

THIRTY-TWO BIT MICROS POWER WORKSTATIONS

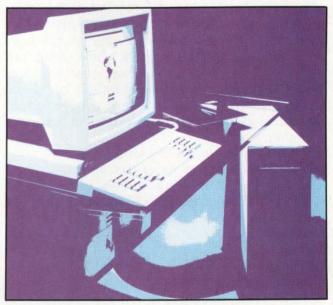
New "star" processors require strong supporting casts and clever designs to be effective engines in engineering workstations.

by Nicolas Mokhoff, Senior Editor

With system engineers just beginning to reap the benefits of their 16-bit microprocessor-based designs, and 32-bit chips about to be integrated into new designs, a complacent observer might conclude that there will soon be an IBM/370 mainframe-equivalent computer on every professional's desk. Yet, behind this "ethereal" work environment is a more realistic prognosis. The mainframe-per-desk dream will only materialize when all components of this powerful workstation perform as members of one orchestra in a symphony of information processing and communication.

To make successful "data music" together, 16and 32-bit microprocessors must perform in concert within a system architecture. No matter what outstanding features a sophisticated microprocessor possesses, the chip by itself contributes little to the workstation's overall performance. It must also be incorporated on an efficient bus architecture and surrounded with proper hardware and software support.

Moreover, high performance workstations usually embody more than one "star" microprocessor. In an efficient multitask, multiprocess workstation, various 8-, 16-, and 32-bit separate processors are used for such data-intensive functions as graphics, high speed I/O, diagnostics, and communications. Thus, this multiprocessing capability must be accommodated within the designer's system specification a tricky task, to say the least.



The current frenetic pace in defining 32-bit microprocessor bus specifications lends credence to the notion that design engineers need more than glorified VLSI chips to make their systems really work. Thus, both chip manufacturers and users have strongly identified their marketing strategies and applications with one of four open-system bus schemes, such as Multibus II, VMEbus, NuBus, and Futurebus, or with some kind of proprietary bus. These proprietary 32-bit bus schemes are closely related to a particular hardware configuration and are therefore limited in appeal to the entire design community.

One such "closed" open-system bus scheme is in the works at Digital Equipment Corp (Maynard,



Syte Technology's first workstation, the model 300, displays the kind of power now available to the design engineer. It is designed for engineering-oriented applications including software development, computer aided engineering, and project management. The multiple microprocessor hardware lets users make fast floating point calculations on a DEC VAX-11/750 supermini. The system allows multiple operating systems to run concurrently on one mode; simultaneously on multiple computers on the network.

Mass). The company is developing a 32-bit bus architecture for a whole family of new 32-bit machines. If history is a guide, DEC should have wide success in promulgating a whole new board industry on the par of its O-bus and O-22 compatible board business. However, because those boards are intimately tied to DEC computers, they remain of interest only to that particular segment of the design community.

For the rest of the design world, choosing among available open-system buses can be a harrowing experience. Of course, advocates of the respective schemes will defend their bus to the death based on worthy technical merits. However, they will also readily admit that such factors as marketing, and compatibility with an installed base of products that sport their choice bus's 8- and 16-bit predecessors, are critical in the selection process.

The bus standardization issue is, in itself, a moving target. It is best, therefore, to let the actual standards documents supply the sufficient information on the individual buses (see reference section, "Obtaining bus specifications," on p 112). In light of recent developments, it is perhaps more beneficial to concentrate on several arbitrary hardware and software choices from manufacturers of sophisticated workstations. In all cases, the companies choose a processor, system architecture, software environment, and communication capability to produce a single-user networked workstation that suits a particular set of specifications for a well-targeted market. Among the workstations highlighted are those from Syte Information Technology (San Diego, Calif), Sun Microsystems (Mountain View, Calif),

Apollo Computer, Inc (Chelmsford, Mass), Tektronix (Wilsonville, Ore), Hewlett-Packard (Palo Alto, Calif), Jupiter Systems, Inc (Berkeley, Calif), and Saber Technology Corp (San Jose, Calif). This analysis offers a general perspective on both the components and the thinking process needed to optimize the new 32-bit micros.

In the case of Syte Information Technology, company principals went out of their way to endorse the National Semiconductor (Santa Clara, Calif) NS32032 when that chip was introduced. The microprocessor became the CPU for the company's first product—the model 300 workstation. Aside from the publicity benefits for both companies, the endorsement also yielded some interesting insights into the technical evaluations done by Syte engineers. According to Syte system architect, Michael Fischer, "For the first time, a single chip [NS32032] incorporates many features that were previously associated with mainframe machines."

An efficient chip architecture

Two key features of the NS32032 are the symmetry of its instruction set and the ability to efficiently run programs written in high level languages. The instruction set's orthogonality allows all instruction types to operate on all addressing modes and data types. This makes it relatively easy to construct efficient programs in either assembly language or high level languages. And, because special cases need not be used to any great extent, portability is extended and programs are easier to debug and modify. Moreover, the features allowing efficient execution of high level language programs become even more important. This is because virtually all of the software for modern processors (including applications, compilers, and operating systems) is now written in high level languages.

Part of this high level language support is provided by a module-linkage facility. This facility permits independently compiled modules to call each other through a mechanism that does not require a linking loader. The benefits here are easy use and easy distribution of utility and support software. According to Fischer, the NS32032's module-linkage facility protects proprietary code because source code need not be distributed. The modules are encapsulated and independent. They can thus be efficiently shared using the common-linkage mechanism, regardless of the source language in which the module was written.

