input checked="" type="checkbox"/> Σ	
		1 1	X H 6 2 5 6		/	Σ	
		1 2	X E 0 0 0 0		/	Exit F.P.	
		1 3	B 0 2 0 9		/	P[\bar{x}_i]	
		1 4	A 0 2 2 6		/	<input checked="" type="checkbox"/> 1 @ 29	
		1 5	Y 0 2 0 9		/		
		1 6	B 0 2 1 0		/		
		1 7	A 0 2 2 6		/	1 @ 29	
		1 8	X B 6 2 5 3		/	ctr	
		1 9	A 0 2 2 6		/	<input checked="" type="checkbox"/> 1 @ 29	
		2 0	X H 6 2 5 3		/	ctr	
		2 1	X S 6 2 5 4		/	<input checked="" type="checkbox"/> (n-1) @ 29	
		2 2	T 0 2 0 7		/		
		2 3	X P 2 4 0 0		/	tab	
		2 4	X Z 0 0 0 1		/	1 @ 29 & delay	
		2 5	R []		/	<input checked="" type="checkbox"/> 24.0	
		2 6	U []		/		
		2 7	B []		/	\bar{Y}	
		2 8	X S 6 2 5 6		/	Σ	
		2 9	H []		/	<input checked="" type="checkbox"/> b ₀	
		3 0					
		3 1					

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JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 1-15-60		
PROBLEM: β_{xi}, b_{xi} , Partial Corr. Coeff, S_{bxi} , b_o , & est, R, σ est, \hat{R} , $\hat{\sigma}$ est					TRACK 02	
PROGRAM INPUT CODES	STO	LOCATION	INSTRUCTION	PO	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/ <input checked="" type="checkbox"/>					
	0 2 3 2	X P 0 0 0 0	/			
	1 3 3	X B 6 2 5 5	/	N		
	1 3 4	X R 0 0 0 0	/	$\sqrt{\quad} \rightarrow \sqrt{N}$		
	1 3 5	X H 6 2 5 5	/ <input checked="" type="checkbox"/>			
	1 3 6	X B 6 2 5 8	/	\hat{S} est		
	1 3 7	X D 6 2 5 5	/	\sqrt{N}		
	1 3 8	X E 0 0 0 0	/	Exit F.P.		
	1 3 9	X P 2 4 0 0	/ <input checked="" type="checkbox"/>	tab		
, 0 0 0 0 0 0 1	' 4 0	2 0 0 0 0 0 0 0	/	1@ 2 and delay		
	1 4 1	R []]	/			
	1 4 2	U []]	/			
	1 4 3	X P 0 0 0 0	/ <input checked="" type="checkbox"/>	S_b		
	1 4 4	X B 6 2 5 9	/	$1-R^2$		
	1 4 5	S 0 1 4 8	/	"1"		
	1 4 6	X Y 0 0 0 0	/	Change signs R^2		
	1 4 7	X R 0 0 0 0	/ <input checked="" type="checkbox"/>	$\sqrt{\quad}$	R	
	1 4 8	X H 6 2 5 7	/	R		
	1 4 9	X B 6 2 5 9	/	$1-R^2$		
	1 5 0	X R 0 0 0 0	/	$\sqrt{\quad}$		
	1 5 1	X U 0 0 0 0	/ <input checked="" type="checkbox"/>	Acc $\rightarrow M$		
	1 5 2	M []]	/	$\sigma_y \rightarrow S$ est		
	1 5 3	X H 6 2 5 9	/	S est		
	1 5 4	X E 0 0 0 0	/			
	1 5 5	X P 1 6 0 0	/ <input checked="" type="checkbox"/>	cr.		
	1 5 6	X Z 0 0 0 0	/			
	1 5 7	X P 1 6 0 0	/	cr.		
	1 5 8	R []]	/			
	1 5 9	U []]	/ <input checked="" type="checkbox"/>			
	1 6 0	X B 6 2 5 7	/	R		
	1 6 1	X P 0 0 0 0	/	Print		
	1 6 2	X B 6 2 5 9	/ <input checked="" type="checkbox"/>	S est		
	1 6 3	X P 0 0 0 0	/ <input checked="" type="checkbox"/>	Print		



