

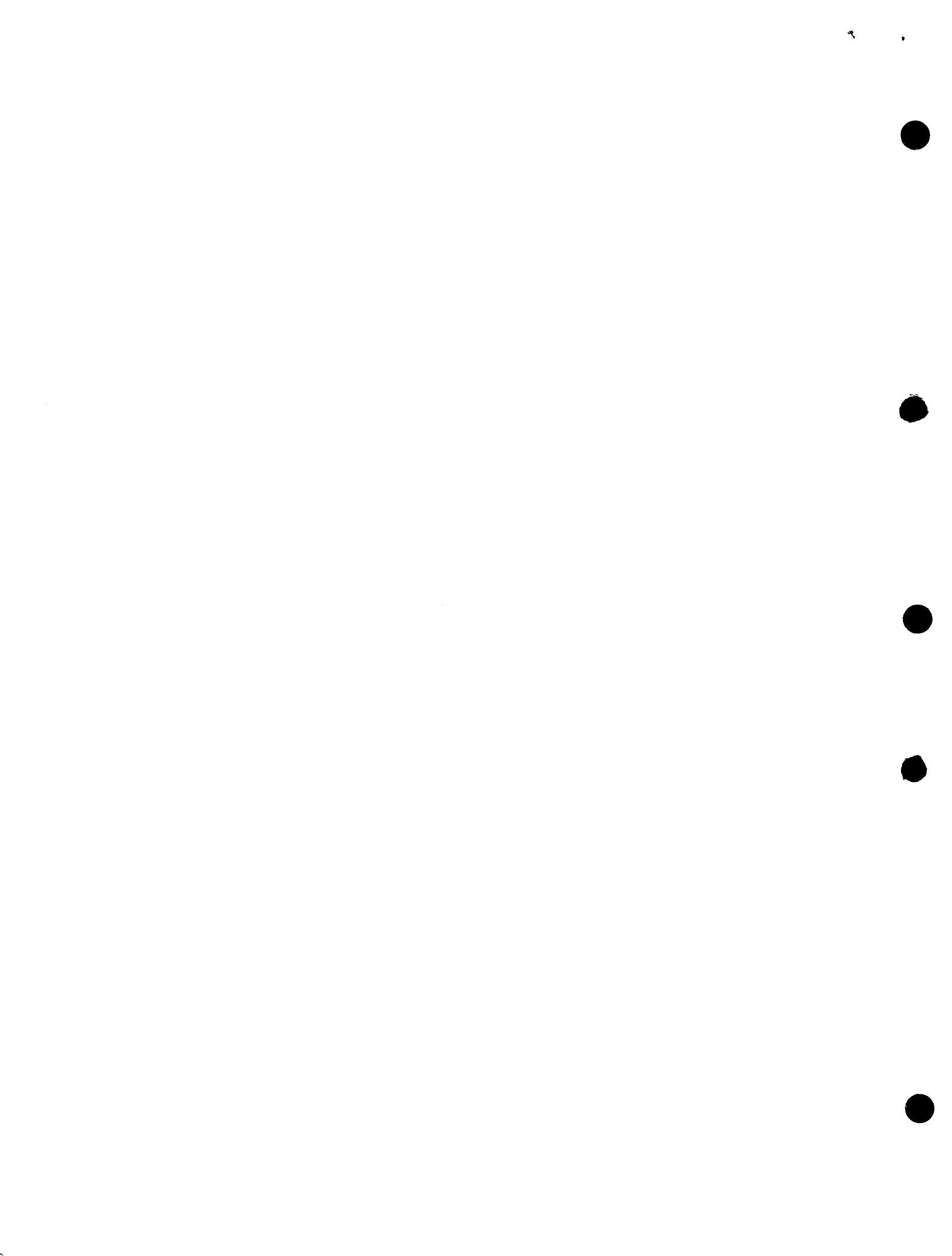
TITLE: Statistical Subroutines
Floating Point Input

AUTHOR: William F. Burggrabe
Compumatrix, Incorporated
Clayton 5, Missouri

DISCLAIMER:

"The authors of this program material, the POOL organization and Royal McBee believe this program to be correct; however, they bear no responsibility, financial or otherwise, for errors resulting from its use. This program is distributed only to individual and installation members of POOL. Further distribution of this manual and accompanying tapes for use by non-members is prohibited".

* * * * * * * * * * * * * * * * *
*
* THIS PROGRAM IS DISTRIBUTED TO *
*
* MEMBERS OF POOL ONLY; DISTRIBUTION *
*
* TO NON MEMBERS OF POOL IS PROHIBITED *
*
* * * * * * * * * * * * * * * * *



COMPUMATIX STATISTICAL SUBROUTINES
(FLOATING POINT INPUT)

I. Storage Allocation

A) Standard Subroutines

<u>Program #</u>	<u>Location</u>	<u>Description</u>
10.4	0000-0263	Program Input
11.2	0300-0563	Data Input (Fixed)
12.1A	0600-0850	Data Output (Fixed)
25.0R	0900-1163	Float - Unfloat
24.0	1200-2163	Floating Point Interpretive
11.6-12.6	2200-2763	Floating Point Input-Output
29.0	2800-2963	Matrix Inversion

B) Statistical Subroutines:

<u>Sample Problem #</u>	<u>Location</u>	<u>Description</u>
1	3000-3215	Floating Point Δ Matrix Prep., Print, Float
2	3219-3263*	Δ Matrix Scale
3	3300-3515	Calculate Means, Standard Deviations and correlation Coefficient Δ Matrix (Print)
4	3516-3606	Convert Δ Rij Matrix to <input type="checkbox"/> Rij Matrix (Modified)

(Statistical Subroutines - Cont'd)

Page 2
F2-130

<u>Sample Problem #</u>	<u>Location</u>	<u>Description</u>
5	3607-3660	Invert <input type="checkbox"/> Rij Matrix and Print
6	3662-4005	Compute and Print: Beta Weights, Regression Coefficients; Partial Correlation Coefficient and Standard Error of the Independent Variables; the Constant Term (B_0) and its' Standard Error; the Sample Multiple Correlation Coefficient and Standard Error of Estimate; the Universe Multiple Correlation Coefficient and Standard Error of Estimate.
4006	4006 Stop	
7	4007-4106	Compute \bar{Y} , \bar{Y}_{cal} ($\bar{Y}-\bar{Y}_{cal}$) and Print (Floating Point)
C) <u>Data and Computational Storage</u>		
<u>Area</u>	<u>For</u>	<u>Required</u>
6200-6231	Standard Deviations	N
4132-4163	Coefficient of Equation	N
4200-6131	Δ Data Matrix and Correlation Coefficient Matrix <input type="checkbox"/> Rij Matrix and Inverse	$N^2 + 2 N + 1$ N
4201-4201+N	Means	N
6132-6163	Scale Factors	(N + 1)
6200-6231	Record	(N + 1)
6232-6263	Temp. and Line Set	----

(Data and Computational Storage - Cont'd)

Page 3
F2-130

<u>Area</u>	<u>For</u>	<u>Required</u>
6300-6363	Temp. for Floating Point, Etc.	-----
* Note:	3215	XU3300 (To skip scaling)
	3215	XU3220 (To do scaling)

3220	XH1200)	Enter Floating Point
3221	XU1200)	
3222	XI0000	Read Scale Factors
3223	XE0000	Exit F. P.
3224	Lo. Matrix Scaling Sub.	

II. Operation:

- A) Load hex tapes A and Ba (See storage allocation A and B for tape contents). Note exception: 10.4 is not on tape A or Ba.
- B) Insert sample problem data tape in the typewriter and depress break points 4 and 8. Start the tape reading via a program input routine (10.0, 10.3 or 10.4). All start fill and transfers are on the tape.
- C) The computer will halt on the stop and transfer instruction (.0003000'). A start compute signal will initiate the computation (or B.P. # 32 could have been depressed).
- D) The program will proceed to the completion of the regression analysis and then stop in location 4006 (XZ0000).
- E) A start compute signal will cause an entry into the subroutine to compute the residuals, (Y-Ycal). The regression equation coefficients are stored correctly by the subroutine that computes them in Floating Point and need not be entered before the first record of the original data is re-read.

III. Format:

- A) Set carriage return stop at 4.
- B) Set tabs at 12, 20, 28, 36, 44, etc.
N + 1 tabs. (8 numbers apart).
- C) For very large problems the automatic C. R. must be used or all spacing tabs in program # 1 and 3 removed (See write ups) and a column type printout used.

- D) Since break points separate every major phase of this group of subroutines, these spaces may be used for exits to heading printing operations or other calculations, without disrupting actual program steps.

IV. General:

- A) The subroutine designates as "No. 2" (Scaling) has not been used in this sample problem since then, in general, special handling would be required in the residual computation.
- B) The subroutines were assembled except for locations 3219-3223 and 4006 by filling the following subroutine Lo on top of the previous subroutine L_F.

FLOATING POINT DATA

COMPUMATIX INC.

SAMPLE PROBLEM STATISTICS SUBROUTINES (FLOATING POINT)

;006233'

xz0003' no. of variables

xz0005' no. of records

xz6200' Lo. of record

xz4200' Lo. of Δ data matrix

xz1200' Lo. of floating point

xz4201' Lo. of means

xz6200' Lo. of standard deviations

xz0000' Lo. of sq. Rij matrix

xz6132' Lo. of scale factors

xz2800' Lo. of matrix inversion (29.0)

xz4132' Lo. of coefficients of regression equation

deprēss break points 4 and 8 for straight thru operation

to the residual computation

.0003000'

data

+006200'1'1'4'1'-0000000''

+006200'1'1'4'3'-0000000''

+006200'1'3'3'2'-0000000''

+006200'1'6'2'5'-0000000''

+006200'1'8'4'-0000000''

F2-130
 Compumatrix Statistical
 Subroutines - Floating Pt.

DATA CONTINUED

N		ΣX_1		ΣX_2		ΣY	
.5000000	01	.1800000	02	.1300000	02	.1500000	02
		ΣX_1^2		$\Sigma X_1 X_2$		$\Sigma X_1 Y$	
		.1100000	03	.2500000	02	.7100000	02
				ΣX_2^2		$\Sigma X_2 Y$	
				.4500000	02	.3200000	02
						ΣY^2	
		\bar{X}_1		\bar{X}_2		\bar{Y}	
.3600000	01	.2600000	01	.3000000	01	.5500000	02
σ_{x_1}		σ_{x_2}		σ_y			
.3006659	01	.1496663	01	.1414213	01		
r_{11}		r_{12}		r_{ly}			
.1000000	01	.9688981-	00	.7996129	00		
		r_{22}		r_{2y}			
		.1000000	01	.6614376-	00		
				r_{yy}			
				.1000000	01		

Inverse of r_{ij} Matrix

.6084443	02	.4759427	02	.1717134-	02		
.4759427	02	.3900739	02	.1225603-	02		
.1717134-	02	.1225603-	02	.6623824	01		
β_{x1}		b_{x1}		$r_{ly}.2$		σ_{bx1}	
.2592361	01	.1219344	01	.8553412	00	.5222230	00
β_{x2}		b_{x2}		$r_{2y}.2$		σ_{bx2}	
.1850295	01	.1748364	01	.7624686	00	.1049098	01
		b_0				σ_{b0}	
		.5935385-	01			.3885488	00
R		σ_{EST}		\hat{R}		$\hat{\sigma}_{EST}$	
.9214280	00	.5494909	00	.8354996	00	.8688215	00

F2-130
Compumatrix Statistical
Subroutines - Floating Pt.

DATA - CONTINUED

Data repeated for residual computation

+006200'1'1'4'1'-0000000'

.1000000 01 .1058073 01 .5807304- 01-

+006200'1'1'4'3'-0000000'

.3000000 01 .2277417 01 .7225832 00

+006200'1'3'3'2'-0000000'

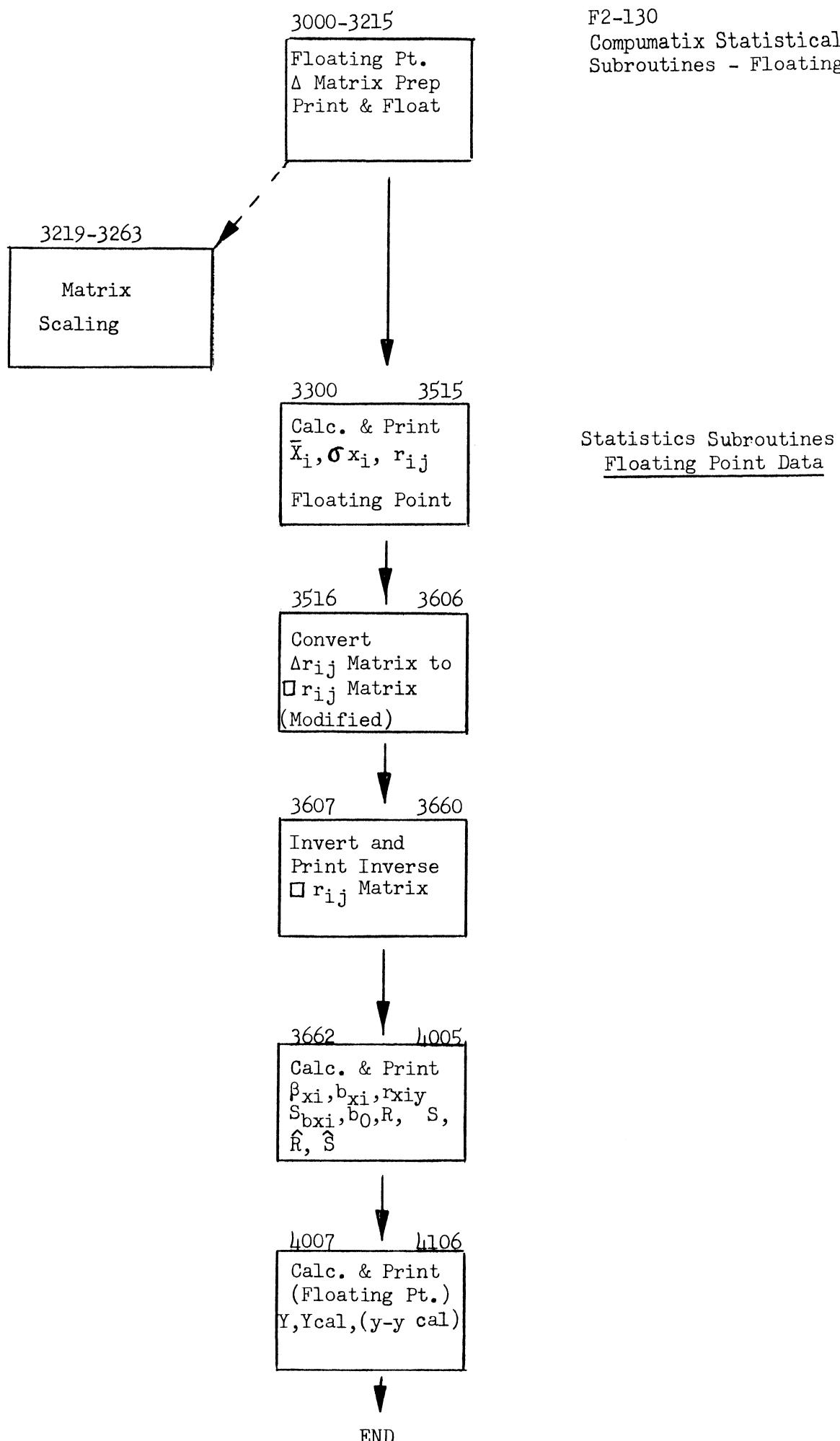
.2000000 01 .2967740 01 .9677398- 00

+006200'1'6'2'5'-0000000'

