UNIVERSITY OF ILLINOIS DIGITAL COMPUTER

LIBRARY ROUTINE F5 - 229

TITLE

Integration of a System of Ordinary Differential Equations up to a Specified Value of One Variable.

TYPE

Closed with 3 program parameters.

NUMBER OF WORDS

60

TEMPORARY STORAGE

0, 1, 2

PURPOSE

This subroutine will integrate a system of n simultaneous first order ordinary differential equations, in which each derivative is expressed explicitly in terms of the variables thus:

$$y_{0}^{t} = f_{0} (y_{0}, y_{1}, ..., y_{n-1})$$

$$y_1 = f_1 (y_0, y_1, ..., y_{n-1})$$

$$y_{n-1}^{t} = f_{n-1} (y_0, y_1, ..., y_{n-1})$$

Integration is carried out by means of the Gill-Kutta method, described in routine Fl from a set of initial values of the variables until one specified variable y_k reaches the value Y_k . Equal step intervals are used until y_k is near to Y_k . At this time the step interval h is automatically readjusted in accordance with the rule $h=(Y_k-y_k)/y'_k$ of the Newton-Raphson method until y_k converges to Y_k with an error of at most 2^{-39} . Control is then returned to the main routine. Locations 3 through 7 must contain the preset parameters a, b, c, n, d as integers before and during input of routine F5. We must have a < b < c.

METHOD OF USE

a is the location for the first variable y₀. Other variables occupy succeeding locations so that y₁ occupies a + i. The initial values are originally placed in these locations and routine F5 alters them during the integration process.

b is the location for the first scaled desivative 2^m h y_0 . Other derivatives occupy succeeding locations so that 2^m h y_1 ' occupies b + i first auxiliary subroutine must calculate these desired vatives and place them in their locations.

c Locations c + i, (i = 0, 1, ..., n-1) are used as temporary storage by F5. These locations must be cleared before entering F5 with a new set of initial values.

n is the number of differential equations to be solved.

d is the location of the first word of the auxiliary subroutine.

Entry to F5 is made by means of the instructions

and control is returned to the left hand side of p+2. The scaling parameter m is used in the same fashion as in routine Fl and, if varied, will change the step interval h provided the auxiliary subroutine is unchanged. The program parameter a+k is the location of y_k , the variable which is brought to the value Y_k . The value Y_k must be in the accumulator at the time of entry.

The auxiliary subroutine must be provided by the user. It must be programmed as a closed subroutine using standard entry and must use the variables obtained from a,a+1,...,a+n-1 to compute each 2^m h f and place it in location b + i, for each i = 0,1, ...,n-1.

A more complete description of the method of integration is contained in the description of routine Fl. For a discussion of accuracy, scaling, and the choice of parameters h and m the reader is referred to this description.

NOTES

The time per step is approximately the same as for \mathbb{R}^n but the number of steps per entry into \mathbb{R}^n may be difficult to determine. In case y_k never reaches Y_k the integration process will not terminate.

EXAMPLE

One wishes to find values of x such that

$$y = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \frac{-t^2}{2} dt$$

assumes the values .9, .99, and .999. First write the integral as a set of first order differential equations by introducing a new variable

$$u = \frac{1}{\sqrt{2\pi}} \mathcal{L} \frac{-x^2}{2}$$

We may then write

$$\mathbf{x}^{\dagger} = \mathbf{1}$$

$$\mathbf{u}^{\dagger} = -\mathbf{x}\mathbf{u}$$

as the set of equations to be solved by F5. Initial conditions x = 0, $u = \frac{1}{\sqrt{2\pi}}$, $y = \frac{1}{2}$ may be placed in S3, 1S3, 2S3 before

starting the integration. The entry

may be made repeatedly with .9, .99, and .999 in the accumulator to obtain the corresponding three values of x. The initial conditions need not be reset.

DATE December 7, 1970	
PROGRAMMED BY E. Muller	
APPROVED BY XE, Muller	
REVISED BY RIFLLIMER	9/22/