Another important feature for high level language support is the chip's set of addressing modes. The available modes include stack-frame support, with a hardware-frame pointer register; static-data area support, with a hardware pointer register; and dualdisplacement indirect addressing modes with both a pre- and post-index for accessing pointers in a stack frame or in the static area. Other modes featured are external addressing for referencing external

variables located in other areas; external addressing for referencing external variables in other modules; and scaled-index mode, which makes array indexing much simpler, according to Fischer.

The many instructions in the NS32032 instruction set are uniquely oriented toward efficient, high level language support. These instructions include interactive array subscript calculations, array-index bounds checking, a multiway branch, and independent division operations for producing quotient and remainder. (Most machines take the time to produce both quotient and remainder in all cases, even though only one is usually needed.) In addition, there are string operations that generalize to bytes, words, and double words; and bit-field operations that enable accessing of variable-length, bit-addressed fields anywhere in memory without byte boundary and alignment restrictions. There is also a rich set of floating point operations to extend the integer operations in a consistent manner.

Moreover, the chip's memory management architecture is patterned after the memory management system used on a number of successful large scale machines, including the IBM 370 series and DEC VAX. Memory management support instructions are tightly integrated with the CPU instruction set. Various tightly coupled CPU functions on peripheral chips can be implemented in a "custom slave." Instructions exist for this slave, and the NS32032 hardware user can supply the slave circuitry.

The four principles of tight coupling

The chip's tightly coupled architecture provides a firm basis for Syte's closely coupled system architecture in the 300 workstations, as well as in the company's overall network of model 300 workstations—the series 3000. The Syte architecture serves as the foundation of a product family that the company plans to develop throughout the decade. This architecture's principles define the structure of the hardware, software, and user interface. These principles can be generically applied to the majority of workstation architectures. Moreover, these principles are incorporated in four main objectives: a single-level, network-wide, and demand-paged address space; a single, uniform interface between all system resources; a configuration that supports a wider range of performance levels; and a technologyindependent system that is economically feasible.

The first objective, a network-wide address space, allows any user (or object) to gain direct access using a common mechanism (or any other object or resource) on the Syte network. Bruce Hamilton, the company's vice president of engineering, says that a global address space of 64 bits is sufficient to accommodate the substantial increases in memory and bulk storage that any technology advances might provide during this decade. Thus, to accommodate the large address space in the network, demand

paging is used within the address space itself. There, it supports virtual memory spaces to create an independent address space for each process running anywhere in the network. Demand paging permits a program, or a combination of programs larger than the physical memory, to be run on any node in the network. Initially, each process's virtual address space will be 24 bits or 16 Mbytes. Larger process address spaces up to 32 bits will be supported when the technology is economical, according to Hamilton. Demand paging is now a key feature in other manufacturer workstations as well.

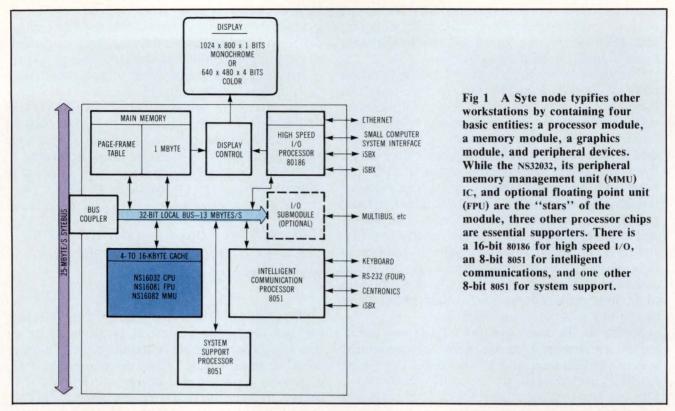
The NS32032 chip incorporates many features previously associated with mainframe machines.

The second objective, a single, uniform interface between all system resources, is provided by an operating system kernel called the global environment manager (GEM). Files, directories, buffers, processes, windows, and devices are all treated as objects by the GEM. Different object types are arranged in a hierarchy and messages are interpreted by the object to which they are sent. The sender of a message need only know which object to send the message to, and what is to be done with it—nothing about how it will be done.

The GEM creates all objects with a unique identifier to permit unambiguous communication between all objects in a network. An object only interprets its own messages and manages its internal data structures. The capabilities of any object can be extended or modified without altering any code associated with other objects.

The ability to configure a system to support a wide range of performance levels is the company's third objective and is achieved by optimizing the performance of a single node (a standalone workstation). Thus, the Syte architecture provides many performance levels: closely coupled, multiprocessor configurations for high performance; loosely coupled configurations for distributed processing; and multiuser configurations for a low cost per station advantage. The configuration quality is enhanced by using standard interfaces for external connections. These include RS-232, Multibus (IEEE 796), iSBX (IEEE P959), Ethernet (IEEE 802.3), Small Computer System Interface (American National Standards Institute-X3T9.2), and OIC-02/OIC-24. Finally, the fourth objective technology independence—is met by having all system software written in a high level language, using proprietary high bandwidth internal buses, and adhering to industry standard external interfaces.