.5000000 01 .4877406 01 .1225934 00

+006200'1'8'1'4'-0000000'

.4000000 01 .3819365 01 .1806345 00



TITLE: Least Squares Floating Point Triangular Matrix Preparation

AUTHOR: William F. Burggrabe
Compumatrix, Incorporated

DATE: August 28, 1959

PURPOSE: Given N records of n variables of the form 1, X_1 , X_2 , ... X_n in floating point this subroutine will prepare the upper triangle of the least squares matrix. The matrix rows are stored sequentially in the following format:

$N, \Sigma X_1, \Sigma X_2, \dots \Sigma X_n; \Sigma X_1^2, \Sigma X_1 X_2 \dots \Sigma X_1 X_n;$
 $\Sigma X_2^2, \dots \Sigma X_2 X_n; \dots; \Sigma X_n^2$

At the completion of the processing for N records, the matrix may be optionally printed out.

RESTRICTIONS:

- 1) Normal restrictions of 24.0, 11.6 - 12.6
- 2) No limit to the number of records provided no overflow is encountered; the number of variables is limited only by available machine storage.

Required computational storage:

Data L_O to $L_O + n + 1$
Matrix L_O to $L_O + \frac{(n + 1)(n + 2)}{2}$

- 3) The following information must be supplied:

6233 n
6234 N
6235 L_O Record
6236 L_O Δ Matrix
6237 L_O Floating Point System

- 4) Data Format - see input
- 5) Print Out - see output
- 6) The records are not permanently stored.

GENERAL INFORMATION ON METHOD:

Since little mathematical description need be given, a description of the program sequence will be outlined here.

1) Initialization

Clear the matrix storage area to zero

2) Matrix Preparation

N-records, n variables

3) Optional print out of floating point matrix.
(Transfer control up)

A break point stop separates each phase of the operation, as well as the processing of each record.

CODING INFORMATION

A) Storage: Subroutine 2 tracks 16 sectors

External storage as noted under restriction 3 and the following:

Computed	6258 Ctr 6259 Ctr 6260 Temp (6261 n + 1 @ 29 (6262 n + 2 @ 29 (6363 <u>(n+1) (n+2)</u> @ 29 <hr style="width: 100%; border: 0; border-top: 1px solid black; margin-top: 5px;"/>
----------	---

Data L_o to $L_o + n + 1$

Matrix L_o to $L_o + \frac{(n+1)(N+2)}{2}$

B) Linkage and calling sequence: Since this is one of a group of statistical subroutines, location 6233 to 6263 have been reserved for initialization information and no calling sequence is required.

Linkage R Lo + 215
U Lo

C) Input : As described under Restriction 3 and:

Data format

First record.

+ PP Data Lo' 1' X1' X2'Xn' -00000000'

Following records.

+ PP Data Lo + 1 X₁' X₂' ... X_n' -0000000'

The leading "one" may be present in all records if desired.
In this case all records have the same code word as the first record.

- D) Output: The computed matrix is stored sequentially beginning in the specified location. It may be printed out in floating point in the following format:

N	ΣX_1	ΣX_2	...	ΣX_n
tab	ΣX_1^2	ΣX_2	...	ΣX_n
tab	tab	ΣX_2^2	...	ΣX_n
.				
.				
.				
tab	tab	etc. ...		ΣX_n^2

The tabs may be suppressed by changing Lo + 206 to T (Lo+207) or U(Lo + 47)

Note: Transfer Control down exits from Print Routine

- E) Location of constants:

L ₀ + 111	1 @ 29
+ 112	3wwj (Mask)
+ 113	1 @ 3
+ 119	1 @ 29
+ 121	1 @ 29
+ 203	0 and delay

- F) The actual matrix preparation time is approximately:

$$\frac{(n+1)(N+2)}{2} (1.30) + .031(n+1) \quad N = \text{seconds compute time}$$

+ Data read in time

- G) Program stops:

Lo + 39 BP 4 after initialization
Lo + 42 BP 8 after last record of matrix prep.
Lo + 159 BP 4 after each record, except last
Lo + 214 BP 4 after printing matrix

FLOATING POINT MATRIX PREPARATION

Operating Procedure

Prepare the data tape as per instructions under input and fill the required storage locations 6233-6237 as under restriction 3. Insert the data tape in reader and transfer to the routine Lo or use a main program with the required linkage.

After initialization a stop (BP 4) in Lo + 39 will occur. Depression of start compute lever will cause the first record to be read, the necessary computation for that record and an exit to (BP 4) in Lo + 159 prior to reading the next record. (This feature allows for machine stoppage on large problems)

After all records have been processed, the program will halt on BP 8 in Lo + 42. If it is desired to eliminate the floating point matrix print out, depress transfer control before continuing the program. This causes a transfer to Lo + 214 (BP 4) the end of the print sequence. (NOTE: Depression of the transfer control switch during the printing operation will cause an exit from the print routine at the end of the particular line being printed).

A start compute signal will transfer control back to the main program.

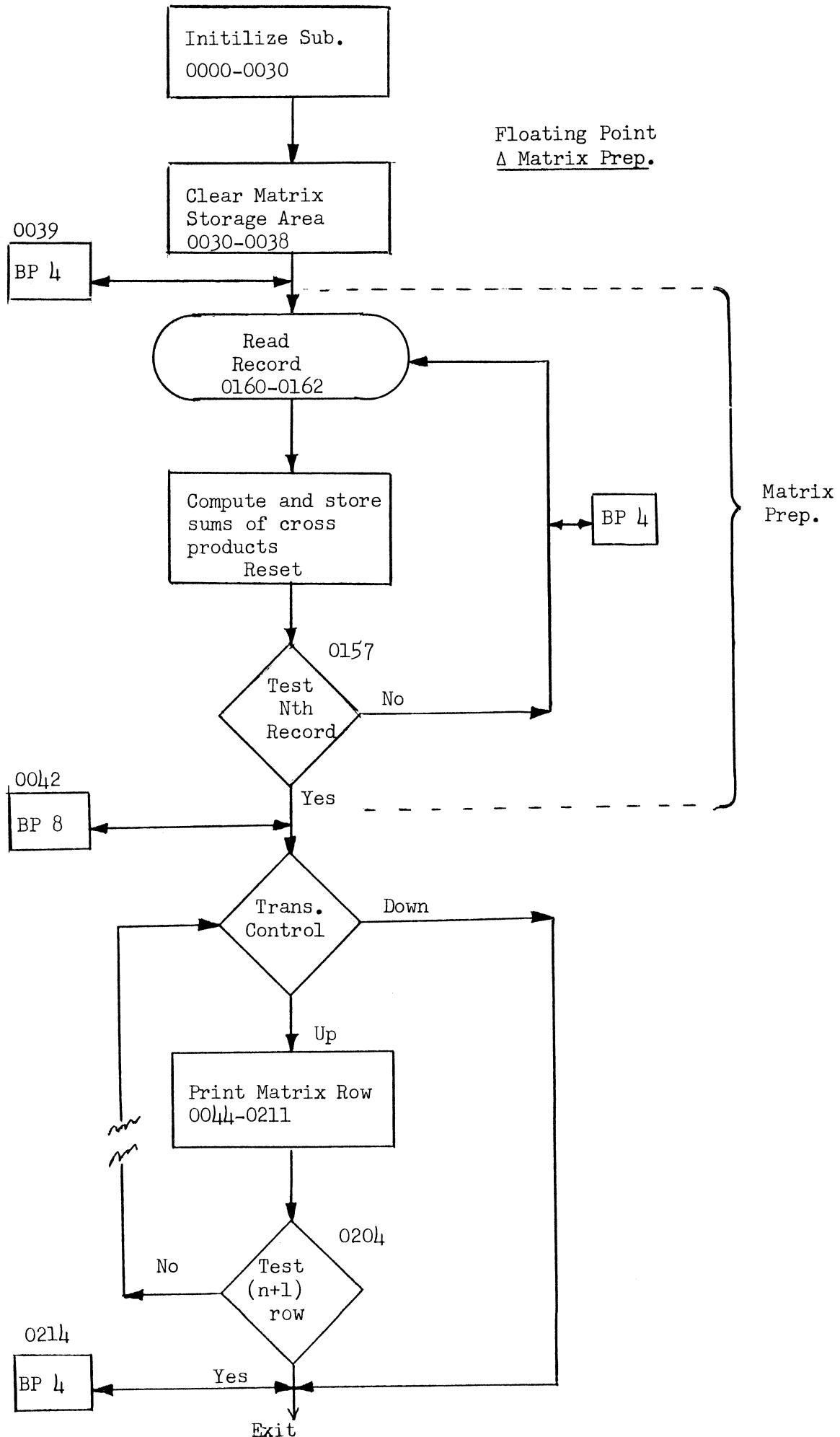
SAMPLE PROBLEM FLOATING POINT Δ MATRIX PREP.

;006233'xz0003' no. variables }
;006234'xz0005' no. records }
;006235'xz6200' Lo. record }
;006236'xz5000' Lo. Δ matrix }
;006237'xzl200' Lo. floating point }

.0003000' transfer to matrix prep. data follows

+006200'1'1'4'1'-0000000' }
+006200'1'1'4'3'-0000000' }
+006200'1'3'3'2'-0000000' } Data
+006200'1'6'2'5'-0000000' }
+006200'1'8'1'4'-0000000' }

.5000000	01	.1800000	02	.1300000	02	.1500000	02
		.1100000	03	.2500000	02	.7100000	02
				.4500000	02	.3200000	02
						.5500000	02



LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE 1 / 5	
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 4-29-59		
PROBLEM: Floating Point Δ Matrix Prep					TRACK 00	
PROGRAM INPUT CODES	PO S	LOCATION	INSTRUCTION	STOP S	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/	<input checked="" type="checkbox"/>				
		0 0 0 0 0	X B 6 2 3 3	/	n	
		0 1	A 0 1 1 1	/	1 @ 29	
		0 2	X H 6 2 6 1	/	(n+1) @ 29	
		0 3	A 0 1 1 1	/	<input checked="" type="checkbox"/> 1 @ 29	
		0 4	X H 6 2 6 2	/	(n+2) @ 29	
		0 5	X N 6 2 6 1	/	(n+1) @ 29	$\frac{(n+1)(n+2)}{(n+1)(n+2)}$ @ 27
		0 6	M 0 1 1 3	/	<input checked="" type="checkbox"/> 1 @ 3	$\frac{(n+1)(n+2)}{(n+1)(n+2)}$ @ 29
		0 7	X C 6 2 6 3	/	<input checked="" type="checkbox"/> $\frac{(n+1)(n+2)}{2}$ @ 29	
		0 8	X B 6 2 3 5	/	Lo Record	
		0 9	Y 0 1 0 3	/		
		1 0	Y 0 1 0 4	/	Init. Matrix Prep	
		1 1	Y 0 1 1 0	/	<input checked="" type="checkbox"/>	
		1 2	X A 6 2 6 1	/		
		1 3	Y 0 1 1 4	/		
		1 4	X B 6 2 3 6	/	Lo Δ Matrix	
		1 5	Y 0 1 0 5	/	<input checked="" type="checkbox"/>	
		1 6	Y 0 1 0 6	/	Matrix Prep	
		1 7	Y 0 1 0 0	/		
		1 8	Y 0 0 3 2	/	Clear	
		1 9	Y 0 0 4 9	/	<input checked="" type="checkbox"/> Print $\frac{(n+1)(n+2)}{2}$ @ 29	
		2 0	X A 6 2 6 3	/	$\frac{(n+1)(n+2)}{2}$ @ 29	
		2 1	X C 6 2 6 0	/	Matrix L _f +1	
		2 2	X S 6 2 3 4	/	No records @ 29	
		2 3	C 0 1 2 0	/	<input checked="" type="checkbox"/> Matrix Prep Ctr	
		2 4	X B 6 2 3 7	/	Lo Floating Point	
		2 5	Y 0 1 0 1	/	} arith	
		2 6	Y 0 1 0 2	/		
		2 7	Y 0 1 6 0	/	<input checked="" type="checkbox"/> data in	
		2 8	Y 0 1 6 1	/		
		2 9	Y 0 0 4 7	/	} Print	
		3 0	Y 0 0 4 8	/		
		3 1	B 0 2 0 3	/	<input checked="" type="checkbox"/> o	

