WAVE MATE, INCORPORATED 280 BULLET REV F MANUAL

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I INTRODUCTION

The Wave Mate BULLET REV F is a fast, compact and very powerful single board computer (SBC). The BULLET REV F provides a 4 megahertz CPU, 128K bytes of random access memory (RAM), up to 16K bytes of erasable programmable memory (EPROM), two RS-232-C ports, a Centronics printer interface, a diskette serial interface (supporting four 8-inch, four 5-inch, and two 3-inch drives), and SCSI bus interface for Winchester disk controllers. This 4 megahertz Z80, along with a powerful direct memory access controller (DMA) for data transfer and a greatly enhanced C-BIOS, executes CP/M PLUS at a previously unheard of speed. Video display communication is provided through one of the RS-232-C ports, to which many different serial terminals may be attached. Future I/O expansion is provided through a special bus link. Because the BULLET contains two serial ports and 128K bytes of memory, an efficient and economical two-user system may be realized.

II DESIGN PHILOSOPHY

The Wave Mate BULLET REV F has been designed to be the heart of an extremely low cost, high performance microcomputer system. It is ideally suited for high performance single user CP/M and multi-user MP/M small business applications. It is also capable of providing intelligent terminal, distributed processing, and high speed local networking capabilities. Special BULLET hardware features and a greatly enhanced C-BIOS have been implemented in order to overcome limitations of the CP/M operating system encountered in most existing hardware configurations.

Since most small microcomputer systems are I/O bound (rather than compute bound), the BULLET design has addressed this fact by incorporating into its architecture a flexible DMA facility, fully interrupt driven I/O, and a high speed floppy disk controller. The 4MHZ Z80 CPU was chosen with a full complement of Zilog compatible peripheral chips. This insures a cost effective, simple design; yet unlike most other implementations, the design results in full use of the microprocessor's capabilities.

The BULLET REV F has been designed with the OEM/systems integrator in mind. Its compact size, low power requirement, and single supply voltage make it easy to incorporate into both existing and new equipment.

III HARDWARE DESCRIPTION

A. Physical Considerations

The BULLET REV F is packaged on a single printed circuit board measuring 7.875 inches (20 cm) by 10.7 inches (27.2 cm). Mounting holes .156 inches (4 mm) in diameter are provided .250 inches (6.4 mm) from the corners. The maximum height of the board, considering pin lead protrusion through the board on the underside as well as component height, is .625 inches (15.8 mm). Additional height must be provided for the header connectors for the I/O and power; however, all connectors have been placed on the component side of the board. Component and connector identifiers have been silk screened on the board.

B. Electrical Requirements

The BULLET REV F requires only one regulated 5 volt power supply, which under normal room temperatures need supply only 1.5 amps. Actual current consumption depends upon use of the optional EPROM and whether the SCSI bus is being used. The plus and minus voltages, required for the RS-232 operation, are generated on the board itself.

For power, an AMP connector, part # 350211-1, has been mounted on the board. The mating connector, supplied by the user, must be an AMP part # 1-480424-0 with AMP contacts #60617-4 or equivalent. OEMs that require a low profile power connector should contact Wave Mate regarding an optional connector. If a switching power supply is used, the board and ALL disk drives MUST be shielded from noise.

- C. CPU, DMA, and Interrupt System
- 1. Central Processing Unit (CPU):

The Zilog Z80 CPU device is clocked at the maximum four megahertz rate with no memory wait states.

2. Direct Memory Access (DMA) Facility:

There is a Zilog DMA controller on the BULLET REV F. This device provides for data transfer from/to any memory location or I/O device at rates of up to one megabyte per second. External logic is provided which allows transfers from/to any RAM memory bank at the same data rate. It should be noted that only the RAM memory is accessible to the DMA devices, EPROM and ROM memory are not in the DMA map.