The Syte network consists of nodes connected by an Ethernet local area network (LAN). The GEM operating system runs in a supervisory mode on each



node to make the total resources of the network available to all users. A processor module in each node is connected to the network through its high speed I/O subsystem via Intel (Santa Clara, Calif) 80186 and 8051 interface chips (Fig 1).

A node is the basic physical entity in the network. It consists of one or more of the following: a processor module, a memory module, a graphics module, and peripheral devices (eg, Winchester disks, quarter-inch streaming tape, a floppy disk, and a line printer). Each module contains cooperating systems that perform the functionally distributed tasks. The modules communicate via a 25-Mbyte/s Sytebus. A node can contain up to four copies of each type of module; up to eight modules in any combination.

Bit slicing into a graphics processor

Thirty-two bit microprocessors are still not powerful and flexible enough to accommodate high resolution graphics requirements. Thus, the graphics module is designed with a high speed, microprogrammed, bipolar graphics processor (AMD 29116) and 1 Mbyte of display memory. Its high resolution display output can drive one to eight 1000- x 800pixel monochrome monitors, one 1000- x 8-pixel color monitor, or two 1000- x 800-pixel x 4-plane color monitors. The graphics processor performs display-list interpretation, vector-generation raster operations, and full chip-and-pick support. A Syte node can contain up to four graphics modules.

As with other modules, the company's graphics module has a closely coupled architecture. In conventional systems, interactive graphics display generators usually attach to their host computers as peripherals. This type of loosely coupled configuration requires that all graphics information be transferred between the host and the display generator by programmed I/O or DMA transfers. This not only incurs the I/O handling overhead of the host operating system, but also imposes a bottleneck on the flow of information between the application program and the display generator. As a result, the loose coupling reduces performance by increasing the amount of data transferred, and requires software and/or firmware whose only function is to support the transfer process.

Syte's high performance distributed workstations are bound by a more tightly coupled display subsystem organization. Typically, this tighter coupling eliminates the interface circuitry by placing the display generator directly on the workstation's I/O bus. This saves the cost of the interface, but does not address either excess data transfers or the additional software required to support the transfer.

The architecture of the system's graphics facilities reduces the data transferred and the support software required. The product line has two implementations that solve these problems. One is oriented for high performance at intermediate cost; the second for intermediate performance at low cost. Both of these graphics options are closely coupled to the rest of the system, and are supported in a transparent manner to the application software. This is done by using the same objects, messages, and external data structures.

The first implementation uses an optional onboard display subsystem on the processor module. This subsystem generates a high resolution monochrome

(1000 x 800) or medium resolution (640 x 480 x 4) color display directly from the onboard main memory. A separate memory port is used to fetch display data from memory without involving the local bus, which connects to other subsystems. The sole interface is shared by main memory, which all of the processing subsystems already use. Cost is minimized because not even interboard busing is required for the display generator.

The second implementation is the graphics module, which attaches to the 25-Mbyte/s Sytebus. The close coupling between the graphics module and the processing subsystems on other modules is achieved by using the common physical address space of the Sytebus. The coupling operates in both directions. Image memory on the graphics module is directly addressable as system memory. Moreover, the graphics processor can directly address any offboard memory to access display data structures, font descriptions, etc. The display list can be managed by the same memory management routines as the rest of the system, and without the need to maintain two parallel data structures.

Because Syte is a relatively new startup company, its engineers could design the tightly coupled display subsystem from the start to fit within the overall system architecture. But, working for an established organization such as Tektronix, which has the constraints of an established product architecture, calls for different tactics. Such is the case for Tektronix engineers in Wilsonville, Ore concerning their design of the 4115B graphics terminal.

Popping the bottleneck cork

The design goal of the 4115B is to increase the performance level of the 4113 graphics terminal from the normally adequate 2-s response time to "instantaneous" response. This requirement is due to user exposure to powerful single-unit systems, which allow functions to be performed locally and thus require realtime response.

The 4113's bottleneck appeared because the central processor (the 8086) was severely overloaded and the vector-generator hardware was idle most of the time. To remedy this, Tektronix engineers opt for the bitslice route instead of using a fast 32-bit micro. The vector-generator hardware is replaced with a microprogrammable bit-slice "picture processor." This allows the lower level graphics-processing functions to be off-loaded from the 8086. Along with the bitslice processor, the picture processor contains several hardware accelerators for speed-critical tasks. The entire "update" is constructed to fit onto two standard-sized cards.

The 4115B picture processor is an instruction-set processor that executes programs (display lists) built by code running on the 8086. The initial specification of the display-list format was done by software engineers who wrote the original 8086 code, and by

the micro coders who would implement the instruction set. While the specification evolved along with the implementation, task partitioning between the 8086 and the picture processor did not change drastically after the first specification.

As in the 4113 and the 4115B, the 8086 comprises the multitasking operating system, host communication, peripheral management, and display-list management functions. The code in the 4115B, however, differs significantly from that of the 4113 in several key areas. For example, many data paths are 32 bits wide in order to support the 32-bit coordinate space. Also, new algorithms and data structures allow faster, more space-efficient creation of many small graphics segments. New code is also used to drive the hardware dialogue overlay and cursor overlay (not present in the 4113). Moreover, an additional 8087 numeric coprocessor is used for the wide arithmetic operations needed to generate graphics-image transforms for the picture processor.

One 32-bit workstation uses an "ideal" combination to produce one of the industry's fastest and highest resolution displays.