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL				PAGE OF 2 / 5
JOB NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 4-29-59
PROBLEM: Floating Point Δ Matrix Prep				TRACK 00
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION OPERATION ADDRESS	STOP CONTENTS OF ADDRESS NOTES
	/			
	/ <input checked="" type="checkbox"/>			
	0 0 3 2	1 1	C []	/ Σ area
	1 3 1 3	1 1	B 0 0 3 2	/
	1 3 1 4	1 1	A 0 1 1 1	/ 1 @ 29
	1 3 1 5	1 1	Y 0 0 3 2	/ <input checked="" type="checkbox"/>
	1 3 1 6	1 1	E 0 1 1 2	/
	1 3 1 7	1 1	X S 6 2 6 0	/
	1 3 1 8	1 1	T 0 0 3 1	/
	1 3 1 9	1 1	X Z 0 4 0 0	/ <input checked="" type="checkbox"/>
	1 4 1 0	1 1	R 0 1 2 2	/ } Matrix Prep
	1 4 1 1	1 1	U 0 1 6 0	/ } Linkage
	1 4 1 2	1 1	X Z 0 8 0 0	/
	1 4 1 3	8 0 0 T	0 2 1 4	/ <input checked="" type="checkbox"/> Skip matrix Print
	1 4 1 4	1 1	X B 6 2 6 1	/ n + 1 @ 29
	1 4 1 5	1 1	X C 6 2 5 9	/ ctr 1 → (n+1)
	1 4 1 6	1 1	X C 6 2 5 8	/ ctr 2 → 0
	1 4 1 7	1 1	R []	/ <input checked="" type="checkbox"/> F.P. linkage
	1 4 1 8	1 1	U []	/
	1 4 1 9	1 1	B []	/ n Σ X _i X _j _n
	1 5 1 0	1 1	X P 0 0 0 0	/ Print Σ X _i X _j
	1 5 1 1	1 1	X E 0 0 0 0	/ <input checked="" type="checkbox"/> Exit F.P.
	1 5 1 2	1 1	B 0 0 4 9	/
	1 5 1 3	1 1	A 0 1 1 1	/ 1 @ 29
	1 5 1 4	1 1	Y 0 0 4 9	/
	1 5 1 5	1 1	X B 6 2 5 8	/ <input checked="" type="checkbox"/> ctr 2
	1 5 1 6	1 1	A 0 1 1 1	/ 1 @ 29
	1 5 1 7	1 1	X H 6 2 5 8	/
	1 5 1 8	1 1	X S 6 2 5 9	/ ctr 1
	1 5 1 9	1 1	T 0 0 4 7	/ <input checked="" type="checkbox"/>
	1 6 1 0	1 1	X P 1 6 0 0	/ cr. end of line
	1 6 1 1	1 1	X C 6 2 5 8	/ ctr 2 → 0
	1 6 1 2	1 1	X B 6 2 5 9	/ ctr 1 (Line number)
	1 6 1 3	1 1	U 0 2 0 0	/ <input checked="" type="checkbox"/>



LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 3 / 5	
JOB NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 4-29-59		
PROBLEM: Floating Point Δ Matrix Prep					TRACK 01	
PROGRAM INPUT CODES	PO STO	LOCATION	INSTRUCTION	PO STO	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/	<input checked="" type="checkbox"/>				
		0,1,0,0	[]	/	Lo Δ Matrix	
		1 0 1	R []	/		
		1 0 2	U []	/		
		1 0 3	P []	/	<input checked="" type="checkbox"/> X ₁	
		1 0 4	M []	/	X _k $\sum_{j=1}^k X_i X_j$	
		1 0 5	A []	/	X _{k+1} $\sum_{j=1}^{k+1} X_i X_j$	
		1 0 6	H []	/	X _{i,j}	
		1 0 7	X E 0 0 0 0	/	<input checked="" type="checkbox"/>	
		1 0 8	B 0 1 0 5	/		
		1 0 9	U 0 1 2 5	/		
, 0 0 0 0 0 0 0 8	/	1 1 0	[]	/	Data Lo	
		1 1 1		/	<input checked="" type="checkbox"/> 1 @ 29	
		1 1 2	3 w w j	/	Mask	
		1 1 3	1 0 0 0 0 0 0 0	/	1 @ 3	
		1 1 4	[]	/	Data L _f + 1	
		1 1 5	8 1 0 0 0	/	<input checked="" type="checkbox"/> cr in hex	
		1 1 6		/	delay	
		1 1 7	8 1 0 0 0	/	(Hex) cr in hex	
		1 1 8	U 0 1 2 1	/	Exit Path	
, 0 0 0 0 0 0 6	/	1 1 9		/	<input checked="" type="checkbox"/> 1 @ 29	
		1 2 0		/	-n @ 29	
		1 2 1		/	1 @ 29 & delay	
		1 2 2	U []	/	Exit Matrix Prep.	
		1 2 3		/	<input checked="" type="checkbox"/>	
		1 2 4		/	1 @ 29	
		1 2 5	A 0 1 1 1	/	1 @ 29	
		1 2 6	Y 0 1 0 5	/		
		1 2 7	Y 0 1 0 6	/	<input checked="" type="checkbox"/>	
		1 2 8	U 0 1 3 1	/		
		1 2 9		/		
		1 3 0		/		
		3 1	B 0 1 0 3	/	<input checked="" type="checkbox"/>	

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL				PAGE OF 4 / 5		
JOB NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 4-29-59		
PROBLEM: Floating Point Δ Matrix Prep				TRACK 01		
PROGRAM INPUT CODES	P STOP	LOCATION	INSTRUCTION	P STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/	X				
		0 1 3 2	A 0 1 1 1	/	1 @ 29	
		3 3	E 0 1 1 2	/	3wwj mask	
		3 4	Y 0 1 0 3	/		
		3 5	S 0 1 1 4	X	Data L _f +1	
		3 6	T 0 1 0 1	/		
		3 7	U 0 1 4 5	/		
		3 8	Y 0 1 0 3	/		
		3 9	Y 0 1 0 4	X		
		4 0	E 0 1 1 2	/	3wwj mask	
		4 1	U 0 1 4 2	/		
		4 2	S 0 1 1 4	/		
		4 3	T 0 1 0 1	X		
		4 4	U 0 1 4 8	/		
		4 5	B 0 1 2 4	/	1 @ 29	
		4 6	A 0 1 0 4	/		
		4 7	U 0 1 3 8	X		
		4 8	B 0 1 0 0	/	Lo Δ Matrix	
		4 9	Y 0 1 0 6	/		
		5 0	Y 0 1 0 5	/		
		5 1	B 0 1 1 0	X	Lo Data	
		5 2	Y 0 1 0 3	/	Lo Data	
		5 3	Y 0 1 0 4	/		
		5 4	B 0 1 1 9	/		
		5 5	A 0 1 2 0	X	-N @ 29	
		5 6	H 0 1 2 0	/		
		5 7	T 0 1 5 9	/		
		5 8	U 0 1 1 5	/	Exit Path →	
		5 9	X Z 0 4 0 0	X	BP 4 stop after each record	
		6 0	R []	/	← U here	
		6 1	U []	/	for Matrix prep portion	
		6 2	X I 0 0 0 0	/		
		6 3	U 0 1 0 3	X	Input data	



CARRIAGE RETURN

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 5 / 5
JOB NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 4-29-59	
PROBLEM: Floating Point Δ Matrix Prep					TRACK 0 2
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS NOTES
			OPERATION ADDRESS		
	/				
	/ <input checked="" type="checkbox"/>				
	0 2 0 0		S 0 1 1 1	/	1 @ 29
	1 0 1		X H 6 2 5 9	/	
	1 0 2		S 0 1 1 1	/	1 @ 29
	1 0 3		X Z 0 0 0 0	/ <input checked="" type="checkbox"/>	delay & 0
	1 0 4	8 0 0 T	9 2 1 2	/	→ Exit Path finished last line
	1 0 5	X S	6 2 3 3	/	n @ 29 (How many tabs)
	1 0 6		T 9 2 0 8	/	
	1 0 7		U 0 0 1 7	/ <input checked="" type="checkbox"/>	Print next line of numbers
	1 0 8		X P 2 4 0 0	/	tab
	1 0 9		X Z 9 0 0 0	/	delay
	1 1 0		A 9 1 1 1	/	1 @ 29
	1 1 1		U 9 2 0 6	/ <input checked="" type="checkbox"/>	
	1 1 2		X P 1 6 0 0	/	cr.
	1 1 3		X Z 9 0 0 0	/	
	1 1 4		X Z 9 4 0 0	/	B.P. 4 stop after printing
	1 1 5		U []	/ <input checked="" type="checkbox"/>	
	1 1 6			/	
	1 1 7			/	
	1 1 8			/	
	1 1 9			/ <input checked="" type="checkbox"/>	
	1 2 0			/	
	1 2 1			/	
	1 2 2			/	
	1 2 3			/ <input checked="" type="checkbox"/>	
	1 2 4			/	
	1 2 5			/	
	1 2 6			/	
	1 2 7			/ <input checked="" type="checkbox"/>	
	1 2 8			/	
	1 2 9			/	
	1 3 0			/ <input checked="" type="checkbox"/>	
	1 3 1			/ <input checked="" type="checkbox"/>	



CARRIAGE RETURN



CONDITIONAL STOP CODE

TITLE: Triangular Matrix Scaling

AUTHOR: William F. Burggrabe
Compumatrix, Incorporated

DATE: September 4, 1959

PURPOSE: Given a matrix in floating point of the form ...

$$\begin{array}{cccccc} N & \Sigma \frac{x_1}{c_1} & \Sigma \frac{x_2}{c_2} & \dots & \Sigma \frac{x_n}{c_n} \\ & \Sigma \left(\frac{x_1}{c_1} \right)^2 & \Sigma \frac{x_1}{c_1} \times \frac{x_2}{c_2} & \dots & \Sigma \frac{x_1}{c_1} \times \frac{x_n}{c_n} \\ & & & \cdot & \\ & & & \cdot & \\ & & & \Sigma \left(\frac{x_n}{c_n} \right)^2 & \end{array}$$

And scale factors l , c_1 , c_2 ... c_n compute the matrix.

$$\begin{array}{cccccc} N & \Sigma x_1 & \Sigma x_2 & \Sigma x_3 & \dots & \Sigma x_n \\ & \Sigma x_1^2 & \Sigma x_1 x_2 & \dots & \Sigma x_1 x_n \\ & & & \cdot & \\ & & & \cdot & \\ & & & \cdot & \\ & & & \Sigma x_n^2 & \end{array}$$

RESTRICTIONS:

- 1) The following locations must contain:

6236 Lo matrix
6237 Lo floating point 24.0
6241 Lo scale factors
6261 (n+1) @ 29 - Matrix order

- 2) The scale factors in floating point must be stored in the same order as the matrix components.
3) Normal Limitations of 24.0, 11.6 - 12.6.
4) All scale factors must be stored. (i.e.) Where a scale factor is unity it must be stored

$$(1 \times 1 \times N = N, 1 \times C_1 \times \frac{X_1}{C_1} = X_1, \text{ etc.})$$

CODING INFORMATION:

- A) Subroutine storage - 41 sectors

External storage	6236	Lo Δ Matrix
	6237	Lo Floating Point
	6241	Lo scale factors
	6260	Temp storage
	6261	(n+1) @ 29*

- B) Linkage

R Lo + 40
U Lo

- C) Input - the following must be stored in memory

- 1) Δ Matrix in floating point
- 2) Scale factors in floating point

- D) Output Scaled Δ matrix. Stored in the same location as unscaled matrix.

- E) Constants

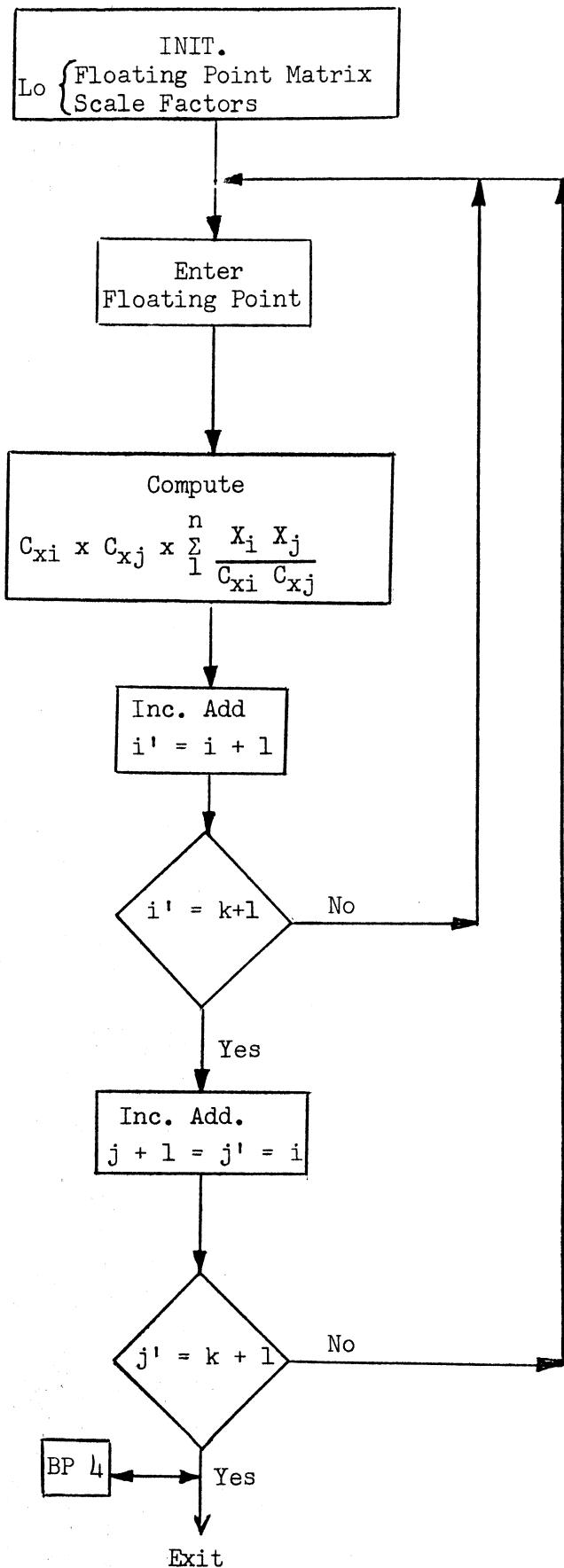
Lo + 30 XZ6363 Mask
Lo + 31 1 @ 29

- F) Timing (n+1)(n+2) x .65 sec.