External device multiplexing allows both the floppy disk controller and the SCSI bus interface to use the DMA channel and controls transfers between the memory banks. Device selection and memory control is selected through an external write only register. I/O port addresses for the DMA controller and the external control register is as follows:

1A HEX DMA channel 0 status/control

14 HEX DMA channel 0 external control

DMA I/O device selection and memory control are programmed into the external control register and are defined as follows:

BIT 1 DEVICE

0 FDC floppy disk controller 1

SCSI bi-directional bus

RAM memory control of DMA operations is selected according to the following fields:

Select source bank Bit 4 Bit 6 Select destination bank

The source and destination RAM memory bank selection bit fields are defined as follows:

0 Bank 0 1 Bank 1

The remaining bits in this register are unused. Note that when a transfer is between an I/O port and memory, the memory control bit fields for both the source and destination must be programmed the same and must contain the desired memory bank number for the I/O. Care must be exercised if the software desires to move only one byte by using the DMA byte mode and the force ready command. If the DMA senses external ready when it is enabled, the full byte count plus one will be immediately transferred when the DMA is enabled. To avoid this, the software must check the state of the external ready pin and program the DMA to transfer on the opposite ready condition. Then when the force ready command is issued, only one byte will transfer if byte mode has been programmed.

The bus request priority out line of DMA1 is present on the external bus connector as *BAO, and additional DMA devices may be added. If additional DMA devices are added, they will be of lower priority and will not have access to the special hardware on the board which allows efficient memory to memory data moves and I/0.

3. Priority Interrupt Structure:

All peripheral devices are connected to the standard Zilog interrupt priority daisy chain. The priority interrupt daisy chain is provided with look ahead logic which terminates on the external bus connector. Thus any devices added to the external bus may use the priority interrupt daisy chain. When using the

interrupt daisy chain, the Z80 must be programmed in interrupt mode 2 (IM2). The priorities are shown below, from the highest priority to the lowest:

- 1. DMA
- 2. DART with FDC on the B level
- 3. PIO with Centronics and SCSI
- 4. Clock Timer Circuit
- 5. External Devices
- 4. I/O Port Assignments:

The following chart summarizes the I/O port assignments.

PORT	DEVICE
0 1 2 3	DART Channel A Data DART Channel A Status/Control DART Channel B Data DART Channel B Status/Control
4 5 6 7	PIO Port A Data PIO Port B Data PIO Port A Control PIO Port B Control
8 9 A B	CTC Channel 0 CTC Channel 1 CTC Channel 2 CTC Channel 3
10 11 12 13	FDC Command/Status Port FDC Track Register FDC Sector Register FDC Data Register
14	External DMA Control Register (Write only)
16	External FDC Register (Hardware Control)
17	Memory Map Select Register (Write only)
19	SCSI Bi-directional Data Bus
1A	DMA Status/Control
18	Hardware Status Register (Read only)

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D. Memory System

1. Random Access Memory (RAM):

There are 128K bytes of random access memory on the BULLET REV F. The memory is physically organized as two 64K banks. External support logic allows the DMA devices to directly access anv location within this 128K memory system. Although the DMA device can move data from/to any address within the 128K bytes of RAM on the BULLET REV F, the Z80 can only address 64K bytes at any one To provide greater versatility, memory mapping of the CPU time. address space is provided through an I/O port. There is a common memory area which is always in the CPU's context. The CPU's common memory is from CO00 HEX to FFFF HEX. This is equivalent to 16K bytes of address space. The remaining 48K of CPU address space may be mapped from one of two banks of 48K. The remaining 16K of RAM may be mapped in from 8000 HEX to BFFF HEX as a system space for the MP/M operating system. Note that the state of the CPU memory map does not affect the DMA operations; that is, the memory banks are constant for the DMA device as it can access the full 128K of RAM memory. For example, assume two CPU memory maps each contain a program, and the currently executing program requests the operating system to read a sector. The operating system could initiate a DMA read sector operation to transfer the data from the disk to the user space. The operating system could then switch CPU address banks and start the second program executing while the DMA operation was being performed, without affecting the transfer of data to the first program.