The picture processor executes commands from a display list that is resident in system memory. It transforms graphics primitives, described in a 32-bit integer coordinate space, into 1280- x 1024-pixel screen-coordinate space, and clips the results to rectangular view ports on the screen. It scan-converts the transformed primitives and writes pixels into the frame buffer. Using information from the display list, the picture processor also controls the appearance parameters (eg, primitive attributes such as line style, filled or hollow areas, and background transparency of dot-matrix characters).

Since the picture processor is an independently executing processor, it must gain access to the system bus and perform data transfers to and from system memory and I/O devices. In the 4115B, the details of these low level operations are hidden from the microcode. Two hardware state machines (both resident in a single registered programmable array logic IC) implement the bus-acquisition and datatransfer protocols.

A single microinstruction activates the machines. The microcode can then continue executing until it needs the results of a bus read, or until it tries to start another bus operation. At that time, a hardware "wait" mechanism temporarily halts the picture processor until the original cycle is completed. Thus, microcode does not have to test any status flags to see if a transfer is completed before starting another transfer.

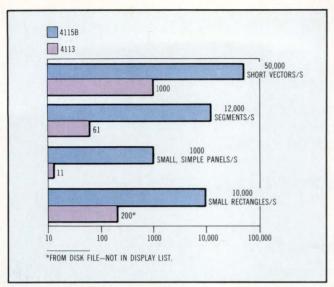


Fig 2 When Tektronix engineers enhanced the 4113 graphics terminal with a picture processor and added special microcode to the 8086 processor, the result was the 4115B terminal featuring a 32-bit coordinate space. When comparing the system performance of the two terminals in terms of the amount of elements that can be drawn per second, the 4115B excels considerably.

To assist in the transformation of points from 32-bit terminal-coordinate space, the picture processor also features low cost, serial/parallel multiplier hardware. Like the bus-transfer circuitry, this hardware is activated by, and can operate in parallel with, microcode. Moreover, to achieve the desired processing speed, up to 48- x 48-bit multiplications are performed using multiple passes and partial-product accumulation in microcode.

Testing a design's value requires a quantitative metric against which system performance is measured. For the design of the 4115B, senior engineer Douglas Doornink and his design team at the Tektronix Information Display Division establish performance metrics according to the product's target areas. The metrics measure the per-second drawing speed of vectors, segments, and simple

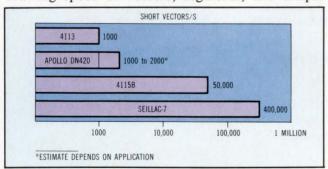


Fig 3 The performance of the 4115B can be compared to the performance of other architectures by using just the speed at which short vectors are drawn as the metric. For the relatively limited amount of upgrading done on the 4113 terminal, the 4115B fares well above the Apollo DN420. However, it does not approach the speed of a Seillac-7, where the operations are performed through a pipeline architecture.

panels. All vectors and panels have two-dimensional transforms applied to them as they are drawn.

From analyzing sample pictures from typical applications, the team determines that the average vector length is about 10 pixels on a 1280 x 1024 display. Pictures in this category have an average number of vectors equal to 30,000. Pictures with longer pixels have typically fewer vectors. In the worst case, an application may have only one vector per segment; in the best case, all vectors would be in one segment. According to Doornink, because the picture processor incurs significant overhead for each segment, both cases require benchmarking.

Another important picture type is that using simple panels. A simple panel is defined as a panel having fewer than 16 edges. One implementation of a simple panel is in a solids model, where a mesh description is used and the image is generated with many quadrilaterals. For these image types, the quadrilaterals have an area of about 100 pixels. There are other applications such as VLSI computer aided design, in which the panels to be filled are even simpler and can be rendered by rectangles. Because of this, another benchmark for the rectangle fill performance is needed, again using rectangles within an area of 100 pixels.

The performance gains from adding a microcoded picture processor are dramatic, as shown in Fig 2. Some performance comparisons to four other architecture types are also included. Overall, the 4115B fares well compared to the more conservative approaches (Fig 3).

"Ideal" combination makes a fast display

For its part, Saber Technology Corp develops its 32-bit workstation using an "ideal" combination of the NS32032, the Unix operating system, and a proprietary circuit technology called QSEL. The result is one of the industry's fastest and highest resolution displays—a 19-in. video monitor with a 60-Hz noninterlaced refresh rate that can address bit-mapped graphics with a full gray-scale resolution of 1664 x 1248 pixels.

To complement its high resolution monitor, a graphics subsystem is designed to support the 2-million pixel image for ultrahigh resolution. And, to meet the needs of three-dimensional design and solids modeling, the graphics subsystem architecture is based on a proprietary high bandwidth bus structure (Fig 4).

The system provides true bit-mapped graphics and allows control of any pixel placement and movement. The graphics subsystem can take data (eg, a design) directly from mass storage by bypassing the CPU, and bring it to the video display very quickly under DMA control. The image memory unit is comprised of image planes designed to the 2-million pixel density of the display. The basic subsystem can contain up to eight image planes.