* From CI Δ matrix prep. routines.

Δ

MATRIX SCALING



PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL						PAGE OF 1 / 2
JOB NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe		PROGRAM CHECKED BY: POOL Review		DATE 4-9-59
PROBLEM: Matrix Scale						TRACK 00
PROGRAM INPUT CODES	STO	LOCATION	INSTRUCTION OPERATION	ADDRESS	STO	CONTENTS OF ADDRESS
						NOTES
	/					
	/	X				
	0 0 0 0	X B	6 2 3 7	/		Lo F. P.
	0 1	Y	0 0 1 1	/		
	0 2	Y	0 0 1 2	/		
	0 3	X B	6 2 3 6	/	X	Lo Matrix
	0 4	Y	0 0 1 3	/		
	0 5	Y	0 0 1 7	/		
	0 6	X B	6 2 4 1	/		Lo Scale Factors
	0 7	Y	0 0 1 4	/	X	
	0 8	Y	0 0 1 6	/		
	0 9	X A	6 2 6 1	/		(n+1) @ 29 → L _f +1 (Scale Factors)
	1 0	X Y	6 2 6 0	/		
	1 1	R	[]	/	X	F.P. Linkage
	1 2	U	[]	/		
	1 3	P	[]	/		$\Sigma X_i X_j$
	1 4	M	[]	/		C X _i
	1 5	X U	0 0 0 0	/	X	Acc → Mult.
	1 6	M	[]	/		C X _i
	1 7	H	[]	/		C X _i C X _j $\Sigma X_i X_j$
	1 8	X E	0 0 0 0	/		Exit F.P.
	1 9	B	0 0 1 3	/	X	Add of $\Sigma X_i X_j$
	2 0	A	0 0 3 1	/		1 @ 29
	2 1	Y	0 0 1 3	/		
	2 2	Y	0 0 1 7	/		
	2 3	B	0 0 1 4	/	X	Add. of C X _i
	2 4	A	0 0 3 1	/		1 @ 29
	2 5	Y	0 0 1 4	/		
	2 6	E	0 0 3 0	/		Mask
	2 7	X S	6 2 6 0	/	X	L _f +1 of C X's
	2 8	T	0 0 1 1	/		Loop
	2 9	U	0 0 3 2	/		
	3 0	X Z	6 3 6 3	/		Mask
	3 1	X Z	0 0 0 1	/	X	1 @ 29



CARRIAGE RETURN

/ = CONDITIONAL STOP CODE

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 2 / 2		
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 4-9-59			
PROBLEM: Matrix Scale					TRACK 00		
PROGRAM INPUT CODES	STR	LOCATION	INSTRUCTION		STR	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
		1					
		1	X				
		0 0 3 2	B	0 0 1 6	'		
		1 3 3	A	0 0 3 1	'	1 @ 29	
		1 3 4	Y	0 0 1 4	'		
		1 3 5	Y	0 0 1 6	'	X	
		1 3 6	E	0 0 3 0	'		
		1 3 7	X S	6 2 6 0	'		
		1 3 8	T	0 0 1 1	'	loop	
		1 3 9	X Z	0 4 0 0	'	X	BP 4 stop after scaling
		1 4 0	U	[]	'		
		1 4 1			'		
		1 4 2			'		
		1 4 3			'	X	
		1 4 4			'		
		1 4 5			'		
		1 4 6			'	X	
		1 4 7			'		
		1 4 8			'		
		1 4 9			'		
		1 5 0			'		
		1 5 1			'	X	
		1 5 2			'		
		1 5 3			'		
		1 5 4			'		
		1 5 5			'	X	
		1 5 6			'		
		1 5 7			'		
		1 5 8			'		
		1 5 9			'	X	
		1 6 0			'		
		1 6 1			'		
		1 6 2			'		
		1 6 3			'	X	

TITLE: Calculation of means, standard deviations and correlation coefficient triangular matrix

AUTHOR: William F. Burggrabe, Jr.
Compumatrix, Incorporated

DATE: September 23, 1959

PURPOSE: Given a floating point Δ matrix as prepared by either the fixed or floating point Δ matrix preparation subroutine, compute the means, standard deviations and the all simple correlation coefficients.

n = Number variables

N = Number records

The Rij matrix replaces all cross product terms in the original matrix. The means and standard deviations (n values each) will be stored in the correct order starting in the Lo specified. Each value is printed out in normal floating point form as computed. (See sample problem).

RESTRICTIONS:

- 1) Normal restrictions of 24.0, 11.6 - 12.6
- 2) Required computational storage

mean Lo thru Lo + (n-1)

σ_x Lo thru Lo + (n-1)

Δ Data matrix Lo thru Lo + $\frac{(n+1)(n+2)}{2} - 1$

Δ Rij matrix replaces all but first row of Δ data matrix

- 3) The following information must be supplied:

Location 6233	n @ 29
6236	Lo Δ data matrix
6237	Lo floating point
6238	Lo means
6239	Lo standard deviations

6258)

6259) Temp. storage area

6260)

6261 n + 1 @ 29*

* Supplied by Compumatrix, Inc. Δ Matrix Prep. Progs.

- 4) Output: 24.0 - 12.6 format

GENERAL INFORMATION ON METHOD:

The equations used are:

$$1) \bar{x}_i = \frac{\sum x_i}{N}$$

- 2) Standard deviation

$$\sigma_{x_i} = \sqrt{\frac{\sum x_i^2}{N} - (\bar{x})^2}$$

- 3) Correlation coefficient

$$R_{ij} = \frac{\frac{\sum x_i x_j}{N} - \bar{x}_i \bar{x}_j}{\sigma_{x_i} \sigma_{x_j}}$$

CODING INFORMATION:

- A) Storage - subroutine 2 tracks and 17 sectors

Calculated storage as described above under "restrictions" 2 and 3

- B) No calling sequence required.

Linkage (R Lo + 216
 (U Lo)

- C) Input: None

- D) Output: Format of 24.0 - 12.6

All answers are printed as computed. The correct number of tabs preceeds the printing of each diagonal element of rij matrix (see sample problem). The tabs may be eliminated by changing t[0209] in 0207 to u[0208] or u0127.

- E) Constants 0024 l @ 29
 0201 XZ6363 mask

and areas mentioned under Restriction (3).

F) Timing: The approximate times including printing are:

Means: 3 n sec.

Standard deviations: 4 n sec.

r_{ij} matrix: $n(n+1)$ x 2.25 sec.

Where n is the total number of variables.

G) Program stops:

0051 Breakpoint 8 \bar{x}_i calculations complete

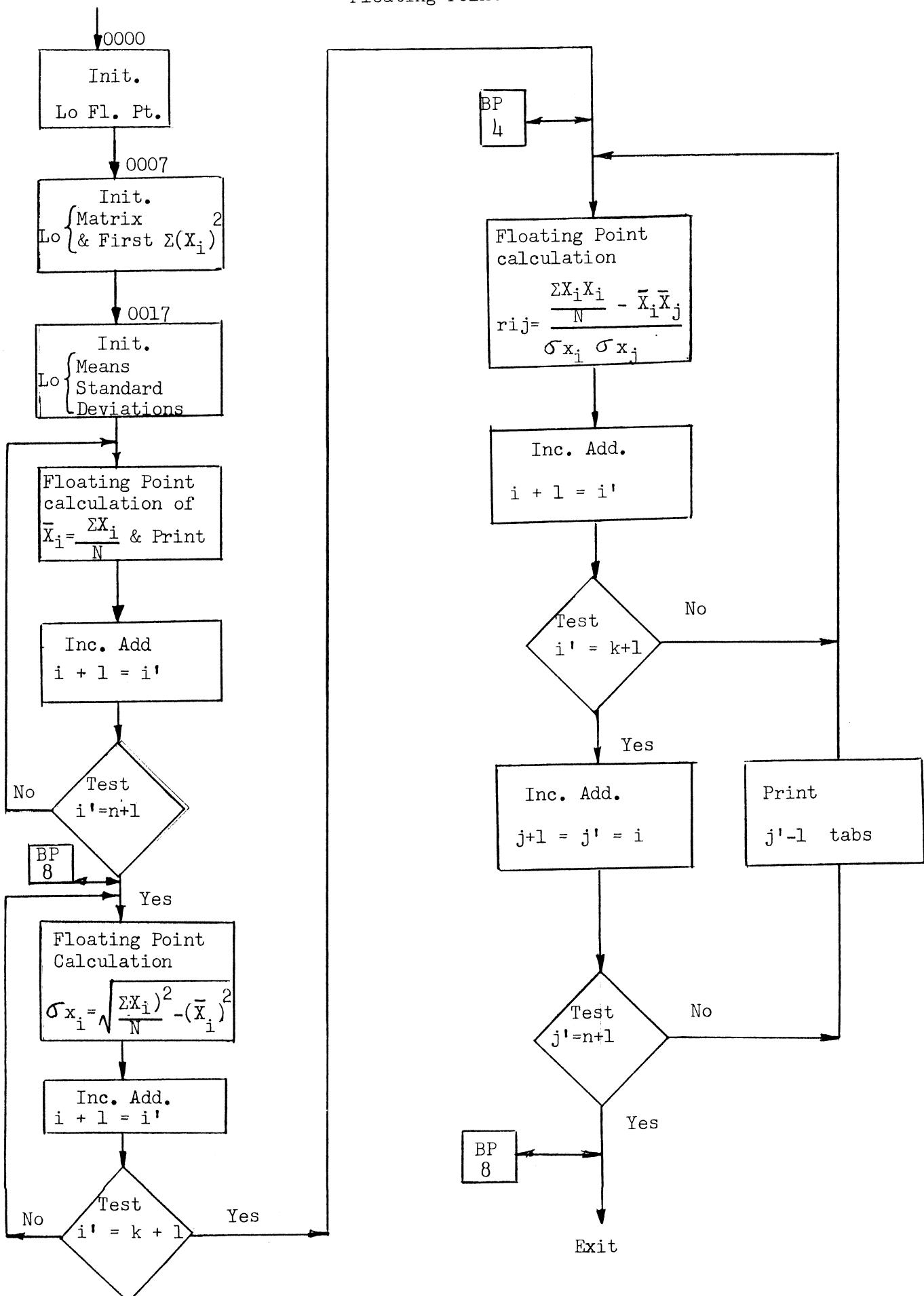
0022 Breakpoint 4 σ_{x_i} calculation complete

0215 Breakpoint 8 r_{ij} calculation complete

Flow Diagram
Calculation of Means, Standard Deviations and
Correlation Coefficient Triangular Matrix
Floating Point

POOL Prog. no. F2-130

3



PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL				PAGE OF 1 / 5
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 4-20-59
PROBLEM: Given: Δ Matrix: Compute & Print \bar{X}_i , σ_{x_i} , R_{ij} Matrix (F.P.)				TRACK 00
PROGRAM INPUT CODES	STO STO	LOCATION	INSTRUCTION OPERATION ADDRESS	STO STO CONTENTS OF ADDRESS
				NOTES
	/			
	/ <input checked="" type="checkbox"/>			
		9 0 0 0	X B 6 2 3 7	/ Lo Floating Point
		1 0 1	Y 0 0 3 3	/ mean } sub
		1 0 2	Y 0 0 3 4	/ mean } sub
		1 0 3	Y 0 0 5 5	/ <input checked="" type="checkbox"/>
		1 0 4	Y 0 0 5 6	/
		1 0 5	Y 0 1 2 7	/ rij } sub
		1 0 6	Y 0 1 2 8	/ rij } sub
		1 0 7	X B 6 2 3 6	/ <input checked="" type="checkbox"/> Lo Δ Matrix
		1 0 8	Y 0 0 3 6	/ mean }
		1 0 9	Y 0 0 6 1	/ σ } Lo of N
		1 1 0	Y 0 1 3 3	/ rij
		1 1 1	A 0 0 2 4	/ <input checked="" type="checkbox"/> 1 @ 29
		1 1 2	Y 0 0 3 5	/ Lo first $\sum(X_i)$ (For mean)
		1 1 3	X A 6 2 3 3	/ gives Lo first n $\sum(X_i)^2$ (N @ 29)
		1 1 4	Y 0 0 6 0	/ σ_{x_i} sub
		1 1 5	Y 0 1 3 2	/ <input checked="" type="checkbox"/> rij } sub
		1 1 6	Y 0 1 3 7	/ rij } sub
		1 1 7	X B 6 2 3 8	/ Lo mean
		1 1 8	Y 0 0 3 7	/ mean sub
		1 1 9	Y 0 0 5 7	/ <input checked="" type="checkbox"/> σ_{x_i} } sub
		1 2 0	Y 0 0 5 8	/ σ_{x_i}
		1 2 1	Y 0 1 2 9	/ rij } sub
		1 2 2	Y 0 1 3 0	/ rij } sub
		1 2 3	X P 1 6 0 0	/ <input checked="" type="checkbox"/> cr.
		1 2 4	X Z 0 0 0 1	/ delay & 1 @ 29
		1 2 5	X B 6 2 3 9	/ Lo standard deviations
		1 2 6	Y 0 1 0 0	/ σ_{x_i} sub
		1 2 7	Y 0 1 3 5	/ <input checked="" type="checkbox"/>
		1 2 8	Y 0 1 3 6	/
		1 2 9	X B 6 2 3 6	/ Lo Δ Matrix
		3 0	X A 6 2 6 1	/ n + 1 @ 29
		3 1	X C 6 2 6 0	/ <input checked="" type="checkbox"/> Mean L_f +1 to test out