LOCATION	ORDER	NOTES	PAGE 1
	00 K		
	00 K 26 1000N (F5)		
	L5 5F	h	
0	L4 6F		
,	00 20F	-c+n in 53	
1	46 53L		
2.	L5 3F	Ħ	
2	42 54L		
7	00 20F	a in 54	
3	46 54 L		
4	L5 4F	K	•
4	LO 3F		
5	42 55L	-b-a in 55	
5	00 20F		
6	46 55L		
0	L5 5F	5	
7	LO 4F		
. (42 56L	-c-b in 56	
8	00 20F		
O	46 56 1.		
9	L5 58L		
;	22 1014F	End of interlude	
10	40 1F		
10	LO 59L	y_k in 1	
11	40 2F	K	
	L3 F	$y_k - Y_k$ in 2	
12	10 (m)F	A A	
	L6 2F	Is $ Y_k - y_k < h y'$, ? <
13	32 38L		
	L3 2F	Is $ Y_k - y_k < 2^{-39}$?
14	F4 57L	11. 11.	
3	36 (p+2)F		
15	50 57L		
· • • • • • • • • • • • • • • • • • • •	L5 2F		
16	00 (m)F	$-K = \frac{Y_k - y_k}{h y'_k}$	
	66 F	Y ₁ -y ₁	

F5

LOCATION	ORDER	NOTES	PAGE 2
17	S5 F		
/	40 58L		
18	22 3 8 L		
	50 58 L		
, 19	L5 (q _{i,j})F		
	40 1F		
20	79 (k _{i,j})F		
	40 F		
21	LO (1)F		a.
	LO 1F	(k _{i,j} - B _j q _{ij})	
22	40 2F	ل ل لو ـــ	•
	50 (A _j)F		•
23	7J 2F		
	L4 2F		
24	10 (m) F	$(k_{ij} - B_j q_{ij}) (A_j + 1) 2^{-m}$	
	40 2F	20 0 20 0	
25	L4 (y _{ij})F		
	40 (y _{i,j+1}	F step y _i	
26	L5 2F		
	50 57L		
27	00 (m)F	from r _{i,j+l}	
	40 2F		•
28	50 (c _j)F		
	7J F		
29	LO F		
	L4 1F	$C_{j} k_{ij} - k_{ij}$	
30	L4 2F		
	L4 2F		
31	L4 2F		
	40 (q _{i,j+1})	F q _{ij} + 3 r _{i,j+l}	
32	L5 25L	$\prod_{i=1}^{n} A_i$	
	L4 29L		
33	42 25L		
	46 25L		
34	L4 55L		
	46 20L	· · · · · · · · · · · · · · · · · · ·	

LOCATION	ORDER		NOTES	PAGE 3
35	L4 56L			
-	42 31L			
36	46 19L		Step addresses depending on	i until i = n
	LO 53L			_
37	32 18L			
	50 37L			
38	26 S7			
	L5 (49)L		П	
39	42 38L			
	32 8L			
40	46 21L			
	10 10F		Increase j and adjust addr	esses depending
41	L4 34L		on j	
	42 22L			
42	46 28L			
	L5 54L			
43	26 33L			
*** €	00 F	•		·
44	40 F			. Links and the second
*	00 F	1/2	c ₀ , c ₃	1000
45	NO F			
	00 F	- 1/2	A _O	E.S. C.
46	40 F			
	00 207106	i 7811 8 6j 1/	$\sqrt{2}$ C_1 , A_2	
47	80 F	,	<u> </u>	of the state of th
	00 292893	 218814J <i>-</i> 1/	A_1, C_2	085 CM
48	80 F	. · ·	1 2	. P. CO W.
	00 166666	666667J - 5/	6 A ₃	
49	LJ 1025F	-11, 1,		
	06 1074L	25, 50L	vide Straight	Tab 25
50	LJ 3129L	-9,2,27, h	Maria de la Carta	<u> </u>
	06 3123L	51L	, A	
51	LF 57L	-8,2,26,		**************************************
	06 2100L	52L		िखंड. . :
	- Table			

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LOCATION	ORDER		NOTES	PAGE 4
52	LJ 1025F	-11,1,28,		
)E	07 53L	53L		
5.7	64 (c+n)F			
53	00 49L			
54	80 (a)F			
74	00 (a)F		End constants set by interlude	
55	00 (a)F			
)) ·	00 (b-a)F			
56	00 (c-b)F			
	00 (c-b)F			
57	00 (C-D)F			
71	00 F	zero		
58	00 F			
	26 L			
	26 IN			
0	40 59L		Y _k in 59	
	K 5F			
1	46 12L			
	46 16L		m in 12, 16, 24 and 27	
. 2	46 24L			
*	46 27L			
3	42 5L		p+l in 5	
	F4 57L		link in 14	
4	42 14L			
	I'A AAT		K in 58	
5	40 58L		Ц	
	L5 (p+1)F		a+k in 9	
· 6	42 9L		Ц	
	L4 55L		b+k in 8	
7	42 8L		Η	
•	50 7L		-Enter Auxiliary	
8	26 87		Ц	
	L5 (b+k)F		2 ^m h y' _k in 0	
9	40 F		μ -	
	L5 (a+k)F			
	01 60 K	1		and communicated and control control control