Selection of the CPU memory map is accomplished by outputting a map code to the Segment Register at I/O port 17 HEX. The function of the map code bits is as follows:

SEGMENT REGISTER CONTROL FUNCTIONS:

Bit H	Function
-------	----------

4	Select system space overlay: 0 = no overlay
	l = overlay
0	Select active bank (non-common memory):
	0 = Bank 0 is selected
	l = Bank l is selected

The address mapping function of the Memory Map Register contents is shown in the following table:

	0000-3FFF	Logical CP 4000-7FFF	U Address 8000-BFFF	C000-FFFF
Segment Register	bank/seg	bank/seg	bank/seg	bank/seg
0xxx0 0xxx1 1xxxx	B0,S0 B1,S0	B0,S1 B1,S1	B0,S2 B1,S2 B1,S3	B0,S3 B0,S3 B0,S3

Key to physical "bank/seg" mapping:

в0	Physical	Bank	0	S0	Segment	Ο,	0000-3FFF	
Bl	Physical	Bank	1	Sl	Segment	1,	4000-7FFF	
				S2	Segment	2,	8000-BFFF	
				S3	Segment	3,	C000-FFFF	
					-	•		

2. Read Only Memory (ROM):

Initial program loading (the boot process) may be done from a flexible diskette by a 32 byte program in ROM. This function is selected by switch four on SW1. Upon power up or reset, if this switch is OFF, the ROM is mapped into a starting address of zero which is the Z80 starting address after power up reset. In addition, reset enables switch selection of the floppy disk boot parameters. The boot device and mode are determined by the settings of the 8-position DIP switch on the BULLET REV F. The physical disk unit number is always unit zero regardless of whether it is a 3, 5 or 8 inch drive. The ROM location is read only, a write to its address space will be placed into RAM. The function of the ROM is to read the first sector from track zero into RAM memory starting at address zero. When this is achieved with no disk I/O error, the ROM starts executing the code at location 32 HEX. At any time after a reset, an input or output to the port address 1A HEX (the DMA port) will disable the ROM and it will no longer be accessible until another reset occurs.

3. Erasable Programmable Read Only Memory (EPROM):

A location for an optional EPROM is located at socket Ul31. This socket is configured as an Intel Universal Memory Site. It accepts either a 24-pin 2732A, or 28-pin 2764, or 28-pin 27128 EPROM. Selection of the type is controlled by jumper option. Refer to the section on switches and jumpers for configuration data. If an EPROM is installed, it may be selected as the reset program by setting SWl switch four ON. If this option is selected, the program starting at location zero in the EPROM will execute upon reset. At any time after a reset, an input or output to the port address IA HEX (the DMA port) will disable the reset mapping of the EPROM. The BULLET REV F is shipped without EPROM unless special OEM arrangements have been made. E. I/O System

The I/O system is partially decoded on the BULLET REV F. Seven bits of the I/O space are decoded, thus all unassigned port addresses from 20 HEX to 7F HEX may be used by external hardware. The I/O space from 20 HEX to 2F HEX is set aside for OEM manufactured devices, and the space from 30 HEX to 3F HEX is reserved for Wave Mate developed peripherals. The space from 40 HEX to 7F HEX is currently unassigned.

1. Hardware Status Register:

A read only hardware status register at port 1B HEX is provided to check the state of the following functions:

BIT STATUS FUNCTION

- 0 Centronics Busy Bit
- 1 DIP switch 2
- 2 DIP switch 3
- 3 *Floppy disk two sided
- 4 Floppy disk head load status
- 5 *Floppy disk exchange (8-inch only)
- 6 FDC interrupt request line
- 7 FDC data request line

2. Floppy Disk Controller/Formatter (FDC):

This device is a Synertek SY1793-002. It is upward compatible with the Western Digital FD1793 controller. The following I/O port addresses are assigned to this device:

- 10 HEX Command/Status register
- 11 HEX Track register
- 12 HEX Sector register
- 13 HEX Data register

Since this is not a Zilog device and not capable of generating or responding to the Zilog priority daisy chain interrupt, it is connected to the DART *RIB (ring indicator B) input to provide an interrupt vector. External logic provides for control of four 8-inch floppy disk drives, four 5-inch floppy disk drives, and two 3-1/2-inch floppy disk drives. The external logic also provides for software control of the spindle motors (5-inch and 3-inch drives only), and side select. These functions are controlled by a write only register. The following table gives the FDC external control port addresses and bit definitions:

FDC DISK CONTROL REGISTER, PORT 16 HEX:

Bits 0-3	Unit select number, as follows:
	0, 1, 2, & 3 are the 5-inch drives; 4, 5, 6 & 7 are
	the 8-inch drives, and 8 & 9 are the 3-inch drives.
Bit 4	Set to select side 2.
Bit 5	Set to disable 3 & 5 inch spindle motors.
Bit 6	Set for 1 MHZ controller operation, reset for 2 MHZ

- Bit 6 Set for 1 MHZ controller operation, reset for 2 controller operation.
- Bit 7 Set to select single density operation, reset to select double density operation.

The FDC device is capable of formatting and reading a wide variety of soft sectored diskettes. With 8-inch drives, it is compatible with the IBM 3740 format and FM recording and the IBM System-34 format and MFM recording. With 5-inch drives, it is compatible with both single density and double density soft sector formats. Data separation for all modes is provided by a digital data separator circuit.

3. Dual Asynchronous Receiver/Transmitter (DART):

This device provides two independent asynchronous serial data channels. Each channel has an independent baud rate which is derived from the first two channels of the counter timer circuit (described in the following section). These baud rates are determined by the CTC and DART programming and can range from 110 baud to 76.8 kilobaud. In addition, the transmit/receive word parameters are fully programmable within the DART. Channel A and B of the DART provide a full implementation of the RS-232-C interface type E, with the exception that there is no circuit CE (ring indicator). Channel A of the DART is normally used for the system console. The channel B ring indicator input is used by the floppy disk controller to request an interrupt vector on the Zilog daisy chain interrupt system. The DART is the second device on the interrupt priority daisy chain, following the DMA device.

The DART registers are at the following port addresses:

0 HEX Channel A data

1 HEX Channel A status/control

- 2 HEX Channel B data
- 3 HEX Channel B status/control

4. Counter Timer Circuit (CTC):

This device provides four independently programmable counter/timer channels. Channel 0 is used to provide the baud clock for the DART channel A. Channel 1 is used to provide the baud clock for the DART channel B. Channels 2 and 3 are used together to provide a real time clock capability and clock interrupts. This is achieved by using channel 2 as a timer and channel 3 as a counter. Channels 0, 1, and 2 have their inputs connected to a crystal controlled clock which provides a 1.2288 MHZ frequency. The CTC device is the fourth device on the interrupt priority daisy chain.

The CTC registers are at the following I/O port addresses:

Channel	0	8	HEX
Channel	1	9	HEX
Channel	2	A	HEX
Channel	3	В	HEX

5. Parallel Input/Output Controller (PIO):

This device provides two 8-bit parallel I/O ports. It is used to implement the Centronics interface and the SCSI bus control interface. Port B provides the Centronics data and handshake signals. Port A is used in bit mode to provide status of the SCSI bus interface. The control signal assignments presented here are further described under the applicable I/O device.

PIO PORT A, SCSI BUS CONTROL (BIT MODE):

Bit	0:	ATN	output
Bit	1:	RST	output
Bit	2:	SEL	output
Bit	3:	BUSY	input
Bit	4:	MSG	input
Bit	5:	C/D	input
Bit	6:	REQ	input
Bit	7:	I/O	input

Note that program control allows these devices to operate in either interrupt driven or polled mode. The PIO device is the third device on the interrupt priority daisy chain.

The PIO registers are at the following I/O port addresses:

4	HEX	Port	A	data
5	HEX	Port	В	data
б	HEX	Port	A	control
7	HEX	Port	В	control

6. Centronics Printer Port:

The Centronics printer interface has been implemented with the use of a Zilog PIO device. The PIO port B is programmed in output mode and provides data output and handshaking to the interface. The Centronics status is sensed in the hardware status register. When bit zero is 1 the interface is busy, when it is zero the interface is not busy. If the interface is not busy, data may be written to the PIO data port B. An interrupt may be programmed when the interface accepts the data and additional data written to port B during the interrupt service routine.