CARRIAGE RETURN



CONDITIONAL STOP CODE

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 2 / 5	
JOB NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 4-20-59		
PROBLEM: Given: Δ Matrix; Compute & Print \bar{X}_i, σ_{x_i} Rij Matrix (F.P.)					TRACK 00	
PROGRAM INPUT CODES	STOP STO	LOCATION	INSTRUCTION	D STO	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/ <input checked="" type="checkbox"/>					
	0 0 3 2	X P 1 6 0 0	/		cr.	
	1 3 3	R []	/		F. Point	
	1 3 4	U []	/		n	
	1 3 5	B []	/ <input checked="" type="checkbox"/>	ΣX_1		
	1 3 6	D []	/		No. of records	
	1 3 7	H []	/		\bar{X}_1	
	1 3 8	X P 0 0 0 0	/		Print \bar{X}_1	
	1 3 9	X E 0 0 0 0	/ <input checked="" type="checkbox"/>		Exit Floating Point	
	1 4 0	B 0 0 3 7	/		Add \bar{X}_1	
	1 4 1	A 0 0 2 4	/		1 @ 29	
	1 4 2	Y 0 0 3 7	/			
	1 4 3	B 0 0 3 5	/ <input checked="" type="checkbox"/>		Add. ΣX_1	
	1 4 4	A 0 0 2 4	/		1 @ 29	
	1 4 5	Y 0 0 3 5	/			
	1 4 6	E 0 2 0 1	/		3wwj mask	
	1 4 7	X S 6 2 1 6 1 0	/ <input checked="" type="checkbox"/>			
	1 4 8	T 9 0 3 3	/		loop back n times	
	1 4 9	X P 1 6 0 0	/		cr.	
	1 5 0	X Z 0 0 0 0	/		delay	
	1 5 1	X Z 9 8 0 0	/ <input checked="" type="checkbox"/>		BP 8 stop after means	
	1 5 2	X B 6 2 6 1	/		(n+1) @ 29	
	1 5 3	X C 6 2 6 0	/		Temp 1 (ctr)	
	1 5 4	X P 1 6 0 0	/		Δ Matrix $I_f + 1$ (set for σ_{x_1}) (Temp 1)	
	1 5 5	R []	/ <input checked="" type="checkbox"/>		F.P.	
	1 5 6	U []	/			
	1 5 7	P []	/		\bar{X}_1	
	1 5 8	M []	/		\bar{X}_1	
	1 5 9	X H 6 2 5 9	/ <input checked="" type="checkbox"/>		Temp 2 $n (\bar{X}_1)^2$	
	1 6 0	B []	/		$\sum X_i^2$	
	1 6 1	D []	/		No of records	
	1 6 2	X S 6 2 5 9	/ <input checked="" type="checkbox"/>		\bar{X}_1^2	
	6 3	X R 9 0 0 0	/ <input checked="" type="checkbox"/>		\checkmark	

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL				PAGE OF 3 / 5		
JOB NO. F2-130	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 4-20-59		
PROBLEM: Given: Δ Matrix; Computes & Print X_i , σ_{xi} , Rij Matrix (F.P.)				TRACK 00		
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/ <input checked="" type="checkbox"/>					
	0 1 0 0	H []	/		Standard Deviation	
	0 1	X P 0 0 0 0	/		Print stand. Div.	
	0 2	X E 0 0 0 0	/			
	0 3	B 0 0 5 7	/ <input checked="" type="checkbox"/>	Add. of \bar{X}_i		
	0 4	A 0 0 2 4	/	1 @ 29		
	0 5	Y 0 0 5 7	/			
	0 6	Y 0 0 5 8	/			
	0 7	B 0 1 0 0	/ <input checked="" type="checkbox"/>	Add of σ_{xi}		
	0 8	A 0 0 2 4	/	1 @ 29		
	0 9	Y 0 1 0 0	/			
	1 0	X B 6 2 6 0	/	Temp 1 (n+1, n, n-1, etc.)		
	1 1	S 0 0 2 4	/ <input checked="" type="checkbox"/>	1 @ 29		
	1 2	X H 6 2 6 0	/	Temp 1	n	
	1 3	A 0 0 6 0	/	Add. of ΣX_i	i^2	
	1 4	Y 0 0 6 0	/			
	1 5	B 0 0 2 4	/ <input checked="" type="checkbox"/>	1 @ 29		
	1 6	X S 6 2 6 0	/	Temp 1 (Test out when = 1)		
	1 7	T 0 0 5 5	/	loop back	(n times)	
	1 8	X P 1 6 0 0	/	cr.		
	1 9	X Z 0 0 0 0	/ <input checked="" type="checkbox"/>			
	2 0	X P 1 6 0 0	/	cr.		
	2 1	X Z 0 0 0 0	/			
	2 2	X Z 0 4 0 0	/	Bp. 4 stop after σ_{xi} cal.		
	2 3	X B 6 2 3 8	/ <input checked="" type="checkbox"/>	Lo mean		
	2 4	X A 6 2 3 3	/	n @ 29		
	2 5	X C 6 2 6 0	/	mean L _f +1	(Temp 1)	
	2 6	X C 6 2 5 9	/	tab counter	(Temp 2)	
	2 7	R []	/ <input checked="" type="checkbox"/>	F.P.		
	2 8	U []	/			
	2 9	P []	/	\bar{X}_i		
	3 0	M []	/	\bar{X}_j		
	3 1	X H 6 2 5 8	/ <input checked="" type="checkbox"/>	Temp 3	($\bar{X}_i \bar{X}_j$)	



CARRIAGE RETURN

= CONDITIONAL STOP CODE

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL				PAGE OF 4 / 5
JOB NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 4-20-59
PROBLEM: Given: Δ Matrix; Computes & Print X_i, σ_{xi} , Rij Matrix (F.P.)				TRACK 01

PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION		STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
	/						
	/						
		0 1 3 2	B []		/	$\Sigma X_i X_j$	
		3 3	D []		/	No. of records	
		3 4	X S 6 2 5 8		/	Temp. 3	
		3 5	D []		/	σ_{xi}	
		3 6	D []		/	σ_{xi}	
		3 7	H []		/	rij	
		3 8	X P 0 0 0 0		/	Print rij	
		3 9	X E 0 0 0 0		/	Exit F.P.	
		4 0	B 0 1 3 2		/	add $\Sigma X_i X_j$	
		4 1	A 0 0 2 4		/	1 @ 29	
		4 2	Y 0 1 3 2		/		
		4 3	Y 0 1 3 7		/		
		4 4	B 0 1 3 6		/	add σ_{xi}	
		4 5	A 0 0 2 4		/	1 @ 29	
		4 6	Y 0 1 3 6		/		
		4 7	B 0 1 3 0		/	add \bar{X}_j	
		4 8	A 0 0 2 4		/	1 @ 29	
		4 9	Y 0 1 3 0		/		
		5 0	E 0 2 0 1		/	3wwj mask	
		5 1	X S 6 2 6 0		/	σ_{xi} mean L _f +1	
		5 2	T 0 1 2 7		/		
		5 3	B 0 1 3 5		/	add σ_{xi}	
		5 4	A 0 0 2 4		/	1 @ 29	
		5 5	Y 0 1 3 5		/		
		5 6	Y 0 1 3 6		/		
		5 7	B 0 1 2 9		/	add \bar{X}_i	
		5 8	A 0 0 2 4		/	1 @ 29	
		5 9	Y 0 1 2 9		/		
		6 0	Y 0 1 3 0		/		
		6 1	E 0 2 0 1		/	3wwj mask	
		6 2	X S 6 2 6 0		/	σ_{xi} mean L _f +1	
		6 3	T 0 2 0 2		/		

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 5 / 5		
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 4-20-59			
PROBLEM: Given: Δ Matrix; Computes & Print X_i , σ_{xi} , Rij Matrix (F.P.)					TRACK 02		
PROGRAM INPUT CODES	PO S	LOCATION	INSTRUCTION		STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
	/						
	/	X					
		0 2 0 0	U	0 2 1 3	/	Exit Path	→
		0 1	X Z	6 3 6 3	/	mask for extract's	
		0 2	X P	1 6 0 0	/	cr.	
		0 3	X B	6 2 5 9	/	tab ctr	}
		0 4	A	0 0 2 4	/	1 @ 29	{ increase tab ctr by 1
		0 5	X C	6 2 5 9	/		
		0 6	X S	6 2 5 9	/	make acc. negative	
		0 7	T	0 2 0 9	/	print tab	
		0 8	U	0 1 2 7	/	Exit tab loop	
		0 9	X Z	0 0 0 0	/	delay	
		1 0	X P	2 4 0 0	/	tab	
		1 1	A	0 0 2 4	/	1 @ 29	
		1 2	U	0 2 0 7	/	loop	
		1 3	X P	1 6 0 0	/	cr.	
		1 4	X Z	0 0 0 0	/		
		1 5	X Z	0 8 0 0	/		
		1 6	U	[]	/		
		1 7			/		
		1 8			/		
		1 9			/	X	
		2 0			/		
		2 1			/		
		2 2			/		
		2 3			/	X	
		2 4			/		
		2 5			/		
		2 6			/		
		2 7			/	X	
		2 8			/		
		2 9			/		
		3 0			/		
		3 1			/	X	

TITLE: Convert triangular Rij matrix to a square Rij matrix -- modified.

AUTHOR: William F. Burggrabe, Jr.
Compumatrix, Incorporated

DATE: October 13, 1959

PURPOSE: Given a triangular matrix as prepared by the subroutine "Calculation of Means, Standard Deviations and Δ Correlation Coefficient Matrix", convert the Δ correlation coefficient portion to a square Rij matrix with the initial location of Δ Rij equal to the initial location of the \square Rij. This routine also sets automatically location 6240 to the correct address.

RESTRICTIONS:

- A) The Lo Δ Rij matrix = Lo \square Rij matrix
- B) The entire subroutine is in fixed point and will operate on both fixed and floating point format matricies, but will not operate on matricies in an extended range format.
- C) External storage as on attached sheet.

METHOD: The subroutine takes advantage of the symmetry of the matrix and sets cell ij = cell ji. A looping process builds both the row and column cells of the square matrix while stepping through the matrix from the bottom.

CODING INFORMATION:

- A) Storage: 56 sectors
- B) Constants: Lo + 51 1 @ 2
Lo + 52 1 @ 29
Lo + 53 Mask
- C) Linkage: R [Lo + 55]
U [Lo]
- D) Stops: Break point 4 at end of conversion
- E) Timing: Approximately $\frac{n(n+1)}{6}$ seconds.

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL						PAGE OF 1 / 1
JOB NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review		DATE 10-13-59	
PROBLEM:	External Storage $\Delta \rightarrow \square$ Rij Modified				TRACK 62	
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION ADDRESS			
	/					
	/					
	6 2 3 2			/		
	3 3	X Z []	/	n @ 29	No variables *	
	3 4		/			
	3 5		/			
	3 6	X Z []	/	Lo Δ Data	Matrix	*
	3 7		/			
	3 8		/			
	3 9		/			
	4 0	X Z []	/	Lo \square rij Matrix		
	4 1		/			
	4 2		/			
	4 3		/			
	4 4		/		Note: * These locations	
	4 5		/		must be filled prior	
	4 6		/		to entry into the	
	4 7		/		subroutine.	
	4 8		/			
	4 9		/			
	5 0		/		Note ✓: These locations	
	5 1		/		normally filled by	
	5 2		/		Δ Matrix Prep sub.	
	5 3		/			
	5 4		/			
	5 5		/			
	5 6		/			
	5 7		/			
	5 8	[]	/			
	5 9	[]	/	Temp storage		
	6 0	[]	/			
	6 1	[]	/	n + 1 @ 29	* ✓	
	6 2	[]	/			
	6 3	[]	/	(n+1)(n+2) @ 29	* ✓	



CARRIAGE RETURN

/ = CONDITIONAL STOP CODE

MAY 1964 111341X

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE 1 / 2		
JOB NO. F2-130	PROGRAM NO. BURGGRABE	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 10-10-59			
PROBLEM: $\Delta Rij \rightarrow \square Rij$ Matrix Conversion					TRACK 00		
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION		STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
; 0 0 0 Lo	/						
/ 0 0 0 Lo	/	X	B 6 2 3 6	/	Lo Δ data Matrix		
		X	A 6 2 6 3	/	$(n+1)(n+2)@$	29	
		S	0 0 5 2	/	1 @ 29		
		Y	0 0 1 7	/	\square B []	$L_f \Delta$ data matrix	
		X	B 6 2 3 6	/	Lo Δ data matrix		
		X	A 6 2 6 1	/	n + 1 @ 29		
		X	C 6 2 4 0	/	Lo Δ rij matrix & Lo \square rij matrix		
		X	C 6 2 6 0	/	\square Temp# 1 \rightarrow 0		
		X	C 6 2 5 9	/	Temp# 2 \rightarrow 0	Init. ctr's	
		X	C 6 2 5 8	/	Temp# 3 \rightarrow 0		
		X	B 6 2 3 3	/	n @ 29		
		X	N 6 2 3 3	/	\square n @ 29		
		M	0 0 5 1	/	1 @ 2 \rightarrow $n^2 @ 29$		
		X	A 6 2 4 0	/	Lo \square rij matrix		
		S	0 0 5 2	/	1 @ 29	$L_f \square$ rij matrix	
		Y	0 0 1 8	/	\square H []		
		Y	0 0 1 9	/	C []		
		B	[]	/	rij Δ matrix		
		H	[]	/	rij \square (row)		
		C	[]	/	\square rij \square (Col)		
		B	0 0 1 7	/	B []		
		S	0 0 5 2	/	1 @ 29		
		Y	0 0 1 7	/	B []		
		B	0 0 1 8	/	\square H []		
		S	0 0 5 2	/	1 @ 29		
		Y	0 0 1 8	/	H []		
		X	Y 6 2 5 8	/	Temp# 3		
		B	0 0 1 9	/	\square C []		
		X	S 6 2 3 3	/	n @ 29		
		Y	0 0 1 9	/	C []		
		E	0 0 5 3	/	3wwj Mask		
		X	S 6 2 5 8	/	\square Temp# 3		

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 2 / 2	
JOB NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 10-10-59		
PROBLEM: $\Delta Rij \rightarrow \square Rij$ Matrix Conversion					TRACK 00	
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	A D O R S	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/	<input checked="" type="checkbox"/>				
		9 0 3 2	T 0 0 3 4	'	Test out	
		1 3 3	U 0 0 1 7	'	loop	
		1 3 4	B 0 0 1 9	'	C[]	
		1 3 5	X A 6 2 5 9	' <input checked="" type="checkbox"/>	Temp 2	0,1,2,...n-1
		1 3 6	Y 0 0 1 8	'	H[]	
		1 3 7	X B 6 2 5 9	'	Temp 2	
		1 3 8	A 0 0 5 2	'	1@ 29	} Inc. ctr. 2
		1 3 9	X C 6 2 5 9	' <input checked="" type="checkbox"/>	Temp 2	
		1 4 0	X B 6 2 5 8	'	= old H[]	
		1 4 1	X A 6 2 6 0	'	Temp 1	0,n,2n...(n-1)n
		1 4 2	Y 0 0 1 9	'	C[]	
		1 4 3	X B 6 2 6 0	' <input checked="" type="checkbox"/>	Temp 1	} Inc. ctr. 1
		1 4 4	X A 6 2 3 3	'	n@ 29	
		1 4 5	X C 6 2 6 0	'	Temp 1	
		1 4 6	B 0 0 1 8	'	H[]	
		1 4 7	E 0 0 5 3	' <input checked="" type="checkbox"/>	3wwj	Mask
		1 4 8	X S 6 2 4 0	'	Lo \square rij matrix	
		1 4 9	T 0 0 5 4	'	test out	
, 0 0 0 0 0 0 3	,	1 5 0	U 0 0 1 7	'	loop →	
		1 5 1	2 0 0 0 0 0 0	' <input checked="" type="checkbox"/>	1@ 2	
		1 5 2		'	1 @ 29	
		1 5 3	3 w w j	'	Mask	
		1 5 4	X Z 0 4 0 0	'	BP 4 stop after conversion	
.	0 0 0 0 0 0	1 5 5	U []	' <input checked="" type="checkbox"/>	Exit	
		1 5 6		'		
		1 5 7		'		
		1 5 8		'		
		1 5 9		' <input checked="" type="checkbox"/>		
		1 6 0		'		
		1 6 1		'		
		1 6 2		'		
		1 6 3		' <input checked="" type="checkbox"/>		



TITLE: Compute and Print Matrix Inverse

AUTHOR: William F. Burggrabe, Jr.
Compumatrix, Incorporated

DATE: April 24, 1959

PURPOSE: A) Initialize and transfer control to the matrix inversion routine (29.0)
B) Printout the inverse if it is desired (transfer control up).