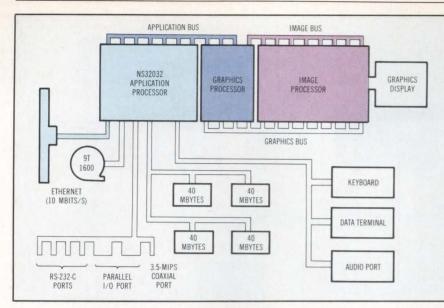


Fig 4 An example of 32-bit microprocessor power combined with innovative circuitry for display on a high resolution screen (1664 x 1248 pixels with a full gray scale) is Saber Technology's Interactive Graphics Computer System (IGCS). An NS32032 running at a 10 MHz controls the graphics subsystem, which uses a proprietary 20-Mbyte/s bus and OSEL circuit technology as a fast graphics buffer. The Berkeley Unix operating system, Ethernet, and IBM coaxial connections ensure that the workstation is a standalone unit and an integral part of a computer aided engineering network.

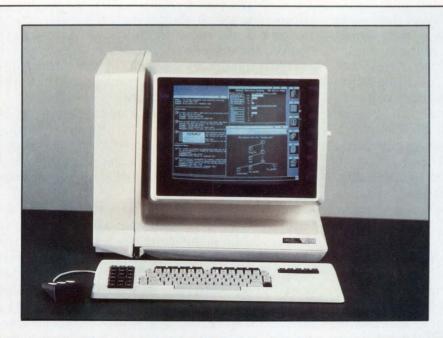
Expansion is available for a total of 24 image planes. The image subsystem supports a unique ultrahigh speed display interface providing 180-MHz video with 24-bit color resolution. Each primary color has an effective 8-bit conversion at the very high video data rate. The rate results in a pixel time of less than 6 ns.

The NS32032 used in Saber's workstation runs at 10 MHz and processes at approximately 1.2 million instructions per second (MIPS). The system also has a high performance floating point coprocessor. Saber has designed its own memory access (DMA) system. The DMA has a 20-Mbyte/s transfer rate and 8 variable-burst length, dynamically relocatable channels. All DMA devices are first in, first out (FIFO) buffered.

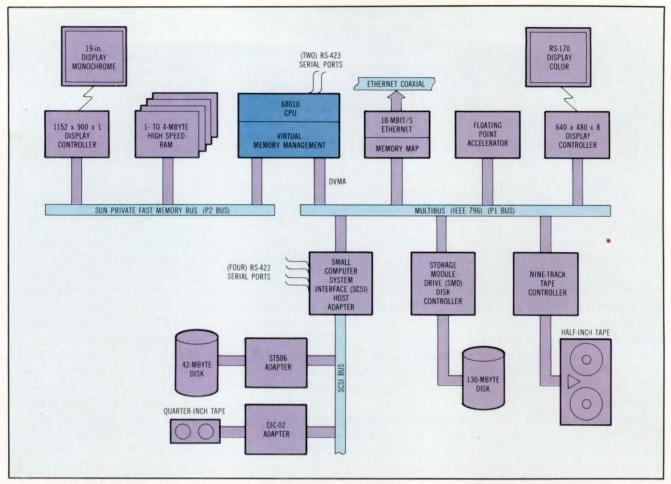
Saber's system, dubbed the Interactive Graphics Computer System (IGCS), has two independent disk controllers, each on a separate DMA channel with its own disk subsystem. One is allocated to the Unix operating system, the other is used for applications. Each disk subsystem can support four drives.

Meanwhile, Apollo Computer adds a 32-bit workstation as another node for its proprietary Domain network. The company dubs the Domain as a distributed processing system designed for both generalpurpose and interactive graphics applications.

In essence, the network is a collection of powerful personal workstations and "server" computers interconnected by a high speed LAN. Both workstations and server computers can run very large and complex applications. The personal workstation is provided with a high resolution, bit-mapped display. Therefore, each user can display the output of programs written in Fortran, C, or Pascal. A Domain server processor can act as a file or peripheral server, as well as a gateway to other networks. All workstations and server processors share a common



The Apollo DN320 workstation distinguishes itself by incorporating a standard hardware floating point processor. The processor is implemented in bit-slice technology. This allows structuring of both 32-and 64-bit floating point data formats that adhere to the IEEE standard. As another node in the Domain network, the DN320 offers each user 1.5 Mbytes of main memory, 16 Mbytes of virtual address space and a 1024- x 800-pixel display. A 68010 is used as the central processor.



Adherence to an open-system architecture and to industry bus standards is a design requirement for the Sun-2. Using the IEEE 796 Multibus specifications for the card cage and backplane, the unit divides its tasks between the two respective connectors. P1 is used for 1/0 access to a wide variety of peripherals, while P2 provides access for high speed data transfers to both main memory and display memory.

network-wide virtual memory system that allows groups of users to share programs, files, and peripherals.

Like the networks from Syte and Sun Microsystems, the Domain station consists of three main parts: a powerful processor with a large virtual address space, a high speed cache, and a high resolution, bit-mapped graphics display subsystem. Moreover, the workstation supports a full 256-Mbyte virtual address space. Thus, applications that exist on mainframes or superminicomputers can be converted to the Domain system with minimal effort, according to Dave Nelson, Apollo's vice president of research and development. The structure of virtual memory is based on objects that are 32-bit, byte-addressable virtual address spaces and accessible from anywhere in the network.

