

I/O Dataspec.

PRODUCT Analog Input

MODEL 620-850 thru 853

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varian data machines

ANALOG INPUT MODULES

INTRODUCTION

The Models 620-850 through -853, Analog Input Modules (AIM) are options for use with the Varian 620 series and V73 computers. The AIM provides an analog multiplexer (MUX), analog-to-digital converter (ADC), sample and hold amplifier and programmable timer.

The MUX accepts middle or high level analog signals which are sequentially or randomly selected, sampled and held for conversion by the ADC. The ADC outputs a 13-bit or 10 bit word in binary two's complement format to the computer. The timer can be used to establish time intervals for system control.

GENERAL DESCRIPTION

The MUX transfers external analog signals in differential or single-ended form to the ADC. The content of each analog MUX channel addressed is converted to an equivalent 13-bit or 10-bit digital value. The AIM is designed to function in either of two operating modes: Sequential or Random. The Sequential Mode allows the MUX channels to be scanned and sequentially selected. Each scan starts with the first channel and a channel advance signal increments the MUX to the next higher channel. At the end of a scan cycle, the MUX is set to the first channel and an end-of scan interrupt is provided.

The Random Mode allows the MUX channel address selection to be determined under computer program control. This mode permits the selection of MUX channels in any sequence.

The ADC employs the successive approximation technique for conversion. Its conversion rate is 13 microseconds for 13 bits with a sample-and-hold-amplifier settling time of 6 microseconds, thus providing a 50 kHz throughput rate or 5 microseconds for 10 bits with the same sample-and-hold amplifier settling time, thus providing 100 kHz throughput rate. The ADC can be initiated by the computer, the Programmable Timer or an external pulse. The Programmable Timer provides an internal and external control capability.

Under internal control, the Timer sets a timing interval through a data word which it receives from the computer. The Timer decrements the data word until the zero state is reached. The Timer then emits a pulse, restores the original data word and again initiates the cycle. Under external control, the Timer can be inhibited at any time by an external signal level which holds the Timer at its load point. Timing intervals start at the instant the external signal level is removed or set to a high logic state. New timing intervals can be sent by the computer while the Timer is externally inhibited.

AIM data transfers can occur by programmed output command execution or under the optional Buffer Interface Controller (BIC) control. When operating under program control, data transfers are initiated by the computer and are executed under input/output instruction control. When operating with a BIC, data transfers are initiated by the computer and are executed without input/output instruction control. The BIC permits automatic, high- or low-speed, block data transfers between the AIM and the computer memory without disturbing the sequence of the main program.

The Models 620-850 through -853 AIM represent a minimal capability providing 16 different or single-ended analog channels. This basic configuration can be readily expanded up to 256 analog channels. The Models 620-860A, 861A Multiplexer Expansion Modules provide plug-in expansion in increments of 16 differential or 16 single-ended channels. Larger systems can be configured by repeating the AIM expansion with maximum capability up to 2048 channels.

PREREQUISITES

- 620 or V73 System Computer
- Expansion Chassis (requirements determined on individual system basis)
- 620-88 Analog Power Supply (requirements determined on individual system basis)
- 620-20 Buffer Interface Controller (BIC) (optional)
- 620 Peripheral Backplane Wiring Panel (requirements determined on individual system basis).