RESTRICTIONS:

- 1) Normal restrictions of 24.0, 12.6 and 29.0
- 2) See attached sheet for external information that must be supplied.
- 3) Output - 12.6 format

CODING INFORMATION:

- A) Storage: 55 sectors and under two above.
- B) Linkage: R (Lo + 54)
U (Lo)
- C) Input: None
- D) Output: 12.6 format with a carriage return after each row.

NOTE: Transfer control down skips printing to Lo + 53.

E) Constants:

Lo + 28	1 @ 29
Lo + 29	14 @ 29
Lo + 30	XZ0149
Lo + 31	1 @14

F) Timing:

Inversion: Approximately $1.08 n^3$ seconds
Printout: Approximately $2 n^2$ seconds

G) Program Stops:

Lo + 15* B.P. 8 inversion complete
Lo + 53 B.P. 4 printing complete

*Depression of transfer control before continuing causes a transfer to Lo + 53, thus eliminating the printing phase of the program.

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 1 / 1	
JOB NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 4-24-59		
PROBLEM: External Storage					TRACK 62	
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/	X				
		6 2 3 2		/		
		1 3 3	X Z []]	/	n @ 29 = Matrix order *	
		1 3 4		/		
		1 3 5		/	X	
		1 3 6		/		
		1 3 7	X Z []]	/	Lo floating point *	
		1 3 8		/		
		1 3 9		/	X	
		1 4 0	X Z []]	/	Lo rij Matrix *	
		1 4 1		/		
		1 4 2	X Z []]	/	Lo inversion sub. 29.0 *	
		1 4 3		/	X	
		1 4 4		/		
		1 4 5		/		Note: * These locations
		1 4 6		/		must be filled prior
		1 4 7		/	X	to entry into sub-
		1 4 8		/		routine
		1 4 9		/		
		1 5 0		/		
		1 5 1		/	X	
		1 5 2		/		
		1 5 3		/		
		1 5 4		/		
		1 5 5		/	X	
		1 5 6		/		
		1 5 7		/		
		1 5 8		/		
		1 5 9	[]]	/	X Temp & Ctr	
		1 6 0	[]]	/	Temp & Ctr	
		1 6 1		/		
		1 6 2		/		
		6 3		/	X	



LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL				PAGE OF 1 / 2
JOB NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 4-24-59
PROBLEM: Call-in, Compute & Print - Inverse (Rice F.P.M.I.)				TRACK 00

PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
; 0 0 0	Lo	1				
/ 0 0 0	Lo	/	X	B	6 2 3 3	n @ 29
		0 0 0 0	D	0 0 3 1	1 @ 14	
		0 1	X	A	6 2 4 0	Lo Rij matrix
		0 2	C	0 0 1 4	/	
		0 3	X	B	6 2 4 2	Lo matrix Inversion Sub (Rice M.I.)
		0 4	Y	0 0 1 3	/	
		0 5	A	0 0 2 9	XZ0014	
		0 6	Y	0 0 1 2	/	
		0 7	A	0 0 3 0	XZ0149	
		0 8	Y	0 0 1 1	/	
		0 9	X	B	6 2 3 7	Lo Floating Point
		1 0	Y	[]	/	(Matrix Inversion Lo + 163)
		1 1	R	[]	/	Matrix Inversion
		1 2	U	[]	/	Linkage
		1 3	[]	/		
		1 4		/		Code word
		1 5	X	Z	0 8 0 0	/ BP 8 stop after inversion
		1 6	X	C	6 2 6 0	Clear acc.
		1 7	8	0 0 T	0 0 5 3	Skip inverse print-out
		1 8	X	C	6 2 6 0	ctr 1 → 0
		1 9	X	C	6 2 5 9	/ ctr 2 → 0
		2 0	X	B	6 2 3 7	Lo Floating Point
		2 1	Y	0 0 3 2	/	
		2 2	Y	0 0 3 3	/	
		2 3	X	B	6 2 4 0	/ Lo Rij matrix inverse
		2 4	Y	0 0 3 4	/	
		2 5	X	P	1 6 0 0	cr.
		2 6	X	Z	0 0 0 0	/ delay
		2 7	U	0 0 3 2	/	transfer over constants
		2 8	X	Z	0 0 0 1	1 @ 29
		2 9	X	Z	0 0 1 4	14 @ 29
		3 0	X	Z	0 1 4 9	Used to set up Rice F.P.M.I.
		3 1	X	Y	0 0 0 0	/ 1 @ 4

Royal McBee Corporation
DATA PROCESSING DIV.
PORT CHESTER, NEW YORK



LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 2 / 2	
JO'S NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY. Burggrabe	PROGRAM CHECKED BY. POOL Review	DATE 4-24-59		
PROBLEM: Call-in, Compute & Print - Inverse (Rice F.P.M.I.)					TRACK 00	
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/					
		0 0 3 2	R []	/		
		3 3	U []	/		
		3 4	B []	/		No. to print
		3 5	X P 0 0 0 0	/	<input checked="" type="checkbox"/>	Print No.
		3 6	X E 0 0 0 0	/		Exit F.P.
		3 7	B 0 0 3 4	/		add. of no. printed
		3 8	A 0 0 2 8	/		1 @ 29
		3 9	Y 0 0 3 4	/	<input checked="" type="checkbox"/>	
		4 0	X B 6 2 6 0	/		ctr 1
		4 1	A 0 0 2 8	/		1 @ 29
		4 2	X H 6 2 6 0	/		ctr 1
		4 3	X S 6 2 3 3	/	<input checked="" type="checkbox"/>	n @ 29
		4 4	T 0 0 3 2	/		loop n times
		4 5	X P 1 6 0 0	/		cr.
		4 6	X C 6 2 6 0	/		ctr 1 → 0
		4 7	X B 6 2 5 9	/	<input checked="" type="checkbox"/>	ctr 2
		4 8	A 0 0 2 8	/		1 @ 29
		4 9	X H 6 2 5 9	/		ctr 2
		5 0	X Z 0 0 0 0	/		delay
		5 1	X S 6 2 3 3	/	<input checked="" type="checkbox"/>	n @ 29
		5 2	T 0 0 3 2	/		loop n times
		5 3	X Z 0 4 0 0	/		BP 4 stop after printing
		5 4	U []	/		Exit
		5 5		/		
		5 6		/		
		5 7		/		
		5 8		/		
		5 9		/	<input checked="" type="checkbox"/>	
		6 0		/		
		6 1		/		
		6 2		/		
		6 3		/	<input checked="" type="checkbox"/>	

TITLE: Calculation of Beta Weights, Regression Coefficients; Partial Correlation Coefficient and Standard Error of the Independent Variables; the Constant Term (b_0) and its Standard Error; the Sample Multiple Correlation Coefficient and Standard Error of Estimate; the Universe Multiply Correlation Coefficient and Standard Error of Estimate.

AUTHOR: William F. Burggrabe, Jr.
Compumatrix, Incorporated

DATE: May 26, 1960

PURPOSE: Given the inverse of the correlation coefficient matrix, the means and standard deviations of the variables; compute and printout the above.

RESTRICTIONS:

- 1) The last row and column of the matrix contain elements corresponding to the dependent variable. (Explanation under "Method").
- 2) Normal restrictions of 24.0 and 12.6
- 3) See attached sheet for external storage of information that must be supplied.
- 4) 25.0R in 0900

METHOD:

- A) Given a correlation coefficient matrix of the form:

	X_1	X_2	X_3	...	Y
X_1	R_{11}	R_{12}	R_{13}	...	R_{1y}
X_2	R_{21}	R_{22}	R_{23}	...	R_{2y}
X_3	R_{31}	R_{32}	R_{33}	...	R_{3y}
.
.
.
Y	R_{y1}	R_{y2}			R_{yy}

An inverse of the (Rij) matrix is computed yielding:

	X ₁	X ₂	...	Y
X ₁	$\frac{1}{V_{1,23} \dots Y}$	$\frac{\beta_{21,34} \dots}{V_{2,13} \dots y}$...	$\frac{\beta_{y1,23} \dots}{V_{y,123} \dots}$
X ₂	$\frac{\beta_{12,34} \dots}{V_{1,23} \dots y}$	$\frac{1}{V_{2,13} \dots y}$...	$\frac{\beta_{y2,13} \dots}{V_{y,123} \dots}$
.
.
.
Y	$\frac{\beta_{1y,23} \dots}{V_{1,23} \dots y}$	$\frac{\beta_{2y,13} \dots}{V_{2,13} \dots y}$...	$\frac{1}{V_{y,123} \dots}$

B) Where:

1. The β 's, Beta weights, are equal to the coefficients of the equation:

$$\frac{y^1 - \bar{Y}}{\sigma_y} = \beta_1 \frac{(X - \bar{X})_1}{\sigma_{x_1}} + \beta_2 \frac{(X - \bar{X})_2}{\sigma_{x_2}} + \dots + \beta_{n-1} \frac{(X - \bar{X})_{n-1}}{\sigma_{x_{n-1}}}$$

y^1 = Predicted Value

$\beta_1 = \beta_{y1,23} \dots$

$\beta_2 = \beta_{y2,13} \dots$

\bar{x}_i, \bar{Y} = means

σ_{x_i}, σ_y = standard deviations

The β 's are obtained by dividing each column element by the principle diagonal element in that column.

NOTE: All β 's for all multiple regression equations (i.e., are available in the inverse.

2. The regression coefficients are obtained from the beta weights as follows:

$$b_0 = \bar{Y} - \bar{x}_1 \frac{\sigma_y}{\sigma_{x1}} \quad \beta_1 = \bar{x}_2 \frac{\sigma_y}{\sigma_{x2}} \quad \beta_2 = \bar{x}_3 \frac{\sigma_y}{\sigma_{x3}} \quad \beta_3 = \dots$$

$$b_1 = \beta_1 \frac{\sigma_y}{\sigma_{x1}}$$

$$b_2 = \beta_2 \frac{\sigma_y}{\sigma_{x2}}, \quad \text{Etc.}$$

3. The partial correlation coefficients are obtained by:

$$r_{ab,cde \dots}^2 = \frac{\left(\frac{\beta_{ab,cde \dots}}{V_{a,bcde \dots}} \right) \cdot \left(\frac{\beta_{ba,cde \dots}}{V_{b,acde \dots}} \right)}{\left(\frac{1}{V_{a,bcde \dots}} \right) \cdot \left(\frac{1}{V_{b,acde \dots}} \right)}$$

However, because of the symmetry of the inverse,

$$\frac{\beta_{ab,cde \dots}}{V_{a,bcde \dots}} = \frac{\beta_{ba,cde \dots}}{V_{b,acde \dots}}$$

Therefore, each partial correlation coefficient may be obtained by dividing the corresponding off principal diagonal element by the square root of the product of the row, column elements of the principal diagonal.

4. Standard error of regression coefficient --

$$S_{bi} = \hat{s} \cdot \sqrt{\frac{(1-r_{iy,123 \dots}^2)}{N \sigma_i^2 (1-R_{i,123 \dots}^2)}}$$

5. The regression multiple correlation coefficients for the n equations are computed as follows:

$$R_{a,bcde}^2 = 1 - \frac{1}{\text{ath diag. element}}$$

or--

$$R = \sqrt{1 - \frac{\frac{1}{1}}{\frac{1}{V_{y,123 \dots}}}}$$

Etc.

6. The standard error of estimate is:

$$S = \sigma_y \sqrt{1 - R^2}$$

7. Universe multiple correlation coefficient --

$$\hat{R} = \sqrt{1 - (1-R^2) \left(\frac{N-1}{N-n} \right)}$$

8. Universe standard error of estimate --

$$\hat{S} = \sigma_y \sqrt{(1-\hat{R}^2) \left(\frac{N}{N-1} \right)}$$

- c) The program that has been written assumes the dependent variable cells to occupy the last column and/or row. However, a routine could be written for any other designation, or since the program does not alter the inverse, rows and columns could be interchanged, to put the correct elements in the proper locations for this program.