It's all part of the domain

To explain the advantages of object-based systems, Nelson comments, "In conventional timesharing systems, separate mechanisms are frequently used to implement similar system functions." For example, Nelson points out that programs may be managed by a paging system, whereas data files are accessed and handled through a file system. Thus, two distinct system mechanisms exist to handle similar system entities. In contrast, he notes, a Domain-type system deals exclusively with objects without regard to their physical location on the network or their specific functions. According to Nelson, the object abstraction simplifies the overall system design by casing all system entities into a common framework and by managing them with a common set of mechanisms.

The DN320, for example, can execute up to 24 concurrent processes with 16 Mbytes of virtual address space per process on the terminal's multiwindow display. Standard within the DN320 is a floating point unit implemented in microcoded bitslice technology.

Sun Microsystems' workstations sport similar features. Based on the 68010 and, when available, on the 68020 32-bit architecture, the Sun-2 can also use up to 16 Mbytes of virtual address space per process. As a fairly new startup company, its engineers go to excruciating extremes to make sure their design adheres to popular standards (Fig 5). This will allow future Suns within the same family to communicate, and thus stay transparent to technology innovations.



As with other standalone workstations, the Sun-2 family runs on a Unix derivative that allows each station to operate without a separate disk storage unit. Instead, diskless nodes use the Ethernet network to perform demand paging as well as routine file 1/0. The 68010-based workstation is designed for easy upgrading to true 32-bit computing power when the 32-bit (both address and data) 68020 chips become available.

Currently, Sun-2 workstations operate the 68010 processor with a 10-MHz clock. At this high clock rate, most microprocessor systems are limited by the speed of their main memory because the CPU must incur one or more wait states on every access to memory. These states are essentially wasted clock cycles. While some designs attempt to relieve this problem by introducing expensive high speed cache memory access, Sun engineers use a custom memory management unit (MMU) that allows the processor to access all of main memory without wait states. In effect, this turns all of main memory into cache.

The MMU implements two-level address translation for virtual memory operations, providing both segment and page addressing. The MMU hardware supports multiprocessing by having separate read, write, and execute commands for both the operating system and the user on every memory page. Optimizations for the company's Unix operating system include referenced and modified bits for each page of memory to facilitate efficient demand-paging algorithms, and hardware support for eight separate contexts to facilitate rapid process switching.

Unix is emerging as the standard operating system for this new generation of professional workstations. This is largely due to the popularity of the PDP-11

and the VAX-11—two units responsible for Unix's widespread use. But, Bill Joy, vice president of research and development at Sun Microsystems, adds a warning to the current Unix euphoria by saying, "It would be naive to assume that Unix is unqualifiedly suitable to this personal computing environment, or that the changes made in the past few years to the most advanced versions of Unix were directly applicable to the workstation environment." According to Joy, the change from a timesharing environment to a shared-resource personal computing environment requires a reexamination of the Unix system facilities on these machines.

Joy joined Sun straight from the University of California at Berkeley, where he designed and implemented the Berkeley version of Unix, called Unix 4.1 BSD. He later helped develop Unix 4.2 BSD. As such, he may be the most qualified to expand on the virtues and limitations of Unix (see Panel, "Massaging Unix for the workstation").

Variations on the Unix theme

While Sun Microsystems has placed its stake in the Berkeley version of Unix 4.2 BSD, Hewlett-Packard is gambling on an enhanced version of AT&T Bell Lab's Unix. The company's version is called HP-UX and is for the HP 9000 series 500 computers, a series based on the company's proprietary 32-bit, three-chip set. HP-UX is a combination of AT&T Bell Lab's Unix, portions of the University of California at Berkeley's Unix implementation, and Hewlett-Packard software enhancements. Because Unix is easy to implement on a variety of processors and computer architectures, Hewlett-Packard engineers see it as the ideal choice. Moreover, it is compatible to the distinct architecture of current HP 9000 products: the 68000-based series 200 and the company's 32-bit based series 500 computers. HP-UX is also planned for future products.

Obviously, HP-UX facilitates easy importation of Unix-derived programs onto Hewlett-Packard equipment, and offers users a consistent, powerful program development environment. Complementary extensions address the company's own manufacturer's productivity network (MPN). It reflects the company's view of how computer systems can be used in manufacturing organizations to improve productivity.

Rather than implementing every function of system III Unix, Hewlett-Packard software engineers include features that are important for either porting standard software or for their absolute program development value. With these guidelines, a compatibility hierarchy is used in which kernel services have the highest priority. Library subroutines have the second choice, and commands have the third choice. As a result of this approach, HP-UX includes all System III kernel intrinsics and all libraries except for a handful of graphics subroutines. More than

"Massaging" Unix for the workstation

Unix is available today on all major 16-bit and soon-to-be-available 32-bit microprocessors, all vying for use in high performance workstations. It is the dominant system on the Motorola 68000 family. And, with the forthcoming high performance 32-bit chips, Unix will be available on a mature architecture where an individual workstation will pack more performance than the large time-shared DEC VAX-11/780. This turn of events will put new demands on Unix, because it needs to change to meet single-user system needs, rather than spend its efforts trying to apportion an overloaded time-sharing system.

Bill Joy, vice president of research and development at Sun Microsytems, places his bets on a new version of the Berkeley 4.2 BSD as the predominant version for the 32-bit based workstations. "The standard versions of Unix in use today, Version 7, Xenix [from Microsoft], and System III from Western Electric are all similar in facilities," says Joy, "but all of these systems lack true interprocess communication primitives." He notes that while the pipe facility allows related processes to communicate in a one-directional, byte-stream fashion, the standard Unix versions lack facilities for unrelated processes to communicate, and for communication over a local network.