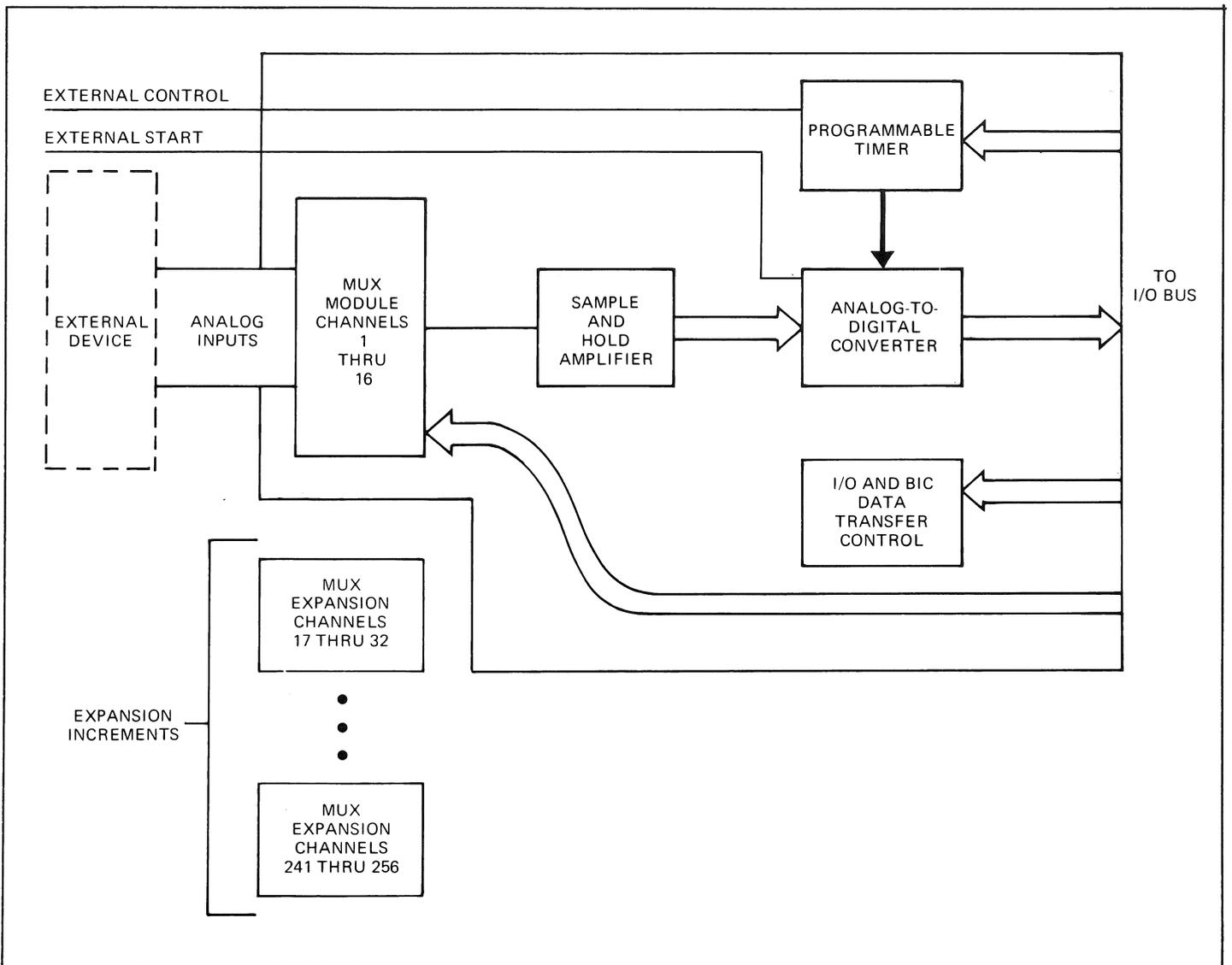
SOFTWARE

A comprehensive software package is provided comprising a Test Program and an I/O Driver Program. The Test Program is an effective tool in determining the operational status of the AIM.

The I/O Driver Program provides convenient access to the AIM without detailed knowledge of the hardware. The program can be used by itself or embedded in an operating system. The I/O Driver Program consists of the following two independent routines: Programmed Data Transfers and Direct Memory

Access Data Transfers. These routines permit the user to specify the following parameters:

- Channel selection technique (Random or Sequential)
- Last channel specification for Sequential Mode or channel list specification for Random Mode
- Destination array and quantity of incoming data
- Time between each data point.
- An error address to which control will pass when any one of several error conditions is detected.