7. SCSI Bus Interface:

A SCSI bus interface is provided which is capable of controlling a variety of SCSI compatible devices. It is most commonly used to communicate with a Winchester disk controller.

The SCSI bus interface is implemented by a bi-directional data port at 19 HEX. Status and control of the SCSI is implemented with the PIO Port A programmed in bit mode, and through hardware handshaking. A read from port 19 HEX accesses the data on the SCSI data bus. A write to port 19 HEX latches the data, which will be read by the external device when it reads the SCSI data bus. Note that a read or write to this port causes the hardware to assert *ACK if enabled.

Users wishing to program the SCSI should be familiar with the operation of the SCSI as described in ANSI X3T9.2/82-2.

IV I/O CONNECTORS

1. Jl - 50 Pin General Purpose External Bus Connector:

A 50 pin male header is used to permit the Z80 CPU bus and the DMA bus to be used externally from the BULLET REV F. The pin-out of this header is shown below.

PIN 1 2 3 4 5 6 7 8 9 0 11 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	SIGNAL D0 D1 D2 D3 D4 D5 D6 D7 CLOCK GND A0 A1 A2 A3 A4 A5 A6 A7 A8 A9 A10 A11 A12 A13 A14 A15 GND *BAO N/C N/C	1/0 10 10 10 10 10 10 10 10 10 10 10 10 10	DESCRIPTION Data Bit 0 Data Bit 1 Data Bit 2 Data Bit 3 Data Bit 4 Data Bit 5 Data Bit 6 Data Bit 7 4 MHZ system clock Ground Address Bit 0 Address Bit 1 Address Bit 2 Address Bit 2 Address Bit 3 Address Bit 4 Address Bit 5 Address Bit 5 Address Bit 6 Address Bit 7 Address Bit 7 Address Bit 8 Address Bit 9 Address Bit 10 Address Bit 12 Address Bit 12 Address Bit 12 Address Bit 13 Address Bit 13 Address Bit 14 Address Bit 15 Ground Bus Acknowledge Out (DMA)
31 32 33 34 35 36 37 38 39 40 41 42 43 44	N/C *RESET *INT N/C *BSREQ *BSACK *IORQ *MREQ *RD *WR *MI *RFSH *NMI *WAIT	0 I 0 0 0 0 0 0 0 1 I	Reset Out Interrupt (CPU) Bus Request (DMA) Bus Acknowledge (CPU) I/O Request (CPU) Memory Request (CPU) Read (CPU) Write (CPU) Write (CPU) Machine Cycle One Memory Refresh (CPU) Non Maskable Interrupt (CPU) Wait (CPU)

45 46	*HALT *DMEM	0 1	Halt (CPU) Disable on board memory
47 48	*IEOUT N/C	ō	External Interrupt Priority
49 50	N/C VCC	0	+ 5 VOLTS

The female mating connector to Jl is 3M part number 3425-6000 or equivalent. The output lines are capable of driving a maximum of 4 CMOS loads or 1 TTL load. The maximum cable length to be attached to Jl cannot exceed 12 inches.

2. J2 - 50 Pin SCSI Interface Connector:

A 50 pin male header is used to connect to a SCSI bus compatible peripheral. The pin-out of the header is shown below.

PIN	SIGNAL	I/0	DESCRIPTION
2	*SDO	IO	Data Bit O
4	*SD1	10	Data Bit l
6	*SD2	IO	Data Bit 2
8	*SD3	IO	Data Bit 3
10	*SD4	IO	Data Bit 4
12	*SD5	IO	Data Bit 5
14	*SD6	IO	Data Bit 6
16	*SD7	IO	Data Bit 7
32	*ATN	0	Attention
34	*SPARE		Spare
36	*BUSY	I	Bus busy
38	*ACK	0	Acknowledge
40	*RST	0	Reset
42	*MSG	I	Message
44	*SEL	0	Select
46	*C/D	I	Command/Data
48	*REQ	I	Request
50	*I/O	I	Input/Output

Odd numbered pins 1 through 49 are all connected to ground.