CODING INFORMATION:

- A) Storage 3 tracks 10 sectors plus external storage on attached sheet.
- B) Linkage R (Lo + 309)
U (Lo)
- C) Input None
- D) Output 12.6 - format (See sample problem)
- Order: $\beta_1, b_1, R_{1y,2} \dots S_{b1}$ C.R.
 $\beta_2, b_2, R_{2y,1} \dots S_{b2}$ C.R.
etc.
 $B_{n-1}, b_{n-1}, R_{n-ly,1} \dots$ C.R.
Tab b_0 Tab S_{b0} C.R.
C.R.
 $R, , S, \hat{R}, \hat{S}$
- E) Constants Lo + 226 l @ 29
Lo + 240 l @ 2
Lo + 148 Floating point "1"
- F) Timing: Approximately 10 n seconds
- G) Stops: Lo + 308 B.P. 4 stop at completion of program

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 1 /1
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE	
	F2-130	Burggrabe	POOL Review	1-15-60	
PROBLEM: External Storage					TRACK 62
PROGRAM INPUT CODES	LOC STO S	LOCATION	INSTRUCTION OPERATION ADDRESS	PO STO S	CONTENTS OF ADDRESS
	/				
	/			/	
	6 2	3 2		/	
		3 3	X Z []]	/	n @ 29 order of inverse *
		3 4	X Z []]	/	n @ 29 no. of records *
		3 5		/	
		3 6		/	
		3 7	X Z []]	/	Lo Floating Point *
		3 8	X Z []]	/	Lo means *
		3 9	X Z []]	/	Lo standard deviations *
		4 0	X Z []]	/	Lo inverse (rij matrix) *
		4 1		/	
		4 2		/	
		4 3	X Z []]	/	Lo regression coefficients *
		4 4		/	
		4 5		/	
		4 6		/	* Note: These locations must
		4 7		/	be filled prior to entering
		4 8		/	into subroutine
		4 9		/	
		5 0		/	
		5 1		/	
		5 2		/	
		5 3	[]]	/	
		5 4	[]]	/	
		5 5	[]]	/	
		5 6	[]]	/	
		5 7	[]]	/	
		5 8	[]]	/	Temp
		5 9	[]]	/	Temp
		6 0	[]]	/	Temp
		6 1	[]]	/	n + 1 @ 29 *
		6 2		/	
		6 3		/	



CARRIAGE RETURN

/ = CONDITIONAL STOP CODE

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE 1 / 7	
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 1-15-60		
PROBLEM: β_{xi} , b_{xi} , Partial Corr. Coeff, S_{bxi} , b_0 , & est, R, σ est, \hat{R} , $\hat{\sigma}$ est					TRACK 00	
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/					
		0 0 0 0	X B 6 2 3 3	/	n @ 29	
		0 1	X N 6 2 3 3	/	n @ 29	
		0 2	M 0 2 4 0	/	l @ 2	
		0 3	S 0 2 2 6	/	<input checked="" type="checkbox"/> l @ 29	
		0 4	X A 6 2 4 0	/	Lo \square Matrix Inverse	
		0 5	Y 0 0 6 0	/	Add [1/ V_n]	
		0 6	X B 6 2 3 3	/	n @ 29	
		0 7	S 0 2 2 6	/	<input checked="" type="checkbox"/> l @ 29	
		0 8	X H 6 2 5 4	/	Temp ctr	
		0 9	X A 6 2 4 0	/	Lo \square Matrix Inverse	
		1 0	Y 0 1 1 7	/	- β_i / V_n	
		1 1	Y 0 1 3 1	/	<input checked="" type="checkbox"/>	
		1 2	X B 6 2 4 0	/	Lo \square Matrix Inverse	
		1 3	Y 0 1 2 7	/	Add 1/ V_i	
		1 4	X B 6 2 3 9	/	Lo σ 's	
		1 5	Y 0 1 2 3	/	<input checked="" type="checkbox"/> Add [σ_{xi}]	
		1 6	Y 0 1 4 0	/	"	
		1 7	Y 0 1 4 1	/	"	
		1 8	X A 6 2 5 4	/	n-1 @ 29	
		1 9	Y 0 1 1 2	/	<input checked="" type="checkbox"/> Add [σ_x]	
		2 0	Y 0 1 2 2	/	"	
		2 1	Y 0 2 5 2	/	"	
		2 2	X B 6 2 4 3	/	Lo Reg. Coeff	
		2 3	Y 0 2 3 1	/	<input checked="" type="checkbox"/> Add [b_0]	
		2 4	A 0 2 2 6	/	l @ 29	
		2 5	Y 0 1 2 4	/	Add [b_{xi}]	
		2 6	Y 0 2 1 0	/		
		2 7	X B 6 2 3 8	/	<input checked="" type="checkbox"/> Lo means	
		2 8	Y 0 2 0 9	/		
		2 9	X A 6 2 5 4	/	n-1 @ 29	
		3 0	Y 0 2 2 9	/	Add Y	
		3 1	X B 6 2 3 7	/	<input checked="" type="checkbox"/> Lo floating point	

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 2 / 7	
JOB NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 1-15-60		
PROBLEM: β_{xi} , b_{xi} , Partial Corr. Coeff., S_{bxi} , b_o , & est, R , σ^2 est, \hat{R} , $\hat{\sigma}^2$ est					TRACK 00	
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/	X				
		0 0 3 2	Y 0 0 5 7	/		
		3 3	Y 0 0 5 8	/		
		3 4	Y 0 1 1 5	/		
		3 5	Y 0 1 1 6	/	X	
		3 6	Y 0 2 0 7	/		
		3 7	Y 0 2 0 8	/		
		3 8	Y 0 2 2 7	/	X	
		3 9	Y 0 2 2 8	/	X	
		4 0	Y 0 2 4 1	/		
		4 1	Y 0 2 4 2	/		
		4 2	Y 0 2 5 8	/		
		4 3	Y 0 2 5 9	/	X	
		4 4	X B 6 2 3 4	/		N @ 29
		4 5	S 0 2 2 6	/		1 @ 29
		4 6	X R 0 9 2 5	/		Float 25.0R
		4 7	X U 0 9 0 0	/	X	
		4 8	X Z 0 0 2 9	/		
		4 9	X C 6 2 5 7	/		n-1
		5 0	X B 6 2 3 4	/		n @ 29
		5 1	X S 6 2 3 3	/	X	n @ 29
		5 2	X R 0 9 2 5	/		Float 25.0R
		5 3	X U 0 9 0 0	/		
		5 4	X Z 0 0 2 9	/		
		5 5	X C 6 2 5 8	/	X	N-P
		5 6	X C 6 2 5 3	/		Temp → 0
		5 7	R []	/		24.0
		5 8	U []	/		
		5 9	B 0 1 4 8	/	X	"1"
		6 0	D []	/		$1/V_n$
		6 1	X H 6 2 5 9	/		$(1-R^2)$
		6 2	X D 6 2 5 8	/	X	$(1-R^2)/(N-1)$
		6 3	X H 6 2 5 8	/	X	

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 3 / 7	
JOB NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 1-15-60		
PROBLEM: β_{xi} , b_{xi} , Partial Corr. Coeff. S_{bxi} , b_o , & est, R , σ_{ext} , \hat{R} , $\hat{\sigma}^2$ est				TRACK 01		
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/					
	0 1 0 0	X U 0 0 0 0	/		Acc $\rightarrow M$	
	0 1	X M 6 2 5 7	/		$(n-1) \rightarrow (1-R^2)$	
	0 2	X Y 0 0 0 0	/		Change signs $\rightarrow -1+R^2$	
	0 3	A 0 1 4 8	/	X "1"	$\rightarrow \hat{R}^2$	
	0 4	X H 6 2 6 0	/			
	0 5	X B 6 2 5 7	/		N-1	
	0 6	A 0 1 4 8	/			
	0 7	X H 6 2 5 5	/	X		
	0 8	X U 0 0 0 0	/			
	0 9	X M 6 2 5 8	/			
	1 0	X R 0 0 0 0	/			
	1 1	X U 0 0 0 0	/	X		
	1 2	M []]	/		σ_y	$\hat{\sigma}^2$ est
	1 3	X H 6 2 5 8	/			
	1 4	X E 0 0 0 0	/		Exit	F.P.
	1 5	R []]	/	X	24.0	
	1 6	U []]	/			
	1 7	P []]	/		$-\beta/V_n$	
	1 8	X M 6 2 5 9	/		V_n	
	1 9	X Y 0 0 0 0	/	X	Change sign	
	2 0	X P 0 0 0 0	/		Print β_i	
	2 1	X U 0 0 0 0	/		Acc $\rightarrow M$	
	2 2	M []]	/		σ_y	
	2 3	D []]	/	X	σ_{x_i}	
	2 4	H []]	/		b_{xi}	
	2 5	X P 0 0 0 0	/			
	2 6	B 0 1 4 8	/		"1"	
	2 7	D []]	/	X	$1/V_i$	
	2 8	X H 6 2 5 7	/		$(1-R_i)$	
	2 9	X M 6 2 5 7	/		$\beta_i \cdot V_i$	
	3 0	X U 0 0 0 0	/	X		
	3 1	M []]	/	X	$-\beta_i/V_i$	$-\beta_{iy} \cdot \beta_{yi}$

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE 4 / 7	
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 1-15-60		
PROBLEM: β_{xi} , b_{xi} , Partial Corr. Coeff, S_{bxi} , b , & est, R , σ est, \hat{R} , $\hat{\sigma}$ est					TRACK 01	
PROGRAM INPUT CODES	F O R M A T S T O R E	LOCATION	INSTRUCTION	L O C A T I O N S	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/	X 1 3 2	X Y 0 0 0 0	/		
		X 3 3	X H 6 2 5 6	/	$r^2 \cdot \text{xxx}$	Partial
		X 3 4	X I R 0 0 0 0	/	\checkmark	$riy \cdot \text{xxxx}$
		X 3 5	X P 0 0 0 0	/	X	$riy \cdot \text{xxxx}$
		X 3 6	B 0 1 4 8	/	"1"	
		X 3 7	X S 6 2 5 6	/	r^2	
		X 3 8	X D 6 2 5 7	/	$(1-R_1^2)$	
		X 3 9	X D 6 2 5 5	/	X	N
		X 4 0	D [] [] []	/	σ_{xi}	
		X 4 1	D [] [] []	/	σ_{xi}	$(1-r^2)/N \sigma (1-R_1^2)$
		X 4 2	X R 0 0 0 0	/	\checkmark	$\sqrt{C_{11}}$
		X 4 3	X U 0 0 0 0	/	X	Acc $\rightarrow M$
		X 4 4	X M 6 2 5 8	/	$\hat{\sigma}$	est
		X 4 5	X P 0 0 0 0	/	Print	(S_{bxi})
		X 4 6	X E 0 0 0 0	/		
		X 4 7	X P 1 6 0 0	/	X	
, 0 0 0 0 0 0 1	/	X 4 8	4 0 0 0 0 0 2	/	F.P. "1"	& delay
		X 4 9	B 0 1 1 7	/	Add $[-\beta_i/V_n]$	
		X 5 0	X A 6 2 3 3	/	n@ 29	
		X 5 1	Y 0 1 1 7	/	X	
		X 5 2	Y 0 1 3 1	/		
		X 5 3	B 0 1 2 3	/	D[σ_{xi}]	
		X 5 4	A 0 2 2 6	/	1@ 29	
		X 5 5	Y 0 1 2 3	/	X	
		X 5 6	Y 0 1 4 0	/		
		X 5 7	Y 0 1 4 1	/		
		X 5 8	B 0 1 2 4	/	H[b _{xi}]	
		X 5 9	A 0 2 2 6	/	X	1@ 29
		X 6 0	Y 0 1 2 4	/		
		X 6 1	B 0 1 2 7	/	D[1/V _i]	
		X 6 2	X A 6 2 6 1	/	(n+1) @ 29	
		X 6 3	Y 0 1 2 7	/	X	

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE 5 / 7	
JOB NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 1-15-60		
PROBLEM: β_{xi} , b_o , Partial Corr. Coeff. $S_{\beta xi}$, b_o , & est, R , Σ est, \hat{R} , $\hat{\Sigma}$ est					TRACK 02	
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/					
		0 2 0 0	X B 6 2 5 3	/	ctr	
		0 1	A 0 2 2 6	/	l @ 29	
		0 2	X H 6 2 5 3	/	ctr	
		0 3	X S 6 2 5 4	/	<input checked="" type="checkbox"/> n-1 @ 29	
		0 4	T 0 1 1 5	/		
		0 5	X C 6 2 5 3	/	ctr	
		0 6	X C 6 2 5 6	/	Σ area	
		0 7	R []	/	<input checked="" type="checkbox"/> 24.0	
		0 8	U []	/		
		0 9	P []	/	\bar{x}_i	
		1 0	M []	/	b_{xi}	
		1 1	X A 6 2 5 6	/	<input checked="" type="checkbox"/> Σ	
		1 2	X H 6 2 5 6	/	Σ	
		1 3	X E 0 0 0 0	/	Exit F. P.	
		1 4	B 0 2 0 9	/	P [\bar{x}_i]	
		1 5	A 0 2 2 6	/	<input checked="" type="checkbox"/> l @ 29	
		1 6	Y 0 2 0 9	/		
		1 7	B 0 2 1 0	/		
		1 8	A 0 2 2 6	/	<input checked="" type="checkbox"/> l @ 29	
		1 9	Y 0 2 1 0	/	<input checked="" type="checkbox"/>	
		2 0	X B 6 2 5 3	/	ctr	
		2 1	A 0 2 2 6	/	<input checked="" type="checkbox"/> l @ 29	
		2 2	X H 6 2 5 3	/	ctr	
		2 3	X S 6 2 5 4	/	<input checked="" type="checkbox"/> (n-1) @ 29	
		2 4	T 0 2 0 7	/		
		2 5	X P 2 4 0 0	/	tab	
		2 6	X Z 0 0 0 1	/	l @ 29 & delay	
		2 7	R []	/	<input checked="" type="checkbox"/> 24.0	
		2 8	U []	/	-	
		2 9	B []	/	\bar{Y}	
		3 0	X S 6 2 5 6	/	Σ	
		3 1	H []	/	<input checked="" type="checkbox"/> b_o	