MODULE FLOW DIAGRAM

SPECIFICATION

Multiplexer

Gain and Accuracy
 Voltage Gain +1 or +10
 Accuracy $\pm 0.01\%$ of F.S.
 Gain Temp. Coefficient ± 10 PPM/ $^{\circ}$ C

Input Specifications

Signal Voltage ± 10 V or ± 1 V
 Maximum Source Impedance 1K ohms
 Common Mode Voltage plus
 Signal Voltage ± 10 volts
 Absolute Maximum ± 15 volts

"ON" Channel Specifications

Switch Impedance 500 ohms (typical)
 Input Impedance 10^9 ohms, 80 pF
 Common Mode Rejection 80 dB, 0 to 60 Hz

"OFF" Channel Specifications

Impedance 10^{10} ohms, 4 pF

NOTE: All switches open when power is turned off.

Output Specifications

Output Voltage Range ± 10 volts
 Output Current 100 mA
 Output Impedance 20 ohms
 Voltage Drift ± 50 μ V/ $^{\circ}$ C

Dynamic Response

Frequency Response (Tracking error with
 F.S. peak-to-peak sine
 wave applied to a single On
 Channel. 1K source impedance)

Accuracy of .01% 250 Hz
 Accuracy of .1% 2500 Hz

Crosstalk

ON Channel 1K to ground < 1 mV. F.S. peak-to-peak 1
 kHz sine wave applied to 15 OFF Channels.

Settling Time to .01% of 10 volts: 10 microseconds.
 (Switching between two channels with dc voltage of +10V
 and -10V on each channel respectively).

Digital Outputs

End of Scan Low True Signal
 which begins when the ADC starts
 to convert the data for the
 "Last Channel" of the Multiplexer
 Sequential Mode, and ends when
 the ADC starts to convert the
 next time. Held High when the
 Multiplexer is in the Random Mode.
 Fanout: 10 logic loads. Maximum
 capacitive load: 1000 pF.

Control Flip/Flop R-S flip/flop which is set High
 True by the EXC 3YY, and is
 reset by EXC0YY, EXC1YY, EXC2YY
 or System Clear.
 Also may be wire-ored and reset
 by pulling down the output.

Analog to Digital Converter

Resolution 13 or 10 binary bits
 Output Format two's complement
 Conversion Accuracy $\pm 0.012\%$ of Full Scale
 $\pm 1/2$ LSB
 Conversion Time . 13 microseconds, maximum (13 bits)
 5 microseconds, maximum (10 bits)
 Throughput Rate 50 kHz, maximum (13 bits)
 100 kHz, maximum (10 bits)
 Temperature Coefficient ± 50 μ V/ $^{\circ}$ C, maximum
 Warm up Time Essentially Zero
 Full Scale Range ± 10 V

Digital Outputs

BUSY High (true) during Analog to
 Digital Conversion. Available fanout:
 8 logic loads. Maximum capacitive
 load: 100 pF.
 STORE Low (true) during the
 last 1 microsecond of the BUSY signal.
 Available fanout: 10 logic loads.
 Maximum capacitive load: 1000 pF.
 Output Enable High (true) during the
 time ADC data is on the E-Bus
 (1.90 microseconds). Available
 fanout: 20 logic loads. Maximum
 capacitive load: 100 pF.

Digital Inputs

EXT START 1K ohms to +5V,
 Lower to start ADC.
 Must raise and relevel to
 restart ACD.
 EXT SENSE 5.6K ohms to +5V, Low
 true sense input. Computer may
 test the status of this input
 with a SEN 2YY instruction.

Sample & Hold

Gain and Accuracy

Voltage Gain +1
 Accuracy $\pm 0.01\%$
 Gain Temp Coefficient ± 10 PPM/ $^{\circ}$ C

Track Mode

Full Power Response 75 kHz
 (F.S. peak-to-peak sine wave)
 Slew rate 4V/microsecond
 Settling Time to ± 1 mV 4 microseconds

Input Characteristics, Single Ended

Signal Range ± 10 V
 Maximum Rating, without damage ± 15 V
 Input Impedance ... 50K ohms in parallel with 5000 pF
 Offset Voltage ± 2 mV maximum
 VS Temperature ± 50 μ V/ $^{\circ}$ C