The female mating connector to J2 is 3M part number 3425-6000 or equivalent. The maximum cable length to be attached to J2 should not exceed 6 meters.

3. J3 - 10 Pin Serial Port Connector:

A ten pin male header is used to attach a RS-232-C serial terminal to the BULLET REV F using the DART channel A. A ten pin male header is used to attach a second RS-232-C serial terminal to the BULLET REV F.

PIN	SIGNAL	I/0	DESCRIPTION
1	*TXDB	0	Transmit Data
2	*RXDB	I	Receive Data
3	* DTRB	0	Data Terminal Ready
4	*RTSB	0	Request To Send
5	*CTSB	I	Clear To Send
6	*DCDB	I	Data Carrier Detect
7	RLSDB	0	Receive Line Signal Detect
8	GND	0	Ground
9	*CRESET	I	Computer Reset
10	GND	0	Ground

The female mating connector to J3 is 3M part number 3473-6000 or equivalent. The above signals correspond to the Zilog DART definitions. See the cable section for recommended RS-232-C usage.

4. J4 - 10 Pin Serial Port Connector:

A ten pin male header is used to attach a RS-232-C serial terminal to the BULLET REV F using the DART channel A. When using the WAVE MATE provided C-BIOS and CP/M, this port is used as the system console. The pin-out of the header is shown below.

PIN	SIGNAL	I/0	DESCRIPTION
1	*TXDA	0	Transmit Data
2	*RXDA	I	Receive Data
3	*DTRA	0	Data Terminal Ready
4	*RTSA	0	Request to Send
5	*CTSA	I	Clear To Send
6	*DCDA	I	Data Carrier Detect
7	RLSDA	0	Receive Line Signal Detect
8	GND	0	Ground
9	*CRESET	I	Computer Reset
10	GND	0	Ground

The female mating connector to J4 is 3M part number 3473-6000 or equivalent. The above signals correspond to the Zilog DART definitions. See the cable section for recommended RS-232-C usage. 5. J5 - 26 Pin Centronics Printer Port Connector:

A 26 pin male header is used to attach a Centronics type printer to the SUPER BULLET. The pin-out of this header is shown below.

PIN	SIGNAL	I/0	DESCRIPTION
1	*CSTRB	0	Strobe
3	CDTA1	0	Data Bit l
5	CDTA2	0	Data Bit 2
7	CDTA3	0	Data Bit 3
9	CDTA4	0	Data Bit 4
11	CDTA5	0	Data Bit 5
13	CDTA6	0	Data Bit 6
15	CDTA7	0	Data Bit 7
17	CDTA8	0	Data Bit 8
19	*CACK	I	Acknowledge
21	CBUSY	I	Busy

Even pins 10 through 24 are all connected to ground.

The female mating connector to J5 is 3M part number 3499-6000 or equivalent. The maximum cable length to be attached to J5 should not exceed 8 feet.

6. J6 - 50 Pin 8-inch Floppy Disk Drive Connector:

A 50 pin male header is used to attach from one to four 8-inch Shugart 800 compatible disk drives to the BULLET REV F. The pin-out of this header is shown below.

PIN	SIGNAL	I/0	DESCRIPTION
2	*XTG43	0	Track greater than 43
10	*FD2S	I	Disk is two sided
12	*XDCG	I	Disk has been changed (door opened and
			closed)
14	*XSIDE	0	Side Select
18	*XHLD	0	Head Load
20	*INDEX	I	Index Pulse
22	*READY	I	Ready
26	*SEL1	0	Select Drive #1
28	*SEL2	0	Select Drive #2
30	*SEL3	0	Select Drive #3
32	*SEL4	0	Select Drive #4
34	*XDIR	0	Direction
36	*XSTEP	0	Step
38	*XWDAT	0	Write Data
40	*XWGAT	0	Write Gate
42	*TR00	I	Track Zero Sensor
44	* WPROT	I	Write Protect Sensor
46	*RDATA	I	Read Data

All odd numbered pins are connected to ground.