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PREPARED FOR: LGP-30, RPC-4000 Users Organization - POOL					PAGE OF 7 / 7	
JOB NO.	PROGRAM NO. F2-129	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 1-15-60		
PROBLEM: β_{xi} , b_{xi} , Partial Corr. Coeff, S_{bxi} , b_0 , & est, R , σ_{est} , \hat{R} , $\hat{\sigma}_{est}$					TRACK 03	
PROGRAM INPUT CODES	D O S T O P STOP	LOCATION	INSTRUCTION		CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS		
	/					
	/	X	B	6 2 6 0	/	
	0 3	0 0 0			\hat{R}^2	
	0 1		x R	0 0 0 0	/	
	0 2		X P	0 0 0 0	/	
	0 3		X B	6 2 5 0	/	\hat{S}_{est}
	0 4		X P	0 0 0 0	/	
	0 5		X E	0 0 0 0	/	
	0 6		X P	1 6 0 0	/	cr.
	0 7		X Z	0 0 0 0	/	delay
	0 8		X Z	0 4 0 0	/	Stop
	0 9		U	[] []	/	Exit
	1 0				/	
	1 1				/	
	1 2				/	
	1 3				/	
	1 4				/	
	1 5				/	
	1 6				/	
	1 7				/	
	1 8				/	
	1 9				/	
	2 0				/	
	2 1				/	
	2 2				/	
	2 3				/	
	2 4				/	
	2 5				/	
	2 6				/	
	2 7				/	
	2 8				/	
	2 9				/	
	3 0				/	
	3 1				/	



CARRIAGE RETURN

I = CONDITIONAL STOP CODE

TITLE: Calculation of Y^1 and $(y-y^1)$ given a set of coefficients $(B_0, B_1, \dots B_n)$ and a set of records $(l, X_1, X_2 \dots X_n)$

AUTHOR: Allen G. Renz
Compumatrix, Incorporated

DATE: October 8, 1959

PURPOSE: To read in a set of records, each record containing values for $X_1, X_2, \dots X_n$ and Y , and calculate a predicted value of Y, Y^1 , using a set of coefficients stored in the machine. Also calculate $(y-y^1)$ and print out Y, Y^1 , and $(y-y^1)$.

RESTRICTIONS:

- A) Normal restrictions of 11.2 and 12.1
- B) Coefficients must be stored in machine prior to entering subroutine in order, (i.e., $b_0, b_{x1}, \dots, b_{xn}$) in fixed point @ q of variables.
- C) The number of variables is limited only by machine storage available.

CODING INFORMATION:

- A) Storage
 - 1) Program - 54 sectors
 - 2) External storage - 6232 to 6263 (See attached sheet)
 - 3) 11.2 data input - 0300-0563
 - 4) 12.1 data output - 0600-0763

- B) No calling sequence is required.

Linkage: R (Lo + 50)

U (Lo + 00)

- C) Input is in 11.2 data input format in the following sequence:

First record

P ± qq (Lo record) ' l' X₁' X₂' ... X_n' Y' -00000000''

Following Records:

P ± qq (Lo record +1)' X₁' X₂' ... X_n' Y' -00000000''

- D) Output: Output is in 12.1 fixed point data output format. Three columns are printed out:

y₁ y¹ and (y-y¹) at ZQ of variables (X₁ ... X_n)

- E) Location of constants:

Lo + 36 l@ 29

Lo + 51 XZ 0300

Lo + 52 XZ 6363

Lo + 53 Temp storage

- F) Timing: 5 sec/15 X's/ record + input and print time

- G) Program stops:

Lo + 45 B.P. 4 after print out

Lo + 49 B.P. 8 after completion

- H) Storage Requirement(External)