Debugging support

Joy contends that standard Unix also has very poor support for debugging. The only available debugger program does not support source-level debugging, but requires the inspection of assembly language and low level program details in operation. In addition, the standard Unix has little support for the smart terminals, which have become widely available and quite inexpensive. One must recall that Unix was written when the predominant terminals were hardcopy or refresh terminals. Programs only adequately supported terminals with cursor addressing and other features.

As the principal developer of 4.2 BSD, Joy says that this version addresses the various usage problems on smart workstations, expecially when these are tied in a network. Joy explains, "The 4.2 BSD system includes a number of enhancements to the earlier standard systems. First and foremost of these enhancements is full support for local networking and interprocess communications." According to Joy, this support provides full access to local network protocols, and allows unrelated processes to conveniently communicate. The system includes abstract models of both datagram and socket-oriented communication, and allows processes to perform I/O operations without blocking. The processes can thus multiplex input from and output to different streams.

In addition, the standard 4.2 BSD system includes a full implementation of the Defense Advanced Research Project Agency's (DARPA) transmission communication protocol and Internet interface protocols. Other protocol implementations are underway for the system. These include support for standard protocols, such as X.25. The 4.2 BSD system has a source language debugger (dbx) that replaces the previous assembly language expressions, the setting of breakpoints and conditional breakpoints, and other features commonly found in other commercial systems.

The 4.2 BSD system includes a terminal data base, first developed for the Berkeley version of Unix Version 7. This data base allows programs to be written independent of the terminal type being used. Joy says that this approach is quite successful, and descriptions of several hundred different terminal types are available. This allows Unix to support the wide range of CRT terminals found in the market today. The 4.2 BSD also includes support for virtual memory management, an essential requirement for supporting the large applications typical of the VAX/Unix environment. This virtual memory support also lets Unix support substantial Lisp applications. It can also off-load applications from the popular PDP-10 engine, for which the PDP-10 address space has proved to be insufficiently large.

Improvements still necessary

With all these enhancements, however, 4.2 BSD leaves room for improvement for use on workstations, according to Joy. Among the improvements Joy would like to see for the single-user environment are better access to files as server machines; a better memory management facility to accommodate the required number of individual jobs on each station; improved paging algorithms that will not degrade performance; and optimized process scheduling.

Porting to a new processor is one way to improve upon 4.2 BSD. That, however, is not an easy task. Porting requires modification of the Unix source code so that it works on another type of computer system.

According to Jeffrey Schriebman, president of Unisoft Systems (Berkeley, Calif), the most rigorous aspect of the task is porting the kernel. This is because the kernel interacts with the computer hardware more than any other part of the operating system. Anywhere from 20 to 30 percent of the 15,000 lines of kernel source code need to be changed to make Unix operational on a new CPU.

Approximately 10 to 20 percent of the kernel involves interaction with the memory management unit (MMU). This includes process creation, resource allocation, and process swapping. When a new MMU is used for an existing CPU type, this code must be redone.

Another 10 percent of the kernel code involves the device drivers. This code generally needs to be changed even for a minimal-effort port. The remaining portion (approximately 70 to 80 percent) of the Unix kernel code should pass through the porting process unchanged. This makes most of the source code the same for a VAX, a Bell 3B20, or a Motorola 68000.

While porting the Unix kernel is the most demanding part of the porting task and requires the most experience, it is only part of the job, according to Schriebman. Porting the 300,000 lines of utility software as well as the innumerable application packages presents several subtle difficulties. Also, if the target machine uses a new CPU, the source code must be checked for machine dependence.

While the popularity of Unix is increasing dramatically, so is the proliferation of different Unix versions and implementations. "Porter" engineers are thus faced with as many benefits as limitations when writing compatible software between machines.

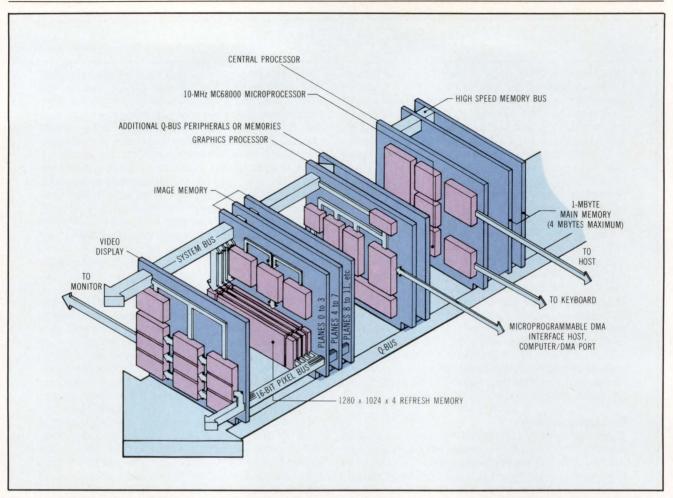


Fig 6 An example of a high resolution workstation designed on the Q-bus is the Jupiter 12. Sporting a 32-bit 68010 processor, the unit also runs the Unix operating system and connects to an Ethernet. Among the standard graphics capabilities incorporated in the single workstation through the power of a 32-bit microprocessor are anti-aliasing vectors, solids, and text. Display-list management with three-dimensional transformations into multiple windows is also available.