The female mating connector to J6 is 3M part number 3425-6000 or equivalent. The maximum cable length to be attached to J6 should not exceed 8 feet.

7. J7 - 34 Pin 5-1/4 Inch Mini Floppy Disk Drive Connector:

A 34 pin male header is used to attach from one to four 5-1/4 inch Shugart 400 compatible disk drives to the BULLET REV F. The pin-out of this header is shown below.

PIN	SIGNAL	I/0	DESCRIPTION
4	*MHLD	0	Head Load (jumper option)
6	*MSEL4	0	Select Drive #4
8	*INDEX	I	Index Pulse
10	*MSEL1	0	Select Drive #1
12	*MSEL2	0	Select Drive #2
14	*MSEL3	0	Select Drive #3
16	*MMTR	0	Motor On
18	*MDIR	0	Direction
20	*MSTEP	0	Step
22	*MWDAT	0	Write Data
24	*MWGAT	0	Write Gate
26	*TR00	I	Track Zero Sensor
28	*WPROT	I	Write Protect Sensor
30	*RDATA	I	Read Data
32	*MSIDE	0	Side Select
34	*RDY	I	Ready (jumper option)

All odd numbered pins are connected to ground.

The female mating connector to J7 is 3M part number 3414-6000 or equivalent. The maximum length of cable to be attached to J7 should not exceed 8 feet.

8. Jl0 - 26 Pin 3-1/2 Inch Micro Floppy Disk Drive Connector:

A 26 pin male header is used to attach one or two 3-1/2 inch Sony compatible disk drives to the BULLET REV F. The pin-out of this header is shown below.

PIN	SIGNAL	I/0	DESCRIPTION
1	*ZMTR	0	Motor On
2	*ZSEL1	0	Select Drive #1
3	N/C		
4	*ZSEL2	0	Select Drive #2
6	*ZDIR	0	Direction
8	*ZSTEP	0	Step
10	*ZWDAT	0	Write Data
12	*ZWGAT	0	Write Gate
14	*ZHLD	0	Head Load
16	*ZSIDE	0	Side Select
18	*INDEX	I	Index Pulse

20	*TR00	I	Track Zero Sensor
22	*WPROT	I	Write Protect Sensor
24	*RDATA	I	Read Data
26	*RDY	I	Ready

Odd numbered pins 3 through 25 are connected to ground.

The female mating connector to J10 is 3M part number 3499-6000 or equivalent. The maximum length of cable to be attached to J10 should not exceed 8 feet.

9. Jll - 4 Pin Power Connector:

- PIN DESCRIPTION
- 1 Not Connected
- 2 Not Connected
- 3 Ground (+5V Return)
- 4 +5V Plus or Minus 0.25V at 2.0A

The female mating connector is AMP part number 1-480424-0 with AMP contacts #60617-4 or equivalent.

V SYSTEM SETUP

Prior to a cold start boot strap operation, a system serial video console and floppy disk drive must be connected to the BULLET REV F.

System console. For Wave Mate software, a serial terminal console must be connected to J4. Reference should be made to Section IV of this manual for the appropriate connector pin-outs.

System floppy disk drive. The system can be booted from either a 5-inch mini floppy or an 8-inch floppy drive, either operating in single or double density recording. The disk drive chosen for the boot strap operation must be wired as drive 0, and its characteristics must be reflected by the setting of switches SW1-5 through SW1-8.

System printer. The system printer may be either a Centronics parallel or an RS-232 serial model. If a Centronics printer is selected, then another serial port is free for use in other ways; i.e., communications port, second printer or terminal.

A. Switches and Jumpers

1. Switches:

An eight position DIP switch designated as SWl is located on the BULLET REV F.

SW1-1 is used to control power to the SCSI bus termination resistors. If the SCSI bus interface is not being used this switch should be off to reduce unnecessary power dissipation. If the SCSI bus is in use this switch MUST be on.

SW1-2 and SW1-3 are unassigned.

SW1-4 is used to select the BOOT ROM device. If this switch is off a system reset will cause program execution to transfer to the 32 byte ROM on the board. If the switch is on program execution will transfer to the EPROM device (if provided).