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE OF 6 / 7	
JOB NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 1-15-60		
PROBLEM: β_{xi} , b_{xi} , Partial Corr. Coeff, S_{bxi} , b_0 , & est, R, σ^2 est, R^2 , σ^2 est					TRACK 02	
PROGRAM INPUT CODES	P S T O R E	LOCATION	INSTRUCTION	P S T O R E	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/ <input checked="" type="checkbox"/>					
	9 2 3 2	X P 0 0 0 0	/			
	3 3	X B 6 2 5 5	/	N		
	3 4	X R 0 0 0 0	/	<input checked="" type="checkbox"/> $\sqrt{N} \rightarrow \sqrt{N}$		
	3 5	X H 6 2 5 5	/ <input checked="" type="checkbox"/>			
	3 6	X B 6 2 5 8	/	σ^2 est		
	3 7	X D 6 2 5 5	/	\sqrt{N}		
	3 8	X E 0 0 0 0	/	Exit F.P.		
	3 9	X P 2 4 0 0	/ <input checked="" type="checkbox"/>	tab		
, 0 0 0 0 0 0 7	/ 4 0 2 0 0 0 0 0 0		/	1@ 2 & delay		
	4 1	R []]	/			
	4 2	U []]	/			
	4 3	X P 0 0 0 0	/ <input checked="" type="checkbox"/>	S_{ax}		
	4 4	X B 6 2 5 9	/	$1-R^2$		
	4 5	S 0 1 4 8	/	"1"		
	4 6	X Y 0 0 0 0	/	change signs R^2		
	4 7	X R 0 0 0 0	/ <input checked="" type="checkbox"/>	$\sqrt{ }$	R	
	4 8	X H 6 2 5 7	/	R		
	4 9	X B 6 2 5 9	/	$1-R^2$		
	5 0	X R 0 0 0 0	/	$\sqrt{ }$		
	5 1	X U 0 0 0 0	/ <input checked="" type="checkbox"/>	Acc $\rightarrow M$		
	5 2	M []]	/	$\sigma_y \rightarrow \sigma$ est		
	5 3	X H 6 2 5 9	/	σ ext		
	5 4	X E 0 0 0 0	/			
	5 5	X P 1 6 0 0	/ <input checked="" type="checkbox"/>	cr.		
	5 6	X Z 0 0 0 0	/			
	5 7	X P 1 6 0 0	/	cr.		
	5 8	R []]	/			
	5 9	U []]	/ <input checked="" type="checkbox"/>			
	6 0	X B 6 2 5 7	/	R		
	6 1	X P 0 0 0 0	/	Print		
	6 2	X B 6 2 5 9	/	σ est		
	6 3	X P 0 0 0 0	/ <input checked="" type="checkbox"/>	Print		

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL					PAGE 7 / 7	
JOB NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 1-15-60		
PROBLEM: β_{xi} , b_{xi} , Partial Corr. Coeff, S_{bxi} , b_0 , & est, R, σ est, \hat{R} , $\hat{\sigma}$ est					TRACK 03	
PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	POS	CONTENTS OF ADDRESS	NOTES
			OPERATION			
	/					
	/					
		0 3 0 0	X B 6 2 6 0	/	\hat{R}^2	
		0 1	X R 0 0 0 0	/		
		0 2	X P 0 0 0 0	/		
		0 3	X B 6 2 5 8	/	X $\hat{\sigma}$ est	
		0 4	X P 0 0 0 0	/		
		0 5	X E 0 0 0 0	/		
		0 6	X P 1 6 0 0	/	cr.	
		0 7	X Z 0 0 0 0	/	X delay	
		0 8	X Z 0 4 0 0	/	stop	BP. 4
		0 9	U []]	/	Exit	
		1 0		/		
		1 1		/	X	
		1 2		/		
		1 3		/		
		1 4		/		
		1 5		/	X	
		1 6		/		
		1 7		/		
		1 8		/		
		1 9		/	X	
		2 0		/		
		2 1		/		
		2 2		/		
		2 3		/	X	
		2 4		/		
		2 5		/		
		2 6		/		
		2 7		/	X	
		2 8		/		
		2 9		/		
		3 0		/		
		3 1		/	X	

TITLE: Calculation of Y^1 and $(y-y^1)$ given a set of coefficients and a set of records.

AUTHOR: Allen G. Renz
Compumatrix, Incorporated

DATE: October 6, 1959

PURPOSE: To read in a set of records, each record containing values for $X_1, X_2 \dots X_n$ and Y , and calculate a predicted value of Y^1 , using a set of coefficients stored in the machine also calculate $(y-y^1)$ and print out Y^1 , and $(y-y^1)$.

RESTRICTIONS:

- A) Normal restrictions of 24.0, 11.6 and 12.6
- B) Coefficients must be stored in machine prior to reading the first record, in order (i.e. $b_0, b_{x1}, \dots b_{xn}$)
- C) The program requires one track
- D) The number of variables is limited only by machine storage available.

CODING INFORMATION:

- A) Storage
 - 1) Program - one track
 - 2) F.P.I.S. - 16 tracks
 - 3) External storage - 6232 to 6263 (see attached sheet)
- B) No calling sequence is required.
Linkage: R (Lo + 57)
U (Lo + 00)
- C) Input is in 11.6 floating point input format in the following sequence:

First record

$\pm P$ (Lo record)' 1' X_1' X_2' ... X_n' Y' -00000000''

Following records

$\pm P$ (Lo record + 1)' X_1' X_2' ... X_n' Y' -00000000''

D) Output: Output is in floating point format. Three columns are printed out: Y, Y¹, and (y-y¹).

E) Location of constants:

Lo + 46 l @ 29
Lo + 63 XZ6363 Mask

F) Timing:

$[(7 + 1.2n) \text{ sec.} + \text{record read time}] N$

where n = No. variables

N = No. records

G) Program stops:

Lo + 47 (B.P. 4) after print out of each record

Lo + 56 (B.P. 8) after completion of N records

External Storage Required

y' and $(y-y')$ Floating Point Calculation

6233 - n, No. of variables @ q = 29

6234 - N, No. of records @q = 29

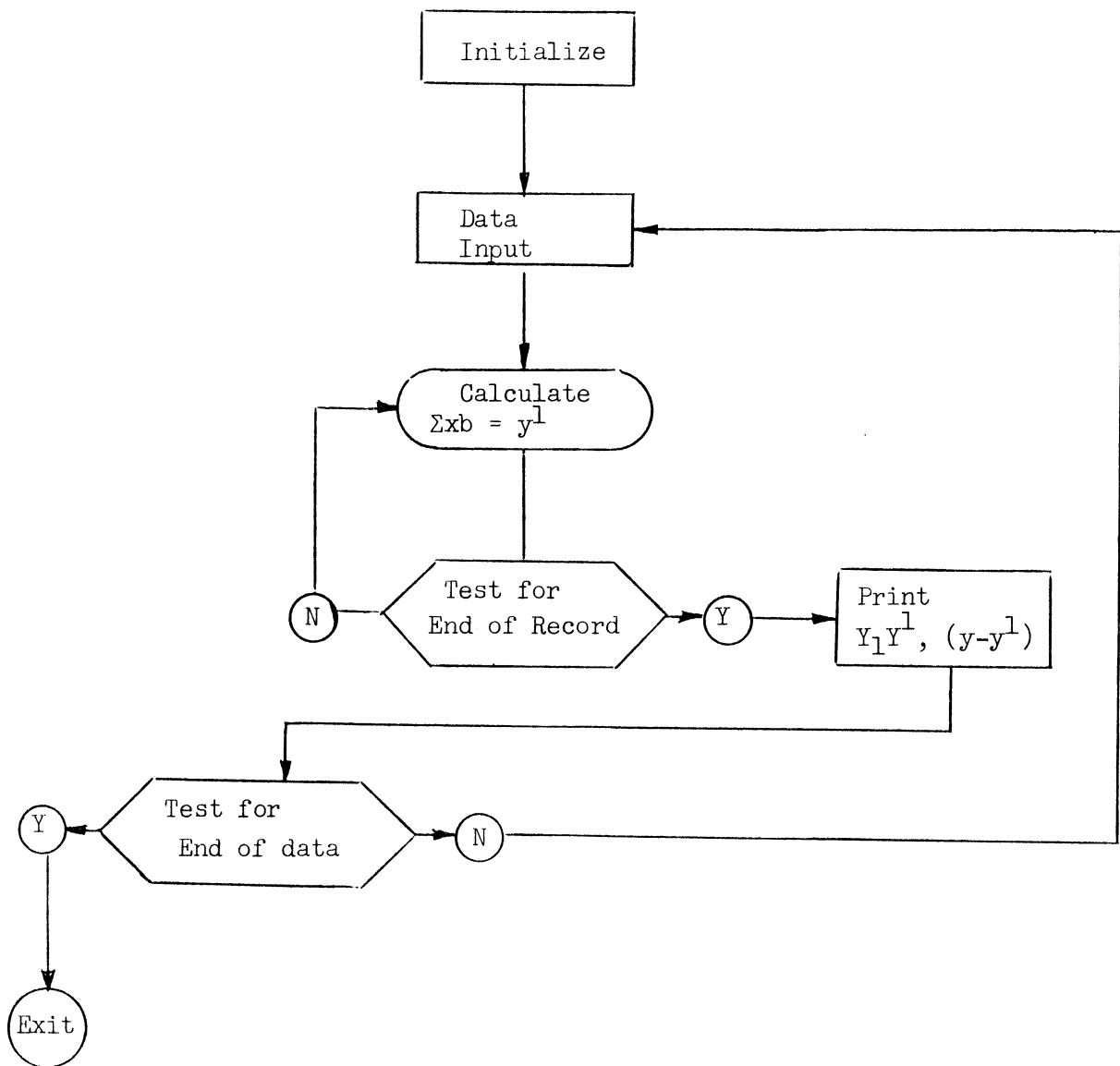
6235 - Lo of record

6237 - Lo of Floating Point Int. System

6243 - Lo of Coefficients

6258-6260 - Temporary storage

Calculation of Y^1 and $(y-y^1)$



LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL				PAGE OF 1 / 2
JOB NO.	PROGRAM NO. F2-130	PROGRAM PREPARED BY: Burggrabe	PROGRAM CHECKED BY: POOL Review	DATE 10-5-59
PROBLEM: Calculation of Y' & (Y-Y') [Floating Point]				TRACK 00

PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION	STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION			
; 0 0 0	I					
/ 0 0 0	I	X				
		0 0 0 0	X B 6 2 3 5	I	Lo Record	
		0 1	Y 0 0 2 1	I		
		0 2	X A 6 2 3 3	I	n @ 29	L _f record
		0 3	Y 0 0 3 6	I	X	
		0 4	Y 0 0 5 8	I		
		0 5	X B 6 2 4 3	I	Lo Coeff.	
		0 6	Y 0 0 2 2	I		
		0 7	X B 6 2 3 7	I	X	Lo Floating Point
		0 8	Y 0 0 1 7	I		
		0 9	Y 0 0 1 8	I		
		1 0	Y 0 0 3 3	I		
		1 1	Y 0 0 3 4	I	X	
		1 2	Y 0 0 6 0	I		
		1 3	Y 0 0 6 1	I		
		1 4	X C 6 2 6 0	I	Acc → 0	
		1 5	X S 6 2 3 4	I	X	N @ 29
		1 6	X C 6 2 6 0	I		-N @ 29
		1 7	X R []	I		
		1 8	X U []	I		
		1 9	X I 0 0 0 0	I	X	
		2 0	X C 6 2 5 8	I		
		2 1	X P []	I	X _i	
		2 2	X N []	I	bx _i	→ Σ bx in Acc.
		2 3	X E 0 0 0 0	I	X	
		2 4	B 0 0 2 2	I		
		2 5	A 0 0 4 6	I	l @ 29	
		2 6	Y 0 0 2 2	I		
		2 7	B 0 0 2 1	I	X	
		2 8	A 0 0 4 6	I	l @ 29	
		2 9	Y 0 0 2 1	I		
		3 0	E 0 0 6 3	I	XZ 6363	
		3 1	S 0 0 5 8	I	X	

LGP-30 CODING SHEET

PREPARED FOR: LGP-30, RPC-4000 Users' Organization - POOL				PAGE OF 2 / 2
JOB NO.	PROGRAM NO.	PROGRAM PREPARED BY:	PROGRAM CHECKED BY:	DATE 10-5-59
PROBLEM: Y' &(Y-Y') Floating Point				TRACK 00

PROGRAM INPUT CODES	STOP	LOCATION	INSTRUCTION		STOP	CONTENTS OF ADDRESS	NOTES
			OPERATION	ADDRESS			
	/						
	/						
	0 0 3 2		T 0 0 6 0		/		
	3 3		X R []		/		
	3 4		X U []		/		
	3 5		X H 6 2 5 8		/	X Y'	
	3 6		X B []		/	Y	
	3 7		X P 0 0 0 0		/		Print Y
	3 8		X S 6 2 5 8		/	Y'	
	3 9		X H 6 2 5 9		/	X (Y-Y')	
	4 0		X B 6 2 5 8		/		
	4 1		X P 0 0 0 0		/		Print Y'
	4 2		X B 6 2 5 9		/		
	4 3		X P 0 0 0 0		/	X	Print (Y-Y')
	4 4		X E 0 0 0 0		/		
	4 5		X P 1 6 0 0		/		
	4 6		X Z 0 0 0 1		/		
	4 7		X Z 0 4 0 0		/	X Stop after print out	
	4 8		X B 6 2 3 5		/		Lo record
	4 9		Y 0 0 2 1		/		
	5 0		X B 6 2 4 3		/		Lo Coeff.
	5 1		Y 0 0 2 2		/	X	
	5 2		X B 6 2 6 0		/		
	5 3		A 0 0 4 6		/		
	5 4		X H 6 2 6 0		/		
	5 5		T 9 0 1 7		/	X	
	5 6		X Z 0 8 0 0		/		Stop after N records
	5 7		U []		/		Exit
	5 8	[]			/		L Record
	5 9				/	X	
	6 0		X R []		/		
	6 1		X U []		/		
	6 2		U 9 0 2 1		/		
	6 3		X Z 6 3 6 3		/	X	Mask