125 of the most useful System III commands and a small, but important number of Berkeley 4.2 BSD commands are also offered.

To satisfy customer base enhancements, programming languages, graphics, database management, device and instrumentation I/O, local area networking, and friendly user interfacing are being standardized. These extensions, which appear as additional kernel intrinsics, libraries, and commands, will bridge the gap between the company's HP-UX and non-HP-UX computers.

A matter of compatibility

According to Michael Hetrick, project manager at Hewlett-Packard's Loveland, Colo facility, perhaps the most critical issue in establishing the future course for HP-UX is its degree of compatibility with AT&T Bell Lab's Unix and the Berkeley version. Says Hetrick, "While 4.2 BSD Unix is currently the superior version, Bell is developing improved versions that could eventually surpass 4.2 BSD in capability and reliability." Also, four microprocessor manufacturers are in the process of validating System V, AT&T Bell Lab's latest Unix version, on its microprocessor products. The four companies are Motorola (Phoenix, Ariz), Zilog (Campbell, Calif), National Semiconductor, and Intel (see Computer Design, Aug 1983, p 113). System v could become the most affordable Unix and the Unix of choice for portable application programs.

In light of these factors, Hewlett-Packard engineers choose the Bell System III version as the base standard. The compatibility hierarchy will determine which portions of System v and its successors are HP-UX candidates.

Hetrick projects extensions beyond the Bell versions if these fail to meet company requirements in a timely fashion. However, he says he prefers to adopt an existing Unix-based implementation before embarking on an original design project. The potentially rich source of enhancements will most certainly come from the University of California at Berkeley 4.2 BSD version, whose features such as the C shell, mailer, and selected kernel intrinsics are expected additions.

Hetrick also says that Microsoft's (Bellevue, Wash) Xenix, with its large intalled base and a potentially well-developed source of Unix application

programs, might also influence the HP-UX operating system. This is because both Xenix and HP-UX are being selectively enhanced with Bell System V and Berkeley features to the same System III definition. Thus, conformance between the Xenix and HP-UX is likely.

Although Unix is emerging as the standard, its system facilities must be reevaluated in light of changes in the workstation environment.

In support of low cost computer systems, Hewlett-Packard engineers are also examining methods of subsetting HP-UX without sacrificing compatibility or an easy growth to the higher performance systems. Code-compaction and reduction techniques for both the operating system kernel and the diskresident commands are being considered. Under investigation is a high performance distributed HP-UX operating system that allows individual workstations to rely totally on shared-network peripherals. Thus, the cost per system is dramatically reduced, but local processing power is maintained. HP-UX will also be modified to support several European languages and the 16-bit Kanji character set. Thus, localized application program solutions will be possible.

Jupiter Systems Inc's vice president and director of technical support, Peter Harris, places his confidence in the Berkeley Unix 4.2 in more direct terms by stating, "If you were marooned on a desert island and only had one operating system to run on your workstation, it would have to be the Berkeley version." Harris was under different design constraints when developing the Jupiter 12 color raster graphics workstation. Based on a 68010, and using the Q-bus as the central data distribution channel, the workstation had to have a graphics resolution of 1280 x 1024 pixels at a 60-Hz refresh rate. The graphics also had to be accessible by many users (Fig 6).

According to Harris, "It is quite common for a team of programmers, all ostensibly working on graphics programs, to be able to share a graphics display. They all have their own alphanumeric terminal, of course, but everybody shares the single graphics screen display." In a development environment, says Harris, a large percentage of clock time will be spent on the text editor or compiling and linking. These cycles typically run from a minimum of 1 min for a small change, to all day for a major new software module. When it comes time to look at the graphics screen, adds Harris, it will only take 1 or 2 s (at worst case 1 min if things are done slowly) to actually draw the picture—the result of all the programming.

This kind of situation calls for high performance, high resolution single-user workstations. To achieve high speed and access to every individual pixel, Jupiter engineers use a high speed 16-bit ALU for coordinate transformation, and assign statements to each pixel instead of using function calls. Also, a 32-bit microprocessor provides at least 21 bits of logical addressing for 1280 x 1024 pixels, while an image memory port window is mapped to the main memory bus. The result is a station, with from 4 to 32 memory planes, that allows the user to choose between a color lookup table system with a 16.7-million color palette, or two different RGB options with up to 8 bits per color and 8 bits of overlay.

Thus, workstations currently entering the market are ready to serve high performance applications from the office desk environment. While 32-bit microprocessors play a key role in making workstations powerful entities, much remains to be done on the periphery to make these micro "stars" awardwinning performers. It still remains to be seen who has the best supporting cast.

Obtaining bus specifications

Readers interested in obtaining the latest versions of opensystem 32-bit bus specifications should contact the following individuals:

Multibus II:

John Beaston, Intel Corp, 5220 NE Elan Young Pkwy, Hillsboro, OR 97123.

NuBus:

George White, Texas Instruments, 17881 Cartwright Rd, Irvine, CA 92714.

VMEbus:

Wayne Fischer, Force Computers Inc, 2041 Mission College Blvd, Santa Clara, CA 95054.

IEEE Futurebus:

Paul Borrill, University College London, Mullard Space Science Lab, Holmbury St Mary, Dorking RH5 6NT England.

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Low 712