SW1-5 through SW1-8 are used to initialize the floppy disk controller to be compatible with the type of drive being used in the boot strapping of the system.

The types of drives and the appropriate switch settings are shown in the following table:

FLOPPY TYPE	SW1-5	SW1-6	SWl-7	SW1-8
Double density 3-inch floppy	off	on	on	on
Single density 5-inch floppy	on	on	off	off
Double density 5-inch floppy	on	on	off	on
Single density 8-inch floppy	on	off	on	off
Double density 8-inch floppy	on	off	on	on

2. Jumpers:

Jumper configurations on the BULLET REV F are set as follows and should seldom need change:

- JUMPER FUNCTION
- El This jumper is used to select onboard enabling of the ready line when 5-inch disk drives are selected. If the system is connected to 5-inch disk drives which have a drive ready signal on interface pin 34, then this jumper may be left open, otherwise it should be closed. The board is shipped with this jumper closed.
- E3 This jumper is used to select Address/Power operation to U131 pin 26. U131 is a universal EPROM site and may be used with 2732, 2764, or 27128 EPROM devices. If a 2732 is used, pin 26 must be powered. When jumpered from 1 to 2, power is provided. If a 2764 or 27128 is used, this must be jumpered from 2 to 3 to provide proper addressing. The board is shipped with a jumper from 1 to 2.
- E4 This jumper is used for 5-inch disk drives which require an external head load signal on pin 4 of the interface. When jumpered, this signal is active when the 1793 asserts head load. The board is shipped with this jumper open.

B. Serial Cable Information

The following cable chart is presented to aid in connection of the serial I/O devices to standard RS-232-C terminals. It should be noted that the RS-232-C circuit names define the direction of the signal between Data Communication Equipment (DCE) and Data Terminal Equipment (DTE). These signal names should not be confused with the signal names assigned by Zilog to the DART. The Zilog names closely follow the usage of the DART as part of a DTE. In the BULLET REV F, the DART will generally be used as a DCE circuit.

RS-232-C Circuit Name	DB25S Pin	Signal Direction	10 Pin Header	DART Name
BA-Transmitted Data	2	>	2	RxD
BB-Received Data	3	<	1	TXD
CA-Request To Send	4	>	5	CTS
CB-Clear To Send	5	<	4	RTS
CC-Data Set Ready	6	<	3	DTR
AB-Signal Ground	7	<>	8	GND
CF-Received Line				
Signal Detect	8	<	7	RLSD
CD-Data Terminal				
Ready	20	>	6	DCD

Note: The DB25S pin number above refers to the industry standard D subminature connector with 25 contacts. The 10 pin header refers to J3, J4, J8, and J9 on the BULLET REV F.

C. Connecting Floppy Disk Drives

The following disk drive configuration tables are presented to aid in connection of 8-inch and 5-inch floppy disk drives to the BULLET REV F. It should be noted that there are few options on the 5-inch drives and configuration is usually simple. The 8-inch drives sometimes present difficulties due to the number of options and differences in names of the option strapping between drive manufacturers. When optioning 8-inch drives, the following point should be kept in mind: The stepper motor which positions the heads must be enabled with drive select, not head load. This is the most common cause of difficulty. If not set up in this manner, the drive will not move the heads when a restore command without head load is issued.

SHUGART SA400/450/410/460 JUMPER OPTIONS

NAME	OPEN/SHORT
MX	open
DS0	short for unit 0, otherwise open
DSl	short for unit 1, otherwise open
DS2	short for unit 2, otherwise open
DS3	short for unit 3, otherwise open
MS	short
MM	open

SHUGART SA800 JUMPER OPTIONS

NAME	OPEN/SHORT
T3,T4,T5,T6	short
Tl	short
Т2	short
DS1	short for unit 1, otherwise open
DS2	short for unit 2, otherwise open
DS3	short for unit 3, otherwise open
DS4	short for unit 4, otherwise open
RR	short
RI	short
R,I,S	short
HL	open
DS	short
WP	short
NP	open
D	open
A,B	short
X	open
С	short
2	short
Y	open
DC	short