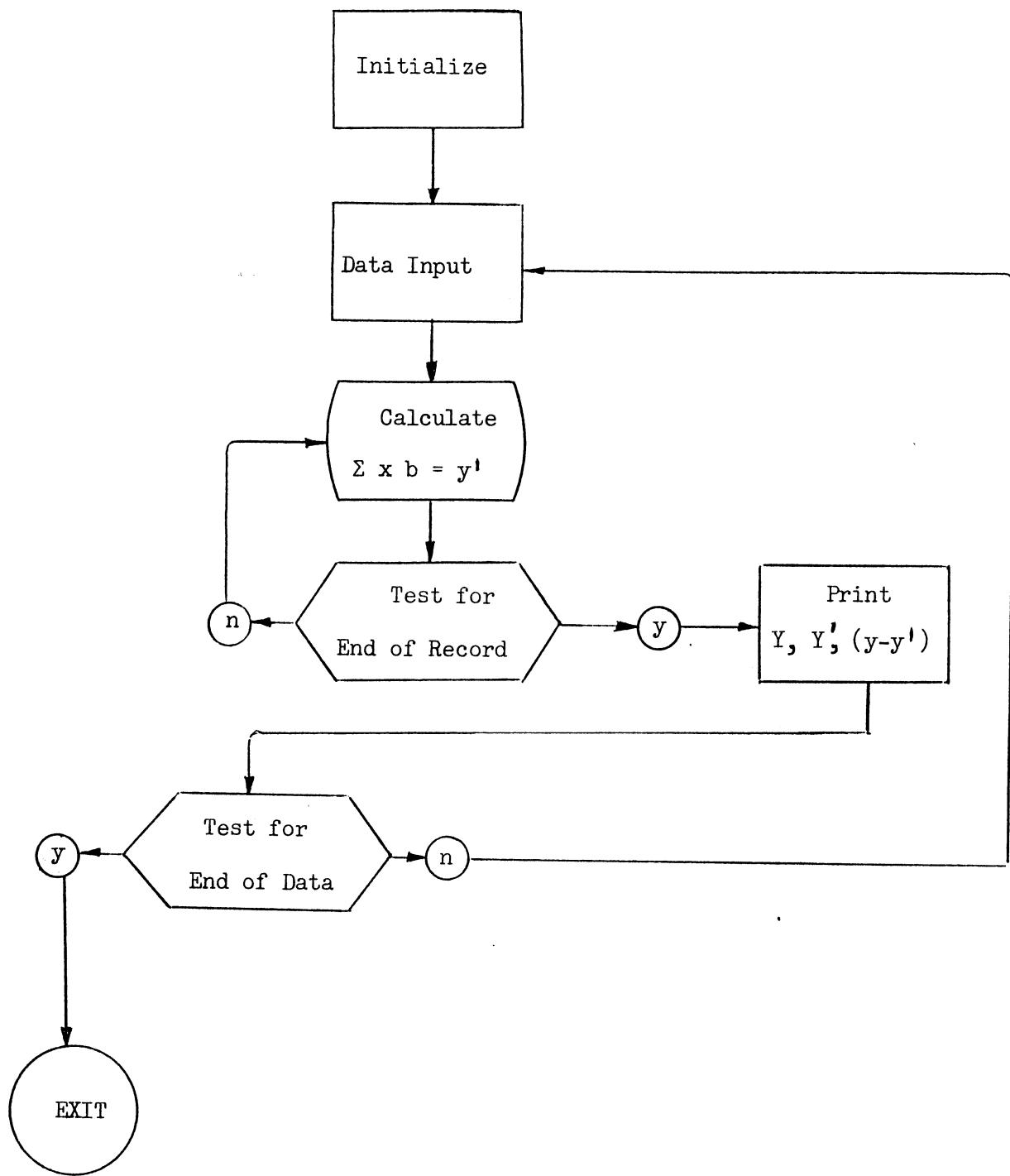
6232 - Two times the data q@q = 29

6233 - n, no. of variables @ q = 29

6234 - N, no. of records @ q = 29

6235 - Lo of the record

6243 - Lo of the coefficients

Calculation of Y^1 and $(y-y^1)$ 

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JOB NO.	PROGRAM NO. F2-129	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 10-6-59			
PROBLEM: Calc. & Print Y, Y' (Y-Y') Fixed Point					TRACK 00		
PROGRAM INPUT CODES	P S T O P	LOCATION	INSTRUCTION		P S T O P	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
	/						
	/ <input checked="" type="checkbox"/>						
	/ 0,0,0	X, B 6 2, 3, 5	/	Lo Record			
	/ 0,1	Y 0 0, 1, 8	/				
	/ 0,2	Y 0 0, 3, 0	/				
	/ 0,3	X, A 6 2, 3, 3	/ <input checked="" type="checkbox"/> n @ 29	no variables			
	/ 0,4	Y 0 0, 3, 1	/	L _f Record			
	/ 0,5	Y 0 0, 5, 3	/				
	/ 0,6	X, B 6 2, 4, 3	/	Lo of coefficients			
	/ 0,7	Y 0 0, 1, 7	/ <input checked="" type="checkbox"/>				
	/ 0,8	B 0 0, 5, 1	/	XZ0300			
	/ 0,9	X, A 6 2, 3, 2	/	Q of printout			
	/ 1,0	Y 0 0, 4, 0	/				
	/ 1,1	X, C 6 2, 6, 0	/ <input checked="" type="checkbox"/> Acc → 0				
	/ 1,2	X, S 6 2, 3, 4	/	N @ 29	Number of records		
	/ 1,3	X, C 6 2, 6, 0	/	ctr			
	/ 1,4	X, C 6 2, 5, 8	/	Σ storage			
	/ 1,5	X, R 0 3, 0, 8	/ <input checked="" type="checkbox"/> read record				
	/ 1,6	X, U 0 3, 0, 0	/				
	/ 1,7	B []	/	b _{xi}			
	/ 1,8	M []	/	x _i			
	/ 1,9	X, A 6 2, 5, 8	/ <input checked="" type="checkbox"/> Σ(b · X) _i				
	/ 2,0	X, C 6 2, 5, 8	/	Σ(b · X) _{i+1}			
	/ 2,1	B 0 0, 1, 7	/	B [] b _{xi}			
	/ 2,2	A 0 0, 3, 6	/	1 @ 29			
	/ 2,3	Y 0 0, 1, 7	/ <input checked="" type="checkbox"/>				
	/ 2,4	B 0 0, 1, 8	/	M [] x _i			
	/ 2,5	A 0 0, 3, 6	/	1 @ 29			
	/ 2,6	Y 0 0, 1, 8	/				
	/ 2,7	E 0 0, 5, 2	/ <input checked="" type="checkbox"/> XZ 6363				
	/ 2,8	S 0 0, 5, 3	/	L _f record			
	/ 2,9	T 0 0, 1, 7	/				
	/ 3,0	B []	/	1 @ q			
	/ 3,1	M []	/ <input checked="" type="checkbox"/> y @ q	y @ 2q			



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PREPARED FOR: LGP-30, RPC-4000 Users' Organization				PAGE OF 2 /2		
JOB NO.	PROGRAM NO. F2-129	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 10-6-59		
PROBLEM: Calc. & Print Y, Y' (Y-Y') Fixed Point				TRACK 00		
PROGRAM INPUT CODES	POSS	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/	X H 6 2 5 7	'	Y		
	0 0 3 2	X S 6 2 5 8	'	Y'	@ Q	
	3 3	X C 6 2 5 9	'	Y-Y'		
	3 4	X P 1 6 0 0	'	cr.		
	3 5	X Z 0 0 0 1	'	delay & 1 @ 29		
	3 6	X B 6 2 5 7	'	Lo print area		
	3 7	X R 0 6 0 5	'	12.1a		
	3 8	X U 0 6 0 0	'			
	3 9	X I Z []	'	NNQQ		
	4 0	X B 6 2 3 5	'	Lo record		
	4 1	Y 0 0 1 8	'			
	4 2	X B 6 2 4 3	'	Lo coeff.		
	4 3	Y 0 0 1 7	'			
	4 4	X Z 0 4 0 0	'	BP 4 after each record		
	4 5	X B 6 2 6 0	'			
	4 6	A 0 0 3 6	'	1 @ 29		
	4 7	T 0 0 1 3	'			
	4 8	X Z 0 8 0 0	'	BP 8	At completion	
	4 9	U []	'	Exit		
	5 0	X Z 0 3 0 0	'	for print code (12.1a)		
	5 1	X Z 0 3 0 0	'	mask		
	5 2	X Z 6 3 6 3	'	L _f Record		
	5 3	X Z 0 0 0 0	'			
	5 4		'			
	5 5		'			
	5 6		'			
	5 7		'			
	5 8		'			
	5 9		'			
	6 0		'			
	6 1		'			
	6 2		'			
	6 3		'			